

Introduction to Discrete Event Simulation II

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13th February 2012

Southampton

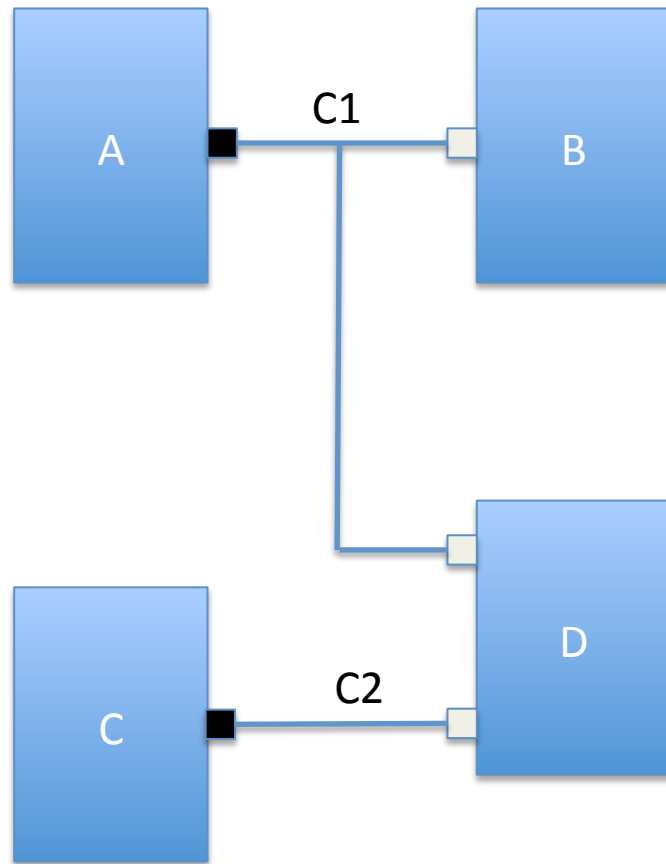


Introduction

- Discrete Event Simulation Principles – Review
- The Testbench
- Simulation-based Verification
- Sign Off
- Summary



Discrete Event Simulation



COMPONENT VIEW

Components: A, B, C, D (processes)

Connections: C1, C2 (unidirectional)

Ports: IN  OUT 

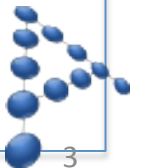
SIMULATOR API

GetValue(port)

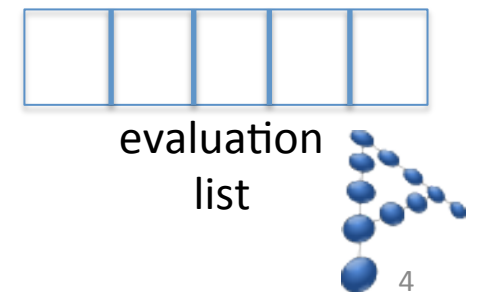
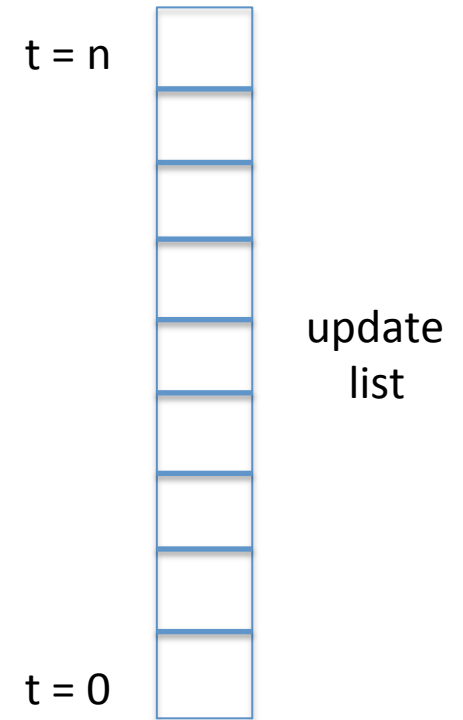
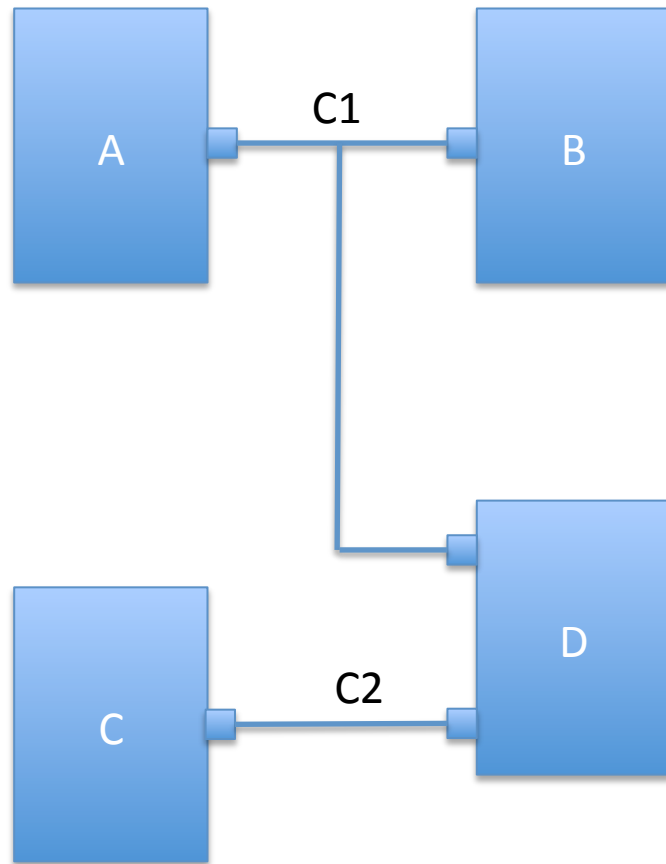
HasChanged(port)

SetValue(OUT port, val, delay)

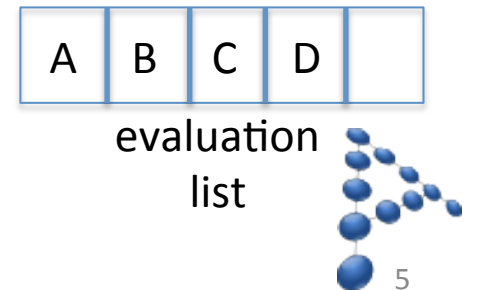
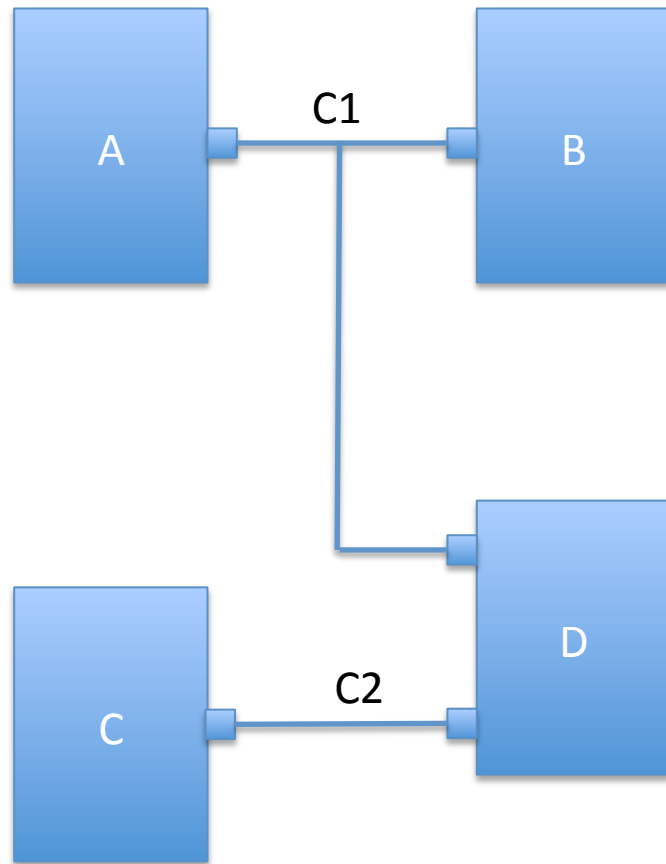
ScheduleEval(component, delay)



