Supplementary Note: Hybrid Longitudinal-Transverse Phonon Polaritons

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Supplementary Note 1: Formalism

We can write the ionic equation of motion for a polar dielectric crystal coupled to an electric field, in the form

\[ \omega_T^2 - \omega(\omega + i\gamma) \] \[ \mathbf{X} = -\beta_T^2 \nabla \cdot \mathbf{X} + \beta_L^2 \nabla \times \nabla \times \mathbf{X} - \frac{\alpha}{\rho} (\nabla \phi - i\omega \mathbf{A}), \] (1)

where \( \omega_T \) is the polar dielectric’s transverse phonon frequency, \( \gamma \) the phonon damping rate, \( \mathbf{X} \) is the ionic displacement, \( \alpha \) is the light-matter coupling strength given by

\[ \alpha = \sqrt{\rho \varepsilon_0 \varepsilon_\infty \left( \omega_L^2 - \omega_T^2 \right)}, \] (2)

\( \rho \) is the density, \( \beta_T \) (\( \beta_L \)) the transverse (longitudinal) phonon velocities and \( \phi \) (\( \mathbf{A} \)) is the scalar (vector) potential related to the electromagnetic fields \( \mathbf{E}, \mathbf{H} \) by

\[ \mathbf{E} = -\nabla \phi + i\omega \mathbf{A}, \]

\[ \mathbf{H} = \frac{1}{\mu_0} \nabla \times \mathbf{A}. \] (3)

Taking the divergence (curl) of Eq. (1) and defining auxiliary scalar (vector) potentials \( Y = \nabla \cdot \mathbf{X}, \Theta = \nabla \times \mathbf{X} \) we can find decoupled equations of motion for the longitudinal auxiliary potential

\[ \left[ \omega_L^2 - \omega(\omega + i\gamma) \right] \mathbf{Y} = 0, \] (4)

and transverse one

\[ \left[ \omega_T^2 - \omega(\omega + i\gamma) \right] \Theta = i\omega \frac{\alpha}{\rho} \nabla \times \mathbf{A}, \] (5)

where we utilised the Coulomb gauge condition \( \nabla \cdot \mathbf{A} = 0, \) the absence of free charges \( \nabla \cdot \mathbf{D} = 0, \) and the constitutive relation linking the electric and displacement fields to the ionic displacement

\[ \mathbf{D} = \varepsilon_0 \varepsilon_\infty \mathbf{E} + \alpha \mathbf{X}. \] (6)

We also introduced the longitudinal phonon frequency

\[ \omega_L^2 = \omega_T^2 + \frac{\alpha^2}{\varepsilon_0 \varepsilon_\infty \rho}, \] (7)

where \( \varepsilon_\infty \) is the high-frequency dielectric constant of the polar dielectric. In terms of the newly defined potentials we can reconstruct the ionic displacement by substitution as

\[ \mathbf{X} = \frac{1}{\omega_T^2 - \omega(\omega + i\gamma)} \left[ \beta_T^2 \nabla \times \Theta - \frac{\beta_T^2 \varepsilon_\infty}{\varepsilon(\omega, 0)} \nabla Y \right] - \frac{\alpha}{\rho} (\nabla \phi - i\omega \mathbf{A}), \] (8)

where we recognised the dielectric function of a polar dielectric crystal in the absence of spatial dispersion

\[ \varepsilon(\omega, 0) = \varepsilon_\infty \left[ \frac{\omega_L^2 - \omega(\omega + i\gamma)}{\omega_T^2 - \omega(\omega + i\gamma)} \right]. \] (9)

