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PITCH ROLL BUOY DIRECTIONAL WAVE DATA  
PROCESSING USING AN ACORN MICROCOMPUTER

HARDWARE & SOFTWARE  
DETAILS

K.G.Birch and J.A.Ewing

March 1985

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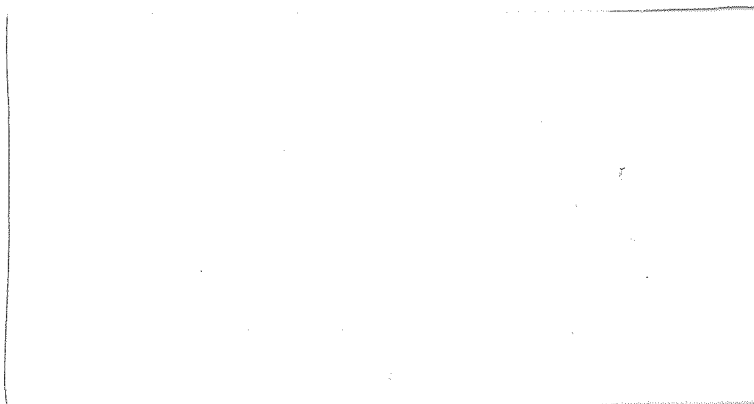
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## Circuits and Diagrams

Hardware Interface

Figure 1.

Cross Spectral Estimates

Figure 2.

One Dimensional Wave Spectra, Angular Harmonics and  
Directional Parameters

Figure 3

Energy Spectra plotted on linear axes

Figure 4.

Energy Spectra plotted on logarithmic axes

Figure 5.

Plots of Mean Direction and Directional Spread

Figure 6.

## 1. Objective.

In many of today's wave measurements programmes it is desirable to produce real time directional wave spectra, a system using an inexpensive microcomputer has been developed to accommodate this need.

## 2. Introduction

The pitch roll buoy is regularly used for the collection of wave data in the open ocean from an attendant ship. Normally the data is recorded in digital format on magnetic tape and after the cruise it is processed on a mainframe computer. This system works well but the processed data is not available until some time after the cruise. The laboratory mainframe computer has one advantage over the microcomputer that of speed, however this is not an overriding consideration at sea as sequential wave measurements are at least one hour apart and in routine sampling schemes measurements are usually separated by three hours.

The implementation of near real time processing is achieved by transmitting the serial data from the Pitch Roll Buoy Monitor Unit asynchronously to the microcomputer. The data is stored on disc in its raw format, and subsequently processed using the Fast Fourier Transform (FFT) algorithm to produce a directional spectrum with the results being stored on disc. The spectra are then plotted on linear or logarithmic axes to VDU and/or printer. The availability of near real time wave information thus allows decisions to be made on the planning and organization of experimental programs of work at sea.

## 3. System Description.

### Data Acquisition.

The microcomputer used in the system is the Acorn BBC Model B, with 6502 Second Processor, Dual Disc drive and Epson FX-80 Printer. The microcomputers memory is insufficient to hold the raw data set and carry out the processing, therefore the data is written to disc as it is acquired. The Operating System requires the use of the resident processor to write data from the temporary storage buffer to the disc controller, this means that although the software can be synchronised directly to the Pitch Roll Buoy any disc write operation will lose data and synchronisation. To overcome this problem it is necessary to allow the data transmission to between Buoy and Computer to be asynchronous, the use of a First in First Out Register (FIFO) makes this possible.

The data format used in the Pitch Roll Buoy is ten channels of three digit Binary Coded Decimal (BCD). The data from channels 0-3 (Acceleration, Pitch, Roll and Compass) is repeated in channels 4-7 with channel 8 as the record number and channel 9 as the scan count. To

reduce the data storage to a minimum only the first four channels of data are stored with redundant data being rejected by software. The hardware interface (fig.1) causes the BCD digits to be strobed into FIFO with one character in the least significant nibble of each byte (thirty characters per data frame). At the end of each data frame an extra strobe is generated, with the most significant nibble of the data byte being forced true.

The transfer of data between the FIFO and the User Port is carried out under software control with a handshake routine. At the start of data acquisition the program prompts the operator to CLEAR THE MICROBUFFER (FIFO) this deletes any data previously acquired. The data is then entered into the microcomputer when the CBI line of the User Port is strobed by the FIFO. When the strobe is received the User port latch is read and the byte is checked to determine if the most significant nibble is true, if false the byte is discarded. The User Port then strobes the FIFO using the CB2 line. The FIFO then presents the next data byte to the User Port and strobes the CBI line. This sequence of acquiring bytes continues until an end of frame flag is detected, this establishes software synchronisation with the knowledge that the next byte will be the first data character of the next data frame. The data bytes are then acquired using the handshake routine, each being checked for end of frame flag, if false the byte is stored in memory until an end of frame flag is detected. The three BCD characters of each channel are then used to calculate the channel value as an integer variable within the computer. All ten channels are then displayed on the VDU and the first four channels are written to disc. The computer continues to acquire data until the required number of data points is reached. The ability of the software to recognise the end of data frame by testing for the high nibble being true means that any errors within any one frame of data do not cause errors in subsequent data frames.

The Operating System of the microcomputer stores data to be written to disc in a 256 byte buffer. When the buffer is full the Operating System halts the program and passes the data through the processor to the disc controller. Each time a disc write operation is made the disc must first be spun up to speed, this combined with the actual write operation takes approximately two seconds, and it is this delay that makes input of data under software control mandatory. Despite this delay the computer is easily able to catch up time lost during the disc write cycle.

## Data Processing

### Theory

The method of computing the directional wave spectrum from the pitch-roll buoy follows the theory given by Longuet-Higgins et al; (1963: In "Ocean Wave Spectra", Prentice-Hall, 111-136). Essentially the directional spectrum is derived from the six cross spectral estimates obtained from correlating the heave acceleration with the two component slopes in the North-East directions. We denote heave acceleration by the subscript 1 and the slopes in north and east directions by the subscripts 2 and 3 respectively.

The basic data thus consists of the cross-spectra  $C_{11}, C_{22}, C_{33}, Q_{12}, Q_{13}$  and  $C_{23}$ . From these data, estimates of the

normalized angular harmonics  $A_1, B_1, A_2, B_2$  and the check ratio,  $R$ , are obtained. Finally a number of statistical parameters are evaluated, namely:-

TH1 = mean wave direction from 1st order angular harmonics,  
TH12 = mean wave direction from 2nd order angular harmonics,  
TH2 = directional spread,  
S1, S2 = estimates of exponent of cosine-power law obtained from 1st and 2nd order angular harmonics.

#### Method of Processing

The processing proceeds in three stages:-

(i) Program GEO reads the raw data of heave acceleration, pitch, roll and compass and computes geo-orientated data in the form of heave acceleration and two component slopes (That is, the series 1, 2 and 3 referred to above). These data are written to disc. Each series consists of 4 groups of 1024 data points sampled simultaneously at 0.5 sec interval. CAL2 and CAL3 are calibrations for pitch and roll in units of radians per digital unit (d.u.) CAL 4 is the compass calibration (radians per d.u.), OF4 is the magnetic variation offset (in radians).

(ii) Program DWS carries out the main computation. The appropriate cross-spectra (see above) are evaluated in turn by reading the data from selected pairs of channels previously stored on disc using program GEO. Spectral estimates are obtained using the Fast Fourier Transform (FFT) algorithm over 1024 data points and repeating this operation over four sections. Finally, spectral estimates are formed from the average over seven adjacent harmonics, thus having fifty six degrees of freedom with frequencies at 7/512 Hz interval.

CAL1 is the calibration for heave in units of 'g' per d.u. Procedure DPAR calculates the statistical parameters. Procedure FFT is the Fast Fourier Transform.

The cross spectra, angular harmonics, check ratio and directional parameters are printed out. Finally the wave height spectrum, mean direction and angular spread are written to disk ready for plotting.

