

# Opportunities for formal methods in the analysis of pervasive adaptation

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# Conclusion

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  - ▶ True in all realms of human activity: complex artifacts require blueprints of all sorts;
  - ▶ Yet, mysteriously some believe one could design, build, maintain, service, upgrade, evolve, ... systems of the complexity of ecologies just by implementing the right support.  
But to build a house is not sufficient to design good bricks ...
- Without practice, there is no useful formal method.
  - ▶ models conceived in abstract are not abstract models, just cathedrals in the desert.
- Without new tools, there is no realistic formal model of adaptation.
  - ▶ this is a hard concept, that includes research areas big per se that we cannot handle (eg complex systems, emergent behaviour, ...)

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- Formal models cover the entire spectrum of development:
  - ▶ specification, validation, implementation, verification, ...
- Emerging behaviour typical of adaptation needs statements of 'fitness for purpose':
  - ▶ need languages to specify those and techniques to verify them
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- work with changing and unpredictable environments;
- work with lack of relevant information;
- work with tight resource constraints;
- work with internal hypothesis built from observations;
- work by making hypothesis and testing them against observations of the world;
- and, most importantly,  
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**processes**  $\mapsto$  **agents**??

goal-oriented  
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Reject intelligence-based and bio-inspired approaches per se.  
Accept when backed by solid mathematical tools, like eg:  
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Existing approaches: game theory and mechanism design; negotiation (because often the environment is just others like you); evolutionary, probabilistic.

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# Simple Adaptation via Bayesian Learning

The model  $\lambda_\theta$ :

- Each principal  $p$  behaves in each interaction according to a fixed and independent probability  $\theta_p$  of ‘success’ (and therefore  $1 - \theta_p$  of ‘failure’).

The framework:

- Interface (Trust computation algorithm,  $\mathcal{A}$ ):
  - ▶ Input: A sequence  $h = x_1 x_2 \cdots x_n$  for  $n \geq 0$  and  $x_i \in \{\mathbf{s}, \mathbf{f}\}$ .
  - ▶ Output: A probability distribution  $\pi : \{\mathbf{s}, \mathbf{f}\} \rightarrow [0, 1]$ .
- Goal:
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## Trust computation $\mathcal{A}_0$

$$\mathcal{A}_0(\mathbf{s} \mid h) = \frac{N_{\mathbf{s}}(h)}{|h|}$$

$$\mathcal{A}_0(\mathbf{f} \mid h) = \frac{N_{\mathbf{f}}(h)}{|h|}$$

$N_x(h)$  = “number of  $x$ ’s in  $h$ ”

Bayesian analysis inspired by  $\lambda_{\beta}$  model:  $f(\theta \mid \alpha \beta) \propto \theta^{\alpha-1} (1-\theta)^{\beta-1}$

## Properties:

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# Cross entropy

An information-theoretic “distance” on distributions

Cross entropy of distributions  $\mathbf{p}, \mathbf{q} : \{o_1, \dots, o_m\} \rightarrow [0, 1]$ .

$$D(\mathbf{p} \parallel \mathbf{q}) = \sum_{i=1}^m \mathbf{p}(o_i) \cdot \log(\mathbf{p}(o_i)/\mathbf{q}(o_i))$$

It holds  $0 \leq D(\mathbf{p} \parallel \mathbf{q}) \leq \infty$ , and  $D(\mathbf{p} \parallel \mathbf{q}) = 0$  iff  $\mathbf{p} = \mathbf{q}$ .

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# Expected cross entropy

A measure on probabilistic trust algorithms

- Goal of a probabilistic trust algorithm  $\mathcal{A}$ : given a history  $\mathbf{X}$ , approximate a distribution on the outcomes  $\mathcal{O} = \{o_1, \dots, o_m\}$ .
- Different histories  $\mathbf{X}$  result in different output distributions  $\mathcal{A}(\cdot | \mathbf{X})$ .

