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1 A Scalable Performance–Complexity Tradeoff for 2 Constellation Randomization in Spatial Modulation

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Abstract—It is widely recognized that traditional single radio frequency 5 6 (RF)-chain-aided spatial modulation (SM) does not offer any transmit 7 diversity gain. As a remedy, constellation randomization (CR), relying on 8 transmit prescaling (TPS), has been shown to provide transmit diversity 9 for single-RF-chain-aided SM. In this paper, we propose a low-complexity 10 approach to SM with the aid of constellation randomization (SM-CR) that 11 considerably improves the transmit diversity gain of SM at a reduced 12 computational burden compared with conventional SM-CR. While con-13 ventional SM-CR performs a full search among a set of candidate TPS 14 factors to achieve the maximum minimum Euclidean distance (MED) in 15 the received SM constellation, here, we propose a thresholding approach, 16 where, instead of the maximum MED, the TPS aims to satisfy a specific 17 MED threshold. This technique offers a significant complexity reduction 18 with respect to the full maximization of SM-CR, since the search for TPS 19 is terminated once a TPS set is found that satisfies the MED threshold. Our 20 analysis and results demonstrate that a scalable tradeoff can be achieved 21 between transmit diversity and complexity by appropriately selecting the 22 MED threshold, where a significant complexity reduction is attained, while 23 achieving a beneficial transmit diversity gain for the single-RF SM.

24 *Index Terms*—Constellation shaping, multiple-input single-output, 25 spatial modulation (SM), transmit prescaling (TPS).

I. INTRODUCTION

27 Spatial modulation (SM) has been shown to offer a low-complexity 28 design alternative to spatial multiplexing, where only a subset (down 29 to one) of radio frequency (RF) chains is required for transmission 30 [1], [2]. Early work has focused on the design of receiver algorithms 31 for minimizing the bit error ratio of SM at low complexity [1]–[5]. 32 Matched filtering is shown to be a low-complexity technique for 33 detecting the activated antenna index (AI) [1]–[3]. A maximum like-34 lihood (ML) detector is introduced in [4] for reducing the complexity 35 of classic spatial multiplexing ML detectors, whereas the complexity 36 imposed can be further reduced by compressive sensing detection 37 approaches [5]. In addition to receive processing, several transmit 38 precoding (TPC) approaches have been proposed for receive antenna 39 (RA)-aided SM, where the spatial information is mapped onto the RA 40 index [6]–[8].

41 Relevant work has also proposed constellation shaping for SM 42 [9]–[14]. Specifically, in [9], the transmit diversity of coded SM

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is analyzed for different *spatial constellations*, which represent the 43 legitimate sets of activated transmit antennas (TAs). Furthermore, 44 Yang *et al.* in [10] conceived a symbol constellation optimization 45 technique for minimizing the bit error rate (BER). Indeed, spatial and 46 symbol constellation shaping are discussed separately in the afore- 47 mentioned reference. By contrast, the design of the received SM con- 48 stellation that combines the choice of the TA as well as the transmit 49 symbol constellation is the focus of this paper. A number of con- 50 stellation shaping schemes [11]–[14] have also been proposed for the 51 special case of SM, which is referred to as space shift keying, where the 52 information is purely carried in the spatial domain, by the activated AI. 53 However, the application of the above constellation shaping to the SM 54 transmission, where the transmit waveform is modulated, is nontrivial. 55

Recent work has focused on shaping the receive SM constellation by 56 means of symbol prescaling at the transmitter, aiming for maximizing 57 the minimum Euclidean distance (MED) in the received SM constel- 58 lation [15]–[17]. The constellation shaping approach in [15] and [16] 59 aims at fitting the receive SM constellation to one of the existing opti- 60 mal classic constellation formats in terms of minimum distance, such 61 as, e.g., quadrature amplitude modulation (QAM). Due to the strict 62 constellation fitting requirement imposed on both amplitude and phase, 63 this prescaling relies on the inversion of the channel coefficients. In the 64 case of ill-conditioned channels, this substantially reduces the received 65 signal-to-noise ratio (SNR). This problem has been alleviated in [17], 66 where a constellation shaping scheme based on phase-only scaling is 67 proposed. Still, the constellation shaping used in the above schemes is 68 limited in the sense that it only applies to multiple-input-single-output 69 systems, where a single symbol is received for each transmission, and 70 thus, the characterization and shaping of the receive SM constellation 71 is simple. 72

Closely related to this work, a transmit prescaling (TPS) scheme 73 was proposed for SM [19], where the received SM constellation is 74 randomized by TPS for maximizing the MED between its points for a 75 given channel. A number of randomly generated candidate sets of TPS 76 factors are formed offline, known to both the transmitter and the re- 77 ceiver, and the transmitter then selects that particular set of TPS factors 78 that yields the SM constellation having the maximum MED. Against 79 this background, in this paper, we propose a low-complexity relaxation 80 of the above optimization instead of an exhaustive search, where the 81 first TPS factor set that is found to satisfy a predetermined threshold is 82 selected, thus reducing the computational burden of the TPS operation. 83 The proposed scheme is shown to provide a scalable tradeoff between 84 the performance attained and the complexity imposed, by accordingly 85 selecting the MED threshold.

This paper is organized as follows: In Section II, the basic system 87 model is first introduced, and the proposed scheme is then discussed. 88 The computational complexity of the proposed technique is analyzed 89 in Section III, and its performance against the state of the art is 90 evaluated in Section IV. Finally, in Section V, we draw the key 91 conclusions of our study. 92

II. SPATIAL MODULATION WITH THRESHOLD CONSTELLATION 93 RANDOMIZATION (SM-TCR) 94

Consider a multiple-input multiple-output (MIMO) system, where 95 the transmitter and the receiver are equipped with N_t and N_r antennas, 96

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97 respectively. For simplicity, unless stated otherwise, in this paper, we 98 assume that the transmit power budget is limited to unity, i.e., P = 1. 99 We focus on the single-RF-chain-aided SM approach, where the trans-100 mit vector is in the all-but-one zero form $\mathbf{s}_m^k = [0, \ldots, s_m, \ldots, 0]^T$, 101 with $[.]^T$ denoting the transpose operator. Here, $s_m, m \in \{1, \ldots, M\}$ 102 is a symbol taken from an *M*-order modulation alphabet that rep-103 resents the transmitted waveform in the baseband domain conveying 104 $\log_2(M)$ bits, whereas k represents the index of the activated TA (the 105 index of the nonzero element in \mathbf{s}_m^k) conveying $\log_2(N_t)$ bits in the 106 spatial domain. Clearly, since s is an all-zero vector apart from s_m^k , 107 there is no interantenna interference.

