

Radial Basis Function Classifier Construction Using Particle Swarm Optimisation Aided Orthogonal Forward Regression

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Outline

- 1 Motivations
 - Existing Approaches
 - Our Novelty
- 2 PSO Aided OFR Based RBF Classifier
 - Tunable RBF Modelling
 - PSO Aided OFR Algorithm
- 3 Experimental Results
 - Breast Cancer Data
 - Diabetes Data
 - Thyroid Data
- 4 Conclusions

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Existing RBF Classifiers

- **Nonlinear** optimisation \Rightarrow optimise all RBF classifier's parameters: centres, variances or covariances and weights
 - Very “sparse” (small size), but all problems associated with “nonlinear” optimisation
- **Linear** optimisation \Rightarrow set RBF centres to training data and fix a variance: seek a “linear” subset classifier
 - Orthogonal least squares forward selection:
 - Sparse, good performance, and efficient construction
 - Need to specify RBF variance (via cross validation)
 - Sparse kernel modelling methods:
 - Sparse (though not as sparse as OLS), good performance
 - Need to specify kernel variance and other hyperparameters (via cross validation)

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Combined Linear/Nonlinear Learning

- Linear approach \Rightarrow state-of-the-art efficient ROLS-LOO, but fixed bases and a common RBF variance
- Nonlinear approach \Rightarrow optimise all parameters, but a too large and complex nonlinear optimisation
- Combined linear/nonlinear approach:
 - Retain advantage of linear optimisation \rightarrow use orthogonal forward regression to add RBF bases one by one
 - Have tunable RBF bases for enhanced modelling capability \rightarrow use nonlinear optimisation
- Each stage of OFR, optimise one tunable base, i.e. determine RBF base's centre and covariance
 - **How efficient** this combined RBF classifier modelling, in comparison with state-of-the-art ROLS-LOO?

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Tunable-RBF Classifier

- **Two-class** training set $D_N = \{\mathbf{x}_k, y_k\}_{k=1}^N$, where $\mathbf{x}_k \in \mathcal{R}^m$ is pattern vector and $y_k \in \{\pm 1\}$ class label
- Construct **RBF classifier** as linear combiner of RBF bases $\{g_i(\mathbf{x}_k)\}_{i=1}^M$

$$\hat{y}_k = f^{[M]}(\mathbf{x}_k) = \sum_{i=1}^M w_i g_i(\mathbf{x}_k)$$

where w_i are weights, with estimated class label

$$\tilde{y}_k = \text{sgn}(\hat{y}_k)$$

- Generic **RBF base** is given by

$$g_i(\mathbf{x}) = K \left(\sqrt{(\mathbf{x} - \boldsymbol{\mu}_i)^T \boldsymbol{\Sigma}_i^{-1} (\mathbf{x} - \boldsymbol{\mu}_i)} \right)$$

where $\boldsymbol{\mu}_i$: i th centre vector, $\boldsymbol{\Sigma}_i$: i th diagonal covariance matrix, and $K(\bullet)$: chosen basis function

Orthogonal Decomposition

- **Regression** model on training set D_N : $\mathbf{y} = \mathbf{G}_M \mathbf{w}_M + \mathbf{e}$
- **Orthogonal decomposition** of regression matrix, $\mathbf{G}_M = \mathbf{P}_M \mathbf{A}_M$:

$$\mathbf{A}_M = \begin{bmatrix} 1 & \alpha_{1,2} & \cdots & \alpha_{1,M} \\ 0 & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \alpha_{M-1,M} \\ 0 & \cdots & 0 & 1 \end{bmatrix}$$

$\mathbf{P}_M = [\mathbf{p}_1 \ \mathbf{p}_2 \ \cdots \ \mathbf{p}_M]$ is orthogonal, $\mathbf{A}_M \mathbf{w}_M = \boldsymbol{\theta}_M$, and equivalently:

$$\mathbf{y} = \mathbf{G}_M \mathbf{w}_M + \mathbf{e} \Leftrightarrow \mathbf{y} = \mathbf{P}_M \boldsymbol{\theta}_M + \mathbf{e}$$

