

Prediction of jet mixing noise with Lighthill's Acoustic Analogy and geometrical acoustics

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A computational aeroacoustics prediction tool based on the application of Lighthill's theory is presented to compute noise from subsonic turbulent jets. The sources of sound are modeled by expressing Lighthill's source term as two-point correlations of the velocity fluctuations and the sound refraction effects are taken into account by a ray tracing methodology. Both the source and refraction models use the flow information collected from a solution of the Reynolds-Averaged Navier-Stokes equations with a standard k -epsilon turbulence model. By adopting the ray tracing method to compute the refraction effects a high-frequency approximation is implied, while no assumption about the mean flow is needed, enabling the authors to apply the new method to jet noise problems with inherently three-dimensional propagation effects. Predictions show good agreement with narrowband measurements for the overall sound pressure levels and spectrum shape in polar angles between 60° and 110° for isothermal and hot jets with acoustic Mach number ranging from 0.5 to 1.0. The method presented herein can be applied as a relatively low cost and robust engineering tool for industrial optimization purposes. © 2017 Acoustical Society of America.

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I. INTRODUCTION

Despite great reductions of aircraft noise achieved in the past few decades, the current trend of continuous growth of air traffic worldwide will demand further reduction of noise emission by civil and military aircraft. Due to the inherent complexity of aerodynamic noise generation and propagation phenomena, industrial and academic efforts have been focused on the development of reliable and computationally low-cost noise prediction tools for the aircraft design process. Jet mixing noise is one among the dominant sources of aircraft noise, being more pronounced at take-off condition. As the jet mixing noise has been greatly reduced by increasing the bypass ratio of dual-stream-jet engines, further jet mixing noise reductions are likely to rely on modifications of the nozzle geometry that may result in the use of non-axisymmetric nozzles and therefore very complex three-dimensional flows. For instance, it has been verified both experimentally^{1–3} and computationally⁴ that the use of chevron nozzles and non-concentric dual-stream nozzles can lead to jet mixing noise reduction.

The development of numerical prediction methods for jet noise is perhaps one of the oldest areas of aeroacoustics. Methods ranging from empirical database⁵ to high-fidelity

and computationally expensive methods^{6–8} have been considered over the past few decades. Nevertheless, a cheap, fast, and reliable numerical method that provides an accurate prediction is still needed to help the optimization process in an industrial context. The hybrid numerical methodology based on a Reynolds Averaged Navier-Stokes (RANS) solution of the flow presented in this paper is seen as an alternative method to fulfill this requirement.

An early application of such hybrid methodology to compute jet mixing noise was presented by Balsa and Glike⁹ and Balsa *et al.*,¹⁰ who used analytical profiles to describe the mean flow and model the source term of the equation presented by Lilley.¹¹ The approach was later extended by Khavaran *et al.*¹² and Khavaran and Krejsa¹³ to use a numerical RANS $k - \epsilon$ solution of the mean flow into the so-called MGBK (Mani, Glike, Balsa, and Khavaran) method; thus consolidating the use of a RANS $k - \epsilon$ and an acoustic analogy to model jet mixing noise.

The idea was further explored by Tam and Auriault,¹⁴ who modeled the sound sources via an analogy with the kinetic theory of gases. They added the proposed source term to an adjoint formulation of the Linearized Euler Equations, therefore departing from the use of an acoustic analogy; their predictions of far-field sound pressure level (SPL) showed good agreement with measurements. Morris and Farassat¹⁵ showed that although not explicitly an

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75 acoustic analogy, Tam and Auriault's method is akin to what
 76 can be derived from an acoustic analogy, and showed that
 77 the improvements by Tam and Auriault's method was the
 78 better description of the turbulence statistics relevant for the
 79 description of the sources of sound.

80 Self¹⁶ followed by proposing a model based on
 81 Lighthill's Acoustic Analogy (LAA) with an improved
 82 description of the relevant turbulence statistics based on
 83 empirical evidence by Harper-Bourne.¹⁷ The main improve-
 84 ment was the consideration of frequency-dependent time and
 85 length-scales when modeling velocity correlations present in
 86 LAA's source term. The proposed model resulted in good
 87 agreement with experimental data, notably with a better
 88 description of the decay at low and high frequencies when
 89 compared to the LAA-based method of Morris and
 90 Farassat.¹⁵ Self and Azarpeyvand^{18,19} and Azarpeyvand and
 91 Self²⁰ further developed the idea of frequency-dependent
 92 scales of velocity correlations by proposing a new time scale
 93 which was applied to the MGBK method.

94 In this paper a source model based on the LAA with the
 95 new time scale of Refs. 18–20 is presented. The resulting
 96 statistical source is shown to result in a good description the
 97 far-field spectrum at 90°. To overcome the shortcoming of
 98 LAA that ignores effects of propagation, a geometrical
 99 acoustics approximation is applied. The application of geo-
 100 metrical acoustics is not new in jets,^{21–23} but it is, to the
 101 authors best knowledge, for the first time coupled to a source
 102 model based on the LAA to predict jet mixing noise instead
 103 of just analyze aspects of it. Another way to compute the
 104 propagation effects is to solve the adjoint formulation of the
 105 linearized Euler equations using a finite difference method
 106 (FDM).²⁴ Using a FDM, however, increases the computa-
 107 tional cost of the overall prediction method as the FDM is
 108 expensive and known to generally require a mesh of higher
 109 quality (finer and structured) than the RANS mesh. The ray
 110 tracing method used in this paper, in contrast, needs only to
 111 interpolate the results from the RANS into a coarser mesh.
 112 The main objective of this paper is therefore to introduce
 113 and benchmark a novel hybrid aeroacoustics method that can
 114 be applied to predict the far-field noise from arbitrary three-
 115 dimensional jets. The method was created with the goal of
 116 providing the ability for both the analysis and the optimiza-
 117 tion of nozzles that would be compatible with novel configu-
 118 rations, yet requiring relatively low computational cost.

119 The remainder of the paper is organized as follows.
 120 Section II deals with the source and propagation models
 121 developed as part of this work. The experimental setup and
 122 solution of the mean flow are presented in Sec. III. Also in
 123 Sec. III the far-field noise predictions for jets at different
 124 Mach numbers and temperature ratios predicted using the
 125 new model will be compared against the available experi-
 126 mental data at different angles. Results will be presented for
 127 jet noise prediction at 90°, source distribution, flow factor,
 128 and jet noise directivity. Finally, Sec. IV concludes the paper.

129 **II. MATHEMATICAL MODEL**

130 The mathematical modeling of the new jet noise predic-
 131 tion tool is provided in this section. The far-field noise can

be predicted by coupling the source and propagation models,
 presented in Secs. II A and II B. The models are derived sep-
 arately, emphasizing the fact that they are completely inde-
 pendent and can be used in isolation.

A. Source model

The starting point of the source model is the Lighthill
 equation,²⁵ as presented by Ribner.²⁶ The far field spectrum
 can be written as

$$P(\mathbf{x}; \omega) = \frac{1}{(4\pi r)^2} \frac{1}{a_0^4} \bar{\rho}^2 D_f^{-5} d_{ijkl} \int \Phi \mathcal{F}[I_{ijkl}] d^3 \mathbf{y}, \quad (1)$$

where $r = |\mathbf{x}|$ is the distance to the far-field observer, and \mathbf{x}
 and \mathbf{y} are, respectively, the observer and source locations.
 The coordinate system (r, θ, φ) is shown in Fig. 1. In Eq.
 (1), a_0 is the reference speed of sound, $\bar{\rho}$ is the mean fluid
 density, D_f is the Doppler factor $(1 - M_c \cos \theta)$, d_{ijkl} is the
 tensor giving the quadrupolar directivity, Φ is the flow factor
 (introduced in the next section), \mathcal{F} denotes the Fourier trans-
 form, and I_{ijkl} represents the contribution from fourth-order
 velocity correlations.