(iii) Program PLMZ reads the data from disc and plots to VDU a selected parameter under operator command from the User Keys. The wave height spectrum can be plotted on linear axes or logarithmic axes. If linear axes are chosen a maximum scale value of either 0.1, 1.0 or 10.0  $M^2/M/Hz$  is selected to give the best screen resolution of the data.

The directional parameters TH1 and TH2 are plotted together on linear axes.

Hard copy of any graphical display on the screen may be obtained via User Key menu.

#### 4. Program Timing

The time taken for the analysis of four sections of data (each of 1024 records) is thirty minutes, this time will be reduced in the future by the use of an FFT Rom.



SOFTWARE DESCRIPTIONData AcquisitionPRBDW

Lines 10-90 Main program: This is three Procedures, the first two (PROCsetup and PROCscreen) control screen headings and text windows. The third procedure (PROCdin) controls the input of data, the writing to screen and the storing of data to disc.

Lines 110-160 PROCsetup: This procedure stores the screen heading as a series of strings which are accessed by PROCscreen.

Lines 180-250 PROCscreen: This procedure writes the screen heading and sets up the text window.

Lines 260-300 PROCdin. Clears screen and prompts the operator to enter file name. Drive 1 is enabled and a file opened with the file name written to disc.

Lines 310-340 Clears screen and writes command to 'CLEAR MICROBUFFER' to screen and awaits command input to start data acquisition.

Lines 360-400 Declares addresses used by labels in assembler routines. Dimensions storage area for machine code.

Lines 440-490 Initialises storage pointers and counters.

Lines 500-720 RUPT is an interrupt routine which is executed immediately the FIFO strobes CB1. The current contents of the accumulator, the X and the Y registers are saved to stack and recalled at completion of the routine. The input port is read and saved in a temporary storage area, the high nibble is checked for end of frame flag, which if true causes the end of frame marker to be set and no more bytes are called. However if the high nibble is false the byte is stored in memory until a complete data set has been collected. After each data byte is stored the CB2 line is strobed with a 6 microsecond pulse and the bytes which were saved to stack are reloaded to the accumulator, and to the X and Y registers. For the duration of the CB2 pulse all interrupts are inhibited ensuring the length of the pulse is not affected at any time by a system interrupt. When a frame flag is detected in the data, a marker (FF hex) is set which the Basic program waiting to detect.

Lines 730,840 The routine GO sets up the User Port for the input of data latched by a negative going pulse on CB1, and the IRQ2 vectors are set to point to the routine RUPT.

Lines 850-930 The routine STRB is called after the data set has been processed, it resets the end of frame marker and strobes the CB2 line to commence the input of a new data frame.

Lines 950-960 Calls the initialisation routines.

Lines 970-980 Sets print format and sets data frame counter to zero.

Lines 990-1000 Causes strobe to FIFO to be generated and waits for data frame marker to be detected.

Line 1010 Detects first data frame marker and causes data prior to that time to be ignored.

Lines 1020-1060 Prints all ten channels of data to screen and writes first four channels to disc.  
Lines 1070-1090 Print clear line on screen to make data easier to read, increments frame counter and checks whether the record is completed.  
Lines 1100-1110 File closed and drive 0 enabled.

PRBDW

```

10 REM PROG IS CALLED PRBDW
20 *****
30 REM THIS PROG INPUTS DATA FORM P/R BUOY
40 REM FIRST FOUR DATA CHANNELS ARE WRITTEN TO DISC
50 MODE 7
60 PROCsetup
70 PROCscreen
80 PROCdin
90 END
100 *****
110 DEFPROCsetup
120 DIM TITLE$(2)
130 TITLE$(0)="                PITCH ROLL BUOY"
140 TITLE$(1)=" ACC          ROLL          ACC          ROLL          R NUM"
150 TITLE$(2)="          PITCH COMPASS PITCH COMPASS SCAN"
160 ENDPROC
170 *****
180 DEF PROCscreen
190 FOR N%=0 TO 2
200 IF N%=1 THEN PRINT
210 PRINTTITLE$(N%)
220 NEXT
230 VDU28,0,23,39,4
240 ENDPROC
250 *****
260 DEFPROCdin
270 CLS
280 *DRIVE 1
300 INPUTTAB(10,10)"INPUT FILE NAME",A$
310 X=OPENOUT A$:PRINT#X,A$
315 CLS
320 PRINTTAB(10,6)"CLEAR MICROBUFFER"
330 PRINTTAB(2,9)"PRESS ANY KEY TO START DATA INPUT"
340 B$=GET$
350 ?&8E=0
360 IRQ2V=&0206
370 OSASCI=&FFE3
380 OSBYTE=&FFF4
390 STORE =&3000
400 DIM INIT 400
410 FOR I%= 0 TO 2 STEP 2
420 P%=INIT
430 [OPT I%
440 .INIT   LDA  £&00
450         STA  &8F
460         STA  &8E           \RESET POINTERS
470         LDA  £&E0
480         STA  &FE6C        \SET CB2 HIGH
490         RTS
500 .RUPT  PHA:TXA:PHA:TYA:PHA  \SAVE REGISTERS
510         LDA  &FE60        \READ INPUT PORT
520         STA  &301F        \SAVE IN TEMP STORE
530         AND  £&F0        \MASK LOW 4 BITS
540         CMP  £&F0        \CHECK FOR FRAME SYNC

```

```

550      BEQ FRAME          \DETECT FRAME
560      LDA &8E            \LOAD STORAGE POINTER
570      TAX                \STORE IN X REG
580      LDA &301F          \RELOAD DATA
590      AND £&0F           \MASK OFF HIGH 4 BITS
600      STA STORE,X       \STORE DATA
610      INC &8E            \INCREMENT STORAGE POINTER
620      LDA £&C0
630      SEI                \DISABLE INTERRUPTS
640      STA &FE6C          \SET CB2 LOW
650      LDA £&E0
660      STA &FE6C          \SET CB2 HIGH
670      CLI                \ENABLE INTERRUPTS
680      JMP FINAL
690.FRAME LDA £&FF          \SET FRAME SYNC PTR
700      STA &8E            \STORE STORAGE POINTER
710.FINAL PLA:TAY:PLA:TAX:PLA \RESTORE REGISTERS
720      RTI
730.GO   SEI                \DISABLE INTERRUPTS
740LDA £&97:LDX £&6C       \SELECT PCR ON USER VIA
750      LDY £0:JSR OSBYTE  \SET UP TO DETECT H-L TRANS.

760      LDA £&97:LDX £&6E  \SELECT IER ON USER VIA
770      LDY £&6F:JSR OSBYTE \DISABLE ALL BUT CB1

INTERRUPTS
780      LDA £&97:LDX £&6E  \SELECT IER ON USER VIA
790      LDY £&90:JSR OSBYTE \ENABLE CB1 INTERRUPTS
800      \SET IRQ2 VECTORS TO POINT TO

RUPT
810      LDA £RUPT MOD 256:STA IRQ2V
820      LDA £RUPT DIV 256:STA IRQ2V+1
830      CLI                \ENABLE INTERRUPTS
840      RTS
850.STRB LDA £&00
860      STA &8E            \RESET FRAME SYNC
870      LDA £&C0
880      SEI                \DISABLE INTERRUPTS
890      STA &FE6C          \SET CB2 LOW
900      LDA £&E0
910      STA &FE6C          \SET CB2 HIGH
920      CLI                \ENABLE INTERRUPTS
930      RTS
940]NEXT I%
950 CALL INIT
960 CALL GO
970 @%=04
980 J=0
990 CALL STRB
1000 IF ?&8E=255 THEN 1010 ELSE 1000
1010 IF J=0 THEN 1080
1020 FOR I=12288 TO 12317 STEP 3
1030 D%=INT(?I*100+?(I+1)*10+?(I+2))
1040 PRINT D%;
1050 IF I<12298 THEN PRINT£X,D%
1060 NEXT
1070 PRINT
1080 J=J+1
1090 IF J=4098 THEN 1100 ELSE 990

```

```
1100 CLOSEEX  
1110 *DRIVE0  
1120 ENDPROC  
1130 *****
```

Data Processing

GEO

Lines 10-60 Rem statements with program description,also array dimensions and output format code.