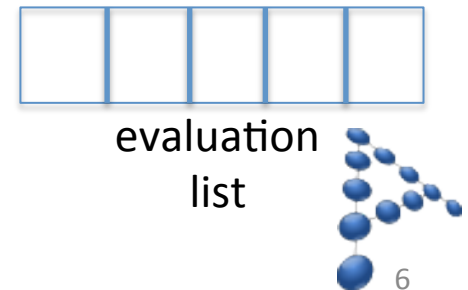
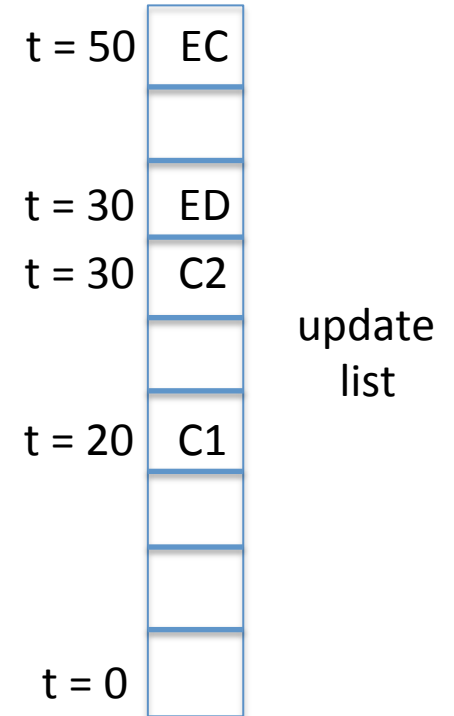
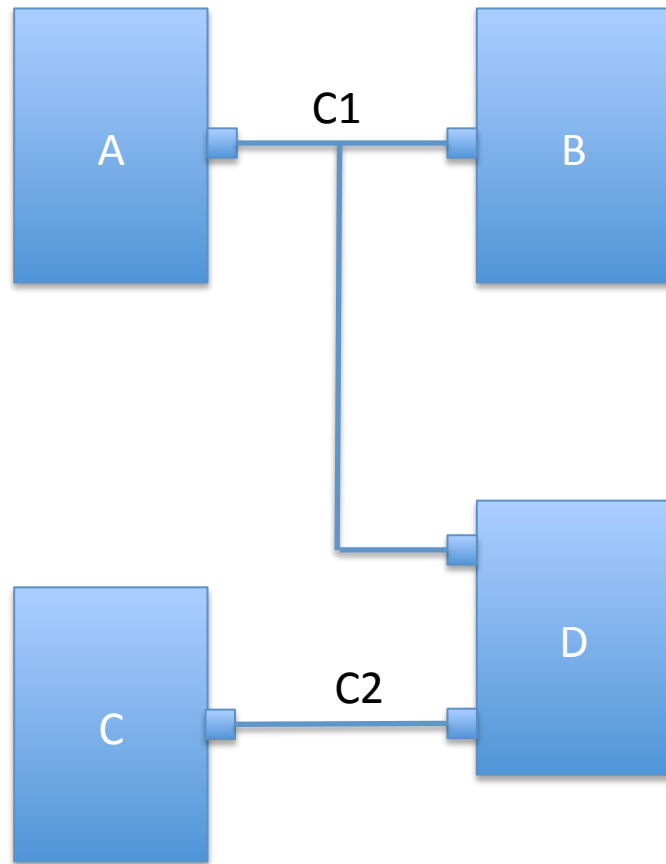
The Two-list Simulation Algorithm



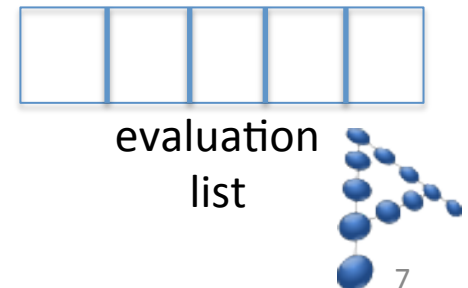
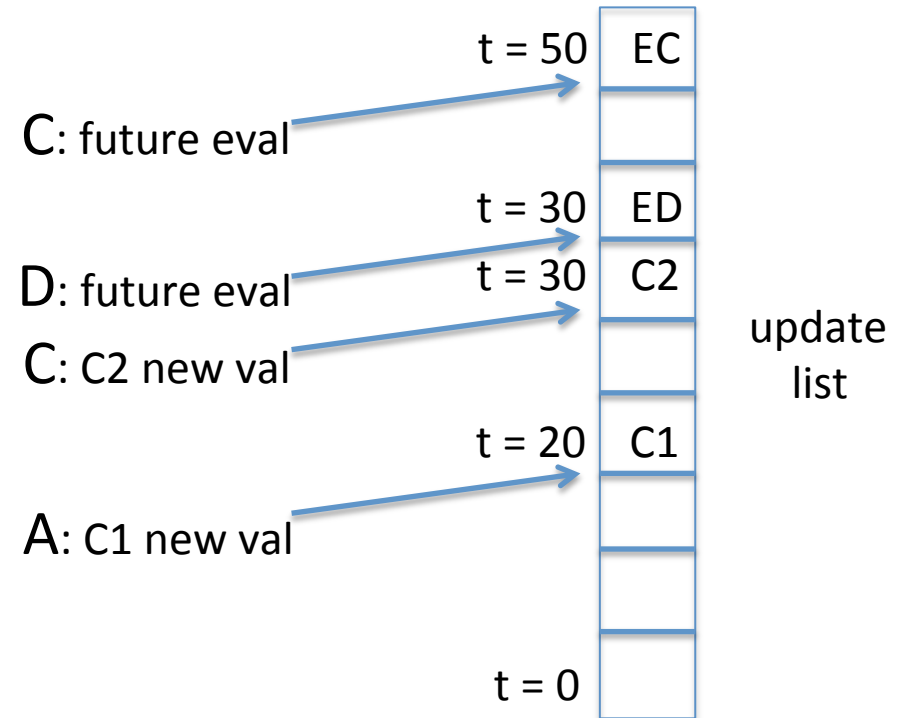
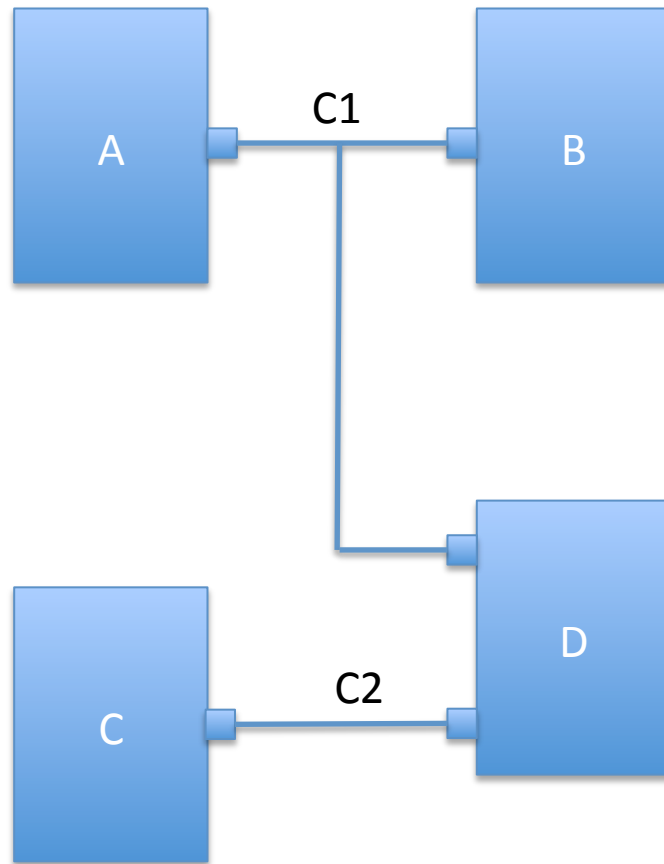
Time Zero Initialisation: Evaluate all Components



