

INTERNAL DOCUMENT

No. 286

IOS

DEACON LABORATORY

I.O.S.D.L. STAND ALONE PUMP (SAP)

A Deep Water In-Situ Filtration Pump
Serial No. SAP

by

N.J. Hooker
and L.H. Wright

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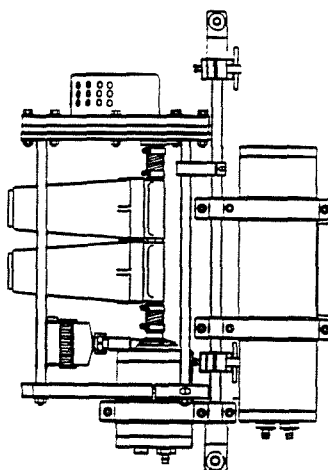
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HANDBOOK
MARCH 1989

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SPECIFICATION: IOSDL STAND ALONE PUMP SYSTEM

Physical

| | |
|------------------------------|--|
| Major Components | : Pump/Motor case Control unit + battery case Filter stack Release bar assembly |
| Size | : 40 x 22 x 16 inches 1016 x 559 x 406 mm |
| Weight in air | : 110 lbs (50 kgs) |
| Weight in water | : 55 lbs (25 kgs) |
| Pump | : IOSDL design, centrifugal type magnetically coupled drive |
| Motor | : Permanent magnet type with disc armature 24 volt drive PML motor model G9M4 |
| Filter size/type | : 293 mm diameter disc. GFC, GFF, Nuclepore or cartridge. Pore size is dependent on scientific requirements and vary from 1 micron upwards |
| Flow meter | : Kent mechanical volume displacement type with digital readout Type k198/25b flow rate 31-3000 litres/hr Type k190/15b flow rate 20-2500 litres/hr |
| Control electronics | : IOSDL electronic design mounted on pcb |
| Depth capability | : 0 to 5500 metres |
| Pump control | : Variable delay start $\frac{1}{2}$ to 120 hrs, $\frac{1}{2}$ hr step Variable pumping time $\frac{1}{2}$ to 4 hrs, $\frac{1}{2}$ hr step |
| Pump rate | : 1300 litres/hr @ zero head at 16 volts |
| Power | : Batteries, Lead Acid paste, 2 x 8 off 2V 5AH |
| Deployment methods | : 1. By mooring 2. Suspended by wire 3. For surface waters (down to 40 metres), use conducting cable and shipboard power supply |
| Ancillary equipment required | : 1. Battery charger Constant voltage, constant current 0-30V, 0-10 Amps 2. Filter handling facilities |

SECTION 1 GENERAL INFORMATION

The STAND ALONE PUMP (SAP) is a device designed to pump large volume (1000 l+) sea-water samples through a series of filter configurations in order to collect suspended particulate material from the water column. The SAP consists of a motor/pump assembly which is powered by a 16 volt battery pack; control is achieved by an electronic timer which is adjustable to give a delay time followed by a run time. The volume of water sampled is dependent upon the filter configuration used and the concentration of suspended material in the sample, the maximum being 1200 l/hr. The flow is recorded using a mechanical flowmeter.

The pressure cases containing the pump/motor and the battery and electronics are arranged around an IOS release bar assembly allowing the equipment to be used either as part of a mooring or suspended from a ship.

The SAP has a working depth capability of 5500 m.

SECTION 2 OPERATION PROCEDURE

2.1 Setting the Timer

The pump operation is controlled by an electronic timer circuit which is first switched ON (Power Switch SWT5, see Fig. (a)), the green LED will then start flashing. When set the timer runs through a cycle which consists of a pre-set delay time followed by a running time. During this later phase the power is applied to the motor and the pump activated. Both these time periods are variable and are set by means of switches SWT 3 and SWT 4 on the pcb (see Fig.(a)) and the sequence initiated by SWT 1. The Switches SWT 3 and SWT 4 have multi-coloured sliders used to select a defined time period, the definitions of which are listed below:

| SWT 3 DELAY TIME | | SWT 4 ON TIME | |
|------------------|------------------|---------------|------------------|
| brown | $\frac{1}{2}$ hr | brown | $\frac{1}{2}$ hr |
| red | 1 hr | red | 1 hr |
| orange | 2 hrs | orange | 2 hrs |
| yellow | 4 hrs | yellow | 4 hrs |
| green | 8 hrs | | |
| blue | 16 hrs | | |
| purple | 32 hrs | | |
| grey | 64 hrs | | |

These switches are made by operating a slider, in the direction away from the OFF mark. This selects the value shown and operating more than one slider will result in the individual time values being added together to give a total time.

Example:

To select a 5 hr delay time and a 2 hr run time the following would be selected.

| SWT 3 | | SWT 4 | |
|--------|-----|--------|-----|
| brown | off | brown | off |
| red | on | red | off |
| orange | off | orange | on |
| yellow | on | yellow | off |
| green | off | | |
| blue | off | | |
| purple | off | | |
| grey | off | | |

Note on selection restrictions:

The combinations possible from the SWT 3 delay time switch can be used in any permutation to give the required delay time in the range from $\frac{1}{2}$ hr to 127.5 hrs. However SWT 4 could be set to run for 7.5 hrs which is outside of the performance capability of the battery pack and the practical limitations of filter packing capacity so therefore RUNNING TIME SHOULD BE LIMITED TO 4 HRS.

Activation of Control Cycle

To activate the delay/on time sequence SWT 1 is depressed once, every time subsequently this is depressed it will reset the start time of the cycle.

Test Cycle Facility

On setting the required time values it is sensible to check the function of the circuit by running it through the test cycle. This is achieved by holding down SWT 2 (RED BUTTON) and then pressing SWT 1 once. This activates the circuit by using second time pulses instead of 1 hour pulses thus allowing the complete delay and run time to occur in a few seconds rather than hours. The run time is indicated by the RED LED being lit.

2.2 Pre-Deployment Procedure (See Typical Deployment Checklist)

(a) Ensure that the battery pack is in a charged condition, the off load voltage should be 17-17.4V, 75-100% of full capacity (see Section 4 for further details).

(b) Set SWT 3 and SWT 4 to give required times. Remember to note the settings.

(c) Test the timer circuit by running the test cycle described in Section 2.1, with the battery pack connected to the motor tube to ensure the correct operation of the motor on command from the timer. On completion of this test the timer is ready to be reset using SWT 1. Remember to record the sequence start time.

(d) Carefully install the battery pack and timer assembly into its pressure case, checking that the 'O' ring seal is in good condition and is smeared with Vaseline.

(e) Reconnect the lead between the battery pack and the motor tube.

THE S.A.P. IS NOW READY FOR DEPLOYMENT.

2.3 Deployment Techniques

The equipment is built around the IOS release bar assembly which allows the unit to be deployed in a number of ways.

(a) On the end of a wire, lowered from the ship then allowed to run through operation cycle.

(b) In-line as part of a string mooring, deployed, activated then released.

(c) For sampling the upper 20 m or less it is possible to deploy the unit on a load-bearing line with a trailing power lead connected to the DC power supply used for battery charging. The voltage is adjusted to allow for the voltage drop in the cable and is set to give an initial current of 4 amps. In order to prevent damage to the control electronics this voltage must NEVER EXCEED 30V. Visual monitoring of the current drop will give an indication when the filter is packed and sampling complete. In the surface waters, where material densities are greatest, the sample time can be often only a few minutes and this is a very efficient way of sampling.

SECTION 3 SYSTEM DESCRIPTION

3.1 Electronic Control

Description of Circuit Operation

(a) Pump Timer Electronics (PCB1)

Refer to drawings (SAP1, 3, 4, 5 & 6).

Supply for the circuit is from the same battery pack that is used to supply the pump motor. The supply is connected to the printed circuit board via a three way 0.2 inch pitch screw connector (CON1), 0 volt to pin 1, +ve voltage to pin 2 which should not exceed +20 volts. +ve voltage is then connected via the printed circuit board to the supply side of the relay contacts RLA1, the switched output of RLA1 is then routed back to pin 3 CON1 for connection to the pump motor. +ve voltage is also connected via Power Switch SWT5 to IC8 (78L05) for regulation to +5 volts. A smoothing capacitor (C1) is connected between +ve voltage at IC8's input and 0 volts, also a pair of smoothing capacitors (C2) and (C3) are connected between the regulated +5 volt output (IC8) and 0 volt. This regulated +5 volts is used to power the CMOS logic circuitry, the various control switches and the pump motor relay coil (RLA1).

First stage of the logic circuit consists of IC1 combined with a 32768 Hz quartz crystal oscillator, R1, R2, C4, C5 and C6. The oscillator frequency can be monitored at pin 9 IC1 and is set to the precise frequency by adjusting variable capacitor C4. IC1 then divides this frequency through 14 stages to generate a precision 2 Hz/0.5 sec square wave output (Q14) at pin 3 IC1. The reset input (RST) pin 12 IC1 is connected through a logic inverter (1/6th IC7) to the circuit's reset switch (SWT1), this resets the 14 internal divider stages of IC1 with the rest of the circuit. The 2 Hz/0.5 sec square wave output is used as the output of the first stage of the circuit and provides a precision timebase for the rest of the circuit.

Second stage of the logic circuit IC2, IC3 is used to divide the timebase still further to generate 0.5 hr pulses for normal mode operation of the timer circuit or during 'test' mode, test switch (SWT2) held down, allow the previous 0.5 sec pulses to pass through. These two timing pulse outputs are selected by loading binary data into the JAM inputs J1-J4 IC2 and J0-J7 IC3 as shown

below:-

| IC2 | J1 | J2 | J3 | J4 |
|------|----|----|----|--------|
| norm | 1 | 1 | 1 | 1 = 15 |
| test | 1 | 0 | 0 | 0 = 1 |

| IC3 | J0 | J1 | J2 | J3 | J4 | J5 | J6 | J7 |
|------|----|----|----|----|----|----|----|---------|
| norm | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 = 240 |
| test | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 = 1 |

The results are:-

1. Normal mode $0.5 \text{ sec} * 15 * 240 = 1800 \text{ sec}/0.5 \text{ hr}$ output
2. Test mode $0.5 \text{ sec} * 1 * 1 = 0.5 \text{ sec}$ output

This binary data is set up using the test switch (SWT 2), pull-up resistor (R3) and a logic inverter (1/6th IC7). The binary data is loaded into IC2 and IC3 when the reset switch (SWT1) is depressed or each IC reloads itself when its own carry out (C0) output goes low, this is done with a logical 'OR' arrangement on each IC's preset enable (PE) input. The 'OR' arrangement on IC1's (PE) input pin 1, uses a logical 'AND' gate (1/4 IC6) followed by a logic inverter (1/6th IC7) and on IC2 the (APE) input pin 9 uses diodes D1, D2 and resistor R4 to form a discrete logical 'OR' gate. The 0.5 hr or 0.5 sec output pulses from this stage are used as the timing intervals for the final stages. The green light emitting diode LED D5 is used to indicate which timing interval has been selected and is connected between output (Q1) pin 6 IC2 and 0 volts with a series resistor R7. During normal running mode 0.5 hr intervals, D5 flashes 0.5 sec ON, 0.5 sec OFF, for a cycle of 7.5 secs. During test mode it lights continuously.