The convective Mach number (M_c) is assumed to
 depend on the local Mach number (U_1/a) and the nozzle exit
 Mach number ($M = U/a_0$) and is given by¹²

$$M_c = \frac{1}{4} \left(\frac{U_1}{a} \right) + \frac{1}{3} M, \quad (2)$$

where U_1 is the local mean axial velocity, U the jet-exit
 velocity, and a the local mean sound speed.

The tensor I_{ijkl} represents the contribution of the fourth-
 order velocity correlation terms and is given by

$$I_{ijkl}(\tau) = \int \frac{\partial^4}{\partial \tau^4} \overline{v_i v_j v_k v_l} d^3 \xi, \quad (3)$$

where $v_i = U_i + u_i$ is the instantaneous velocity vector, the
 prime indicates that the property is evaluated at a different

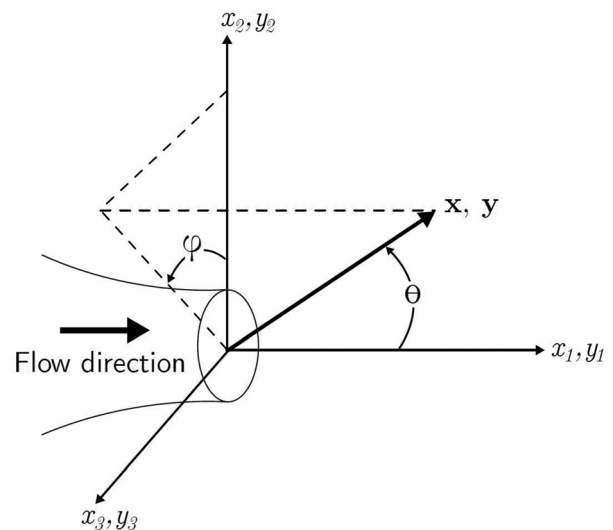


FIG. 1. Cartesian and spherical coordinate systems.

158 instant in time (separated by τ) and different location in
159 space (separated by $\xi \equiv \{\xi_1, \xi_2, \xi_3\}$).

160 Only the fluctuating velocities are considered as
161 efficient sources of mixing noise, so that Eq. (3) can be
162 written as

$$I_{ijkl}(\tau) = \int \frac{\partial^4}{\partial \tau^4} \overline{u_i u_j u'_k u'_l} d^3 \xi, \quad (4)$$

163 which is equivalent to the “self-noise” component as by
164 Ribner.²⁶

165 To model the cross-correlation in Eq. (4) some assump-
166 tion about turbulence is necessary. We consider that turbu-
167 lence is isotropic and locally homogeneous, so it follows a
168 normal joint probability between u_i and u'_j . Therefore
169 $\overline{u_i u_j u'_k u'_l}$ can be expressed in terms of second-order correla-
170 tions as^{26,27}

$$\overline{u_i u_j u'_k u'_l} = \overline{u_i u_j} \overline{u'_k u'_l} + \overline{u_i u'_k} \overline{u_j u'_l} + \overline{u_i u'_l} \overline{u_j u'_k}. \quad (5)$$

171 These second-order correlations can, in turn, be expressed in
172 terms of independent spatial and temporal correlation func-
173 tions as²⁶

$$\overline{u_i u'_j}(\xi, \tau) = R_{ij}(\xi)g(\tau). \quad (6)$$

174 Noting that $\partial^4 (\overline{u_i u_j} \overline{u'_k u'_l}) / \partial \tau^4 = 0$ as $\overline{u_i u_j}$ and $\overline{u'_k u'_l}$ are inde-
175 pendent of time separation (τ), and using Eqs. (5) and (6),
176 Eq. (4) can be rewritten as

$$I_{ijkl} = \frac{\partial^4 g^2}{\partial \tau^4} \int (R_{ik} R_{jl} + R_{il} R_{jk}) d^3 \xi. \quad (7)$$

177 Again invoking the assumption of isotropic and locally
178 homogeneous turbulence, the spatial correlation term, R_{ij} ,
179 takes the form²⁷

$$R_{ij} = \overline{u_i^2} \left[\left(f + \frac{1}{2} |\xi| f' \right) \delta_{ij} - \frac{1}{2} f' \frac{\xi_i \xi_j}{|\xi|} \right], \quad (8)$$

180 where f is a function of the separation vector ξ , and
181 $f' = df/d\xi$. Among different possibilities,²⁶ f is assumed
182 here to take a Gaussian distribution form

$$f(\xi) = \exp\left(-\pi \frac{\xi^2}{L^2}\right), \quad (9)$$

183 where L is the length-scale at the source location.

184 With the substitution of Eqs. (8) and (9) in Eq. (7) and
185 performing the integral over the source region (ξ), the term
186 I_{ijkl} reduces to

$$I(\tau) = \frac{\rho^2}{2\sqrt{2}} k^2 L^3 \frac{\partial^4 g^2(\tau)}{\partial \tau^4}, \quad (10)$$

187 where k is the local mean turbulent kinetic energy.

188 Here the directivity index $ijkl$ is dropped to emphasize
189 that the source is isotropic due to the assumption of isotropic
190 turbulence. Thus the far-field directivity is modeled by the

convective amplification given by D_f^{-5} and refraction (pre-
sented in Sec. II B).

It is assumed that the temporal correlation function, g ,
also takes a Gaussian distribution form, as

$$g(\tau) = \exp(-\tau^2/\tau_0^2), \quad (11)$$

where τ_0 is the time scale at the source location. Taking the
Fourier transform of $\partial^4 g^2 / \partial \tau^4$ in Eq. (10) leads to

$$I(\Omega) = \frac{\sqrt{\pi}}{4} k^2 L^3 \tau_0 \Omega^4 \frac{\sqrt{2\pi}}{2} \exp\left(-\frac{\tau_0^2 \Omega^2}{8}\right), \quad (12)$$

where Ω is the modified frequency

$$\Omega = \omega \sqrt{(1 - M_c \cos \theta)^2 + (\alpha k^{1/2}/a_0)^2}, \quad (13)$$

where α is an experimental parameter with value of 0.5.¹²

The length-scale L can be calculated using parameters
obtained from a RANS $k - \varepsilon$ simulation as^{12,28}

$$L = c_\ell \frac{k^{3/2}}{\varepsilon}, \quad (14)$$

where c_ℓ is an empirical constant and ε is the turbulent dissi-
pation rate. The time scale τ_0 takes the form

$$\tau_0 = c_\tau \frac{k}{\varepsilon}, \quad (15)$$

where c_τ is an empirical constant.

Rewriting the length-scale in terms of the time scale Eq.
(12) takes the form

$$I(\Omega) = \frac{\sqrt{\pi}}{4} \frac{c_\ell^3}{c_\tau^3} k^{7/2} \rho^2 \tau_0^4 \Omega^4 \exp\left(-\frac{\tau_0^2 \Omega^2}{8}\right), \quad (16)$$

which gives the spectrum of the source emitting from a sin-
gle correlated volume of turbulence in the jet. Note that the
coefficient c_τ is in the definition of the time scale τ_0 ; so even
if the term c_ℓ^3/c_τ^3 were combined as a single coefficient, c_τ
would still be needed for τ_0 .

