Energy Efficient Visible Light Communications Relying on Amorphous Cells

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Abstract—In this paper, we design an energy efficient indoor Visible Light Communications (VLC) system from a radically new perspective based on an amorphous user-to-network association structure. Explicitly, this intriguing problem is approached from three inter-linked perspectives, considering the cell formation, link-level transmission and system-level optimisation, critically appraising the related optical constraints. To elaborate, apart from proposing hitherto unexplored Amorphous Cells (A-Cells), we employ a powerful amalgam of Asymmetrically Clipped Optical Orthogonal Frequency Division Multiplexing (ACO-OFDM) and transmitter pre-coding aided Multi-Input Single-Output (MISO) transmission. As far as the overall systemlevel optimisation is concerned, we propose a low-complexity solution dispensing with the classic Dinkelbach's algorithmic structure. Our numerical study compares a range of different cell formation strategies and investigates diverse design aspects of the proposed A-Cells. Specifically, our results show that the A-Cells proposed are capable of achieving a much higher energy efficiency per user compared to that of the conventional cell formation for a range of practical Field of Views (FoVs) angles.

Index Terms—Energy Efficiency, Optical Wireless, Small Cells, Optical OFDM, Optical MIMO

I. INTRODUCTION

1) Background: Improving the attainable energy efficiency has been one of the salient design objectives of modern wireless communications [1]. In the post-4G era, quantifying energy efficiency became a challenge owing to the emerging Heterogeneous Networks (HetNet) in pursuit of 'green' designs [2]-[6]. With the launch of the global 5G research initiatives, the community expanded its horizon from Radio Frequency (RF) cellular networks both to millimetre wave [7] and to optical wireless concepts [8]. Owing to this paradigmshift to higher frequencies, the disruptive large-scale Multi-Input Multi-Output (MIMO) architecture has attracted substantial interests, with the goal of further improving the achievable energy efficiency [9]. Apart from the classic perspectives on energy efficiency, the novel concepts of wirelessly powered communications [10], [11] are also emerging. Despite all the above advances, there is a paucity of literature on designing

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energy efficient optical wireless systems, especially indoor Visible Light Communications (VLC) systems.

With the advent of high-power Light Emitting Diodes (LEDs) and high-sensitivity Photo-Diodes (PD), the VLC concept appears to be especially promising in the small-cell family of the 5G era [12]. By modulating the visible light produced by the LEDs way above the human eye's fusion frequency, the dual goal of communication and illumination can be realised simultaneously. The pioneering implementation of VLC using LEDs was carried out by the Nakagawa laboratory in 2004 [13], which stimulated significant research attention. The link-level data rates of 100s of MBits/s have been reported using state-of-the-art LEDs and photo-detectors [14]. The modulation schemes have evolved from simple pulse based modulation to more sophisticated Asymmetrically Clipped / DC-biased Optical Orthogonal Frequency Division Multiplexing (ACO/DCO-OFDM) [15], [16]. More ambitious GBits/s targets have also been achieved with the aid of optical MIMO techniques [17] and by using advanced LEDs [18]. Apart from these exciting link-level achievements, the system-level study of VLC has also been developed for broadening its scope beyond point-to-point applications [19]–[24].

2) Motivation: However, most of the above-mentioned VLC research aimed for increasing the attainable throughput, whilst paying less attention to energy efficiency. In fact, LEDs are primarily used for illumination, where typically a constant DC power is provided to satisfy the illumination requirements and to maintain sufficient forward biasing voltages across the LEDs for communications. Hence, the additional communication function should not perturb the illumination requirements nor should it violate the LEDs physical limits. Desirably, the extra communication-related power consumption invested should also be as low as possible, while maintaining a minimum required Quality of Service (QoS). This is also true when no illumination is required during daytime. Hence, valuable research has been dedicated to link-level energy efficiency focusing on brightness and dimming control with the aid of both modulation-related [25], [26] and coding-related [27], [28] techniques. However, there is no system-level investigation on energy efficient VLC systems supporting multi-users, which may require a radically new design approach.

When considering the attainable system-level energy efficiency of a particular network, the specific structure of associating the users with the network plays a crucial role. As a result, it has limited benefits to optimise the power consumption of an inefficient user-to-network association structure. Thanks to the flexibility in indoor VLC systems design [12], we advocate an amorphous user-to-network association structure for indoor VLC systems. To elaborate, in conventional structures, the cells are typically formed from a network-centric perspective, without taking into account the users' positions, where the design flow is based on defining a cell constituted by one or more Access Points (APs) and then associating the users with it. In RF cellular systems having hundreds or thousands of random uniformly distributed users, the conventional structure may indeed be applicable. However, when considering an indoor VLC system supporting only a few dozen users, naively applying the conventional structure may become inefficient, since the users are sporadic. Moreover, in VLC systems, the number of APs may be higher than the number of users, creating an ultra dense AP deployment. Hence, we propose Amorphous Cells (A-Cells) from a user-centric point of view by considering the users' positions, where the design flow is based on grouping the users together and then associating the APs with them, resulting in irregular shape cells.

- 3) Scope: We design an energy efficient indoor VLC system relying on an amorphous structure under practical optical constraints by considering three interlinked design aspects, namely the cell formation, the link-level transmission and the system-level power allocation. Logically, the cell formation strategy determines the specific association between the APs and users, while the transmission strategy and the power allocation jointly determine the signal strength and the amount of interference. Explicitly,
 - we propose two A-Cells formation techniques, namely the edge-distance and centroid-distance based A-Cells. The beneficial construction of A-Cells constitutes the basis of a structurally energy efficient indoor VLC system;
 - we propose a new link-level transmission scheme by amalgamating the ACO-OFDM and our Vector Transmission (VT) and Combined Transmission (CT) based Multiple Input Single Output (MISO) transmission of [12];
 - we propose an efficient low-complexity algorithm for maximising the system-level energy efficiency employing the advocated link-level transmission scheme associated with the proposed A-Cells.

Our paper is organised as follows. In Section II-A, we embark on designing the proposed amorphous structure, while in Section II-B, we discuss the transmission schemes employed and finally we perform system optimisation in Section II-C. The achievable performance of our design is characterised in Section III and we close in Section IV.

II. SYSTEM DESCRIPTION

Consider an indoor VLC environment having N APs uniformly installed on the ceiling, where each AP is constituted by an array of L LEDs pointing vertically downwards. These APs will be used for communicating with K users and at the same time for providing illumination. As discussed before, supporting wireless communications should not violate the main illumination requirements and should obey the LEDs

physical limits. Hence, the communications-related power investment should be as low as possible in order to minimise the perturbations imposed on the lightening function, while maintaining a minimum required QoS. This leads to communications-related energy efficiency maximisation as

$$\max_{\mathcal{F},\mathcal{T},\mathcal{P}} f_t(\mathcal{F},\mathcal{T},\mathcal{P})/f_p(\mathcal{F},\mathcal{T},\mathcal{P}),\tag{1}$$

where $f_t(\cdot)$ represents the achievable throughput, which is a function of the cell formation strategy \mathcal{F} , of the link-level transmission strategy \mathcal{T} and of the power allocation strategy \mathcal{P} . Furthermore, $f_p(\cdot)$ represents the power consumption, which is also a function of \mathcal{F} , \mathcal{T} and \mathcal{P} . Since \mathcal{F} and \mathcal{T} are potentially enumerable, we can reformulate (1) given \mathcal{F} and \mathcal{T} as 1 .

$$\max_{\mathcal{P}} f_{t|\mathcal{F},\mathcal{T}}(\mathcal{P})/f_{p|\mathcal{F},\mathcal{T}}(\mathcal{P}). \tag{2}$$

To adopt a clear structure, we will elaborate 1) on the cell formation strategy in Section II-A by describing the channel characteristics in Section II-A1, then introducing the motivation of A-Cells in Section II-A2 and finally detailing the construction of A-Cells in Section II-A3; 2) on the transmission strategy in Section II-B by introducing ACO-OFDM and MISO transmission in Section II-B1 and Section II-B2 respectively, and then introducing the optical constraints in Section II-B3; 3) on the power allocation strategy in Section II-C by outlining our problem formulation, transformation and simplification in Section II-C1, Section II-C2 and Section II-C3, respectively.

A. Amorphous Structure

Fixing \mathcal{F} in (1) not only reduces the complexity of the problem, but also constitutes a logically appealing arrangement, since cell formation is the pivotal system design stage.

