## NATIONAL INSTITUTE OF OCEANOGRAPHY

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THE RING MODULATOR AS
A DETECTOR OF CORRELATIONS

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### Appendix to N.I.O. Internal Report No. A 1

### "The Ring Modulator as a Detector or Correlations"

Discussion of the output noise levels when a low-pass filter is connected in the output

On re-reading this report the authors realise that the manner in which the performances of a true multiplier and of a ring modulator are compared may be misleading.

The noise levels used for the calculation of the comparative signal/noise ratios of a true multiplier and of a ring modulator (plotted in figure 6) are the <u>unsmoothed</u> noise levels: that is, with no filter whatsoever on the output of the circuit. It must not be assumed that the effect of a smoothing circuit connected in series with the output will reduce the noise by a similar proportion in both circuits. The authors have not been able to calculate the effect of smoothing the output of a ring modulator and this is why the comparison had to use the unsmoothed noise levels.

In the case of a true multiplier, if the mean square voltage contained in a bandwidth df at a frequency f is  $E_{\rm x}$  (f) df for the x signal Ey (f) df for the y signal, the mean square noise output voltage  $V_{\rm S}^2$  which is obtained when the output is passed through a low-pass filter with a narrow bandwidth Af 12 is given by

$$V_s^2 = \frac{1}{2} K^2 \triangle f_2$$
  $\int_0^\infty E_x(f) E_y(f) df$ 

where K is the multiplier constant.

 $\mathbf{E}_{\mathbf{x}}(\mathbf{f})$ ,  $\mathbf{E}_{\mathbf{y}}(\mathbf{f})$ , etc. will be called energy density functions.

This result is correct only if the bandwidths of  $\mathrm{E}_{\mathrm{x}}(\mathrm{f})$  and  $\mathrm{E}_{\mathrm{v}}(\mathrm{f})$  are much greater than  $\triangle$  f<sub>2</sub>, since it assumes that the energy density of the output fluctuations is constant within the pass band of the low pass filter.

If  $E_{\rm x}(f)$  and  $E_{\rm y}(f)$  are similar "square" frequency bands of width  $\triangle$  f<sub>1</sub>, the mean square voltage  $V_{\rm F}^2$  of the unsmoothed output voltage may be calculated by integrating the complete output energy spectrum. Combining this with the formula above gives:

$$V_S^2 / V_F^2 = \triangle f_2 / \triangle f_1$$

which is the result stated on page 3 of the report.

If the smoothing bandwidth  $\triangle f_2$  is comparable with the signal bandwidths, the output noise may be calculated from the following formula for the energy density of the unsmoothed output fluctuations at a frequency p  $\mathbb{E}_v(p) = (K^2/4) \int_0^\infty [\mathbb{E}_x(f)\mathbb{E}_y(f+p) + \mathbb{E}_x(f+p)\mathbb{E}_y(f)] df$ 

$$E_{\mathbf{v}}(\mathbf{p}) = (\kappa^2/4) \left( \sum_{\mathbf{p}} [E_{\mathbf{x}}(\mathbf{f}) E_{\mathbf{y}}(\mathbf{f} + \mathbf{p}) + E_{\mathbf{x}}(\mathbf{f} + \mathbf{p}) E_{\mathbf{y}}(\mathbf{f})] d\mathbf{f} \right)$$

This equation takes account only of difference frequencies, so that there is still a limitation that  $\bigwedge$   $f_2$  must be less than the sum of the lowest frequencies present in x and y.

These formulae are correct whatever the correlation between x and y.

The fluctuations are measured about the mean D.C. output due to the correlated component.

> M.J. Tucker J. Crease 7.6.55

### Distribution

The same as N.I.O. report A 1

## The Ring Modulator as a Detector of Correlations

### SUMMARY

The ring modulator has been used to detect correlations between two voltages. Its characteristics are an approximation to those of a true multiplier. In this paper its action is rigourously examined for inputs with Gaussian voltage distributions, that is, with voltages similar to that of random noise. It is shown that for small correlations the output "signal/noise" ratio is only 7% (0.6 db) down on that of a true multiplier over a certain range of working conditions, whilst for large correlations the signal/noise ratio is better in the ring modulator than the true multiplier.

#### Introduction

A ring modulator used symmetrically with input voltages of comparable magnitude (fig. 1) has been used to detect correlations between two radio signals received in a radio-telescope (ref. 1). The detection and measurement of correlations also has several important applications in Oceanographic research (ref. 2) and it is possible that the ring modulator might be useful for this purpose.

The ideal correlation detector is a device which multiplies the two inputs. If the multiplier has a characteristic equation v = kxy, then V = krxy. (All definitions of symbols are listed on one page at the end of the report). No electronic multipliers which are both satisfactory and simple have so far been developed and the ring modulator offers a simple alternative that is satisfactory in some applications. Simple multipliers have large zero fluctuations whilst the output of a ring modulator is very stable compared with the magnitude of the input voltages that it will handle. The output drift can be kept considerably below 0.1% of the peak voltages. In order that the ring modulator may be used in this way it is necessary to know how to determine the correlation coefficient of the inputs from the mean output and also to know whether the ratio of the output due to random correlations in the input is as good as that in a true multiplier. This ratio will be called the output signal to noise ratio.

