Micro-Raman Measurement of Bending Stresses in Micromachined Silicon Flexures

V. T. Srikanth, Anna K. Swan, M. Selim Unlu, Senior Member, IEEE, Bennett B. Goldberg, and S. Mark Spearing, Member, ASME

Abstract—Micron-scale characterization of mechanical stresses is essential for the successful design and operation of many micromachined devices. Here we report the use of Raman spectroscopy to measure the bending stresses in deep reactive-ion etched silicon flexures with a stress resolution of ~10 MPa and spatial resolution of ~1 μm. The accuracy of the technique, as assessed by comparison to analytical and finite-element models of the deformation, is conservatively estimated to be 25 MPa. Implications for the use of this technique in microsystems design are discussed.

Index Terms—Microelectromechanical systems (MEMS), micro-Raman, reliability, stress.

I. INTRODUCTION

MICROELECTROMECHANICAL systems (MEMS) can be subjected to mechanical loads during fabrication [1], deployment [2] and operation [3] and are susceptible to failure due to fracture [3], buckling [4], and stiction [5]. Assessment of the reliability of micromachined structures requires accurate characterization of mechanical stresses. Direct measurement of local stresses must often accompany analytical or numerical models for deformation due to imprecise knowledge of materials properties, inability to predict the magnitudes of intrinsic residual stresses, and to assist in microsystems design [6].

Several techniques now exist for measuring stresses in microscale structures. The ones commonly used in MEMS design include wafer curvature measurement, fabrication of passive strain sensors, bulge tests, bending tests, and resonant tests [7]. These techniques are primarily used to characterize residual stresses in thin-film structures with a lateral spatial resolution typically exceeding tens of microns.

The increasing range of applications for MEMS, especially in power generation and propulsion [8], has led to growing interest in structures with critical dimensions in the range 0.1 to 10 mm. The accuracy of the technique, as assessed by comparison to analytical and finite-element models of the deformation, is conservatively estimated to be 25 MPa. Implications for the use of this technique in microsystems design are discussed.

Consider, for example, the fluidic package of recently developed silicon microrocket and microengine devices that consists of metal tubes joined to silicon structures using glass seals. Numerical analysis and observations of brittle fracture indicate large stresses, with significant gradients over micron distances, in this composite structure [9]. The existing techniques cannot readily be used to measure such stresses.

There is a clear need for new experimental techniques capable of characterizing residual and applied stresses with micron spatial resolution in micromachined structures. A possible candidate is micro-Raman spectroscopy. It is well known that spectroscopy can be used to characterize stresses with micron spatial resolution in macroscale structures and silicon microelectronic devices [10]–[28]. The few existing spectroscopic characterization studies of MEMS [29]–[33] do not comprehensively evaluate the utility and limitations of this technique in microsystems design. In this paper, we present an evaluation of micro-Raman stress measurements by characterizing the bending stresses in micromachined single-crystal silicon flexures.

II. FABRICATION OF SILICON FLEXURES

The flexures are monolithic single-crystal silicon structures fabricated using a single-mask deep reactive-ion etching process (see Fig. 1). Each flexure is 3000 μm long, 480 μm wide, and the radius of curvature of the fillet at the root is 65 μm. The cross section of the flexures is not perfectly rectangular: the top surface is 150 μm thick, while the thickness of the bottom surface varies between 120 and 130 μm. All the measurements and

Fig. 1. Scanning electron micrograph of deep reactive-ion etched single-crystal silicon flexures. The scale bar represents 1 mm.

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calculations reported in this paper refer to stresses in the vicinity of the top surface.