1) Channel Characteristics: Before introducing the cell formation strategy, a brief description of the VLC channel characteristics is essential. The optical channel between the kth user and the nth AP is constituted by both the direct Line-of-Sight (LoS) component $h_{k,n}^0$ and its reflections, but we only consider the first reflection $h_{k,n}^1$, since higher-order indirect reflections are typically negligible. Specifically, the LoS component is given by [13]

$$h_{k,n}^{0} = \frac{(m_L + 1)A_{PD}}{2\pi d^2} \cos^{m_L}(\theta) \cos(\psi) f_{of}(\psi) f_{oc}(\psi), \quad (3)$$

where the Lambert index $m_L=-1/\log_2\left[\cos(\phi_{1/2})\right]$ depends on the semi-angle $\phi_{1/2}$ at half-illumination of the source. A_{PD} is the physical area of the PD receiver, d is the distance between the kth user and the nth AP, θ is the angle of irradiance from the nth AP and ψ is the angle of incidence at the kth user. Still referring to (3), $f_{of}(\psi)$ and $f_{oc}(\psi)$ denote the gain of the optical filter and of the optical concentrator employed, respectively. Furthermore, $f_{oc}(\psi)$ can be written as

$$f_{oc}(\psi) = n_r^2 / \sin^2(\psi), \psi \le \psi_F; \quad f_{oc}(\psi) = 0, \psi > \psi_F, \quad (4)$$

¹Re-evaluating (2) upon the change of cell formation and transmission strategy would impose an excessive complexity. Fortunately, indoor VLC systems typically have low-mobility. Hence, updating (2) semi-adaptively, not instantaneously, strikes a comprise, although the optimal updating frequency is application-specific. However, these interesting points are out of our scope.

where ψ_F represents half of the receiver's Field-of-View (FoV) and n_r is the refractive index of a lens at a PD receiver. By contrast, the first reflected component is given by [13]

$$h_{k,n}^{1} = \sum_{v} \sum_{\tau} \frac{\rho_{r} A_{r} d^{2}}{d_{v,\tau,1}^{2} d_{v,\tau,2}^{2}} \cos(\alpha_{v,\tau}) \cos(\beta_{v,\tau}) h_{k,n}^{0}, \quad (5)$$

where $d_{v,\tau,1}$ is the distance between the nth AP and the (v,τ) th reflection point, while $d_{v,\tau,2}$ is the distance between the (v,τ) th reflection point and the kth user. Furthermore, $\alpha_{v,\tau}$ and $\beta_{v,\tau}$ denote the angle of incidence for the incoming light and the angle of irradiance for the outgoing light at the (v,τ) th reflection point, having a tiny area of A_r and a reflectance factor of ρ_r . Furthermore, the pair of summations in (5) represent all the reflections from the walls. Finally, the aggregated channel between the kth user and the nth AP is given by $h_{k,n}=h_{k,n}^0+h_{k,n}^1$, where we assumed single-tap channel response. In the following, we use only the LoS component for constructing the A-Cells, but we will use the aggregated channel for the rest of our design.

2) Motivation of A-Cells: Fig 1 portrays the conventional structure (left) and the amorphous structure (right) for a $15m\times15m$ indoor VLC system having 8×8 APs (marked by squares) and 20 users (marked by circles) under three typical scenarios (same, more and less number of cells), where the users' positions are drawn from a uniform random distribution, whilst employing the parameters of Table I. Owing to space-limitations, in Fig 1 we only show the edge-distance based A-Cells having a predefined distance threshold of $d_0 = 3.5m$.

Conventional cells typically have a fixed shape. For example, we may partition the $15m\times15m$ indoor environment into four square-shaped cells having $(4\times4)=16$ APs per cell, where the users are associated with cells depending on the users' positions relative to the square-shaped boundary amongst the cells. Within each cell, we may switch off the communications function of the specific APs having no LoS links to the users in their vicinity (indicated by hollow small squares), since improving the energy efficiency is our goal. The related examples may be seen in the left of Fig 1, where we refer to this bench-marker as 'S16'. Similarly, we also have the special bench-marker of 'S1', which represents the scenario of using each AP to create an individual cell and again, the idle mode is used for those APs, which have no LoS links to the users in order to save energy [29].

A common observation concerning the conventional arrangement 'S16' in the left of Fig 1 is that the resultant cells are all constrained within the four partitioned areas. However, this arrangement may not be the most appropriate. For example, in the southwest cell of Fig 1a, the 'boundary user' 'A' is clearly far from user 'C' in the same cell, but it is more close to user 'B' in the neighbouring cell. Hence, there might be a tendency for user 'A' to separate from user 'C' and to join user 'B', as seen in Fig 1b of A-Cells. This is also true for the 'boundary user' 'D' in the northeast cell of Fig 1a, since it is more close to the users located in the southeast cell, than to the rest of the distant users in the same cell. More examples are shown in Fig 1c, where two clusters of boundary users highlighted by ellipses join A-Cells of Fig 1d. In addition to a different user-to-network association, the status

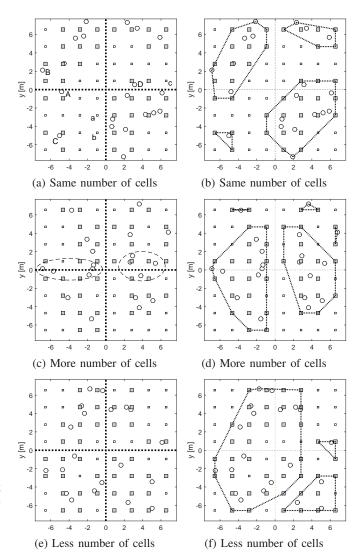


Fig. 1: Illustration of the conventional (left) and the amorphous structure (right) for VLC indoor systems.

of APs is also different, where for example, APs ('a','b','c') were switched from idle mode in conventional cells of Fig 1a to become active in the A-Cell of Fig 1b, since they have LoS connections to the associated users. Hence, the proposed A-Cells are capable of *breaking boundaries*, leading to a higher and a lower number of A-Cells in Fig 1d and Fig 1f.

3) Construction of A-Cells: Let us first introduce some common notations. We let \mathcal{C} be the specific set hosting all cells, where for the cth cell \mathcal{C}_c , we have $|\mathcal{N}_c|$ APs hosted in the set \mathcal{N}_c serving $|\mathcal{K}_c|$ users of the set \mathcal{K}_c , with $|\cdot|$ being the cardinality of a set. Note that these notations are in generic sense, including both conventional cells and A-Cells. We are now ready to discuss the construction of A-Cells.

We firstly construct a *full* user-to-network association matrix M^f having K rows and N columns corresponding to K users and N APs 2 . The [k, n]th entry of M^f is set to the LoS

²The availability of the full user-to-network association matrix rely on the acquisition of channel knowledge at the AP side, which can be readily estimated at the user side and then fed back to the AP at the cost of a modest overhead. This is because the VLC channels are pre-dominantly static and the channel knowledge can be characterised by a single attenuation factor.

channel $h_{k,n}^0$. We then carry out AP anchoring as follows:

- 1) Initialise user-to-network association matrix $M = M^f$.
- 2) Find the best user-AP pair $[k^*, n^*]$ having the strongest LoS channel amongst all entries of M and then collect the best user-index k^* in k^* .
- 3) Set all entries in the k^* th row and in the n^* th column of M to zero in order to exclude them from further consideration throughout the AP anchoring process.
- 4) If there are still positive entries in M, we repeat this process from Step 2. Otherwise, we output M as the sub-matrix of M^f constituted by all rows from k^* .

The objective of AP anchoring is to have exclusive user-AP pairs ensuring that each of those users in k^* will be served at least by its own anchor AP. Those users who have not found their anchor APs will be scheduled during the next anchoring round, however scheduling is beyond our current scope.

Having the user-to-network association matrix M, the distance based A-Cells are constructed, where the users are firstly grouped based on a pre-defined distance threshold d_0 and then we select APs associated with those users 3 as follows:

- 1) Introduce the counter c, which is initialised as c = 1.
- 2) We commence forming cell C_c by recruiting the first user, who has not been included in any cells. Hence, this user will be the only one in the set K_c and along with the associated AP set N_c containing all the APs providing LoS connections to the first user.
- 3) Recruit another user from the set of hitherto unassigned users, who has the smallest distance from the edge/centroid of the cell C_c , provided that their distance is shorter than d_0 . In this step, the edge of the cell is characterised by connecting its containing users' positions. We then update cell C_c , which results in the expanded set of K_c and N_c .
- 4) We repeat Step 3 until no additional users can be grouped. As a result, we completed the update of cell C_c , which resulted in the final set of K_c and N_c .
- 5) Set all entries of the association matrix M associated with the users in \mathcal{K}_c to zero. If there are still positive entries in M, we increment c and repeat from Step 2.

Upon the completion of user grouping, we have to resolve the associated AP ambiguity, since some cells may have conflicting AP assignments. In those cases, any ambiguously assigned AP n is exclusively included in the c^* th cell containing those users to whom the ambiguously assigned AP n has the strongest LoS connection. Finally, note that the entire set of APs \mathcal{N}_a involved in the ultimately constructed cells, namely $\mathcal{N}_a = \mathcal{N}_1 \cup \mathcal{N}_2 \cdots \cup \mathcal{N}_{|\mathcal{C}|}$, constitutes a subset of whole set of available APs in the room. For those unassigned APs in $\bar{\mathcal{N}}_a$, no communications are activated. To ease understanding, we include the pseudo-code in Algorithm 1. Regarding the complexity imposed, the first step of AP anchoring requires only an order of $\mathcal{O}(K)$ operations and an order of $\mathcal{O}(K)$ log(K)

³When constructing distance based A-Cells, the mutual distances between users are required. After acquiring the channel knowledge, the distances between users and APs can be inferred from (3). As a result, classical positioning may be used for determining the users' positions. Hence, the mutual distances between users can be readily calculated.