For the per-antenna TPS approach, which is the focus of this paper, 109 the signal fed to each TA is scaled by a complex-valued coefficient 110 $\alpha_k, k \in \{1, ..., N_t\}$ for which we have $E\{|\alpha_k|\} = 1$, where |x|111 denotes the amplitude of a complex number x, and $E\{.\}$ denotes the 112 expectation operator. Defining the MIMO channel vector as **H** with 113 elements $h_{m,n}$ representing the complex-valued channel coefficient 114 between the *n*th TA and the *m*th RA, the received symbol vector can 115 be written as

$$\mathbf{y} = \mathbf{H}\mathbf{A}\mathbf{s}_m^k + \mathbf{w} \tag{1}$$

116 where $\mathbf{w} \sim C\mathcal{N}(0, \sigma^2 \mathbf{I})$ is the additive white Gaussian noise com-117 ponent at the receiver, with $C\mathcal{N}(\mu, \sigma^2)$ denoting the circularly 118 symmetric complex Gaussian distribution with a mean of μ and a 119 variance of σ^2 . Furthermore, $\mathbf{A} = \text{diag}(\mathbf{a})$ is the TPS matrix with 120 $\mathbf{a} = [\alpha_1, \alpha_2, \dots, \alpha_{N_t}]$, and $\text{diag}(\mathbf{g})$ represents the diagonal matrix 121 with its diagonal elements taken from vector \mathbf{g} . Note that the diagonal 122 structure of \mathbf{A} guarantees having a transmit vector $\mathbf{x} = \mathbf{As}$ with a 123 single nonzero element, so that the single-RF-chain aspect of SM is 124 preserved.

125 At the receiver, a joint ML detection of both the TA index and the 126 transmit symbol is obtained by the minimization, i.e.,

$$\begin{aligned} [\hat{s}_m, \hat{k}] &= \arg\min_i \|\mathbf{y} - \dot{\mathbf{y}}_i\| \\ &= \arg\min_{m,k} \|\mathbf{y} - \mathbf{HAs}_m^k\| \end{aligned} \tag{2}$$

127 where $\|\mathbf{x}\|$ denotes the norm of vector \mathbf{x} , and $\dot{\mathbf{y}}_i$ is the *i*th constellation 128 point in the received SM constellation. By exploiting the specific 129 structure of the transmit vector, this can be further simplified to

$$[\hat{s}_m, \hat{k}] = \arg\min_{m,k} \|\mathbf{y} - \mathbf{h}_k \alpha_m^k s_m\|$$
(3)

130 where \mathbf{h}_k denotes the *k*th column of matrix **H**. It is widely recognized 131 that the performance of the detection as formulated above is dominated 132 by the MED between the adjacent constellation points $\dot{\mathbf{y}}_i$ and $\dot{\mathbf{y}}_j$ in the 133 receive SM constellation, i.e.,

$$d_{\min} = \min_{i,j} \|\dot{\mathbf{y}}_i - \dot{\mathbf{y}}_j\|^2, \ i \neq j.$$

$$\tag{4}$$

Accordingly, to improve the likelihood of correct detection, con-135 stellation shaping TPS schemes conceived for SM aim at maximizing 136 this MED. The optimum TPS matrix A^* can be found by solving the 137 optimization problem of [20]

$$\mathbf{A}^{*} = \arg \max_{\mathbf{A}} \min_{i,j} \|\dot{\mathbf{y}}_{i} - \dot{\mathbf{y}}_{j}\|^{2}, \ i \neq j$$
(5)
s.t.c.
$$\operatorname{trace}(\mathbf{A}^{*H}\mathbf{A}^{*}) \leq P$$

138 and, additionally for single-RF-chain-aided SM, subject to \mathbf{A}^* having 139 a diagonal structure. In the above, \mathbf{A}^H and trace(\mathbf{A}) represent the 140 Hermitian transpose and trace of matrix \mathbf{A} , respectively. The above 141 optimization, however, is an NP-hard problem, which makes finding the TPS factors prohibitively complex and motivates the conception 142 of lower-complexity suboptimal techniques. Indeed, it has been shown 143 that the TPS approach in [19], by selecting among a set of predeter- 144 mined randomly generated TPS vectors instead of fully optimizing the 145 TPS, offers a near-optimal performance with the lowest complexity 146 among the TPS optimization approaches [20], [21].

TPS Vector Generation: Accordingly, with SM-TCR first, a number 148 of D random candidate TPS vectors are generated, in the form of \mathbf{a}_d , 149 where $d \in [1, D]$ denotes the index of the candidate set, and \mathbf{a}_d is 150 formed by the elements $\alpha_m^{k(d)} \sim C\mathcal{N}(0, 1)$. To ensure that the average 151 transmit power remains unchanged, the scaling factors are normalized 152 to unit power. These are made available to both the transmitter and the 153 receiver before transmission. These assist in randomizing the received 154 constellation, which is most useful in the critical scenarios where two 155 points in the constellation of $\mathbf{Hs}_m^k, m \in [1, M], k \in [1, N_t]$ happen to 156 be very close.

A. Thresholded Selection of TPS 158

For a given channel, based on knowledge of vectors \mathbf{a}_d , both the 159 transmitter and the receiver can determine the received SM constel- 160 lation for the *d*th TPS set by calculating the legitimate set of [m, k] 161 combinations in 162

$$\hat{\mathbf{y}} = \mathbf{H} \mathbf{A}_d \mathbf{s}_m^k \tag{6}$$

where $\mathbf{A}_d = \operatorname{diag}(\mathbf{a}_d)$ is the diagonal matrix that corresponds to 163 the candidate set \mathbf{a}_d . Then, for the given channel coefficients, the 164 transmitter and the receiver can choose independently the scaling 165 vector \mathbf{a}_o . Alternatively, if no channel state information is available 166 at the transmitter (receiver), the receiver (transmitter) can inform the 167 transmitter (receiver) concerning the optimum \mathbf{a}_o by transmitting a 168 number of $\lceil \log_2(D) \rceil$ bits. Contrary to the SM-CR in [19], where the 169 maximum MED among all *D* possibilities is chosen, here, a threshold- 170 based approach is introduced, where the search for TPS is terminated 171 when a candidate TPS is found that satisfies a MED threshold. This 172 optimization problem can be expressed as 173

$$\mathbf{A}_{o} = \begin{cases} \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{j}\}\neq\\\{m_{i},k_{j}\}\neq\\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{i},k_{p}\}\\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \theta \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{p}\}}} \|\mathbf{H}\mathbf{s}_{m_{1}}^{k_{1}} - \mathbf{H}\mathbf{s}_{m_{2}}^{k_{2}}\|^{2} \\ & \sup_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{p}\}}} \|\mathbf{H}\mathbf{A}_{d}\mathbf{s}_{m_{1}}^{k_{1}} - \mathbf{H}\mathbf{A}_{d}\mathbf{s}_{m_{2}}^{k_{2}}\|^{2}, \text{ otherwise} \\ & \{m_{i},k_{p}\} \end{cases} \end{cases}$$
(7)

