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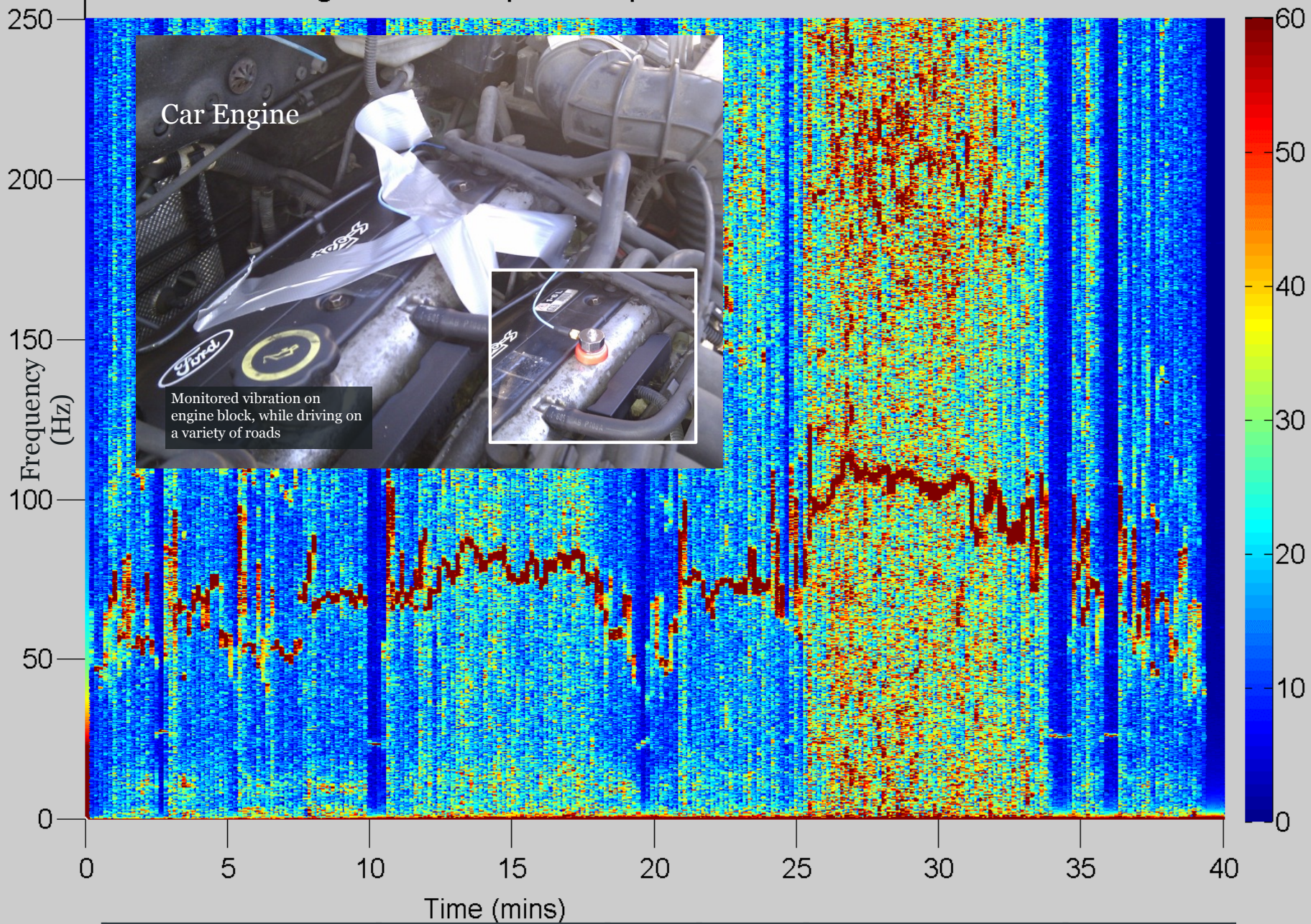
Transient and Power-Neutral Computing: A Paradigm Shift for Embedded Systems?

Geoff Merrett, 02 April 2016

“Hilariously Low Power Computing” Workshop
ASPLOS 2016, Atlanta GA

Single-Sided Amplitude Spectrum of Acceleration level

Acceleration(mg)



mph:

30

60

20

60

70

30

Outline

*towards storage-less and
power-centric systems*

- **Energy-Harvesting** Systems

Operating from harvested energy

- **Energy-Neutral** Computing

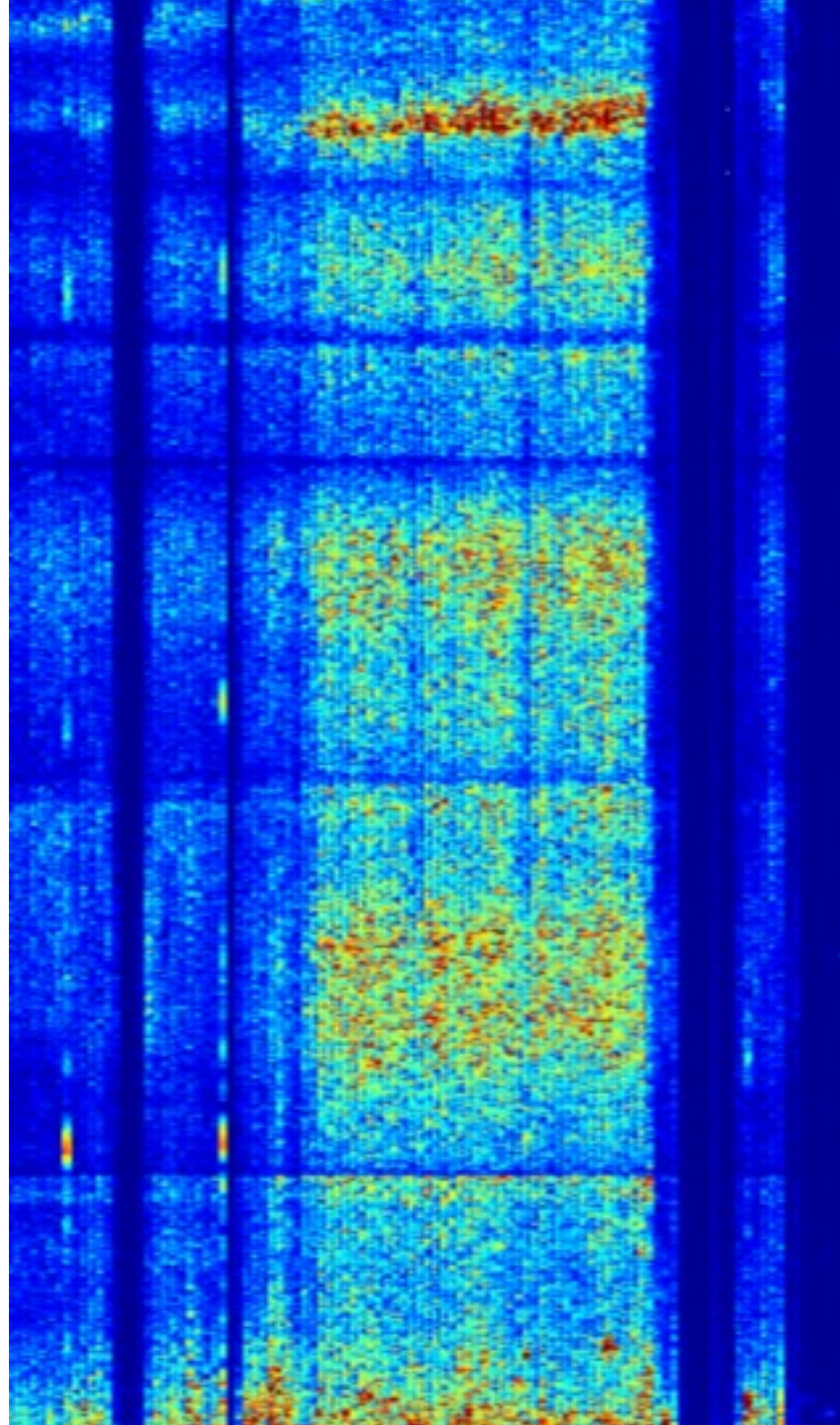
Buffering energy for a battery-like supply

- **Transient** Computing

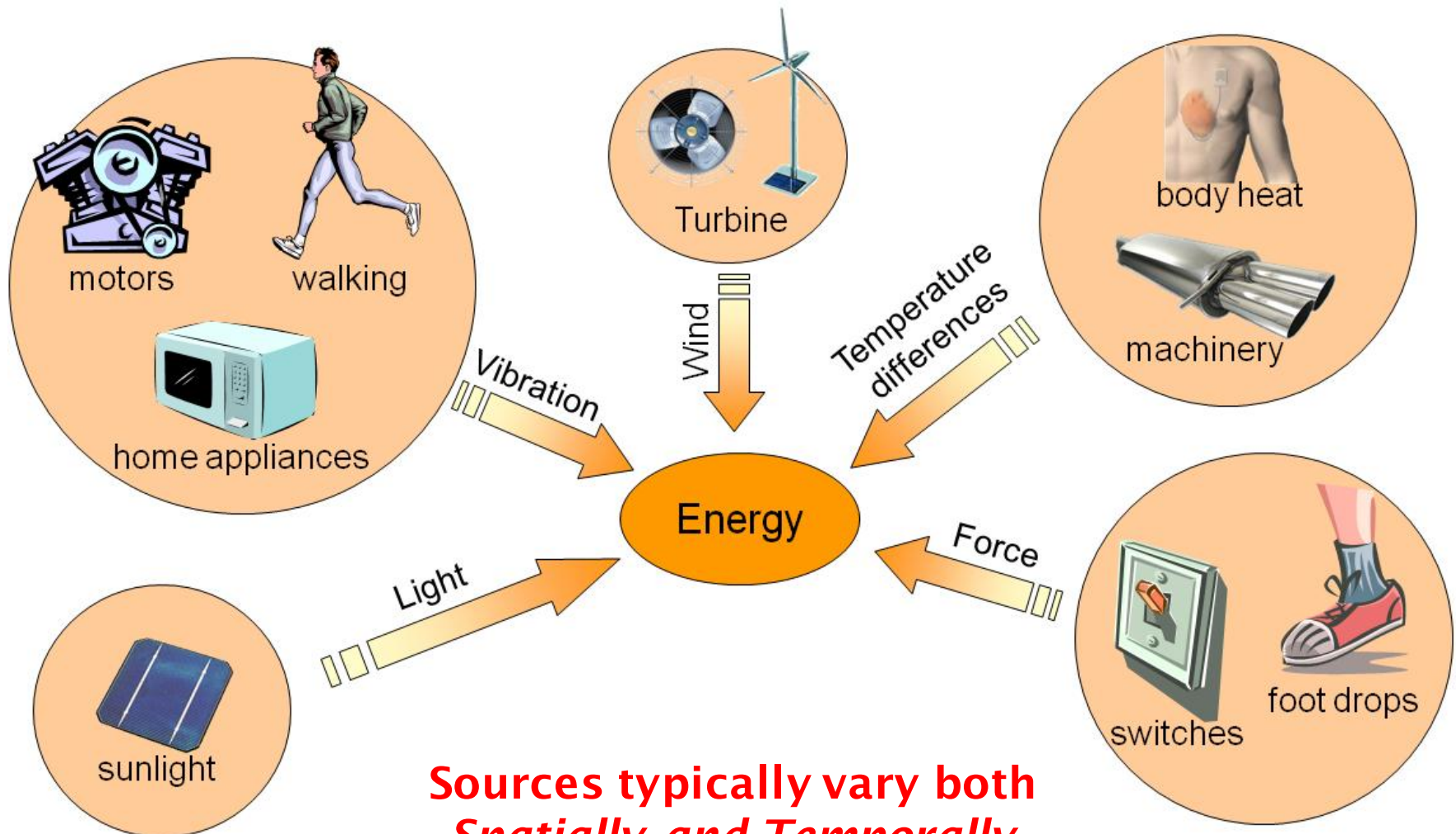
Computation when power is available

- **Power-Neutral** Computing

Adaptive computation when power is available



Energy Harvesting



**Sources typically vary both
*Spatially and Temporally***

Energy harvesting

Irregular and unpredictable power generation

Autonomy

Irregular and unpredictable power consumption

*enable computation to be sustained
despite an intermittent supply*

Outline

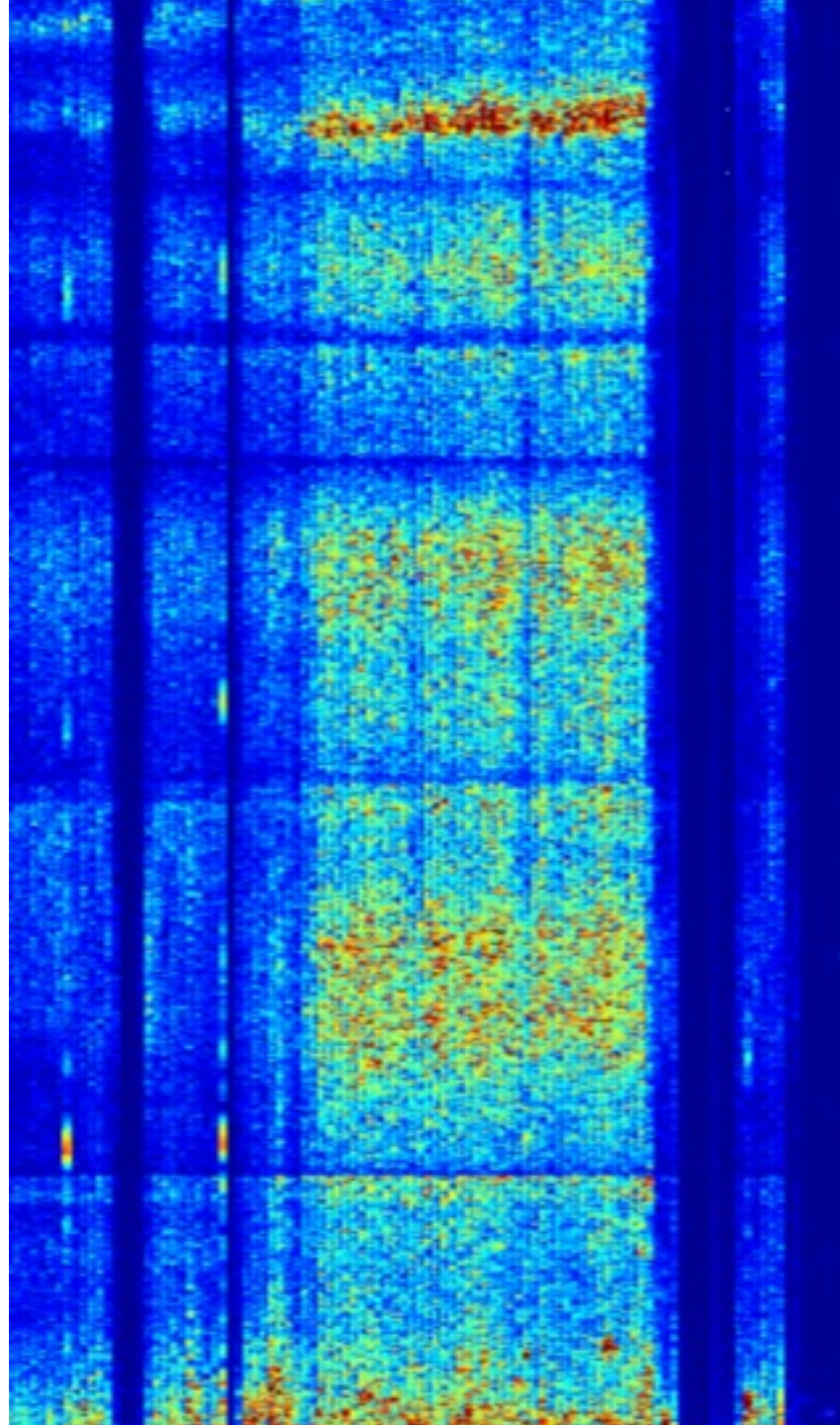
*towards storage-less and
power-centric systems*