Expected cross entropy from  $\lambda$  to  $\mathcal{A}$

$$ED^n(\lambda || \mathcal{A}) = \sum_{\mathbf{X} \in \mathcal{O}^n} Prob(\mathbf{X} | \lambda) \cdot D(Prob(\cdot | \mathbf{X} \lambda) || \mathcal{A}(\cdot | \mathbf{X}))$$

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Consider the beta model  $\lambda_\beta$  and the algorithms  $\mathcal{A}_0$  of maximum likelihood (Despotovic et al.) and  $\mathcal{A}_1$  beta (Mui et al.).

## Theorem

If  $\theta = 0$  or  $\theta = 1$  then  $\mathcal{A}_0$  computes the exact distribution, whereas  $\mathcal{A}_1$  does not. That is, for all  $n > 0$  we have:

$$\text{ED}^n(\lambda_\beta \parallel \mathcal{A}_0) = 0 < \text{ED}^n(\lambda_\beta \parallel \mathcal{A}_1)$$

If  $0 < \theta < 1$ , then  $\text{ED}^n(\lambda_\beta \parallel \mathcal{A}_0) = \infty$ , and  $\mathcal{A}_1$  is always better.

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For any  $\theta \in [0, 1]$ ,  $\theta \neq 1/2$  there exists  $\bar{\epsilon} \in [0, \infty)$  that minimises  $\text{ED}^n(\lambda_\beta \parallel \mathcal{A}_\epsilon)$ , simultaneously for all  $n$ .

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That is, unless behaviour is completely unbiased, there exists a unique best  $\mathcal{A}_\epsilon$  algorithm that for all  $n$  outperforms all the others.  
If  $\theta = 1/2$ , the larger the  $\epsilon$ , the better.

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- Algorithm  $\mathcal{A}_0$  is optimal for  $\theta = 0$  and for  $\theta = 1$ .
- Algorithm  $\mathcal{A}_1$  is optimal for  $\theta = \frac{1}{2} \pm \frac{1}{\sqrt{12}}$ .

# A trust model based on event structures

Move from  $O = \{s, f\}$  to complex outcomes

## Interactions and protocols

- At an abstract level, entities in a distributed system interact according to protocols;
- Information about an external entity is just information about (the outcome of) a number of (past) protocol runs with that entity.

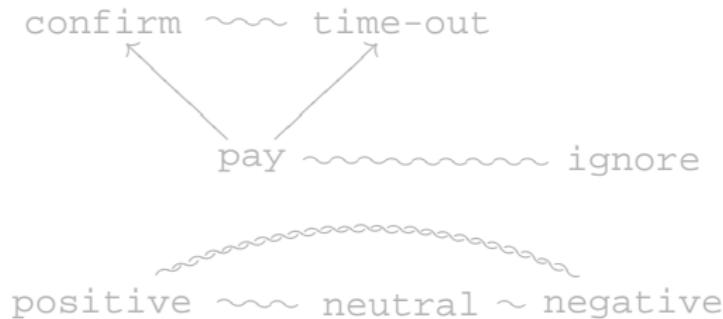
## Events as model of information

- A protocol can be specified as a **concurrent process**, at different levels of abstractions.
- Event structures were invented to give formal semantics to truly concurrent processes, expressing "**causation**" and "**conflict**".