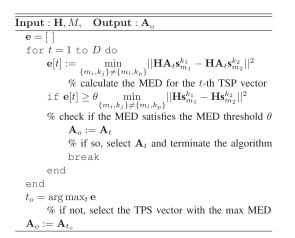
where θ represents the MED threshold with respect to the MED 174 without TPS. Equivalently, for the case of single-RF-chain-based SM, 175 this can be simplified to 176

$$\mathbf{A}_{o} = \begin{cases} \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{j}\}\neq\\ \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ arg \max_{d} & \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{l},k_{p}\}\\\{m_{l},k_{p}\}}} \| \mathbf{h}_{k_{1}}a_{m_{1}}^{k_{1}}s_{m_{1}} - \mathbf{h}_{k_{2}}a_{m_{2}}^{k_{2}}s_{m_{2}} \|^{2}, \text{otherwise} \\ & \{m_{l},k_{p}\} \end{cases}$$

$$(8)$$

In other words, the search stops if a TPS set is found that satisfies 177 the threshold; otherwise, the TPS that offers the maximum MED is 178 returned, following a full search as in SM-CR. For completeness, 179 we present the associated algorithm in Table I. It will be shown that 180 this process offers significant computational benefits with respect to 181 full SM-CR. 182

TABLE I Algorithm SM-TCR



183 Based on (8), the transmitter sends $\mathbf{x} = \mathbf{A}_o \mathbf{s}_m^k$, and the receiver 184 applies the ML detector according to

$$[\hat{s}_m, \hat{k}] = \arg\min_{m,k} \|\mathbf{y} - \mathbf{H}\mathbf{A}_o \mathbf{s}_m^k\|.$$
(9)

It should be noted that, to dispense with the need for channel state information at the transmitter (CSIT), the receiver can select the best scaling factors using (8) and then feed the index of the scaling matrix is \mathbf{A}_o selected from the set of D candidates back to the transmitter, using $\lfloor \log_2(D) \rfloor$ bits. This constitutes major overhead savings for the proposed scheme with respect to the existing TPS schemes for SM that interful CSIT, while obtaining similar performance.

192 B. Transmit Diversity and Performance Trends

193 While the transmit diversity order of the single-RF SM is known to 194 be one [9], the proposed TPS introduces an amplitude-phase diversity 195 in the transmission, which is an explicit benefit of having D candidate 196 sets of TPS factors to choose from. Accordingly, it was shown in 197 [19] that the obtained transmit diversity order corresponds to the 198 θ -dependent gain in the average MED associated with CR as

$$G(\theta) = \frac{E\{\min_{m,k} \| \mathbf{H} \mathbf{A}_o \mathbf{s}_{m_1}^{k_1} - \mathbf{H} \mathbf{A}_o \mathbf{s}_{m_2}^{k_2} \|^2\}}{E\{\min_{m,k} \| \mathbf{H} \mathbf{s}_{m_1}^{k_1} - \mathbf{H} \mathbf{s}_{m_2}^{k_2} \|^2\}}.$$
 (10)

In addition, SM systems with N_r uncorrelated RAs have been 200 shown to experience a unity transmit diversity order and a receive 201 diversity order of N_r . Accordingly, since the proposed scheme attains 202 a θ -dependent transmit diversity order of $G(\theta)$, the total diversity order 203 becomes $\delta = N_r G(\theta)$. The resulting probability of error P_e obeys the 204 high-SNR trend of

$$P_e = \alpha \gamma^{-N_r G(\theta)} \tag{11}$$

205 where γ is the transmit SNR, and α is an arbitrary nonnegative 206 coefficient. We verify the above theoretical performance trend against 207 simulation in the following.

208 III. COMPUTATIONAL COMPLEXITY

It is clear from the above discussion that the proposed SM-TCR 210 leads to a computational complexity reduction with respect to con-211 ventional SM-CR, due to the early termination of the TPS search, 212 after a calculation of $t \leq D$ out of D TPS sets. Here, we analyze this 213 computational complexity reduction at the receiver. This analysis is

 TABLE II

 COMPLEXITY FOR THE PROPOSED SM-TCR SCHEME

SM-TCR	Operations	
Constellation Optimization		
$\mathbf{HA}_{d}\mathbf{s}_{m}^{k}, \forall m, k \qquad \qquad \times t$	$(2N_r+1)N_tMt$	
$ \mathbf{f}_{m_1,m_2}^{k_1,k_2(d)} = \mathbf{H}\mathbf{A}_d \mathbf{s}_{m_1}^{k_1} - \mathbf{H}\mathbf{A}_d \mathbf{s}_{m_2}^{k_2} , \times t \forall m_1, m_2, k_1, k_2, m_1 \neq m_2, k_1 \neq k_2 $	$2N_r {N_t M \choose 2} t$	
$ \begin{array}{c} \text{check:} \\ \min\{\mathbf{f}_{m_1,m_2}^{k_1,k_2(d)}\} \geq \\ \theta \min_{\{m_i,k_j\}\neq} \mathbf{Hs}_{m_1}^{k_1} - \mathbf{Hs}_{m_2}^{k_2} ^2 \times t \\ \{m_i,k_p\} \end{cases} $	$\binom{N_tM}{2}t$	
ML Detection		
$g_m^k = \mathbf{y} - \mathbf{H}\mathbf{A}_o \mathbf{s}_m^k ^2, \forall m, k \qquad \times B$	$2N_tMN_rB$	
$\arg\min g_m^k imes B$	$N_t M B$	
Total: $(2Nr+1)\left[\binom{N_tM}{2}+N_tM\right]t+0$	$(2N_r+1)\overline{N_tMB}$	

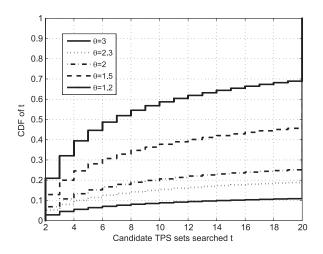


Fig. 1. Cumulative distribution function of the number of candidate TPS searched (t) for various values of θ , D = 20, 4-QAM.

complemented by the following results on the distribution of t. For ref- 214 erence, we have assumed a Long-Term Evolution Type-2 time-division 215 duplex frame structure [18]. This has 10-ms duration that consists of 216 ten subframes out of which five subframes, each containing 14 symbol 217 time slots, are used for downlink transmission, yielding a frame size of 218 F = 70 for the downlink, whereas the rest are used for both uplink and 219 control information transmission. A slow-fading channel is assumed, 220 where the channel remains constant for the duration of the frame. 221