The action of the modulator depends upon the statistical distribution of voltages in the inputs and it will be a ssumed that this is of "normal" or Gaussian form, which is one of the most common met with in practice.

### The Modulator Characteristics

The circuit is shown in its conventional form in fig. 1(a) and has been rearranged to make the analysis easier in fig. 1(b). The resistors in series with the rectifiers are necessary in the present application in order to make the modulator present a reasonably high impedance to the signal sources. It will be assumed that the rectifiers are perfect; that is, they act as switches which have zero resistance when a current is flowing through them in one direction, and an infinite resistance when there is a voltage across them in the reverse direction. It will also be assumed that the signal sources have zero internal impedance and that the output is connected to an infinite impedance.

There are eight possible states of conduction of the modulator but for convenience in subsequent calculation four of these have been split and twelve states are therefore shown in table 1.

It is interesting to compare the characteristics of the ring modulator with those of a true multiplier (fig. 2). It will be seen that the former may be regarded as a straight line approximation to the

latter. An important difference is the spacing of the intersections of the characteristics with the line x=y. In the true multiplier the distance from the origin increases according to a square law, whereas, in the modulator the characteristics are equally spaced. This means that the modulator approximates most nearly to a multiplier with a characteristic equation v=k xy/l. It will be seen later that this fact emerges from the analysis.

### The Detection of Correlations

Only an outline of the mathematics will be given in this section; certain calculations will be given in more detail in appendix 2. The analysis of the action of a true multiplier is not new, but is included for purposes of comparison. The results are presented in four stages in which the following are calculated.

- (a) The mean d.c. output from a true multiplier with partly correlated inputs.
- (b) The r.m.s. value of the fluctuations in the output voltage of a true multiplier with partly correlated inputs.
- (c) The mean d.c. output and r.m.s. value of the fluctuations in the output voltage of a ring modulator with partially correlated inputs.
- (d) Comparison of the signal to noise ratio of a ring modulator with that of a true multiplier.

For convenience in calculation it will be assumed that the voltage y is produced by adding a proportion c of the voltage x to another voltage z which is uncorrelated with x, that is, y = cx + z. This type of correlation is indistinguishable from correlations produced in any other way (appendix 1) and there is therefore no loss of generality in making this assumption.

The results obtained in this way will be in terms of c, X, Z but these may be expressed in terms of r, X, Y (X, Y can both be measured) for, by definition:

$$r = \frac{\overline{xy}}{xy} = \frac{\overline{x(cx+z)}}{xy} = \frac{cx}{y}$$
 (x and z being uncorrelated).

also 
$$y = \frac{cx + z}{2}$$
  
and  $y^2 = c^2x^2 + 2cxz + z^2$   
 $\therefore y^2 = c^2x^2 + z^2 = r^2y^2 + z^2$   
 $\therefore c = \frac{ry}{x}$   
 $z^2 = y^2(1 - r^2)$  (1)

(a) The mean d.c. output from a true multiplier

$$v = kxy$$

Therefore it follows from the definition of r that:

$$\overline{v} = k\overline{x}\overline{y} = krXY \neq krp$$
 (2)

(b) The fluctuations in the output of a true multiplier due to partially correlated inputs

In what follows the factor k will be assumed to be unity. As it is only a scale parameter it may be re-introduced as necessary at any stage.

The probability distribution P(v) dv is defined as the probability of the output being between v and v+dv. The range of x and z corresponding to this range of output is shown by the shaded strips S1, S2 in fig. 3. The strips are bounded by the hyperbolas v=(cx+z)x and v+dv=(cx+z)x. The joint probability of x, z falling in a small area dx dz is given by

$$P_{X}(x) P_{Z}(z) dxdz$$

$$P(v)dv = \int_{S_{1} + S_{2}} P_{X}(x) P_{Z}(z) dxdz$$

On specifying the distributions  $P_X$ ,  $P_Z$  the integral can be evaluated. P(v) then gives all the information that can be obtained about the output. In this article all random variables will be assumed normally distributed.

The derivation of P(v) is given in appendix 2. It is found to be

$$P(v) = \frac{\frac{rv}{XY(1-r^2)}}{e^{\frac{rv}{XY\sqrt{1-r^2}}}} K_0 \left[ \frac{|v|}{XY(1-r^2)} \right] \dots (3)$$

where  $K_{O}(x)$  is a modified Bessel Function of the second kind (ref.3)

The mean output is

$$\overline{v} = \int_{-\infty}^{+\infty} v P(v) dv$$

and this can be verified to be krXY in agreement with (a)