In Refs. 18–20 a new time scale was proposed, which is
shown to better describe the energy transfer process related
to the jet noise generation process. The new time scale is
given by

$$\tau_0^* = \tau_0 \left(\frac{L}{D}\right)^{2/3}, \quad (17)$$

where D is the nozzle diameter. Replacing τ_0 with τ_0^* in Eq.
(16) and inserting the result in Eq. (1) yields

$$P(\mathbf{x}; \omega) = \frac{1}{64\pi^{3/2}} \frac{1}{r^2 a_0^4} \frac{c_\ell^3}{c_\tau^3} \int \Phi(\mathbf{x}|\mathbf{y}) D_f^{-5} \bar{\rho}^2 k^{7/2} \\ \times \tau_0^{*4} \Omega^4 \exp\left(-\frac{\Omega^2 \tau_0^{*2}}{8}\right) d^3 \mathbf{y}. \quad (18)$$

In Sec. II B the ray tracing solution of the sound propa-
gation through the jet flow is presented and the associated
flow factor, Φ , is introduced.

220 **B. Propagation model**

221 A major drawback of LAA is that the refraction of
 222 sound by the mean flow is difficult to be accounted for
 223 because of the assumptions needed to describe the source
 224 term. Therefore alternative methods, for instance, through
 225 the definitions of the “Flow Factor” using the asymptotic
 226 solution of Lilley’s equation, are necessary to model the
 227 effect of the mean flow. In this paper, we tackle this problem
 228 by introducing a Flow Factor parameter to take into account
 229 the sound-flow refraction phenomenon using a high-
 230 frequency approximation of sound propagation in non-
 231 uniform media by geometrical acoustics. The derivation of
 232 the ray tracing equations presented in this section follows
 233 the description of Pierce.³⁰ The obvious advantage of the
 234 proposed technique to Lilley’s asymptotic solution is its ver-
 235 satility and the possibility of using the new method for com-
 236 plex and asymmetric jet flows.

237 If x_p^{ray} is a point on the wavefront defining the position
 238 of a ray, this point will follow the wavefront with velocity

$$\frac{dx_p^{\text{ray}}}{dt} = v(x_p^{\text{ray}}, t) + n(x_p^{\text{ray}}, t)a(x_p^{\text{ray}}, t), \quad (19)$$

239 where n is the vector normal to the wavefront. It is possible
 240 to calculate the ray path by integrating Eq. (19) with respect
 241 to time if v , a , and n are known. However, the evaluation of
 242 n requires the reconstruction of the wavefront at each space
 243 time interval, which is not straightforward as it requires the
 244 position of all neighboring rays. A simpler solution is possi-
 245 ble by using the wave-slowness vector, which is also normal
 246 to the wavefront and is defined as

$$s = \frac{n}{a + v \cdot n}, \quad (20)$$

247 which can be written in the following form after some math-
 248 ematical manipulation:

$$s^2 = \frac{\Omega^2}{a^2}, \quad (21)$$

249 where $\Omega = 1 - v \cdot s$. Equation (21) accounts for the slow-
 250 ness factor variation in space with the mean velocity and
 251 sound speed field.

252 The ray-tracing equations can be written in the
 253 Cartesian coordinate system,³⁰ which are represented by six
 254 ordinary differential equations that couple the ray position
 255 and the slowness vector

$$\frac{dx_i^{\text{ray}}}{dt} = U_i + \frac{as_i}{1 - U_j s_j}, \quad (22)$$

$$\frac{ds_i}{dt} = -\frac{1 - U_j s_j}{a} \frac{\partial a}{\partial x_i} - s_j \frac{U_j}{x_i}. \quad (23)$$

256 The above system is solved by integrating Eqs. (22) and
 257 (23) in time using a fourth-order Runge–Kutta method, while
 258 the mean flow properties, i.e., U_i and a and associated deriv-
 259 atives, are obtained by interpolation from a numerical RANS
 260 flow-field solution. The equations are integrated until the ray

exits the RANS simulation domain (i.e., unidirectional
 flow), from where it is considered to follow a straight line to
 the far-field observer position.

The ray tracing equations give no direct information
 about the acoustic pressure amplitude. It is therefore neces-
 sary to resort to the concept of ray-tubes and conservation of
 energy which leads to the Blokhintzev invariant.^{30,31} The
 invariant shows that along a given ray

$$\frac{\overline{p^2}VA}{(1 - U_i s_i)\rho a^2} = \text{const}, \quad (24)$$

where p is the acoustic pressure, $V = |dx^{\text{ray}}/dt|$ is the magni-
 tude of the ray velocity vector, and A is the ray-tube area.
 Using Eq. (24) for a ray traced from the source location, y ,
 to the far-field observer, x , results in

$$\frac{\overline{p^2}|_x}{\overline{p^2}|_y} = \frac{V}{(1 - U_i s_i)\rho a^2} \Big|_y \frac{A|_y}{V}, \quad (25)$$

which quantifies the change in the pressure amplitude along
 a given ray from the source location to the far-field observer.
 However, this is not the amplitude change needed to com-
 pute the flow factor Φ . The aim is to calculate the difference
 of pressure amplitude in the far-field between a ray traced
 over a quiescent medium and traced over the jet mean flow,
 both launched from the same source location. Hence, the
 flow factor used in our methodology is defined as

$$\Phi(x, y) = \frac{\overline{p^2}|_{x,\text{flow}}}{\overline{p^2}|_{x,\text{quiescent}}}, \quad (26)$$

where $\overline{p^2}|_{x,\text{flow}}$ is evaluated at the observer location for a ray
 launched from y and traced over the mean flow and
 $\overline{p^2}|_{x,\text{quiescent}}$ is evaluated at the observer location with the ray
 traced over a quiescent medium (i.e., a straight line between
 source and observer).

To compute Φ from Eq. (25) it is assumed that

$$\overline{p^2}|_{y,\text{flow}} = \overline{p^2}|_{y,\text{quiescent}}, \quad (27)$$

$$\frac{V}{(1 - U_i s_i)\rho a^2} \Big|_{x,\text{quiescent}} = \frac{V}{(1 - U_i s_i)\rho a^2} \Big|_{y,\text{quiescent}} \quad (28)$$

and

$$A|_{y,\text{flow}} = A|_{y,\text{quiescent}}. \quad (29)$$

The flow factor can therefore be given by

$$\Phi(x, y) = \frac{V}{(1 - U_i s_i)\rho a^2} \Big|_{y,\text{flow}} \frac{A|_{x,\text{quiescent}}}{V} \frac{A|_{x,\text{flow}}}{V}. \quad (30)$$

The first fraction on the right-hand side of Eq. (30) is
 evaluated using the ray tracing solution and the flow infor-
 mation obtained from the RANS solution. The ray-tube area

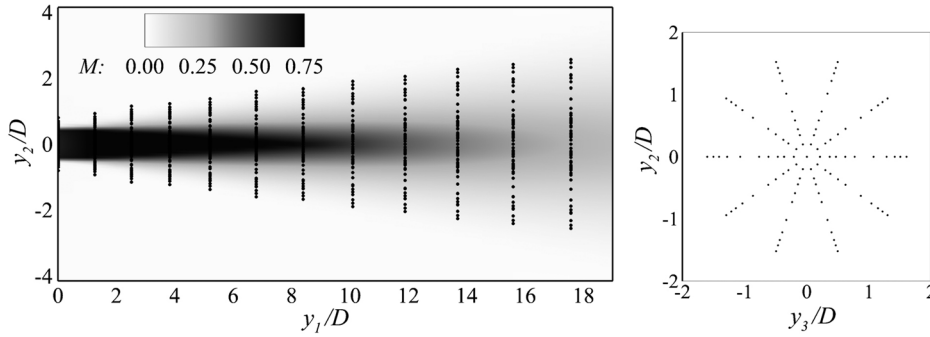


FIG. 2. Black dots show source locations for ray tracing method.