The starting material for fabrication was a double-polished, (1,0,0)-oriented, single-crystal silicon wafer. One surface was coated with photoresist AZ4620 spun to a speed of 4000 rpm to achieve a final thickness of \( \sim 10 \mu m \). After photolithography and development, the patterned photoresist served as a masking material during the etching of the silicon substrate. Deep-reactive-ion etching was performed in a Surface Technology Systems inductively coupled plasma reactor, with alternating cycles of reactive-ion etching in a SF\(_6\) plasma and polymer deposition from a CF\(_4\) plasma. The etch rate was \( \sim 2.2 \mu m/\text{min} \) and the selectivity of silicon to photoresist approximately 70:1 [34]. The unetched photoresist was subsequently stripped in oxygen plasma.

After fabrication, a 1 mm diameter silicon sphere was inserted between the tips of two adjacent flexures. The deflections of the tip \( \delta \) of the flexures were measured to be 69.5 \( \mu m \) and 87 \( \mu m \), respectively. The error in the measurement of \( \delta \) is estimated to be \( \sim 1 \mu m (\pm 1.5\%) \). Care was taken to avoid torsional loads during the loading process.

### III. MODELS FOR MECHANICAL DEFORMATION

#### A. Euler–Bernoulli Beam

As a first approximation, we model each flexure as an Euler–Bernoulli beam of uniform rectangular cross-section of length \( L \), width \( b \), thickness \( h \), and tip deflection \( \delta \), as shown in Fig. 2. This implies the following set of assumptions [35]: 1) plane sections remain plane; 2) the beam is initially straight; 3) the beam is homogeneous and perfectly elastic; 4) the flexure deforms in pure bending; and 5) Poisson contraction (or expansion) is not constrained. This last assumption is valid for narrow beams \((b < 5h)\) and because the Poisson ratio of silicon for the orientation under consideration is only 0.064 [36]. The choice of single-crystal silicon as the starting material ensures that the flexures are not subjected to any residual stresses.

The theory of small deformations is valid since \( L > 20h \) and \( L > 40\delta \). When the flexure is deformed in pure bending, we expect a uniaxial stress \( \sigma_{xx} \) that is tensile at the surface \( z = h \), compressive at the surface \( z = 0 \), and zero at \( z = (h/2) \). All other stress components are identically zero. The spatial variation of \( \sigma_{xx} \) is then given by [35]

\[
\sigma_{xx}(x, z) = \frac{3E\delta h}{2L^3}(L-x) \left[-1 + \frac{2z}{h}\right].
\]

The value of the Young’s modulus \( E \) along the \([1,1,0]\)-direction in the \((0,0,1)\)-plane of silicon is used in (1) to match the crystallography of the structure under consideration. This value has been estimated to be 168.9 GPa [36].

Equation (1) is invalid in a region of order \( h \) in the vicinity of the root as a consequence of Saint-Venant’s principle [35]. The assumptions of plane sections remaining plane, and of uniaxial stress distribution, are violated in this region due to the finite compliance of the supporting silicon structure and any stress concentrations at the fillet. The stress components \( \sigma_{zz} \) and \( \sigma_{xz} \) assume nonzero values at the root. In order to take these effects into consideration, numerical analysis was performed using the method of finite elements.

#### B. Finite-Element Analysis

The deformation of the flexure was analyzed using a general-purpose finite-element solver (ABAQUS [37]). The cross section of the flexure was assumed to be rectangular and a two-dimensional (2-D) model was created using four-node plane stress quadrilateral elements. A portion of the supporting silicon structure was also meshed to account for any support compliance (see Fig. 3). Clamped boundary conditions were imposed on the end of the support. Silicon was modeled as an isotropic solid \((E = 169 \text{ GPa} \) and \( \nu = 0.07 \)) and a total of 26 520 elements were employed in the mesh.

The tip of the beam was subjected to static displacements of 69.5 \( \mu m \) and 87 \( \mu m \) by applying appropriate point forces. The quality of the mesh was verified by first analyzing the stresses without any support compliance. The normal stress, \( \sigma_{xx} \), matched (1) to \( \sim 3\% \). With the same mesh density, but with the addition of the support structure, the values of \( \sigma_{xx} \) matched (1) to \( \sim 7\% \), indicating only a modest support compliance in this structure. The stresses \( \sigma_{zz} \) and \( \sigma_{xz} \) were found to be localized at the root and assume nonzero values only on the domain \( 0 < x < 100 \mu m \).

