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# A FATIGUE ASSESSMENT TECHNIQUE FOR MODULAR AND PRE-STRESSED ORTHOPAEDIC IMPLANTS

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41 **Abstract**

42 Orthopaedic implants experience large cyclic loads, and pre-clinical analysis is conducted to ensure they can  
43 withstand millions of loading cycles. Acetabular cup developments aim to reduce wall thickness to conserve bone,  
44 and this produces high pre-stress in modular implants. As part of an implant development process, we propose a  
45 technique for preclinical fatigue strength assessment of modular implants which accounts for this mean stress, stress  
46 concentrating features and material processing.

47 A modular cup's stress distributions were predicted computationally, under assembly and *in-vivo* loads, and its cyclic  
48 residual stress and stress amplitude were calculated. For verification against damage initiation in low-cycle-fatigue  
49 (LCF), the peak stress was compared to the material's yield strength. For verification against failure in high-cycle-  
50 fatigue (HCF) each element's reserve factor was calculated using the conservative Soderberg infinite life criterion.  
51

52 Results demonstrated the importance of accounting for mean stress. The cup was predicted to experience high cyclic  
53 mean stress with low magnitude stress amplitude: a low cyclic load ratio ( $R_l = 0.1$ ) produced a high cyclic stress ratio  
54 ( $R_s = 0.80$ ). Furthermore the locations of highest cyclic mean stress and stress amplitude did not coincide. The  
55 minimum predicted reserve factor  $N_f$  was 1.96 (HCF) and 2.08 (LCF). If mean stress were neglected or if the stress  
56 ratio were assumed to equal the load ratio, the reserve factor would be considerably lower, potentially leading to  
57 over-engineering, reducing bone conservation.

58 Fatigue strength evaluation is only one step in a broader development process, which should involve a series of  
59 verifications with the full range of normal and traumatic physiological loading scenarios, with representative  
60 boundary conditions and a representative environment. This study presents and justifies a fatigue analysis  
61 methodology which could be applied in early stage development to a variety of modular and pre-stressed prostheses  
62 concepts, and is particularly relevant as implant development aims to maximise modularity and bone conservation.  
63

66    **1 INTRODUCTION**

67    The fracture and fatigue strength of novel joint replacement implants should be verified against the full range of life  
68    cycle loading. This includes impact and cyclic loads several times the weight of the body, as a result of normal  
69    activities [1] and occasional traumatic events such as stumbles and falls [2]. With over one million high magnitude  
70    load cycles per year [3-5] fatigue must be a primary focus in pre-clinical analysis and testing.

71    Recent acetabular cup implant developments have aimed to reduce wall thickness, which permits an increase in  
72    bearing diameter without requiring additional bone removal during surgery [6-8]. A large bearing diameter promotes  
73    joint stability and reduces the risk of dislocation [9, 10], allowing patients to return to an active lifestyle. Bone stock  
74    preservation is beneficial later, if the implant should need to be revised [11]. However, fatigue strength verification  
75    will become particularly important, because reducing the implant's section thickness will increase its cyclic stress.  
76

77    Modular acetabular cups comprise a ceramic or polymeric bearing insert for low wear articulation, and a titanium  
78    alloy (Ti-6Al-4V) outer shell featuring a rough, bioactive Hydroxyapatite (HA) coating to promote cementless  
79    fixation through osseointegration (Figure 1, left). Modular assembly of the insert and shell by a tapered interference  
80    fit enables a range of implant size options. In ceramic bearing cups, the interference fit generates a compressive  
81    residual stress field in the bearing shell rim, which is protective against ceramic fracture under tensile stresses  
82    generated under *in-vivo* loading [7]. Thinner pre-stressed shells (Figure 1, right) also produce a greater push-out  
83    strength at the taper interface than is achieved with a thicker, stiffer shell [8], theoretically reducing the risk of insert-  
84    shell dissociation *in-vivo* [12, 13]. However, this will also generate higher residual tensile stress in the titanium alloy  
85    shell.  
86



88    **Figure 1: Example Traditional, Thick-Walled Ceramic Cup (Trident ®, Stryker, Mahwah, NJ, reproduced with  
89    permission and copyright © of the British Editorial Society of Bone and Joint Surgery [13], left) and Current, Thin-  
90    Walled Cup (DeltaMotion ®, DePuy International, Warsaw, IN).**

91    Standard ISO and ASTM endurance test methods exist for traditional implant designs, but a challenge to the  
92    bioengineer is the development of clinically representative *in-vitro* tests and computational analysis methods for  
93    novel designs. The same applies to computational studies. Traditional analysis of fatigue strength compares the  
94    material's endurance limit to the peak cyclic stress, and expresses the ratio as the reserve factor ( $N_f$ ). A design is  
95    judged safe under a given load regime if the reserve factor is greater than 1, and this may be an appropriate  
96    simplification if the fatigue stress ratio ( $R_s$ ) is close to zero. The high residual stress scenario in thin walled modular  
97    implants would be expected to produce high mean stress and low stress amplitude conditions (a high stress-ratio  
98    fatigue cycle), for which this traditional fatigue analysis method may be inadequate. Furthermore, there are  
99    geometric design features and manufacturing processes that can alter the fatigue life of an implant. Any analysis  
100   should also include the influence of stress-concentrating design features such as fins for primary cup stability, and  
101   for attachment to surgical instruments for cup introduction, impaction, re-positioning and removal (Figure 1). This is  
102   of particular importance in titanium alloy components, which are notch sensitive [14-16]. The influence of  
103   manufacturing and processing upon the fatigue strength of the materials should also be considered, such as the  
104   105

106 incorporation of coatings which are essential for cementless fixation but have been observed to reduce the material's  
107 endurance limit [17]. If these factors are neglected, analysis may over-estimate a design's reserve factor against  
108 fatigue damage initiation. If these factors are accounted for, the traditional approach mentioned above may under-  
109 estimate the true fatigue reserve factor, leading to over engineering. In the case of an acetabular cup, this would  
110 require increasing the wall thickness at the expense of bone conservation, potentially compromising the patient in  
111 future surgery.

112  
113 The objective of this study was to consider increasingly challenging implant development requirements, and propose  
114 a pre-clinical fatigue strength analysis process for novel modular implant concepts. Using this process, thinner  
115 walled implants may be developed that retain a reserve factor against fatigue damage initiation under *in-vivo* loads,  
116 by accounting for residual and cyclic stresses, and stress concentrating features and material processing methods.  
117  
118

119    2    METHODOLOGY

120    2.1    Case Study Implant Design Details

121    The pre-clinical analysis methodology was applied to a thin walled, pre-stressed acetabular cup concept as a case  
 122    study. The study employed implant geometry and (commercially confident) design details representative of a  
 123    prototype variant of a modular ceramic bearing acetabular cup now in clinical use [7, 8]. The worst-case of the full  
 124    range of prosthesis size options in terms of component stresses was selected for analysis, which was the thinnest  
 125    walled option, featuring a nominal 5mm combined wall thickness of the ceramic bearing and titanium alloy shell  
 126    components.