The mean square output about zero is

$$V_0^2 = \int_0^\infty v^2 P(v) dv$$

$$= k^2 (1 + 2r^2) x^2 y^2$$

The mean square  $V_o^2$  includes a contribution from the d.c. output  $\widetilde{v}$  so the mean square of the fluctuations about the mean  $\widetilde{v}$  is

$$V_{F}^{2} = \int_{-\infty}^{\infty} (v - \overline{v})^{2} P(v)$$

$$= V_{o}^{2} - \overline{v}^{2}$$

$$= k^{2}(1 + r^{2})x^{2}y^{2} = k^{2}(1 + r^{2}) p^{2} \qquad (4)$$

The effect of smoothing on the fluctuations about the mean can be shown to reduce VF by the ratio of the signal bandwidth  $\triangle f_1$  to the smoothing circuit bandwidth  $\triangle_2 f_2$  so that the actual output fluctuations have a mean square given by  $V_S^2 = V_F \underline{\triangle f_2}$ . The smoothing also has the  $\underline{\triangle f_1}$ 

effect of centralising the fluctuations about the mean. In fact the greater the smoothing the more nearly are the fluctuations represented by a normal error curve about the mean.

# (c) The mean output and r.m.s. voltage of the fluctuations about the mean in a ring modulator with partially correlated inputs

As in the case of the true multiplier the first aim is to derive the probability distribution function for the output.

It has already been explained that the ring modulator has twelve different states and as these have different characteristics the probability of the modulator being in any given state is evaluated separately. The total probability P(v) dv of the output lying between v and v + dv will then be the sum of the probabilities  $P_i(v)$  dv for the different states as these probabilities are exhaustive and exclusive. Whereas, in the true multiplier P(v) dv was an integral over a strip between two hyperbolas, in the ring modulator the integration is over strips bounded by straight lines approximating to hyperbolas (fig. 4). The expression found for P(v)

is:  

$$P(v) = \sqrt{\frac{2}{\pi}} \left\{ \frac{e^{\frac{-2v^2}{X}}}{x} \text{ erfc} \right. \frac{\sqrt{2}(2x - ry)v + e^{\frac{-2v^2}{Y}}}{xy\sqrt{1 - r^2}} \text{ erfc} \frac{\sqrt{2}(2y - rx)v}{xy\sqrt{1 - r^2}} \right.$$

$$\begin{array}{c}
-\frac{18v^{2}}{x^{2}+y^{2}+2rxy} \\
+\frac{3e}{(x^{2}+y^{2}+2rxy)^{\frac{1}{2}}} & erf \sqrt{2}(2y^{2}-x^{2}+rxy)v \\
xy(x^{2}+y^{2}+2rxy)^{\frac{1}{2}}\sqrt{1-r^{2}}
\end{array}$$

$$+ erf \sqrt{\frac{2}{2}(2x^{2}-y^{2}+rxy)v} \\
+ xy(x^{2}+y^{2}+2rxy)^{\frac{1}{2}}\sqrt{1-r^{2}}$$
(5)

for v > 0

For v < 0 the expression is the same except that v is replaced by |v| and r by -r. erf x and erfc x are the error function and complimentary error function respectively.

The mean value is given in terms of the parameters by:

$$\overline{v} = \int_{-\infty}^{\infty} vP(v) dv = \frac{1}{6} \int_{2\pi}^{\overline{p}} \left\{ \left| 4q + \frac{1}{q} + 4r \right|^{\frac{1}{2}} + \left| q + \frac{4}{q} + 4r \right|^{\frac{1}{2}} - \left| 4q + \frac{1}{q} - 4r \right|^{\frac{1}{2}} - \left| q + \frac{4}{q} - 4r \right|^{\frac{1}{2}} \right\}$$

$$- \left| q + \frac{4}{q} - 4r \right|^{\frac{1}{2}} \right\}$$
(6)

In a number of applications the correlation will be small and an approximation may be used:

$$\overline{v} = \frac{2}{3} \sqrt{\frac{p}{2\pi}} \quad r \quad \left\{ (4q + \frac{1}{q})^{-\frac{1}{2}} + (q + \frac{4}{q})^{-\frac{1}{2}} \right\}$$
 (7)

The function in square brackets is plotted in fig. 5 so the correlation coefficient can easily be found by multiplication of the function by v/p. The general expression for r (eqn. (6)) can be put in the form

$$r = \frac{\overline{v}}{\sqrt{p}} \left[ 6\sqrt{2\pi} \frac{1}{\left[4q + \frac{1}{q} + 4r\right]^{\frac{1}{2}} + \left|q + \frac{4}{q} + 4r\right]^{\frac{1}{2}} - \left|4q + \frac{1}{q} - 4r\right|^{\frac{1}{2}}} \right]$$
(9)

The expression in square brackets gives rise to a series of curves for different values of r which are also shown in fig. 5. An approximate value of r may be assumed in order to locate the right curve to use to find a more accurate value of r.

In all the graphs presented in this report q is only given in the range 0 to 1. As q is merely the ratio of X to Y it is only necessary to call the smallest input X and the largest Y.