Lines 70-130 Screen description of disc configuration required for data processing.

Lines 140-180 Calibration values.

Lines 190-220 File name entry via keyboard.

Lines 240-280 Open input and output files ready for processing.

Lines 290-300 Input File name of raw data

Lines 310-330 Loop for reading data, selecting drive 1 for data input and setting pitch/roll total variables to zero.

Lines 340-380 Read 1024 data points and sums pitch and roll values.

Lines 390-410 Calculates mean value of pitch and roll.

Lines 420-560 Calculates the slopes from pitch and roll values.The acceleration and slope values are then written to disc.

Lines 570-580 Prints end of section data points to screen,then returns for next section.

Lines 590-660 Close files,write instructions to screen as to how to continue processing.

GEO

```

10 REM PROGRAM TO READ P-R DATA AND COMPUTE COMPONENT
SLOPES.FINALLY WRITING TO DISK READY FOR CROSS-SPECTRAL ANALYSIS
20 DIM A(1024),P(1024),R(1024),C(1024)
30 REM A,P,R & C ARE HEAVE ACCN,PITCH,ROLL &COMPASS
40REM MIZEX CALS. IN RADIANS/DIG. UNIT:MAY 1984
50 @%=&20208
60 CLS
70 PRINT TAB(5,7)" RAW DATA DISK IN DRIVE '1'"
80 PRINT TAB(5,10)"PLACE EMPTY FORMATTED DISK"
90 PRINT TAB(12,12)"IN DRIVE '0'"
100 PRINT TAB(5,20)"PRESS ANY KEY TO CONTINUE"
110 V$=GET$
120 FOR I=0 TO 200
130 CLS
140 CAL2=-1.086*10^(-3)
150 CAL3=1.150*10^(-3)
160 CAL4=0.02454
170 REM ASSUME MAG. VARN. IS 14 DEG. WEST
180 OF4=-0.244
190 CLS
200 INPUT TAB(5,8) "FILE NAME WITH RAW DATA",A$
210 INPUT TAB(5,11) "FILE NAME FOR GEO-SERIES",AA$
230 REM LOOP 4 TIMES OVER 1024 RECORDS
240 *DRIVE 0
250 Z=OPENOUT AA$
260 PRINT#Z,AA$
270 *DRIVE 1
280 ZZ=OPENIN A$
290 CLS
300 INPUT#ZZ,C$:PRINT TAB(16,10) C$
310 FOR J%=1 TO 4
320 *DRIVE 1
330 S1=0.:S2=0.
340 FOR I%=1 TO 1024
350 INPUT#ZZ,A(I%),P(I%),R(I%),C(I%)
360 S1=S1+P(I%)
370 S2=S2+R(I%)
380 NEXT I%
390 REM COMPUTE MEANS
400 MP=S1/1024.
410 MR=S2/1024.
420 *DRIVE 0
430 REM GEO-ORIENTATE SERIES
440 FOR I%=1 TO 1024
450 THETA=C(I%)*CAL4+OF4
460 THETA=0.0
470 U=COS(THETA)
480 V=SIN(THETA)
490 S=P(I%)-MP
500 T=R(I%)-MR
510 S=S*CAL2
520 T=T*CAL3
530 X=S*U-T*V

```

```
540 Y=T*U+S*V
550 PRINT£Z,A(I%),X,Y
560 NEXT I%
570 PRINT J%,A(1024),X,Y
580 NEXT J%
590 CLOSE£ZZ
600 CLOSE£Z
610 CLS
620 PRINT TAB(8,4)"TO CONTINUE PROCESSING"
630 PRINT TAB(1,8)"TRANSFER DISK CONTAINING FILE ";CHR$(136);AA$
640 PRINT TAB(6,10)"FROM DRIVE '0' TO DRIVE '1'"
650 PRINT TAB(4,12)"PLACE SYSTEMS DISK IN DRIVE '0'"
660 PRINT TAB(3,18);"TYPE";CHR$(136);"CHAIN DWS:."CHR$(137);"AND
PRESS RETURN"
```



DWS

Lines 10-70 Set up arrays. A and B are used in FFT. Arrays Cxy are cross spectra. Arrays ACxy are averaged cross spectra.

Lines 80-150 Array size is 1024. T is length of section in seconds. NH% is the number of harmonics for spectral average.

Lines 160-230 Set initial cross spectra to zero.

Lines 250-290 Input number of sections to be processed. CAL1 is heave calibration in 'g' per digital units

Lines 300-420 Set up file names. M% is number of sections

Lines 430-640 Compute cross spectra for series 1 and 2. Print out last array values for check purposes.

Lines 650-810 Cross spectra for series 1 and 3

Lines 820-980 Cross spectra for series 2 and 3

Lines 990-1190 Compute average cross spectra (over NH% adjacent harmonics). AE is wave height spectrum obtained from C11 in usual method.

Lines 1200-1270 Print out cross-spectral estimates

Lines 1280-1490 Evaluate and print out angular harmonics (A1, B1, A2, B2) check ratio (R) and directional parameters (TH1, TH2). Write AE, TH1, TH2 to disc ready for plotting.

Lines 1500-1760 Procedure DPAR evaluates directional parameters given angular harmonics