The final stages of the logic circuit incorporate one 8 bit user presettable binary counter (IC4) for the 'DELAY TIME' and one 4 bit user presettable binary counter (IC5) for the 'ON TIME'. These two counters are user presettable by means of an 8 way DIL switch (SWT3) for 'DELAY TIME' selection and a 4 way DIL switch (SWT4) for 'ON TIME' selection together with 47k ohm resistor networks (RN1 and RN2). The DIL switches have each slider

connected through a 47k ohm resistor to 0 volts logic 0 in the 'OFF' position, which becomes connected to +5 volts logic 1 in the 'ON' position. These switches have labels on them indicating the time interval each slider represents, any combination of slider positions are allowed, the labelled values of each one in the 'ON' position are simply added together for each switch to obtain a suitable user defined time period for both the 'DELAY TIME' and 'ON TIME' counters.

Time periods available are in binary multiples of the pulse duration input to this stage i.e. in normal running mode 0.5 hr multiples in test mode 0.5 sec multiples. The required time periods are set up using the DIL switches to select the logic levels of the JAM inputs J0-J7 (IC4) 'DELAY TIME' and JAM inputs J0-J3 (IC5) 'ON TIME' and are loaded when reset switch SWT1 is depressed (see below):-

| | | | | | | | | |
|---------------|-----|----|----|----|----|----|----|-----|
| SWT3 No. | a | b | c | d | e | f | g | h |
| (IC4) input | J0 | J1 | J2 | J3 | J4 | J5 | J6 | J7 |
| binary value | 1 | 2 | 4 | 8 | 16 | 32 | 64 | 128 |
| time interval | 0.5 | 1 | 2 | 4 | 8 | 16 | 32 | 64 |

| | | | | |
|---------------|-----|----|----|----|
| SWT4 No. | a | b | c | d |
| (IC5) input | J0 | J1 | J2 | J3 |
| binary value | 1 | 2 | 4 | 8 |
| time interval | 0.5 | 1 | 2 | 4 |

The above time intervals are in either hours or seconds as previously mentioned.

The timing pulses entering this final stage of the logic circuit are gated through to the required counter IC as it is needed. On pressing the reset switch SWT1 the carry out (C0) output of each counter is forced to logic 1 and both counters are loaded with a binary count corresponding to the logic levels at their JAM inputs, as selected on the DIL switches. When the reset switch is released both counters are ready to count down to zero when they receive rising edges from the timing pulses at the CLK inputs. When zero is reached in each

counter its carry out (CO) output is set to logic 0 indicating that the appropriate time duration for that counter has been completed.

The timing pulses are gated through to IC4 'DELAY TIME' counter first by ANDing them (1/4 IC6) with its own logic 1 carry out (CO) output. When the 'DELAY TIME' interval is complete (CO) goes low and IC4 will see no more CLK pulses and (CO) will be frozen low.

During the 'DELAY TIME', IC5 'ON TIME' counter will see no timing pulses. (CO) IC4 is inverted (1/6 IC7) then ANDed with (CO) IC5, this produces a logic 0 during 'DELAY TIME' but goes high when delay time is complete, this result is used as the 'PUMP MOTOR ON' signal and ANDed (1/4 IC6) with inverted timing pulses, the result of which is inverted again to provide the CLK input for IC5 'ON TIME' counter, the (CO) output IC5 remains high until the counter has completed the 'ON TIME' timing interval. (CO) IC5 then goes low which causes the 'PUMP MOTOR ON' signal to go low this completes the timing sequence and no further counting is done.

Output from the logic circuit is the 'PUMP MOTOR ON' signal which is applied to the gate of FET1. When the signal is logic 1 FET1 turns on and allows +5 volts to be applied across the relay coil (RLA/1), it also allows +5 volts to be applied across series pair resistor R6 and red light emitting diode LED D4. D4 is lit and indicates that the 'PUMP MOTOR ON' signal is present. Relay contacts close and allow +ve supply volts to be present at pin 3 on (CON1).

(b) Motor Control Circuit (PCB2)(refer to Tube Connections Diagram (SAP3))

The motor control circuit is mounted within the motor pressure case and is used to slowly increase the current flowing through the pump motor, bringing it up to full speed slow enough to prevent the magnetic drive from breaking as the filter pump comes on load. The acceleration time will vary with the load on the pump.

The circuit consists of a ramp voltage applied to the gate of a high power field effect transistor (FET2) whose Drain to Source resistance decreases as

the ramp voltage at its gate increases, allowing increasing current to flow through the motor, controlling the motor's acceleration until full load speed is reached. The ramp voltage is generated when the timer electronics close the contacts of (RLA/1), allowing the +ve volts from the battery pack to be switched to the +ve supply rail of the motor control circuit. When the +ve voltage is switched to the circuit, current is allowed to flow through diode (D6) and resistor (R8) to charge up capacitor (C7), this rising capacitor voltage is the ramp voltage that is applied to the gate of FET2.

3.2 Motor/Pump

The pump is a centrifugal type, driven via a magnetic coupling by a disc armature printed motor. The drive voltage is 16 volts and the maximum current drawn is 4 amps, this being at full flow. The advantages of using the magnetic coupling are that it eliminates the need for a driving shaft passing through the end-cap, which would require a power-consuming lip-seal, and thus reduces the number of batteries carried. In order for the limited amount of torque available from such a coupling to be fully utilised the frictional resistance of the moving parts such as the bearings must be low and this is achieved by using a ceramic shaft and bush supporting the impellor with a ceramic thrust washer taking the axial loading due to the magnetic forces. The impellor is restricted from excess axial movement by a tungsten-carbide pivot on its upper face which runs in a cup bearing of the same material. This configuration gives acceptable frictional resistance and low wear characteristics due to the ceramic components. Another condition of magnetic-couplings is that they have maximum rotational speed they can tolerate before decoupling. This effect is most noticeable when the impellor accelerates from rest to full speed when being switched on, and in order to lessen this snatching torque a slow-start voltage ramp circuit is employed to allow the power to be applied gradually over a few seconds.

Note: AVOID RUNNING PUMP DRY.

3.3 Filter Configuration

The material to be extracted from the water sample is collected by means of filter elements through which the sea-water passes. There are two configurations currently in use:

(a) A flat disc filter of 293 mm dia. which is supported on a flat plate within the FILTER HOUSING. This can be either a glass-fibre matt type (GFF or GFC) which has an average pore size dependent on its construction or a polycarbonate film (NUCLEPORE) whose pore size can be more accurately controlled.

The filter housing consists of a series of polypropylene plates which are arranged in such a way that a filter is sandwiched between the top plate and the filter-support plate which includes a perforated spiral feature to allow the water to percolate evenly across the filters's entire surface. The extreme edge of the filter has an O-ring and square section rubber seal to ensure that the water flows only through the TOP HAT into the filter and not via the edges. The entire assembly is constructed of plastic, including nuts and bolts, in an attempt to avoid sample contamination.

(b) A cylindrical cartridge filter which is held in a FLOWTECH CARTRIDGE HOLDER (type 1M), two of which are connected in series and placed between the output side of the filter housing and the input side of the pump.

Both types of filter are typically of 1 micron pore size although this is dependent on the experiment and could be changed to users' requirements.

3.4 Flow Recording

The volume of water sampled by the device is recorded on a mechanical flowmeter, the position of which is dependent on the configuration of filters in use. When using the two in-line Flowtech cartridge filters a KENT KSM type no. K134-15B is connected to the output side of the pump. When the cartridge filters are not required then a K198-25B flowmeter can be connected on the INPUT side in their place, this enforces less of a flow restriction than the smaller meter.

3.5 Flow Performance

When assessing the flow performance of the pump it is important to distinguish between tank test conditions where the voltages can be maintained by using C.V. power supplies, and actual environmental working conditions where the performance is influenced by the following factors:

- (a) the filter configuration being used and the type of filter material,
- (b) the concentration of suspended material in the water being filtered,
- (c) the voltages powering the pump.

Fig. b shows the initial flow rates of the pump, first at a free flow condition and then with various filter materials and configurations. These values represent the initial flows as indicated by tank trials in fresh-water as opposed to the conditions prevalent in the ocean.

During sampling the filter will collect the particulate material as the water is drawn through it, and in doing so the flow rate will decrease as the individual pores of the filter become clogged. This happens much faster in surface waters where particle distributions are higher than in clearer mid-water depths. Once the filter has been packed to capacity there will be no more volume sampled and if the pump runs for any length of time after this then it is simply wasted time and battery capacity.

The most effective way to gauge the maximum filtering times for a particular water-column is to take a series of filters at the same depth, each one of an increased duration until the extended running time no longer results in increased volumes sampled. Following this approach will quickly build up

experience and enable the user to pre-assess required running times without wasting sampling time.

Added to this variable flow decrease is the effect of the voltage decreasing as the battery power is consumed and the result is that the flow performance declines in the form of a downward curve. The exact form of this curve is difficult to define as each deployment might have differing contributory factors, however sea trials on pumps coupled to a flow sensor, allowing real-time measurement of flow, have shown flow against time for typical filter configurations and commonly used filter materials in a mid-water situation.

IOS experience has shown that the longest practical run time required when using 1 micron filter elements in mid-water is THREE HOURS. Although the battery is capable of running for four hours it is more likely that filter saturation will have occurred by then and the volume pumped in the later stages would be minimal. As mentioned above, sampling in the surface waters or close to the sea-bed where resuspended sediments occur would result in these run times being reduced, in the worst case to a half hour.

SECTION 4 AUXILIARY EQUIPMENT

4.1 Battery Charger Requirement

The following charging conditions must be followed to ensure long life of the battery pack (BP1).

To enable full charge voltage to be repeatably achieved, DO NOT let the 'on load' battery pack voltage fall below 12.5 volts, this voltage is reached when 95% of the battery's capacity has been utilised.

To prevent permanent damage to the cells, DO NOT let the 'on load' battery pack voltage fall below 7 volts, below this voltage and damage to the battery pack cells will occur, 100% recharge will not be possible and battery pack capacity will be significantly reduced.