The mean square output about zero is:

$$V_{0}^{2} = \int_{-\infty}^{\infty} v^{2}P(v)dv.$$

$$= \frac{p}{2\pi} \int_{4\pi}^{4\pi} \cdot \frac{q + \frac{1}{q}}{9} - \frac{1}{2} \left(q - q + \frac{1}{q}\right) \tan^{-1} \frac{4q}{(1 - 4q^{2})}$$

$$-\frac{1}{2} \left(q - q + \frac{1}{q}\right) \tan^{-1} \left(\frac{\frac{4}{q}}{q^{2} - 4}\right) - \frac{2}{3}$$

$$(0 < \tan^{-1} < \pi)$$

$$(r small).$$
(10)

For r small  $\rm V_0^2$  is approximately the same as  $\rm V_F^2$  so (10) may be used when considering the fluctuations about the mean. The general expression for  $\rm V_0^2$  is given in the appendix.

When  $\frac{x}{y}$  or 4 is >> 1,  $v_0^2 = \frac{p}{4q} = \frac{y^2}{4}$ . This expresses the fact that when the modulator is well out of balance one input merely acts as a switch for the other.

# (d) Comparison of Signal to Noise Ratio in a True Multiplier and Ring Modulator

By signal to noise ratio is meant the ratio of  $\overline{ extbf{v}}$  to  $extbf{V}_{\overline{ extbf{r}}}.$ 

From 2, 4.

$$G_{r.m.} = \frac{r}{\sqrt{1 + r^2}}$$
 r for small r. ..... (11)

and from 7, 10

Gt.m. = 
$$\frac{2}{3}r \left[ (4q + \frac{1}{q})^{-\frac{1}{2}} + (q + \frac{4}{q})^{-\frac{1}{2}} \right]$$
 for small r. (12)  

$$\begin{cases} 4\pi \left( q + \frac{1}{q} \right) - \frac{1}{2} \left( q - q + \frac{1}{q} \right) \tan^{-1} \frac{4q}{q} - \frac{1}{2} \left( q - q + \frac{1}{q} \right) \tan^{-1} \left( \frac{4}{q} - \frac{2}{3} \right) \frac{1}{2} \\ \frac{1}{q} - \frac{1}{q} = \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} + \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q} + \frac{1}{q} + \frac{1}{q} \right) - \frac{1}{2} \left( \frac{1}{q} - \frac{1}{q} + \frac{1}{q$$

In fig. 6 the ratio of  $G_{r.m.}$  is given in terms of the % and d.b. loss of the ring modulator compared with the true multiplier. It can be seen that, for r small, its loss when the inputs are balanced is only 0.6 db (7%). It is clear also that optimum conditions for detection occur when the inputs are approximately balanced. The value of  $G_{r.m.}$  may be obtained from these curves by multiplication of the given ratio by  $\frac{r}{\sqrt{1+r^2}}$ .

### References.

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- 2. Tucker M.J. Proc. Roy. Soc. A. Vol. 202 P.565 (1950).
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### MJT/JC/BS

### Symbols

х) х) Instantaneous input voltages. Instantaneous output voltage. Instantaneous component of y that is uncorrelated with x. X, Y, Z. Root Mean Square Values of x, y, z.  $V_{\Omega}$ R.M.S. value of v about zero. R.M.S. value of v about the mean d.c. output before smoothing.  $V_{\mathbb{H}^1}$ R.M.S. value of v about the mean d.c. output after smoothing.  $V_{S}$  $\tilde{\mathbf{x}}$ The bar over a symbol represents a time mean over a long period. The proportion of x that is added to z to form y, that is, C y = cx + z. Parameters specifying the performance of the modulator. Correlation coefficient between x, y. k Scale constant in true multiplier.  $P_X(x)$ ,  $P_Z(z)$  Probability distributions of x and z. P(v)Probability distribution of the output v.  $P_{i}(v)$ Probability distribution of v for the ring modulator in state i.  $G_{t.m.}$ ,  $G_{r.m.}$  The output signal to noise ratio in a true multiplier and a ring modulator.  $\Delta f_1$ ,  $\Delta f_2$ . Bandwidth of input signals (assumed equal) and of smoothing

filter in output.

### Appendix 1.

## On determining the process producing a correlation between two signals

The problem is: given two time dependent signals which are partially correlated, is it possible to distinguish between the various possible ways in which the correlation could have been produced, assuming that no further information is available?

In practice the problem may be simplified to distinguishing between direct correlation in which the signals are:

$$x(t) = \alpha(t)$$
  
 $y(t) = \alpha(t) + \beta(t)$ 

and partial correlation in which the signals are:

$$x(t) = \chi(t) + a \xi(t),$$
  

$$y(t) = \hat{\lambda}(t) + b \xi(t).$$

It is easiest to consider the signals as a series of discrete readings  $x_1,\ldots,x_n$  and  $y_1,\ldots,y_n$ . Arguments applying to such series can clearly be generalized to apply to continuous signals.

In the first type of correlation this gives a series of pairs of simultaneous equations:-

$$x_1 = \lambda_1$$
  $y_1 = \beta_1 + c \lambda_1$   
 $x_2 = \lambda_2$   $y_2 = \beta_2 + c \lambda_2$ 

Now c is unknown and at first sight there is insufficient information to solve the equations easily but if it is stipulated that  $\checkmark$  (t),  $\checkmark$ 3 (t) are uncorrelated then there is an extra condition that  $\frac{1}{N}$   $\stackrel{N}{\searrow}$   $\checkmark$   $\stackrel{N}{\searrow}$   $\stackrel{N}{\longrightarrow}$  o which makes the equations unique.