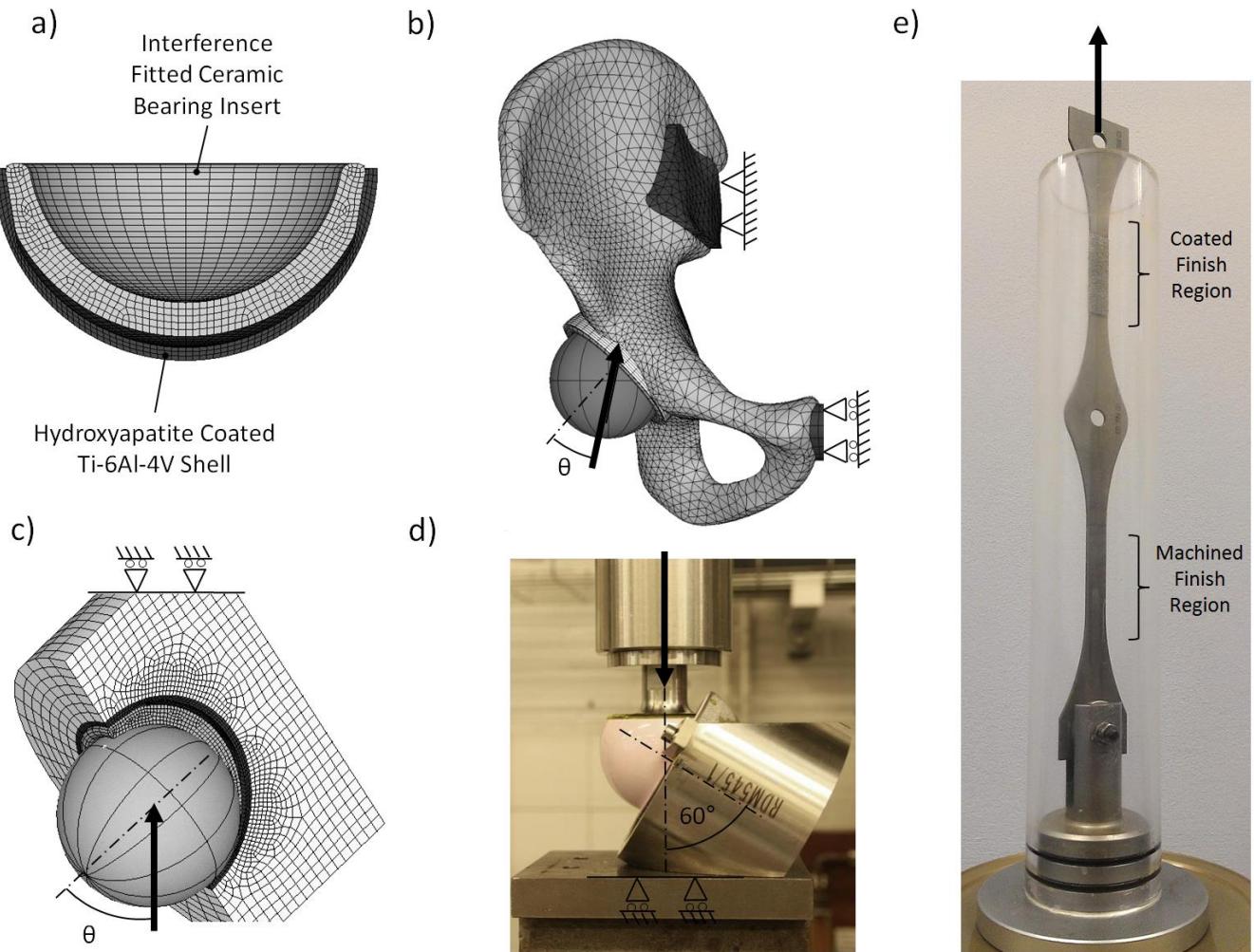
127    2.2    FE Analysis Methodology

128    Finite element (FE) analysis was used to predict the stresses in the implant components under assembly and a range  
 129    of clinical loading scenarios. The implant geometry (Figure 2a) was drawn in SolidWorks CAD software  
 130    (SolidWorks Corp., Concord, MA, USA) imported into ANSYS 14 FE analysis software (ANSYS Inc., Canonsburg,  
 131    PA, USA), map-meshed with 13,200 twenty-node hexahedral elements (64,612 nodes), and its two components were  
 132    assigned linear elastic material properties (Table 1) [18]. A Coulomb slip-stick friction model was used to simulate  
 133    contact between the insert and shell, with a coefficient of static friction of 0.32 (Appendix 2), determined by  
 134    empirical fit to experimental data. Contact employed 8-node surface-to-surface contact and target elements, with an  
 135    Augmented Lagrangian contact algorithm.

136

137

138



139    **Figure 2: Modelling and Testing Arrangements.** a) FE Model Schematic of Acetabular Cup Components, b) FE Model of  
 140    Assembled Cup Implanted in Composite Hemi-Pelvis, c) FE Model of Assembled Cup Implanted in PMMA Support, and  
 141    d) Physical Test Setup with PMMA Support. e) Representative Material Strength and Endurance Data Test Setup with  
 142    Environmental Chamber

143

144

**Table 1: Assigned Material Properties**

Model Region	Material	Young's Modulus (GPa)	Poisson's Ratio
Cup Bearing Insert <sup>a</sup>	BIOLOX Delta (CeramTec AG, Plochingen, Germany)	350	0.22
Cup Outer Shell <sup>b</sup>	Ti-6Al-4V ELI Alloy	114	0.34
Analogue Bone <sup>c</sup>	Cortical Bone: Short Glass Fibre Reinforced Epoxy (Sawbones AG, Malmo, Sweden)	16.7	0.3
	Cancellous Bone: Polyurethane Foam (Sawbones AG, Malmo, Sweden)	0.155	0.3
Test Support Material <sup>d</sup>	PMMA (Technovit ® 3040, Heraeus GmbH, Hanau, Germany)	2.3	0.35

146 <sup>a</sup> [http://www.ceramtec.com/files/mt\\_biolox\\_delta\\_en.pdf](http://www.ceramtec.com/files/mt_biolox_delta_en.pdf) p11 [18,33]147 <sup>b</sup> ASTM F136-12a [18,32]148 <sup>c</sup> [http://www.sawbones.com/catalog/pdf/us\\_catalog.pdf](http://www.sawbones.com/catalog/pdf/us_catalog.pdf) p75 [18,19]149 <sup>d</sup> [http://heraeus-kulzer-technik.de/media/webmedia\\_local/media/metallo/downloads\\_1/BR\\_Technovit\\_englisch.pdf](http://heraeus-kulzer-technik.de/media/webmedia_local/media/metallo/downloads_1/BR_Technovit_englisch.pdf) p24 [20]

150 The cup was modelled as supported in two ways:

- first, implanted in a generic hemi-pelvis geometric model (Zygote Inc., UT, USA) with material properties and cortical shell thickness representing a composite analogue hemi-pelvis model (#3405, Sawbone AG, Malmö, Sweden [19]), fixed in all directions at the sacro-iliac joint, and in the medial-lateral direction at the pubic symphysis (Figure 2b), and
- second, in a laboratory test setup, with the cup mounted in a bed of PMMA potting medium (Technovit 3040 polymethyl methacrylate, Heraeus Kulzer GmbH, Hanau, Germany [20]), fixed at its base (Figure 2c).