292 ratio cannot be computed directly from the ray tracing solu- 320
 293 tion and is approximated by the ray density ratio in the far 321
 294 field. 322

295 To compute the ray density ratio, the far-field is repre- 323
 296 sented as a spherical shell, discretized in spatial elements 324
 297 ($\sim 10^4$ far-field bins for the results in this paper), and a large 325
 298 number of rays ($\sim 6 \times 10^5$) are launched from each source 326
 299 location within the jet flow. To achieve a uniform spatial dis- 327
 300 tribution, the far-field bins and the ray launching angles are 328
 301 defined using the vertices of a geodesic sphere.³²⁻³⁴ Each ray 329
 302 is assigned to a far-field bin by comparing its far-field loca- 330
 303 tion with the far-field bin coordinates. The number of rays 331
 304 assigned to each far-field bin is summed as N_{flow} for rays 332
 305 traced through the mean flow and $N_{\text{quiescent}}$ when a quiescent 333
 306 medium is considered. Thus, Eq. (31) can be written as 334

$$\Phi(x, y) = \frac{\frac{V}{(1 - U_i s_i) \rho a^2} \Big|_{y, \text{flow}} N_{|x, \text{flow}}}{\frac{V}{(1 - U_i s_i) \rho a^2} \Big|_{x, \text{flow}} N_{|x, \text{quiescent}}} \quad (31)$$

307 The flow factor (Φ) must now be calculated for a finite 340
 308 number of source locations y ($\sim 10^3$) within the jet domain. 341
 309 The locations are non-uniformly distributed in the jet domain, 342
 310 with clusters of sources in regions of high velocity gradients 343
 311 and turbulent kinetic energy. An example of the distribution 344
 312 of about 1700 sources for a single-flow jet is presented in 345
 313 Fig. 2. Having presented the source and propagation models, 346
 314 in Sec. III results for single-stream jets at different operating 347
 315 conditions will be presented and discussed.

316 **III. RESULTS AND COMPARISONS**

317 The canonical circular single-stream jet has been 348
 318 extensively studied analytically, numerically, and experi- 349
 319 mentally.^{15,26,29} In this section, some aspects of the sound 350

320 generation of a circular single-stream jet at different oper- 321
 322 ating conditions are presented and discussed using the 323
 324 method developed in Sec. II. A total number of 12 operat- 325
 326 ing conditions have been considered. They comprise three 327
 328 Mach numbers: $M=0.5, 0.75,$ and 1.0 (reference sound 329
 330 speed in the far-field is 340 m/s); and four temperature 331
 332 ratios: $\text{TR}=1.0, 1.5, 2.0$ and 2.5 (where TR is the ratio 333
 334 between the jet-exit temperature and the reference temper- 335
 336 ature of 288 K in the surrounding medium). The nozzle in 337
 338 this study is shown in Fig. 3. 339

340 For each of the 12 cases, measurements of far-field spec- 341
 342 tra are available and a corresponding CFD (Computational 343
 344 Fluid Dynamics) RANS $k - \epsilon$ solution is conducted. The 345
 346 measurements of far-field noise were carried out in the Noise 347
 348 Test Facility at QinetiQ Pyestock, United Kingdom. The 349
 350 facility comprises of a chamber of area $27 \times 26 \text{ m}^2$ and 14 m 351
 352 height, being anechoic down to approximately 90 Hz . Results 353
 354 used in this paper are recorded using a microphone array at 355
 356 12 m ($\approx 120 D$) from the nozzle exit and are presented as 1 m 357
 358 loss-less data. 359

340 A brief description of the mean flow solution is pre- 341
 342 sented in Sec. III A, followed by a presentation of the results 343
 344 computed with the source and propagation models presented 345
 346 in this paper. The main emphasis of the results is to show the 347
 348 accuracy in the far-field noise prediction and the possibility 349
 350 to account for three-dimensional propagation effects for a 351
 352 realistic spreading jet. 353

347 **A. Mean flow solution**

348 The mean flow is computed with a standard finite volume 349
 350 second-order commercial CFD solver.³⁵ The continuity, 351
 352 momentum, and energy equations are solved for a compressible 353
 354 gas, along with the equation of state for an ideal gas. To model 355
 356 the jet flow the standard $k - \epsilon$ model is used, with the two addi- 357
 358 tional equations solved using the standard coefficients. 359

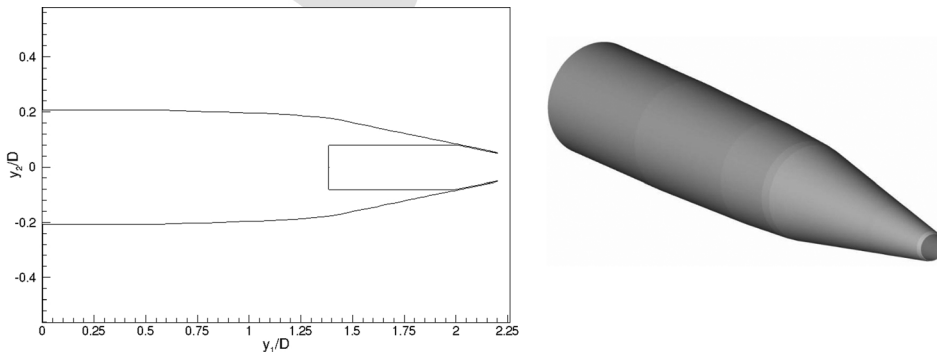


FIG. 3. Geometry of the $D = 0.1016 \text{ m}$ nozzle.

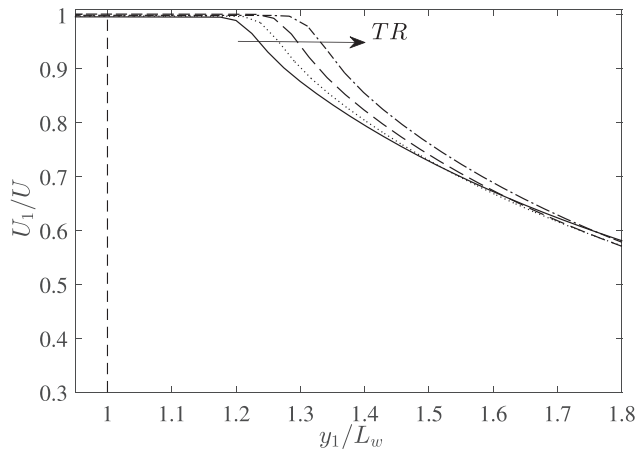


FIG. 4. Centerline axial velocity decay with axial distance normalized by empirical length of potential core (L_w) (Ref. 37) for $M=0.75$ jets. Solid line, $TR=1$; dotted line, $TR=1.5$; dashed line $TR=2$; and dashed-dotted line $TR=2.5$. The parameter L_w was computed for each temperature ratio. The fact that the curves start to decay at higher y_1/L_w shows that the over-prediction of the potential core length by RANS $k-\varepsilon$ worsens with increased temperature ratio.