Energy-Harvesting Systems

Operating from harvested energy

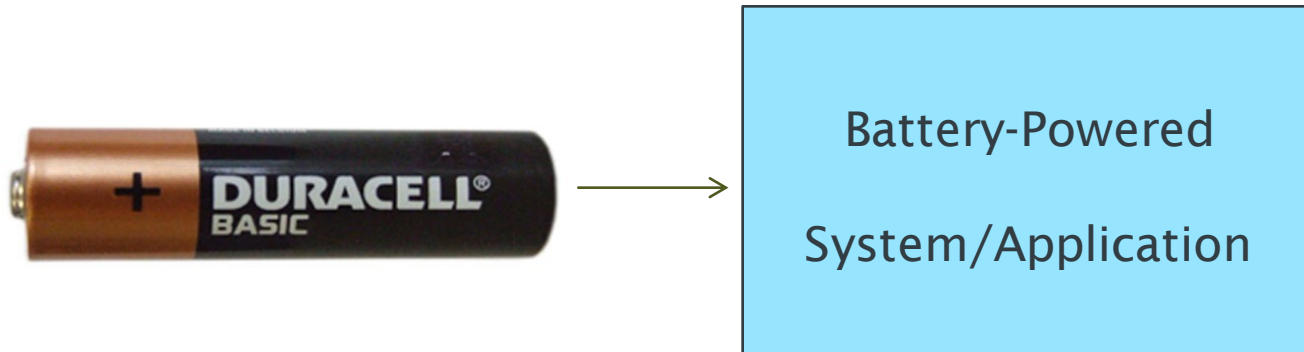
Energy-Neutral Computing

Buffering energy for a battery-like supply



Energy-Neutral Computing

- Traditional embedded systems want to be run from a *battery-like* power supply



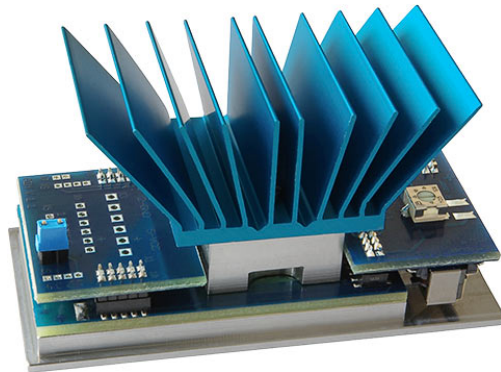
Power/current (virtually) unlimited at time t

Limited amount of energy over lifetime T



Energy-Neutral Computing

- Traditional embedded systems want to be run from a *battery-like* power supply

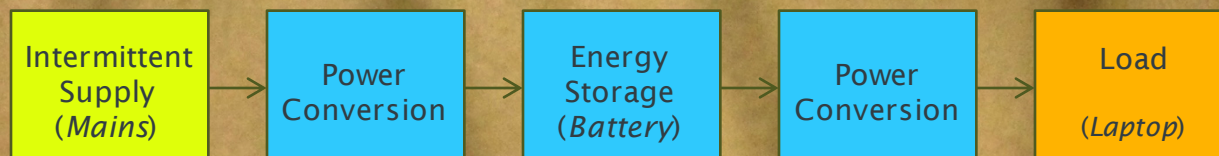


Battery-Powered
System/Application

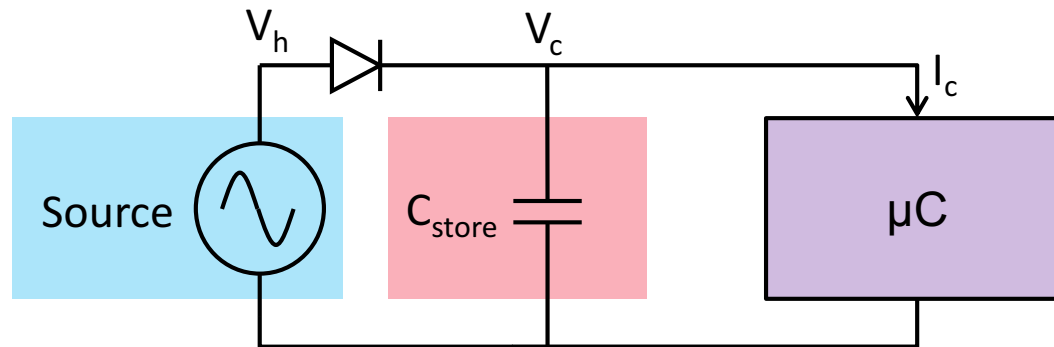
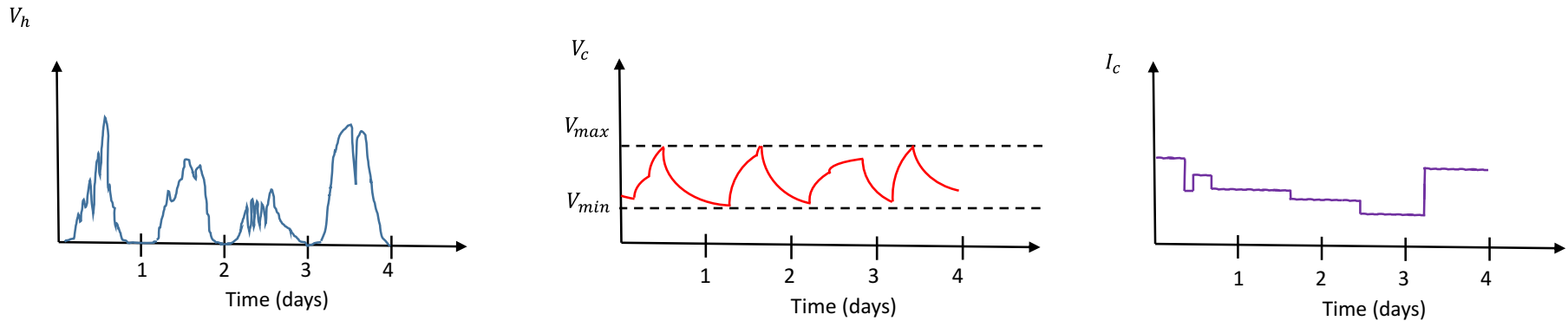
Power/current limited (and varying/intermittent) at time t

(Virtually) unlimited amount of energy and lifetime T





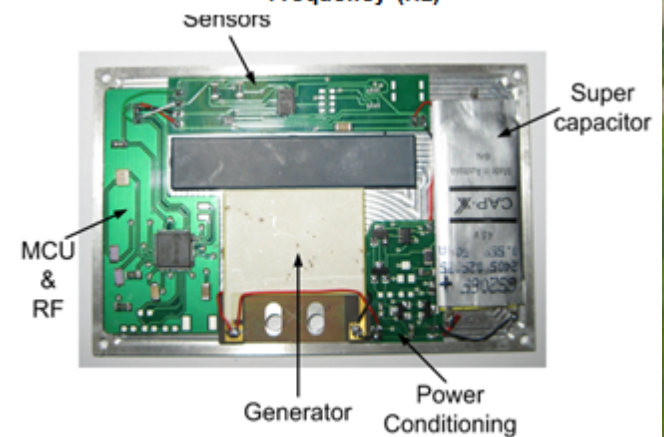
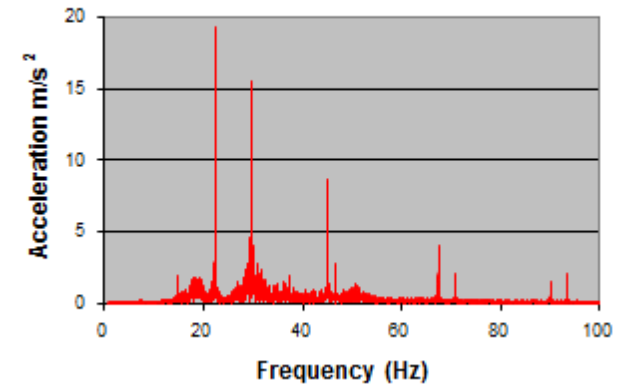
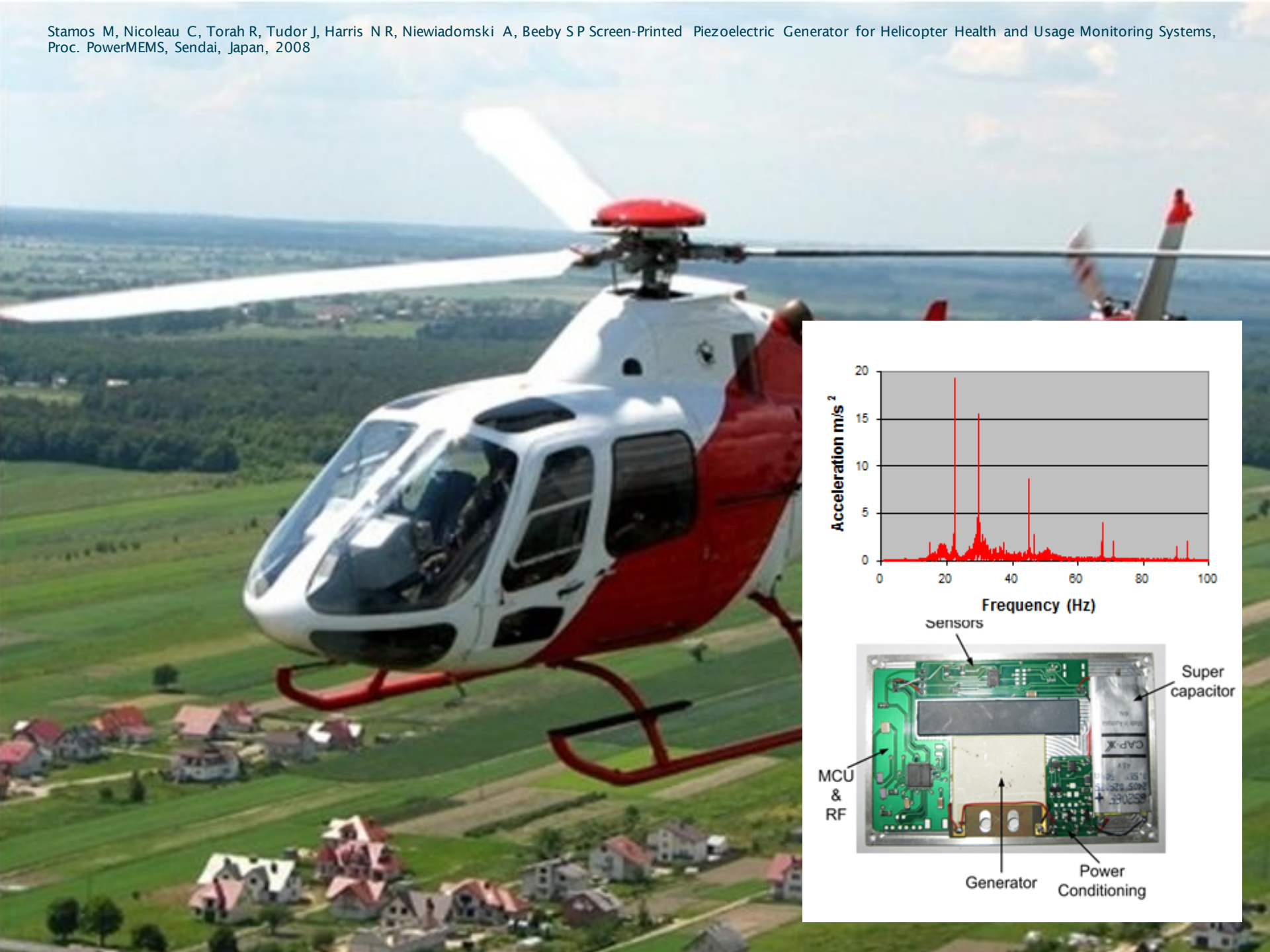
Energy-Neutral Computing



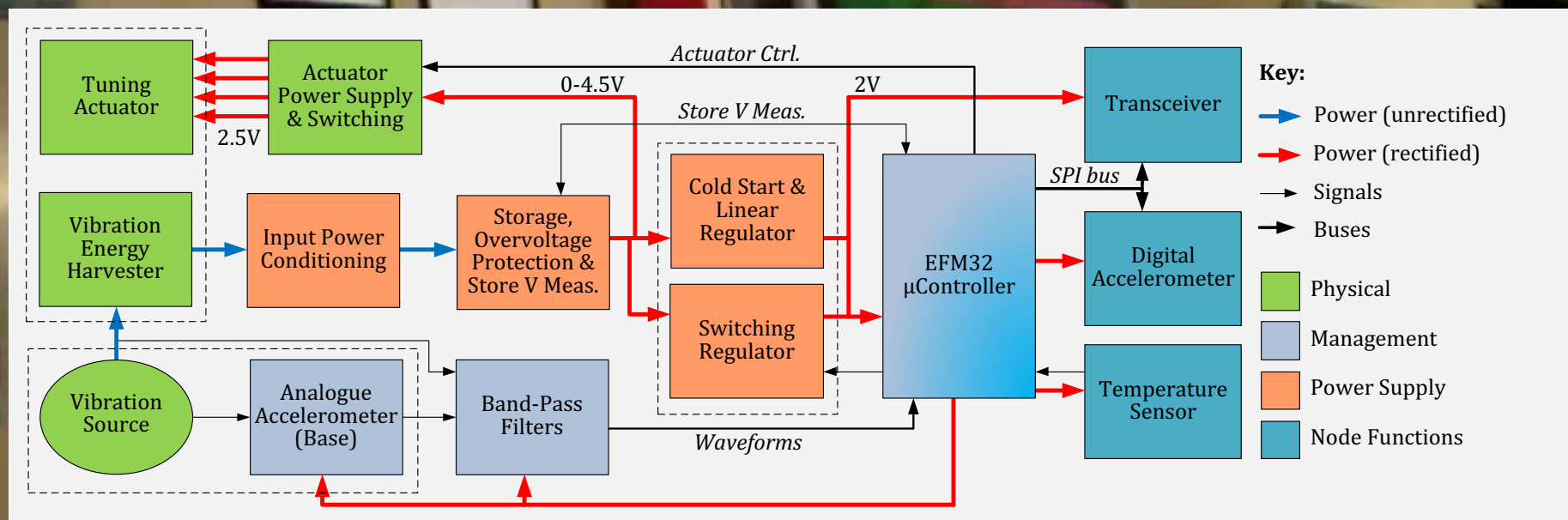
Energy Neutrality is Achieved if:

$$\int_{(n-1) \cdot T}^{n \cdot T} P_h(t) dt = \int_{(n-1) \cdot T}^{n \cdot T} P_c(t) dt$$

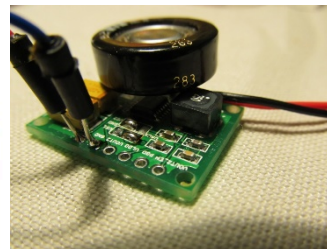
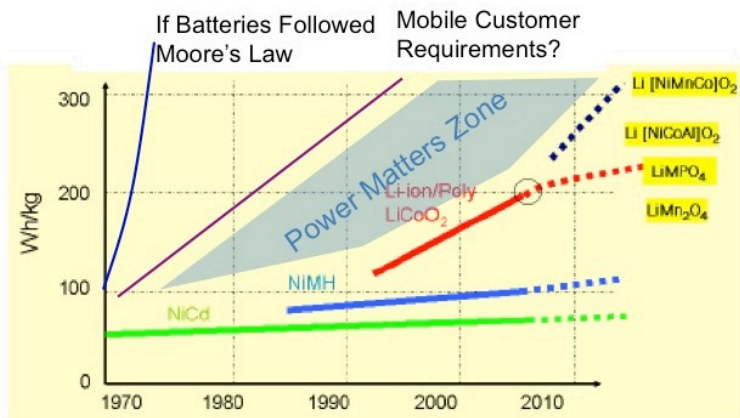
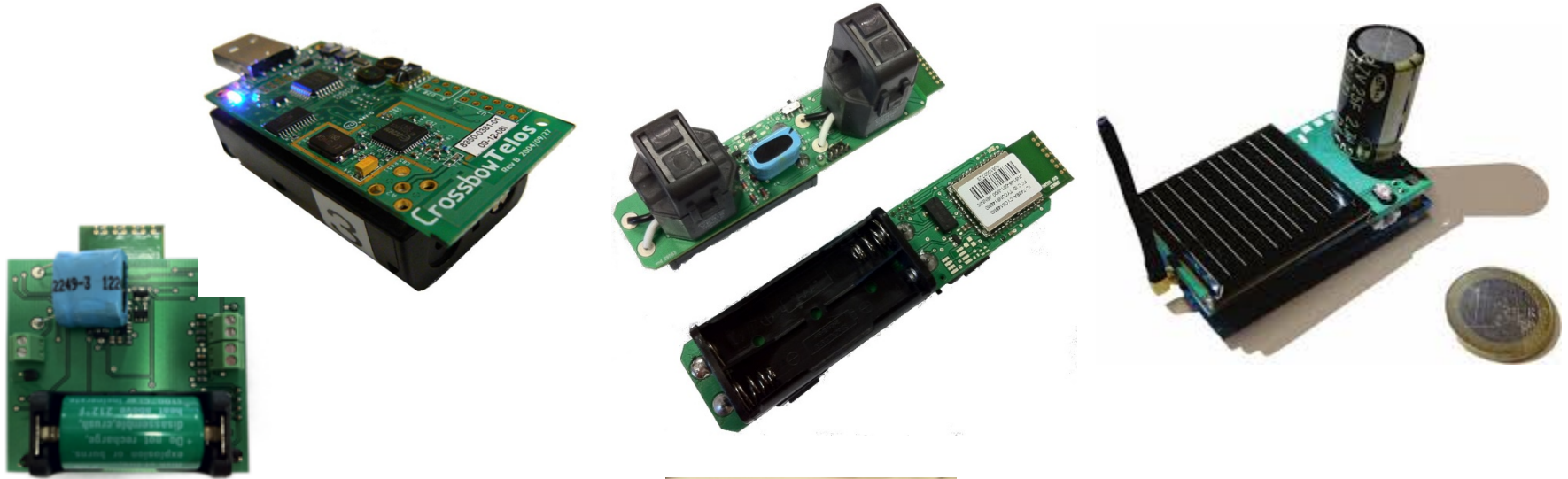
(assuming that $V_c(t) > V_{min}$ for all t)