Algorithm 1 Distance based A-Cells

```
1: initialise c = 1, \mathcal{K}_0 = \emptyset
  2: while M \succ 0 do
                k = \{\min k : k \notin \mathcal{K}_0\}, \mathbf{a} = \{\forall n : M[k, n] > 0\}
  3:
                C_c: \{\mathcal{K}_c = \{k\}, \mathcal{N}_c = \{a\}\}, \mathcal{K}_c^o = \varnothing
  4:
                while \mathcal{K}_c \neq \mathcal{K}_c^o do
  5:
                        \mathcal{K}_c^o = \mathcal{K}_c, \, \mathcal{K}_0 = \mathcal{K}_0 \cup \mathcal{K}_c \\ k^* = \arg\min_{k \notin \mathcal{K}_0} \mathcal{D}(k, \mathcal{C}_c)
  6:
  7:
                        if \mathcal{D}(k^*, \mathcal{C}_c) \leq d_0 then
  8:
                                \mathbf{b} = \{ \forall n : M[k^*, n] > 0 \}
  9:
                                C_c: \{\mathcal{K}_c = \mathcal{K}_c \cup k^*, \, \mathcal{N}_c = \mathcal{N}_c \cup \boldsymbol{b}\}
10:
                        end if
11:
                end while
12:
                M[\mathcal{K}_c,:] = 0, c = c + 1
13:
14: end while
15: for all n \in \mathcal{N}_1 \cup \mathcal{N}_2 \cdots \cup \mathcal{N}_{|\mathcal{C}|} do
               c^* = \arg\max_{\forall c} \{\max_{k \in \mathcal{K}_c} h_{k,n}^0\}
\mathcal{N}_c = \mathcal{N}_c \setminus n, \quad \forall c \neq c^*
16:
17:
18: end for
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for finding the best user-AP pair. Furthermore, the complexity of Algorithm 1 is linear within the range of $[\mathcal{O}(K^2), \mathcal{O}(K^3)]$ owing to its hierarchical algorithmic structure.

B. Link-level Transmission

Let us now discuss the transmission strategy relying on the amalgamation of ACO-OFDM and MISO transmission. Our forthcoming elaborations are equally applicable both to the conventional cells and to the proposed A-Cells.

1) ACO-OFDM: We first consider the downlink ACO-OFDM transmission from the nth AP $n \in \mathcal{N}_c$ to the kth user $k \in \mathcal{K}_c$ in the cth cell \mathcal{C}_c . Let N_s represent the number of ACO-OFDM sub-channels and let $\mathbf{s}_n \in \mathbb{C}^{N_s/4}$ represent the Frequency Domain (FD) information-bearing symbol vector transmitted from the nth AP. Then the resultant ACO-OFDM symbol vector $\mathbf{s}_n^f \in \mathbb{C}^{N_s}$ is constituted by the odd sub-channel entries of zero and the even sub-channel entries of

$$s_n^f[m] = \begin{cases} s_n[m/2] & \text{if } m \le N_s/2 \text{ and is even} \\ s_n^{\text{conj}}\left[\frac{N_s - m + 2}{2}\right] & \text{if } m > N_s/2 \text{ and is even.} \end{cases}$$
 (6)

It becomes plausible that the ACO-OFDM mapping of (6) obeys the Hermitian symmetry property, which allows us to create real-valued Time Domain (TD) signal samples $\boldsymbol{s}_n^t \in \mathbb{R}^{N_s}$ after the classic IFFT operation. Since the odd-indexed FD sub-channels are set to zero in the specific ACO-OFDM mapping of (6), the first-half of the TD signal samples are copied to the second-half of the TD signal samples, albeit with their signs flipped. As a result, the TD signal samples can be conveyed with all the negative parts clipped at zero. The clipping-distortion imposed by the removal of the negative amplitudes only occurs at the odd-indexed FD sub-channels carrying no data and hence can be ignored, despite the fact that the amplitude of the TD signal samples is halved.

The clipped positive and real-valued TD signal samples $\tilde{\mathbf{s}}_n^t \in \mathbb{R}_+^{N_s}$ in conjunction with the DC-bias current are then forwarded to the LEDs, where the TD signal envelope is

used for modulating the intensity of the LEDs. To elaborate a little further, the clipped TD signal samples $\tilde{\mathbf{s}}_n^t$ obey the clipped Gaussian distribution with a parameter of $\sigma_{s_n^t}$. Hence, the average optical power of the TD signal samples $\tilde{\mathbf{s}}_n^t$ is $P^o = \sigma_{s_n^t}/\sqrt{2\pi}$ and the total radiated optical power plus DC is $P = P^{dc} + P^o$. Correspondingly, the average electronic power of the TD signal samples \mathbf{s}_n^t is $P_t^e = \sigma_{s_n^t}^2$, while the average electronic power of the FD ACO-OFDM symbol vector associated with its even-order half is $P_f^e = 2P_t^e$.

The kth user's receiver is comprised of a PD and a transimpedance amplifier. After the removal of DC component and followed by direct detection relying on the Optical to Electrical (O/E) conversion factor of γ , the discrete-time model of the received FD symbol vector $\boldsymbol{y}_k \in \mathbb{C}^{N_s}$ after FFT becomes

$$\mathbf{y}_k = (\gamma/2) \operatorname{diag}[\mathbf{h}] \mathbf{s}_n^f + \mathbf{I}_k + \mathbf{w}_k, \tag{7}$$

where $\boldsymbol{h} \in \mathbb{R}^{N_s}$ hosts the FD channel responses. Since the ACO-OFDM VLC channels can be safely considered as being non-dispersive for a bandwidth B upto 20 MHz [30], each entry of \boldsymbol{h} becomes a single-tap gain factor $h_{k,n}^{-4}$. Furthermore, $\boldsymbol{I}_k \in \mathbb{C}^{N_s}$ denotes the interference imposed on the kth user. Finally, $\boldsymbol{w}_k \in \mathbb{C}^{N_s}$ represents the noise vector accounting for both the shot noise and the thermal noise at the receiver, which can be modelled as zero-mean complex-valued AWGN with a variance of $\sigma^2 = N_0 B$, where $N_0 \approx 10^{-22}$ A²/Hz [14]. Extracting the information-bearing sub-channels from \boldsymbol{y}_k , for each $m \in \{2,4,\ldots,N_s/2\}$ we have,

$$y_k[m] = (\gamma/2)h_{k,n}s_n^f[m] + I_k[m] + w_k[m].$$
 (8)

Remark II-B1: Energy efficiency maximisation of conventional RF systems typically relies on Shannon's capacity expression for $f_t(\cdot)$ in (2), assuming Gaussian-distributed signalling. However, optical systems relying on Intensity Modulation/Direct Detection (IM/DD) can only have real-valued positive signals. Unfortunately, there is a lack of *exact* capacity expressions for optical systems, despite the existence of various forms of capacity bounds [31]. Hence, we consider ACO-OFDM, since it is a widely used optical modulation scheme exhibiting a higher power efficiency than DCO-OFDM, which allows us to derive an analytically tractable capacity expression [32], [33] for our energy efficiency maximisation problem to be discussed in Section II-C. Suffice to say that, the capacity expression of DCO-OFDM has to take into consideration the non-linear clipping distortion effects [33], which are hence set aside for our future research.

2) MISO Transmission: Having discussed the above point-to-point scenario, let us now discuss the multi-user scenario. For the cth cell having $|\mathcal{N}_c|$ APs and $|\mathcal{K}_c|$ users, the equivalent physical layer may be modelled as a multi-user MISO system for $|\mathcal{K}_c| > 1$ or as a single-user MISO system for $|\mathcal{K}_c| = 1$. In the former case, we employ VT based on Zero Forcing (ZF) Transmit Pre-Coding (TPC) for eliminating the inter-user-interference within the cth cell, while for the latter case, we employ CT for maximising the received signal power.

 4 We consider white LEDs constructed by using blue LEDs having a phosphor layer, which have a typical bandwidth of 20 MHz. This is achievable if a blue filter is used at the receiver side. Our methodology is also eminently applicable, when LEDs with \geq 100 MHz bandwidth become available.

When $|\mathcal{K}_c|=1$, CT is employed, where we transmit the same signal $s_n^f[m]=x_{k_0}[m]$ from all $n\in\mathcal{N}_c$ APs to the only user $k_0\in\mathcal{K}_c$. The signals arriving at the k_0 th receiver can be constructively combined, since all the channels emerging from all \mathcal{N}_c APs to the user k_0 are positive. Hence, for the mth subchannel $m\in\{2,4,\ldots,N_s/2\}$, we have the single-user MISO expression of (8) written as

$$y_{k_0}[m] = (\gamma/2) \sum_{n \in \mathcal{N}_c} h_{k_0,n} \varrho_n^{ct} x_{k_0}[m] + I_{k_0}[m] + w_{k_0}[m],$$
 (9)

where we set normalised electronic power of $x_{k_0}[m]$ being unity and let $\varrho_n^{ct} = \sqrt{2P_{c,n}^{ct}}$ with $P_{c,n}^{ct}$ to be optimised. By contrast, for $|\mathcal{K}_c| > 1$, VT is employed. For the mth subchannel $m \in \{2,4,\ldots,N_s/2\}$, we have the multi-user MISO expression of (8) written as

$$\boldsymbol{y}[m] = (\gamma/2)\boldsymbol{H}\boldsymbol{s}^f[m] + \boldsymbol{I}[m] + \boldsymbol{w}[m], \tag{10}$$