Following the complexity analysis in [19], we quantify the number 222 of operations required in each step of the SM-TCR search in Table II. 223 From the table, we have a total SM-TCR receiver complexity of 224

$$C(t) = (2Nr+1)\left[\binom{N_tM}{2} + N_tM\right]t + (2Nr+1)N_tMB.$$
(12)

To complete this complexity discussion, in Fig. 1, we show the dis- 225 tribution of t as a function of the increasing threshold values of θ . It can 226 be seen that low numbers of candidate TPS searched t are obtained with 227 high probability, particularly in the cases of low MED thresholds θ . 228 While large complexity savings can be observed in the figure, it is 229 important to note that the complexity of SM-TCR is upper bounded by 230 that of SM-CR, since $t \leq D$. 231

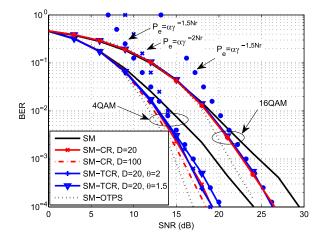


Fig. 2. BER versus SNR for a (4×2) -element MIMO with SM, SM-OTPS, SM-CR and SM-TCR, 4-QAM, and 16-QAM.

IV. SIMULATION RESULTS

233 To evaluate the benefits of the proposed technique, this section 234 presents numerical results based on Monte Carlo simulations of 235 conventional SM without scaling (termed as SM in the figures), 236 SM-CR, and the proposed SM-TCR. The channel's impulse response 237 is assumed to be perfectly known at the transmitter. Without loss of 238 generality, we assume that the transmit power is restricted to P = 1. 239 MIMO systems with four TAs employing 4-QAM and 16-QAM 240 modulation are explored, albeit it is plausible that the benefits of the 241 proposed technique extend to larger-scale systems and higher-order 242 modulation.

First, we characterize the attainable BER performance with an 243 244 increasing transmit SNR for a (4 \times 2)-element MIMO employing 245 4-QAM and 16-QAM, for various values of the MED threshold θ in 246 Fig. 2. The performance of the highly complex TPS design in [21] 247 based on convex optimization, and termed SM-OTPS in the figure, is 248 also shown here for reference, where it can be seen that the proposed 249 SM-TCR, with orders-of-magnitude less complexity than SM-OTPS, 250 still performs within 1-2 dB from the optimization-based SM-OTPS. 251 The theoretical trends of (11) are also shown, where it can be seen that 252 they provide a close match for the high-SNR system behavior. It can 253 be seen that the slope of the BER curves increases with increasing θ , 254 which indicates an increase in transmit diversity order. Indeed, the 255 BER of SM-TCR is identical to that of SM-CR for $\theta = 2$ in the case of 256 4-QAM and $\theta = 1.5$ in the case of 16-QAM. In both cases, significant 257 complexity savings are obtained, as shown in the results that follow.

Fig. 3 shows the average computational complexity expressed in 259 terms of numbers of operations (NOPs) for SM-TCR with increasing 260 MED threshold values θ . The complexity of SM and SM-CR is also 261 depicted for reference. It can be seen that as the MED threshold 262 increases, the optimization becomes tighter, leading to complexity 263 close to that of the full SM-CR. For reduced values of θ , however, sig-264 nificant complexity gains are obtained, where the NOPs for SM-TCR 265 are down to less than 55% of those for SM-CR for 4-QAM and 40% 266 for 16-QAM, respectively. A similar trend can be observed in Fig. 4, 267 where the performance is shown for increasing θ , where performance 268 is quantified in terms of goodput in bits per frame, i.e.,

$$T = \log_2(N_t M) \cdot F(1 - P_F) \tag{13}$$

269 with P_F denoting the frame error probability and F = 70 being 270 the frame length used in these results, following [19]. The specific 271 selection of the MED threshold θ in practice can be based on the

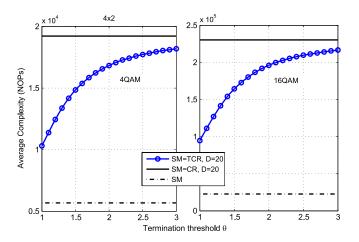


Fig. 3. Average complexity versus θ for a (4 \times 2)-element MIMO with SM-TCR, 4-QAM, and 16-QAM.

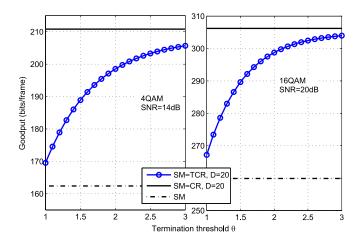


Fig. 4. Goodput versus θ for a (4 × 2)-element MIMO with SM-TCR, 4-QAM, and 16-QAM.

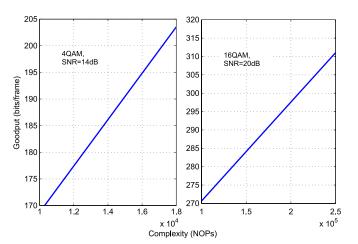


Fig. 5. Goodput versus average complexity for a (4×2) -element MIMO with SM-TCR, 4-QAM, and 16-QAM.

desired tradeoff between the complexity in Fig. 3 and (12), the transmit 272 diversity obtained, and the performance observed in Fig. 4 and (10) and 273 (11). Finally, Fig. 5 shows the direct performance-versus-complexity 274 tradeoff. A linear relation between goodput and complexity can be 275

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276 observed. More importantly, where previously either a low-complexity 277 unit-diversity SM or a high-complexity high-diversity SM-CR alter-278 native could be chosen, here, a scalable tradeoff is offered between 279 these two extremes with the aid of SM-TCR, by selecting the MED 280 thresholds θ accordingly.

V. CONCLUSION

A new low-complexity constellation shaping approach has been introduced for SM. While conventional CR offers a considerable transmit diversity gain at the cost of increased computational complexity compared with the conventional SM, the proposed scheme delivers a scalable tradeoff between the transmit diversity obtained are and the complexity by appropriately selecting the MED threshold was demonstrated, while still considerably improving the attainable performance of conventional SM.

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AQ1 = Please provide publication update in Ref. [2]. AQ2 = Please provide publication update in Ref. [8]. AQ3 = Please provide publication update in Ref. [19].