After a heavy discharge cycle, recharge the battery pack as soon as possible or 100% recharge may not be achieved.

Charging Conditions (see Battery Pack Characteristics)

There is no limit on the charging current imposed by the characteristic of the lead acid cell but the charging diodes D9 and D10 in the charging lead supplied, are limited to 6 amps, so DO NOT exceed 6 amps charging current.

Recommendations for a battery charger are:-

Heavy duty power supply with current and voltage limit controls so the maximum current output and maximum voltage output can be set when charging.

Method of charging:-

Carefully disconnect the 18" lead between the battery pack and the motor tube.

The battery pack assembly with the electronic timer circuit must be removed from the 20 inch pressure case, use the 6 inch C-spanner (supplied).

Once removed the assembly should be placed in the wooden charging rack (supplied) in close proximity to the charging supply.

DO NOT attempt to charge the battery pack while in the sealed pressure case.

1. Set the voltage limit control of the charging supply to 20 volts. DO NOT exceed 20 volts.
2. Set the current limit control on the charging supply to 0 amps.
3. Connect the charging lead (supplied) to the charger supply terminals, then plug the 4-way connector end of the lead to the 4-way bulkhead connector socket on the battery assembly end-cap. Now turn the current limit control up to about 4 amps. DO NOT exceed 6 amps.

The charging voltage will drop at first but as the cells charge up the voltage will increase back to 20 volts. After 1 hour of recharging the battery pack terminal voltage should be near to 16.65 volts.

When the charging current is down to 0.5 amp and the voltage up to 20 volts the battery pack should be fully charged, so the charger can be switched off and the charging lead disconnected.

ALLOW 3 OR 4 HOURS FOR A COMPLETE CHARGE AFTER A HEAVY DISCHARGE CYCLE.

SECTION 5 MAINTENANCE

5.1 Pre-Cruise

Batteries

Check the condition of batteries, their ability to take and hold a charge and the physical condition of the cases etc.

Electronics

Switch circuit ON (Power Switch SWT5, see Fig. (a)) and run circuit through a few test cycles, varying the time periods to ensure correct operation.

O-Rings

The O-ring seals in the end-caps and in the vicinity of the pump assembly should be checked for deterioration and replaced if required. The O-rings should be lightly greased with Vaseline, as should the grooves.

Pump Assembly

The motor assembly should be inspected by unscrewing the bottom end-cap of the pump-motor tube and withdrawing the motor assembly. This will allow access to check that the wires are secured to the terminals on the motor and that all screws holding this assembly together are tightened.

Important Note: There should be no reason to disturb the driving magnet assembly as this is set to give the running clearance necessary to avoid contact with the magnetic window. Deviation from the 0.055 thou of inch setting will either result in loss of effective coupling if the gap is increased or physical contact between the rotating drive magnets and the stationary window if gap is insufficient. This clearance allows for the deflection the window undergoes when subjected to the high hydrostatic pressures experienced at depth.

General

Prior to deployment check to ensure all fixing nuts and bolts are secure.

5.2 Post-Cruise

General

After deployment in sea-water it is important that the unit be washed down with fresh-water to remove any salt.

End-Caps and O-Rings

All end-caps should be removed from their pressure cases and the O-rings and O-ring grooves cleaned before re-assembly, as should the O-ring seals in the pump assembly.

Pump Assembly

During the dismantling of the pump and window the condition of the tungsten-carbide bearing components can be inspected for wear and the pump chamber cleared of any debris which might have collected around the top-bearing spider.

Whilst the screws which locate the pump housing are removed, the corresponding threads in the end-cap should be cleaned and refilled with Vaseline to prevent any corrosive reaction between the aluminium end-cap and the stainless screws.

Great care should be taken when re-assembling these pump components, with particular attention to aligning the rotor concentrically, so that it is free to rotate without fouling the pump-housing.

Battery Pack

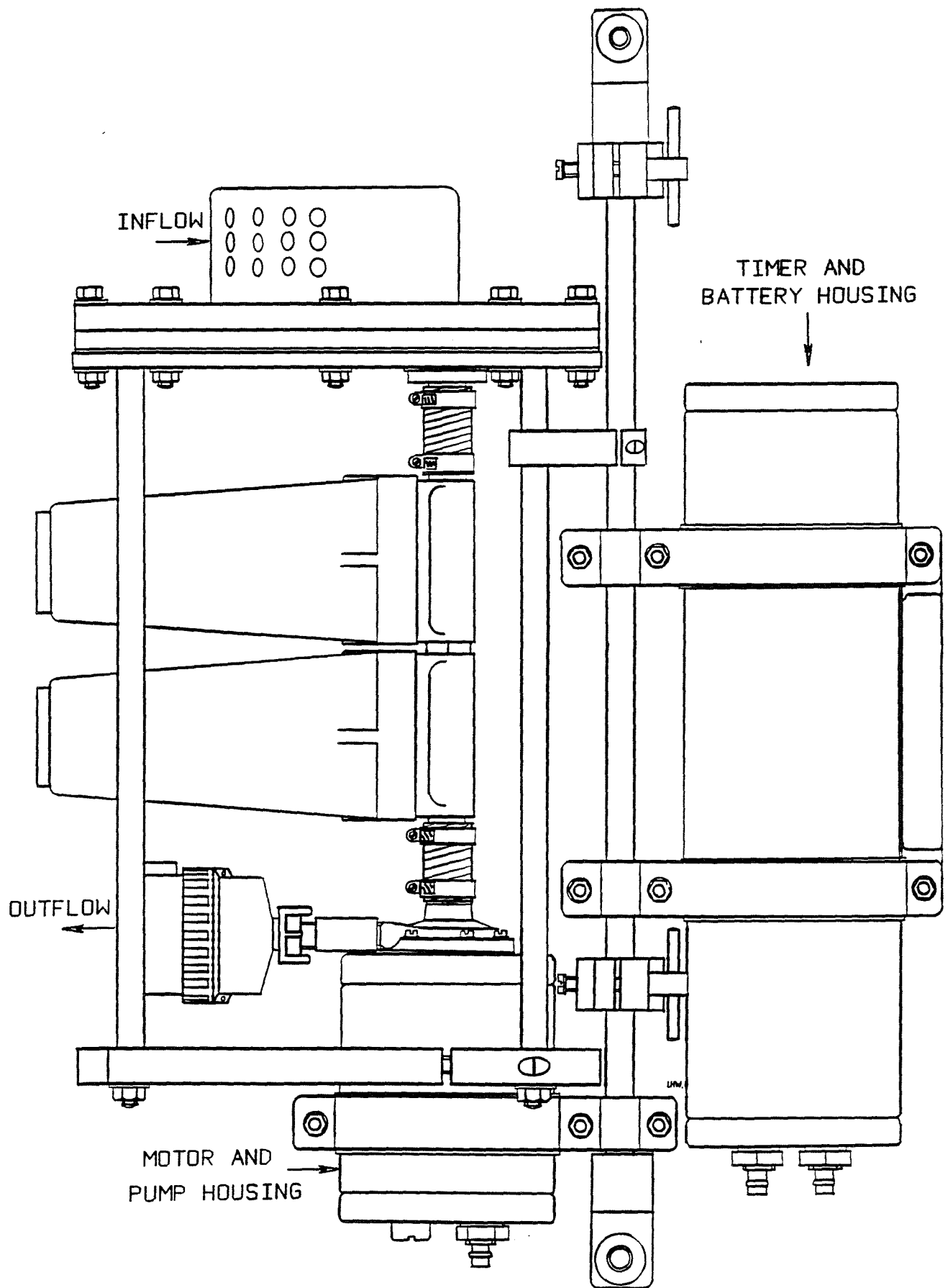
When work is completed it is important to recharge the pack to the capacity voltage in order to maximise the shelf life of the lead acid cells, periodic checking and recharging are also recommended.

Disabling the Electronics

Reset SWT 3 and SWT 4 so that all switches are in OFF position to avoid the possibility of accidental activation of circuit.

When decommissioning the SAP prior to a long period of inactivity (i.e. 2 months+), the electronics should be switched OFF (Power Switch SWT5, see Fig. (a)). For short intervals this is not required as providing the battery pack is fully charged then the power used by the active electronics, including the flashing green LED, is minimal.

Disconnect lead between battery pack and pump, clean both connector and lead.