where $\boldsymbol{y}[m] \in \mathbb{C}^{|\mathcal{K}_c|}$ is the received FD symbol vector of all the $|\mathcal{K}_c|$ users in the cth cell on the mth sub-channel, while $\boldsymbol{s}^f[m] \in \mathbb{C}^{|\mathcal{N}_c|}$ is the FD symbol vector transmitted from all $|\mathcal{N}_c|$ APs in the cth cell on the mth sub-channel. Finally, $\boldsymbol{H} \in \mathbb{R}^{|\mathcal{K}_c| \times |\mathcal{N}_c|}$ is the channel between the $|\mathcal{K}_c|$ users and the $|\mathcal{N}_c|$ APs, while $\boldsymbol{I}[m] \in \mathbb{C}^{|\mathcal{K}_c|}$ is the inter-cell-interference imposed on all $|\mathcal{K}_c|$ users in the cth cell on the mth sub-channel. To eliminate the inter-user-interference, we employ TPC, which is formulated as $\boldsymbol{s}^f[m] = \boldsymbol{G}\boldsymbol{x}[m]$, where $\boldsymbol{x}[m] \in \mathbb{C}^{|\mathcal{K}_c|}$ is the multi-user FD symbol vector and the ZF precoding $\boldsymbol{G} \in \mathbb{R}^{|\mathcal{N}_c| \times |\mathcal{K}_c|}$ is explicitly formulated as $\boldsymbol{G} = \boldsymbol{H}^\dagger$, which is the pseudo-inverse of \boldsymbol{H} . Hence, (10) can be decomposed into $|\mathcal{K}_c|$ parallel streams and for any $k \in \mathcal{K}_c$, yielding

$$y_k[m] = (\gamma/2)\varrho_k^{vt} x_k[m] + I_k[m] + w_k[m],$$
 (11)

where we set normalised electronic power of $x_k[m]$ being unity and let $\varrho_k^{vt} = \sqrt{2P_{c,k}^{vt}}$ with $P_{c,k}^{vt}$ to be optimised.

Remark II-B2: It is natural to consider multi-user MISO transmission in VLC systems using VT to eliminate the interuser-interference. The roots of VT are in the celebrated results of information theory, where Dirty Paper Coding (DPC) is found to be capable of achieving the broadcast channel's capacity [34]. Owing to its non-linear complex nature of implementing DPC, the low-complexity ZF constitutes a popular alternative, which was shown to exhibit a negligible performance loss compared to DPC in the high Signal to Noise Ratio (SNR) regime, when the number of APs is larger than the number of users [35]. Hence, this important theoretical finding benefits directly a range of modern communications systems. For example, the concept of VT is similar to the successful employment of 'vectoring' in the state-of-the-art Digital Subscriber Line (DSL) based G.fast system invoked for coping with the crosstalk between twisted pairs. This operation is also reminiscent of the concept of the Coordinated Multiple Point (CoMP) transmission regime of classic RF cellular communications conceived for mitigating the intercell-interference at the cell edge [36]. In practice, to facilitate VT from $|\mathcal{N}_c|$ APs to $|\mathcal{K}_c|$ users, both the channel matrix **H** and the users' data x[m] have to be shared amongst the $|\mathcal{N}_c|$ APs. Fortunately, this requirement can be satisfied, since the VLC channels are pre-predominately static, while the sharing of all users' data $\boldsymbol{x}[m]$ requires a more capable back-haul.

3) Optical Constraints: Typically, the forward current of the DC-biased and clipped TD signal samples should be within the LED's dynamic range [30]. Since the total radiated optical power is directly proportional to the forward current, we describe the optical constraints in terms of their optical power.

The total optical power radiated from an AP should satisfy the per-LED dynamic range of $P_{min} \leq P/L \leq P_{max}$, where we assume that each of the L LEDs constituting an AP emits the same optical power. For example, a practical dynamic range of a Vishay TSHG8200 LED is between $P_{min} = 5$ mW and $P_{max} = 50$ mW at room temperature. For satisfying a predefined illumination requirement constituted by the minimum illumination \mathcal{I}_{min} , the maximum illumination \mathcal{I}_{max} and the average illumination \mathcal{I}_{avg} , we find the minimum required optical power P_{min}^{illu} by solving the problem of

$$P_{min}^{illu} = \min P \quad \text{s.t.}$$

$$\min_{\mu \in [1, K_p]} \sum_{n=1}^{N} h_{\mu,n}^{illu} P \ge \mathcal{I}_{min}, \quad \max_{\mu \in [1, K_p]} \sum_{n=1}^{N} h_{\mu,n}^{illu} P \le \mathcal{I}_{max},$$

$$\mathcal{I}_{avg}^{-} \le \frac{1}{K_p} \sum_{\mu=1}^{K_p} \sum_{n=1}^{N} h_{\mu,n}^{illu} P \le \mathcal{I}_{avg}^{+}, \quad P_{min} \le P/L \le P_{max},$$

where \mathcal{I}^+_{avg} and \mathcal{I}^-_{avg} denote the $\pm 5\%$ of \mathcal{I}_{avg} . Furthermore, $h^{illu}_{\mu,n}$ denotes the luminous flux of the unit optical power provided by the nth AP at the μ th point of the K_p equally partitioned receiver plane, which is given as

$$h_{\mu,n}^{illu} = \frac{(m_L + 1)}{2\pi d^2 \delta} \cos^{m_L}(\theta) \cos(\psi), \tag{13}$$

where δ denotes the optical power to luminous flux conversion factor [14]. Similarly, we also find the maximum optical power $P_{max}^{illu} = \max P$ capable of satisfying the constraints of (12). Note that having predefined illumination requirements also prevents the saturation of the PD receiver, hence we assume the absence of any further clipping at the receiver. As a result, by taking into account both the illumination requirements and LED's physical limits, we have the optical constraint of

$$\max\{P_{min}^{illu}, P_{min}\} \le P/L \le \min\{P_{max}^{illu}, P_{max}\}. \tag{14}$$

In this paper, we fix the DC-bias component ⁵ and assume only negative clipping is incurred by our ACO-OFDM scheme, because we can always set an appropriate margin for preventing upper clipping imposed by the high Peak to Average Power Ratio (PAPR) of ACO-OFDM TD signal samples by controlling the maximum optical output power. More explicitly, to avoid insufficient forward biasing, we set the DC-bias component to be at least as high as the minimum optical power required for satisfying the LED's dynamic range. On the other hand, we also adjust the DC-bias component to 'just' satisfy the predefined illumination requirement. Hence, we

have $P^{dc}/L=\max\{P^{illu}_{min},P_{min}\}$ and the optical requirement of (14) becomes $0\leq P^o/L\leq P^o_{max}$, where

$$P_{max}^{o} = \min\{P_{max}^{illu}, P_{max}\} - \max\{P_{min}^{illu}, P_{min}\}, \quad (15)$$

represents the maximum tolerable additional optical power of each LED, so that the communication function would not violate the illumination and LED instrument requirements.

C. System-level Optimisation

Let us now discuss the system-level energy efficiency maximisation. Our forthcoming elaborations are equally applicable both to the conventional cells and to the proposed A-Cells.

1) Formulation: Let us formulate our energy efficiency maximisation problem by defining system's mean energy efficiency on a per-cell basis as

$$\max_{\mathcal{P}} EE = \frac{1}{|\mathcal{C}|} \sum_{c} EE_{c}(\mathcal{P}), \tag{16}$$

We may also define a *global* energy efficiency as the sum throughput of all cells divided by the total power consumption of all cells, where a centralised approach has to be used. By contrast, the *per-cell* basis definition of (16) supports a more scalable and efficient distributed approach. Since $|\mathcal{C}|$ is a constant, (16) can be solved equivalently by optimising $\max_{\mathcal{P}} \sum_{c} \text{EE}_{c}(\mathcal{P})$, explicitly

$$\max_{\boldsymbol{P}} \sum_{c \in \mathcal{C}_{vt}} \frac{f_{t,c}^{vt}(\boldsymbol{P})}{f_{p,c}^{vt}(\boldsymbol{P}_{c}^{vt})} + \sum_{c \in \mathcal{C}_{vt}} \frac{f_{t,c}^{ct}(\boldsymbol{P})}{f_{p,c}^{ct}(\boldsymbol{P}_{c}^{ct})} \quad \text{s.t.} \quad \text{C1, C2,} \quad (17)$$

where \mathcal{C}_{vt} and \mathcal{C}_{ct} are the sets hosting the specific cells that employ VT and CT, respectively. Furthermore, we have $P = \{P^{vt}; P^{ct}\}$ acting as the power allocation strategy, which is constituted by that of all VT-aided cells $P^{vt} = \{P^{vt}_c, \forall c \in \mathcal{C}_{vt}\}$ and all CT-aided cells $P^{ct} = \{P^{ct}_c, \forall c \in \mathcal{C}_{vt}\}$, where P^{vt}_c and P^{ct}_c are the power allocation strategy for the cth cell using VT and CT, respectively. By scrutinising (17), we find that only those cells in \mathcal{C}_{vt} and \mathcal{C}_{ct} are included in our optimisation. This implies that those APs, which are not included in \mathcal{C}_{vt} and \mathcal{C}_{ct} , are switched into their idle mode.