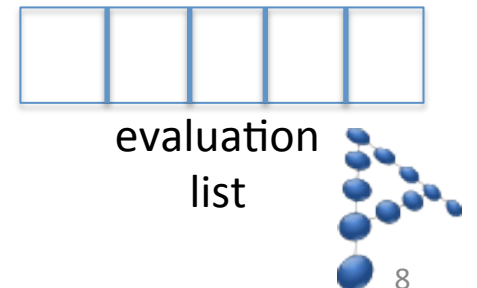
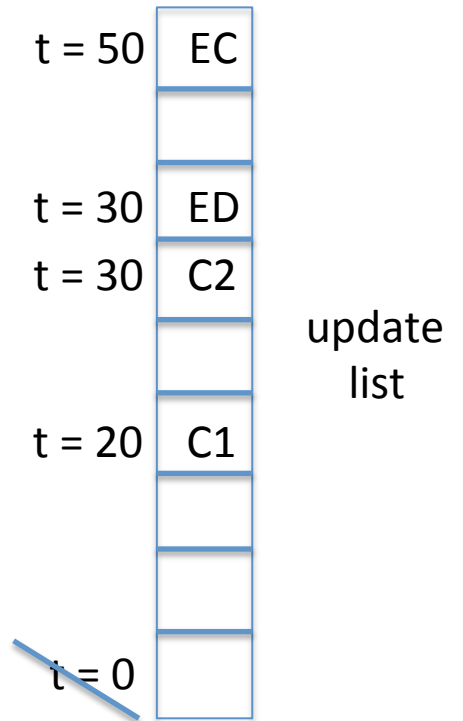
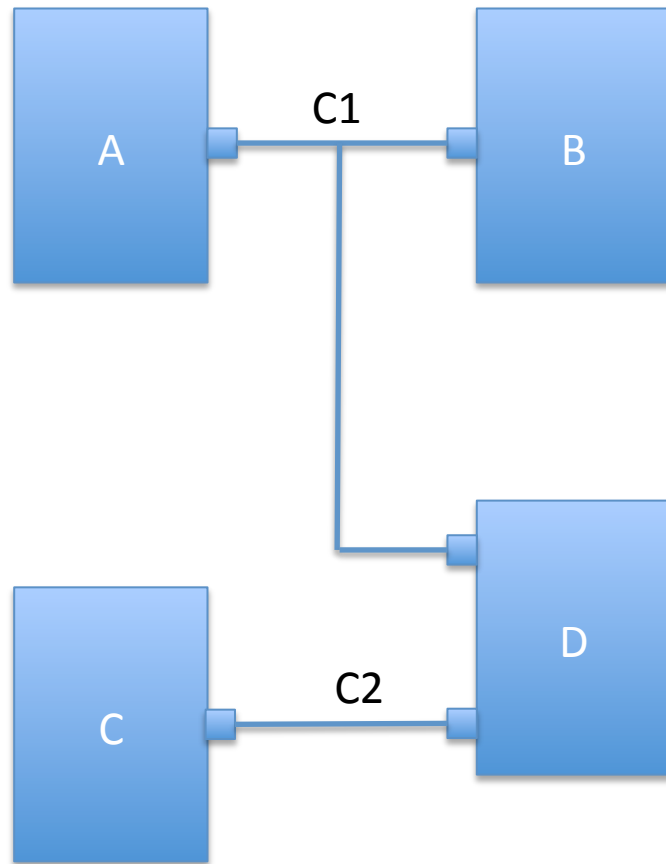
Component evaluations call *SetValue*, *ScheduleEval*



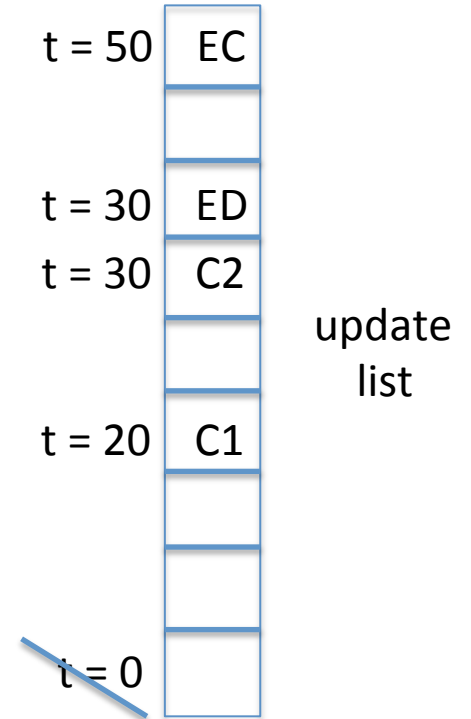
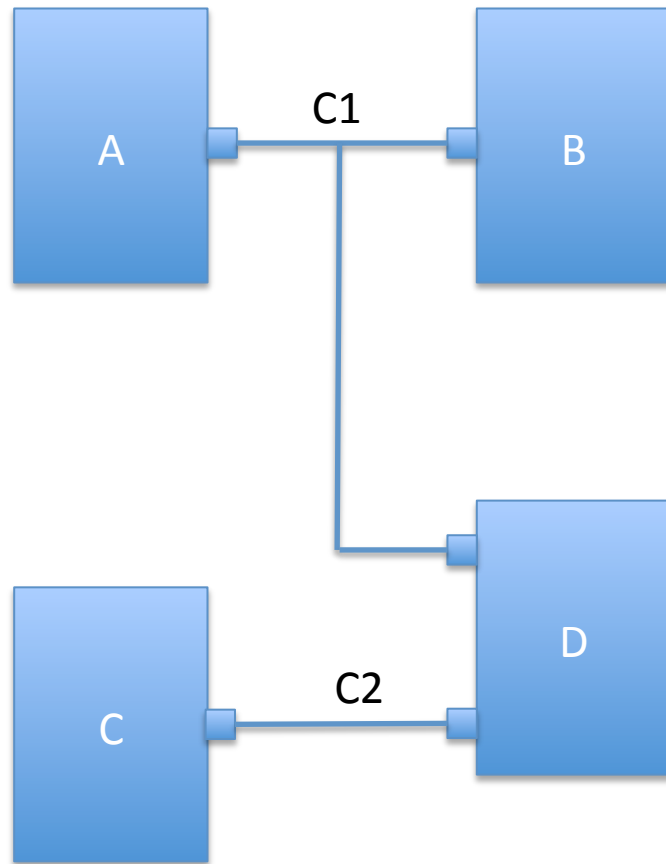
Component evaluations call *SetValue*, *ScheduleEval*