#### C. The Strain Tensor

The analysis of the previous sections refers to a coordinate system with unit vectors parallel to \([1,1,0] \), \([-1,1,0] \) and \([0,0,1] \), such that \( \sigma_{xx} \) is parallel to \([1,1,0] \). The use of the crystal coordinates, with unit vectors parallel to \([1,0,0] \), \([0,1,0] \), and \([0,0,1] \), is more convenient in spectroscopic...
TABLE I

<table>
<thead>
<tr>
<th>Property</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$S_{11}$</td>
<td>7.68 TPa$^{-1}$</td>
</tr>
<tr>
<td>$S_{12}$</td>
<td>-2.14 TPa$^{-1}$</td>
</tr>
<tr>
<td>$S_{44}$</td>
<td>12.6 TPa$^{-1}$</td>
</tr>
</tbody>
</table>

analysis. A simple coordinate transformation results in the following stress ($\sigma_{ij}$) and strain ($\varepsilon_{ij}$) tensors in the crystal coordinate system [38]

$\sigma_{ij} = \begin{bmatrix}
0.5\sigma_{xx} & 0.5\sigma_{xx} & 0 \\
0.5\sigma_{xx} & 0.5\sigma_{xx} & 0 \\
0 & 0 & 0
\end{bmatrix}$

$\varepsilon_{ij} = \begin{bmatrix}
\frac{(S_{11}+S_{12})}{2}\sigma_{xx} & \frac{(S_{11}+S_{12})}{2}\sigma_{xx} & 0 \\
\frac{S_{44}\sigma_{xx}}{2} & \frac{S_{44}\sigma_{xx}}{2} & 0 \\
0 & 0 & S_{12}\sigma_{xx}
\end{bmatrix}$

where $S_{11}$, $S_{12}$, and $S_{44}$ are elements of the compliance tensor of silicon (see Table I).

IV. RAMAN SPECTROSCOPY: THEORY

The phenomenon of Raman scattering, and the effects of mechanical stress on the Raman spectrum of single-crystal silicon, have been extensively studied and documented [10]–[26]. The principal results pertinent to the analysis of the flexure are summarized below.

Monochromatic radiation that is incident on the surface of a solid can, in general, undergo transmission, absorption, and scattering. In Stokes–Raman scattering the incident photons couple with phonon-induced changes in the polarizability of the solid, causing the scattered photons to lose a quantum of lattice energy or phonon relative to the incident photons. Conservation of momentum dictates that only phonons close to the $\Gamma$-point of the Brillouin zone are excited in such processes. Similarly, conservation of energy implies that the frequency ($\omega$) of the excited phonons is given by [10]

$\omega = \frac{1}{\lambda_i} - \frac{1}{\lambda_s}$

where $\lambda_i$ and $\lambda_s$ are the wavelength of the incident and scattered radiation, respectively. The quantity $\omega$ is called the Raman shift and is typically reported in units of cm$^{-1}$. The Raman spectrum, then, is a graph of the scattered intensity as a function of the Raman shift and contains information about the physical and chemical characteristics of the solid.

A schematic illustration of spectroscopy in the backscattering geometry is shown in Fig. 4. Stress-free single-crystal silicon has three degenerate Raman-active optical phonon modes: two transverse and one longitudinal. When the incident and scattered radiation are both parallel to [0, 0, 1], the transverse modes are polarized along [1, 0, 0] and [0, 1, 0], respectively, and the longitudinal mode is polarized along [0, 0, 1]. The scattering efficiency, $I$, can be expressed as [19]

$I = A \sum_j |e_i^t \cdot R_j \cdot e_s|^2$  \quad j = 1, 2, 3,

Here $A$ is a constant, $e_i$ and $e_s$ are the polarization vectors of the incident and scattered light, respectively, the superscript $t$ denotes the transposed vector, and $R_j (j = 1, 2, 3)$ are the Raman polarizability tensors. These second-rank tensors are given by [11]