Lines 1770-2180 Procedure for Fast Fourier Transform

DWS

```
10 CLS
20 INPUT TAB(10,10)"SKIP 0,1,2 OR 3 SECTIONS";SKIP
30 MODE 7
40 DIM
A(1024),B(1024),C11(270),C22(270),C33(270),C23(270),Q12(270),Q13(270)
50 DIM AE(37),AC11(37),AC22(37),AC33(37),AC23(37),AQ12(37),AQ13(37)
60 REM SET ARRAY SIZE N
70 N%=1024
80 *DRIVE 1
90 T=512.
100 NH%=7
110 REM SET RANGE OF FREQUENCIES
120 NL=3:NU=37
130 NN%=270
140 V%=-1
150 RT=1./T
160 FOR K%=1 TO 270
170 C11(K%)=0.
180 C22(K%)=0.
190 C33(K%)=0.
200 C23(K%)=0.
210 Q12(K%)=0.
220 Q13(K%)=0.
230 NEXT K%
240 INPUT TAB(10,10)"NUMBER OF SECTIONS",M%
250 CLS
260 R=0.5*T/(M%*NH%)
270 CAL1=9.926*10(-4)
280 R1=R*CAL1*CAL1
290 R2=R*CAL1
300 CLS
310 INPUT TAB(10,10)"FILE NAME OF INPUT DATA",A$
320 CLS
330 INPUT TAB(10,10)"FILE NAME OF OUTPUT DATA",B$
340 CLS
350 VDU2
360 PRINT TAB(5,10)"FILE NAME OF INPUT ";A$
370 PRINT TAB(5,13)"FILE NAME OF OUTPUT ";B$
380 PRINT TAB(10,15),"NO. OF SECTIONS",M%
390 PRINT "NO. OF HARMONICS IN SPECTRAL ESTIMATES",NH%
400 PRINT
410 PRINT "DATA VALUES":PRINT
420 VDU3
430 @%=&20208
440 Z=OPENIN A$
450 INPUT#Z,C$
460 ADD=LEN(C$)+2
470 PTR#Z=18432*SKIP+ADD
480 FOR L%=1 TO M%
490 FOR I%=1 TO 1024
500 INPUT#Z,A(I%),B(I%),DUM
510 NEXT I%
520 VDU2:PRINT L%,A(1024),B(1024):VDU3
```

```
530  PROCFFT(10,N%,V%)
540  FOR J%=2 TO NN%
550  Q%=N%-J%+2
560  C1=A(J%)+A(Q%)
570  C2=B(J%)+B(Q%)
580  S1=B(J%)-B(Q%)
590  S2=-A(J%)+A(Q%)
600  C11(J%)=C11(J%)+C1*C1+S1*S1
610  C22(J%)=C22(J%)+C2*C2+S2*S2
620  Q12(J%)=Q12(J%)+S1*C2-C1*S2
630  NEXT J%
640  NEXT L%
650  PTRFZ=18432*SKIP+ADD
660  FOR L%=1 TO M%
670  FOR I%=1 TO 1024
680  INPUTFZ,A(I%),DUM,B(I%)
690  NEXT I%
700  VDU2:PRINT L%,A(1024),B(1024):VDU3
710  PROCFFT(10,N%,V%)
720  FOR J%=2 TO NN%
730  Q%=N%-J%+2
740  C1=A(J%)+A(Q%)
750  C3=B(J%)+B(Q%)
760  S1=B(J%)-B(Q%)
770  S3=-A(J%)+A(Q%)
780  C33(J%)=C33(J%)+C3*C3+S3*S3
790  Q13(J%)=Q13(J%)+S1*C3-C1*S3
800  NEXT J%
810  NEXT L%
820  PTRFZ=18432*SKIP+ADD
830  FOR L%=1 TO M%
840  FOR I%=1 TO 1024
850  INPUTFZ,DUM,A(I%),B(I%)
860  NEXT I%
870  VDU2:PRINT L%,A(1024),B(1024):VDU3
880  PROCFFT(10,N%,V%)
890  FOR J%=2 TO NN%
900  Q%=N%-J%+2
910  C2=A(J%)+A(Q%)
920  C3=B(J%)+B(Q%)
930  S2=B(J%)-B(Q%)
940  S3=-A(J%)+A(Q%)
950  C23(J%)=C23(J%)+C2*C3+S2*S3
960  NEXT J%
970  NEXT L%
980  CLOSEFZ
990  FOR I%=NL TO NU
1000 AE(I%)=0.
1010 AC11(I%)=0.
1020 AC22(I%)=0.
1030 AC33(I%)=0.
1040 AC23(I%)=0.
1050 AQ12(I%)=0.
1060 AQ13(I%)=0.
1070 FOR J%=1 TO NH%
1080 K%=J%+NH%*I%
1090 FREQ=(K%-1)*RT
1100 RF4=96.2/(6.2832*FREQ)^4
```

```

1110 AE(I%)=AE(I%)+RF4*C11(K%)*R1
1120 AC11(I%)=AC11(I%)+C11(K%)*R1
1130 AC22(I%)=AC22(I%)+C22(K%)*R
1140 AC33(I%)=AC33(I%)+C33(K%)*R
1150 AC23(I%)=AC23(I%)+C23(K%)*R
1160 AQ12(I%)=AQ12(I%)+Q12(K%)*R2
1170 AQ13(I%)=AQ13(I%)+Q13(K%)*R2
1180 NEXT J%
1190 NEXT I%
1200 MODE3:VDU2
1210 @%=&0000040A
1220 PRINT "      F          C11          C22          C33          Q12          Q13
      C23"
1230 PRINT
1240 FOR I%= NL TO NU
1250  FREQ=(NH%*I%+2)*RT
1260  PRINT FREQ,AC11(I%),AC22(I%),AC33(I%),AQ12(I%),AQ13(I%),AC23(I%)
1270  NEXT I%
1280  PRINT:PRINT
1290  PRINT "      F          E          A1          B1          A2          B2          R          TH1          TH12
TH2      S1          S2"
1300  PRINT
1310  @%=&01020206
1320  Q=OPENOUT B$
1330  FOR I%=NL TO NU
1340  FREQ=(7*I%+2)*RT
1350  S=AC11(I%)
1360  XX=AC22(I%)+AC33(I%)
1370  X1=SQR(S*XX)
1380  A1=AQ12(I%)/X1
1390  B1=AQ13(I%)/X1
1400  A2=(AC22(I%)-AC33(I%))/XX
1410  B2=2.*AC23(I%)/XX
1420  REX=SQR(S/XX)
1430  PROCDPAR(A1,B1,A2,B2)
1440  PRINT FREQ,AE(I%),A1,B1,A2,B2,REX,TH1,TH12,TH2,SP1,SP2
1450  PRINTEQ,I%,AE(I%),TH1,TH2
1460  NEXT I%
1470  VDU3:MODE 7
1480  CLOSEEQ
1490  END
1500  *****
1510  DEF PROCDPAR(A1,B1,A2,B2)
1520  LOCAL X1,X2,Y1,Y2,Y3,Z,Z1,C1,C2
1530  X1=ATN(B1/A1)
1540  Z=DEG(X1)
1550  IF B1>0. AND A1<0. THEN Z=Z+180.
1560  IF B1<0. AND A1<0. THEN Z=Z-180.
1570  IF Z<0. THEN Z=360.+Z
1580  TH1=Z
1590  C1=SQR(A1*A1+B1*B1)
1600  IF C1>1. THEN C1=1.
1610  TH2=SQR(2.-2.*C1)
1620  SP1=2./(TH2*TH2)-1.
1630  TH2=DEG(TH2)
1640  A2=A2+.0001
1650  X2=ATN(B2/A2)
1660  Z1=0.5*DEG(X2)

```

```

1670 IF B2>0. AND A2<0. THEN Z1=Z1+90.
1680 IF B2<0. AND A2<0. THEN Z1=Z1-90.
1690 IF Z1<0. THEN Z1=360.+Z1
1700 TH12=Z1
1710 C2=SQR(A2*A2+B2*B2)
1720 Y1=1.+3.*C2
1730 Y2=SQR(1.+14.*C2+C2*C2)
1740 Y3=2.*(1.-C2)
1750 SP2=(Y1+Y2)/Y3
1760 ENDPROC
1770 *****
1780 DEF PROCFFT(N%,B%,V%)
1790 LOCAL L%,D%,K%,M%,ME%,J%,TR,TI
1800 FOR J%=1 TO B%
1810 A(J%)=A(J%)/B%
1820 B(J%)=B(J%)/B%
1830 NEXT
1840 D%=B% DIV 2
1850 G%=B%-1
1860 J%=1
1870 FOR L%=1 TO G%
1880 IF L%>J% OR L%=J% GOTO 1920
1890 TR=A(J%):TI=B(J%)
1900 A(J%)=A(L%):B(J%)=B(L%)
1910 A(L%)=TR:B(L%)=TI
1920 K%=D%
1930 IF K%>J% OR K%=J% GOTO 1970
1940 J%=J%-K%
1950 K%=K% DIV 2
1960 GOTO 1930
1970 J%=J%+K%
1980 NEXT
1990 FOR M%=1 TO N%
2000 UR=1.0:UI=0.0
2010 ME%=2^M%
2020 K%=ME% DIV 2
2030 PK=PI/K%
2040 WR=COS(PK):WI=V%*SIN(PK)
2050 FOR J%=1 TO K%
2060 FOR L%=J% TO B% STEP ME%
2070 Z%=L%+K%
2080 TR=A(Z%)*UR-B(Z%)*UI
2090 TI=A(Z%)*UI+B(Z%)*UR
2100 A(Z%)=A(L%)-TR:B(Z%)=B(L%)-TI
2110 A(L%)=A(L%)+TR:B(L%)=B(L%)+TI
2120 NEXT
2130 U0=UR*WR-UI*WI
2140 UI=UR*WI+UI*WR
2150 UR=U0
2160 NEXT:NEXT
2170 ENDPROC
2180 *****

```

PLMZ

Lines 10-20 This configures the function keys ready for plotting to be entered when prompted by screen,also loads screen dump routine into memory.  
 Lines 30-240 Enters file name of data to be plotted,reads data and sets plotting scale(IRGE).  
 Lines 250-300 Resets values above 0.5Hz  
 Lines 310-400 Operator prompted to select via user keys plotting requirements.Error message if incorrect key depressed.Screen dump is not allowed until plot has been performed.  
 Lines 400-430 Screen initialisation  
 Lines 440-510 Sets frequency interval and offset.Call PROCBOX to draw graph external lines.Determine using value of II which plotting procedures are required.  
 Lines 520-570 Call procedures to plot directional parameteres,and enable screen dump.Return to keyboard menu.  
 Lines 580-620 Call procedures to plot energy spectra on logarithmic axis,enables screen dump.Returns to keyboard menu.  
 Lines 630-680 Call procedures to plot energy spectra on linear axis,enables screen dump.  
 Lines 690-710 Call screen dump routine ,then returns to keyboard menu.  
 Lines 720-730 Returns system to Drive 0, turn off printer,program end.  
 Lines 750-840 Procedure to plot graph outline.  
 Lines 860-1230 Procedure for annotation of logarithmic axes.  
 Lines 1240-1380 Procedure plots data on logarithmic scale.  
 Lines 1390-1770 Procedure for annotation of linear axes.  
 Lines 1780-1960 Procedure plots data on linear scale.  
 Lines 1970-2320 Procedure for annotation of axes for directional plot.  
 Lines 2330-2570 Procedure for plotting directional data.