Still referring to (17), since ACO-OFDM is employed, we can assume Gaussian signalling for $x_k[m]$ in (11) and for $x_{k_0}[m]$ in (9). Hence, we arrive at

$$f_{t,c}^{vt}(\mathbf{P}) = \sum_{k \in \mathcal{K}_c} \kappa \log_2 \left[1 + \frac{(\gamma^2/2) P_{c,k}^{vt}}{\sigma^2 + I_{c,k}(\mathbf{P}_{\bar{c}}^{vt}, \mathbf{P}^{ct})} \right], \tag{18}$$

$$f_{t,c}^{ct}(\mathbf{P}) = \kappa \log_2 \left[1 + \frac{\left(\gamma^2/2\right) \left(\sum_{n \in \mathcal{N}_c} h_{k_0, n} \sqrt{P_{c,n}^{ct}}\right)^2}{\sigma^2 + I_{c,k_0}(\mathbf{P}_{\overline{c}}^{ct}, \mathbf{P}^{vt})} \right], \quad (19)$$

where $\kappa=(1-p)B/4$ is a constant, with the factor of 4 representing the bandwidth efficiency loss owing to the employment of ACO-OFDM having a bandwidth of B and p denoting the blocking probability. Furthermore, $I_{c,k}(\cdot)$ denotes the interference imposed on the kth user in the cth VT-aided cell, while $I_{c,k_0}(\cdot)$ denotes the interference imposed on the only user k_0 in the cth CT-aided cell. In (18) and (19), $\boldsymbol{P}_{\bar{c}}^{vt}$ and $\boldsymbol{P}_{\bar{c}}^{ct}$ represent the power allocation excluding the cth cell

⁵We fix the DC-biasing by focusing our attention on the communicationsrelated energy efficiency maximisation, despite the possibility of adaptive signal scaling and DC biasing [37]. Note that, when DCO-OFDM is considered, optimising the DC-bias component becomes critical [30].

from all VT-aided and CT-aided cells, respectively, which are used for evaluating the interference terms $I_{c,k}(\cdot)$ and $I_{c,k_0}(\cdot)$. Finally, since the DC-bias component is fixed for illumination, we consider the communications-related power consumption in the electronic domain, which may be written as

$$f_{p,c}^{vt}(\boldsymbol{P}_c) = \sum_{n \in \mathcal{N}_c} \sum_{k \in \mathcal{K}_c} g_{n,k}^2 P_{c,k}^{vt}, \tag{20}$$

$$f_{p,c}^{ct}(\boldsymbol{P}_c) = \sum_{n \in \mathcal{N}_c} P_{c,n}^{ct}, \tag{21}$$

where $g_{n,k}$ is the [n,k]th entry of the TPC matrix G^{-6} . Furthermore, as far as the optimisation constraints are concerned, we impose the per-LED optical power constraint pair C1 of

$$\frac{1}{L} \sqrt{\sum_{k \in \mathcal{K}_c} g_{n,k}^2 P_{c,k}^{vt} / 2\pi} \le P_{max}^o \qquad \forall n \in \mathcal{N}_c, \forall c \in \mathcal{C}_{vt}, \quad (22)$$

$$\frac{1}{L}\sqrt{P_{c,n}^{ct}/2\pi} \le P_{max}^{o} \qquad \forall n \in \mathcal{N}_c, \forall c \in \mathcal{C}_{ct}. \quad (23)$$

We also impose the per-user throughput constraint pair C2 for guaranteeing a minimum required OoS as

$$f_{t,c,k}^{vt}(P_{c,k}^{vt}, \mathbf{P}_{\bar{c}}^{vt}, \mathbf{P}^{ct}) \ge R \qquad \forall k \in \mathcal{K}_c, \forall c \in \mathcal{C}_{vt},$$
 (24)

$$f_{c}^{ct}(\mathbf{P}) \ge R \qquad \forall c \in \mathcal{C}_{ct}.$$
 (25)

Note that neglecting the per-user throughput constraint pair C2 by unilaterally maximising the energy efficiency results in an ill-defined problem, since the user QoS target is ignored.

2) Transformation: The objective function defined in (17) is complex due to the coupled nature of the power allocation strategy. Hence, we opt for decoupling the original problem formulated in (17) so as to allow efficient distributed processing. More explicitly, instead of evaluating the true interference term of (18) and (19), we consider the interference upper bound by assuming that all other cells transmit at their maximum permissible optical power. This implies that we carry out guaranteed energy efficiency maximisation. More specifically, we use constant $I_{c,k}(P_{max}^o)$ to represent the maximum possible interference imposed on the kth user in the cth VT-aided cell, which is written as

$$I_{c,k}(P_{max}^o) = \gamma^2 \pi \sum_{\tilde{c} \in \mathcal{C}, \tilde{c} \neq c} \sum_{n \in \mathcal{N}_{\tilde{c}}} h_{k,n}^2 \left(L P_{max}^o \right)^2.$$
 (26)

Similarly, by replacing $k = k_0$ in (26), we have $I_{c,k_0}(P_{max}^o)$ representing the maximum possible interference imposed on the only user k_0 in the cth CT-aided cell. Correspondingly, we can reformulate the lower bound of (18) and (19) as

$$f_{t,c}^{vt,l}(\boldsymbol{P}_c^{vt}) = f_{t,c}^{vt}(\boldsymbol{P})_{\{I_{c,k}(\boldsymbol{P}_{\bar{c}}^{vt}, \boldsymbol{P}^{ct}) \mapsto I_{c,k}(P_{max}^o), \forall k \in \mathcal{K}_c\}}, \quad (27)$$

$$f_{t,c}^{ct,l}(\mathbf{P}_c^{ct}) = f_{t,c}^{ct}(\mathbf{P})_{\{I_{c,k_0}(\mathbf{P}_{\bar{c}}^{ct}, \mathbf{P}^{vt}) \mapsto I_{c,k_0}(P_{max}^o)\}}.$$
 (28)

It is plausible that (27) and (28) become only the function of the power allocation strategy of the cth cell, which is decoupled from other cells. Furthermore, since the composition

⁶We only consider transmission power as our source of power consumption in (20) and (21). In our future work, other sources of power consumption, such as the signal processing costs, back-haul power consumption etc would be desired to paint the whole picture in terms of the entire network power consumption [29]. However, at the time of writing, quantifying the network power consumption for VLC systems remains an open issue, since integrating it with a certain VLC back-haul requires dedicated treatment.

in (19) or in its lower bound expression of (28) results in a non-concave function, we rely on the lower bounding of (28) in order to arrive at the concave formulation of

$$f_{t,c}^{ct,ll}(\mathbf{P}_c^{ct}) = \kappa \log_2 \left[1 + \frac{(\gamma^2/2) \sum_{n \in \mathcal{N}_c} h_{k_0,n}^2 P_{c,n}^{ct}}{\sigma^2 + I_{c,k_0}(P_{max}^o)} \right]. \quad (29)$$

Upon taking into account (27) and (29), we arrive at the new constraint pair C2 formulated as

$$f_{t,c,k}^{vt,l}(P_{c,k}^{vt}) \ge R \qquad \forall k \in \mathcal{K}_c, \forall c \in \mathcal{C}_{vt},$$

$$f_{t,c}^{ct,ll}(\mathbf{P}_c^{ct}) \ge R \qquad \forall c \in \mathcal{C}_{ct}.$$
(30)

$$f_{t,c}^{ct,ll}(\boldsymbol{P}_c^{ct}) \ge R \qquad \forall c \in \mathcal{C}_{ct}.$$
 (31)

Clearly, this new constraint pair is more strict than the original constraint pair of (24) and (25). Lastly, the constraint pair C1 remains the same, as in (22) and (23).

Following the above transformation, the decoupled energy efficiency maximisation problem becomes

$$\max_{\mathbf{P}} \sum_{c \in \mathcal{C}_{vt}} \frac{f_{t,c}^{vt,l}(\mathbf{P}_{c}^{vt})}{f_{p,c}^{vt}(\mathbf{P}_{c}^{ct})} + \sum_{c \in \mathcal{C}_{ct}} \frac{f_{t,c}^{ct,ll}(\mathbf{P}_{c}^{ct})}{f_{p,c}^{ct}(\mathbf{P}_{c}^{ct})}$$
s.t. (22), (23), (30), (31).

Hence, the problem formulated in (32) can be solved in form of $|\mathcal{C}|$ parallel sub-problems, where we have

$$\max_{\boldsymbol{P}_{c}^{vt}} \frac{f_{t,c}^{vt,l}(\boldsymbol{P}_{c}^{vt})}{f_{c,c}^{vt}(\boldsymbol{P}_{c}^{vt})} \qquad \text{s.t.} \quad (22), (30) \quad \forall c \in \mathcal{C}_{vt}, \quad (33)$$

$$\max_{\boldsymbol{P}_{c}^{vt}} \frac{f_{t,c}^{vt,l}(\boldsymbol{P}_{c}^{vt})}{f_{p,c}^{vt}(\boldsymbol{P}_{c}^{vt})} \qquad \text{s.t.} \quad (22), (30) \quad \forall c \in \mathcal{C}_{vt}, \quad (33)$$

$$\max_{\boldsymbol{P}_{c}^{ct}} \frac{f_{t,c}^{ct,ll}(\boldsymbol{P}_{c}^{ct})}{f_{p,c}^{ct}(\boldsymbol{P}_{c}^{ct})} \qquad \text{s.t.} \quad (23), (31) \quad \forall c \in \mathcal{C}_{ct}. \quad (34)$$

Both (33) and (34) constitute fractional programming problems, which may be solved using Dinkelbach's method [38] by iteratively optimise the subtractive form of (33) and (34). More explicitly, for a particular $c \in C_{vt}$, the procedures are

- 1) Introduce the parameter $t^{vt}_{c,i}$ with i being the iteration index and initialise the parameter as $t^{vt}_{c,1}=0$.
- 2) At each iteration i, solve the inner optimisation problem of the subtractive form of (33), namely

$$\max_{{\bf P}^{vt}} f_{t,c}^{vt,l}({\bf P}_c^{vt}) - t_{c,i}^{vt} f_{p,c}^{vt}({\bf P}_c^{vt}) \quad \text{s.t.} \quad (22), (30).$$

Since the above inner optimisation problem is a concave maximisation problem, the classic dual-decomposition method yields a zero duality gap and hence achieves optimality. Owing to its popularity in solving convex problems, we refer readers for further details to [39].

3) Let $P_c^{vt,*}$ denote the optimal solutions found for the inner optimisation problem, if we have