$R_1 = \begin{bmatrix}
0 & 0 & 0 \\
0 & 0 & 1 \\
0 & 1 & 0
\end{bmatrix}$  \quad $R_2 = \begin{bmatrix}
0 & 0 & 0 \\
0 & 0 & 1 \\
1 & 0 & 0
\end{bmatrix}$

$R_3 = \begin{bmatrix}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 0
\end{bmatrix}$

corresponding to the crystallographic directions [1, 0, 0], [0, 1, 0], and [0, 0, 1], respectively. For backscattering from the (0,0,1)-plane (i.e., both $e_i$ and $e_s$ have the form [$\alpha$, $\beta$, 0], with arbitrary $\alpha$ and $\beta$), (4) and (5) together dictate that only the longitudinal mode has a nonzero scattering efficiency. The Raman spectrum consists of a single peak with a Raman shift ($\omega_l$) of $\sim$521 cm$^{-1}$.

In general, the degeneracy of the Raman frequencies is lifted, and the Raman shifts acquire new values ($\omega_j$) for each of the three modes, when silicon is subjected to external mechanical stresses. The change in the Raman shifts ($\Delta\omega$) is given by [18]

$\Delta\omega_j = \omega_j - \omega_l = \frac{\lambda_j}{2\omega_l}$  \quad j = 1, 2, 3
where \(\lambda_j (j = 1, 2, 3)\) are the eigenvalues of the matrix shown in (7) at the bottom of the page. Here, \(p\), \(q\), and \(r\) are the phonon deformation potentials (PDPs) of silicon (see Table II) and \(\varepsilon_{ij}\) are elements of the strain tensor referred to the crystal coordinate system. For the strain tensor given by (2), the eigenvalues of (7) can be readily shown to be

\[
\lambda_1 = \frac{1}{2} \left[ p\sigma_{xx}(S_{11} + S_{12}) + q\sigma_{xx}(S_{11} + 3S_{12}) + r\sigma_{xx}S_{14} \right]
\]
\[
\lambda_2 = \frac{1}{2} \left[ p\sigma_{xx}(S_{11} + S_{12}) + q\sigma_{xx}(S_{11} + 3S_{12}) - r\sigma_{xx}S_{14} \right]
\]
\[
\lambda_3 = \left[ q(S_{11} + S_{12}) + pS_{12} \right] \sigma_{xx}
\]

(8)

corresponding to the eigenvectors \([1, 1, 0], [-1, 1, 0]\) and \([0, 0, 1]\) respectively. The applied stress can also lead to a change in the Raman polarizability tensors. This change is assumed to be a linear combination of the stress-free tensors given by [25]

\[
R_k^\sigma = (n_1)_k R_1 + (n_2)_k R_2 + (n_3)_k R_3 \quad k = 1, 2, 3
\]

(9)

where the superscript \(\sigma\) denotes the stressed-value of the tensor; \((n_1)_k\), \((n_2)_k\), and \((n_3)_k\) are the directional cosines between the \(k\)th eigenvector of (8) and the three stress-free eigenvectors. From (5), (8) and (9), we obtain

\[
R_1^\sigma = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}
\]
\[
R_2^\sigma = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \\ 1 & -1 & 0 \end{pmatrix}
\]
\[
R_3^\sigma = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}
\]

(10)

As before, for arbitrary \(\varepsilon_1\) and \(\varepsilon_2\), propagating along \([0, 0, 1]\), the Raman spectrum contains a single peak corresponding to the eigenvector \([0, 0, 1]\). From (8), therefore, the change in the Raman shift is simply

\[
\Delta\omega = \frac{\lambda_3}{2\omega_0} = q(S_{11} + S_{12}) + pS_{12} \sigma_{xx}
\]

(11)

For \(\omega_0 = 521\) cm\(^{-1}\), and using the phonon deformation potentials of Anastassakis \textit{et al.} [16], we obtain

\[
\sigma_{xx} \equiv -43.4 \Delta\omega
\]

(12)

and using the phonon deformation potentials of Chandrasekhar \textit{et al.} [15], we obtain

\[
\sigma_{xx} \equiv -51.8 \Delta\omega
\]

(13)

In both (12) and (13), \(\sigma_{xx}\) is expressed in units of megapascals and \(\Delta\omega\) in cm\(^{-1}\).