Engine Condition Monitoring

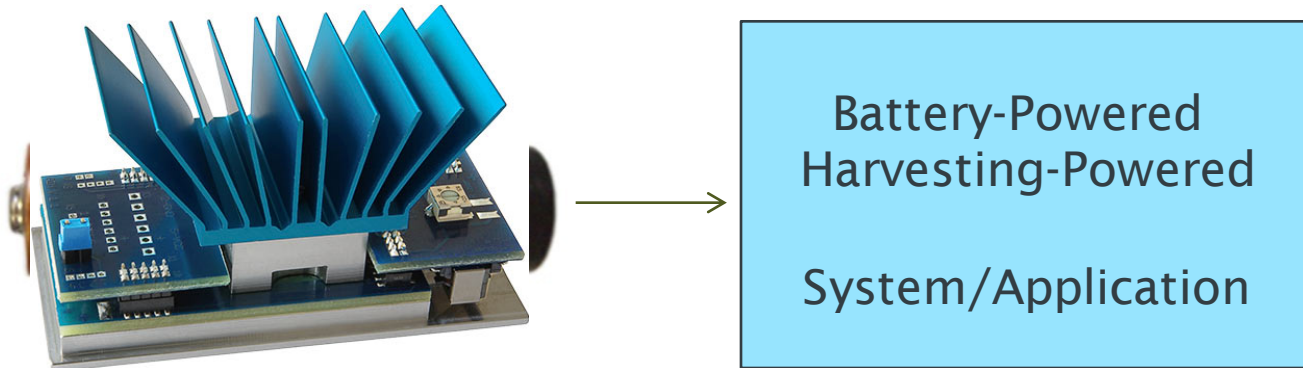


Energy-Neutral Computing



Energy Harvesting Systems

- Don't try to make the energy harvester look like a battery...



- ...but rethink the design of energy harvesting systems.
- *How do we design energy harvesting:*
 - *computation?*
 - *communication?*
 - *electronics?*
 - *systems?*
 - *applications?*

*enable computation to be sustained
despite an intermittent supply...*

*...without the use of additional energy
storage (e.g. supercapacitors or batteries)*

Outline

*towards storage-less and
power-centric systems*

- **Energy-Harvesting** Systems

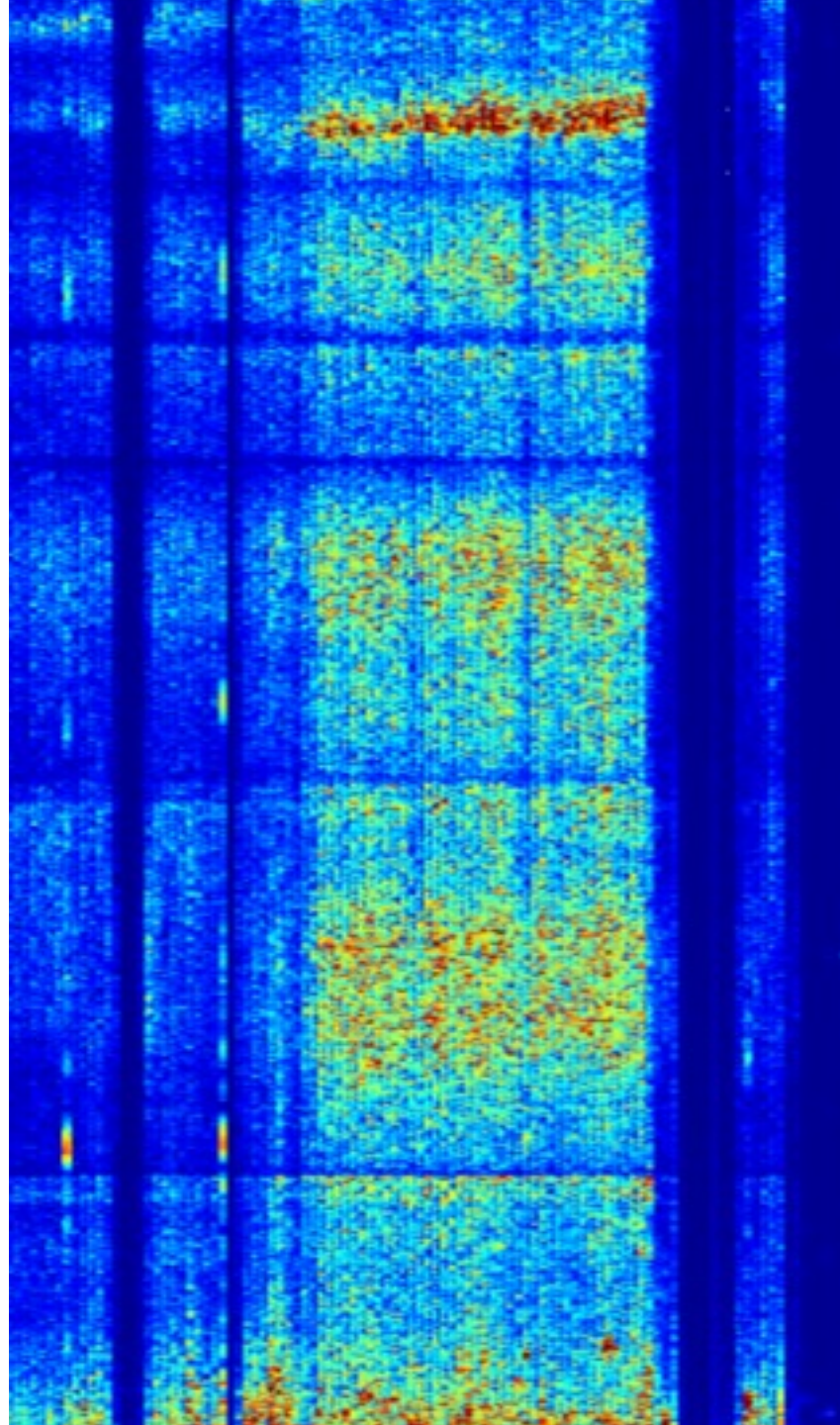
Operating from harvested energy

- **Energy-Neutral** Computing

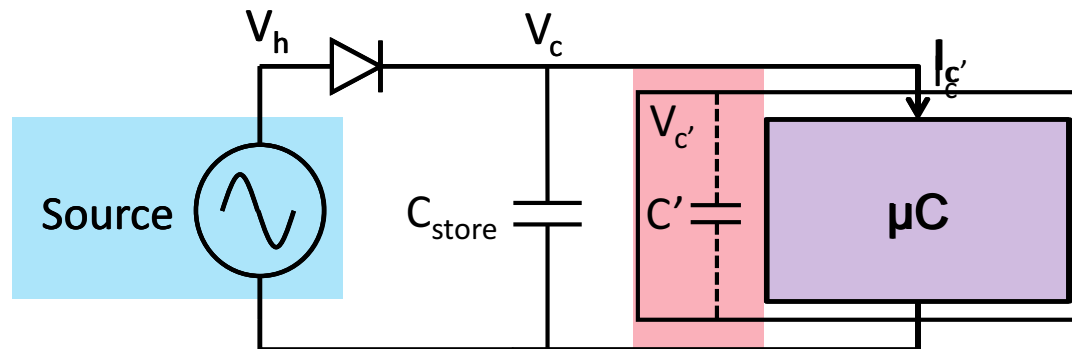
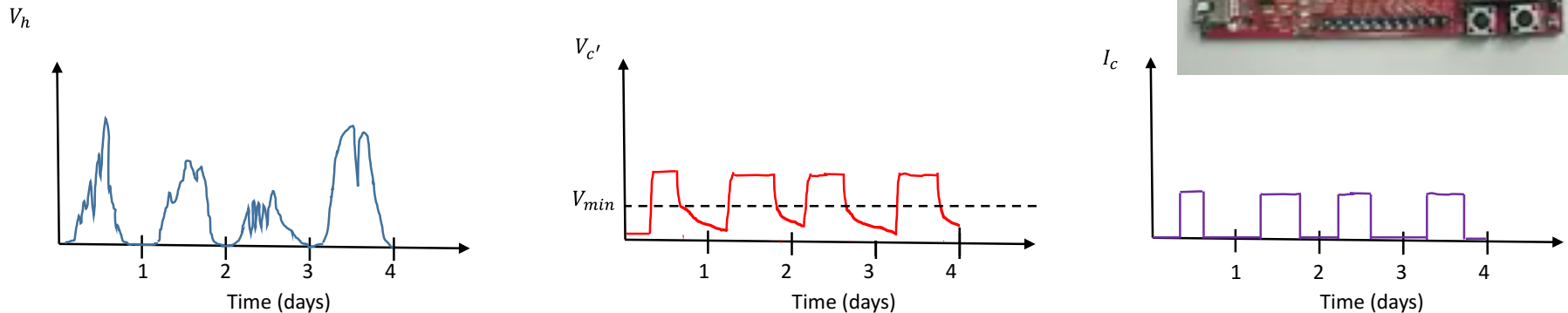
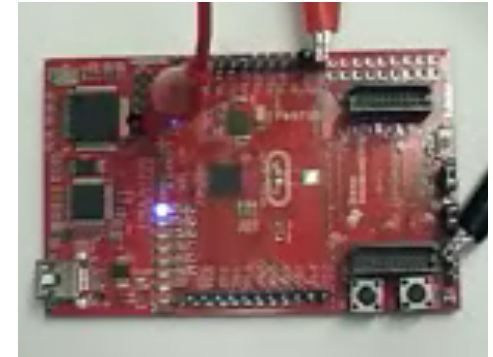
Buffering energy for a battery-like supply

- **Transient** Computing

Computation when power is available



Transient Computing



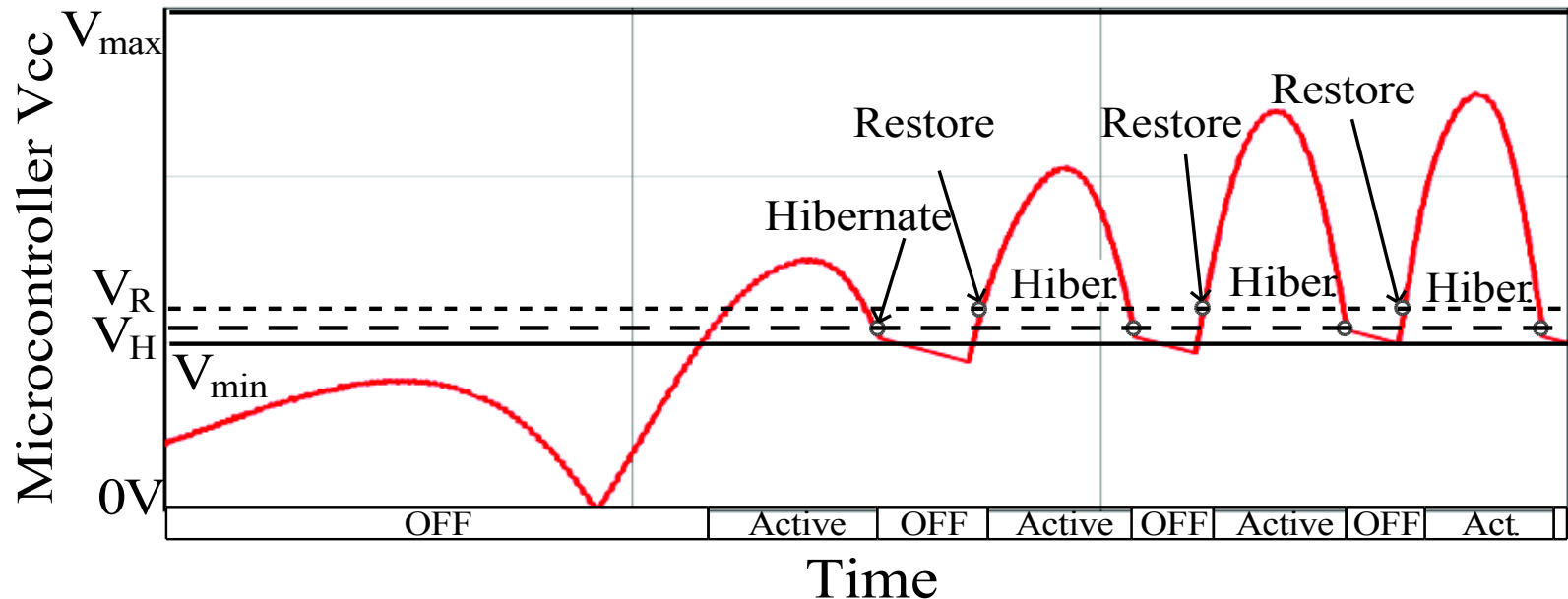
- How can computation accommodate this intermittent supply?

Mementos

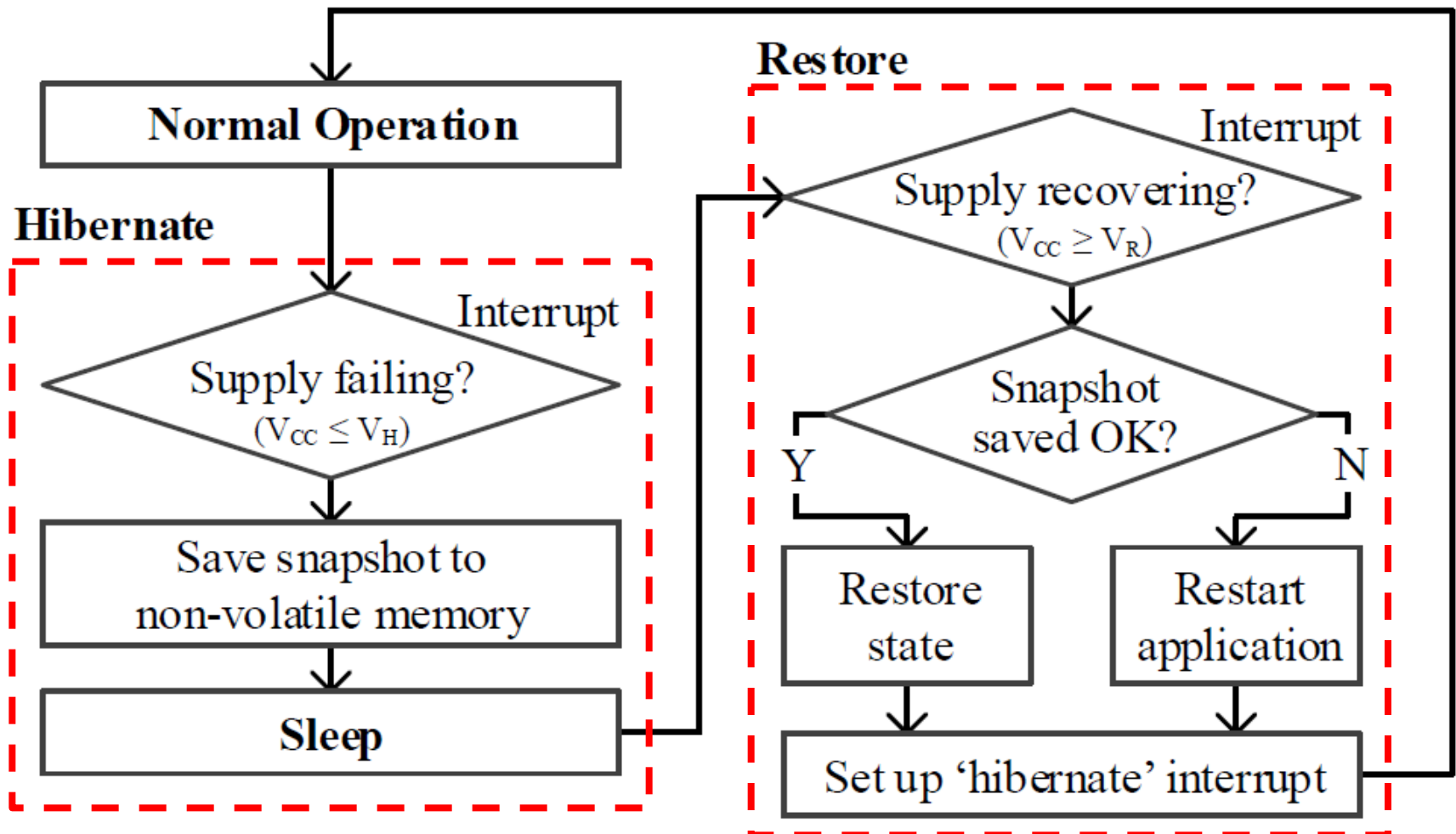
- First/early works in this work
 - Uses concept of check pointing (from fault tolerance)
 - Design/compile-time approach
- Checkpoint placement heuristics, e.g. start of loop/function
 - *Redundant checkpoints/snapshots (causing overheads in both t and E)*
- At a checkpoint, a snapshot is saved if $V_{CC} < \text{a threshold}$
 - *If $V_{CC} \ll \text{threshold}$, may not be enough time to snapshot*
- After an interruption, restores if a valid snapshot was saved
 - *Code executed since the last checkpoint is lost (therefore is re-executed)*