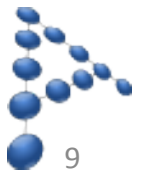
Global Time is Advanced to $t = 20$



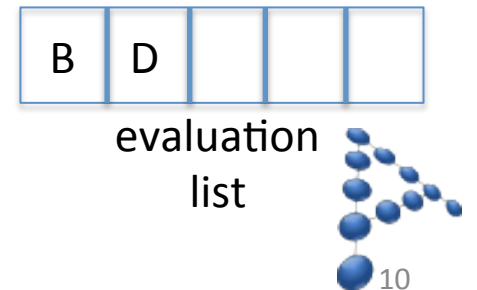
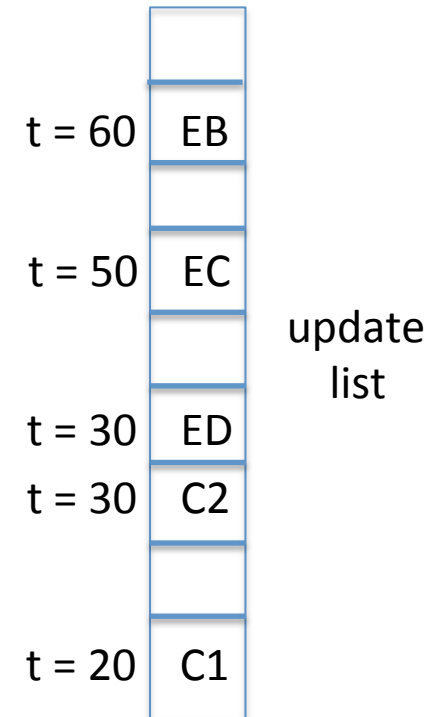
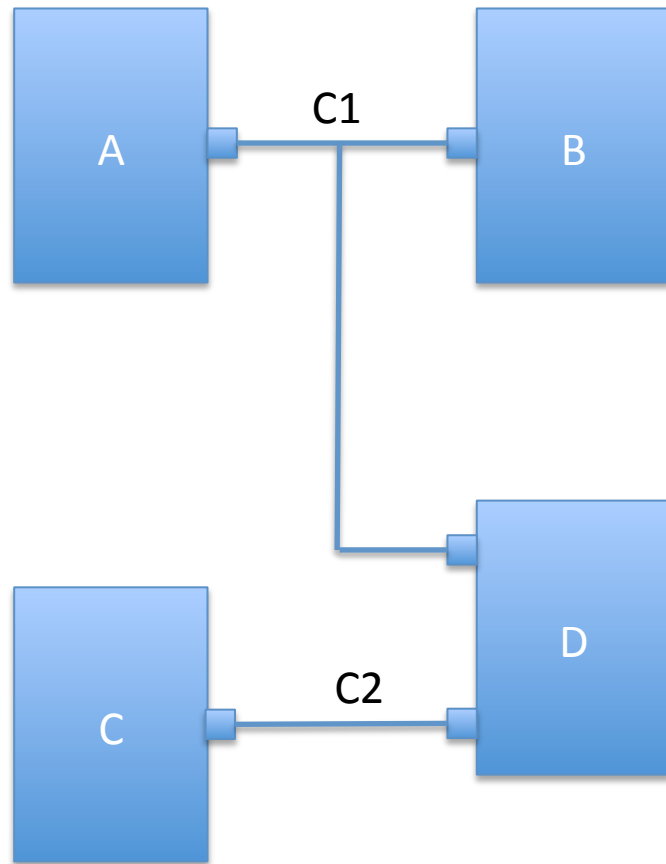
Add to *eval list* each component on C1 *fanout*



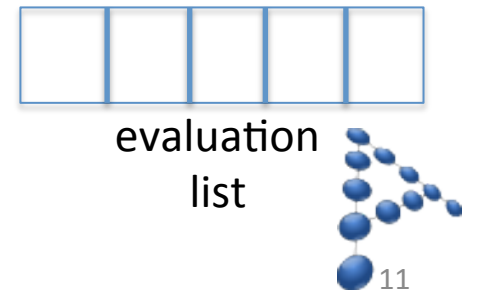
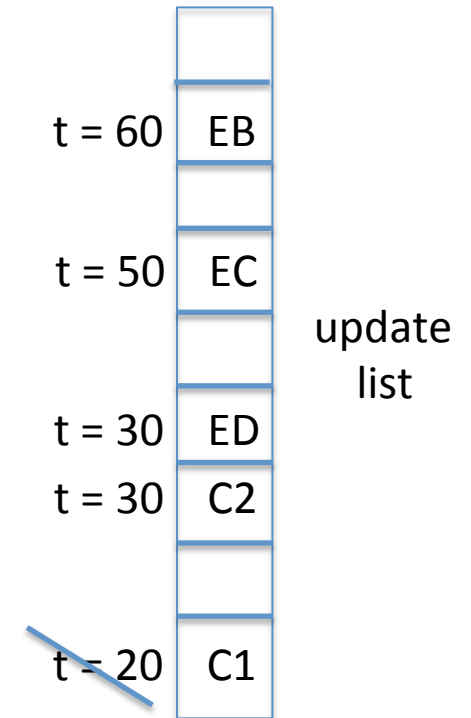
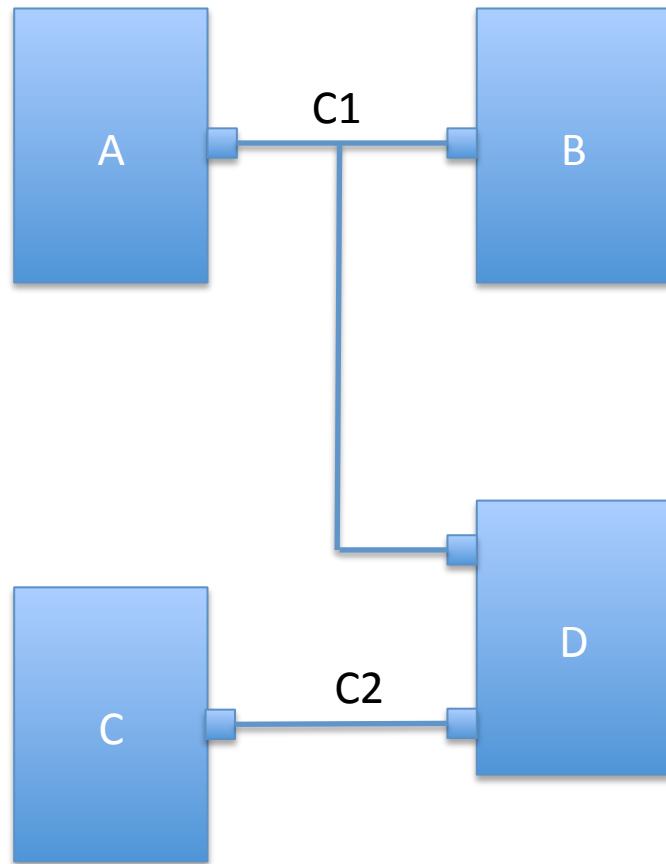
evaluation list