151 In both cases, the cup was modelled as fully bonded to the support structure. 7,660 hexahedral elements (34,160 nodes) were used to mesh the PMMA support, and 36,644 tetrahedral solid and triangular shell elements (56,143 nodes) were used to mesh the hemi-pelvis. The support models were assigned homogeneous linear elastic material properties (Table 1). The hemi-pelvis model (total solution time ~12 hours) was used to obtain baseline results to verify the PMMA support of the laboratory test model (total solution time ~2 hours), which was then used with a considerably finer mesh in order to capture a contact stress peaks at the taper interface. These solution times were obtained using a sparse matrix solver, running in-core on a 3GHz, 8GB RAM desktop machine.

152 A range of surgical positioning was assessed by solving the models for a range of cup inclination angles, of 40° (ideal), 55° and 70° (extreme), all with 20° anteversion. This was achieved directly through cup positioning in the hemi-pelvis models, and indirectly, through alignment of the load vector in the PMMA models. Incorporation of a 10° adducted joint contact force vector in the hemipelvis models [1] gave an angle between the force vector and the cup axis of 34.9°, 47.7° and 61.3° for the three models, respectively. A range of joint contact force magnitudes was applied to represent different loading scenarios, justified below.

### 175 2.3 Loading Scenarios

176 Two loads were applied to each model, representing press fitted assembly, and a superimposed cyclic *in-vivo* activity load. Assembly was simulated using displacement control to press the ceramic insert by its rim into the metal shell, supported at its pole [7]. The assembly press was then removed, and coulomb friction at the taper interface maintained the press-fit and the resulting initial pre-stress in the implant.

181 For high cycle fatigue analysis, gait loading was simulated. A joint contact force of 5.8kN was applied to the implant bearing surface through a single, rigid spherical head with frictionless contact. The effects of articulation and bearing friction were considered separately as described in Section 2.4, local to the cup fixation fins, where the resulting torque would be concentrated. The applied force represents the maximum 584% bodyweight load recorded during jogging from instrumented implant clinical studies [21, 22], which is a likely worst-case *cyclic* normal activity load. Hip replacement patients are reported to exert 1-2.5 million gait cycles per year [3-5, 22] upon each lower limb joint. Although the majority of these cycles are walking loads, jogging represents a worst-case.

188  
189 For low cycle fatigue analysis, abnormal or traumatic loads were considered and an 11kN joint contact force was  
190 applied to the head, to represent stumbling or falling. Stumbling is the highest magnitude, commonly occurring load  
191 event experienced at the hip joint during articulation [2, 22], and sideways falling onto the hip is a typical high  
192 magnitude non-articulating load event. The loads resulting from falling are more variable; peak forces are reported to  
193 reach 8-11 times bodyweight [23, 24], depending upon fall velocity, soft tissue thickness and muscle activity [25].  
194 One in three elderly patients experiences a fall in a given year [26], and stumbling without falling is reported to occur  
195 two or more times per month in 9% of this population. For a young patient, 10 stumbles per month is estimated [22].  
196 Hence, during a 20 year implant life, an implant may experience in the order of 2500 stumbles and 7 falls. Therefore,  
197 these load events can be considered as potential low-cycle fatigue loads.  
198  
199

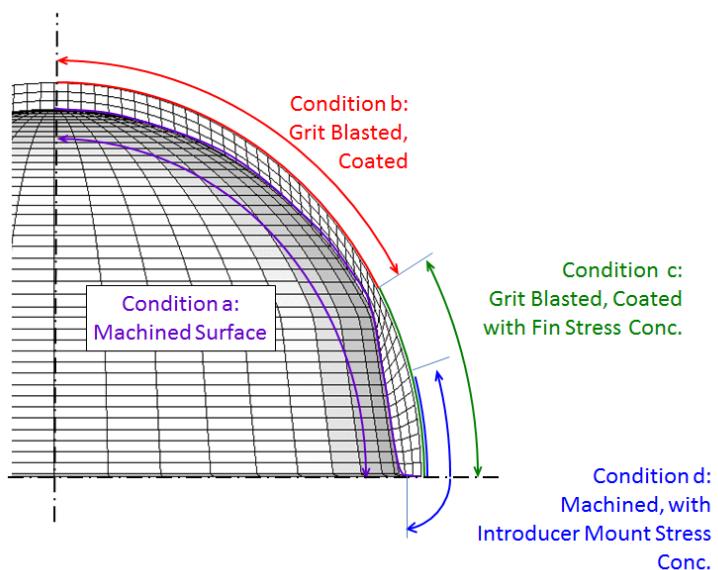
#### 200 2.4 Fatigue Analysis Methodology A: High Cycle Fatigue Loads

201 The assembly loading was predicted to generate a residual tensile stress in the titanium shell; above this, the *in-vivo*  
202 joint contact force was predicted to create additional cyclic tension. The predictions of the FE model were therefore  
203 analysed against an infinite life limit for elastic-plastic materials. Several of these criteria have been established, by  
204 Gerber in 1874 [27], Goodman in 1899 [28], and the most conservative, selected for this study, by Soderberg in 1930  
205 [29].  
206

207 The fatigue reserve factor  $N_f$  versus the Soderberg infinite life limit was calculated as described in Appendix 1 for  
208 each node in the titanium alloy shell. Four sets of parameters were used in the calculation, to represent different  
209 surface finishes and stress concentrations on the cup surfaces (Figure 3):  
210

- 211 a) machined finish on the shell's internal surfaces without stress concentrations,
- 212 b) grit blasted and hydroxyapatite (HA) coated finish on the shell's external surface without stress concentrations,
- 213 c) grit blasted and HA-coated finish in a band around the shell's rim, with additional cyclic stress resulting from  
214 the reaction against torque in the bearing at the shell's anti-rotation fins, and
- 215 d) machined finish in a band around the shell's rim, with additional stress concentration resulting from geometric  
216 features for attachment of the cup's introducer instrument.