# A model for behavioural information

- $ES = (E, \leq, \#)$ , with  $E$  a set of events,  $\leq$  and  $\#$  relations on  $E$ .
- Information about a session is a finite set of events  $x \subseteq E$ , called a **configuration** (which is ‘conflict-free’ and ‘causally-closed’).
- Information about several interactions is a sequence of outcomes  $h = x_1 x_2 \cdots x_n \in \mathcal{C}_{ES}^*$ , called a **history**.

eBay (simplified) example:

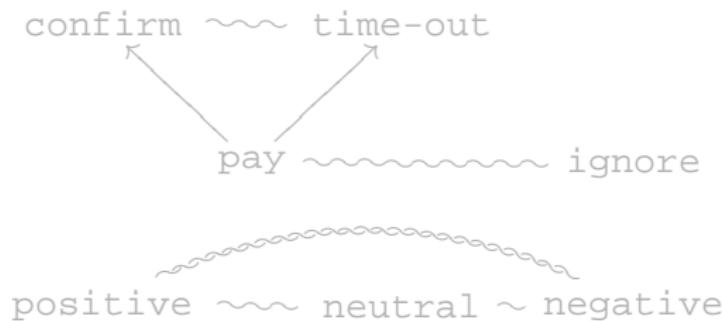


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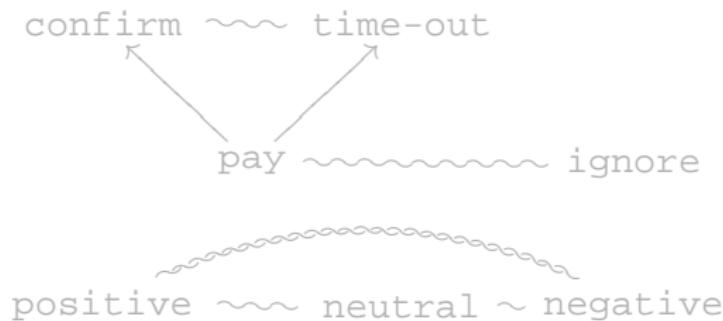


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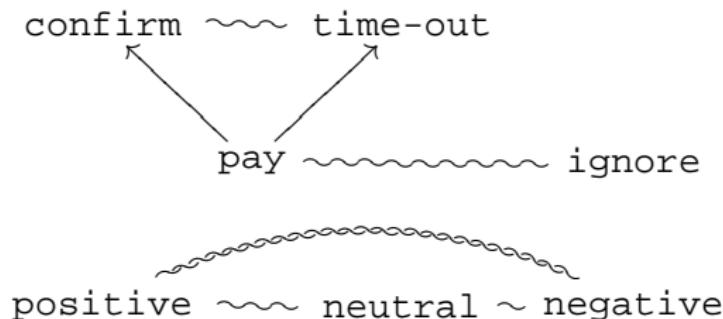


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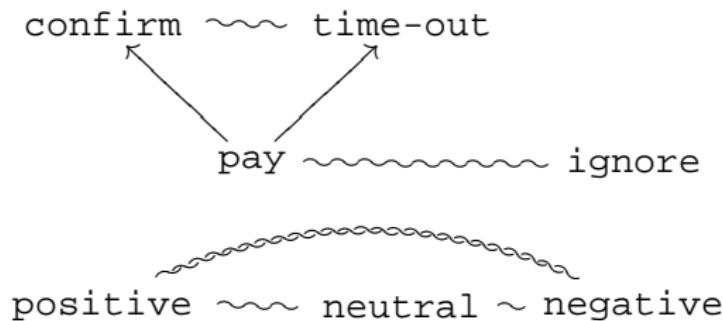


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# A bit of magic: the Dirichlet probability distribution



The Dirichlet family  $\mathcal{D}(\Theta | \alpha) \propto \prod \Theta_1^{\alpha_1-1} \dots \Theta_K^{\alpha_K-1}$

## Theorem

The Dirichlet family is a *conjugate prior* for multinomial trials. That is, if

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then  $\text{Prob}[\Theta | X \lambda]$  is  $\mathcal{D}(\Theta | \alpha_1 + n_1, \dots, \alpha_K + n_K)$  according to Bayes.

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# Interpretation of results

As a result, we can lift the trust computational algorithms based on  $\lambda_\beta$  to our event-base models by replacing

Binomials (Bernoulli) trials  
 $\beta$ -distribution

↔

multinomial trials;  
Dirichlet distribution.