Hibernus

- The motivation for *Hibernus* is to decide when to save a snapshot at run-time
 - Removing overheads (efficiency)
 - Ensuring that a single valid snapshot is always made (reliability)

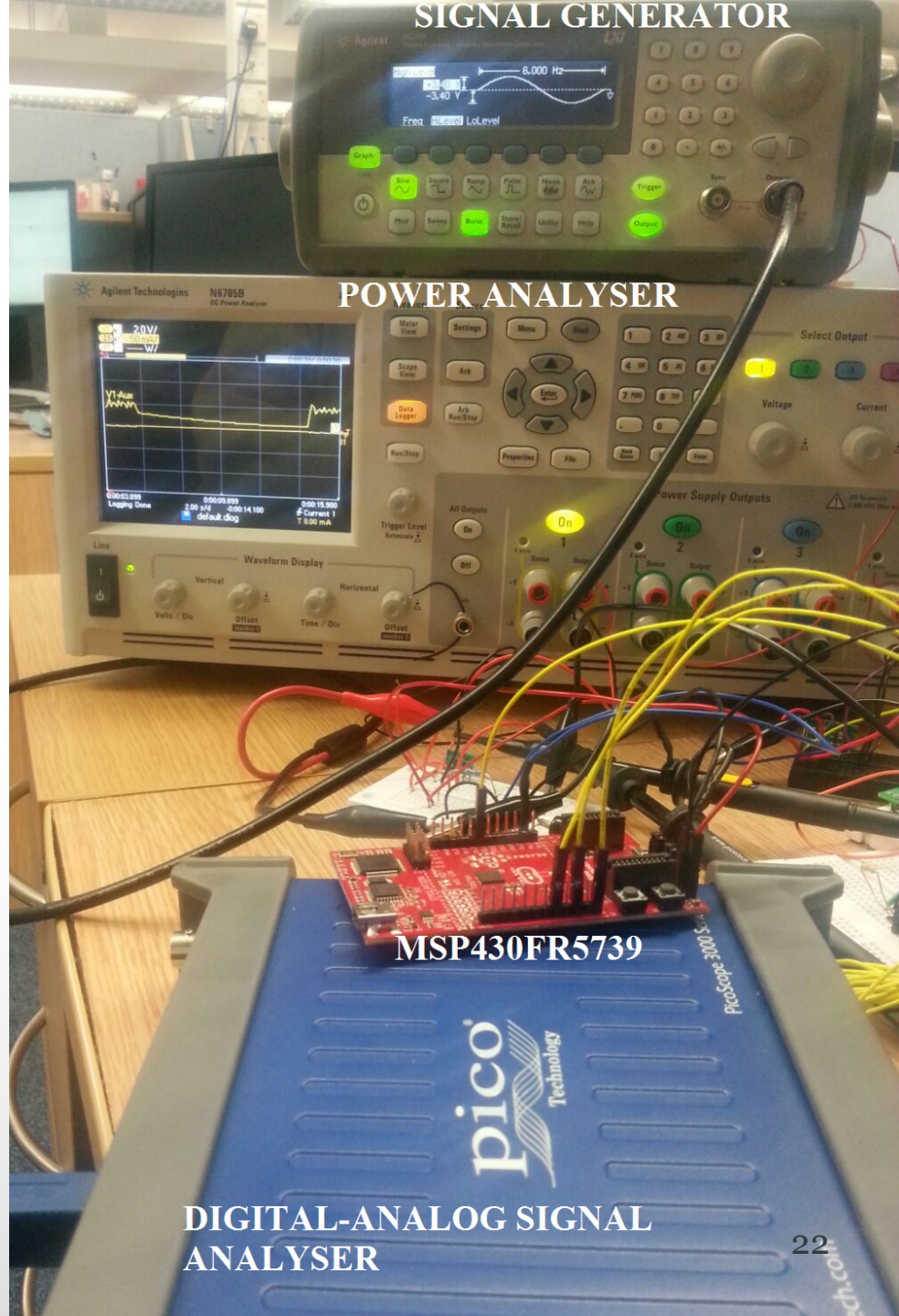


Hibernus: Operation

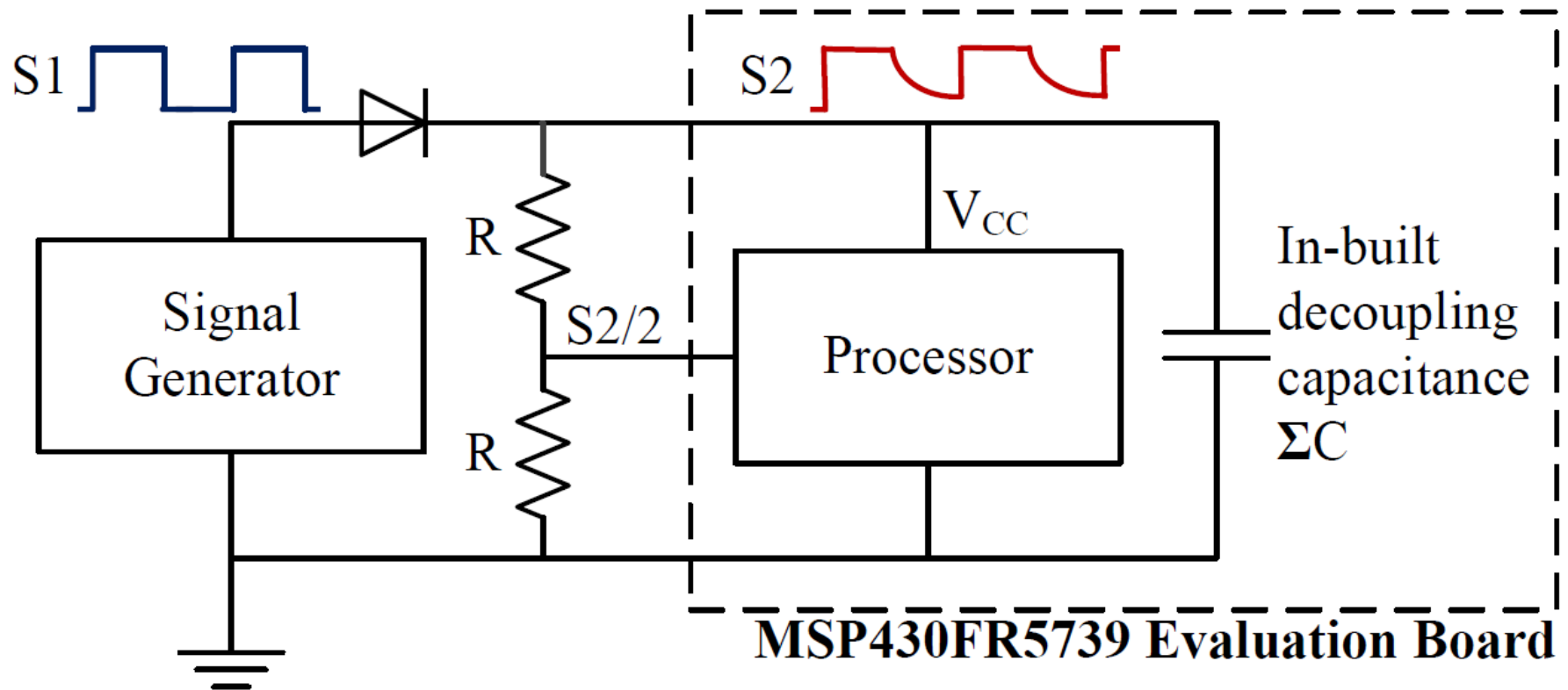


Validation

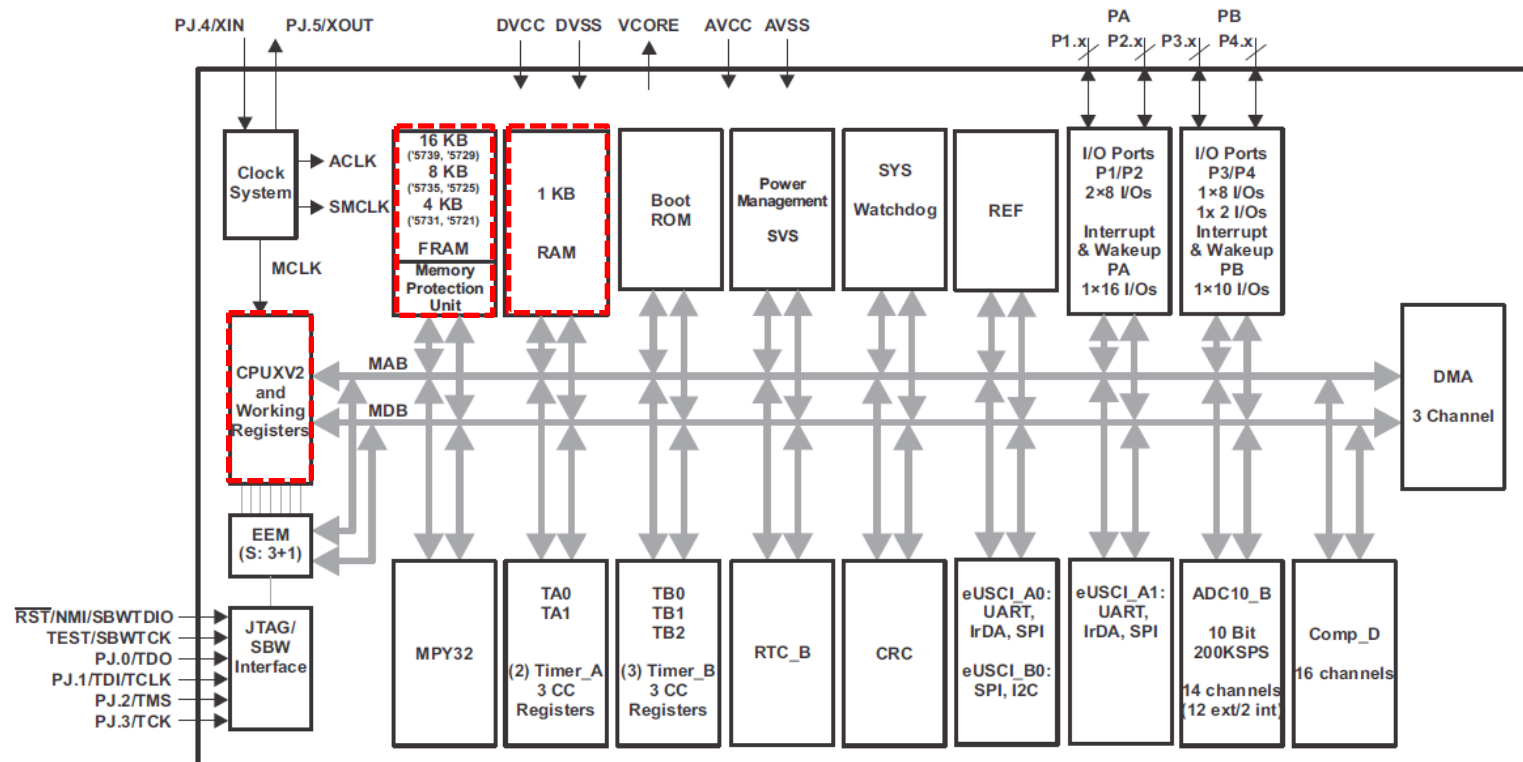
- Implemented on a TI MSP430-FR5739 microcontroller.
- Tested with
 - Multiple workloads (e.g. FFT)
 - Controlled inputs (signal generator with a range of frequencies DC-20Hz)
 - Real energy harvesters



Validation



Testbed: TI MSP430FR Block Diagram



name	origin	length	used	unused	attr
SFR	00000000	00000010	00000000	00000010	RWIX
PERIPHERALS 8BIT	00000010	000000f0	00000000	000000f0	RWIX
PERIPHERALS 16BIT	00000100	00000100	00000000	00000100	RWIX
RAM	00001c00	00000400	00000000	00000400	RWIX
FRAM	0000c200	00003d80	0000067a	00003706	RWIX

The total time needed to store all Core Registers, all RAM and all General Registers is only 1.3ms.

Hibernation Threshold

- Energy consumed hibernating E_σ depends on the size of the volatile memory and the energy for each byte.

$$E_\sigma = n_\alpha E_\alpha + n_\beta E_\beta$$

- Given the total capacitance ($\sum C$), the energy stored E_δ between a given voltage V_H and V_{min} is:

$$E_\delta = \frac{V_H^2 - V_{min}^2}{2} \sum C$$

- To ensure stability, V_H is set to that $E_\sigma < E_\delta$, to enable complete hibernation.