In the second type of correlation there is a series of equations:

$$x_1 = \begin{cases} y_1 + a \xi_1 \\ x_2 = \begin{cases} y_2 + a \xi_2 \end{cases}$$
  $y_1 = \begin{cases} y_1 + b \xi_1 \\ y_2 = \begin{cases} y_2 + b \xi_2 \end{cases}$  etc.

These equations are indeterminant even knowing that  $\xi$ ,  $\delta$  are uncorrelated. There is therefore nothing inconsistent with the known facts in putting a  $\xi(t)=x(t)$ , in which case the equations are similar to the first.

This problem is a major difficulty in statistics. For example, because there is a strong correlation between the consumption of chocolate and the flow of water under Tower Bridge, it does not follow that a proportion of the population watch the Thames and decide to eat more chocolate when it is flowing fast. In fact, of course, the correlation is produced because both are correlated with the meridian altitude of the sun.

# The Probability Diotalbutton of Outpot Voltage from a True Metrophics with partly correlated Inputs

as explained in section b) of the report, the pre-bability distribution function is for v>0;

$$P(v) dv = \int_{S_1 + S_2} P_x(x) P_z(3) dx d3$$

where 
$$v = (c \infty + 3) \infty$$

Consider the transformation

from 9 = -00 to 9 = +00

$$3 = \frac{1}{\sqrt{2}\sqrt{1+c^2}} \left( \sqrt{1+c^2} - c \right) + \left[ \sqrt{1+c^2} + c \right] \omega + \left[ \sqrt{1+c^2} + c \right] \omega \right)$$
 3

Equ. 3. has the effect of changing from rectangular axes to oblique access, to (shown in fig. 3) 9 then rotating them 45° anticlockwise to U, w.

On substituting from 3. into 2. we find that:

Now change from u, w to hyperbolic coordinates p, of given by

Then, 
$$V = \frac{\rho^2}{2\sqrt{1+c^2}}$$

$$dV = \frac{\rho d\rho}{\sqrt{1+c^2}}$$
5.

In these transformations the clements of area become docdy, dudus, people From 5. It is own that the strips  $S_1, S_2$  of constant V become two identical strips in the  $\rho$ ,  $\rho$  plane, parallel to the  $\rho$  ascis, and extending

On substituting from 2.,3,4. into 1. P(v) du Secomes:

now let.

7.

. 6. becomes:

$$P(v)dv = 2\int_{-\infty}^{\infty} \frac{1}{2\pi x^{2}} \exp\left\{-\frac{s^{2}k\cosh 2\psi}{4(1+c^{2})x^{2}z^{2}}\right\} \frac{d\psi}{2} \exp\frac{cs^{2}}{\sqrt{1+c^{2}}2z^{2}}$$
where  $\psi = S + \phi$ 

$$\frac{1}{2} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^$$

where Ko is a Bessel Function of the second kind, with imaginary argument. (Modified Bessel Function).

Similary for vice it is found that

$$P(v)dv = \frac{1}{uxy\sqrt{1-r}} K_0\left(\frac{v}{xy(1-r)}\right) \exp \frac{rv}{xy(1-r)}$$

Finally 8,9, can be combined to give, In all v

$$P(v) = \frac{1}{\pi x y \sqrt{1-r^2}} \, \mathcal{K}_0\left(\frac{|v|}{x y (1-r^2)}\right) \exp \frac{r v}{x y (1-r^2)}$$
 10.

The mean is given by:

$$\vec{v} = \int_{-\infty}^{\infty} v P(v) dv$$

$$= \frac{2}{\pi x y \sqrt{1-r^2}} \int_{0}^{\infty} v \sinh \frac{r v}{x y (1-r^2)} K_0\left(\frac{v}{x y (1-r^2)}\right) dv$$

The mean square about zero is given by:

$$V_{o}^{2} = \int_{-\infty}^{\infty} v^{2} P(v) dv$$

$$= 2 \int_{0}^{\infty} \frac{v^{2}}{\pi x y \sqrt{1-r^{2}}} conh \frac{rv}{x y (1-r^{2})} K_{o} \left(\frac{v}{x y (1-r^{2})}\right) dv$$

$$= (1+2r^{2}) x^{2} y^{2}$$
[10] 3 p. 77]

The Probability Distribution of the Output Voltage in a Ring Modulator with partly cornelated Inputs.

The strips over which  $\int P_{\chi}(x) P_{\chi}(3) dx d3$  is to be evaluated to gue P(v) dv are shown in fig. 4. The output v in each of the states is listed in Table 1.

The calculations for P2 (v) dr are given in some detail whilst the results for the other states are only quoted.