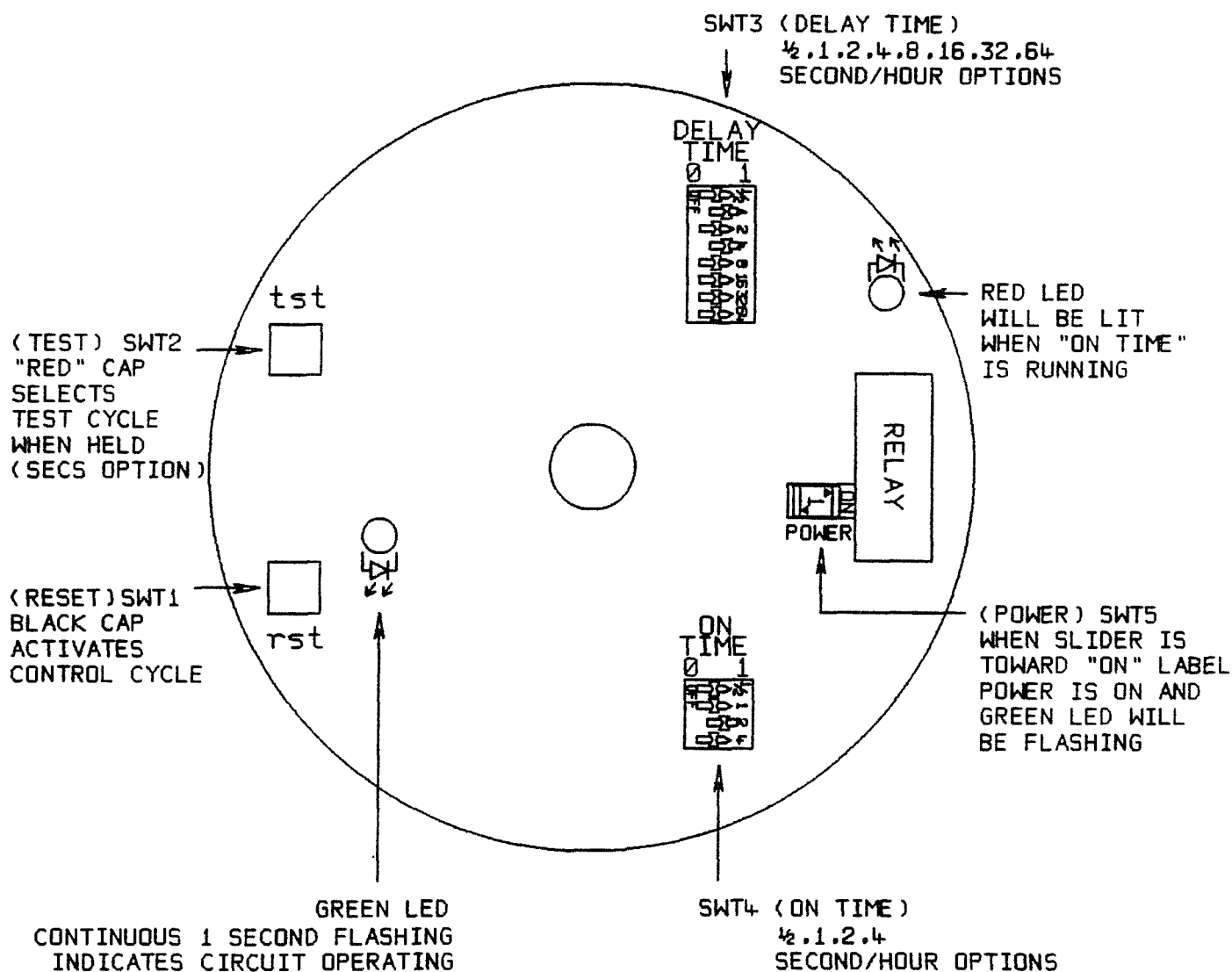


FULL ASSEMBLY DRAWING
STAND ALONE PUMP

DRAWING No I05DL/ SAP9
DRAWN BY LHW
DATE 17/3/88

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OPERATION LAYOUT
STAND ALONE PUMP TIMER ELECTRONICS

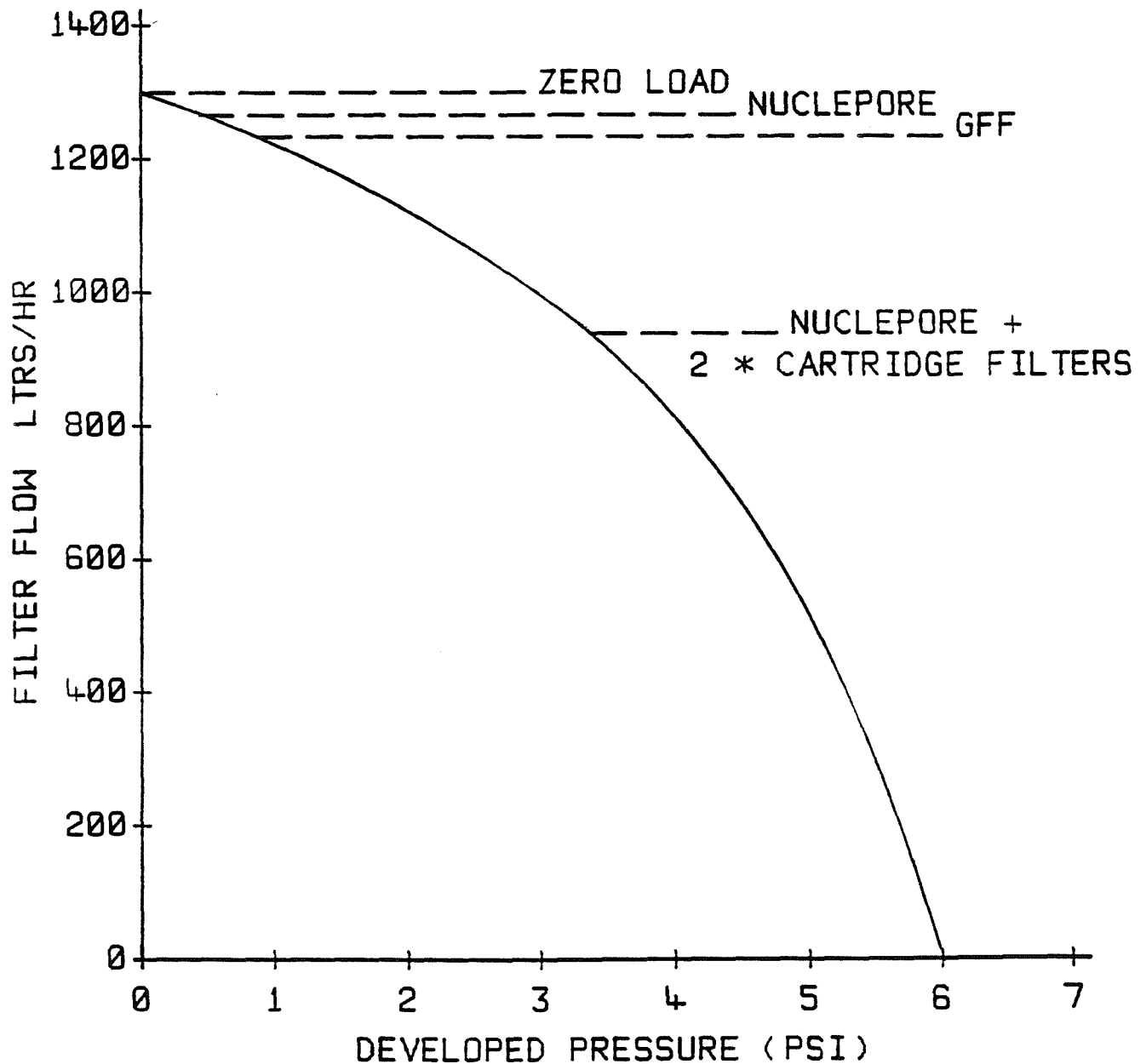
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(fig b)

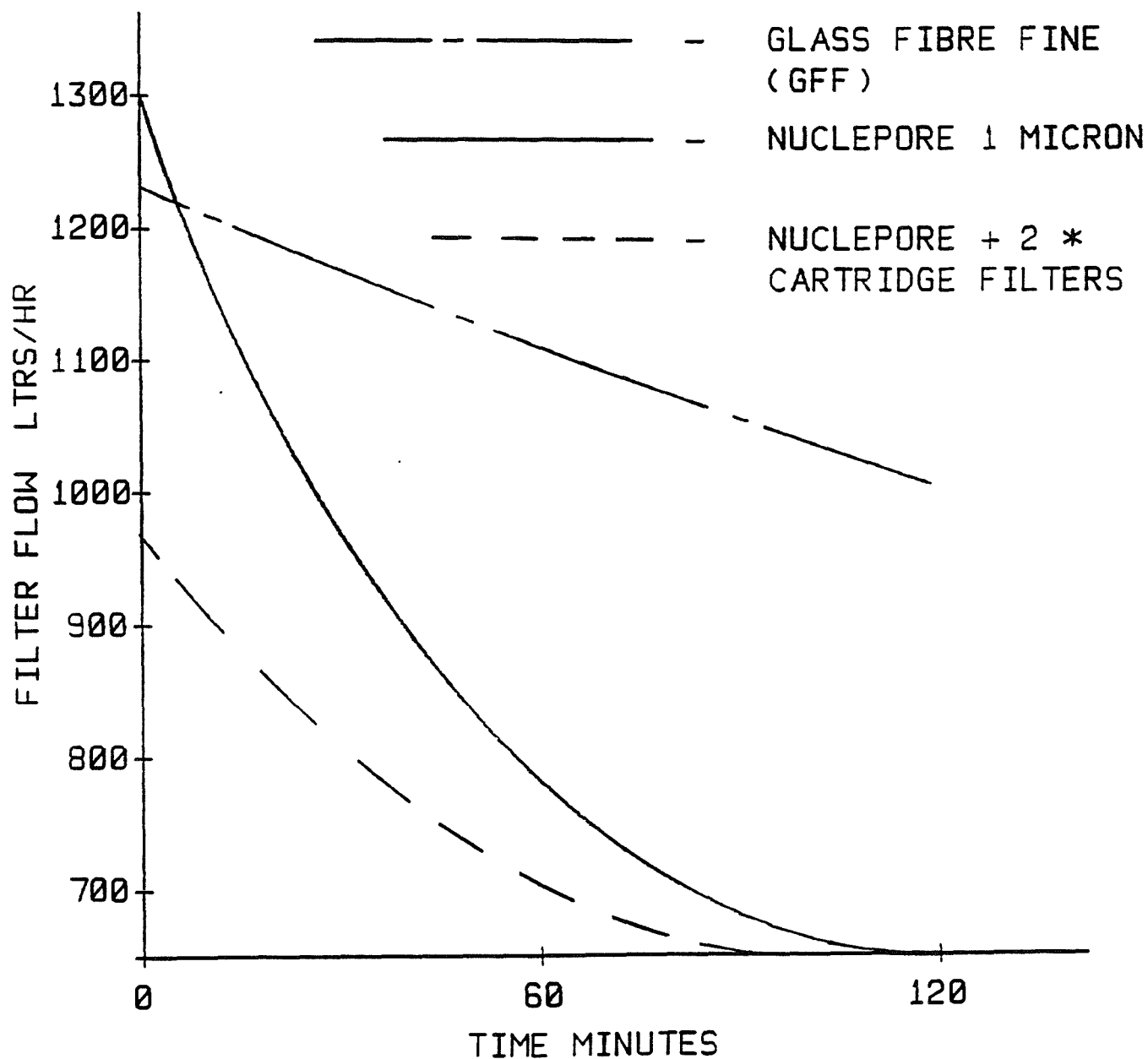
INITIAL PUMP FLOWS AGAINST DEVELOPED PRESSURES
AT CONSTANT 16 VOLTS



| | | |
|--------------------------------|--|----------|
| FLOW GRAPH STAND ALONE PUMP | DRAWING No IOSDL/ SAP7 DRAWN BY NJH DATE 24/1/89 | SHEET No |
|--------------------------------|--|----------|

INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY

FILTER CONFIGURATION FLOW CHARACTERISTICS
MID-WATER COLUMN CONDITIONS

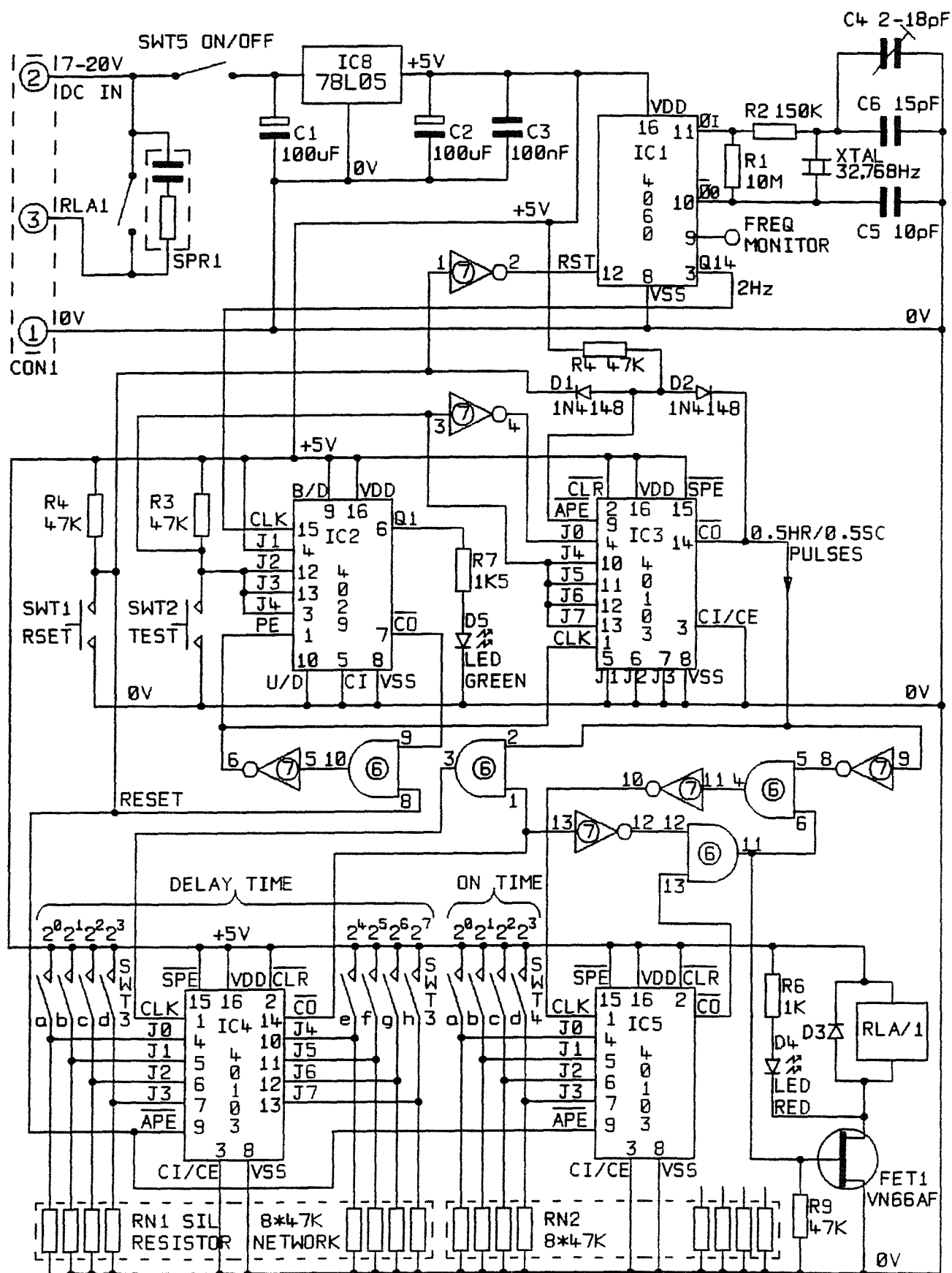


FLOW AGAINST TIME
STAND ALONE PUMP

DRAWING No IOSDL/ SAP8
DRAWN BY NJH
DATE 21/2/89

SHEET No

INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY



IC6 4081 4*AND

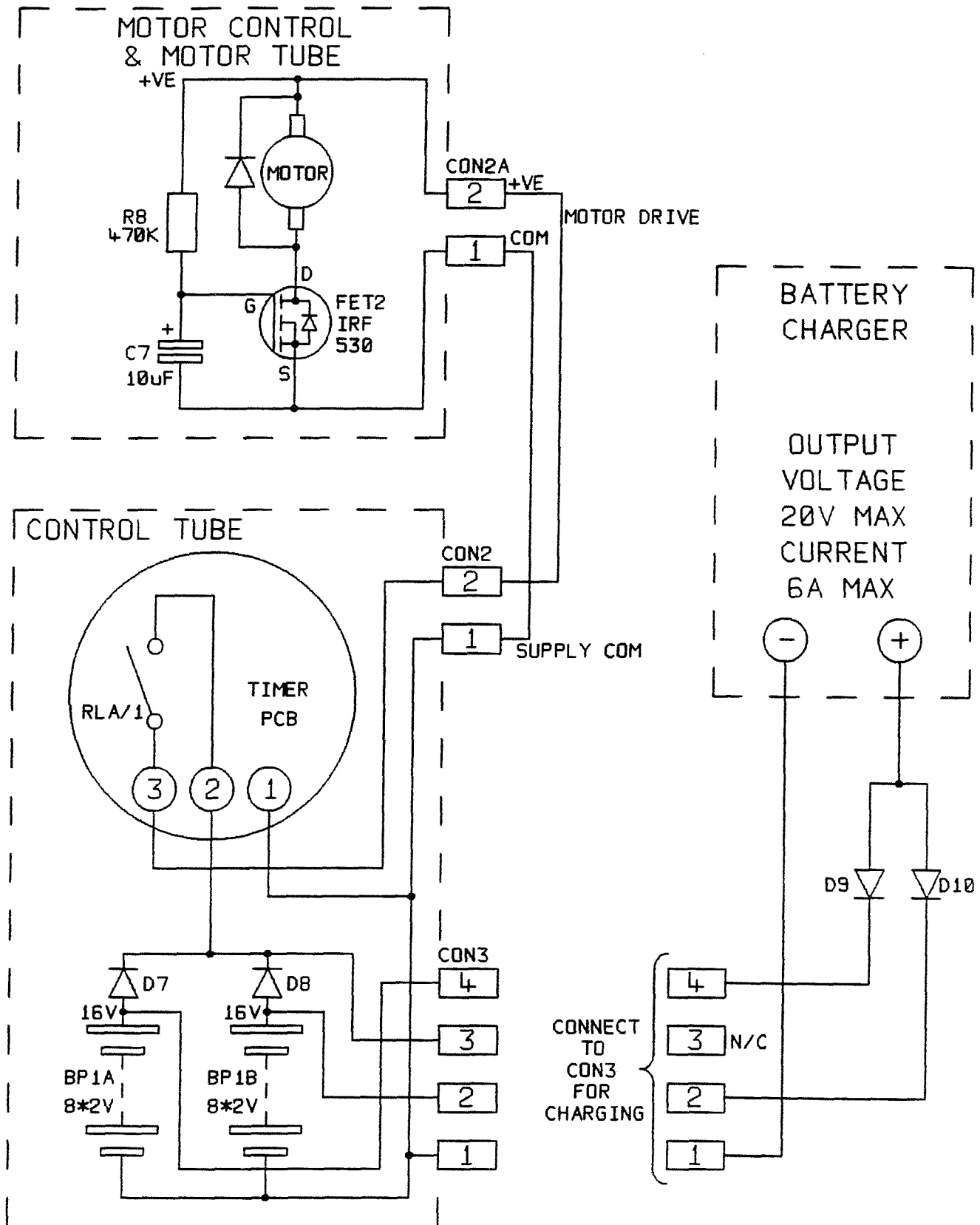
IC7 40106 6*INV

CIRCUIT DIAGRAM
STAND ALONE PUMP TIMER ELECTRONICS

DRAWING No IOSDL/ SAP1
DRAWN BY NJH
DATE 1/12/88

SHEET No

INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY



TUBE CONNECTIONS
STAND ALONE PUMP TIMER ELECTRONICS

DRAWING No IQSDL/ SAP3
DRAWN BY NJH
DATE 6/12/88

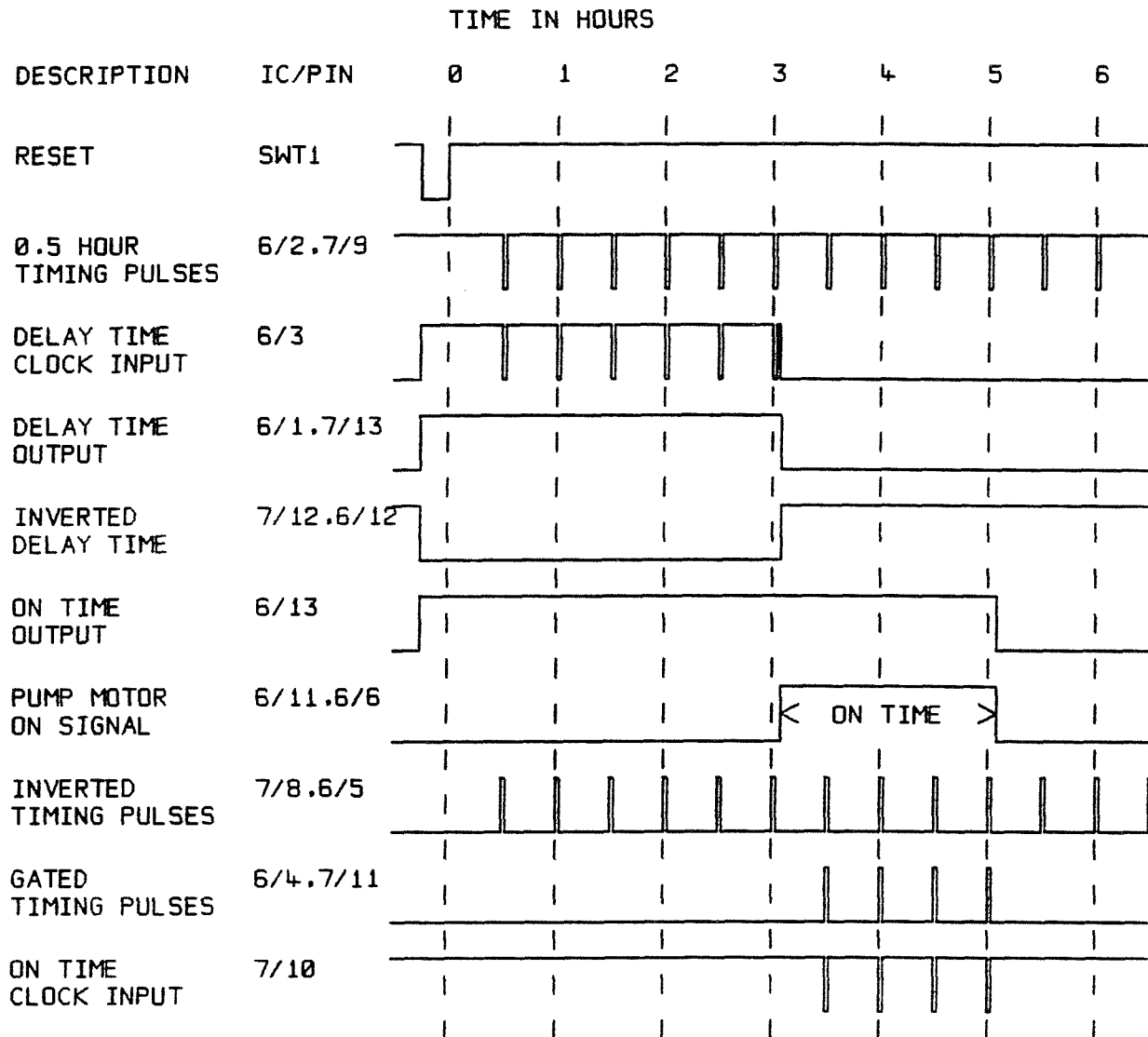
SHEET No

INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY



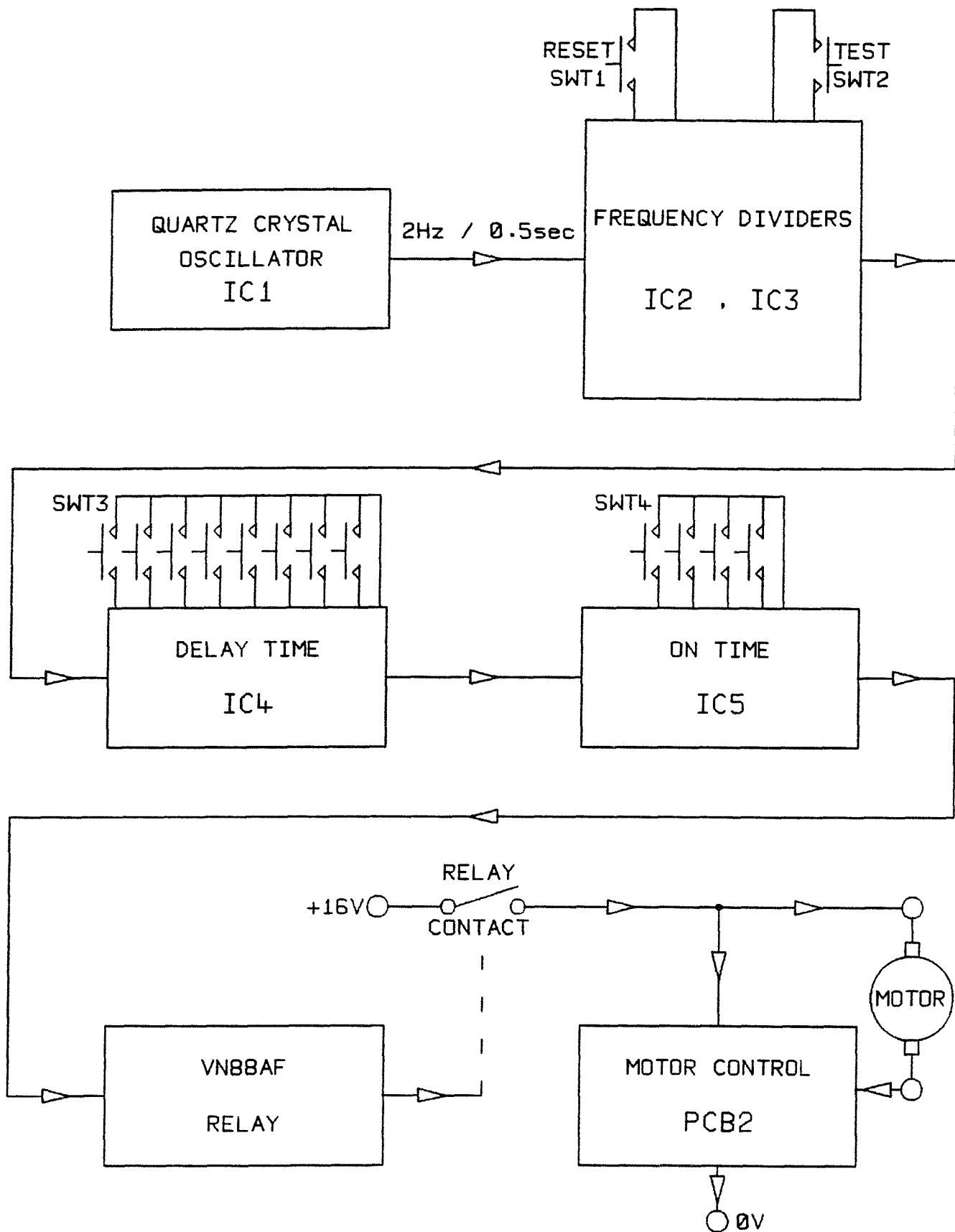
| | | | |
|---|------------|-------------|----------|
| PRINTED CIRCUIT COMPONENT LAYOUTS | DRAWING No | IOSDL/ SAP4 | SHEET No |