Corresponding to any measured change in the Raman shift, therefore, is a uniquely determined value of the local uniaxial stress in the flexure. The locality of the measurement is determined by the spot size, which is 1.3 \(\mu\)m in our measurements.

\section*{V. RAMAN SPECTROSCOPY: MEASUREMENTS}

Raman spectroscopy was performed using a commercial Renishaw spectrometer (model 1000 B) in the backscattering configuration. The spectral excitation was produced by utilizing the 514 nm line of an argon-ion laser. The incident light, polarized parallel to the \([-1, 1, 0]\)-direction, was focused on the \((0,0,1)\)-surface of the structure using a 50X microscope objective, and the scattered light was collected using the same objective, as illustrated in Fig. 4. The direction of polarization of the scattered light was not analyzed. The spot size of the incident beam is estimated to be 1.3 \(\mu\)m, and the sampling depth is \(0.8 \mu\)m, based on the penetration distance of 514 nm light in silicon [10]. Each spectrum therefore represents a stress measurement from a volume \(\sim 1 \mu\)m\(^3\) of silicon.

All the measurements were performed at room temperature (300 K). The incident power was chosen to be 2 mW, corresponding to a power density of 300 kW/cm\(^2\), to minimize local heating due to the laser probe. The time for collecting a single spectrum was between 2 and 4 s. Fig. 5 shows the Raman spectrum of stress-free single-crystal silicon. The peak frequency \(\omega_0\) was determined to be 520.9\(\pm\)0.1 cm\(^{-1}\) by fitting the intensity to a Lorentzian function [39]. The coefficient of determination of the fit was 0.99 and the full width at half maximum intensity was \(\sim 3.5\) cm\(^{-1}\). Fig. 6 shows the Raman shifts obtained from a line scan on stress-free silicon. The spectral resolution is estimated to be \(\pm 0.02\) cm\(^{-1}\) from this measurement. This corresponds to a stress resolution of \(\sim 10\) MPa from (12) and (13).

The bending stresses were characterized by performing line scans across the thickness at several locations along the axis.
Fig. 5. The raman spectrum of stress-free single-crystal silicon.

Fig. 6. Raman shifts determined at several locations on a stress-free silicon wafer from a line scan. The spectral resolution of 0.02 cm⁻¹ corresponds to a stress resolution of ∼10 MPa.

Fig. 7. Raman shift measured as a function of position along thickness using a line scan. (For this scan, ω₀ = 521.01 cm⁻¹).

Fig. 8. Line scans of the same location, using different stepping distances, demonstrate that the measurements are repeatable to ±0.02 cm⁻¹.

The measured changes in the Raman shift were converted into stress values using (12) and (13). The stress profiles at distances of 600 μm and 1200 μm are shown in Figs. 9 and 10, respectively. The predictions of the Euler–Bernoulli model and finite-element models are also shown. The stress values obtained using the phonon deformation potentials of Anastassakis et al. [16] provide a consistently better match to model predictions.

VI. DISCUSSION

A. Resolution and Accuracy

Fig. 6 indicates that the spectral resolution of the measurement is 0.02 cm⁻¹. From (12) and (13), this corresponds to a stress resolution of ∼10 MPa and represents the smallest relative stress difference that can be measured in our experiments. The determination of absolute stress value depends also on the knowledge of the elastic constants and phonon deformation potentials of silicon.