216 Machined surfaces were assumed to have a roughness of  $R_a \approx 0.8 \mu\text{m}$ , and grit blasted surfaces a roughness of  $R_a \approx$   
217  $3.6 \mu\text{m}$  [17]. In the band around the shell's rim, which contained regions of material in both surface conditions c and  
218 d, the surface condition which produced the lower reserve factor value was used.  
219



220  
221 **Figure 3: Schematic View of Titanium Shell showing Different Surface Condition Regions for Manufacturing Processes,**  
222 **and Stress Concentrations from Anti-Rotation Fins and Introducer Mounting Features. Not to Scale.**  
223

224 For all cup regions featuring material conditions a-d, each node's cyclic mean stress and stress amplitude were  
225 calculated from the residual ( $\sigma_{assembly}$ ) and peak cyclic ( $\sigma_{jogging}$ ) load cases, accounting for the fatigue load ratio  $R_L$   
226 (Appendix 1). Over the jogging cycle the cyclic load component varies between approximately 10% and 100% of the  
227 peak load [21], so a value of  $R_L = 0.1$  was used. For condition c, the additional cyclic stress resulting from the

reaction of the bearing's frictional torque by the shell's fins (Figure 1) was added to the stress amplitude for all nodes in a band region around the rim of the shell on its external surface (Figure 3). This additional stress amplitude was determined using a sub-model of the shell featuring a tangentially loaded fin (not reported). The tangential load was determined using a friction factor of 0.05, the maximum measured for the bearings in question in a simulator study by Scholes and Unsworth [30], and exerting the bearing frictional torque that this generated over a single fin.

The influence of stress concentrating geometric features in high cycle fatigue was incorporated in the fatigue stress concentration factor  $K_f$  (Appendix 1), as a function of the stress concentration factor  $K_t$ , which accounts for the stress concentrating effect of geometric features in the structure. For conditions a-c, without geometric stress concentrations, the minimum  $K_t = 1$  was used. For condition d, in the region containing the shell's introducer attachment features,  $K_t$  was conservatively estimated from the results of a sub-model of a section of the shell featuring an introducer attachment wire groove (as in Figure 1, not reported), from the ratio of the local peak stress at the introducer attachment feature to the nominal stress in the shell.

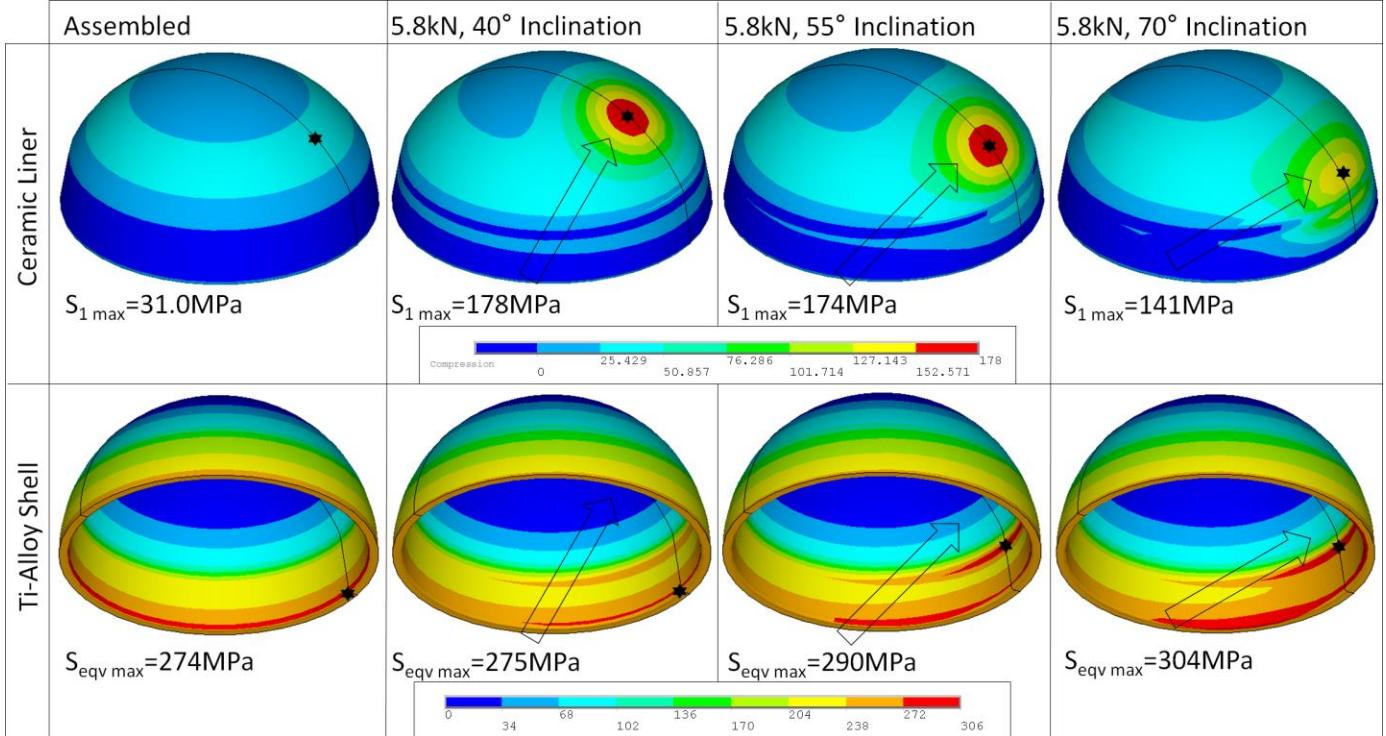
The influence of the shell manufacturing and processing was incorporated in the endurance limit value ( $S_e$ ). A baseline endurance limit for the appropriate Ti-6Al-4V alloy of 500 MPa was used [31] for the machined cases (conditions a and d), and multiplied by a factor of 0.58 to account for the strength reduction caused by grit blasting and plasma-spray coating with HA [17], giving an endurance limit of  $S_e = 290$  MPa for conditions b and c. In all cases the minimum yield strength required by this material's standard [32] of  $S_{yt} = 760$  MPa was used.

## 2.5 Fatigue Analysis Methodology B: Low Cycle Fatigue Loads

The Soderberg approach was used as a conservative criterion to allow design without fatigue damage accumulation under normal, high cycle fatigue loads. However, this approach cannot account for the effects of higher magnitude, low cycle fatigue loads or occasional overloads upon fatigue life. These effects could considerably influence fatigue life through load sequence effects, if damage is accumulated or residual stress is generated by yield. Therefore, low cycle fatigue load events were considered simply, and conservatively, by comparing the material's yield strength to the peak stress under overload conditions, with appropriate stress concentrations applied.