In state 2 
$$v = \frac{(c+1)oc + 3}{6}$$

The limits are found from the inequalities in table 1

where,

$$U = \sqrt{2} \times \frac{1}{X^{2}} \left\{ 2C \left( \frac{2^{2} + c + i^{2} \times i^{2}}{(2^{2} + c + i^{2} \times i^{2})^{2}} - \frac{6 V (c + i) X^{2}}{(2^{2} + c + i^{2} \times i^{2})^{2}} \right\}$$

$$Q = \sqrt{2} \times \frac{1}{X^{2}} \left( \frac{2^{2} + c - 2}{(2^{2} + c + i^{2} \times i^{2})^{2}} \right)$$

$$Q = \sqrt{2} \times \frac{1}{X^{2}} \left( \frac{2^{2} + c + i^{2} \times i^{2}}{(2^{2} + c + i^{2} \times i^{2})^{2}} \right)$$

$$Q = \sqrt{2} \times \frac{1}{X^{2}} \left( \frac{2^{2} + c + i^{2} \times i^{2}}{(2^{2} + c + i^{2} \times i^{2})^{2}} \right)$$

If r, x, y are substituted for c, x, Z it is found that

$$P_{2}(v) = \frac{3}{\sqrt{2\pi}} \frac{\exp\left[\frac{18v^{2}}{x^{2}+y^{2}+2rxy}\right]}{\left(x^{2}+y^{2}+2rxy\right)^{4}} \left[ \frac{\exp\left[\frac{12(2x^{2}+x^{2}+rxy)^{4}\sqrt{1-r^{2}}}{xy(x^{2}+y^{2}+rxy)^{4}\sqrt{1-r^{2}}} + \exp\left[\frac{12(2x^{2}+y^{2}+rxy)^{4}\sqrt{1-r^{2}}}{xy(x^{2}+y^{2}+rxy)^{4}\sqrt{1-r^{2}}} \right]$$

Similary

$$P_{i}(v) = \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{2v^{i}}{x^{2}}\right\} \operatorname{erfc} \sqrt{2(2x-ry)}v$$

$$P_3(v) = \frac{1}{\sqrt{2\pi}} \frac{\exp\left(-\frac{2v^2}{y^2}\right)}{y^2} \text{ erge } \sqrt{2} \frac{(2y-rx)v}{xy\sqrt{1-r^2}}$$

where erf and erfo are the error function and complimentary Citor function.

It is clear from the symmetry of the problem that the other positive states 7,8,9 contribute similar terms to P(r), and 0 4 m p 00

 $P(v) = \lambda (P_1(v) + P_2(v) + P_3(v))$ 

It can be shown that, for uso, P(v) is the same except that u io replaced by IVI and r by -r.

The mean value of v is Jup(v) dv and from the expressions for Pi(v) this integral is seen to involve integrals of the form  $\int_{0}^{\infty} ve^{-\lambda^{2}v^{2}} eff 3v dv = \frac{3}{24^{2}} \frac{1}{(\lambda^{2}+\beta^{2})^{2}}$ 

Jo ve-d'viefestdr = Ldi (1 - Bigh)

Upon substituting ford, & from the Pilv) it is found that

The mean square of the output about zero is jourp(v)dv

This involves integrals of the form:

$$\int_{0}^{\infty} v^{2} e^{-\lambda^{2} v^{2}} \operatorname{erf} \beta v dv = \frac{1}{2 d^{3} \sqrt{11}} \left[ \tan \frac{i}{\lambda} + \frac{\lambda / 3}{(d^{2} + \beta^{2})} \right]$$

$$\int_{0}^{\infty} v^{2} e^{-\lambda^{2} v^{2}} \operatorname{erf} \beta v dv = \frac{1}{2 d^{3} \sqrt{11}} \left[ \frac{11}{2} - \tan \frac{i}{\lambda} - \frac{\lambda / 3}{(d^{2} + \beta^{2})} \right]$$

In these two integrals the values of the tan' terms lie between -T/2 and + II.

On substitution ford, is from the Pi(v) I after combining the various ten' terms together (paying careful attention to the interval in which each term lies) it is found that:

$$A_{0} = \frac{1}{4!!} \left\{ \frac{1}{4!!} \left( \frac{1}{4} + \frac{1}{4} +$$

In this expression for Vo', tan- lies in the range o to IT not - I to + II to

For r=1, there are three different states

1. 
$$\frac{x}{y} = 9 > 2$$
  $V_0^1 = \frac{y^1}{4} = \frac{\rho}{49}$   $\overline{V} = \frac{y}{\sqrt{2\pi}} = \frac{1}{\sqrt{2\pi}} \sqrt{\frac{\rho}{9}}$ 

STATE			RELATIONSHIP: x,y	CONDUCTING DIODES	OUTPUT VOLTAGE V
1	x>o<	y>0{	4>2×	D <sub>2</sub> , D <sub>3</sub>	2
2			2x 3 y > 축	D <sub>1</sub> , D <sub>2</sub> , D <sub>3</sub>	x + y
3			출 > 상	D <sub>2</sub> , D <sub>1</sub>	¥
4		4<0	x >-4	D <sub>21</sub> , D <sub>1</sub>	ž
5			2× >-4> 章	D1, D2, D4	7-x
6			-4>2x	D1. D4	- X
	x<0{	4<0	-4>-2x	D1. D4	
8			-2×>-4>-~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	Di, D3, D4	- X+4 - 6
9			- <u>x</u> > - 4	D3, D4	-4
10		y >0{	-x > y	D3, D4	*** Y
(1			-2x>4>===================================	D2, D3, D4	3-4
12			4>-2×	D2, D3	<u>X</u> 2