The elastic constants of silicon have been measured to ±0.25% [40]; multiple, independent measurements confirm the values of Table I to be accurate. On the other hand, the phonon deformation potentials are known only to ±3% and two independent measurements report values that differ, on average, by about 20% (see Table II). Chandrasekhar, Renucci, and Cardona [15] measured one set using backscattering experiments, while Anastassakis, Cantarero and Cardona [16] revised these values using transmission spectroscopy. The latter values are expected to be more accurate since they exclude any possible surface relaxation effects. Figs. 9 and 10 confirm this expectation.

Ideally, the accuracy of our measurements should be assessed by comparison to results from an alternate, well-established, technique. Lacking any convenient such alternative, we assess the accuracy by comparing the measurements to the predictions of finite element analysis. Using the phonon deformation potentials of Anastassakis et al. [16], the spectroscopic measurements...
match the analysis to 10 MPa in compression but overestimate by ∼25 MPa in tension. The reason for this mild asymmetry is unclear at present. We have considered, and discounted, the following possibilities.

First, the Raman shift is known to be sensitive to ambient conditions. The reference value, \( \omega_D \), was measured prior to every scan to account for such effects. There was no systematic drift during the line scans as demonstrated by Fig. 6. Second, we consider errors due to specimen orientation such that a scan along the \( z \)-axis was also a scan along the \( x \)-axis. An error of 15 MPa in stress measurement requires a misalignment greater than 30°. This is unreasonable since we estimate any such alignment errors to be less than 2° in our setup. Third, the scan direction (i.e., the \( z \)-axis of Fig. 2) is not exactly perpendicular to the neutral axis due to the deformation of the structure. It is simple to show that this geometric effect results in a correction less than 1 MPa, and can be neglected.

Fourth, the cross-section of the flexure is trapezoidal, and not rectangular, as mentioned earlier. Microscopic examinations of nominally identical flexures tested to fracture in bending experiments indicated that the cross-section is still symmetric about the plane \( z = h/2 \). Further, the position of zero stress in Figs. 9 and 10 coincides with the nominal position of the neutral axis \( (z = 75 \, \mu m) \). We conclude that the shape is not solely responsible for the observed asymmetry.

Fifth, it is possible that the flexure suffered unintentional torsional loads, or out-of-plane bending, during deformation. Again, the coincidence of the zero-stress locations with \( z = h/2 \) is an argument against any such additional deformation. It must be noted that, for the crystallography and scattering geometry under consideration, some stress states (such as pure shear) will induce no change in the Raman shift of the longitudinal mode, and cannot be ruled out based purely on the position of the neutral axis. For the same reason, however, such stresses cannot account for the observed asymmetry in tension and compression.

Finally, the structures were prepared using deep reactive-ion etching and it is possible that processing-induced residual stresses are present in the flexures. Any such stresses are expected to occur at the beam edges and should affect the tensile and compressive regions to the same extent. No significant changes of the Raman shift were detected during measurements of undeformed beams. Residual stresses can therefore be excluded from consideration.

We conclude for the present that the accuracy of our measurement lies in the range 10 MPa to 25 MPa. The expectation is that future measurements will result in narrower bounds. It is worth emphasizing that even the conservative estimate of 25 MPa is comparable to the accuracy achieved using other methods of microscale stress measurement and is sufficient for applications in microsystem design.

B. Complex Stress States

The interpretation of stress fields using spectroscopic data requires careful identification of the form of the stress tensor. This is generally true of other microscale stress measurement techniques [7]. Significant errors can occur when such identification is incorrectly made.

As an illustrative example, consider the stresses at the root of the flexure. The finite element analysis indicates normal (\( \sigma_{xx} \) and \( \sigma_{zz} \)) and shear (\( \sigma_{xz} \)) components with magnitudes exceeding 100 MPa. If, instead, the stress field is assumed to be uniaxial and the spectroscopic data converted using (12), the resultant errors can exceed 100 MPa as shown in Fig. 11.