PLMZ

```

10 *FX225,200
20 *LOAD"DUMPCL2"
30 *DRIVE 1
40 DIM E(128),TH1(128),TH2(128)
50 REM THIS IS PROGRAM PLMZ
60 REM IT READS 1-D SPECTRUM E FROM DISK
70 REM ROUTINE FOR PLOTTING 1 & 2-D SPECTRA FROM MIZEX
80 REM LINEAR OR LOG PLOTS ARE MADE
90 REM PLOT IS SELECTED USING II
100 MODE 4
110 PRINTTAB(17,8)"FILE NAME "
120 INPUT TAB(17,8)"FILE NAME "A$
130 CLS
140 PRINTTAB(17,8)A$
150 EMAX=0
160 X=OPENIN A$
170 FOR I%=3 TO 37
180 INPUTEX,I%,E(I%),TH1(I%),TH2(I%)
190 IF E(I%)>EMAX THEN EMAX=E(I%)
200 NEXT I%
210 CLOSEEX
220 IRGE=1
230 IF EMAX>0.1 THEN IRGE=2
240 IF EMAX>1.0 THEN IRGE=3
250 REM SET VALUES ABOVE 0.5 HZ TO ARBITRARY NOS.
260 FOR I%=38 TO 100
270 E(I%)=10^(-4)
280 TH1(I%)=0.
290 TH2(I%)=0.
300 NEXT I%
310 DS=204
320 PRINT TAB(0,28),"ENTER PLOTTING REQUIREMENTS VIA RED KEYS"
330 D=GET
340 IF D>199 AND D<DS THEN 380 ELSE PRINTTAB(0,28),"
WRONG KEY "
350 FOR Q=1 TO 1500
360 NEXT
370 GOTO 320
380 II=D-201
390 IF II=-1 THEN GOTO 720
400 IF II=3 THEN 690
410 COLOUR 1:COLOUR 128
420 GCOL 0,3:GCOL 0,128
430 CLS:CLG
440 REM SET CONSTANTS FOR FRQY. INTERVAL AND OFFSET
450 DF=7./512.:OST=2./512.
460 DD=20
470 XOR=200:YOR=200:XM=800:YM=800
480 PROCBOX(XOR,YOR,XM,YM)
490 IF II=0 THEN GOTO 630
500 IF II=1 THEN GOTO 580
510 IF II=2 THEN GOTO 520
520 FL=0.05:FU=0.40

```

```

530 PROCAXDP(XOR,YOR,DD)
540 PROCDP(FL,FU,DF,1)
550 PROCDP(FL,FU,DF,2)
560 DS=205
570 GOTO 320
580 FL=0.05:FU=0.6
590 PROCAXLOG(XOR,YOR,DD)
600 PROCLOG(FL,FU,DF)
610 DS=205
620 GOTO 320
630 FL=0.04:FU=0.40
640 REM IRGE SETS VERT. SCALE ON LINEAR AXES
650 PROCAXLIN(XOR,YOR,DD,IRGE)
660 PROCLIN(FL,FU,DF,IRGE)
670 DS=205
680 GOTO 710
690 PRINTTAB(0,28),"
700 VDU2:VDU1,12 :CALL &C000:VDU3
710 GOTO 320
720 *DRIVE 0
730 VDU3 :END
740 *****
750 REM PROCEDURES USED FOR PLOTTING RESULTS
760 REMMODIFIED FOR MIZEX CONDITIONS
770 DEF PROCBOX(XOR,YOR,XM,YM)
780 REM DRAWS BOX FOR GRAPH
790 MOVE XOR,YOR
800 DRAW XM+XOR,XOR
810 DRAW XM+XOR,YM+YOR
820 DRAW XOR,YM+YOR
830 DRAW XOR,YOR
840 ENDPROC
850 *****
860 DEF PROCAXLOG(XOR,YOR,DD)
870 REM ANNOATES LOG-LOG AXES
880 LOCAL XK,YK,A,B,D1,D2,D3,D4
890 XK=XOR:YK=YOR
900 A=200:B=160
910 D1=50:D2=40
920 D3=130:D4=-8
930 FOR I%=1 TO 5
940 MOVE XK,YOR
950 DRAW XK,YOR-DD
960 VDU5
970 MOVE XK-D1,YOR-D2
980 IF I%=1 THEN PRINT ".038"
990 IF I%=3 THEN PRINT "0.15 HZ"
1000 IF I%=5 THEN PRINT "0.6"
1010 VDU4
1020 XK=XK+A
1030 NEXT I%
1040 REM
1050 FOR I%=1 TO 6
1060 MOVE XOR,YK
1070 DRAW XOR-DD,YK
1080 VDU5
1090 MOVE XOR-D3,YK-D4
1100 IF I%=1 THEN PRINT "-4"