259 **3 RESULTS**

260 In the ceramic bearing insert, assembly was predicted to generate an axisymmetric residual tension field with a peak  
 261 First Principal stress of 31.0 MPa on its external surface, over which the service loads superimposed a local patch of  
 262 biaxial tension (Figure 4 top). In gait this generated a peak tensile stress of up to 178 MPa at 40° inclination, and in  
 263 stumbling this generated up to 233 MPa (Figure 5 top). The interference fit generated approximately 112 MPa of  
 264 compression in the shell rim, which protected this thinner section of the shell against excessive tension at steeper  
 265 inclinations. Therefore in high cycle fatigue the worst case was predicted to occur at 40° inclination, where the  
 266 position of the residual and service loading stress concentrations coincided, and were approximated to a cycle of  
 267  $\sigma_{mean} = 135$  MPa and  $\sigma_{amp} = 66.2$  MPa (or stress ratio  $R_S = 0.26$  for a load ratio  $R_L = 0.1$ ). The peak low-cycle event  
 268 stress was 233 MPa, or 28% of the material's tensile strength.  
 269



270  
 271 **Figure 4: 1<sup>st</sup> Principal Stress in the Ceramic Bearing Insert (top) and Equivalent Stress in the Titanium Alloy Shell  
 272 (bottom) under 5.8kN Gait Loading Arrow indicates Load Vector, Star indicates Peak Location.**  
 273

274 In the titanium alloy shell, assembly generated axisymmetric residual hoop tension with a peak of 274 MPa at the  
 275 shell rim (Figure 4 bottom). The contact pressure on the taper interface under assembly and loading conditions was  
 276 inspected, and positive contact was predicted around the full periphery of the band under all loading conditions. This  
 277 indicated that under standard service loads, the interference fit would be sufficient to avoid disassembly of the cup-  
 278 insert structure. The peak stress under service loading was located on the internal, machined surface, predicted as  
 279 304 MPa at 70° inclination, and at this location to the predicted cyclic stresses were calculated as  $\sigma_{mean} = 274$  MPa  
 280 and  $\sigma_{amp} = 30.5$  MPa (or stress ratio  $R_S = 0.80$  for a load ratio  $R_L = 0.1$ ).  
 281

282 Considering high cycle fatigue, these raw equivalent stress field data for the titanium alloy shell were used to  
 283 calculate the cyclic mean stress and stress amplitude for each *in-vivo* load case, incorporating geometric stress  
 284 concentrations and worst-case error margins of model verification. These were used to calculate the reserve factor vs.  
 285 the Soderberg infinite life limit for each node in the model, using an appropriate endurance limit for the surface in  
 286 question (Figure 6). The worst case of high cycle fatigue in all measures occurred when the cup was loaded as if  
 287 inclined at 70°. The highest cycle mean stress was 335 MPa on the internal surface, and 314 MPa on the external  
 288 surface, both at the shell rim. The highest stress amplitude was 44.3 MPa on the internal surface at the taper  
 289 interface, and 53.6 MPa at the corresponding height on the external surface (Figure 6). The minimum reserve factors  
 290 were calculated as  $N_f = 1.96$  on the internal surface and 1.96 on the external surface, on the taper interface and on the  
 291 shell's coated external surface near the rim, respectively. Considering low cycle fatigue, the peak cyclic stress in the  
 292 titanium shell under the 11 kN traumatic load case was 366 MPa (Figure 5 bottom), or 48% of the material's yield  
 293 strength, a safety factor of 2.08.

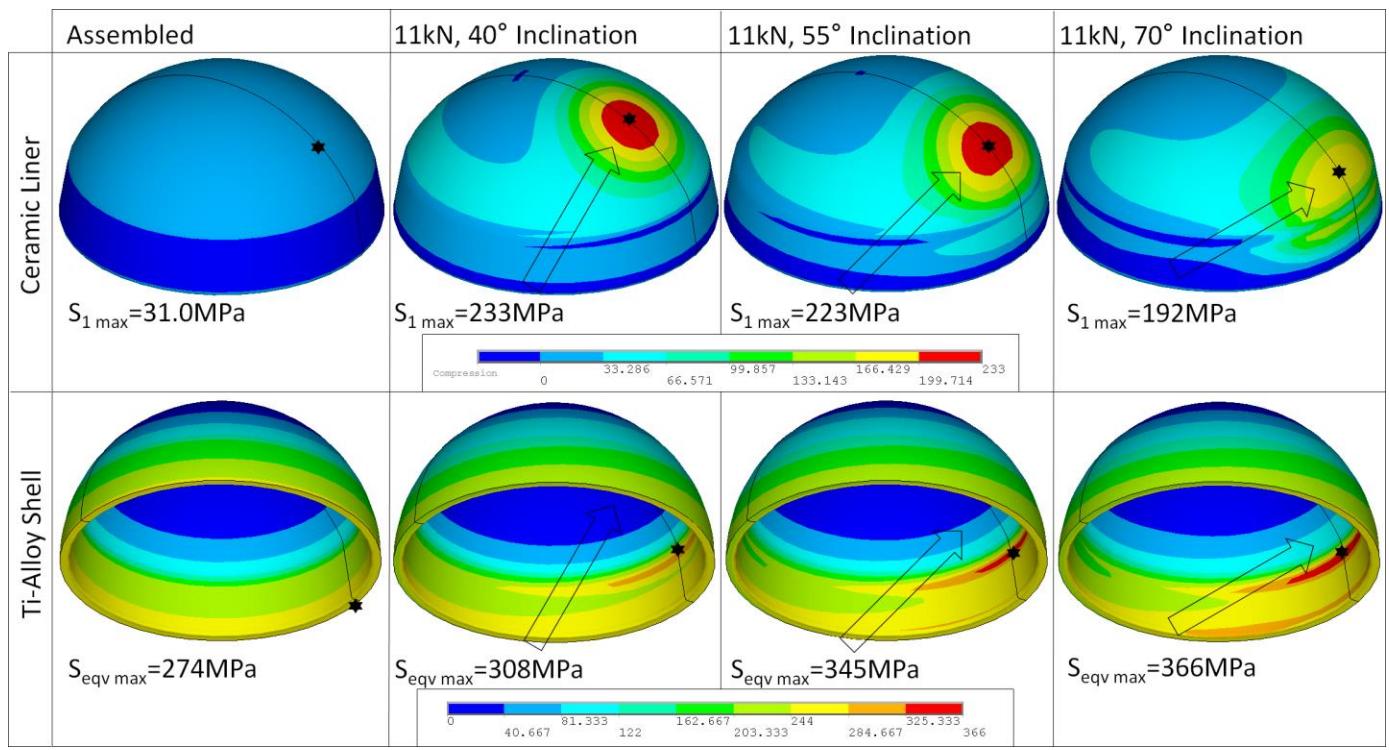


Figure 5: 1<sup>st</sup> Principal Stress in the Ceramic Bearing Insert (top) and Equivalent Stress in the Titanium Alloy Shell (bottom) under 11kN Stumbling Loading Arrow indicates Load Vector, Star indicates Peak Location.