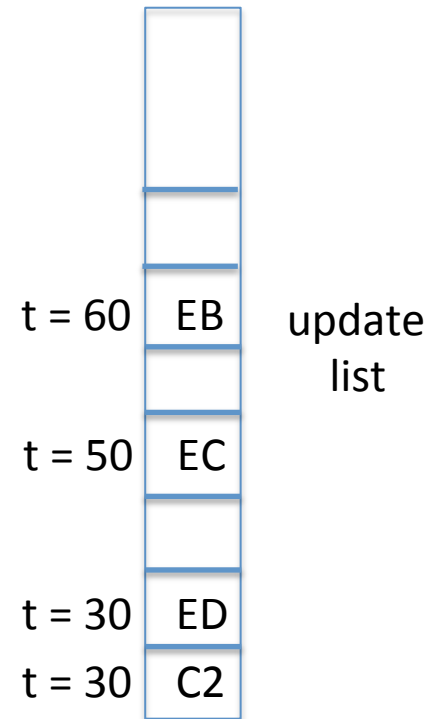
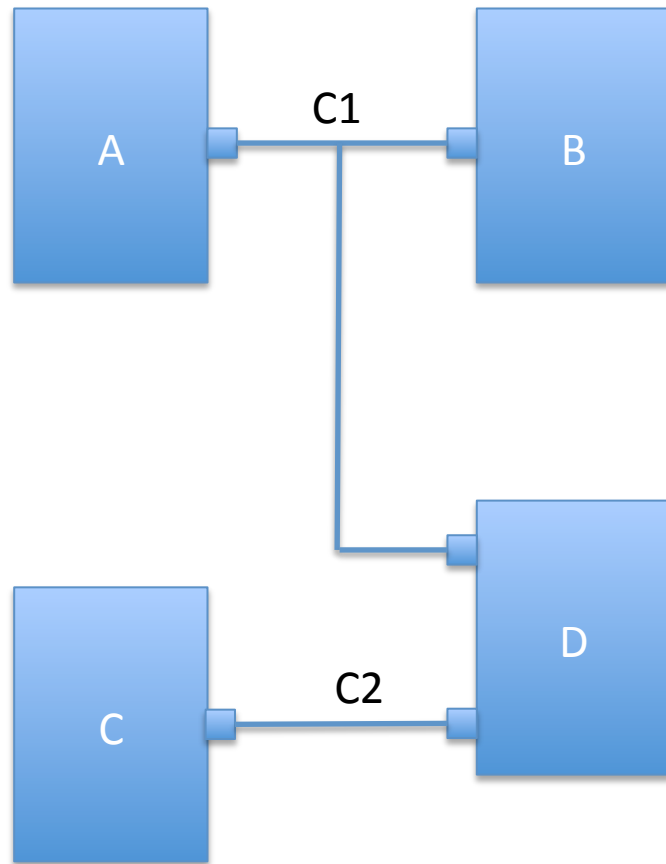
B calls *ScheduleEval* with delay 40



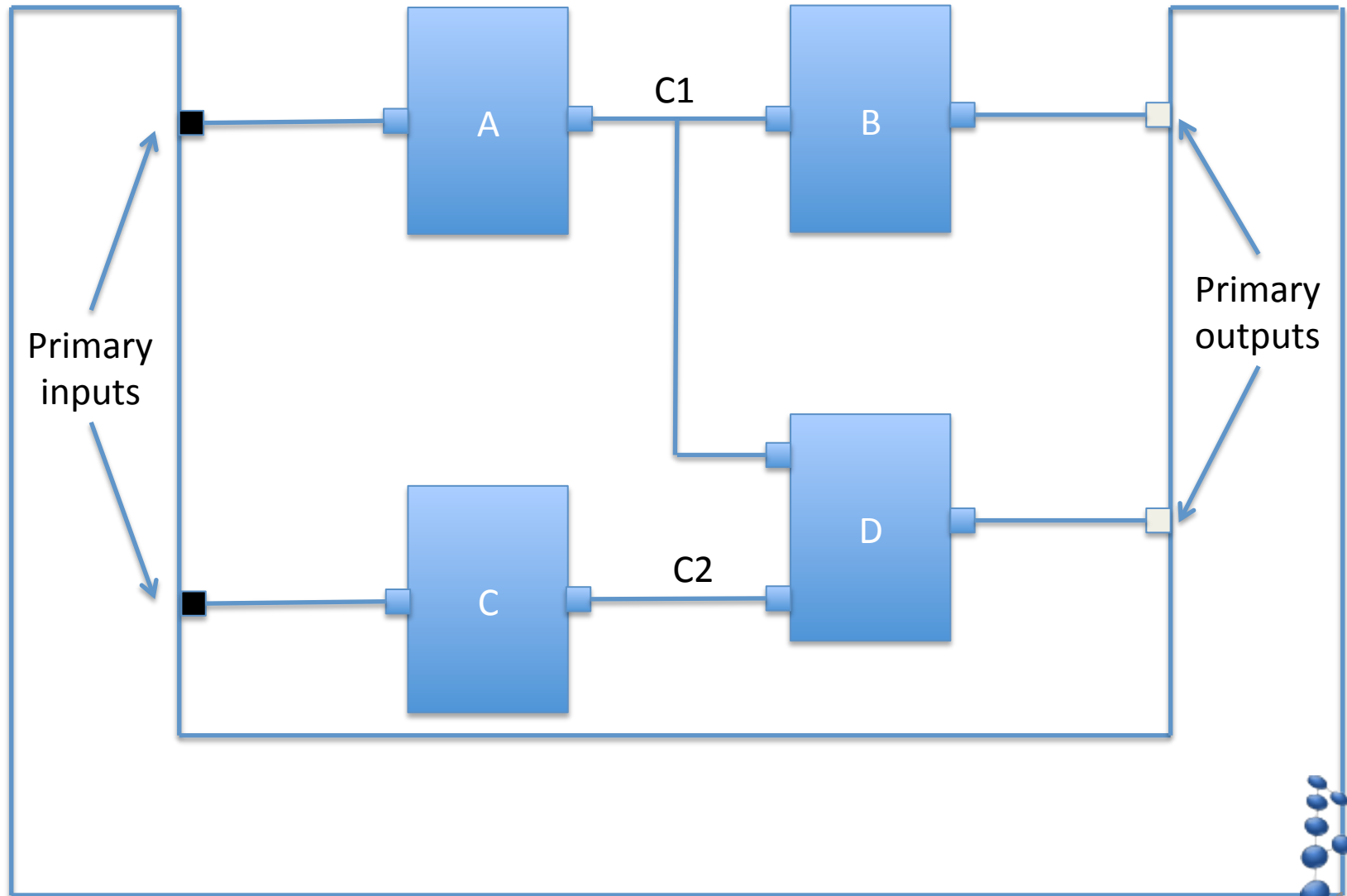
Time advances to $t = 30$: *two* updates