```



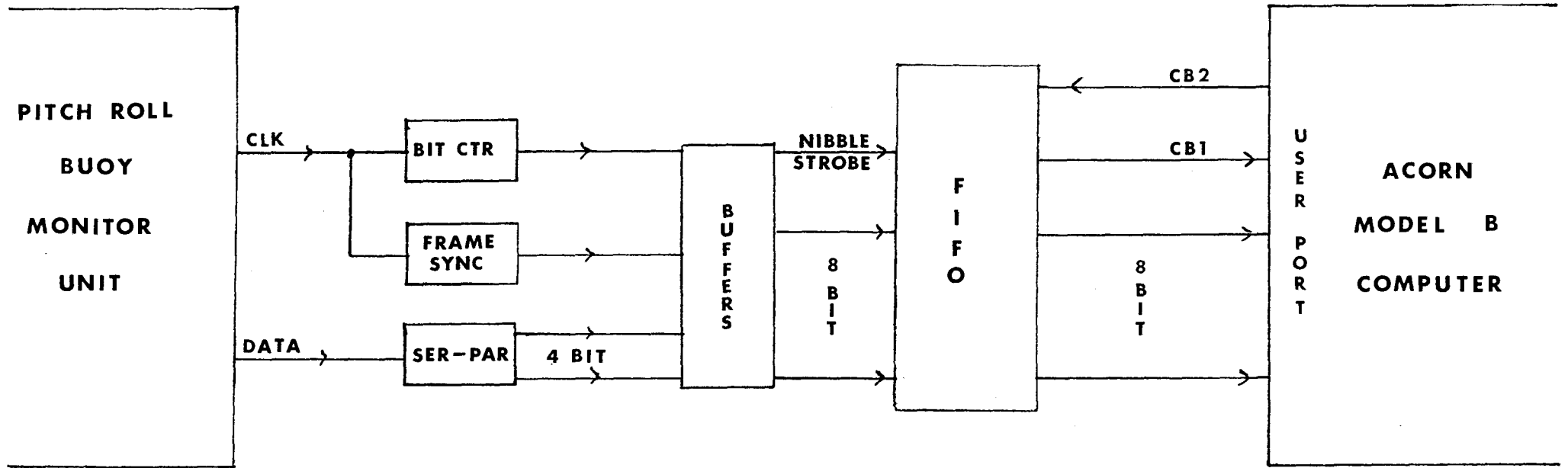
```

1110 IF I%=3 THEN PRINT " -2"
1120 IF I%=5 THEN PRINT " 0"
1130 YK=YK+B
1140 NEXT I%
1150 MOVE 80,730:PRINT "LOG"
1160 MOVE 80,650:PRINT "M*M"
1170 MOVE 67,610:PRINT " HZ"
1180 MOVE 80,630:PRINT "---"
1190 MOVE 750,950:PRINT A$
1200 MOVE 500,950:PRINT "SIR-B"
1210 VDU4
1220 ENDPROC
1230 *****
1240 DEF PROCLOG(FL,FU,DF)
1250 REM PLOTS E ON LOG-LOG
1260 LOCAL J1%,J2%,A,B,C,D
1270 J1%=INT(FL/DF)
1280 J2%=INT(FU/DF)
1290 REM SET A & B FOR SIR-B
1300 A=1.426:B=664.5:C=4:D=160
1310 MOVE (LOG(J1%*DF+OST)+A)*B+XOR,(LOG(E(J1%))+C)*D+YOR
1320 FOR J%=J1%TO J2%
1330 X=(LOG(J%*DF+OST)+A)*B
1340 Y=(LOG(E(J%))+C)*D
1350 DRAW X+XOR,Y+YOR
1360 NEXT J%
1370 ENDPROC
1380 *****
1390 DEF PROCAXLIN(XOR,YOR,DD,IRGE)
1400 REM AXES ON LINEAR SCALES
1410 LOCAL XK,YK,A
1420 XK=XOR:YK=YOR
1430 A=200
1440 D1=40:D2=40:D3=130:D4=-8
1450 FOR I%=1 TO 5
1460 MOVE XK,YOR
1470 DRAW XK,YOR-DD
1480 VDU5
1490 MOVE XK-D1,YOR-D2
1500 IF I%=1 THEN PRINT " 0"
1510 IF I%=3 THEN PRINT "0.2 HZ"
1520 IF I%=5 THEN PRINT "0.4"
1530 VDU4
1540 XK=XK+A
1550 NEXT I%
1560 FOR I%=1 TO 5
1570 MOVE XOR,YK
1580 DRAW XOR-DD,YK
1590 VDU5
1600 MOVE XOR-D3,YK-D4
1610 IF I%=1 THEN PRINT " 0"
1620 IF I%=3 AND IRGE=1 THEN PRINT ".05"
1630 IF I%=3 AND IRGE=2 THEN PRINT "0.5"
1640 IF I%=3 AND IRGE=3 THEN PRINT " 5"
1650 IF I%=5 AND IRGE=1 THEN PRINT "0.1"
1660 IF I%=5 AND IRGE=2 THEN PRINT " 1"
1670 IF I%=5 AND IRGE=3 THEN PRINT " 10"
1680 YK=YK+A

```

```
1690 NEXT I%
1700 MOVE 500,950:PRINT "SIR-B"
1710 MOVE 750,950:PRINT A$
1720 MOVE 80,520:PRINT "M*M"
1730 MOVE 67,480:PRINT " HZ"
1740 MOVE 80,500:PRINT "---"
1750 VDU4
1760 ENDPROC
1770 *****
1780 DEF PROCLIN (FL,FU,DF,IRGE)
1790 REM GRAPHS ON LINEAR SCALES
1800 LOCAL J1%,J2%,A,B
1810 J1%=INT(FL/DF)
1820 J2%=INT(FU/DF)
1830 REM SET A & B FOR SIR-B
1840 A=2000
1850 REM IRGE SCALES TO 0.1,1 & 10M*M/HZ
1860 IF IRGE=1 THEN B=8000
1870 IF IRGE=2 THEN B=800
1880 IF IRGE=3 THEN B=80
1890 MOVE( J1%*DF+OST)*A+XOR,YOR
1900 FOR J%=J1% TO J2%
1910 X=(J%*DF+OST)*A
1920 Y=E(J%)*B
1930 DRAW X+XOR,Y+YOR
1940 NEXT J%
1950 ENDPROC
1960 *****
1970DEF PROCAXDP(XOR,YOR,DD)
1980REM AXES ON LINEAR SCALES FOR DIRECTIONAL PARAMETERS
1990LOCAL XK,YK,A
2000XK=XOR:YK=YOR
2010A=200
2020D1=40:D2=40:D3=130:D4=-8
2030FOR I%=1 TO 5
2040MOVE XK,YOR
2050DRAW XK,YOR-DD
2060VDU5
2070MOVE XK-D1,YOR-D2
2080IF I%=1 THEN PRINT " 0"
2090IF I%=3 THEN PRINT "0.2   HZ"
2100IF I%=5 THEN PRINT "0.4"
2110VDU4
2120XK=XK+A
2130NEXT I%
2140FOR I%=1 TO 5
2150MOVE XOR+DD,YK
2160DRAW XOR-DD,YK
2170VDU5
2180MOVE XOR-D3,YK-D4
2190IF I%=1 THEN PRINT "180"
2200IF I%=3 THEN PRINT " 0  30"
2210IF I%=5 THEN PRINT "180  60"
2220YK=YK+A
2230NEXT I%
2240 MOVE 500,950:PRINT"SIR-B"
2250MOVE 750,950:PRINT A$
2260MOVE 80,760:PRINT"TH1"
```

```
2270MOVE 80,520:PRINT "DEG"
2280 MOVE 220,760:PRINT "TH2"
2290 MOVE 220,520:PRINT "DEG"
2300VDU4
2310ENDPROC
2320 *****
2330DEF PROCDP(FL,FU,DF,ISEL)
2340REM PLOTS OF DIRECTIONAL PARAMETERS
2350REM ISEL=1 OR 2 FOR TH1 OR TH2
2360LOCAL J1%,J2%,A,B
2370J1%=INT(FL/DF)
2380J2%=INT(FU/DF)
2390A=2000
2400REM RANGES:360 DEG FOR TH1,60 DEG FOR TH2
2410IF ISEL=1 THEN B=800/360
2420IF ISEL=2 THEN B=800/60.
2430 IF ISEL=1 THEN YY=TH1(J1%)*B ELSE YY=TH2(J1%)*B
2440MOVE (J1*DF+OST)*A+XOR,YY+YOR
2450FOR J%=J1% TO J2%
2460X=(J%*DF+OST)*A
2470IF ISEL=1 THEN 2500
2480IF ISEL=2 THEN Y=TH2(J%)*B
2490 GOTO 2530
2500 Y=(TH1(J%)+180)
2510 IF Y>360 THEN Y=Y-360
2520 Y=Y*B
2530 IF ISEL=1 THEN DRAW X+XOR,Y+YOR
2540 IF ISEL=2 THEN PLOT 21,X+XOR,Y+YOR
2550NEXT J%
2560ENDPROC
2570 *****
```



PITCH ROLL BUOY - ACORN INTERFACE FIG.1

Cross Spectral Estimates Figure 2.