354 Figure 4 shows the normalized velocity along the jet
355 center-line for a $M=0.75$ jet at different temperature ratios,
356 $TR=1, 1.5, 2,$ and 2.5 . Results are presented in terms of the
357 empirical potential core length as defined by Witze³⁷

$$L_w = (D/2)[0.08(1 - 0.16M)TR^{0.28}]^{-1}, \quad (32)$$

358 so that $y_1/L_w = 1$ represents the end of potential core for a
359 given M and TR . As known, the predictions with the stan-
360 dard $k-\varepsilon$ model result in an over-prediction of the potential
361 core length. Although several turbulence model corrections
362 have been proposed and discussed in the literature,³⁶ we
363 have used the standard model as it is widely available and
364 used in an industrial context. As can be seen, the over-
365 prediction grows with the temperature ratio (TR), making
366 the predictions less reliable for very hot jets. Despite the
367 obvious shortcomings of the $k-\varepsilon$ model, the mean flow
368 solution is still capable of providing good jet noise predic-
369 tion, which will be discussed in Secs. III B–III E.

370 B. Far-field noise prediction at 90°

371 RANS-based prediction methods^{14–16,38,39} generally
372 require empirically calibrated coefficients to relate the statis-
373 tical properties of the mean flow from RANS $k-\varepsilon$ to the rel-
374 evant properties of the sound generation process (or, more
375 recently, calibrated with transient numerical solutions).^{40,41}
376 Contrary to other methods that rely on three coefficients
377 (amplitude, length-scale, and time scale), the method pre-
378 sented in this paper only needs two coefficients, c_ℓ and c_τ .
379 The values for these coefficients are computed by comparing
380 the predicted SPL with the measured noise data at $\theta = 90^\circ$.
381 The optimum values vary slightly with Mach number but
382 more significantly with temperature ratio. The jet noise pre-
383 dictions for isothermal jets are performed using $c_\tau = 0.43$
384 and $c_\ell = 0.8$. For hot jets c_τ is kept at the same value while
385 c_ℓ is allowed to vary from 0.8 for $TR=1$ to around 1.9 for
386 $TR=2.5$.

Figure 5 shows a comparison of the predicted SPL at 387
 $\theta = 90^\circ$ with measured far-field data for the 12 cases consid- 388
ered, in the absence of refraction effects. The good agree- 389
ment observed, both in terms of the overall shape of the 390
spectra and the peak frequency location at different Mach 391
numbers, confirms that the source model captures well the 392
physics of the noise generation mechanism. The need of cali- 393
bration for different temperature ratios is a result of neglect- 394
ing the additional source terms related to hot jets, such as the 395
density variation. Nevertheless, by showing that c_τ can be 396
kept constant while only c_ℓ needs further calibration to prop- 397
erly capture the SPL spectra of the hot jets is an indication 398
that this additional source has a similar nature of the source 399
already modeled. 400

401 C. Source location results

The source model developed in Sec. II can be used to 402
study the distribution of the sound sources in the jet plume. 403
To do so, the volume integral in Eq. (18) is computed only 404
in the $y_2 - y_3$ plane so the contribution to the far-field noise 405
from a slice of the jet is computed as $P_{\text{slice}}(\mathbf{x}, \omega, y_1)$. 406

Figure 6 shows the results for an observer located at 90° 407
in the far-field. Different Strouhal numbers ($St = fD/U$) for 408
isothermal jets at Mach numbers of 0.5, 0.75, and 1 are consid- 409
ered. The source amplitude results are normalized by its 410
value at $St=0.2$. As expected, results have shown the 411
higher-frequency sources are located near the nozzle exit 412
and the most energetic sources are slightly after the end 413
potential core (if the overprediction of the potential core 414
length shown in Fig. 4 is considered, the peak in Fig. 6 415
moves closer to the end of potential core). The collapsing of 416
the results for the three different Mach numbers is evidence 417
that the source distribution is self-similar in frequency and 418
space, with the driving parameters being the Strouhal num- 419
ber for frequency and y_1/L_w for space. 420

421 D. Sound-flow interaction effects

The effect of refraction can further be analyzed in isola- 422
tion by plotting the flow factor computed using the ray trac- 423
ing and ray density ratio. The flow factor $\Phi(\mathbf{x}|\mathbf{y})$ gives the 424
amplification or reduction of the SPL due to the refraction 425
for the noise collected at a microphone location (\mathbf{x}) due to a 426
noise source at (\mathbf{y}) within the jet plume. In this section, the 427
flow factor results in dB, i.e., $(10 \log \Phi)$, are presented in 428
two forms: (i) by fixing the source location (\mathbf{y}) and varying 429
the observer location (\mathbf{x}) in the far-field over $0^\circ < \theta < 180^\circ$ 430
and $0^\circ < \phi < 360^\circ$, and (ii) fixing the observer location (\mathbf{x}) 431
and varying the source location (y_1 and y_2) within the jet 432
plume. This enables a better understanding of the three- 433
dimensional nature of the refraction effects appearing even 434
in the axisymmetry nozzle studied in this paper. 435

First, the effect of refraction is analyzed for sound emit- 436
ted from sources on the lip-line of a $M=0.75$ jet with 437
 $TR=1$, see Fig. 7. The sources are positioned along the noz- 438
zle lip-line ($y_2/D = 0.5$), i.e., within the jet shear-layer 439
where the turbulent kinetic energy (k) peaks and, according 440
to $P(\omega) \propto k^{7/2}$ relation, from Eq. (18), can be considered as 441
one of the most important noise generation regions. Figure 7 442