- After n th stage of OFR, n bases are constructed $\mathbf{G}_n = [\mathbf{g}_1 \ \cdots \ \mathbf{g}_n]$ with corresponding $\mathbf{P}_n = [\mathbf{p}_1 \ \cdots \ \mathbf{p}_n]$ and \mathbf{A}_n , while k th row of \mathbf{P}_n is denoted as $[p_1(k) \ \cdots \ p_n(k)]$

LOO Classification

- Define **leave-one-out** n -term classifier's output

$$\hat{y}_k^{[n,-k]} = f^{[n,-k]}(\mathbf{x}_k)$$

- LOO **signed decision variable** $s_k^{[n,-k]} = y_k \hat{y}_k^{[n,-k]} = \phi_k^{[n]} / \eta_k^{[n]}$
with

$$\eta_k^{[n]} = \eta_k^{[n-1]} - p_n^2(k) / (\mathbf{p}_n^T \mathbf{p}_n + \lambda)$$

$$\phi_k^{[n]} = \phi_k^{[n-1]} + y_k \theta_n p_n(k) - p_n^2(k) / (\mathbf{p}_n^T \mathbf{p}_n + \lambda)$$

where λ is a regularisation parameter

- LOO **misclassification rate** can then be computed efficiently

$$J_n = \frac{1}{N} \sum_{k=1}^N \mathcal{I}_d \left(s_k^{[n,-k]} \right)$$

where indicator $\mathcal{I}_d(y) = 1$ if $y \leq 0$ and $\mathcal{I}_d(y) = 0$ if $y > 0$

Nonlinear Optimisation in OFR

- At n th stage of OFR, determine n th RBF base, i.e. its nonlinear parameters μ_n, Σ_n , by solving nonlinear optimisation

$$\min_{\mu_n, \Sigma_n} J_n(\mu_n, \Sigma_n)$$

- For LOO criterion J_n , there exists an “optimal” model size M : for $n \leq M$, J_n decreases as model size n increases while

$$J_M \leq J_{M+1}$$

Thus, OFR construction procedure is automatically terminated when above condition holds, yielding an M -base model

- We propose to use particle swarm optimisation,

A population based stochastic optimisation method inspired by social behaviour of bird flocks or fish schools (Swarm Intelligence)

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Particle Swarm Optimisation

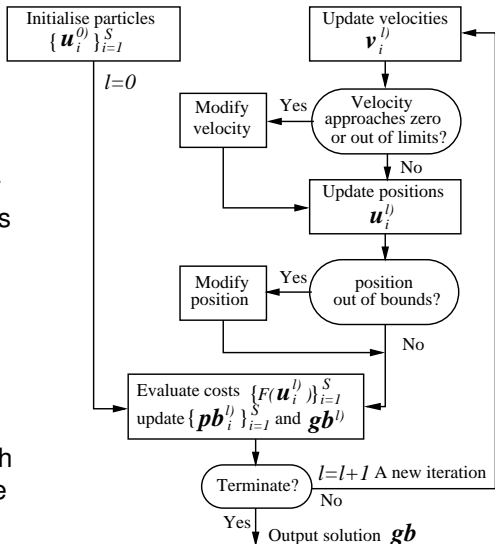
- Solving generic optimisation

$$\mathbf{u}_{\text{opt}} = \arg \min_{\mathbf{u} \in \prod_{j=1}^{m'} P_j} F(\mathbf{u})$$

$\mathbf{u} = [u_1 \cdots u_{m'}]^T$ is parameter vector to be optimised, $F(\bullet)$ is cost, and search space

$$\prod_{j=1}^{m'} P_j = \prod_{j=1}^{m'} [P_{j,\min}, P_{j,\max}]$$

- A **swarm** of **particles**, $\{\mathbf{u}_i^l\}_{i=1}^S$, are evolved in search space, where S is swarm size and l denotes iteration index