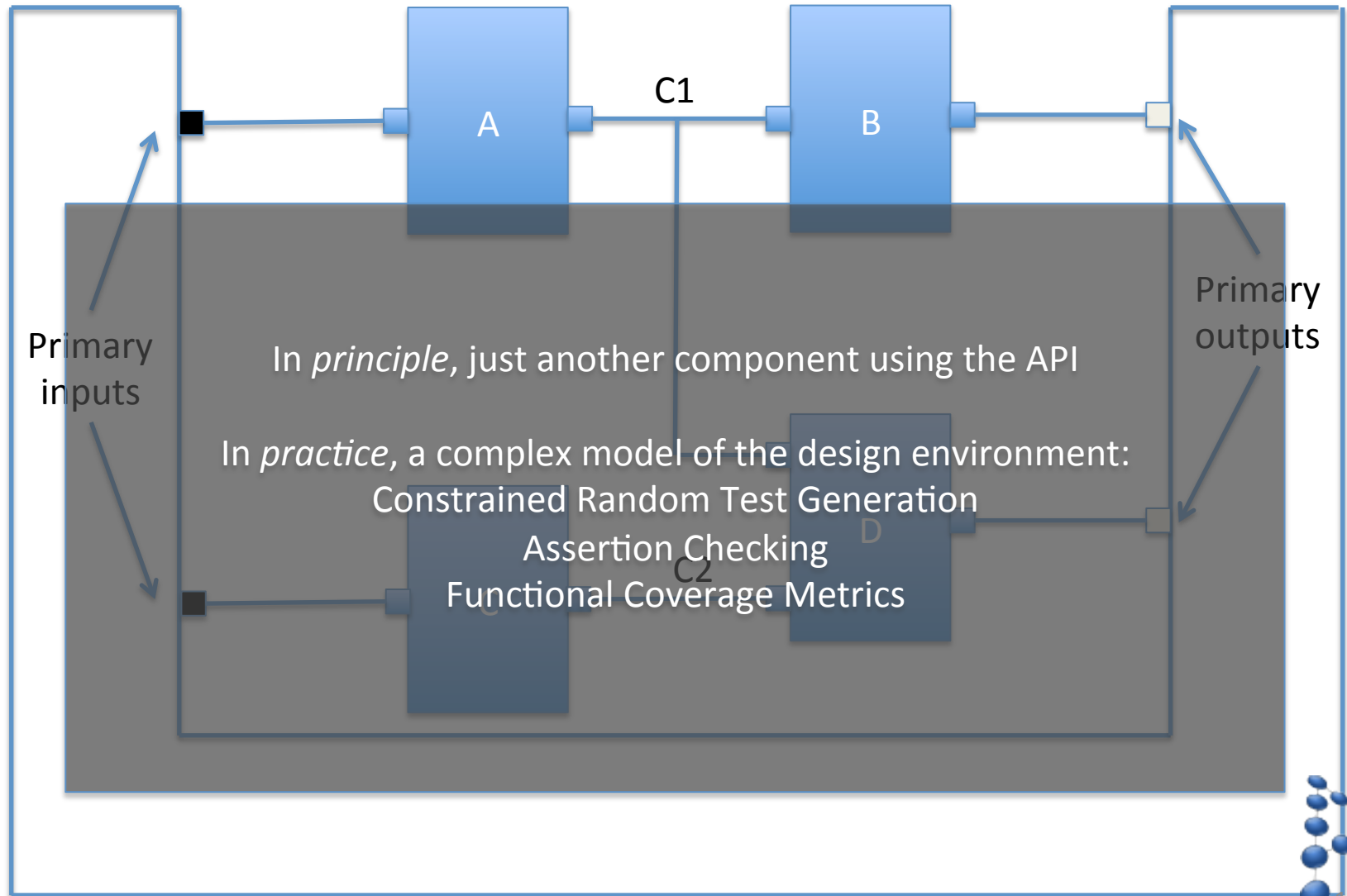
Time advances to $t = 30$: *two* updates, *one* eval



The Simulation Testbench



The Simulation Testbench



Simulation-based Verification

- As opposed to Formal Verification
 - Theorem Proving
 - Model Checking
- Structural Coverage
- Functional Coverage
- Assertion Checking
- Assertion Coverage
- Integrating Formal and Simulation-based Verification

Structural Coverage

Do the requirements- based test cases adequately exercise the structure of the source code?

DO 178B

- Statement Coverage
- Branch (Decision) Coverage
- MC/DC (Modified Condition/Decision Coverage)
 - Unique Cause
 - Masking



MC/DC

(Modified Condition/Decision Coverage)

$$Z = (A \text{ or } B) \text{ and } (C \text{ or } D)$$

A	B	C	D	Z
F	F	F	T	F
...				
T	F	F	T	T



MC/DC

(Modified Condition/Decision Coverage)

$$Z = (A \text{ or } B) \text{ and } (C \text{ or } D)$$

A	B	C	D	Z
---	---	---	---	---

Unique Cause

F	F	F	T	F
...				
T	F	F	T	T

MC/DC

(Modified Condition/Decision Coverage)

$$Z = (A \text{ or } B) \text{ and } (C \text{ or } D)$$

					Z
A					B
					C
					D
Masking	F	F	F	T	F
	...				
	T	F	F	T	T
	T	F	T	F	T
	T	F	T	T	T

MC/DC

(Modified Condition/Decision Coverage)

Summary

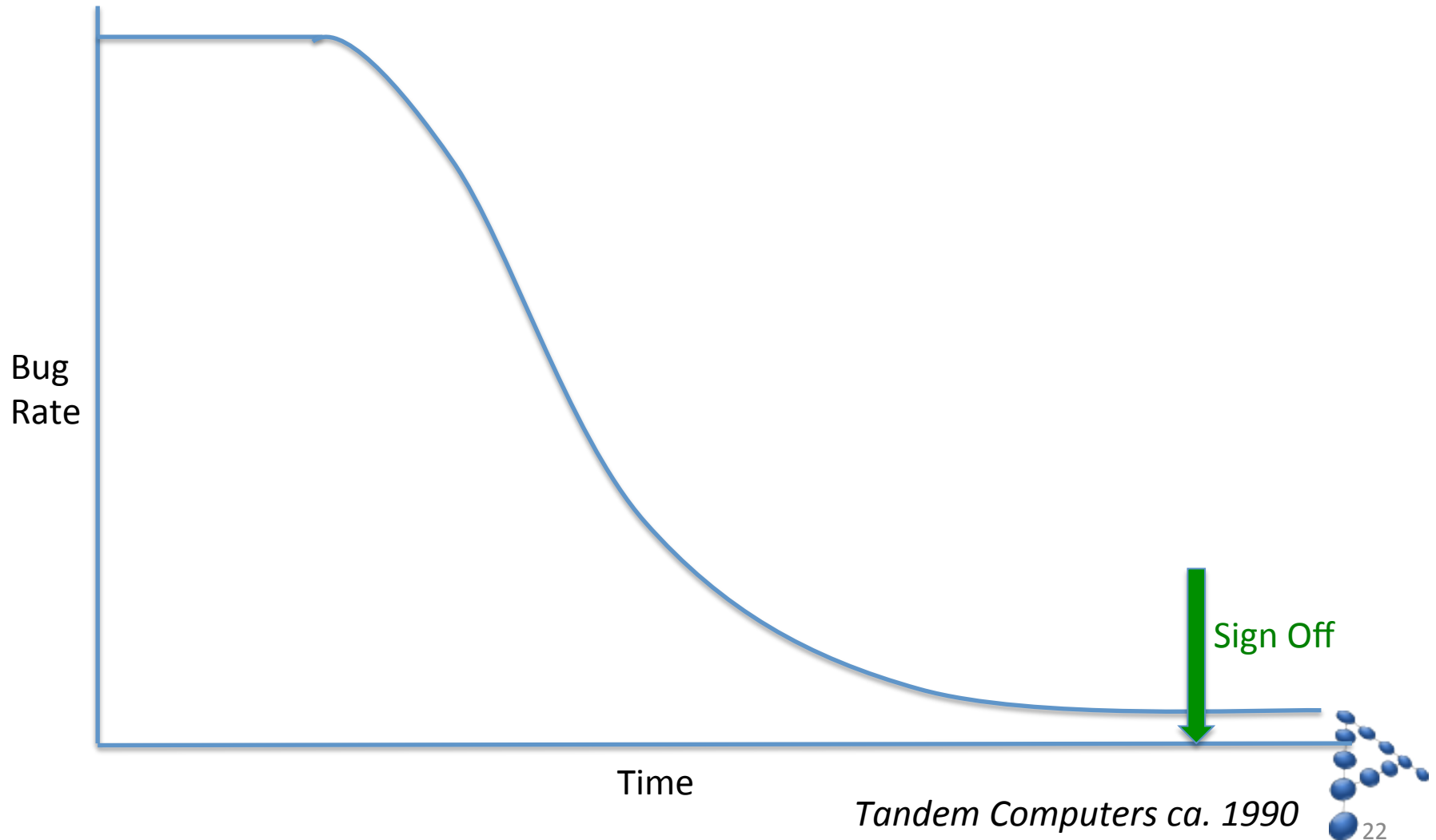
- Masking MC/DC results in fewer tests and shorter simulation runs
- Unique-Cause MC/DC cannot deal with repeated conditions
- Unique-Cause MC/DC may detect more errors (NB not the *actual* DO 178B requirement)

Do the requirements- based test cases adequately exercise the structure of the source code?