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A Scalable Performance–Complexity Tradeoff for Constellation Randomization in Spatial Modulation

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5 Abstract—It is widely recognized that traditional single radio frequency 6 (RF)-chain-aided spatial modulation (SM) does not offer any transmit 7 diversity gain. As a remedy, constellation randomization (CR), relying on 8 transmit prescaling (TPS), has been shown to provide transmit diversity 9 for single-RF-chain-aided SM. In this paper, we propose a low-complexity 10 approach to SM with the aid of constellation randomization (SM-CR) that 11 considerably improves the transmit diversity gain of SM at a reduced 12 computational burden compared with conventional SM-CR. While con-13 ventional SM-CR performs a full search among a set of candidate TPS 14 factors to achieve the maximum minimum Euclidean distance (MED) in 15 the received SM constellation, here, we propose a thresholding approach, 16 where, instead of the maximum MED, the TPS aims to satisfy a specific 17 MED threshold. This technique offers a significant complexity reduction 18 with respect to the full maximization of SM-CR, since the search for TPS 19 is terminated once a TPS set is found that satisfies the MED threshold. Our 20 analysis and results demonstrate that a scalable tradeoff can be achieved 21 between transmit diversity and complexity by appropriately selecting the 22 MED threshold, where a significant complexity reduction is attained, while 23 achieving a beneficial transmit diversity gain for the single-RF SM.

24 *Index Terms*—Constellation shaping, multiple-input single-output, 25 spatial modulation (SM), transmit prescaling (TPS).

I. INTRODUCTION

27 Spatial modulation (SM) has been shown to offer a low-complexity 28 design alternative to spatial multiplexing, where only a subset (down 29 to one) of radio frequency (RF) chains is required for transmission 30 [1], [2]. Early work has focused on the design of receiver algorithms 31 for minimizing the bit error ratio of SM at low complexity [1]–[5]. 32 Matched filtering is shown to be a low-complexity technique for 33 detecting the activated antenna index (AI) [1]–[3]. A maximum like-34 lihood (ML) detector is introduced in [4] for reducing the complexity 35 of classic spatial multiplexing ML detectors, whereas the complexity 36 imposed can be further reduced by compressive sensing detection 37 approaches [5]. In addition to receive processing, several transmit 38 precoding (TPC) approaches have been proposed for receive antenna 39 (RA)-aided SM, where the spatial information is mapped onto the RA 40 index [6]–[8].

41 Relevant work has also proposed constellation shaping for SM 42 [9]–[14]. Specifically, in [9], the transmit diversity of coded SM

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is analyzed for different *spatial constellations*, which represent the 43 legitimate sets of activated transmit antennas (TAs). Furthermore, 44 Yang *et al.* in [10] conceived a symbol constellation optimization 45 technique for minimizing the bit error rate (BER). Indeed, spatial and 46 symbol constellation shaping are discussed separately in the afore- 47 mentioned reference. By contrast, the design of the received SM con- 48 stellation that combines the choice of the TA as well as the transmit 49 symbol constellation is the focus of this paper. A number of con- 50 stellation shaping schemes [11]–[14] have also been proposed for the 51 special case of SM, which is referred to as space shift keying, where the 52 information is purely carried in the spatial domain, by the activated AI. 53 However, the application of the above constellation shaping to the SM 54 transmission, where the transmit waveform is modulated, is nontrivial. 55

Recent work has focused on shaping the receive SM constellation by 56 means of symbol prescaling at the transmitter, aiming for maximizing 57 the minimum Euclidean distance (MED) in the received SM constel- 58 lation [15]–[17]. The constellation shaping approach in [15] and [16] 59 aims at fitting the receive SM constellation to one of the existing opti- 60 mal classic constellation formats in terms of minimum distance, such 61 as, e.g., quadrature amplitude modulation (QAM). Due to the strict 62 constellation fitting requirement imposed on both amplitude and phase, 63 this prescaling relies on the inversion of the channel coefficients. In the 64 case of ill-conditioned channels, this substantially reduces the received 65 signal-to-noise ratio (SNR). This problem has been alleviated in [17], 66 where a constellation shaping scheme based on phase-only scaling is 67 proposed. Still, the constellation shaping used in the above schemes is 68 limited in the sense that it only applies to multiple-input-single-output 69 systems, where a single symbol is received for each transmission, and 70 thus, the characterization and shaping of the receive SM constellation 71 is simple. 72

Closely related to this work, a transmit prescaling (TPS) scheme 73 was proposed for SM [19], where the received SM constellation is 74 randomized by TPS for maximizing the MED between its points for a 75 given channel. A number of randomly generated candidate sets of TPS 76 factors are formed offline, known to both the transmitter and the re- 77 ceiver, and the transmitter then selects that particular set of TPS factors 78 that yields the SM constellation having the maximum MED. Against 79 this background, in this paper, we propose a low-complexity relaxation 80 of the above optimization instead of an exhaustive search, where the 81 first TPS factor set that is found to satisfy a predetermined threshold is 82 selected, thus reducing the computational burden of the TPS operation. 83 The proposed scheme is shown to provide a scalable tradeoff between 84 the performance attained and the complexity imposed, by accordingly 85 selecting the MED threshold.

This paper is organized as follows: In Section II, the basic system 87 model is first introduced, and the proposed scheme is then discussed. 88 The computational complexity of the proposed technique is analyzed 89 in Section III, and its performance against the state of the art is 90 evaluated in Section IV. Finally, in Section V, we draw the key 91 conclusions of our study. 92

II. SPATIAL MODULATION WITH THRESHOLD CONSTELLATION 93 RANDOMIZATION (SM-TCR) 94

Consider a multiple-input multiple-output (MIMO) system, where 95 the transmitter and the receiver are equipped with N_t and N_r antennas, 96

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97 respectively. For simplicity, unless stated otherwise, in this paper, we 98 assume that the transmit power budget is limited to unity, i.e., P = 1. 99 We focus on the single-RF-chain-aided SM approach, where the trans-100 mit vector is in the all-but-one zero form $\mathbf{s}_m^k = [0, \ldots, s_m, \ldots, 0]^T$, 101 with $[.]^T$ denoting the transpose operator. Here, $s_m, m \in \{1, \ldots, M\}$ 102 is a symbol taken from an *M*-order modulation alphabet that rep-103 resents the transmitted waveform in the baseband domain conveying 104 $\log_2(M)$ bits, whereas k represents the index of the activated TA (the 105 index of the nonzero element in \mathbf{s}_m^k) conveying $\log_2(N_t)$ bits in the 106 spatial domain. Clearly, since s is an all-zero vector apart from s_m^k , 107 there is no interantenna interference.