FILE NAME OF INPUT GEO  
 FILE NAME OF OUTPUT AM  
 NO. OF SECTIONS 3  
 NO. OF HARMONICS IN SPECTRAL ESTIMATES 7

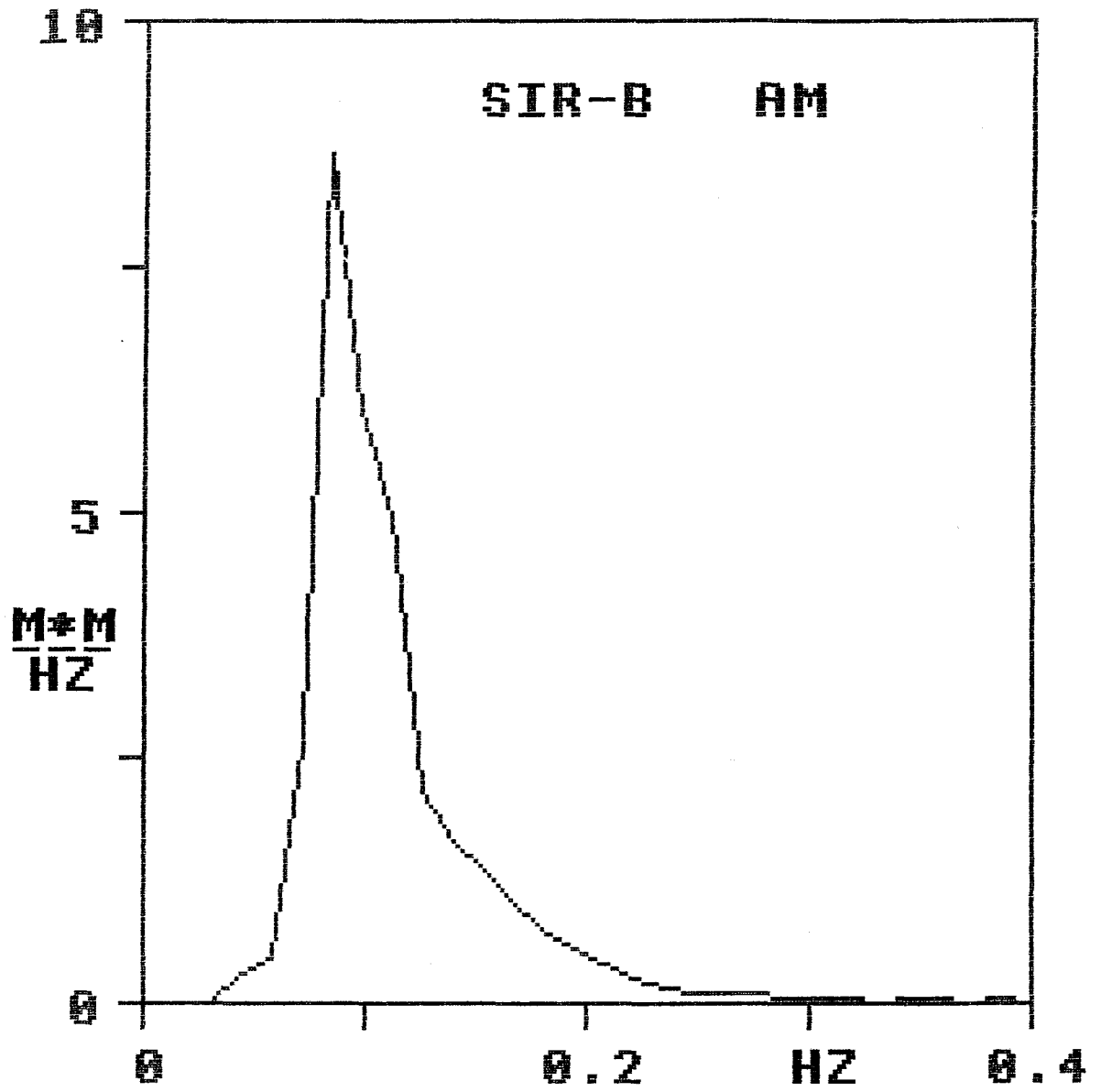
DATA VALUES

1.00	475.00	-0.03					
2.00	499.00	-0.00					
3.00	538.00	0.12					
1.00	475.00	-0.00					
2.00	499.00	0.06					
3.00	538.00	-0.11					
1.00	-0.03	-0.00					
2.00	-0.00	0.06					
3.00	0.12	-0.11					
F	C11	C22	C33	Q12	Q13	C23	
4.492E-2	2.326E-5	1.299E-4	1.68E-4	2.252E-5	5.816E-6	1.008E-5	
5.859E-2	1.172E-4	3.067E-4	1.148E-4	1.054E-4	1.668E-5	3.372E-5	
7.227E-2	1.284E-3	9.033E-4	1.095E-3	8.748E-4	7.949E-4	5.371E-4	
8.594E-2	1.004E-2	9.829E-3	1.869E-3	9.647E-3	8.259E-4	7.061E-4	
9.961E-2	1.012E-2	9.738E-3	3.338E-3	9.541E-3	2.512E-3	1.87E-3	
0.1133	1.514E-2	1.212E-2	2.034E-3	1.317E-2	2.278E-3	1.469E-3	
0.127	1.03E-2	9.685E-3	2.544E-3	9.675E-3	1.836E-3	1.536E-3	
0.1406	9.89E-3	8.124E-3	3.553E-3	8.461E-3	1.003E-3	3.494E-4	
0.1543	1.297E-2	1.126E-2	4.066E-3	1.16E-2	7.823E-4	2.352E-4	
0.168	1.535E-2	1.195E-2	3.604E-3	1.275E-2	6.496E-4	-3.067E-4	
0.1816	1.349E-2	1.246E-2	4.721E-3	1.169E-2	2.822E-3	1.306E-3	
0.1953	1.495E-2	1.569E-2	6.526E-3	1.38E-2	4.278E-3	2.354E-3	
0.209	1.744E-2	1.305E-2	4.006E-3	1.413E-2	4.425E-3	2.805E-3	
0.2227	7.868E-3	6.643E-3	4.526E-3	6.398E-3	2.752E-3	1.85E-3	
0.2363	1.036E-2	8.36E-3	4.457E-3	8.175E-3	1.122E-3	-1.371E-4	
0.25	9.283E-3	6.653E-3	4.565E-3	6.54E-3	2.38E-3	6.654E-4	
0.2637	8.407E-3	7.562E-3	5.215E-3	6.562E-3	1.981E-3	1.215E-4	
0.2773	1.404E-2	1.272E-2	6.576E-3	1.15E-2	2.643E-3	2.388E-3	
0.291	9.133E-3	7.439E-3	3.595E-3	6.808E-3	4.466E-4	-1.679E-4	
0.3047	1.138E-2	1.302E-2	4.061E-3	1.065E-2	1.91E-3	1.536E-3	
0.3184	1.252E-2	8.896E-3	5.881E-3	8.264E-3	1.5E-3	1.741E-3	
0.332	8.398E-3	8.629E-3	9.756E-3	5.71E-3	-9.516E-4	1.926E-3	
0.3457	1.163E-2	8.205E-3	1.173E-2	5.928E-3	-3.9E-3	6.91E-4	
0.3594	1.72E-2	6.637E-3	8.515E-3	4.721E-3	-3.374E-3	1.36E-3	
0.373	1.629E-2	1.122E-2	1.208E-2	2.79E-3	-5.352E-3	3.398E-3	
0.3867	1.992E-2	7.382E-3	1.817E-2	-1.401E-3	-1.148E-2	4.001E-3	
0.4004	1.934E-2	4.322E-3	1.93E-2	1.729E-3	-1.539E-2	-4.036E-4	
0.4141	2.639E-2	7.482E-3	1.433E-2	1.126E-4	-1.137E-2	2.428E-3	
0.4277	2.311E-2	1.067E-2	1.794E-2	-2.426E-3	-1.512E-2	3.035E-3	
0.4414	1.271E-2	8.51E-3	1.283E-2	-1.165E-3	-6.667E-3	1.216E-3	
0.4551	1.345E-2	1.073E-2	9.955E-3	-5.012E-3	-6.731E-3	4.597E-3	
0.4687	1.358E-2	6.132E-3	1.178E-2	-6.101E-4	-9.76E-3	1.078E-3	
0.4824	1.295E-2	6.921E-3	9.512E-3	-1.468E-3	-7.973E-3	1.062E-3	
0.4961	9.523E-3	5.637E-3	1.447E-2	-1.803E-3	-8.333E-3	-2.616E-4	
0.5098	1.607E-2	6.571E-3	7.249E-3	-4.092E-3	-6.759E-3	1.771E-3	