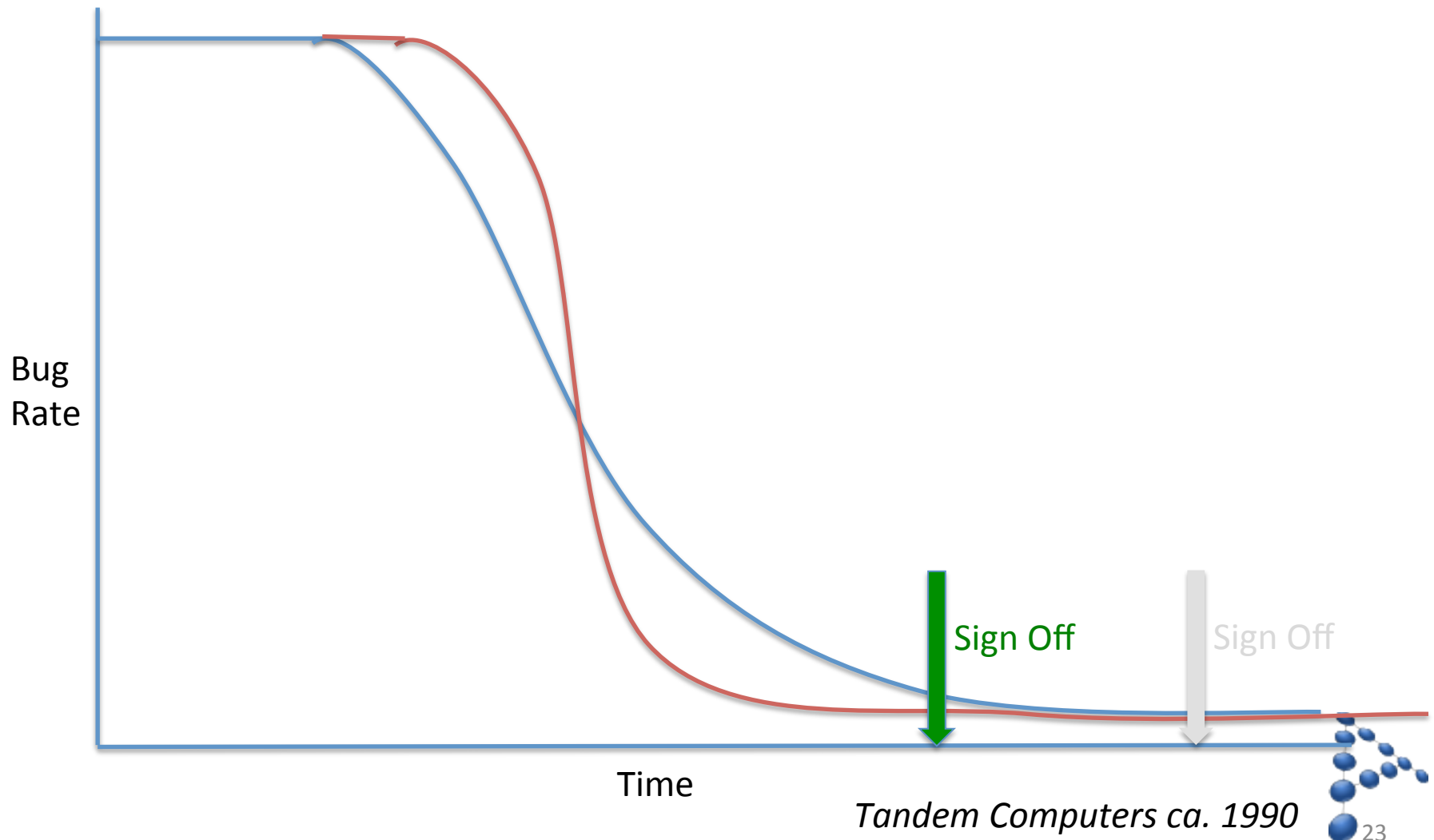
DO 178 C

- Approved: December 2011
- Provision for Formal Methods
- Provision for Object-Oriented Code Development
 - As opposed to Structured Code Development
 - Does MC/DC have the same value?