For the per-antenna TPS approach, which is the focus of this paper, 109 the signal fed to each TA is scaled by a complex-valued coefficient 110 $\alpha_k, k \in \{1, \ldots, N_t\}$ for which we have $E\{|\alpha_k|\} = 1$, where |x|111 denotes the amplitude of a complex number x, and $E\{.\}$ denotes the 112 expectation operator. Defining the MIMO channel vector as **H** with 113 elements $h_{m,n}$ representing the complex-valued channel coefficient 114 between the *n*th TA and the *m*th RA, the received symbol vector can 115 be written as

$$\mathbf{y} = \mathbf{H}\mathbf{A}\mathbf{s}_m^k + \mathbf{w} \tag{1}$$

116 where $\mathbf{w} \sim C\mathcal{N}(0, \sigma^2 \mathbf{I})$ is the additive white Gaussian noise com-117 ponent at the receiver, with $C\mathcal{N}(\mu, \sigma^2)$ denoting the circularly 118 symmetric complex Gaussian distribution with a mean of μ and a 119 variance of σ^2 . Furthermore, $\mathbf{A} = \text{diag}(\mathbf{a})$ is the TPS matrix with 120 $\mathbf{a} = [\alpha_1, \alpha_2, \dots, \alpha_{N_t}]$, and $\text{diag}(\mathbf{g})$ represents the diagonal matrix 121 with its diagonal elements taken from vector \mathbf{g} . Note that the diagonal 122 structure of \mathbf{A} guarantees having a transmit vector $\mathbf{x} = \mathbf{As}$ with a 123 single nonzero element, so that the single-RF-chain aspect of SM is 124 preserved.

125 At the receiver, a joint ML detection of both the TA index and the 126 transmit symbol is obtained by the minimization, i.e.,

$$\begin{aligned} [\hat{s}_m, \hat{k}] &= \arg\min_i \|\mathbf{y} - \dot{\mathbf{y}}_i\| \\ &= \arg\min_{m,k} \|\mathbf{y} - \mathbf{HAs}_m^k\| \end{aligned}$$
(2)

127 where $\|\mathbf{x}\|$ denotes the norm of vector \mathbf{x} , and $\dot{\mathbf{y}}_i$ is the *i*th constellation 128 point in the received SM constellation. By exploiting the specific 129 structure of the transmit vector, this can be further simplified to

$$[\hat{s}_m, \hat{k}] = \arg\min_{m,k} \|\mathbf{y} - \mathbf{h}_k \alpha_m^k s_m\|$$
(3)

130 where \mathbf{h}_k denotes the *k*th column of matrix **H**. It is widely recognized 131 that the performance of the detection as formulated above is dominated 132 by the MED between the adjacent constellation points $\dot{\mathbf{y}}_i$ and $\dot{\mathbf{y}}_j$ in the 133 receive SM constellation, i.e.,

$$d_{\min} = \min_{i,j} \|\dot{\mathbf{y}}_i - \dot{\mathbf{y}}_j\|^2, \ i \neq j.$$
(4)

Accordingly, to improve the likelihood of correct detection, con-135 stellation shaping TPS schemes conceived for SM aim at maximizing 136 this MED. The optimum TPS matrix A^* can be found by solving the 137 optimization problem of [20]

$$\mathbf{A}^{*} = \arg \max_{\mathbf{A}} \min_{i,j} \|\dot{\mathbf{y}}_{i} - \dot{\mathbf{y}}_{j}\|^{2}, \ i \neq j$$
(5)
s.t.c.
$$\operatorname{trace}(\mathbf{A}^{*H}\mathbf{A}^{*}) \leq P$$

138 and, additionally for single-RF-chain-aided SM, subject to \mathbf{A}^* having 139 a diagonal structure. In the above, \mathbf{A}^H and trace(\mathbf{A}) represent the 140 Hermitian transpose and trace of matrix \mathbf{A} , respectively. The above 141 optimization, however, is an NP-hard problem, which makes finding the TPS factors prohibitively complex and motivates the conception 142 of lower-complexity suboptimal techniques. Indeed, it has been shown 143 that the TPS approach in [19], by selecting among a set of predeter- 144 mined randomly generated TPS vectors instead of fully optimizing the 145 TPS, offers a near-optimal performance with the lowest complexity 146 among the TPS optimization approaches [20], [21]. 147

TPS Vector Generation: Accordingly, with SM-TCR first, a number 148 of D random candidate TPS vectors are generated, in the form of \mathbf{a}_d , 149 where $d \in [1, D]$ denotes the index of the candidate set, and \mathbf{a}_d is 150 formed by the elements $\alpha_m^{k(d)} \sim C\mathcal{N}(0, 1)$. To ensure that the average 151 transmit power remains unchanged, the scaling factors are normalized 152 to unit power. These are made available to both the transmitter and the 153 receiver before transmission. These assist in randomizing the received 154 constellation, which is most useful in the critical scenarios where two 155 points in the constellation of $\mathbf{Hs}_m^k, m \in [1, M], k \in [1, N_t]$ happen to 156 be very close.

A. Thresholded Selection of TPS 158

For a given channel, based on knowledge of vectors \mathbf{a}_d , both the 159 transmitter and the receiver can determine the received SM constel- 160 lation for the *d*th TPS set by calculating the legitimate set of [m, k] 161 combinations in 162

$$\hat{\mathbf{y}} = \mathbf{H} \mathbf{A}_d \mathbf{s}_m^k \tag{6}$$

where $\mathbf{A}_d = \operatorname{diag}(\mathbf{a}_d)$ is the diagonal matrix that corresponds to 163 the candidate set \mathbf{a}_d . Then, for the given channel coefficients, the 164 transmitter and the receiver can choose independently the scaling 165 vector \mathbf{a}_o . Alternatively, if no channel state information is available 166 at the transmitter (receiver), the receiver (transmitter) can inform the 167 transmitter (receiver) concerning the optimum \mathbf{a}_o by transmitting a 168 number of $\lceil \log_2(D) \rceil$ bits. Contrary to the SM-CR in [19], where the 169 maximum MED among all *D* possibilities is chosen, here, a threshold- 170 based approach is introduced, where the search for TPS is terminated 171 when a candidate TPS is found that satisfies a MED threshold. This 172 optimization problem can be expressed as 173

$$\mathbf{A}_{o} = \begin{cases} \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{p}\}\neq\\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\}\\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \theta \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{l},k_{p}\}}} \|\mathbf{H}\mathbf{s}_{m_{1}}^{k_{1}} - \mathbf{H}\mathbf{s}_{m_{2}}^{k_{2}}\|^{2} \\ & \sup_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{l},k_{p}\}}} \|\mathbf{H}\mathbf{A}_{d}\mathbf{s}_{m_{1}}^{k_{1}} - \mathbf{H}\mathbf{A}_{d}\mathbf{s}_{m_{2}}^{k_{2}}\|^{2}, \text{ otherwise} \end{cases}$$

$$(7)$$

where θ represents the MED threshold with respect to the MED 174 without TPS. Equivalently, for the case of single-RF-chain-based SM, 175 this can be simplified to 176

$$\mathbf{A}_{o} = \begin{cases} \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{i},k_{j}\}\neq\\ \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ \mathbf{A}_{t}, \text{if} \exists \mathbf{A}_{t} : & \{m_{l},k_{p}\} \\ arg \max_{d} & \min_{\substack{\{m_{i},k_{j}\}\neq\\\{m_{l},k_{p}\}\\\{m_{l},k_{p}\}}} \| \mathbf{h}_{k_{1}}a_{m_{1}}^{k_{1}}s_{m_{1}} - \mathbf{h}_{k_{2}}a_{m_{2}}^{k_{2}}s_{m_{2}} \|^{2}, \text{otherwise} \end{cases}$$