PSO Algorithm Adopted

- Each particle remembers its best position visited – *cognitive information*, $\mathbf{pb}_i^{l)}$, $1 \leq i \leq S$
- Every particle knows best position visited among entire swarm – *social information*, $\mathbf{gb}^{l)}$
- Each particle has a **velocity** $\mathbf{v}_i^{l)}$ to direct its “flying”, and

$$\mathbf{v}_i^{l)} \in \prod_{j=1}^{m'} V_j = \prod_{j=1}^{m'} [-V_{j,\max}, V_{j,\max}]$$

- In our application, $m' = 2m$, each $\mathbf{u}_i^{l)}$ contains a candidate solution for $(\boldsymbol{\mu}_n, \boldsymbol{\Sigma}_n)$, and cost function $F(\mathbf{u}) = J_n(\boldsymbol{\mu}, \boldsymbol{\Sigma})$

PSO Procedure

- **a) Swarm initialisation:** Set iteration index $l = 0$ and randomly generate $\{\mathbf{u}_i^l\}_{i=1}^S$ in search space $\prod_{j=1}^{m'} P_j$

- **b) Swarm evaluation:** Particle \mathbf{u}_i^l has cost $F(\mathbf{u}_i^l)$, based on which \mathbf{pb}_i^l , $1 \leq i \leq S$, and \mathbf{gb}^l are updated

- **c) Swarm update:** Velocities and positions are updated

$$\mathbf{v}_i^{l+1} = w_1 * \mathbf{v}_i^l + rand() * c_1 * (\mathbf{pb}_i^l - \mathbf{u}_i^l) + rand() * c_2 * (\mathbf{gb}^l - \mathbf{u}_i^l)$$

$$\mathbf{u}_i^{l+1} = \mathbf{u}_i^l + \mathbf{v}_i^{l+1}$$

- **d) Termination:** If maximum number of iterations l_{\max} is reached, terminate with solution $\mathbf{gb}^{l_{\max}}$; otherwise, $l = l + 1$ and goto **b)**

PSO Algorithmic Parameters

- **Inertial weight** $w_1 = rand()$, other alternative is $w_1 = 0$ or w_1 set to a small positive constant
- **Time varying acceleration coefficients**

$$c_1 = (0.5 - 2.5) * l/l_{\max} + 2.5, \quad c_2 = (2.5 - 0.5) * l/l_{\max} + 0.5$$
 - Initially, large cognitive component and small social component help particles to exploit better search space
 - Later, small cognitive component and large social component help particles to converge quickly to a minimum
- $S = 10$ to 20 appropriate for small to medium size problems, and empirical results suggest $l_{\max} = 20$ is often sufficient
- **Search space** is specified by problem, **velocity space** can be determined with $V_{j,\max} = 0.5 * (P_{j,\max} - P_{j,\min})$

Computational Complexity

- Let complexity of evaluating cost function once be $C_{\text{single}} \Rightarrow$ total complexity in determining one RBF node is

$$C_{\text{total}} = I_{\text{max}} \times S \times C_{\text{single}}$$

- Complexity of one LOO cost evaluation and associated column orthogonalisation is order of $N \Rightarrow C_{\text{single}} = \mathcal{O}(N)$
- Complexity of **PSO-aided OFR** in constructing M tunable-bases

$$C_{\text{PSO-OFr}} = (M + 1) \times I_{\text{max}} \times S \times \mathcal{O}(N)$$

- Complexity of **ROLS-LOO** in selecting M' fixed-bases from N -candidate set is

$$C_{\text{ROLS}} = (M' + 1) \times N \times \mathcal{O}(N)$$

- PSO-aided OFR is generally simpler for large data set:

$M < M'$, typically $I_{\text{max}} \times S \leq 400$: when $N \geq 400$, $C_{\text{PSO-OFr}} < C_{\text{ROLS}}$