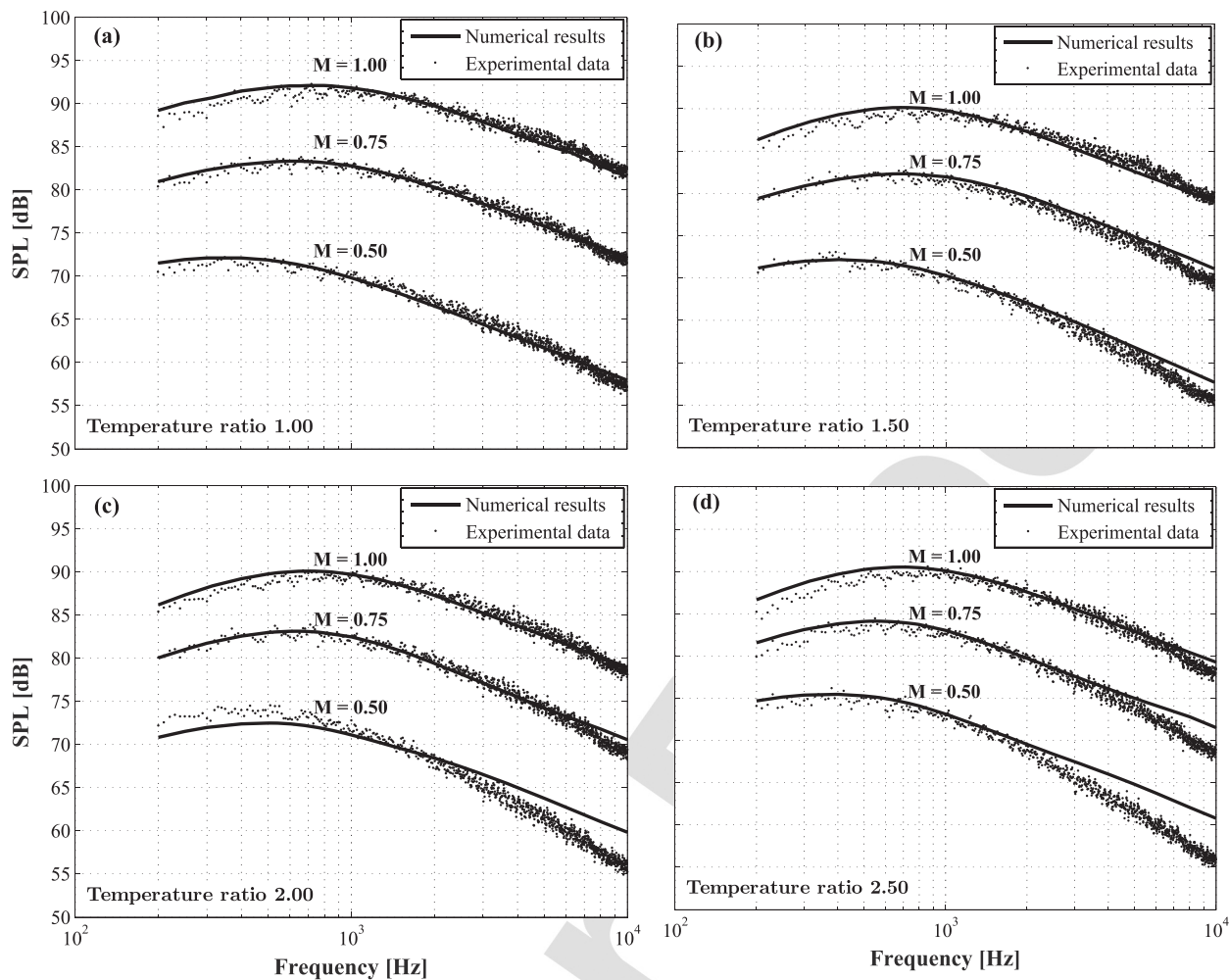


FIG. 5. Far-field SPL predictions and measurements at 90° for different M and TR: (a) TR = 1.00, (b) TR = 1.50, (c) TR = 2.00, (d) TR = 2.50.

443 shows the contour plots of the flow factor, where the negative Flow Factor indicates reduction of SPL due to the flow
 444 refraction and positive values show sound amplification. The white area in the plots represents the shadow zone where no
 445 rays are collected and the ray tracing approximation is no longer valid. The effects of refraction are presented as a
 446 function of the polar and azimuthal angles of the observer for sound emitted from four different source locations on the
 447 lip line with different downstream locations ($y_1/D = 1, 2, 6, 5,$ and 10).

453 For a source located at $y_1/D = 1$ and $y_2/D = 0.5$, the shadow zone has a variable shape along the azimuthal coordi-
 454 nate, see Fig. 7(a). The dashed line A shows that the critical angle defining the shadow zone occurs at about 60° and
 455 it goes from $\varphi \approx 10^\circ$ to 160° . With increasing φ , a new shadow zone area will appear, shown as region B . The
 456 change of the critical angle down to $\theta = 20^\circ$ for observers in the opposite side of the source is an interesting phenomenon
 457 which has not previously been shown. An area of high intensity, i.e., sound amplification, can also be observed within
 458 region B , at about $\theta = 65^\circ$, which is due to the rays entering the potential core of the jet, i.e., the rays that are not being
 459 totally reflected. The potential core in this situation acts like a lens for these rays, focusing them over a small region. This
 460 shows the importance of the effect of the potential core on
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468 sound propagation within the jet plume and the far-field noise amplification, particularly for asymmetric jets.
 469 Another area of strong sound amplification for observers below the jet occurs at $\varphi \approx 90^\circ$ and $\theta \approx 110^\circ$, shown as
 470 Region C.
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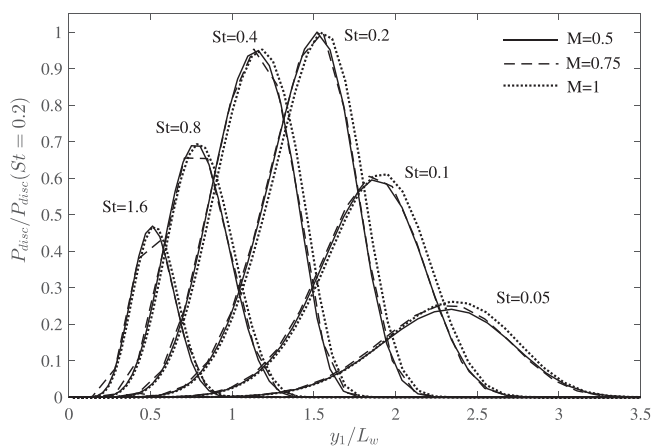


FIG. 6. Source distribution for isothermal jets as a function of axial distance for different Strouhal number ($St = fD/U$), normalized by the maximum of the distribution for $St=0.2$. Axial coordinate normalized by potential core length (L_w). Solid lines, $M=0.5$; dashed lines, $M=0.75$; dotted lines, $M=1$.

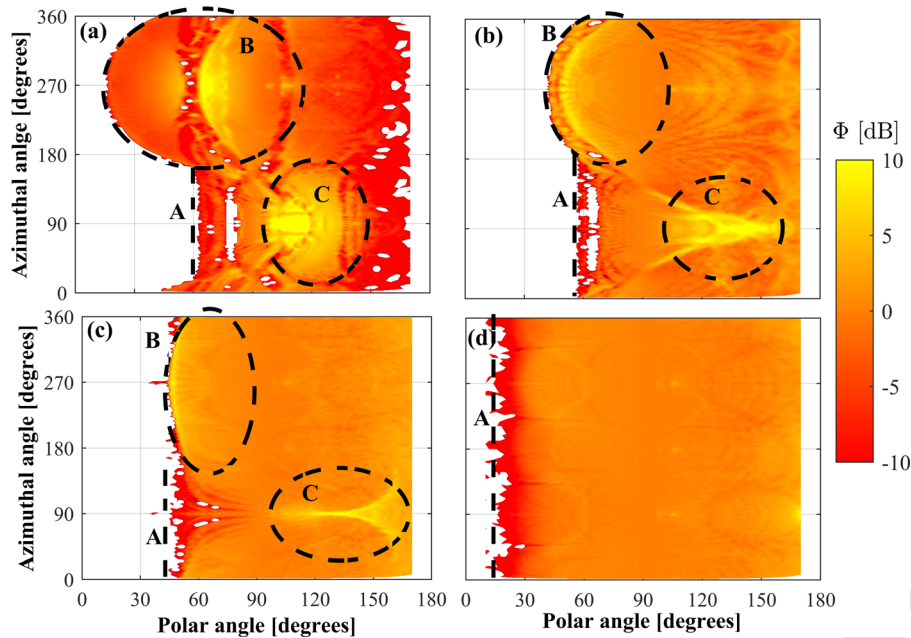


FIG. 7. (Color online) Flow factor for sources on the lip line of isothermal jet with $M = 0.75$. All sources are in the azimuthal angle of $\phi = 90^\circ$, with varying downstream location: (a) $y_1/D = 1$, (b) $y_1/D = 2.6$, (c) $y_1/D = 5$, and (d) $y_1/D = 10$.

473 Moving further downstream, for a point source located
 474 at $y_1/D = 2.6$ and $y_2/D = 0.5$, Fig. 7(b), the Flow Factor
 475 results change considerably, altering not only its shape but
 476 also the critical angle to $\approx 40^\circ$. Also, the noise amplification
 477 region before the shadow zone still plays an important role
 478 for this source location. Regarding region C, the peak area is
 479 becoming sharper and it is spreading along the polar angles.
 480 This can be understood by the fact that more rays are being
 481 convected by the flow due to the jet spreading. A similar
 482 trend has been observed for a source located near the end of
 483 the potential core at $y_1/D = 5$ and $y_2/D = 0.5$, see Fig. 9(c).
 484 The main differences are that the critical angle (shown by
 485 line A) goes down to $\approx 45^\circ$ and varies less with ϕ . Since
 486 the point source is now located near the end of the potential
 487 core, the acoustic lens effect of the potential core, as
 488 observed in Fig. 7(a) (region B), become less obvious and

Region B shrink to a very small θ area over
 $180^\circ < \phi < 360^\circ$. Region C also moves to higher polar
 angles of about $\theta = 140^\circ$. The results in Fig. 7(d) show that
 in the case of a source positioned at $y_1/D = 10$ and
 $y_2/D = 0.5$, in the absence of strong velocity gradient, the
 blockage effect (for $\phi \approx 270^\circ$) is minimized and it is no longer
 possible to identify regions B and C. Following the trend
 from the previous source locations, the critical angle shown
 by line A is further reduced to $\theta \approx 20^\circ$ and becomes effectively
 axisymmetric.