| STAND ALONE PUMP TIMER ELECTRONICS | DRAWN BY | NJH | |
| | DATE | 21/2/88 | |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY | | | |

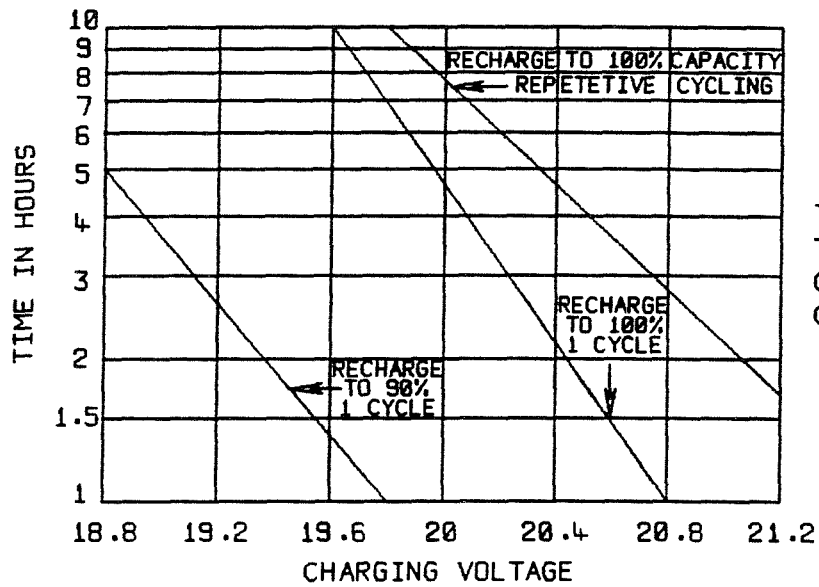
PRINCIPLE WAVEFORMS OF THE PUMP TIMER ELECTRONICS



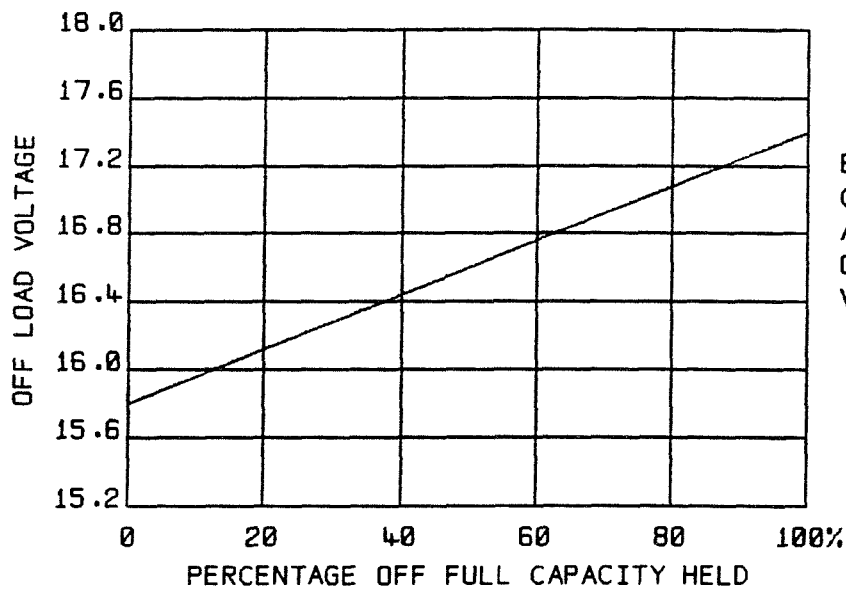
The example timing sequence above shows a 3 hour delay time followed by a 2 hour on time.

| | | |
|---|--|----------|
| TIMING DIAGRAM STAND ALONE PUMP TIMER ELECTRONICS | DRAWING No I0SDL/ SAP5 DRAWN BY NJH DATE 7/12/88 | SHEET No |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY | | |

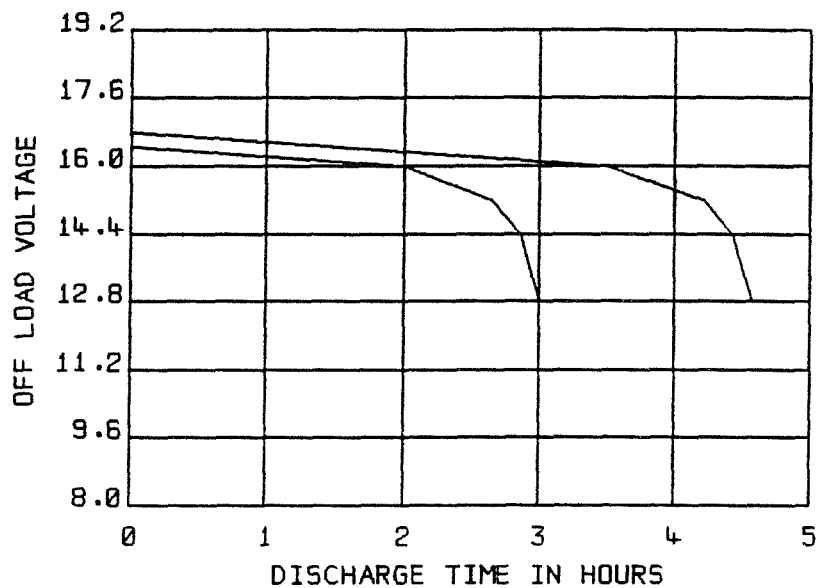




TYPICAL CHARGE TIMES USING CONSTANT VOLTAGE CHARGING UNIT



BATTERY PACK CAPACITY AGAINST OFF LOAD VOLTAGE



TYPICAL DISCHARGE CURVES

BATTERY PACK CHARACTERISTICS
STAND ALONE PUMP

DRAWING No IOSDL/ SAP10
DRAWN BY NJH
DATE 20/3/88

SHEET No

INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY

STAND ALONE PUMP DEPLOYMENT CHECKLIST

SHIP'S NAME:

CRUISE NO.:

DEPLOYMENT NO.:

DATE:

DAY NO.:

SHIP'S POSITION LAT. :

LONG.:

WATER DEPTH:

PUMPING DEPTH:

FILTER SIZE/TYPE:

FILTER LOADED Y/N:

CARTRIDGE LOADED Y/N:

FLOW SENSOR READINGS

PRE DEPLOYMENT:

POST DEPLOYMENT:

WATER PUMPED:

LITRES

TIMER SETTINGS

DELAY TIME:

HRS

ON TIME:

HRS

SEQUENCE START TIME:

HRS

MIN

SEC

TIME IN WATER:

HRS

MIN

SEC

TIME OUT OF WATER:

HRS

MIN

SEC

| CIRCUIT DIAGRAM SYMBOL | ELECTRONICS COMPONENT DESCRIPTION | | | | IDENTIFICATION | | ALTERNATIVES & REMARKS | | | | |
|--|-----------------------------------|--------|-------|---------------------------------------|--------------------------------------|---|------------------------|---------------|--|------------------|------|
| | NAME | RATING | GRADE | TYPE | TRADE OR SUPPLIERS NAME | REFERENCE No. | | | | | |
| R1 | Resistor | 10M | 5% | Metal Film 1/8 Watt | Farnell Electronic Components Ltd | VR2510M | Each | £0.053 | | | |
| R2 | " | 150K | 1% | " " " " | R.S. Components Ltd | 149-026 | Pack of 10 | £0.26 | | | |
| R3-5 | " | 47K | " | " " " " | " " " | 148-893 | " " " | £0.26 | | | |
| R6,7 | " | 2K | " | " " " " | " " " | 148-578 | " " " | £0.26 | | | |
| R8 | " | 470K | " | " " " " | " " " | 149-149 | " " " | £0.26 | | | |
| R9 | " | 47K | " | " " " " | " " " | 148-893 | " " " | £0.26 | | | |
| RN1-2 | Resistor Network | 47K | 2% | SIL 8-Commoned Thick Film 1/8 Watt | " " " | 140-990 | Each | £0.18 | | | |
| C1 | Capacitor | 100µF | 35V | Electrolytic | FEC | 100-829 | " | £0.124 | | | |
| C2 | " | " | 25V | " | " | 100-821 | " | £0.143 | | | |
| C3 | " | 0.1µF | 100V | Ceramic Epoxy Case | R.S. | 125-733 | Pack of 5 | £2.47 | | | |
| C4 | " | 3-16pF | 200V | Miniature Variable Ceramic | FEC | 148-158 | Each | £0.33 | | | |
| C5 | " | 10pF | | Polystyrene 160V | " | 105-054 | " | £0.084 | | | |
| C6 | " | 15pF | | " " | " | 105-055 | " | £0.084 | | | |
| C7 | " | 10µF | 35V | Tantalum | FEC | 100-906 | " | £0.29 | | | |
| D1-3 | Diode | | | IN4148 | " | IN4148-NSC | " | £0.025 | | | |
| D4 | LED Diode | Red | | Standard | R.S. | 586-475 | Pack of 5 | £0.90 | | | |
| D5 | " " | Green | | " | " | 586-481 | " " " | £0.90 | | | |
| D6 | Diode | | | IN4148 | FEC | IN4148-NSC | Each | £0.025 | | | |
| D7-10 | " | 8 Amp | | 80S0045 | " | 80S0045 | " | £1.59 | | | |
| IC1 | Integrated Circuit | CMOS | | 4060 | " | CD4060BCN | " | £0.41 | | | |
| IC2 | " | " | | 4029 | " | CD4029BCN | " | £0.43 | | | |
| IC3-5 | " | " | | 40103 | " | HCF40103BEY | " | £0.73 | | | |
| IC6 | " | " | | 4081 | " | CD4081BCN | " | £0.18 | | | |
| IC7 | " | " | | 40106 | " | CD40106BCN | " | £0.34 | | | |
| IC8 | " | 5V Reg | | 78L05 | " | LM78L05ACZ | " | £0.30 | | | |
| REMARKS | | ISSUE | DATE | REMARKS | | ISSUE | DATE | REMARKS | | ISSUE | DATE |
| Prices November 1988 | | | | | | | | | | | |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| CONTROL TIMER ELECTRONICS FOR STAND ALONE PUMP | | | | | | ELECTRONICS COMPONENTS FOR DRG. No. I.O.S. / MISC 8 | | | | | |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES | | | | | | COMPILED BY NJH | | DATE 18/11/88 | | SHEET No. 1 of 2 | |
| | | | | | | ISSUED | | FOR ORDER No. | | FOR UNITS | |

| CIRCUIT DIAGRAM SYMBOL | ELECTRONICS COMPONENT DESCRIPTION | | | | IDENTIFICATION | | ALTERNATIVES & REMARKS | | |
|--|-----------------------------------|------------------|--------------|--------------------------------------|--------------------------------------|---|------------------------|---------------|------------------|
| | NAME | RATING | GRADE | TYPE | TRADE OR SUPPLIERS NAME | REFERENCE No. | | | |
| XTAL | Crystal | 32768 Hz | | Quartz | Earnell Electronic Components Ltd | 103-868 | Each | £0.54 | |
| FET 1 | Field Effect Transistor | 1.3 Amp | N-Chan | Power Mosfet VN46AF | " | VN46AF | " | £0.74 | |
| FET 2 | " | 14 Amp | N-Chan | Power Mosfet IRE530 | " | IRE530-IR | " | £1.04 | |
| SWT 1 | Switch Red | 50mA | 24V | Keyboard Switch Pushbutton SPNO | " | 146-202 | " | £0.31 | |
| SWT 2 | Switch Drk Gry | " | " | " | " | 146-203 | " | £0.31 | |
| SWT 3 | Switches | 1 Amp | 50V | 8 DIL Single Throw | " | SDS8014 | " | £1.76 | |
| SWT 4 | " | " | " | 4 DIL " " | " | SDS4014 | " | £1.15 | |
| SWT 5 | Switch | " | 100V | DIL SPCO | " | SDC1014 | " | £0.78 | |
| RLA 1 | Relay | 10 Amp | | 6V 53Q Coil SPDT | R.S. Components Ltd | 347-848 | " | £2.09 | |
| SPR 1 | Suppressor | 0.1µF + | 100Q | Contact Suppressor | " | 238-463 | Pack of 5 | £5.44 | |
| CON 1 | Connector | 10 Amp | | 3 Way 0.2" Pitch | FEC | 147-713 | Each | £0.24 | |
| 1 x | DIL Socket | 8 Pin | | Turned Pin | " | 170-112 | " | £0.19 | |
| 2 x | " | 14 Pin | | " " | " | 170-113 | " | £0.34 | |
| 6 x | " | 16 Pin | | " " | " | 170-114 | " | £0.38 | |
| BP 1 | Battery Pack | 10AH 16V | Lead Acid | 16 x 5AH Cyclon Cells | " | 147-181 | " | £4.63 | |
| | Wire Black | 6 Amp | | Extra Flexible Silicone Insulated | " | 146-951 | 5 m Coil | £4.18 | |
| | Wire Red | " | | " | " | 146-952 | " " | £4.18 | |
| Lead 1 | Inter-Connection | Plug each end | 2 Pin | Brantner Double Ended | IOSDL Stores A19 | VMG-2-FS 18" | Each | £24.56 | |
| Lead 2 | Charging Lead | Plug one end | 4 Pin | " " " | " | VMG-4-FS 42" | " | £46.73 | |
| CON 2/2A | Connector | Bulkhead | 2 Pin | Brantner Socket | " | VSG-2-BCL | " | £31.54 | |
| CON 3 | " | " | 4 Pin | " " | " | VSG-4-BCL | " | £26.21 | |
| | Terminal Block | 15A | | 12 Way Surface Mounting | FEC | L1350NI | " | £2.83 | |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| REMARKS | | | | | ISSUE | DATE | REMARKS | ISSUE | DATE |
| Prices January 1989 | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| CONTROL TIMER ELECTRONICS FOR STAND ALONE PUMP | | | | | | ELECTRONICS COMPONENTS FOR DRG. No. I.O.S. / MISC 8 | | | |
| | | | | | | COMPILED BY NJH | | DATE 18/11/88 | SHEET No. 2 of 2 |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES | | | | | | ISSUED | | FOR ORDER No. | FOR UNITS |

| WORKSHOP DETAIL No. & DESCRIPTION | | | MATERIAL | No. OFF | | FINISH & REMARKS | | | | |
|--|------------------------------|--|------------------|----------|---|--------------------------------|---------------|-------|-------------|--|
| | | | | PER UNIT | TOTAL REQD. | | | | | |
| 1 | Motor Housing | | Al Alloy HID 48 | 1 | | Hard anodise ref. IOS Dwg 1945 | | | | |
| 2 | Window Support End-Cap | | Al Alloy HID 89 | 1 | | " " " " " " | | | | |
| 3 | Pivot | | Tungsten Carbide | 1 | | Mods to SP 3 | | | | |
| 4 | Pivot Support Cap | | St. St. | | | 316 S16 | | | | |
| 5 | Impellor | | PVC | 1 | | | | | | |
| 6 | Window | | Titanium | 1 | | | | | | |
| 7 | Upper Bearing Holder | | Nylon | 1 | | Mods to SP 4 | | | | |
| 8 | Spider | | PVC | 1 | | | | | | |
| 9 | Pump Housing Part No. 630006 | | Polyprop | 1 | | Mods to SP1 | | | | |
| 10 | Motor-Side Coupling | | Al Alloy HE 30 | 1 | | | | | | |
| 11 | | | | | | | | | | |
| 12 | | | | | | | | | | |
| 13 | Field Focus Ring | | Mild Steel | 1 | | | | | | |
| 14 | | | | | | | | | | |
| 15 | | | | | | | | | | |
| 16 | Motor Mods | | | 1 | | Mods to SP 2 | | | | |
| 17 | Motor Case End-Cap | | Al Alloy HID 89 | 1 | | IOS Dwg No. N10/5230 Det. 2 | | | | |
| 18 | Motor Support Ring | | Al Alloy HE 30 | 1 | | Natural Anodise | | | | |
| 19 | Bush | | Ceramic | 1 | | Mod to SP 19 | | | | |
| 20 | Shaft | | Ceramic | 1 | | Mod to SP 20 | | | | |
| 21 | Shaft Support Ring | | Polyprop | 1 | | | | | | |
| 22 | Slow Start PCB | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| REMARKS | | | ISSUE | DATE | REMARKS | | | ISSUE | DATE | |
| | | | | | | | | | | |
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| | | | | | | | | | | |
| STAND ALONE PUMP | | | | | MOTOR/PUMP ASSY. | | | | | |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES. DEACON LABORATORY | | | | | WORKSHOP DETAILS FOR DRG. No. I.O.S. / 5557 | | | | | |
| | | | | | COMPILED BY LHW | | DATE 2/12/88 | | SHEET No. 1 | |
| | | | | | ISSUED | | FOR ORDER No. | | FOR UNITS | |