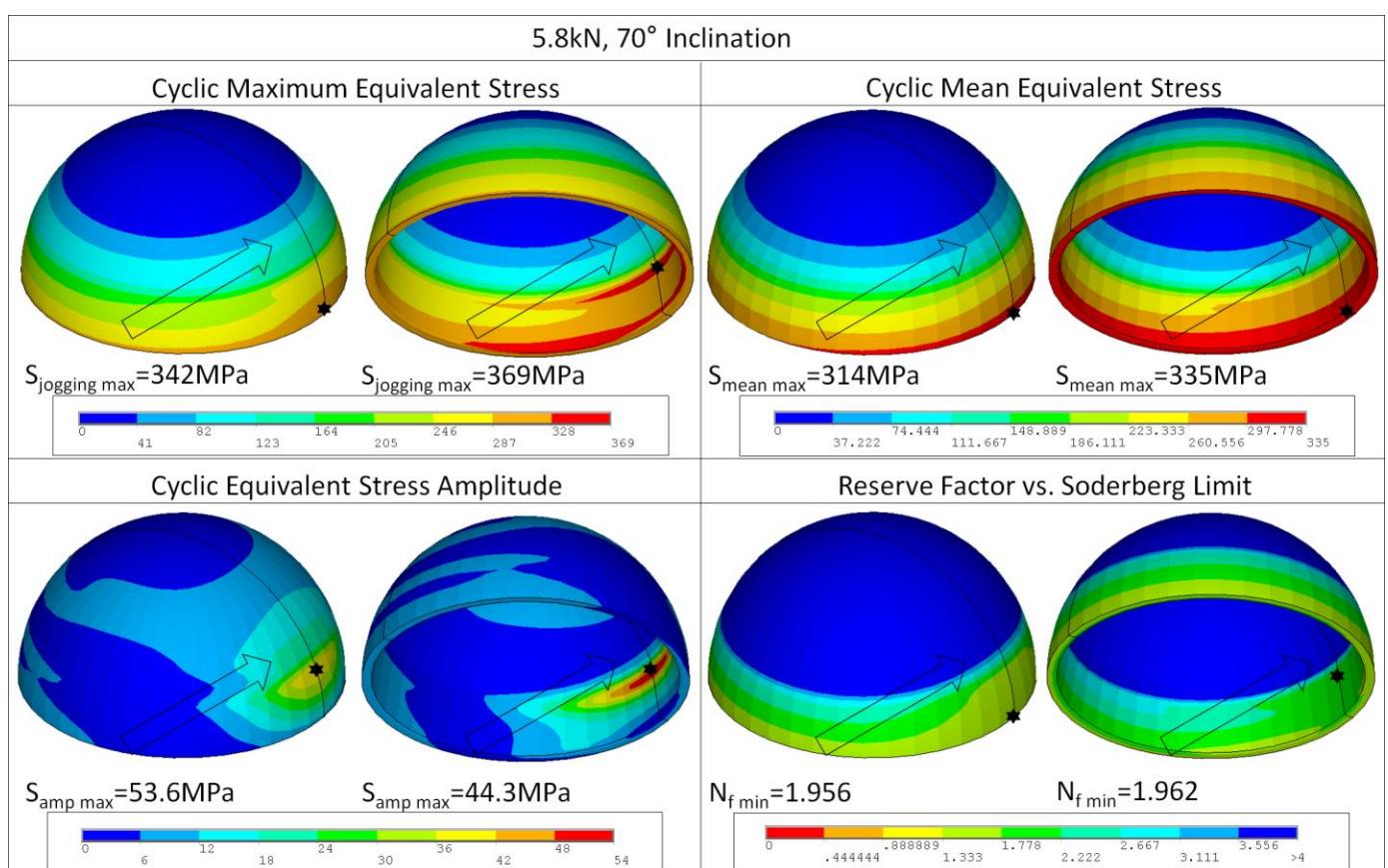


Figure 6: Fatigue Cycle Maximum Stress (top left), Mean Stress (top right), Stress Amplitude (bottom left) and Reserve Factor vs. Soderberg Infinite Life Limit (bottom right) with 70° Cup Inclination. Results shown on External and Internal Surfaces. Arrow indicates Load Vector, Star indicates Peak Location.

These results were corroborated by physical testing (Appendix 2).

305 **4 DISCUSSION**

306 In this study, a fatigue strength assessment methodology for the pre-clinical analysis of modular assembled implants  
307 was demonstrated, using a case-study prototype thin-walled modular acetabular cup, analysed under assembly and  
308 *in-vivo* loading.

310 Predictions from computational analysis suggested that in both implant components, the peak tensile stresses would  
311 be insufficient to cause static failure under traumatic loading. The peak ceramic insert tensile stress was 233 MPa, in  
312 biaxial flexion, 3.56 times below the material's estimated 830 MPa tensile strength. This value was based on a  
313 reported flexural strength of 1384 MPa [33] and the typical 60% ratio of the tensile strength to the flexural strength  
314 for this material type [18]. The peak titanium alloy shell equivalent stress was 366 MPa, 2.08 times below its 760  
315 MPa lower bound yield strength. This was used as verification of the cup under low cycle fatigue conditions.

317 Fatigue analysis under worst-case high cycle loads, representing jogging, considered the mean and cyclic stresses in  
318 comparison to the conservative Soderberg infinite life limit. This took account of the influence of cup manufacturing  
319 methods upon material endurance, and the implicit influence of stress concentrating design features such as fins and  
320 introducer attachment points. For the case study cup concept, this approach predicted reserve factors above 1.96 for  
321 the titanium alloy shell, over a range of loading directions.

323 Considering the ceramic bearing component, published fatigue strength data for the BIOLOX *delta* ceramic material  
324 (CeramTec GmbH, Plochingen, Germany) was sparse. One reported study assessed its fatigue life under extreme  
325 mechanical and environmental conditions for biomechanical applications, and observed no fatigue failures and no  
326 reduction in static strength after 20 million 300 MPa flexion fatigue cycles and hydrothermal aging equivalent to 20  
327 years *in-vivo* [34]. Their conditions were more extreme than the predicted stresses in this cup concept.

329 Fatigue assessment using a single *in-vivo* FE analysis and the Goodman, Gerber and Soderberg limits has precedence  
330 in pre-clinical analysis of existing and conceptual mono-block implants [35, 36]. The modified approach used in this  
331 study, employing full-field analysis of stresses both from residual *and* superimposed *in-vivo* loads was justified  
332 where the fatigue stress ratio  $R_s$  may be considerably larger than the fatigue load ratio  $R_l$  in pre-stressed modular  
333 implants. As a result it was observed that in pre-stressed modular cups, with high residual stress in the titanium alloy  
334 shell, the locations where the peak cyclic mean stress and peak cyclic stress amplitude were experienced did not  
335 correspond with each other, or with the minimum reserve factor location (Figure 6). Conversely, the ceramic  
336 component demonstrated a more conventional low stress ratio, as its residual tensile stresses are lower, so its peak  
337 cyclic stresses corresponded with its overall peak stress (Figure 4).

339 A key step in the verification of design concepts using this methodology would be the collection of case-specific  
340 yield strength and endurance limit data at the appropriate  $R_s$  ratio. This would be collected for each of the modelled  
341 surface conditions, employing the relevant material processing methods, treatments and coatings. A mechanical test  
342 arrangement for collecting case-specific data to add confidence to the technique could include series testing of  
343 machined and coated material finishes, and should be conducted in a representative environment such as Ringers  
344 solution (Figure 2e). It should be noted that this study aims to present the justification of a general fatigue strength  
345 evaluation process for modular implants, rather than to present a testing and analysis process for acetabular cups in  
346 particular. Researchers aiming to employ this process should conduct their own, case-specific material strength  
347 characterisation and model validation exercises.