$$f_{t,c}^{vt,l}(\boldsymbol{P}_{c}^{vt,*}) - t_{c,i}^{vt} f_{p,c}^{vt}(\boldsymbol{P}_{c}^{vt,*}) \le \zeta,$$
 (35)

then the pre-defined convergence threshold ζ is satisfied, where $P_c^{vt,*}$ constitutes the ultimate solution. Alternatively, if the maximum number of iterations ς is reached, we output $oldsymbol{P}_c^{vt,*}$ as the ultimate solution. Otherwise, we update the parameters according to

$$t_{c,i+1}^{vt} = f_{t,c}^{vt,l}(\boldsymbol{P}_c^{vt,*})/f_{p,c}^{vt}(\boldsymbol{P}_c^{vt,*}), \tag{36}$$

and repeat Steps 2 and 3.

The above procedures, referred to as the baseline algorithm ⁷, can be also used for the energy efficiency maximisation of (34) for CT-aided cells and we do not duplicate it here.

3) Simplification: The baseline algorithm requires a number of iterations to converge, where within each iteration, the classic dual-decomposition method invoked, again, requires encapsulated iterations to converge. Hence, we propose an algorithm, which dispenses with the above sophistication.

For any particular VT-aided cell $c \in \mathcal{C}_{vt}$, we use the straightforward equal power allocation strategy of

$$P_{c,k}^{vt} = P_c^{vt} \qquad \forall k \in \mathcal{K}_c. \tag{37}$$

To satisfy the constraint (30), we have

$$P_{c,k}^{vt} \ge (2^{R/\kappa} - 1)[\sigma^2 + I_{c,k}(P_{max}^o)]2/\gamma^2 = P_{c,k}^{vt,l},$$
 (38)

$$P_c^{vt} \ge \max_{k \in \mathcal{K}_c} P_{c,k}^{vt,l} = P_c^{vt,l},\tag{39}$$

while to satisfy the constraint (22), we have

$$P_c^{vt} \le 2\pi (LP_{max}^o)^2 / \sum_{k \in \mathcal{K}_c} g_{n,k}^2 = P_c^{vt,u}.$$
 (40)

As a result, provided that $P_c^{vt,l} \leq P_c^{vt,u}$, we have

$$P_c^{vt} = P_c^{vt,l}. (41)$$

The solution P_c^{vt} in (41) ensures that even the least privileged user $k_w = \arg\max_{k \in \mathcal{K}_c} \{I_{c,k}(P^o_{max})\}$ satisfies the per-user throughput constraint of (30). However, setting P^{vt}_c for other users may 'over-satisfy' their per-user throughput constraint of (30), which leads to an energy efficiency loss. Hence, we improve the above equal power allocation strategy as

- 1) Let \mathcal{K}_c^f be the set hosting those users with fixed power allocation strategies, which is initialised as $\mathcal{K}_c^f = \{k_w\}$. Let \mathcal{K}_c^p be the complement set of \mathcal{K}_c^f hosting those users with adjustable power allocation strategies. Finally, we
- initialise $\pmb{A} = \{P^{vt}_{c,k \in \mathcal{K}_c} = P^{vt}_c\}$. 2) For $k \in \mathcal{K}^p_c$, we reduce the power allocated from $P^{vt}_{c,k} =$ P_c^{vt} given in (41) to $P_{c,k}^{vt} = P_{c,k}^{vt,l}$ given in (38). This will result in the adjusted power allocation strategy of

$$\mathbf{A}_{k} = \{ P_{c,k}^{vt} = P_{c,k}^{vt,l}, \mathbf{\Omega}_{k} \}, \tag{42}$$

$$\mathbf{\Omega}_k = \{ P_{c,j\in\mathcal{K}_c^p}^{vt} = P_{c,j}^{vt,l}, P_{c,\tilde{k}\in\mathcal{K}_c^p,\tilde{k}\neq k}^{vt} = P_c^{vt} \}. \tag{43}$$

3) Repeating Step 2 for all users in \mathcal{K}_c^p leads to $|\mathcal{K}_c^p|$ adjusted power allocation strategies $\{A_k, k \in \mathcal{K}_c^p\}$, where we find the one gives the highest energy efficiency

$$k_p = \arg\max_{k \in \mathcal{K}_c^p} \{ f_{t,c}^{vt,l}(\boldsymbol{A}_k) / f_{p,c}^{vt}(\boldsymbol{A}_k) \}.$$
 (44)

4) If we have

$$f_{t,c}^{vt,l}(\boldsymbol{A}_{k_p})/f_{p,c}^{vt}(\boldsymbol{A}_{k_p}) \ge f_{t,c}^{vt,l}(\boldsymbol{A})/f_{p,c}^{vt}(\boldsymbol{A}),$$
 (45)

then we include k_p in \mathcal{K}_c^f by excluding it from \mathcal{K}_c^p and set $A = A_{k_n}$. Then we repeat the procedure commencing from Step 2. The adjustment stops, when (45) is not met and we output $P_c^{vt,*} = A$.

⁷Other methods solving fractional programming, such as bisection and Charnes-Cooper method, are also interesting but they are beyond our scope.

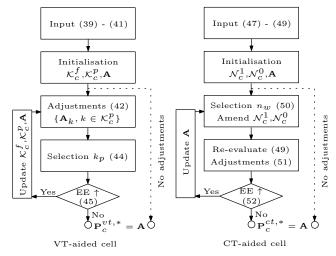


Fig. 2: Flowcharts of the proposed algorithm.

For any particular CT-aided cell $c \in \mathcal{C}_{ct}$, we use the equal power allocation strategy, namely

$$P_{c,n}^{ct} = P_c^{ct} \qquad \forall n \in \mathcal{N}_c. \tag{46}$$

To satisfy the constraint (31), we have

$$P_c^{ct} \ge \frac{(2^{R/\kappa} - 1)[\sigma^2 + I_{c,k_0}(P_{max})]}{(\gamma^2/2) \sum_{n \in \mathcal{N}_c} h_{k_0,n}^2} = P_c^{ct,l}, \tag{47}$$

while to satisfy the constraint (23), we have

$$P_c^{ct} \le 2\pi (LP_{max}^o)^2 = P_c^{ct,u}.$$
 (48)

As a result, provided that $P_c^{ct,l} \leq P_c^{ct,u}$, we have

$$P_c^{ct} = P_c^{ct,l}. (49)$$

Let us now adjust the equal power allocation strategy by turning off the communications function for those APs exhibiting high-attenuation channels, since blindly allocating power to it may lead to energy efficiency loss. More explicitly

- 1) Let \mathcal{N}_c^0 and \mathcal{N}_c^1 be the set hosting the specific APs whose communication functions are turned off and turned on, respectively, where we have $\mathcal{N}_c^0 = \emptyset$ and $\mathcal{N}_c^1 = \mathcal{N}_c$. Initialise $A = \{P_{c,n \in \mathcal{N}_c}^{ct} = P_c^{ct}\}$.
- 2) Locate the weakest AP

$$n_w = \arg\min_{n \in \mathcal{N}_c^1} \{h_{k_0, n}\},\tag{50}$$

and include it in \mathcal{N}_c^0 by excluding it from \mathcal{N}_c^1 . 3) Re-evaluate (47) and (48) using \mathcal{N}_c^1 instead of \mathcal{N}_c in order to get $P_c^{ct,1}$. Hence, we arrive at the new power allocation strategy of

$$\mathbf{A}_{n_w} = \{ P_{c, n \in \mathcal{N}^0}^{ct} = 0, P_{c, n \in \mathcal{N}^1}^{ct} = P_c^{ct, 1} \}.$$
 (51)

4) If we have

$$f_{t,c}^{ct,ll}(\mathbf{A}_{n_w})/f_{p,c}^{ct}(\mathbf{A}_{n_w}) \ge f_{t,c}^{ct,ll}(\mathbf{A})/f_{p,c}^{ct}(\mathbf{A}),$$
 (52)

we set $A = A_{n_w}$ and repeat the above procedure, commencing from Step 2. The adjustments stop when (52) is not met and we output $P_c^{ct,*} = A$.

TABLE I: List of Parameters

LED-related Parameters	
semi-angle at half-illumination $\phi_{1/2}$	60°
gain of optical filter $f_{of}(\psi)$	1
physical area for a PD receiver A_{PD}	1 cm ²
O/E conversion factor γ	0.53 A/W
refractive index n_x	0.55 A/W
	1.5 45°
half of the receiver's FoV ψ_F	
Vishay TSHG8200 LED min optical power P_{min}	5 mW 50 mW
Vishay TSHG8200 LED max optical power P_{max}	
optical power to luminous flux conversion factor δ	2.1 mW/lm
Environment-related Parameters	
room size	$15\times15\times3~\text{m}^3$
user height	0.85 m
number of users (change in Fig 5)	20 (uniform)
AP height	2.5 m
number of APs	8×8 (uniform)
LED array per AP	15×15
reflection efficiency ρ	0.75
illumination requirement $[\mathcal{I}_{min}, \mathcal{I}_{max}, \mathcal{I}_{avg}]$	[200,800,600]
modulation bandwidth B	20 MHz
blocking probability p (change in Fig 4)	0
Baseline Algorithm-related Parameters	
maximum iterations ς (change in Fig 6)	20
convergence threshold ζ	0.01

Remark II-C3: If no power adjustments are carried out, the algorithm proposed for the VT-aided or CT-aided cells only requires a one-off evaluation of (41) or (49), respectively. When adjustments are indeed required, the algorithm proposed requires at most $|\mathcal{K}_c|-1$ or $|\mathcal{N}_c|-1$ additional iterations for the VT-aided or CT-aided cells, respectively. Within each iteration, the dominant complexity component is only linearly increasing according to the order of $\mathcal{O}(\mathcal{K}_c^p)$ or $\mathcal{O}(\mathcal{N}_c^1)$ associated with evaluating (44) or (50) for the VT-aided or CT-aided cells, respectively. To further aid the reader's understanding, a flow chart is included in Fig 2.

III. NUMERICAL RESULTS

Let us now provide simulation results for characterising the energy efficiency of the indoor VLC system relying on the amorphous structure. All our simulations are carried out for 100 random independent snapshots of the user distributions using the parameters included in Table I.

A. Comparisons

For fair comparisons, in Fig 3, the same transmission strategy is employed and the same baseline optimisation algorithm is applied for all the cell formation strategies involved, where we have set the minimum per-user throughput constraint to $R=15~\mathrm{MBits/s}$ for our optimisation algorithm.