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Breast Cancer Data Set

Average classification test error rate in % over 100 realizations

method	RBF type	test error rate	model size
RBF-Network	tunable	27.64 ± 4.71	5
AdaBoost RBF-Network	tunable	30.36 ± 4.73	5
LP-Reg-AdaBoost ("-")	tunable	26.79 ± 6.08	5
QP-Reg-AdaBoost ("-")	tunable	25.91 ± 4.61	5
AdaBoost-Reg ("-")	tunable	26.51 ± 4.47	5
SVM with RBF-Kernel	fixed	26.04 ± 4.74	unavailable
Kernel Fisher Discriminant	fixed	24.77 ± 4.63	200
ROLS-LOO	fixed	25.74 ± 5.00	6.0 ± 2.0
PSO OFR-LOO	tunable	23.04 ± 3.41	2.8 ± 0.9

Data and first 7 results from:

<http://ida.first.fhg.de/projects/bench/benchmarks.htm>

PSO OFR-LOO: $S = 10$ and $l_{\max} = 20$ with complexity of $760 \cdot \mathcal{O}(200)$

ROLS-LOO: with complexity of $1400 \cdot \mathcal{O}(200)$, given RBF variance

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Diabetes Data Set

Average classification test error rate in % over 100 realizations

method	RBF type	test error rate	model size
RBF-Network	tunable	24.29 ± 1.88	15
AdaBoost RBF-Network	tunable	26.47 ± 2.29	15
LP-Reg-AdaBoost ("-")	tunable	24.11 ± 1.90	15
QP-Reg-AdaBoost ("-")	tunable	25.39 ± 2.20	15
AdaBoost-Reg ("-")	tunable	23.79 ± 1.80	15
SVM with RBF-Kernel	fixed	23.53 ± 1.73	unavailable
Kernel Fisher Discriminant	fixed	23.21 ± 1.63	468
ROLS-LOO	fixed	23.00 ± 1.70	6.0 ± 1.0
PSO OFR-LOO	tunable	21.87 ± 1.24	3.5 ± 1.4

Data and first 7 results from:

<http://ida.first.fhg.de/projects/bench/benchmarks.htm>

PSO OFR-LOO: $S = 10$ and $l_{\max} = 20$ with complexity $900 \cdot \mathcal{O}(468)$

ROLS-LOO: with complexity $3276 \cdot \mathcal{O}(468)$, given RBF variance

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Thyroid Data Set

Average classification test error rate in % over 100 realizations

method	RBF type	test error rate	model size
RBF-Network	tunable	4.52 ± 2.12	8
AdaBoost RBF-Network	tunable	4.40 ± 2.18	8
LP-Reg-AdaBoost ("-")	tunable	4.59 ± 2.22	8
QP-Reg-AdaBoost ("-")	tunable	4.35 ± 2.18	8
AdaBoost-Reg ("-")	tunable	4.55 ± 2.19	8
SVM with RBF-Kernel	fixed	4.80 ± 2.19	unavailable
Kernel Fisher Discriminant	fixed	4.20 ± 2.07	140
ROLS-LOO	fixed	4.80 ± 2.20	4.6 ± 1.0
PSO OFR-LOO	tunable	2.48 ± 1.41	3.5 ± 0.8

Data and first 7 results from:

<http://ida.first.fhg.de/projects/bench/benchmarks.htm>

PSO OFR-LOO: $S = 20$ and $l_{\max} = 20$ with complexity $1800 \cdot \mathcal{O}(140)$

ROLS-LOO: with complexity $784 \cdot \mathcal{O}(140)$, given RBF variance

Conclusions

- We have developed a PSO aided OFR based algorithm for constructing tunable RBF classifiers, which combines
 - advantages of “linear” learning (orthogonal forward regression selects RBF bases one by one), and
 - advantages of “nonlinear” learning (particle swarm optimisation optimises one base at each OFR stage)
- Compared with best ROLS-LOO algorithm for selecting subset RBF model from full fixed-base candidate set, the proposed method offers:
 - better test performance, smaller classifier size, and lower complexity in classifier construction process