349 The simulations and tests are subject to several limitations. The true clinical scenario that these models aim to  
350 describe is highly non-deterministic, subject to variability in loading, surgical positioning and the mechanical  
351 properties of the supporting bone and its interface with the implant. Moreover, the geometry of the cup components  
352 is not constant, with each dimension varying across a manufacturing tolerance range. This will have a considerable  
353 effect upon the elastic energy stored in the taper interface and the transmission of stress into the supporting material.  
354 Confidence in the computational analysis could be increased with the consideration of these variables through  
355 probabilistic methods. However, there is no theoretical limit to the range and magnitude of traumatic loads which  
356 can be imposed upon orthopaedic implants, so worst-case test methods and conservative pass criteria must be  
357 defined. In this example, worst realistic case normal, non-microseparating loading (high cycle fatigue) and  
358 occasional overloading (low cycle fatigue) scenarios were simulated, and the results were analysed using  
359 conservative endurance limit, yield strength, stress concentration factor and notch sensitivity factor values. This  
360 approach is conservative and will lead to some additional over-engineering, but it negates the effects of load

361 sequence interactions for the loading regime considered, and is safer for the orthopaedic implant application where  
362 no fatigue damage accumulation may be tolerated. Even worse cases of surgical positioning could occur, but it must  
363 be assumed that these rare cases would be detected during clinical follow-up, and corrected.

364 It is important to note that the analyses presented here represent part of a larger structural verification process:  
365 further testing and analysis would consider the effects of traumatic loading with micro-separation between the head  
366 and the cup, and dynamic bearing edge-loading. These adverse loading conditions may have little clinical  
367 consequence in thicker walled traditional designs [37] but could be of greater concern for thinner-walled implants.  
368 Furthermore, while the presented approach is justified for analysis of the risk of component structural failure through  
369 a single stress concentration, it may not be applicable for predicting progressive failure modes, or failures in the  
370 supporting bone and at fixation interfaces. For example, to predict fatigue micro-cracking of bone cement, or  
371 accumulated damage at a cementless implant-bone fixation interface, a different analysis approach is required, such  
372 as a cumulative fatigue or damage model [38]. Fatigue strength evaluation is only one step in a broader development  
373 process, which should involve a series of verifications with the full range of normal and traumatic physiological  
374 loading scenarios, in a representative environment.

375 The models were also a necessary simplification of the clinical scenario, in order to avoid biasing the development of  
376 the novel prosthesis to a single pelvis. This involved the use of simplified support geometry and stiffness, and there  
377 is a case to develop a generalised test setup for this purpose [39, 40]. Furthermore each model considered a single  
378 quasi-static load vector angle representing the peak joint contact force of the gait cycle. In an axisymmetric  
379 acetabular cup, in which the joint contact force primarily generates tensile stress, this can be accounted for by the  
380 analysis of a range of cup loading angles. However, the analysis of several quasi-static load cases may be necessary  
381 to analyse other implants such as femoral heads and stems, in which the range of joint contact force vector angles  
382 may generate anterior-posterior reverse bending. Bending and articulation generates cyclic tension and compression,  
383 which has long been recognised clinically and was a cause of failure of early femoral stems [41].

384 Further limitations of the modelling process relate to assumptions regarding the fixation between the implant and  
385 bone or support material. Researchers employing this technique will need to make assumptions regarding press-  
386 fitting of cementless fixed implants, the frictional characteristics, and degree of bonded fixation at the implant-bone  
387 interface. This was resolved in the current case-study by considering, in the fatigue stress analysis, additional  
388 stresses that would result from a worst-case of fixation (Section 2.4). This model represented a scenario in which the  
389 bearing frictional torque was sustained by a single fin, indicating complete de-bonding between the cup's fixation  
390 surface and the bone.

391 Care must be taken when using FE models to obtain absolute predictions of stresses, in particular where  
392 discontinuities of geometry or material properties produce stress concentrations. This is relevant to modular  
393 assemblies, where the edge of the contact interface can produce a geometric stress concentration. This factor is of  
394 particular importance with the presented methodology, which is a post-processing of absolute stress predictions.  
395 Stress results must be therefore be verified, and where possible the models validated, in both modular components.  
396 Stress also converges with mesh refinement more slowly than deflections and strain energy [42]. The presented  
397 technique requires accurate stress predictions and therefore thorough assessment of mesh convergence, especially at  
398 potentially stress concentrating edges of contact pairs. This may be achieved through local mesh refinement, use of  
399 p-method FE analysis, or in cases of divergent stress concentrations, the application of stress-concentration-limiting  
400 finite element methods [43]. This approach requires empirical, case-specific data which describes stress attenuation  
401 around stress raising geometry. A simplification of the model related to stress concentrations was the sub-modelling  
402 of the stress concentrating features in the titanium alloy shell. There is the potential that stress concentrating features  
403 in the shell could produce additional stress concentrations in the liner. This was predicted to be only a small effect  
404 with the present implant design, where all stress concentrating features were located in the outside of the metal shell,  
405 but should be considered when this process is applied to other designs.

406 The methodology presented here may have other applications, including the analysis of existing designs which  
407 demonstrate elevated clinical failure rates. The influence of cyclic stresses and wear upon damage at taper interfaces  
408 in modular femoral total hip implants has recently become a subject of particular concern. Clinical evidence  
409 suggests modular taper interfaces may be a source of metal ions, and hence have an influence upon metal sensitivity  
410 reactions [44]. This is also a region of sufficiently high stress to have caused clinical fatigue failures in primary [45]  
411 and revision replacements [46]. Furthermore, whilst bulk mechanical failure of mono-block femoral stems is now a  
412 very rare occurrence, there have been clinical reports of fractures of femoral stems with modular necks, linked to

418 fatigue in Ti-6Al-4V [47] with the possible influence of fretting and corrosion [48, 49] and consistent with regions of  
419 high stress [50]. The approach presented in this study may be applied to understand these clinical failure modes,  
420 extended to incorporate the effects of fretting and corrosion in the endurance limit and stress concentration factors  
421 employed.

## 424 5 CONCLUSIONS

425 This study demonstrates a pre-clinical analysis method for modular orthopaedic implant designs under cyclic  
426 loading, for which the analysis of peak stresses alone may be insufficient. Computational analyses based on  
427 conservative input data and corroborated by physical tests indicated that a case study acetabular cup implant's  
428 structural integrity was sufficient to sustain extreme normal cyclic *in-vivo* loads (i.e. without impingement or  
429 microseparation), when correctly implanted and when malpositioned. The methods illustrate the importance of  
430 considering modular assembly residual stresses upon an implant's strength, alongside stress concentrating effects  
431 arising from manufacturing processes and geometric features. Fatigue strength evaluation is only one step in a  
432 broader development process, which should involve a series of verifications with the full range of normal and  
433 traumatic physiological loading scenarios, with representative boundary conditions and a representative environment.  
434 This study presents and justifies a fatigue analysis methodology which could be applied in early stage development  
435 of a wide range of novel prosthesis designs, and is particularly relevant as implant designs aim to conserve bone at  
436 the expense of reduced safety factors compared to over-engineered traditional designs.