TABLE I

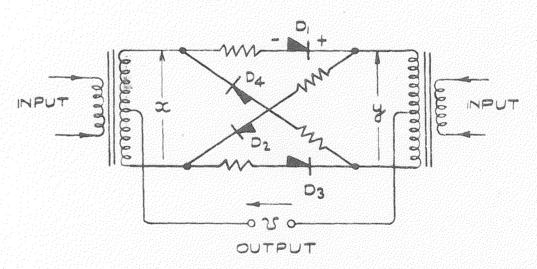


FIG.I(a)

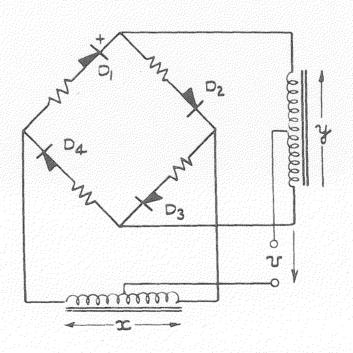
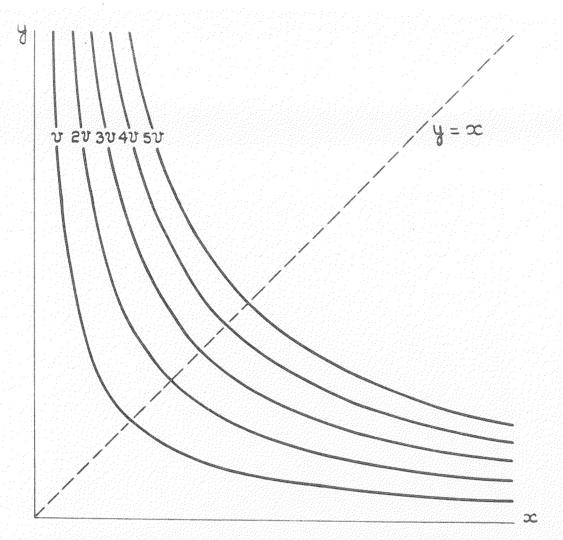
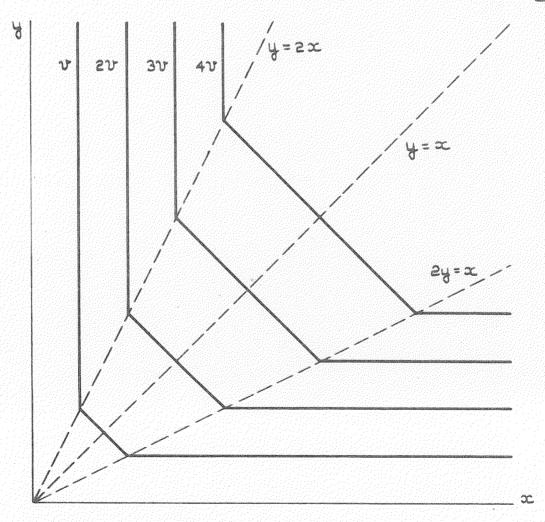


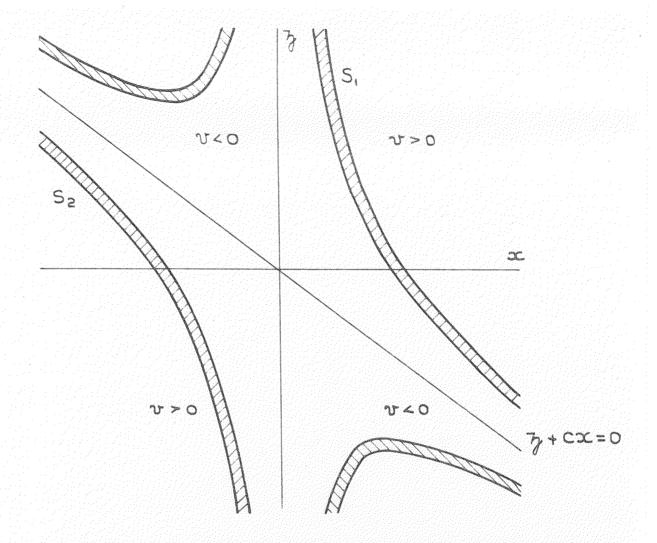
FIG. I(&)



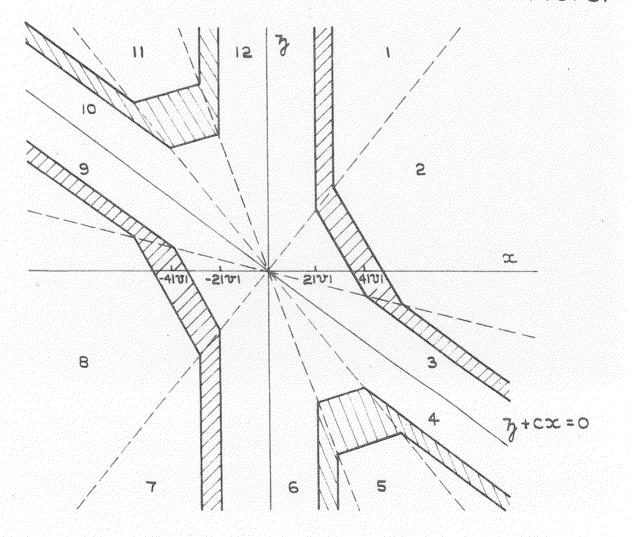
CHARACTERISTICS OF TRUE MULTIPLIER FIG. 2a.