The *Hibernus* Library

- *Hibernus* functionality is contained within the `hibernus.h` library file;
- Application developers only need to include this library the `initialise()`, `hibernate()` and `restore()` routine;

```
#include "hibernus.h"

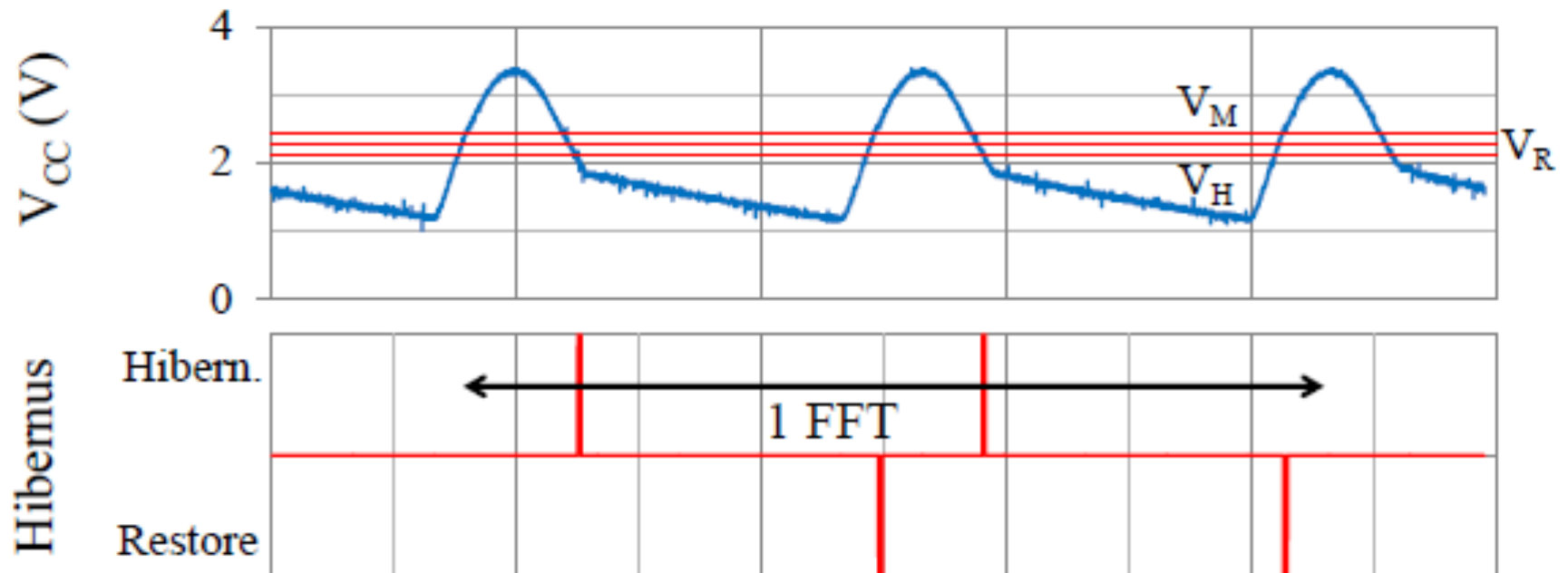
int main (void) {
    if (flag) restore(); //restore system state
    else initialise(); //initialise hibernus
    // application code goes here
}

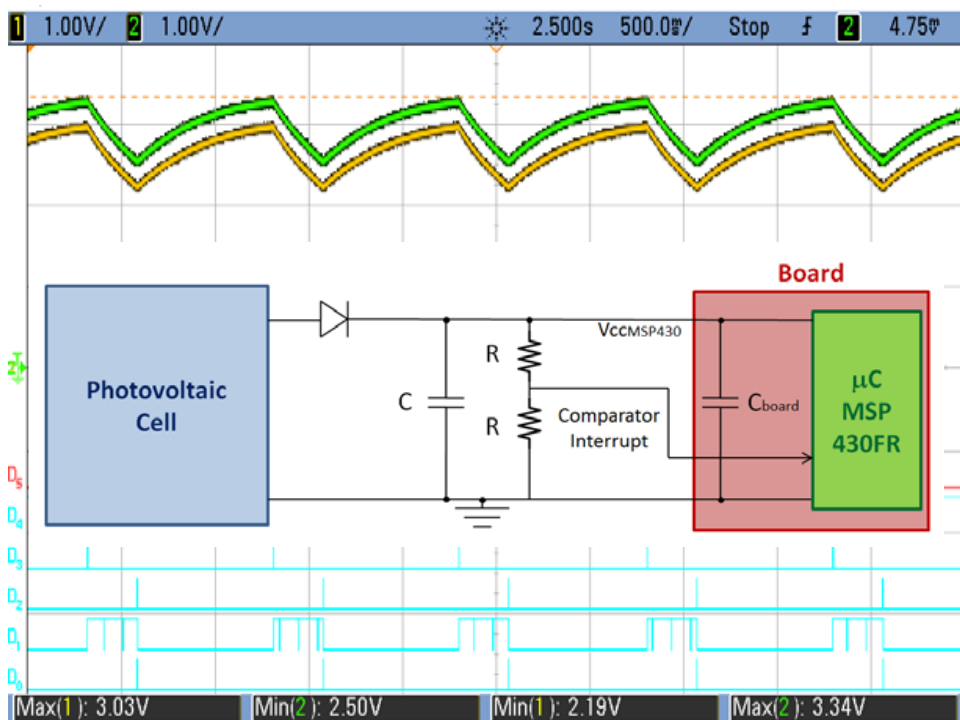
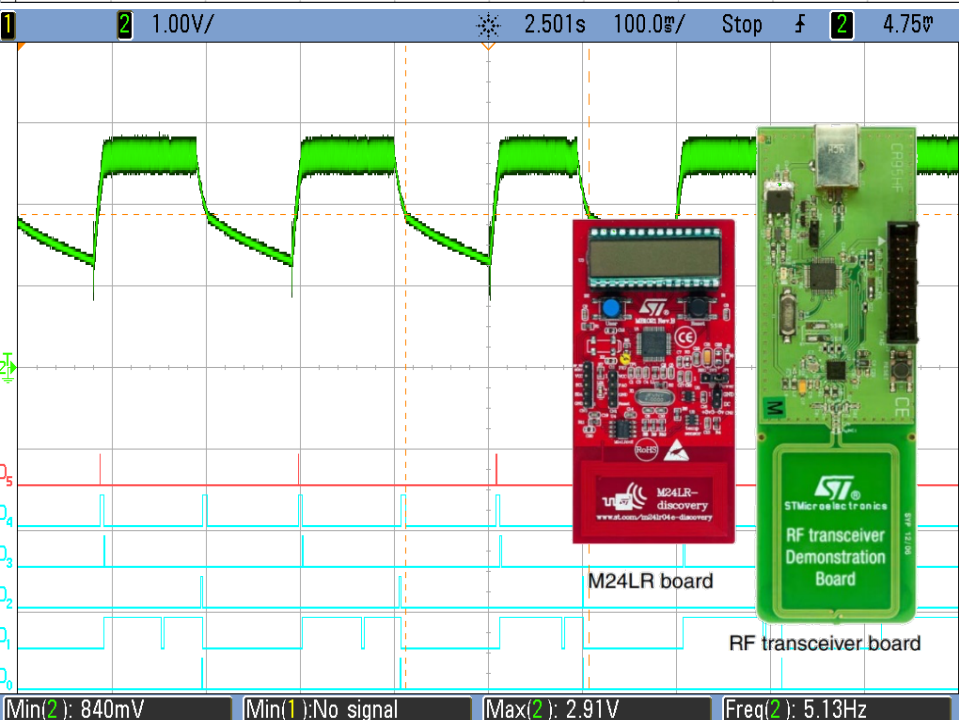
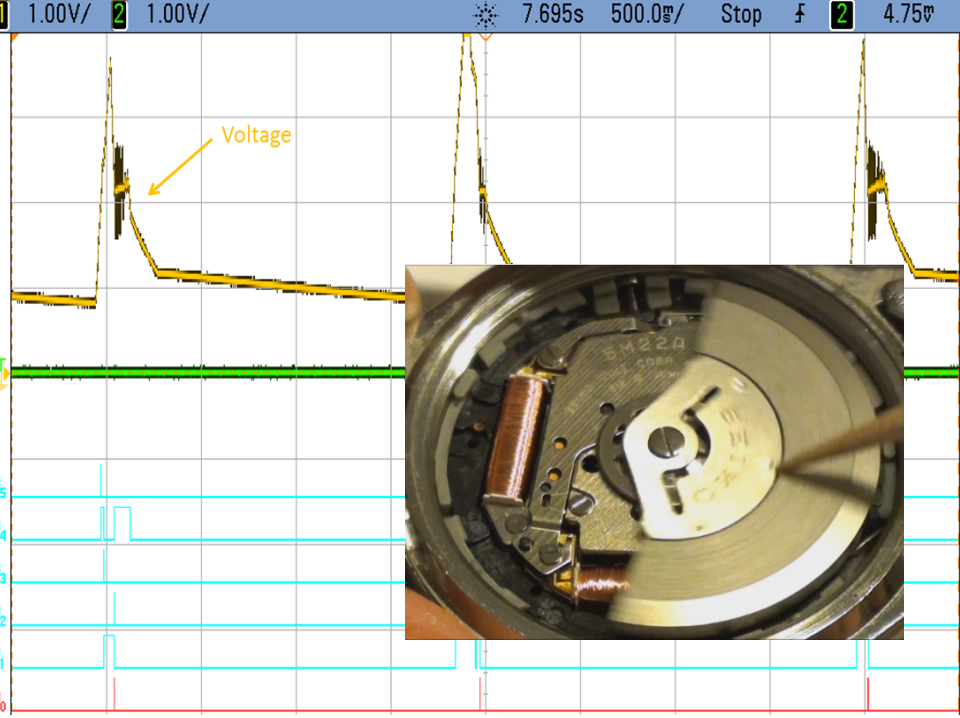
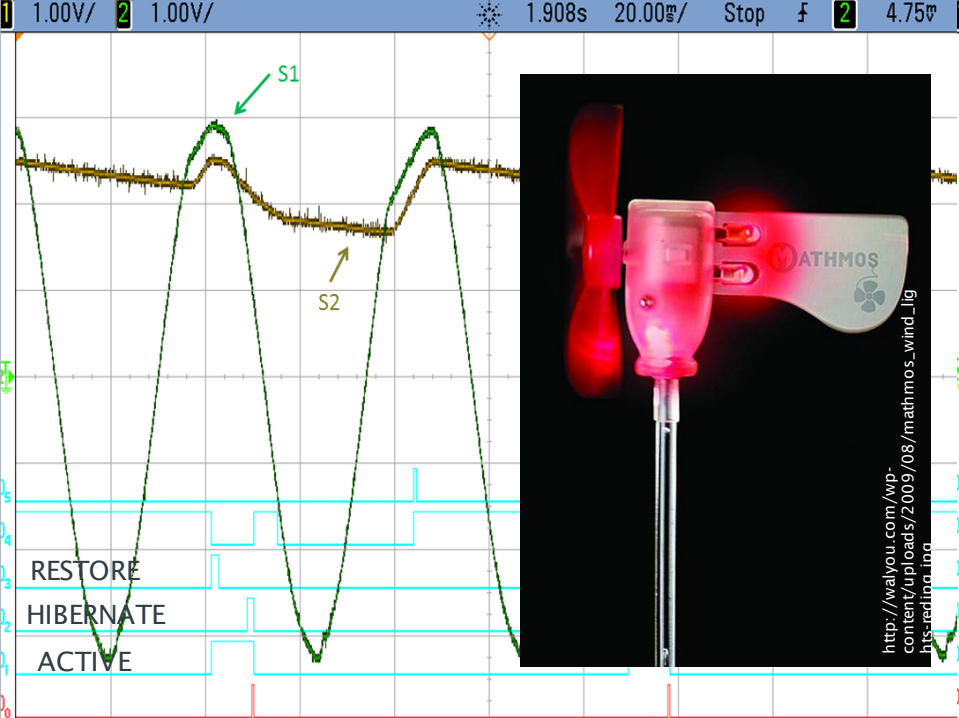
-----

__interrupt void COMP_D_ISR(void) {
    hibernate(); //save system state & sleep
}
```


Hibernus Results

- FFT of tri-axial accelerometer data



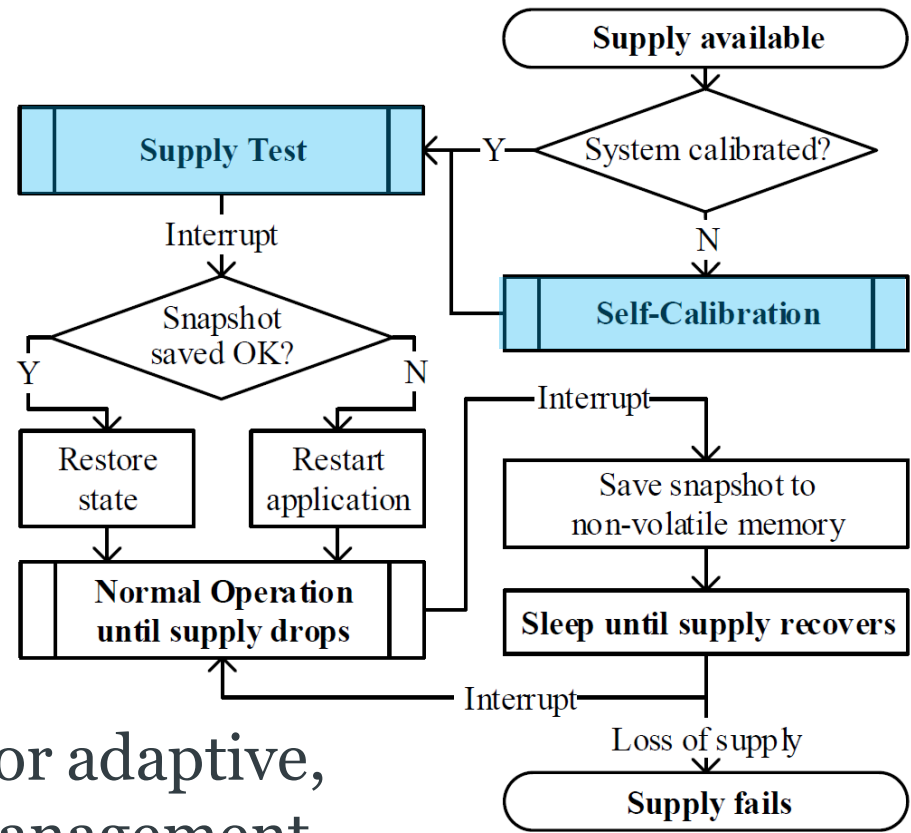


Automatic Calibration of Hibernus

- Hibernus required manual design-time calibration:

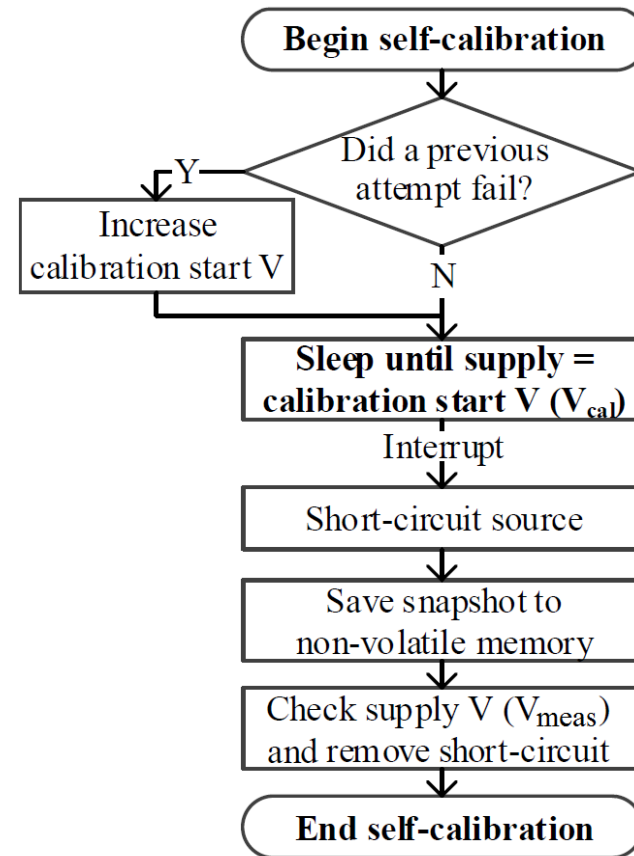
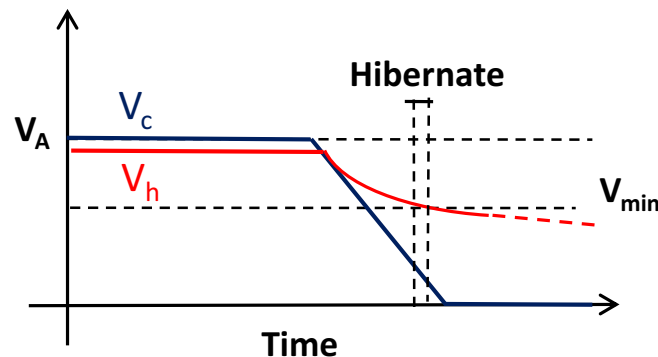
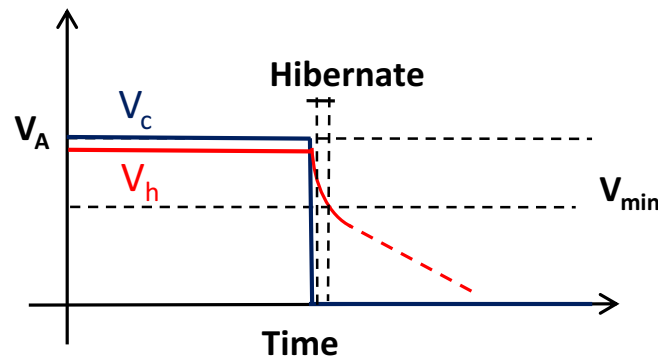
- Select hibernate threshold based on the worst case
[Source Dependent]
- Select hibernate threshold based on C'
[Platform Dependent]
- Select restore threshold based on source dynamics
[Source Dependent]