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## 443 7 DECLARATIONS

### 444 Competing Interests:

445 None Declared.

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### 450 Ethical Approval:

451 Not Required.

455    8 APPENDIX 1: FATIGUE DAMAGE RESERVE FACTOR CALCULATIONS

456    According to Soderberg [29], the reserve factor against high cycle fatigue damage accumulation under a defined  
 457    loading scenario giving non-zero mean stress was calculated using Equation 1:  
 458

$$459 \quad N_f = \left( \frac{K_f \times \sigma_{amp}}{S_e} + \frac{\sigma_{mean}}{S_{yt}} \right)^{-1} \quad (1)$$

460 where:

461     $K_f$       = the fatigue stress concentration factor,  
 462     $\sigma_{amp}$     = the cyclic stress amplitude,  
 463     $\sigma_{mean}$    = the mean stress,  
 464     $S_e$        = the material's endurance limit,  
 465     $S_{yt}$        = the material's yield strength, and  
 466     $N_f$        = the resulting predicted reserve factor.

467  
 468 Each node's cyclic mean stress and stress amplitude were calculated from the residual ( $\sigma_{assembly}$ ) and peak cyclic  
 469 ( $\sigma_{jogging}$ ) load cases, accounting for the fatigue load ratio  $R_L$ . The peak cyclic stress ( $\sigma_{jogging}$ ) contains contributions  
 470 both from the applied joint contact load and the assembly pre-load. The mean stress (Eq.2a) was calculated using the  
 471 cycle stress at maximum 'stance' load ( $\sigma_{max}$ , Eq.2b) and at minimum 'swing' load ( $\sigma_{min}$ , Eq.2c). As the maximum  
 472 stress could occur under the maximum *or* the minimum load, due to the assembly's pre-stress, the stress amplitude  
 473 was calculated as the modulus of the half-difference between stance and swing load stresses (Eq.2d):  
 474

$$\sigma_{mean} = \frac{(\sigma_{max} + \sigma_{min})}{2} \quad (2a)$$

$$\sigma_{max} = \sigma_{jogging} \quad (2b)$$

$$\sigma_{min} = \sigma_{assembly} + R_L \times (\sigma_{jogging} - \sigma_{assembly}) \quad (2c)$$

$$\sigma_{amp} = \left| \frac{(\sigma_{max} - \sigma_{min})}{2} \right| \quad (2d)$$

475  
 476  
 477 The influence of stress concentrating geometric features in high cycle fatigue was incorporated in the fatigue stress  
 478 concentration factor  $K_f$ , calculated by Equation 3:  
 479

$$480 \quad K_f = 1 + q(K_t - 1) \quad (3)$$

481  
 482 where  $q$  is the notch sensitivity factor (0 - 1) and  $K_t$  is the stress concentration factor ( $\geq 1$ ). A notch sensitivity factor  
 483 for Ti-6Al-4V of  $q = 0.44$  was used [51], appropriate for the present scenario's predicted fatigue stress ratio ( $R_s$ ,  
 484 obtained from the FE results).

489    **9 APPENDIX 2: MODEL VERIFICATION AND VALIDATION**

490 All FE model meshes were verified with convergence analyses considering peak stress values (implant model) and  
491 peak deflections (support models). Preliminary FE analyses produced comparable stress distribution predictions for  
492 the hemi-pelvis and PMMA supported cups, and showed that the stiffer PMMA support produced a conservative  
493 case, with approximately 25% higher implant stresses. The more computationally efficient PMMA supported model  
494 was used for the fatigue analysis, as it permitted a considerably finer mesh to be used, of particular importance for  
495 assessment of stress concentrations in the implant. Stresses in the titanium alloy structures remained below the  
496 material's yield strength, verifying the use of a linear elastic material model.

497 The coefficient of friction used in both models for the ceramic liner – titanium alloy shell interface was determined  
498 by empirical fit between the FE model and physical test assemblies. The axial press-in displacement of the liner  
499 relative to the shell was compared at a set assembly load, for coefficients of friction of 0.20, 0.25, 0.30, 0.35 and  
500 0.40. For these C.O.F. values and nominal (mid-tolerance) dimension cup geometry, the predicted displacement was  
501 115%, 107%, 101%, 96% and 91%, respectively, of the mean of ten repeat physical test results. Therefore, by fitting  
502 a second order polynomial to the data, a C.O.F. of 0.32 was selected.

503 The PMMA-supported model was validated experimentally in terms of the generated residual cup stress, using  
504 uniaxial strain gauges to measure the circumferential strain at two locations in eight titanium shells. The  
505 circumferential stress was calculated from the strain data, and their mean value agreed with the FE analysis  
506 predictions to within 10%. Therefore an error margin of 10% was incorporated in the fatigue analysis by applying a  
507 scaling factor of 1.21 to all stresses, compounding the error margin for the two analyses. Validation of the PMMA  
508 supported model versus the hemi-pelvis support was not conducted.

509 For further verification combining the assembly and *in-vivo* loading, physical testing was conducted with prototype  
510 cups. Five cups were fatigue tested using an Instron 8878 axial servo-hydraulic machine (Instron Corp., Norwood,  
511 MA, USA. Capacity 25 kN). The cups were potted in aluminium cylinders with Technovit PMMA at an angle of 60°  
512 to horizontal, and loaded with a compatible modular ceramic ball head between 0.580 kN and 5.80 kN  
513 (approximately 584% bodyweight, load ratio  $R_L = 0.1$  [21]) at a frequency  $f = 30\text{Hz}$  for 10 million cycles. 60°  
514 inclination was the steepest of the modelled loading angles which could be tested practically (Figure 2d), and is  
515 likely to be the most extreme clinical condition. Cups were oriented rotationally so that the stress concentrating  
516 introducer attachment features would align with the highest shell stress location, giving a worst case of positioning.  
517 A limitation was that frictional torque was not included in the fatigue test scenario described, so these effects would  
518 require verification with additional testing, for example on a hip simulator with appropriate support. Following  
519 fatigue testing, the cups were disassembled and the ceramic components were inspected using dye penetrant (Rocol  
520 Flawfinder ®, Rocol Ltd., Leeds, UK) to identify any surface damage. Finally, static burst tests were carried out on  
521 three additional, new cups inclined at 60°, using an Instron 1196 electromechanical test machine applying 0.5 kN/s  
522 ramped loading, until failure or a load of 100 kN was achieved. No cups failed during 10 million fatigue cycles. No  
523 surface damage was observed on inspection using dye penetrant. No cups failed at 100 kN static loading. One cup  
524 was loaded up to 187.5 kN, and failed due to fracture of the ceramic bearing insert.

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