| STANDARD PART No. & DESCRIPTION | | | | TRADE OR SUPPLIERS NAME & CATALOGUE REF. No. | | No. OFF | | FINISH & REMARKS | | |
|-------------------------------------|---------------------------------------|-------|------|---|--|---|----------------|---------------------------------|-------------|-------|
| | | | | | | PER UNIT | TOTAL REQD. | | | |
| 1 | Pump Housing (Body) C25 | | | Charles Austin Pumps Ltd | | 1 | | Mod to Detail 9 | | |
| 2 | Motor G9 M4 | | | Printed Motors Ltd., Bordon | | 1 | | Mod to Detail 16 | | |
| 3 | Pivot (for Rotor) No. 932108 | | | W.S. Ocean Systems, Haslemere | | 2 | | Aanderaa CM Spares Mod to Det 3 | | |
| 4 | Upper Rotor Bearing No. 971193 | | | " " " " | | 2 | | " " " Mod to Det 7 | | |
| 5 | Magnet (Driver) Ø 15 mm x 10 mm | | | Swift Levick, Supermagloy, S. Don | | 6 | | | | |
| 6 | Magnet (Driven) Ø 15 mm x 5 mm | | | " " " " " | | | | | | |
| 7 | Screw St. St., Skt Hd M4 x 0.7 x 12 | | | | | 4 | | | | |
| 8 | Screw St. St., CSK Hd M4 x 0.7 x 40 | | | | | 4 | | | | |
| 9 | Socket Screw, St. St. M6 x 1 x 6 | | | | | 6 | | | | |
| 10 | Screw St. St., Skt Hd M3 x 0.5 x 6 | | | | | | | | | |
| 11 | Screw St. St., Ch Hd M4 x 0.7 x 30 | | | | | 8 | | | | |
| 12 | Screw St. St., CSK Hd M1.6 x 0.35 x 6 | | | | | 3 | | | | |
| 13 | O Seal | | | 50251 | | 2 | | | | |
| 14 | Blanking Plug XSG | | | IOS Dwg 5243 Det. 11 | | 1 | | A19 Stores | | |
| 15 | O Seal | | | 50213 | | 2 | | | | |
| 16 | O Seal 69.5 mm x 75.5 mm x 3 mm | | | RM 0695-30 | | 1 | | | | |
| 17 | Connector | | | VSG 2 BCL | | 1 | | A19 Stores | | |
| 18 | D Washer Part No. 16225 | | | Toton Pumps Ltd., Southampton | | 1 | | Ceramic | | |
| 19 | Ceramic Bush | | | " " " " | | 1 | | Mod to Det. 19 | | |
| 20 | Ceramic Shaft Part No. 6244 | | | " " " " | | 1 | | Mod to Det. 20 | | |
| 21 | Washer Plain St. St. M4 | | | | | 8 | | | | |
| 22 | Washer Spring St. St. M4 | | | | | 12 | | | | |
| 23 | Washer Spring St. St. M3 | | | | | 1 | | | | |
| 24 | O Seal R42 75 | | | Charles Austin Pumps Ltd | | 1 | | | | |
| | | | | | | | | | | |
| REMARKS | | ISSUE | DATE | REMARKS | | DATE | ISSUE | REMARKS | ISSUE | DATE |
| | | | | | | | | | | |
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| | | | | | | | | | | |
| STAND ALONE PUMP | | | | | | MOTOR PUMP ASSY. | | | | |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES | | | | | | STANDARD PARTS FOR DRG. No. I.O.S./5557 | | | | |
| | | | | | | COMPILED BY LHW | | DATE 2/12/88 | SHEET No. 1 | |
| | | | | | | ISSUED | | FOR ORDER No. | FOR | UNITS |

[illegible]

[illegible]

| WORKSHOP DETAIL No. & DESCRIPTION | | | | MATERIAL | No. OFF | | FINISH & REMARKS | |
|--|--------------------------------------|--|--|----------------|----------|---|-----------------------------|---------------|
| | | | | | PER UNIT | TOTAL REQD. | | |
| 47 | Release Bar Assy. 36" Overall Length | | | Titanium | 1 | | IOS Dwg 5348 Sub Assy. D | |
| 48 | Half Clamp | | | " | 6 | | IOS Dwg 5348 Det. 19 | |
| 49 | Clamp Rubber | | | Rubber | 3 | | IOS Dwg 5156 Det. 41 | |
| 50 | Bolt | | | Titanium | 9 | | SPS 10 | |
| 51 | Nut | | | " | 9 | | SPS 13 | |
| 52 | Washer | | | " | 18 | | SPS 16 | |
| 53 | Lower Support Split-Clamp | | | Polyprop | 1 | | | |
| 54 | Top Support Split-Clamp | | | " | 1 | | | |
| 55 | Strut | | | Titanium | 4 | | | |
| 56 | Filter Housing Top Plate | | | Polyprop | 1 | | | |
| 57 | Filter Support Plate | | | " | 1 | | | |
| 58 | Filter Housing Base Plate | | | " | 1 | | | |
| 59 | Support Plate Seal | | | Rubber | 1 | | Shure 40/50 | |
| 60 | Base Plate Seal | | | " | 1 | | " " | |
| 61 | Top Hat | | | Polyprop | 1 | | | |
| 62 | Hose Connector | | | " | 1 | | | |
| 63 | Hose Connector Seal | | | Rubber | 1 | | Shure 40/50 | |
| 64 | Hose | | | PVC Hose | 2 | | See SP 71 | |
| 65 | Flow Meter Adaptor | | | Polyprop | 1 | | | |
| 66 | Flow Meter Connector | | | | 1 | | Mod to part of SP 67 | |
| 67 | Spacer | | | Polyprop | 3 | | | |
| 68 | Handle | | | " | 1 | | | |
| 69 | Wire Mount Split-Clamp | | | Titanium | 2 | | Used with 4 mm or 6 mm wire | |
| 70 | Clamp Bolt | | | St.St. 316 S16 | 2 | | IOS Dwg No. 5243 Det. 22 | |
| 71 | Tommy Bar | | | " " " " | 2 | | " " " " " 23 | |
| REMARKS | | | | ISSUE | DATE | REMARKS | ISSUE | DATE |
| | | | | | | | | |
| | | | | | | | | |
| | | | | | | | | |
| STAND ALONE PUMP | | | | | | FRAME AND FILTER HOUSING ASSY. | | |
| INSTITUTE OF OCEANOGRAPHIC SCIENCES. DEACON LABORATORY | | | | | | WORKSHOP DETAILS FOR DRG. No. I.O.S. / 5557 | | |
| | | | | | | COMPILED BY LHW | | DATE 2/12/88 |
| | | | | | | ISSUED | | FOR ORDER No. |
| | | | | | | FOR | | UNITS |

| STANDARD PART No. & DESCRIPTION | | TRADE OR SUPPLIERS NAME & CATALOGUE REF. No. | No. OF | | REMARKS |
|---------------------------------|---|---|----------|-------------|---------|
| | | | PER UNIT | TOTAL REQD. | |
| 51 | Screw Skt Hd St.St. M10 x 1.5 x 50 | | 2 | | |
| 52 | Helicoil Insert St.St. M10 x 2 1/2 | | 2 | | |
| 53 | Screw Skt Hd St.St. M6 x 1 x 50 | | 2 | | |
| 54 | Nut St.St. M6 x 1 | | 2 | | |
| 55 | Washer St.St. M6 Plain M6 | | 2 | | |
| 56 | Screw Ch Hd Nylon M10 x 1.5 x 25 | | 4 | | |
| 57 | Nut Washer Faced Nylon M12 | | 4 | | |
| 58 | Washer Nylon M12 | | 4 | | |
| 59 | Screw Ch Hd Nylon M8 x 1.25 x 25 | | 8 | | |
| 60 | Bolt Nylon M10 x 1.5 x 60 | | 8 | | |
| 61 | Nut Washer Faced Nylon M10 x 1.5 | | 8 | | |
| 62 | Washer Nylon M10 | | 8 | | |
| 63 | Screw Ch Hd Nylon M6 x 1 x 40 | | 6 | | |
| 64 | Nut Washer Faced Nylon M6 x 1 | | 6 | | |
| 65 | O Seal | OS 85 50-451 | 1 | | |
| 66 | Hose Clip St.St. Size 1 3/8 mm | | 4 | | |
| 67 | Flow Meter KSM K134-15B | Kent Flowmeters, Luton | 1 | | |
| 68 | Cartridge Filter Type 1M | Flowtech Ltd., Reading | 2 | | |
| 69 | 3/4 BSP Hex Nipple (UPVC) | BTU Supplies, Guildford | 1 | | |
| 70 | 3/4 BSP Plain to Threaded Barrel Nipple | " " " | 2 | | |
| 71 | Hose 1" ID Delivery Code 20 | Medway Hydraulics, Chatham | 2 | | |
| 72 | Screw St.St. Skt Hd M10 x 1.5 x 30 | | 4 | | |
| 73 | Screw St.St. Ch Hd M6 x 1 x 8 | | 2 | | |
| 74 | Washer St.St. M6 | | 2 | | |
| 75 | Circlip, St.St. External 5/16" | Anderton Part No. 1400-31 | 2 | | |

| REMARKS | ISSUE | DATE | REMARKS | DATE | ISSUE | REMARKS | ISSUE | DATE |
|---------|-------|------|---------|------|-------|---------|-------|------|
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|------------------|--|--------------------------------|--|---|---------------|------|-------------|
| STAND ALONE PUMP | | FRAME AND FILTER HOUSING ASSY. | | STANDARD PARTS FOR DRG. No. I.O.S. / 5557 | | | |
| | | | | COMPILED BY | LHW | DATE | SHEET No. 3 |
| | | | | ISSUED | FOR ORDER No. | FOR | UNITS |

U.D.O. 1175/00 (5/95)