1) Edge-Distance based A-Cells v.s. Conventional Cells: The left subplot of Fig 3 compares the energy efficiency per user between the conventional cells and the edge-distance based A-Cells having 20 users (hollow) and 25 users (solid). Explicitly, 'E3.5' stands for the edge-distance based A-Cells having $d_0=3.5\mathrm{m}$. This value of d_0 was specifically selected to result in an average number of cells, which is similar to that of the bench-marker scenario 'S16'. We also included the bench-marker scenario 'S1' as introduced in Section II-A2. Since similar trends may also be found for the centroid-distance based A-Cells, we omit them for space economy.

It can be seen from the left subplot of Fig 3 that, for both 20 users and 25 users, the edge-distance based A-Cells exhibit a consistently higher energy efficiency per user than both the conventional cell formations 'S16' and 'S1', where the relative energy efficiency becomes significantly greater upon increasing the FoVs when experiencing more interference. Quantitatively, when having 20 users, the edge-distance based A-Cells are capable of achieving over 4 times (nearly 10 times) energy efficiency per user than that of the benchmarker scenario 'S1' at FoV of 95° (of 100°). Similarly, when compared to the bench-marker scenario 'S16', the edgedistance based A-Cells are capable of roughly doubling the energy efficiency per user at both FoVs of 95° and of 100°. These observations imply that the advocated edge-distance based A-Cells are capable of handling scenarios having more interference. This is true upon slightly increasing the number of users from 20 to 25, where the edge-distance based A-Cells achieve overwhelmingly higher energy efficiency per user than both conventional cell formations 'S16' and 'S1'.

Furthermore, we included the classic scheme of frequency reuse having a factor of two in conjunction with both the conventional cell formations 'S16' and 'S1'. It can be seen from the left subplot of Fig 3 that the edge-distance based A-Cells exhibit a consistently higher energy efficiency per user than both the conventional cell formations relying on frequency reuse for all FoV settings and for both user settings. For all FoVs, as expected, the higher the number of users, the higher the energy efficiency per user of the edge-distance based A-Cells becomes in comparison to both conventional cell formations. Upon increasing the FoVs, the energy efficiency per user achieved by the edge-distance based A-Cells is reduced for both conventional cell formations as well as for both user settings, exhibiting a steeper reduction for the conventional cell formation 'S1'. This is because, the higher the FoV, the more interference is encountered, hence frequency reuse becomes more beneficial. Despite this reduction, the energy efficiency per user achieved by the edge-distance based A-Cells remains at least three times higher when compared to that of the conventional cell formation 'S1' employing frequency reuse and supporting 20 users. To sum up, the edgedistance based A-Cells are significantly more energy efficient than both the conventional cell formations 'S16' and 'S1' operating with or without frequency reuse.

2) Edge-Distance v.s. Centroid-Distance based A-Cells: Owing to the flexibility of the distance based A-Cells, we can appropriately configure them to provide a fair comparison. The right subplot of Fig 3 compares the energy efficiency per user between the edge-distance (hollow) and the centroid-distance (solid) based A-Cells with the average number of A-Cells spanning from 1 to 6. For the edge-distance based A-Cells, we evaluate $d_0 = [3, 3.5, 4, 4.5, 5]$, while for the centroid-distance based A-Cells, we evaluate $d_0 = [5, 6, 7, 8, 9]$. Note that the higher the value of d_0 , the smaller the average number of resultant A-Cells. It can be seen from the right subplot of Fig 3 that the edge-distance based A-Cells exhibit a consistently higher energy efficiency per user than that of the centroid-distance based A-Cells for all resultant average number of A-Cells and for all FoVs, which shows the superiority of

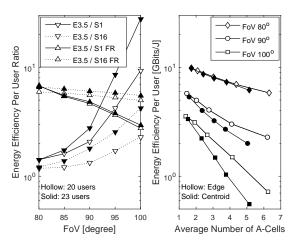


Fig. 3: Energy efficiency per user comparisons of various cell formation strategies (left) as well as between the edge and centroid-distance based A-Cells (right) using the parameters of Table I.

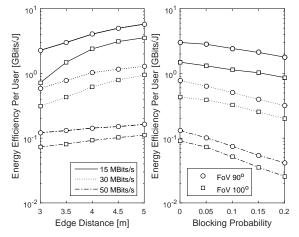


Fig. 4: Energy efficiency per user for edge-distance based A-Cells as a function of the predefined edge-distance threshold (left) and of the LoS and reflected-path blocking probability (right) using the parameters of Table I.

the edge-distance based A-Cells. Indeed, we observe that the superiority of the edge-distance based A-Cells is more prominent at higher FoVs for all resultant average number of A-Cells, while they become very similar at FoV of 80°. Finally, at FoVs of 90° and of 100°, we observe that the superiority of edge-distance based A-Cells is greater when having a larger number of resultant A-Cells, whilst there are marginal differences when the number of A-Cells is small.

B. Details

We now provide detailed observations regarding the edgedistance based A-Cells. In these investigations, we use our baseline algorithm for optimisation. Since similar trends may also be found for the centroid-distance based A-Cells, we omit them for space economy.

1) Effect of Edge Distance: The left subplot of Fig 4 shows the energy efficiency per user for edge-distance based A-Cells as a function of the predefined edge-distance threshold. It can be seen from the left subplot of Fig 4 that as expected, guaranteeing a higher per-user throughput incurs an energy efficiency loss compared to requiring a lower per-user throughput for all predefined edge-distance threshold settings and for both FoVs, demonstrating that any throughput improvement requires extra power to be invested 8. Furthermore, for all throughput constraints and for all predefined edge-distance threshold settings, having a higher FoV results in a consistently lower energy efficiency per user than that of a lower FoV, since more interference is encountered and more APs are involved when having a higher FoV. Finally, we observe that the higher the edge-distance threshold, the higher the energy efficiency per user becomes for all throughput constraints and for both FoVs. However, at this stage, we are reluctant to claim the superiority of setting towards higher edge-distance threshold for the reasons discussed as follows.

In principle, setting a lower edge-distance threshold results into several decoupled A-Cells, whilst having a higher edgedistance threshold results into a few large A-Cells. In both settings, the total number of participated APs remains similar under a given FoV. Having a few large A-Cells creates a largedimensional multi-user MISO system. Hence, it is capable of more easily satisfying a given throughput constraint than forming several decoupled A-Cells. However, having a largedimensional multi-user MISO system will potentially incur additional signal processing costs, such as the inversion of a large matrix at the distributed APs as required by the ZF based TPC. Also, sharing data amongst APs of large A-Cells may require more capable back-haul. Hence, network power consumption by additionally considering the signal processing costs and back-haul power consumption is required to determine the most appropriate edge-distance threshold.

2) Effect of Blocking: The right subplot of Fig 4 shows the energy efficiency per user for edge-distance based A-Cells associated with $d_0 = 3.5 \text{m}$ as a function of the LoS and reflected-path blocking probability. It can be seen from the right subplot of Fig 4 that as expected, the higher the blocking probability, the lower the energy efficiency per user becomes for all throughput constraints and for both FoVs. Furthermore, for all blocking probabilities and for both FoVs, the energy efficiency per user is higher for a lower throughput constraint than for a higher throughput constraint. We observe also that, the slope of the energy efficiency reduction per user is higher for a higher throughput constraint for both FoVs. Finally, for all throughput constraints and for all blocking probabilities, having a higher FoV results in a consistently lower energy efficiency per user than that of a lower FoV, since more interference is encountered and more APs are involved when having a higher FoV. Note that, the blocking model considered here is independent of the FoVs, while we will consider a more realistic FoV-related blocking in the future.