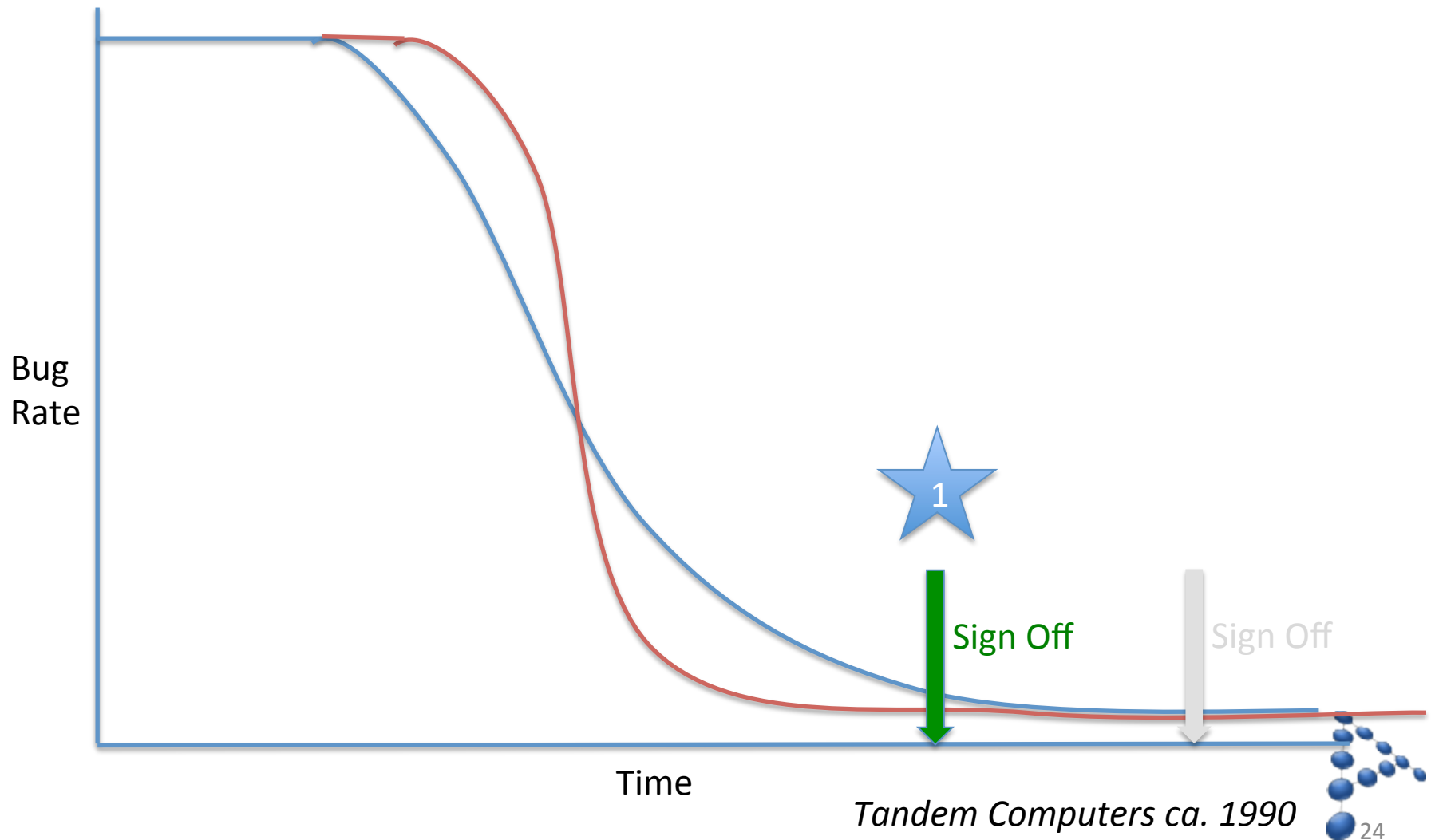
Bug Rate vs Time



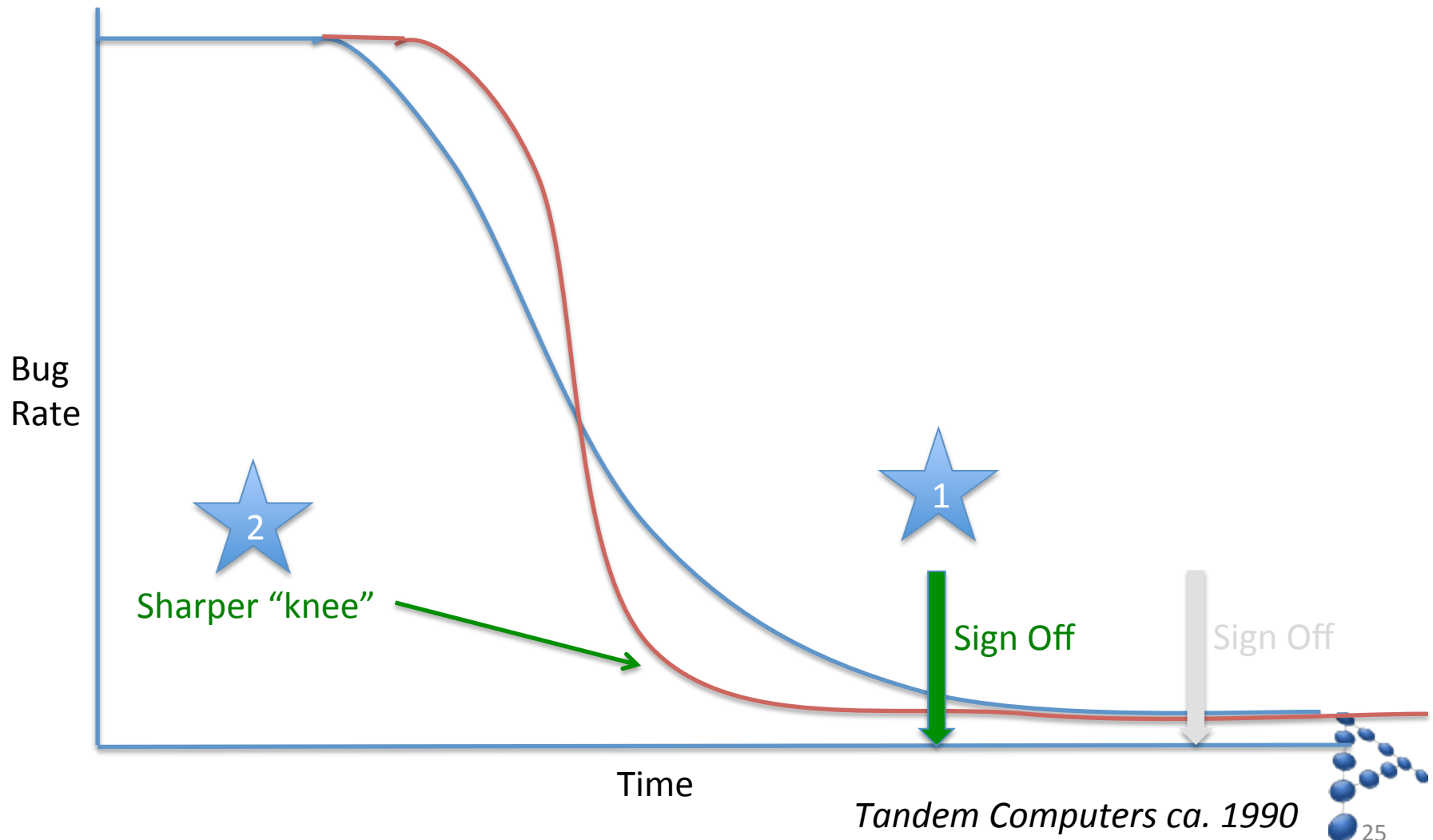
Bug Rate vs Time – *Coverage Directed* Verification



Bug Rate vs Time – *Coverage Directed* Verification



Bug Rate vs Time – *Coverage Directed* Verification



Functional Coverage

- *User-defined* Coverage Metrics
 - Typical Scenarios
 - Error Cases
 - Corner Cases
- High-Level Language Description
- Constrained Random Test Generation from Coverage Description
- “Scoreboarding”

Functional Coverage Example

Transaction Coverage

Transaction Type	Header1	Header2	Typical Value	Min. Value	Max. Value
A					
B			-	-	-
C		-			

Functional Coverage Example

Transaction Coverage

Transaction Type	Header1	Header2	Typical Value	Min. Value	Max. Value
A	●	●	●	●	●
B	●	●	-	-	-
C	●	-	●	●	●

Functional Coverage: 8/11 (73%)



Assertion Checking: PSL (Property Specification Language)

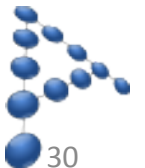
- LTL-based
- Unit of time is the Clock Cycle
- SEREs
 - Sequential Extended Regular Expressions

$\{ a ; \text{ not } a ; b \} \quad | \Rightarrow \quad \{ c \}$

Assertion Checking: PSL (Property Specification Language)

- PSL is converted to *Simulation Monitors*
 - First, convert to Buchi Automata (non-deterministic)
 - Second, generate deterministic automata
 - Third, generate HDL representation
- Simulate the Monitors together with the Design

$\{ a ; \text{ not } a ; b \} \quad | \Rightarrow \quad \{ c \}$



Assertion Coverage

- How effectively do the tests exercise the Assertions?
 - Vacuously Satisfied? (a is always false)
 - Are the SEREs *sensitised* to detect assertion failure?

$$\{ a ; \text{not } a ; b \} \quad | \Rightarrow \quad \{ c \}$$

- Is the set of assertions
 - Necessary?
 - Sufficient?



Integrating Formal and Simulation-based Verification

- PSL SEREs can be verified using a model checker
 - Assertion Coverage principles still apply
 - Assertion Coverage results for simulation and model checking can be combined
- Are the assertions necessary/sufficient?
 - An open problem
 - Scope for using theorem proving?

Verification Sign Off

- Ultimately, an engineer will have to physically provide a signature
- How confident is the engineer that the design meets its specification?
 - The outcome of the verification process must be measurable
 - Bug rate
 - Coverage metrics

Summary

- Discrete Event Simulation
 - Two-List Algorithm for Deterministic Execution
- Coverage-Driven Verification
 - Structural (MC/DC)
 - Functional
- Assertion Checking/Coverage
- Combining Formal and Simulation-based Verification for
 - Earlier Sign Off with
 - Increased Confidence