The results in Figs. 8 and 9 show the flow factor for different
 regions of the jet for an observer at $\phi = 90^\circ$ (i.e., above the
 plane of the figure) and two different polar angles ($\theta = 50^\circ$
 and $\theta = 90^\circ$). Results are presented for an isothermal and
 TR = 2.5 jet. As expected, the refraction factor in the case of
 an observer at $\theta = 90^\circ$ is almost zero, indicating

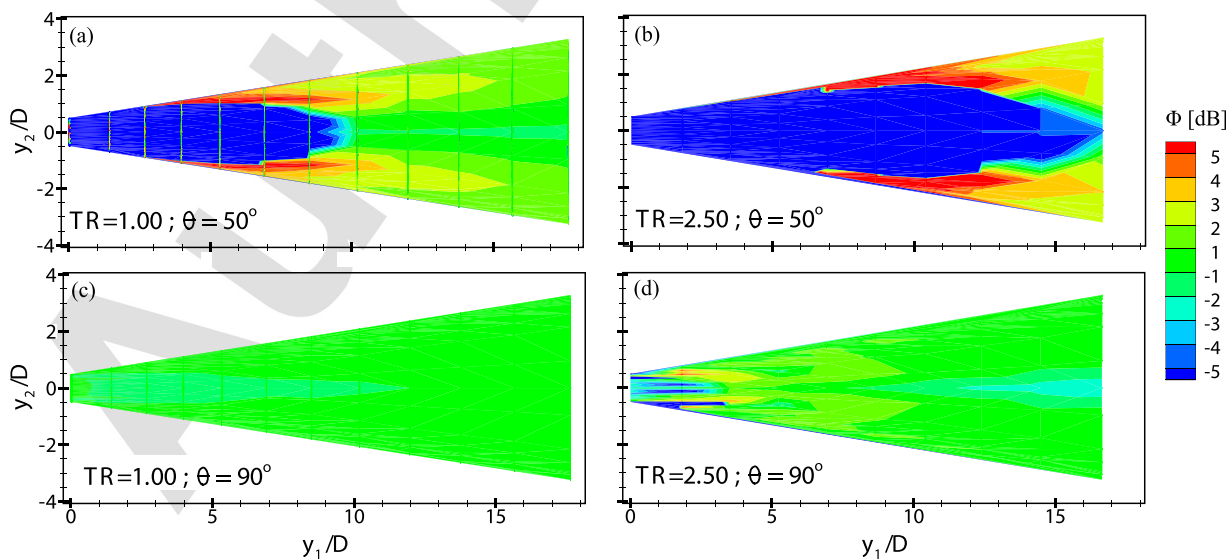


FIG. 8. (Color online) Flow factor for jet with $M = 0.75$ and different temperature ratios: (a) and (c), $TR = 1$; (b) and (d), $TR = 2.5$. Observer above plane of figure ($\phi = 90^\circ$) and different polar angles: (a) and (b), $\theta = 50^\circ$; (c) and (d), $\theta = 90^\circ$.

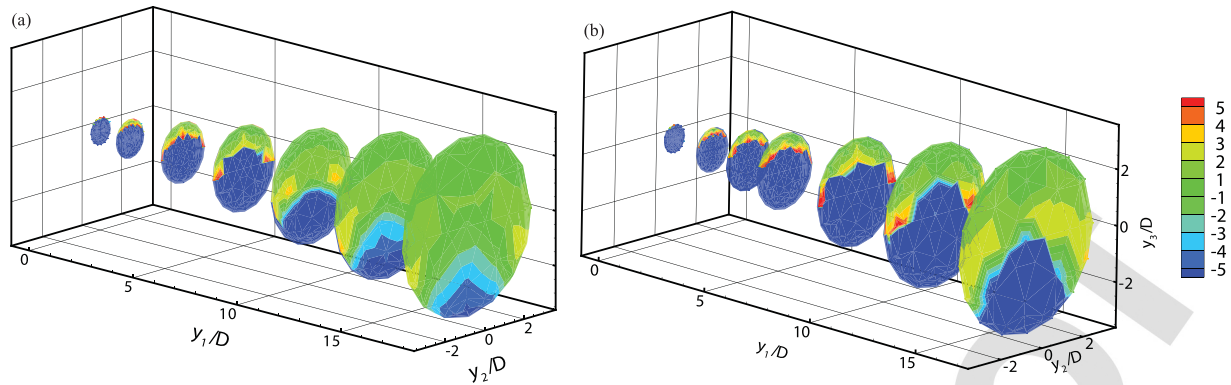


FIG. 9. (Color online) Three-dimensional visualization of flow factor for $M=0.75$ with different temperature ratios: (a) $TR=1$, (b) $TR=2.5$. Far-field observer at $\theta = 50^\circ$ and $\varphi = 0^\circ$.

505 very small refraction effects due to the sound and flow inter- 525
 506 actions. At small polar angles, Figs. 8(a) and 8(b), however, 526
 507 the regions close to the nozzle, where the velocity gradient 527
 508 is large, is significantly affected. Increasing the temperature 528
 509 ratio has also been shown to increase the level of refraction 529
 510 effects. The flow factor results over the $y_1 - y_2$ planes at dif- 530
 511 ferent axial locations for an observer located at $\varphi = 90^\circ$ and 531
 512 $\theta = 50^\circ$ are presented in Fig. 9. The results clearly show that 532
 513 the refraction due to the sound-flow interaction in an axisym- 533
 514 metric jet flow is not axisymmetric and the sources located 534
 515 on the opposite side of the observer suffer more refraction 535
 516 effects. As observed in Fig. 8, increasing the jet temperature 536
 517 ratio increases the region of the jet affected by refraction, 537
 518 Fig. 9(b).

from the jet axis. Results show that the far-field noise can be 525
 generally captured well for observers outside the zone of 526
 silence using the source and refraction model. The issue of 527
 propagation into the zone of silence and the limitations of 528
 the method will be discussed later. 529

530 Having shown that both the spectral behavior of the far- 530
 531 field noise at 90° (Fig. 5) and at different polar angles (Fig. 531
 532 10), and also the Flow Factor at different jet operating condi- 532
 533 tions (Figs. 7–9), we shall now study the overall sound pres- 533
 534 sure level (OASPL) for polar angles in the range of 534
 535 30° – 120° , see Figs. 11 and 12. Figure 11 shows the OASPL 535
 536 results for jets at $M=0.5$ and 0.75 at different temperature 536
 537 ratios ($TR=1.0, 1.5, 2$, and 2.5). Results for a $M=0.5$ jet 537
 538 show that the critical angle in the case of $TR=1$ occurs at 538
 539 about 46° and it moves to higher angles with temperature 539
 540 ratio. As expected, the model fails to predict the far-field 540
 541 noise within the zone of silence, but provides very good 541
 542 agreement at angles greater than the critical angle. The far- 542
 543 field noise comparisons for a $M=0.75$ jet also show that the 543
 544 model developed in this work is capable of predicting the 544
 545 OASPL very accurately outside the zone of silence. It can 545
 546 also be seen from the experimental data that the far-field 546