⁸Different modulations incur different levels of energy investments. For example, Color Shift Keying (CSK) relies on the LEDs' color mapping capability, instead of higher DC power, for achieving an increased data rate.

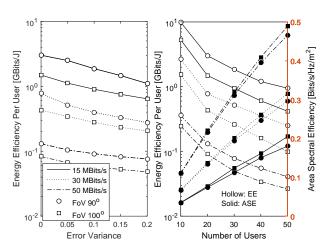


Fig. 5: Energy efficiency per user for edge-distance based A-Cells associated with $d_0=3.5\mathrm{m}$ as a function of error variance (left) and energy efficiency per user versus area spectral efficiency trade-offs (right) as a function of user density using the parameters of Table I.

3) Effect of Imperfect Channel Knowledge: The left of Fig 5 shows the energy efficiency per user for edge-distance based A-Cells associated with $d_0 = 3.5 \text{m}$ as a function of the error variance of imperfect channel knowledge at the distributed APs used for VT or CT. We assumed Gaussian distributed errors and as expected, the achievable energy efficiency per user degrades upon increasing the error variance for all throughput constraints and for both FoVs. Furthermore, for all error variances and for both FoVs, the energy efficiency per user is higher for a lower throughput constraint than for a higher throughput constraint. Furthermore, for all throughput constraints and for all error variances, having a higher FoV results in a consistently lower energy efficiency per user than that of a lower FoV. These investigations imply the importance of having an accurate channel knowledge, where a modest reduction may be observed in the left of Fig 5 at an error variance of 0.2 for all throughput constraints and for both FoVs. Hence, a classic trade-off arises between reducing the error variance and investing extra cost, which will be set aside for our future work.

4) Effect of User Density: The right subplot of Fig 5 shows the energy efficiency per user for edge-distance based A-Cells associated with $d_0=3.5\mathrm{m}$ as a function of user density. It can be seen from the right subplot of Fig 5 that as expected for all throughput constraints and for both FoVs, the higher the number of users, the lower the energy efficiency per user becomes, since the interference becomes more pervasive and more number of APs are involved. Importantly, the most substantial drop appears upon increasing the number of users from 10 to 20, followed by a less dramatic energy efficiency erosion per user beyond 20 users. Furthermore, for all user density settings and for both FoVs, the energy efficiency per user is higher for a lower throughput constraint than for a higher throughput constraint. Finally, for all throughput constraints and for all user density settings, having a higher FoV results

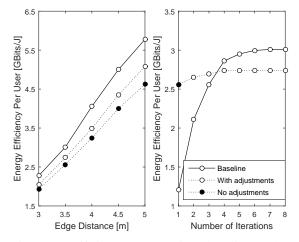


Fig. 6: Energy efficiency per user for edge-distance based A-Cells as a function of the predefined edge-distance threshold (left) and of the number of iterations (right) when using both the baseline algorithm and the proposed algorithm with and without adjustments and using the parameters of Table I.

in a consistently lower energy efficiency per user than that of a lower FoV, since more interference is encountered and more APs are involved when having a higher FoV.

5) Trade-offs: The right subplot of Fig 5 also shows the Area Spectral Efficiency (ASE) for edge-distance based A-Cells associated with $d_0 = 3.5$ m as a function of user density. It can be seen from the right subplot of Fig 5 that as expected, for all user density settings and for both FoVs, the ASE is higher for a higher throughput constraint than for a lower throughput constraint. Furthermore, for all throughput constraints and for both FoVs, the higher the number of users, the higher the ASE becomes. This is because the aggregated throughput is higher for a higher number of users. However, the ASE improvement seen in the right subplot of Fig 5 is achieved at the cost of sacrificing the energy efficiency per user. Achieving a higher ASE at the cost of reducing the energy efficiency contradicts to our original design objective. Similarly, for all throughput constraints and for all user density settings, having a higher FoV results in a slightly higher energy efficiency per user than that of a lower FoV, again at the cost of sacrificing the energy efficiency. Finally, we note that the ASE recorded in the right subplot of Fig 5 is not the maximum achievable ASE, since it was evaluated under the specific constraint of the power allocation strategy obtained when using the energy efficiency as our design objective.

C. Algorithms

We now discuss the performance of our proposed algorithm, where we set the minimum per-user throughput constraint to R=15 MBits/s and FoV of 90^{o} for our investigations.

1) Comparison: The left subplot of Fig 6 shows the energy efficiency per user for edge-distance based A-Cells as a function of the predefined edge-distance threshold, when using both the baseline algorithm and the proposed algorithm with and without adjustments, as detailed in Section II-C3.

For our proposed algorithm relying on adjustments, we set $|\mathcal{K}_c|-1$ and $|\mathcal{N}_c|-1$ as the maximum number of iterations for our VT and CT-aided A-Cells, respectively. It can be seen from the left subplot of Fig 6 that the proposed algorithm operating without adjustments is capable of achieving much of the energy efficiency per user obtained by the baseline algorithm. When relying on additional adjustments, the proposed algorithm achieves a higher energy efficiency per user than that of its non-adjusted counterparts. In particular, it performs quite similarly to the baseline algorithm, when the predefined edge-distance threshold is small.

2) Convergence: The right subplot of Fig 6 shows the convergence of both the baseline and of the proposed algorithm for edge-distance based A-Cells associated with $d_0 = 3.5$ m. It can be seen that the baseline algorithm converges within 6 iterations with further embedded iterations owing to the usage of the dual-decomposition method. For our proposed algorithm, 3 iterations are typically sufficient to approach convergence dispensing with the dual-decomposition method. Despite the ultimate sub-optimality, the intermediate energy efficiency per user achieved by our proposed algorithm is much higher than that of the baseline algorithm. This becomes especially prominent, when we only use a single iteration, which is marked by the solid circle. In the right subplot of Fig 6, quantitatively, the achievable energy efficiency per user of our proposed algorithm after 3 iterations accounts for slightly more than 90% that of its ultimate counterpart constituted by our baseline algorithm.

IV. CONCLUSIONS

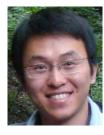
In this paper, we discussed the hitherto-unexplored amorphous structure for constructing energy efficient VLC systems. This problem was approached by the joint design of three inter-linked aspects under the critical consideration of optical constraints. Our numerical results demonstrated that the amorphous structure proposed is beneficial in VLC system design, since it results in a higher energy efficiency than that of the conventional structure. Furthermore, our proposed algorithm is capable of performing close to the baseline algorithm, making it an attractive design alternative. Finally, our proposed amorphous structure constitutes a promising LiFi solution, providing services in various indoor applications, including museums, offices and hospitals. These observations stimulate a range of further research topics, such as the energy efficient VLC system design taking into account the clipping-distortion of DCO-OFDM, the co-design of energy efficient communication and illumination, the network power consumption of VLC system, the comparison to other OOFDM schemes [37], [40], [41], the investigation of non-linear VT, and finally the robust design under channel estimation uncertainties, etc.

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