Even when correctly identified, it is nontrivial to extract multiple stress components from backscattering measurements of Raman shifts. One possibility is to perform self-consistent numerical and spectroscopic analysis to deduce the stress tensor [17]. The other is to perform additional spectroscopic measurements involving the polarizations of, and the relative angles between, the incident and scattered radiation. Such studies are topics of current research [25], [26], [41]. The use of time-resolved spectroscopy to measure dynamic stresses in rotating micromachinery is also being explored.

Many materials including zirconia [21], silicon carbide [22], aluminum nitride [23], and diamond [24] are Raman active...
and can be characterized using spectroscopy. Extensions to polycrystalline materials have also been attempted, although confinement effects due to the finite size of the grains can lead to asymmetric peak broadening and complicate the extraction of stress information from such measurements [27], [28], [31]. Many common metals are typically not Raman active and cannot directly be characterized using spectroscopy.

VII. IMPLICATIONS FOR USE IN MEMS DESIGN

The preceding sections demonstrate that Raman spectroscopy can be used to characterize simple stress states in micromachined single-crystal silicon structures with micrometer spatial resolution. Previously measured values of elastic constants and phonon deformation potentials can be used to obtain a stress sensitivity of \(\sim 10 \, \text{MPa}\), which is usually adequate for designing bulk-micromachined devices. The measurements are rapid, nondestructive, and are made using commercially available instruments.

Whereas this combination of attributes is unique among microscale stress measurement techniques, the inability to resolve complex stresses significantly limits the utility of micro-Raman spectroscopy in design. Fig. 11 highlights this observation. The maximum bending stresses, and the sites for nucleation of brittle fracture [34], occur at the root of the silicon flexures. Yet, backscattering micro-Raman measurements are incapable of accurately characterizing these critical stresses.

Until further advances permit tensorial stress analysis, it is expected that spectroscopy will be most effective when used in conjunction with numerical analysis. This is especially true if one parameter, such as the coefficient of thermal expansion (\(\alpha\)) of one material in a composite structure, is unknown. One example of current interest is the design of glass-silicon hermetic seals in the silicon microrocket device mentioned earlier [9]. The sealing process involves a thermal excursion of over 1000 °C; the resultant thermal stresses cannot be accurately calculated since \(\alpha_{\text{glass}}\) is not well characterized. Hence, we are employing parametric finite-element computations to predict the (uniaxial) stresses in silicon using systematically varied values of \(\alpha_{\text{glass}}\). The value that leads to the closest match with spectroscopically measured stresses will be used in further design [42].

The use of spectroscopy to determine optimal processing parameters, such as annealing conditions to minimize intrinsic residual stresses, defines a second category of applications. Because the phonon deformation potentials are sensitive to structural details (grain size; type and concentration of dopants), the values listed in Table II cannot be used. Changes in the Raman shift will have to be calibrated as functions of the applied stress for each specific set of structures of interest [43].

Finally, it is instructive to note that recent progress in x-ray optics has led to the development of another stress measurement technique—scanning X-ray microdiffraction (\(\mu\)SXRD)—that can determine the entire stress tensor, with micrometer spatial resolution, in mono- and polycrystalline specimens [44]. However, the use of \(\mu\)SXRD in microsystem design is limited by access to high quality synchrotron sources.

VIII. CONCLUSION

Micron-scale characterization of mechanical stresses is essential for the reliable operation of many micromachines. The uniaxial bending stresses in a micromachined single-crystal silicon were characterized using Raman spectroscopy. The stress resolution (\(\sim 10 \, \text{MPa}\)) of this technique is comparable, and the spatial resolution (\(\sim 1 \, \mu\text{m}\)) considerably superior, to those of the other commonly used microscale stress measurement methods. The accuracy of the technique, as assessed by comparison to analytical and numerical analysis of the deformation, is conservatively estimated to be 25 MPa. The utility of this technique in microsystem design was discussed.

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REFERENCES

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