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519 **E. Far-field noise directivity**

520 To assess the ray-tracing based propagation model 520
 521 developed here, the far-field SPL results at different polar 521
 522 angles are presented for different Mach numbers, $M=0.5$, 522
 523 0.75 , and 1.00 , at $TR=1$, see Fig. 10. Results are presented 523
 524 for observers outside the zone of silence at $\theta = 60^\circ$ and 110°

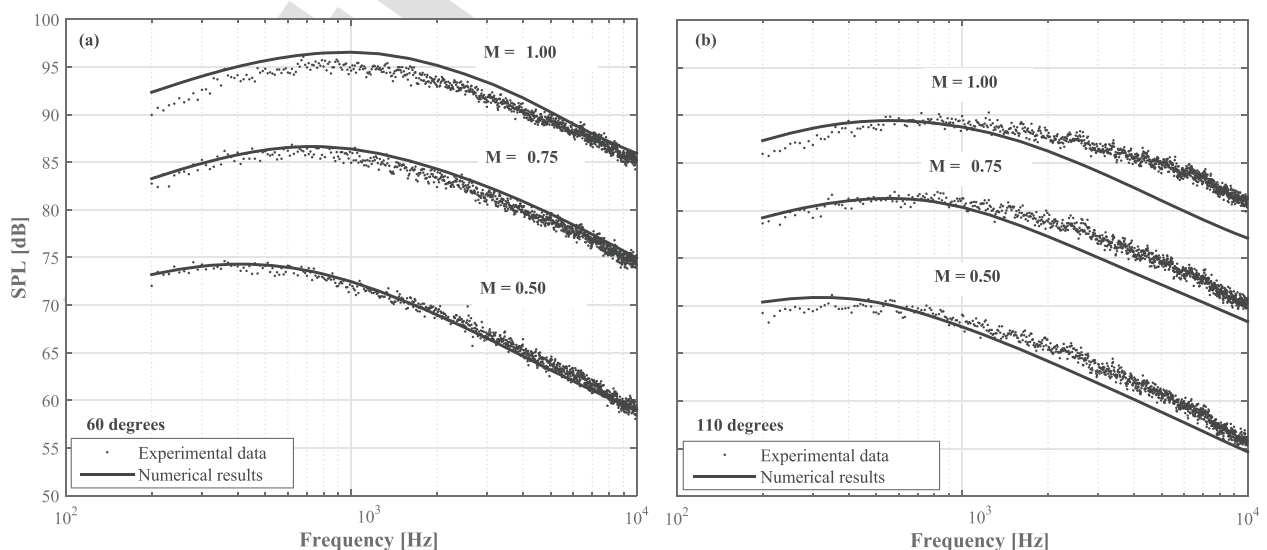


FIG. 10. Far-field SPL predictions and measurements at 60° and 110° for the isothermal jet with different M : (a) $\theta = 60^\circ$, (b) $\theta = 110^\circ$.

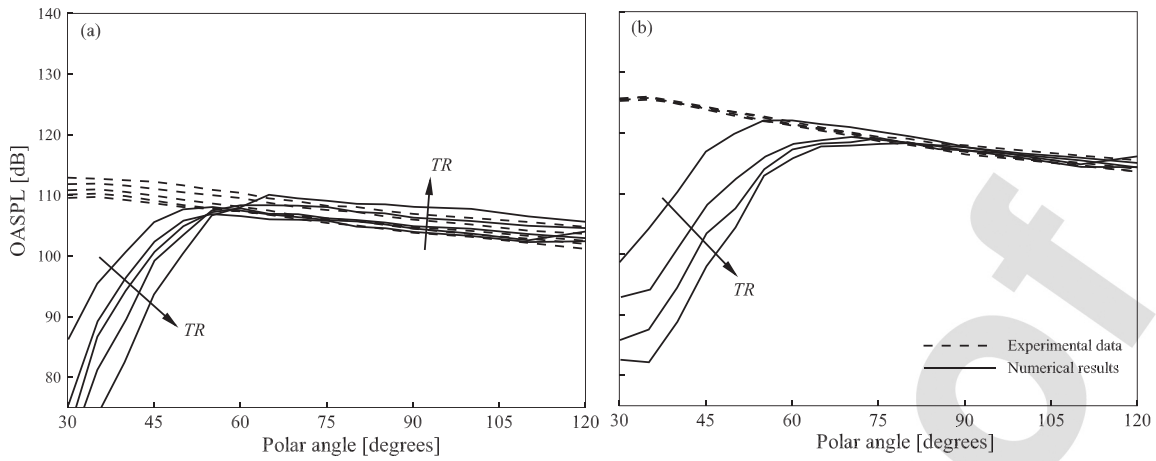


FIG. 11. OASPL prediction (solid lines) and measurements (dashed lines) for (a) $M = 0.5$ and (b) $M = 0.75$ with temperature ratio ranging from 1.0 to 2.5.

547 noise is more sensitive to temperature ratio at low Mach
 548 numbers ($M = 0.5$), and that the source and propagation
 549 models have managed to predict this effect well.

550 **IV. CONCLUSIONS**

551 In this paper an application of the LAA to model the
 552 sources of jet mixing noise coupled to a ray tracing method
 553 to compute effects of refraction is presented. The resulting
 554 method is a promising solution to quickly evaluate the noise
 555 emitted by jets from arbitrary nozzle geometries. This is par-
 556 ticularly desired in an industrial context as it relies on the
 557 standard RANS $k - \epsilon$ solution and makes no further assump-
 558 tion about the flow. Despite the need of calibration with far-
 559 field measurements, only two coefficients are needed instead
 560 of three as it is usually the case for similar methods from the
 561 literature. The coefficients are fixed for isothermal jets in the
 562 subsonic regime, however one of them needs to be changed
 563 with increasing temperature ratio; such need is understood to
 564 result from the neglect of the enthalpy source arising in
 565 heated jets.^{42–47}

AQ8 566 Results show that the method proposed in this paper
 567 captures well the contribution of fine-scale turbulence to jet
 568 mixing noise in the subsonic regime down to a polar angle

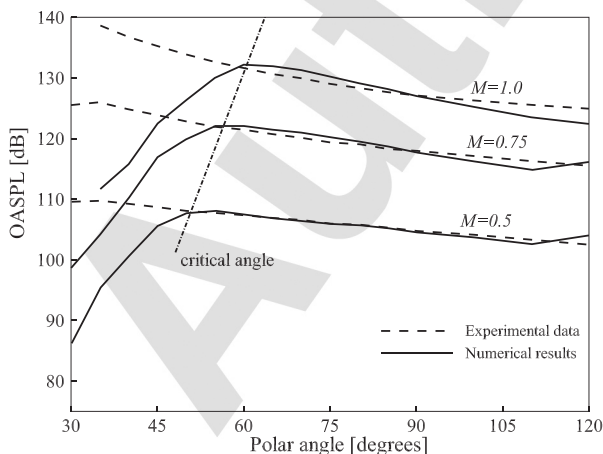


FIG. 12. OASPL prediction (solid lines) and measurements (dashed lines) at $TR = 1.0$ with Mach number ranging from 0.5 to 1.0. The critical angle is shown to increase linearly with M .

of 50° , below which the effect of a shadow zone invalidates
 the real ray tracing assumption. Such range of observer
 angles (above 50°) give valuable information if a quick esti-
 mation of the impact of non-axisymmetric geometries is
 sought. It thus satisfies the requirement of a design tool, pre-
 senting reasonable accuracy at relatively low computational
 cost while being able to consider general three-dimensional
 nozzle geometries.

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