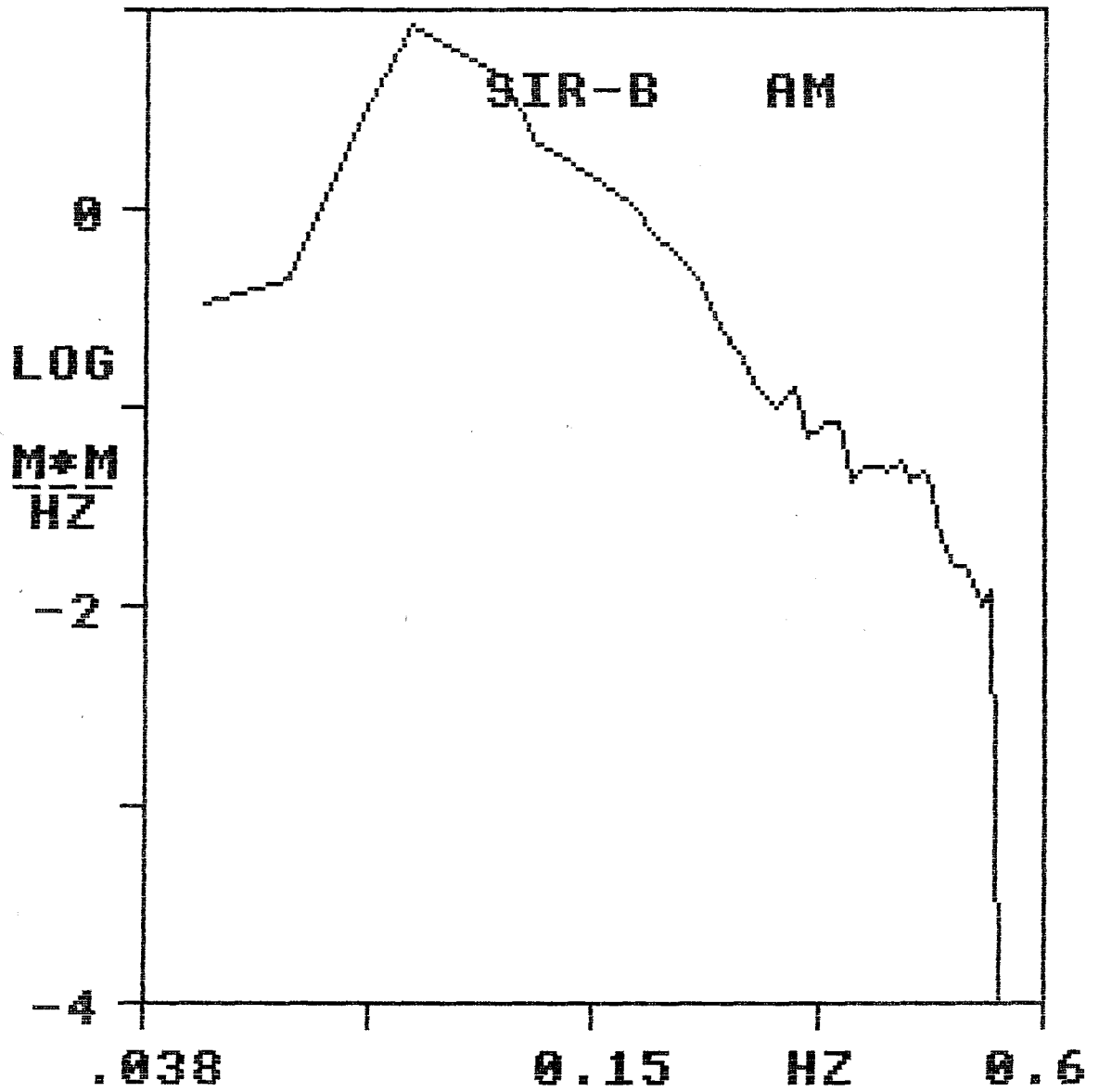
One Dimensional Wave Spectra, Angular Harmonics  
and Directional Parameters Figure 3.

F	E	A1	B1	A2	B2	R	TH1	TH12	TH2	S1	S2
0.04	0.30	0.27	0.07	-0.13	0.07	0.28	14.48	76.04	68.78	0.39	1.86
0.06	0.48	0.47	0.08	0.46	0.16	0.53	8.99	9.68	58.42	0.92	5.10
0.07	2.50	0.55	0.50	-0.10	0.54	0.80	42.26	50.05	41.48	2.82	6.20
0.09	9.70	0.89	0.08	0.68	0.12	0.93	4.89	5.03	26.45	8.39	10.38
0.10	6.12	0.83	0.22	0.49	0.29	0.88	14.75	15.15	30.57	6.02	6.63
0.11	5.21	0.90	0.16	0.71	0.21	1.03	9.81	8.12	23.84	10.55	12.97
0.13	2.19	0.86	0.16	0.58	0.25	0.92	10.75	11.64	28.38	7.15	8.40
0.14	1.43	0.79	0.09	0.39	0.06	0.92	6.76	4.35	36.88	3.83	3.95
0.15	1.39	0.82	0.06	0.47	0.03	0.92	3.86	1.87	33.97	4.69	4.92
0.17	1.10	0.83	0.04	0.54	-0.04	0.99	2.92	357.90	33.74	4.77	6.05
0.18	0.73	0.77	0.19	0.45	0.15	0.89	13.57	9.32	37.12	3.77	4.99
0.20	0.61	0.76	0.23	0.41	0.21	0.82	17.23	13.59	36.91	3.82	4.82
0.21	0.55	0.82	0.26	0.53	0.33	1.01	17.39	15.91	30.48	6.07	8.05
0.22	0.19	0.68	0.29	0.19	0.33	0.84	23.28	30.11	41.08	2.89	3.80
0.24	0.20	0.71	0.10	0.30	-0.02	0.90	7.81	357.99	43.19	2.52	3.05
0.25	0.14	0.64	0.23	0.19	0.12	0.91	20.00	16.24	45.69	2.14	2.37
0.26	0.10	0.63	0.19	0.18	0.02	0.81	16.80	2.95	47.15	1.95	2.12
0.28	0.14	0.70	0.16	0.32	0.25	0.85	12.94	18.92	43.10	2.53	4.04
0.29	0.08	0.68	0.04	0.35	-0.03	0.91	3.75	357.50	45.86	2.12	3.46
0.30	0.08	0.76	0.14	0.52	0.18	0.82	10.17	9.46	38.33	3.47	6.37
0.32	0.07	0.61	0.11	0.20	0.24	0.92	10.29	24.55	50.11	1.61	3.10
0.33	0.04	0.46	-0.08	-0.06	0.21	0.68	350.54	53.14	59.22	0.87	2.35
0.35	0.05	0.39	-0.26	-0.18	0.07	0.76	326.66	79.30	59.21	0.87	2.16
0.36	0.06	0.29	-0.21	-0.12	0.18	1.07	324.45	62.30	64.85	0.56	2.35
0.37	0.05	0.14	-0.27	-0.04	0.29	0.84	297.54	48.61	67.32	0.45	2.95
0.39	0.05	-0.06	-0.51	-0.42	0.31	0.88	263.04	71.71	56.56	1.05	5.81
0.40	0.05	0.08	-0.72	-0.63	-0.03	0.90	276.41	271.54	42.53	2.63	8.37
0.41	0.05	0.00	-0.47	-0.31	0.22	1.10	270.57	72.34	58.77	0.90	3.83
0.43	0.04	-0.09	-0.59	-0.25	0.21	0.90	260.88	70.06	51.53	1.47	3.28
0.44	0.02	-0.07	-0.40	-0.20	0.11	0.77	260.09	75.30	62.19	0.70	2.46
0.46	0.02	-0.30	-0.40	0.04	0.44	0.81	233.33	42.60	57.12	1.01	4.57
0.47	0.02	-0.04	-0.63	-0.32	0.12	0.87	266.42	79.54	49.48	1.68	3.34
0.48	0.01	-0.10	-0.55	-0.16	0.13	0.89	259.57	70.32	54.01	1.25	2.25
0.50	0.01	-0.13	-0.60	-0.44	-0.03	0.69	257.79	271.70	50.20	1.61	4.49
0.51	0.01	-0.27	-0.45	-0.05	0.26	1.08	238.81	50.40	55.54	1.13	2.68

Energy Spectra plotted on linear axes Figure 4.



Energy Spectra plotted on logarithmic axes Figure 5.





Plots of Mean Direction and Directional Spread Figure 6.