- Hibernus++ adds process for adaptive, run-time calibration and management



Hibernus++ Adaptive Hibernation

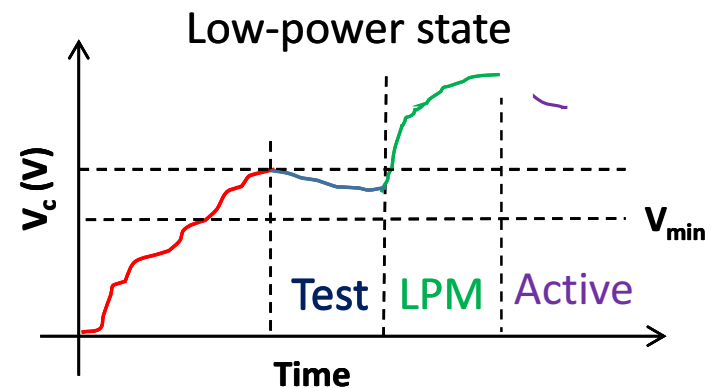
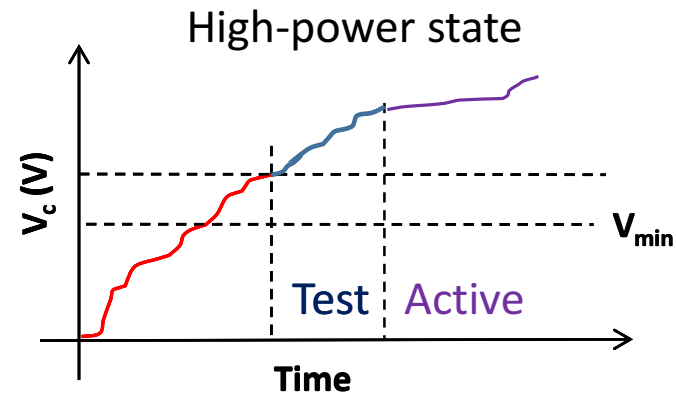
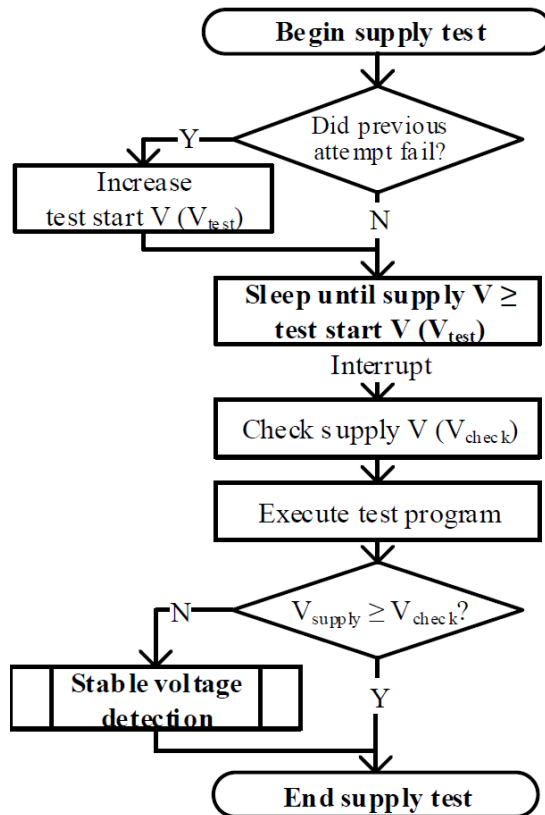
- Calibration Process



Still pick the 'worst case' power loss (so that can always hibernate), put characterize the platform

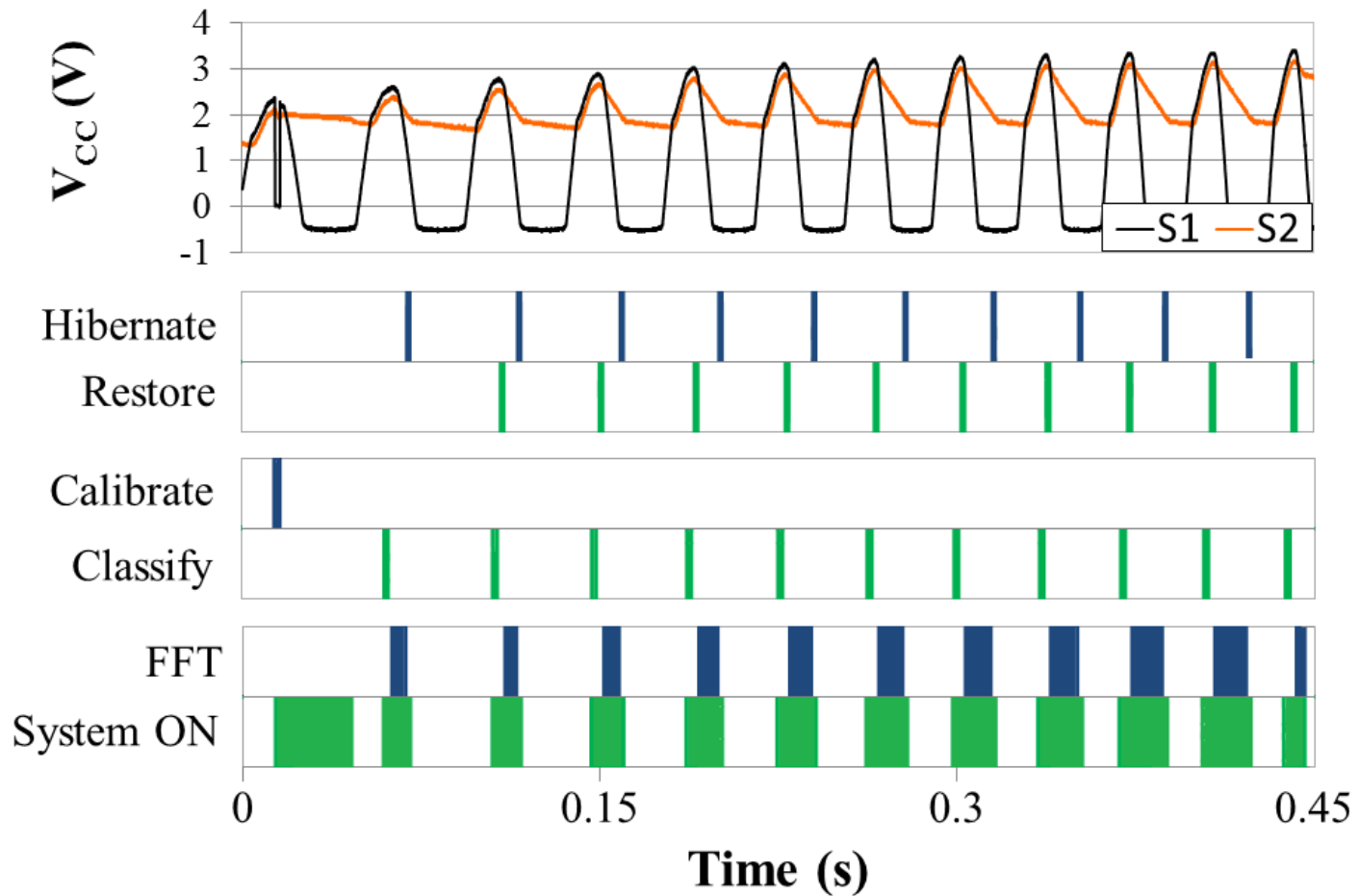
Hibernus++ Adaptive Restore

- Source Classification Process*

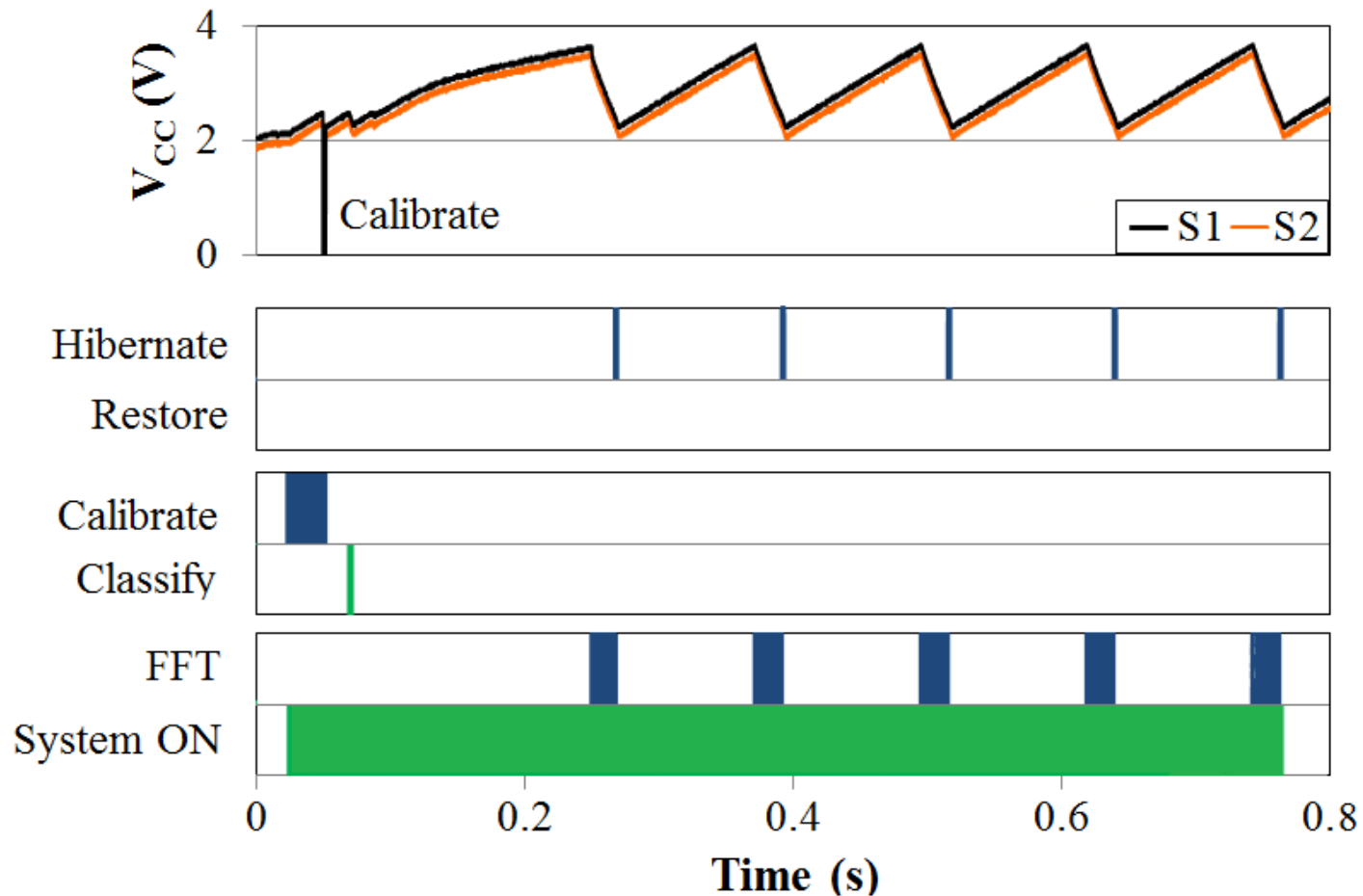


Characterize the source dynamics each time we want to restore, to select the best policy

Hibernus++ Results

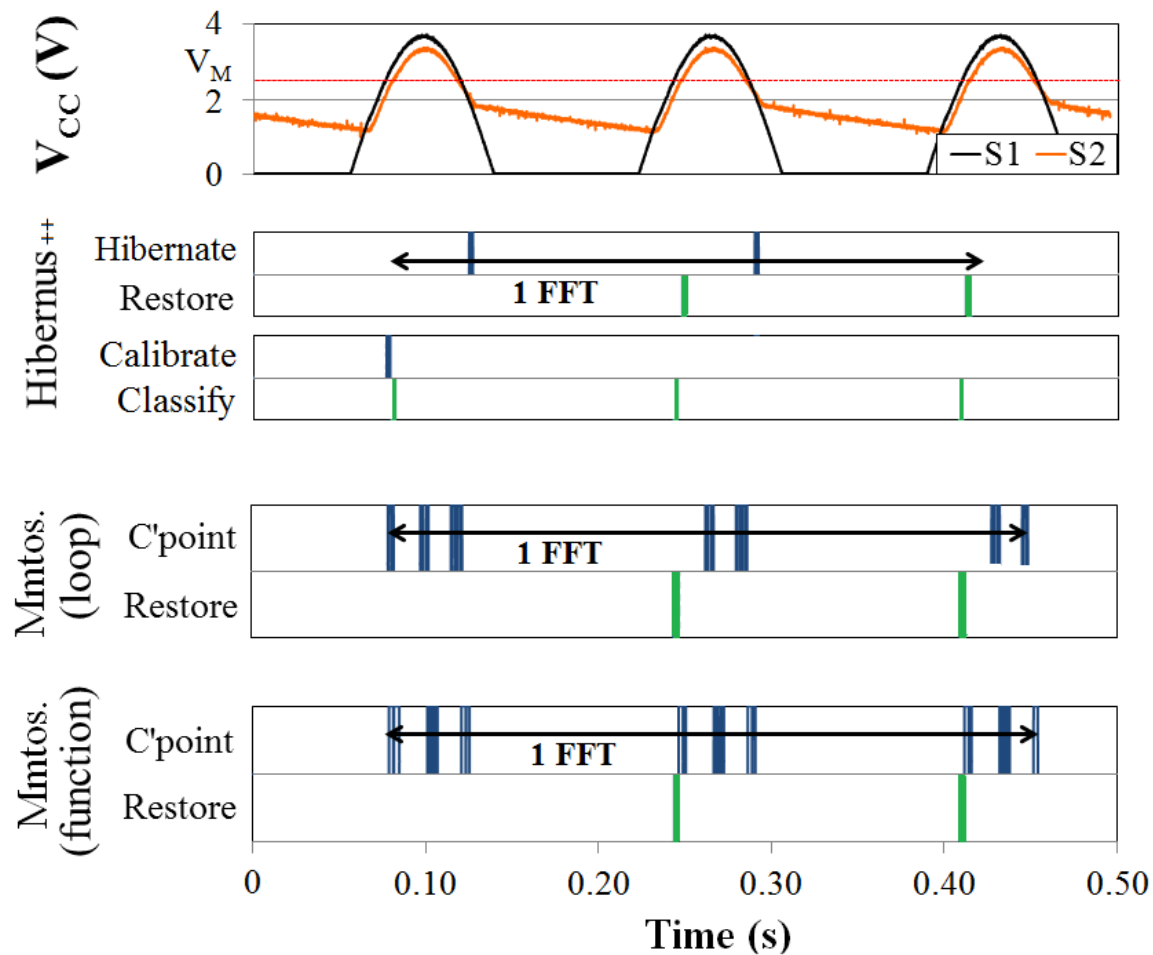


Hibernus++ Results

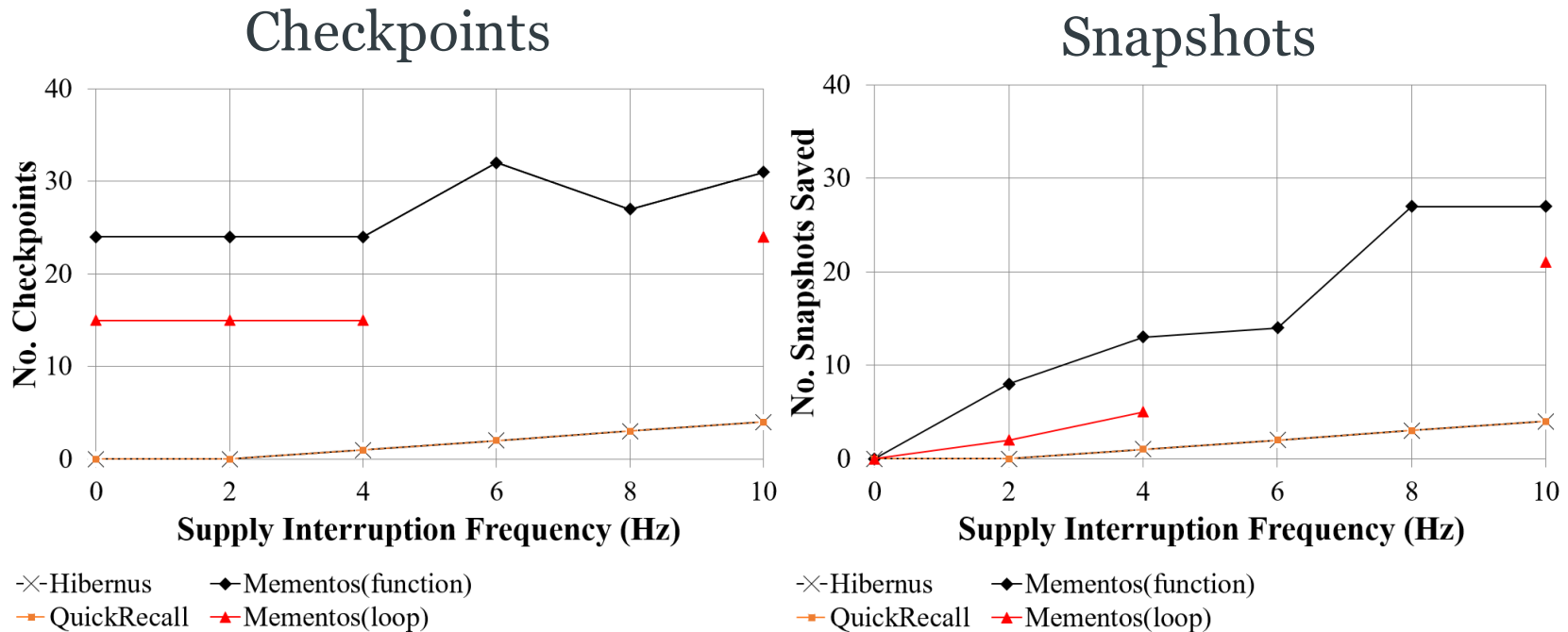


Also go to sleep after hibernating, until restore policy is met again

Comparison



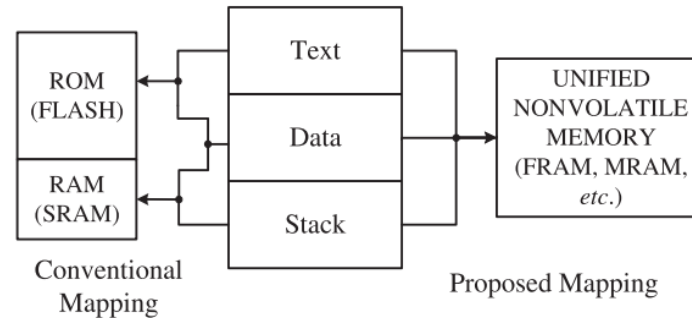
Comparison



- **Hibernus**: checkpoints (and snapshots) every time the voltage drops (i.e. supply interrupted)
- **Mementos**: checkpoints depending on design-/compile-time placement heuristics, and snapshots if a checkpoint occurs AND $V_{CC} < V_{min}$