In other words, the search stops if a TPS set is found that satisfies 177 the threshold; otherwise, the TPS that offers the maximum MED is 178 returned, following a full search as in SM-CR. For completeness, 179 we present the associated algorithm in Table I. It will be shown that 180 this process offers significant computational benefits with respect to 181 full SM-CR. 182

TABLE I Algorithm SM-TCR

$\overline{\mathbf{Input}:\mathbf{H},M,\mathbf{Output}:\mathbf{A}_{o}}$
e = []
for $t=1$ to D do
$\mathbf{e}[t] := \min_{\{m_i, k_j\} \neq \{m_l, k_p\}} \mathbf{H} \mathbf{A}_t \mathbf{s}_{m_1}^{k_1} - \mathbf{H} \mathbf{A}_t \mathbf{s}_{m_2}^{k_2} ^2$
% calculate the MED for the <i>t</i> -th TSP vector
if $\mathbf{e}[t] \geq heta \min_{\{m_i,k_j\} eq \{m_i,k_p\}} \mathbf{Hs}_{m_1}^{k_1} - \mathbf{Hs}_{m_2}^{k_2} ^2$
% check if the MED satisfies the MED threshold θ
$\mathbf{A}_o := \mathbf{A}_t$
% if so, select \mathbf{A}_t and terminate the algorithm
break
end
end
$t_o = \arg \max_t \mathbf{e}$
% if not, select the TPS vector with the max MED
$\mathbf{A}_{o} := \mathbf{A}_{t_{o}}$

183 Based on (8), the transmitter sends $\mathbf{x} = \mathbf{A}_o \mathbf{s}_m^k$, and the receiver 184 applies the ML detector according to

$$[\hat{s}_m, \hat{k}] = \arg\min_{m,k} \|\mathbf{y} - \mathbf{H}\mathbf{A}_o \mathbf{s}_m^k\|.$$
(9)

It should be noted that, to dispense with the need for channel state 186 information at the transmitter (CSIT), the receiver can select the best 187 scaling factors using (8) and then feed the index of the scaling matrix 188 \mathbf{A}_o selected from the set of D candidates back to the transmitter, 189 using $\lfloor \log_2(D) \rfloor$ bits. This constitutes major overhead savings for the 190 proposed scheme with respect to the existing TPS schemes for SM that 191 require full CSIT, while obtaining similar performance.

192 B. Transmit Diversity and Performance Trends

193 While the transmit diversity order of the single-RF SM is known to 194 be one [9], the proposed TPS introduces an amplitude-phase diversity 195 in the transmission, which is an explicit benefit of having D candidate 196 sets of TPS factors to choose from. Accordingly, it was shown in 197 [19] that the obtained transmit diversity order corresponds to the 198 θ -dependent gain in the average MED associated with CR as

$$G(\theta) = \frac{E\{\min_{m,k} \| \mathbf{H} \mathbf{A}_o \mathbf{s}_{m_1}^{k_1} - \mathbf{H} \mathbf{A}_o \mathbf{s}_{m_2}^{k_2} \|^2\}}{E\{\min_{m,k} \| \mathbf{H} \mathbf{s}_{m_1}^{k_1} - \mathbf{H} \mathbf{s}_{m_2}^{k_2} \|^2\}}.$$
 (10)

199 In addition, SM systems with N_r uncorrelated RAs have been 200 shown to experience a unity transmit diversity order and a receive 201 diversity order of N_r . Accordingly, since the proposed scheme attains 202 a θ -dependent transmit diversity order of $G(\theta)$, the total diversity order 203 becomes $\delta = N_r G(\theta)$. The resulting probability of error P_e obeys the 204 high-SNR trend of

$$P_e = \alpha \gamma^{-N_r G(\theta)} \tag{11}$$

205 where γ is the transmit SNR, and α is an arbitrary nonnegative 206 coefficient. We verify the above theoretical performance trend against 207 simulation in the following.

208 III. COMPUTATIONAL COMPLEXITY

It is clear from the above discussion that the proposed SM-TCR 210 leads to a computational complexity reduction with respect to con-211 ventional SM-CR, due to the early termination of the TPS search, 212 after a calculation of $t \leq D$ out of D TPS sets. Here, we analyze this 213 computational complexity reduction at the receiver. This analysis is

 TABLE II

 COMPLEXITY FOR THE PROPOSED SM-TCR SCHEME

SM-TCR	Operations	
Constellation Optimization		
$\mathbf{HA}_{d}\mathbf{s}_{m}^{k},\forall m,k \qquad \qquad \times t$	$(2N_r+1)N_tMt$	
$ \begin{aligned} \mathbf{f}_{m_1,m_2}^{k_1,k_2(d)} &= \mathbf{H}\mathbf{A}_d \mathbf{s}_{m_1}^{k_1} - \mathbf{H}\mathbf{A}_d \mathbf{s}_{m_2}^{k_2} , \times t \\ \forall m_1,m_2,k_1,k_2,m_1 \neq m_2, k_1 \neq k_2 \end{aligned} $	$2N_r {N_t M \choose 2} t$	
$ \begin{array}{c} \text{check:} \\ \min\{\mathbf{f}_{m_{1},m_{2}}^{k_{1},k_{2}(d)}\} \geq \\ \theta \min_{\{m_{i},k_{j}\} \neq} \mathbf{Hs}_{m_{1}}^{k_{1}} - \mathbf{Hs}_{m_{2}}^{k_{2}} ^{2} \times t \\ \{m_{l},k_{p}\} \end{array} $	$\binom{N_t M}{2} t$	
ML Detection		
$g_m^k = \mathbf{y} - \mathbf{H}\mathbf{A}_o \mathbf{s}_m^k ^2, \forall m, k \qquad \times B$	$2N_tMN_rB$	
$\arg\min g_m^k$ ×B	N_tMB	
Total: $(2Nr+1)\left[\binom{N_tM}{2}+N_tM\right]t+($	$2N_r + 1)N_tMB$	

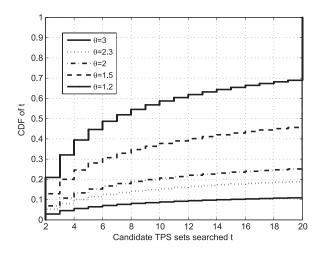


Fig. 1. Cumulative distribution function of the number of candidate TPS searched (t) for various values of θ , D = 20, 4-QAM.