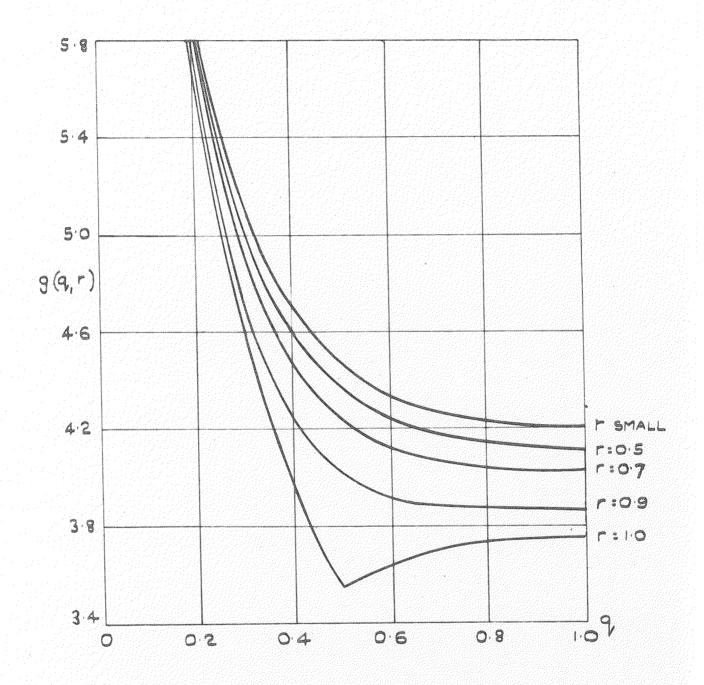
CHARACTERISTICS OF RING MODULATOR FIG. 26.



RANGE OF INTEGRATION FOR TRUE MULTIPLIER FIG. 3.

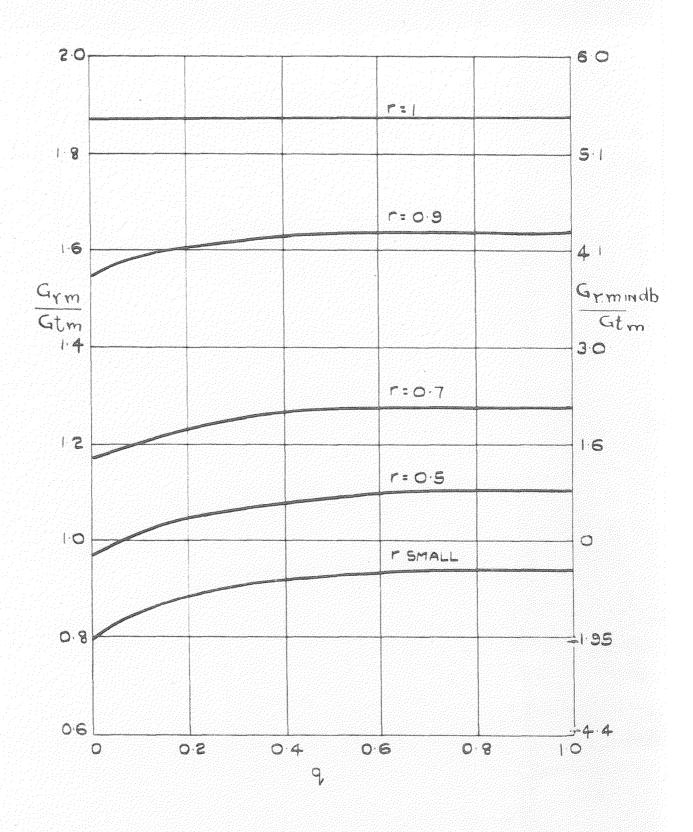


RANGE OF INTEGRATION FOR RING MODULATOR FIG. 4.



# CURVES FOR DETERMINATION OF Y

$$r = \frac{\overline{v}}{\sqrt{p}} q(q,r)$$



COMPARISON OF SIGNAL/NOISE IN RING MODULATOR AND TRUE MULTIPLIER.

### Distribution List.

	Copy No.
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D.R.P.P.	2-11
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The Capt., H. M.U.D.E.	15
Captain Superintendent, A.S.R.E.	16
The Capt., H.M.U.C.W.E.	17
Captain Superintendent, A.E.W.	18
D.S.I.R.	19
The Director, N.P.L.	20
U.S. Naval Attache.	21
N.I.O. File,	22 <b>-</b> 50