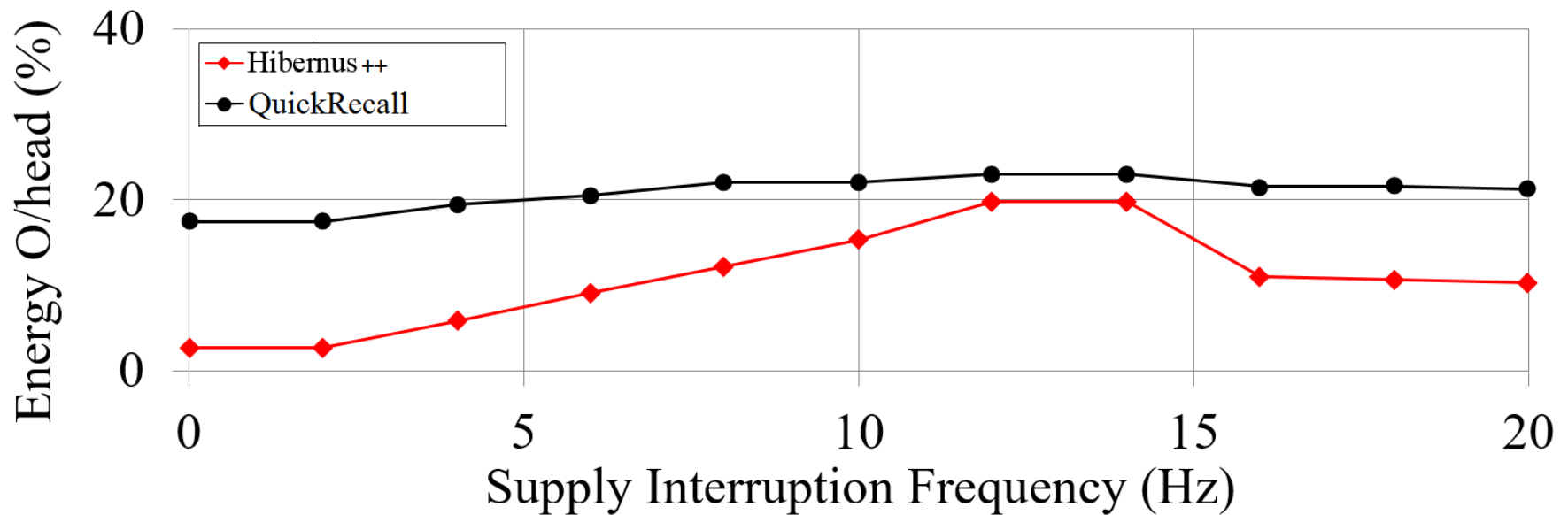
QuickRecall

- Takes advantage of a unified memory system
 - Data + program memory is always in NVM



- Therefore, a snapshot only transfer registers to NVM
 - Elegant solution (+ likewise with NVPs)
 - Much quicker
 - *NVM typically consumes more power...*

Hibernus++ vs Quickrecall



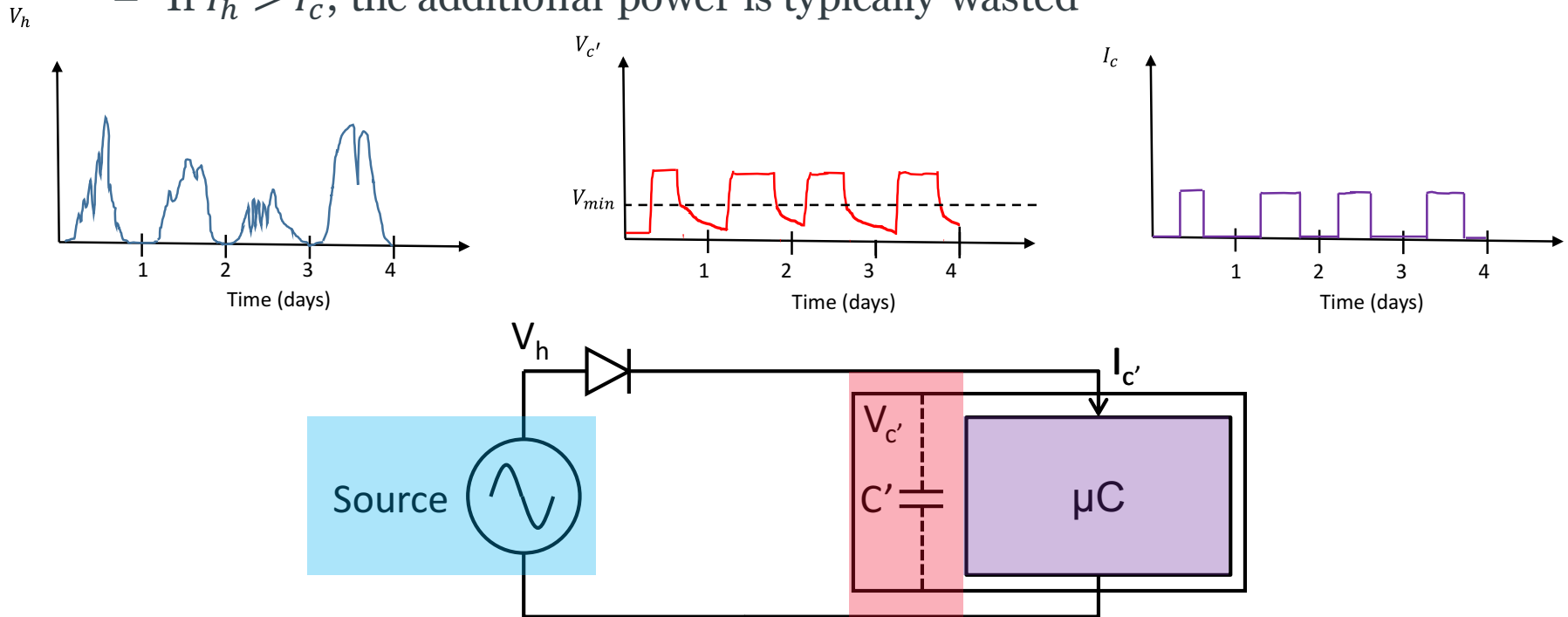
Benefits of Hibernus++

Decoupling capacitance ΣC (μF)	Hibernus			QuickRecall			Hibernus++			
	N. Restore	N. Hibern.	Total Time (ms)	N. Restore	N. C'point	Total Time (ms)	N. Restore	N. Hibern.	Total Time (ms)	V_H (V)
10	-	-	-	-	-	-	2	2	395.2	2.03
20	2	2	376.3	2	2	370.1	2	2	389.4	1.97
30	2	2	376.1	2	2	370.0	1	1	243.7	1.93
40	2	2	376.0	2	2	369.9	1	1	238.9	1.91

Using a voltage input of 3V @ 6Hz

Transient Computing

- Hibernus (and other techniques) are *on* or *off*
 - If $I_h < I_c$, the system hibernates
 - If $I_h > I_c$, the additional power is typically wasted



- Use adaptive operation, like energy-neutral computing?

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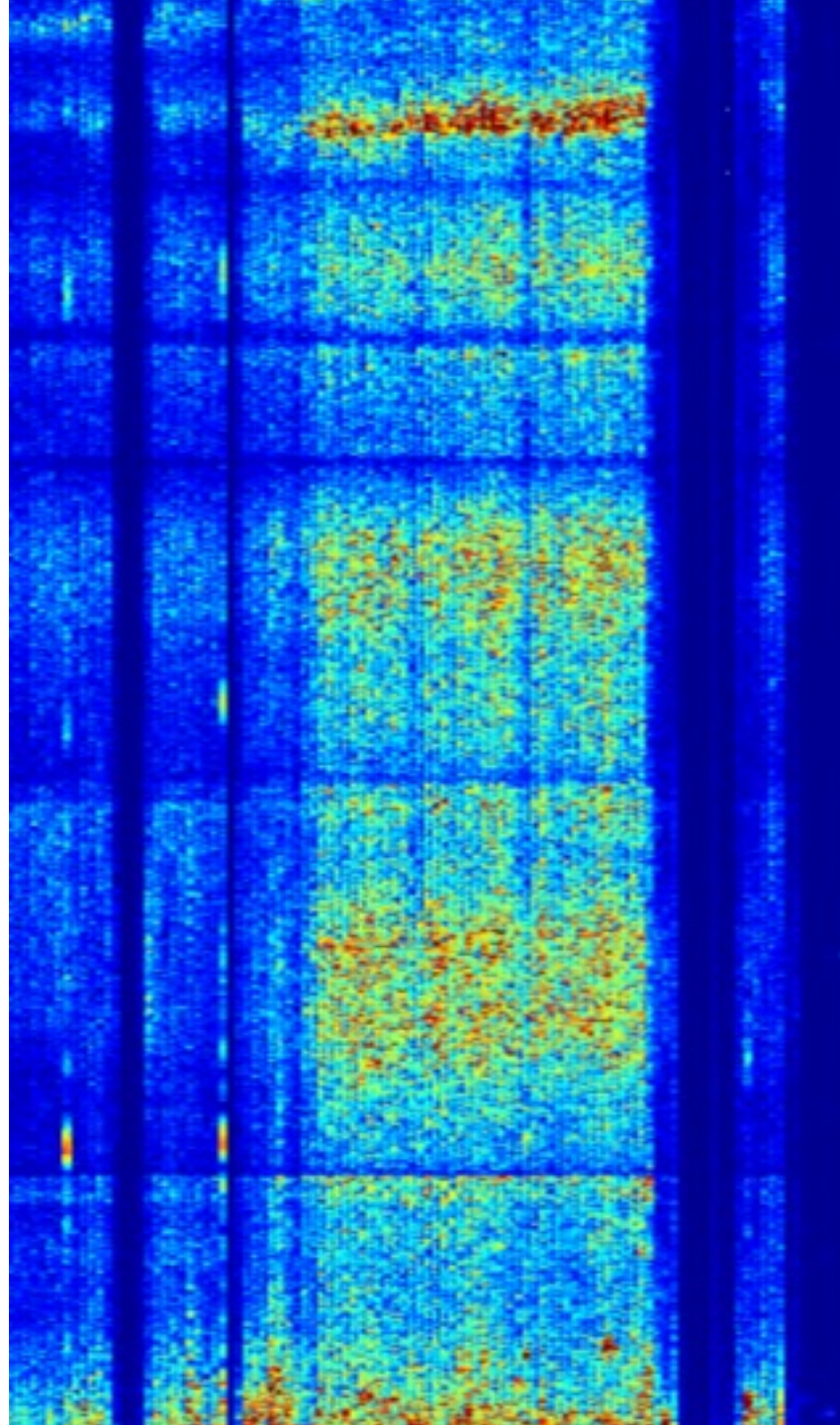
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- **Transient** Computing

Computation when power is available

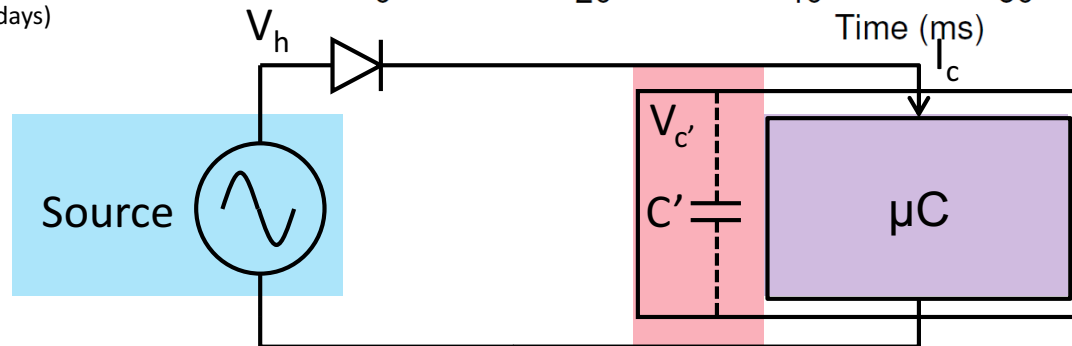
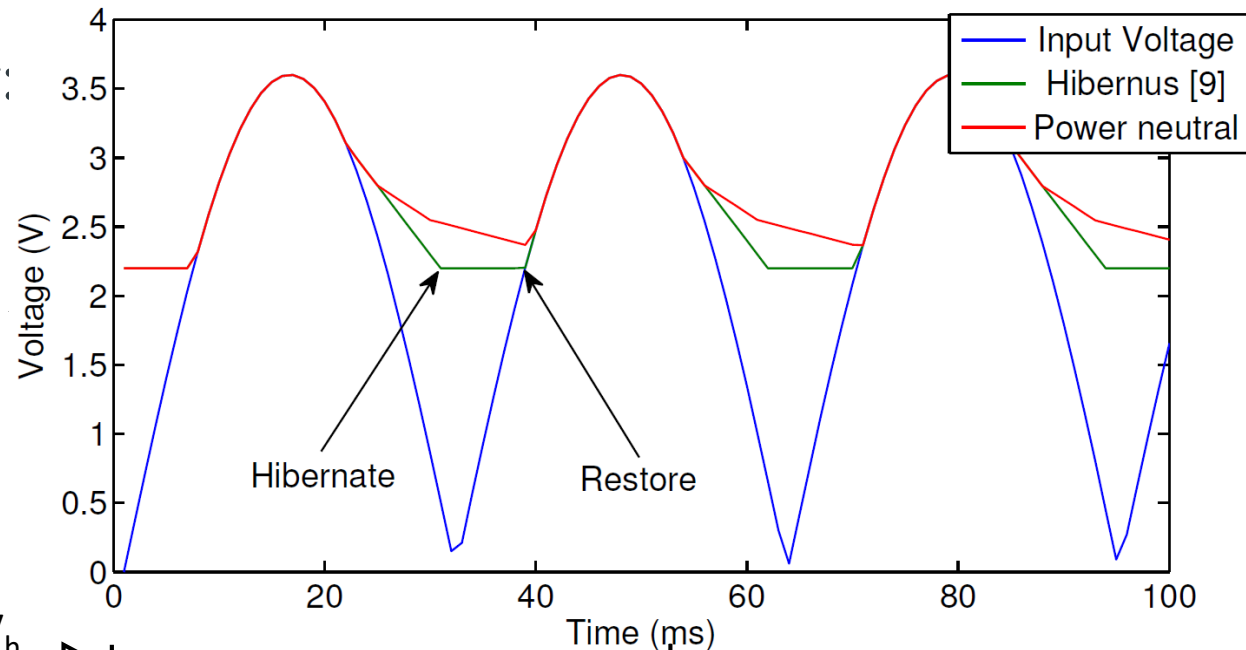
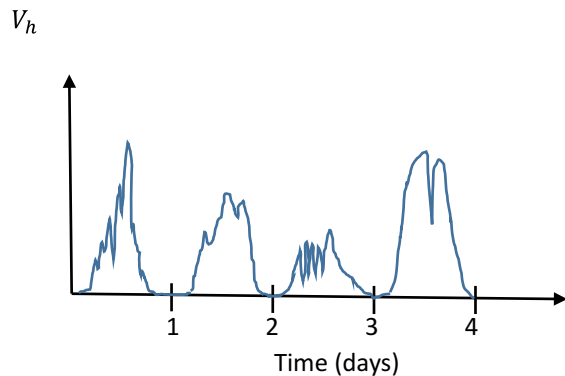
- **Power-Neutral** Computing