complemented by the following results on the distribution of t. For ref- 214 erence, we have assumed a Long-Term Evolution Type-2 time-division 215 duplex frame structure [18]. This has 10-ms duration that consists of 216 ten subframes out of which five subframes, each containing 14 symbol 217 time slots, are used for downlink transmission, yielding a frame size of 218 F = 70 for the downlink, whereas the rest are used for both uplink and 219 control information transmission. A slow-fading channel is assumed, 220 where the channel remains constant for the duration of the frame. 221

Following the complexity analysis in [19], we quantify the number 222 of operations required in each step of the SM-TCR search in Table II. 223 From the table, we have a total SM-TCR receiver complexity of 224

$$C(t) = (2Nr+1)\left[\binom{N_tM}{2} + N_tM\right]t + (2Nr+1)N_tMB.$$
(12)

To complete this complexity discussion, in Fig. 1, we show the dis- 225 tribution of t as a function of the increasing threshold values of θ . It can 226 be seen that low numbers of candidate TPS searched t are obtained with 227 high probability, particularly in the cases of low MED thresholds θ . 228 While large complexity savings can be observed in the figure, it is 229 important to note that the complexity of SM-TCR is upper bounded by 230 that of SM-CR, since $t \leq D$. 231

10 -1.5Nr $=\alpha \gamma$ -2Nr 10 16QAM 监 10 4QAM SM SM-CR D=20 10 SM-CR, D=100 SM-TCR, D=20, 0=2 SM-TCR, D=20, 0=1.5 SM-OTPS 10 0 5 10 15 20 25 30 SNR (dB)

Fig. 2. BER versus SNR for a (4 \times 2)-element MIMO with SM, SM-OTPS, SM-CR and SM-TCR, 4-QAM, and 16-QAM.

IV. SIMULATION RESULTS

233 To evaluate the benefits of the proposed technique, this section 234 presents numerical results based on Monte Carlo simulations of 235 conventional SM without scaling (termed as SM in the figures), 236 SM-CR, and the proposed SM-TCR. The channel's impulse response 237 is assumed to be perfectly known at the transmitter. Without loss of 238 generality, we assume that the transmit power is restricted to P = 1. 239 MIMO systems with four TAs employing 4-QAM and 16-QAM 240 modulation are explored, albeit it is plausible that the benefits of the 241 proposed technique extend to larger-scale systems and higher-order 242 modulation.

First, we characterize the attainable BER performance with an 243 244 increasing transmit SNR for a (4 \times 2)-element MIMO employing 245 4-QAM and 16-QAM, for various values of the MED threshold θ in 246 Fig. 2. The performance of the highly complex TPS design in [21] 247 based on convex optimization, and termed SM-OTPS in the figure, is 248 also shown here for reference, where it can be seen that the proposed 249 SM-TCR, with orders-of-magnitude less complexity than SM-OTPS, 250 still performs within 1-2 dB from the optimization-based SM-OTPS. 251 The theoretical trends of (11) are also shown, where it can be seen that 252 they provide a close match for the high-SNR system behavior. It can 253 be seen that the slope of the BER curves increases with increasing θ , 254 which indicates an increase in transmit diversity order. Indeed, the 255 BER of SM-TCR is identical to that of SM-CR for $\theta = 2$ in the case of 256 4-QAM and $\theta = 1.5$ in the case of 16-QAM. In both cases, significant 257 complexity savings are obtained, as shown in the results that follow.

258 Fig. 3 shows the average computational complexity expressed in 259 terms of numbers of operations (NOPs) for SM-TCR with increasing 260 MED threshold values θ. The complexity of SM and SM-CR is also 261 depicted for reference. It can be seen that as the MED threshold 262 increases, the optimization becomes tighter, leading to complexity 263 close to that of the full SM-CR. For reduced values of θ, however, sig-264 nificant complexity gains are obtained, where the NOPs for SM-TCR 265 are down to less than 55% of those for SM-CR for 4-QAM and 40% 266 for 16-QAM, respectively. A similar trend can be observed in Fig. 4, 267 where the performance is shown for increasing θ, where performance 268 is quantified in terms of goodput in bits per frame, i.e.,

$$T = \log_2(N_t M) \cdot F(1 - P_F) \tag{13}$$

269 with P_F denoting the frame error probability and F = 70 being 270 the frame length used in these results, following [19]. The specific 271 selection of the MED threshold θ in practice can be based on the

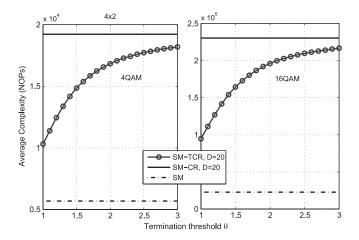


Fig. 3. Average complexity versus θ for a (4 \times 2)-element MIMO with SM-TCR, 4-QAM, and 16-QAM.

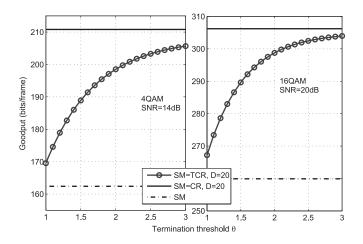


Fig. 4. Goodput versus θ for a (4 × 2)-element MIMO with SM-TCR, 4-QAM, and 16-QAM.

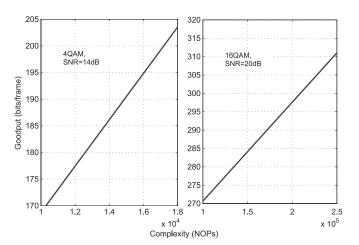


Fig. 5. Goodput versus average complexity for a (4 \times 2)-element MIMO with SM-TCR, 4-QAM, and 16-QAM.

desired tradeoff between the complexity in Fig. 3 and (12), the transmit 272 diversity obtained, and the performance observed in Fig. 4 and (10) and 273 (11). Finally, Fig. 5 shows the direct performance-versus-complexity 274 tradeoff. A linear relation between goodput and complexity can be 275

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276 observed. More importantly, where previously either a low-complexity 277 unit-diversity SM or a high-complexity high-diversity SM-CR alter-278 native could be chosen, here, a scalable tradeoff is offered between 279 these two extremes with the aid of SM-TCR, by selecting the MED 280 thresholds θ accordingly.

V. CONCLUSION

A new low-complexity constellation shaping approach has been introduced for SM. While conventional CR offers a considerable transmit diversity gain at the cost of increased computational comsplexity compared with the conventional SM, the proposed scheme can be a scalable tradeoff between the transmit diversity obtained are and the complexity by appropriately selecting the MED threshold was demonstrated, while still considerably improving the attainable performance of conventional SM.

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AQ1 = Please provide publication update in Ref. [2].

AQ2 = Please provide publication update in Ref. [8].

AQ3 = Please provide publication update in Ref. [19].

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