Adaptive computation when power is available



Power-Neutral Computing

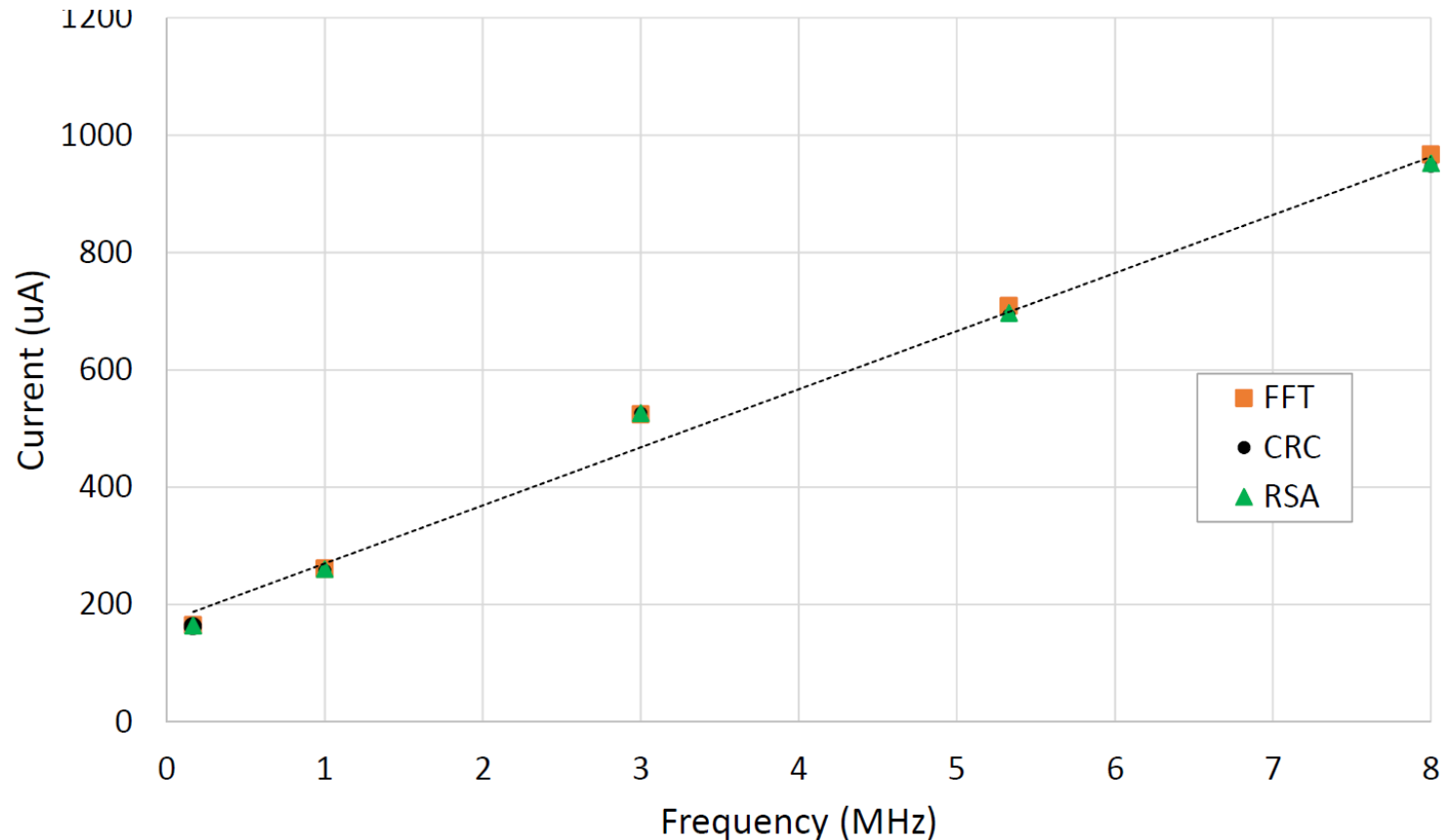
- Energy Neutrality:
- Power Neutrality:



$$\lim_{c' \rightarrow 0} \frac{P_h(t)}{P_c(t)} = 1 \quad \text{or, as } C' \text{ tends to zero, } P_{\text{harvest}}(t) = P_{\text{consume}}(t)$$

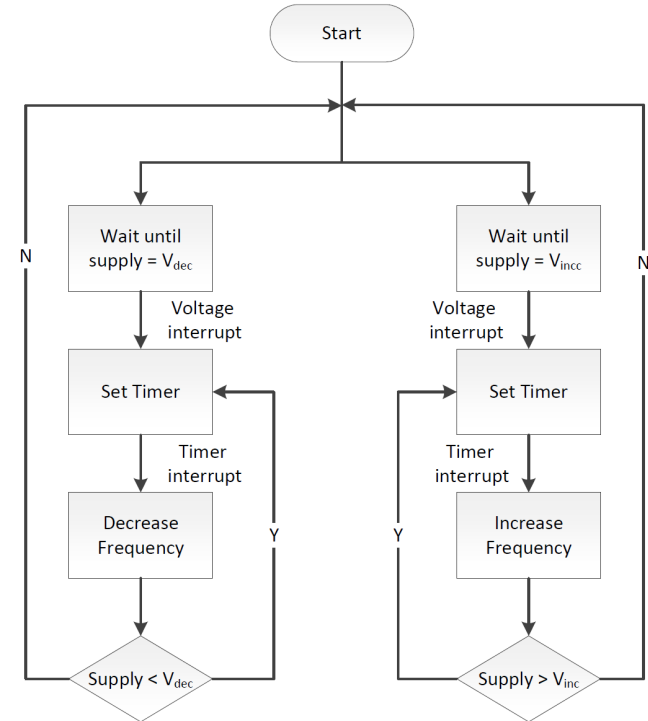
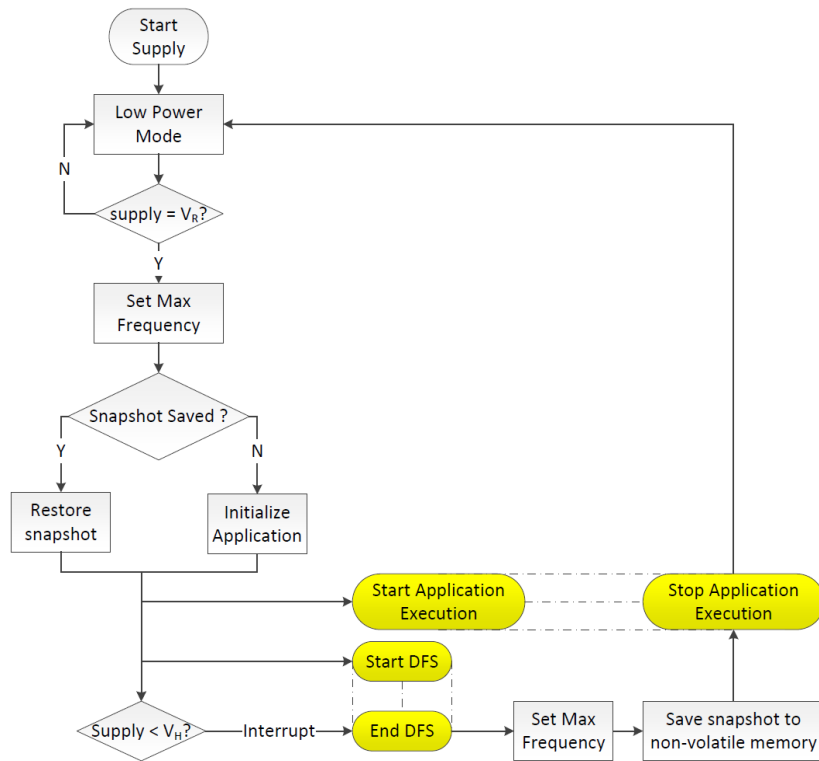
Dynamic Frequency Scaling (DFS)

- On an MSP430

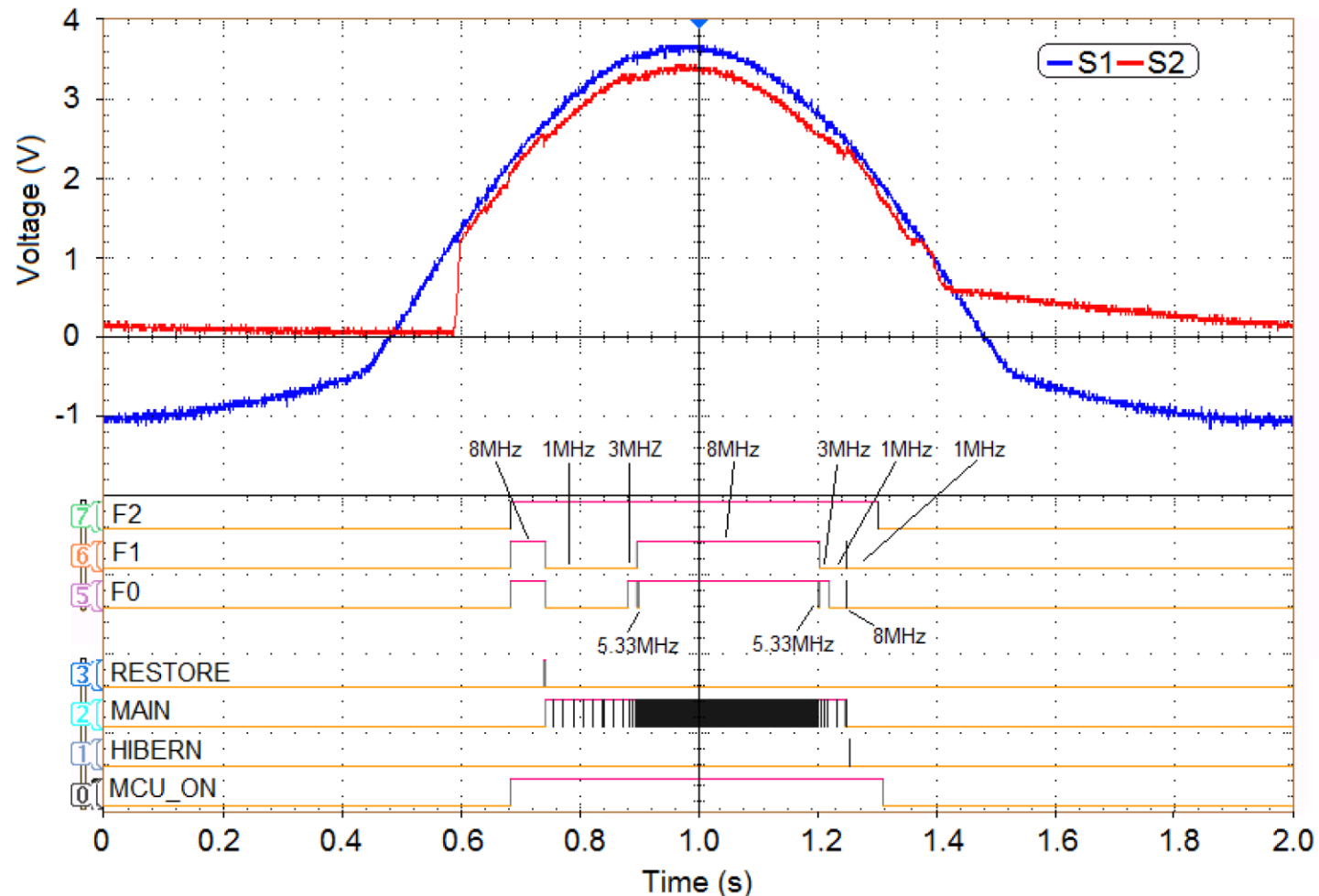


Hibernus with Graceful Degradation

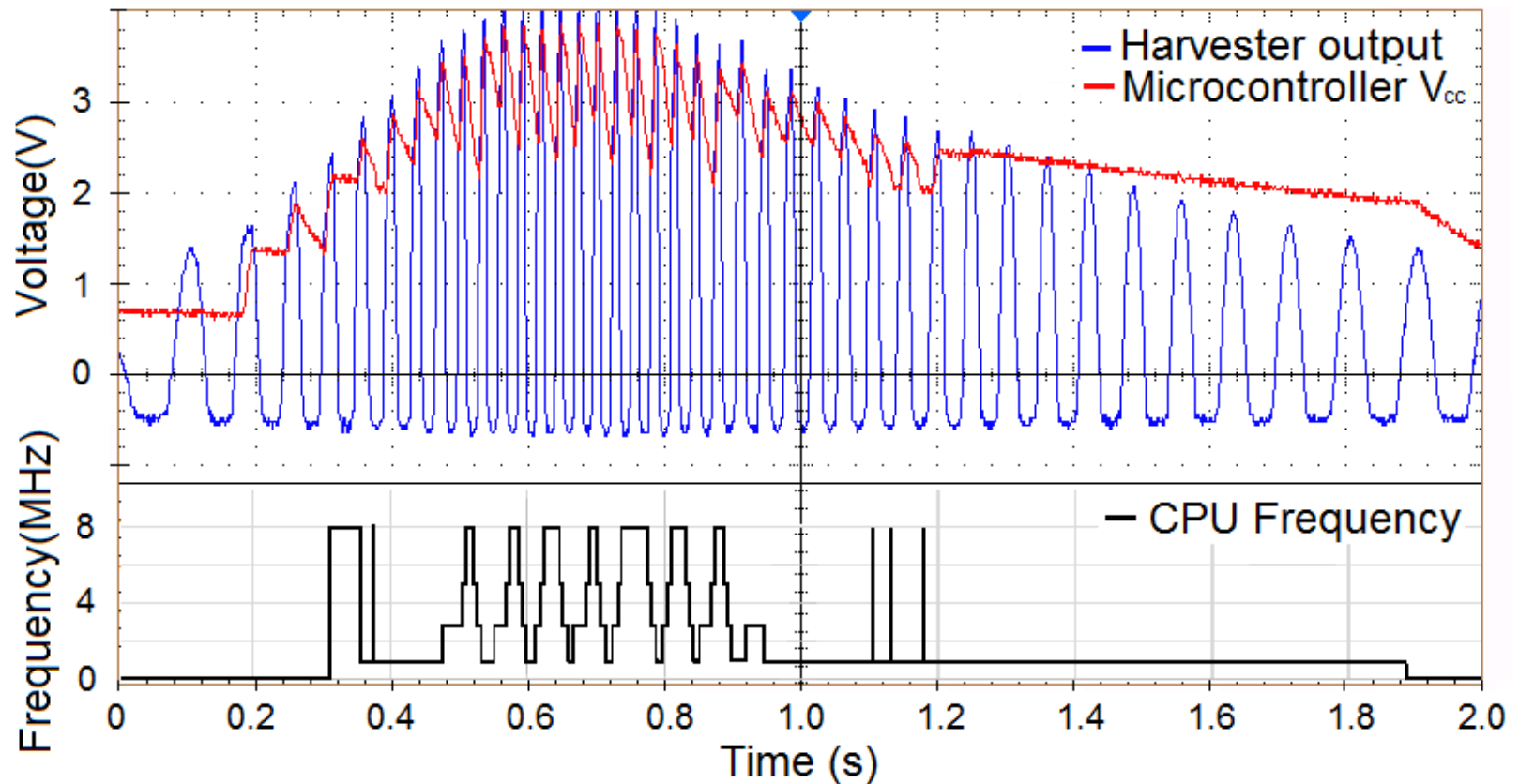
1. Attempts to degrade performance to match source power
2. If it's unable, the system hibernates as previous



Results (Response to Sine Wave)



Results (Response to Wind Turbine)



Power Neutral Benefits

- Total execution from different constant current sources

Application	Current (μA)	Existing System [19]		Power-Neutral System	
		# Hibernate	Time (ms)	# Hibernate	Time (ms)
FFT	200	18	1960	12	1551
	400	13	940	0	608
	600	9	306	0	286
	800	5	202	0	197
CRC	200	5	407	1	338
	400	2	206	0	175.2

Conclusions

a paradigm shift?

Energy-Harvesting Systems

Operating from harvested energy

A lot of potential, particularly in specific application domains

A lot of challenges still to overcome

Inherently different to battery or mains powered systems

Energy-Neutral Computing

Buffering energy for a battery-like supply

Great, for lots of scenarios

Increases size, volume, cost etc

Over-engineered [evolution not revolution]?

Transient Computing

Computation when power is available

Re-thinking the way we design EH systems

But need to rethink the whole system

- *Peripherals*
- *Sensors*
- *Radio communications*
- *The application!*

Power-Neutral Computing

Adaptive computation when power is available

Complementary to transient computing

Need to get better power-proportionality



Thank you!

Any Questions?

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