Longitudinal Equation

The longitudinal equation of motion Eq. (4) is just a scalar Helmholtz equation. Taking the divergence of the displacement field \( \mathbf{D} \) as defined in Eq. (6) we can find

\[ \nabla^2 \phi = \frac{\alpha}{\varepsilon_0 \varepsilon_\infty} \mathbf{Y}, \] (10)

whose solution is simply given by

\[ \phi = \phi_H - \frac{\alpha}{\varepsilon_0 \varepsilon_\infty} \frac{\beta_L^2}{\omega_L^2 - \omega(\omega + i\gamma)} \mathbf{Y}, \] (11)

where \( \phi_H \) is the homogeneous solution of Eq. (10) satisfying \( \nabla^2 \phi_H = 0. \)

Transverse Equation

Using Maxwell’s curl equation in conjunction with the constitutive relation in Eq. (6)

\[ \nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} = \varepsilon_0 \varepsilon_\infty \frac{\partial \mathbf{E}}{\partial t} + \alpha \frac{\partial \mathbf{X}}{\partial t}, \] (12)
we can put Eq. 3 for the transverse potential in the form
\[ i \mu_{0} \omega \Theta = \left[ \frac{\omega^{2} \epsilon_{\infty}}{c^{2}} + \nabla^{2} \right] \nabla \times A. \] (13)

Making a spatial Fourier transform \( \nabla^{2} \rightarrow -k^{2} \) and substituting this back into the transverse equation of motion we arrive at the result
\[ k^{2} - \frac{\omega^{2}}{c^{2}} \epsilon(\omega, k) = 0, \] (14)

where the easily identified spatially dispersive dielectric function is given by
\[ \epsilon(\omega, k) = \epsilon_{\infty} \frac{\omega^{2}}{\omega_{t}^{2} - \omega(\omega + i \gamma)} - \beta_{2}^{2} k^{2}, \] (15)

which reduces to the non-dispersive Eq. 3 in the limit \( \beta_{2} k \ll \omega \).

**Supplementary Note 2: Application to a Polar Halfspace**

Here we apply the general theory previously derived to the specific case of an a-cut polar dielectric halfspace occupying \( z < 0 \) whose c-axis is aligned with the x-axis. The region \( z > 0 \) is filled with a non-resonant dielectric whose dispersionless dielectric function is given by \( \epsilon_{0} \). The system is illuminated from \( z = \infty \) by a TM polarised electromagnetic field with incident wavevector in the x-z plane.

As we saw in the general theory, solutions to the general isotropic equation of motion in the lower halfspace Eq. 11 are separable into three classes. Firstly the homogeneous solution, satisfying \( \nabla^{2} \phi_{H} = 0 \) whose solution is given by
\[ \phi_{H} = -\frac{t_{H}}{\epsilon_{0} \omega} e^{ik_{z} x} e^{ik_{+} z}, \] (16)

yields the following electric and displacement fields in the lower halfspace
\[ E_{H} = -\nabla \phi_{H} = \frac{t_{H} k_{x}}{\epsilon_{0} \omega} (i \hat{x} + \hat{z}) e^{ik_{x} x + k_{z} z}, \]
\[ X_{H} = \frac{\alpha}{\rho \epsilon_{0} \omega} \frac{t_{H} k_{x}}{\omega_{t}^{2} - \omega(\omega + i \gamma)} (i \hat{x} + \hat{z}) e^{ik_{x} x + k_{z} z}, \] (17)

which are chosen to ensure decay away from the interface as \( z \rightarrow -\infty \). Here \( t_{H} \) is a constant to be determined by application of the electromagnetic and mechanical boundary conditions. In the upper halfspace where \( \alpha = 0 \) it is clear that the scalar equation Eq. 10 still admits a homogeneous solution whose out-of-plane wavevector is equal and opposite to that in the lower halfspace. Considering this mode allows the homogeneous solution to be ignored in calculation of the electromagnetic boundary conditions.

Zone-centre longitudinal modes are not considered as solutions of Eq. 11 due to their far off-resonant nature. As a result of Bragg scattering along the crystal c-axis, which for the a-cut system considered is parallel to the x-axis, the in-plane wavevector of the Bragg scattered modes is shifted as \( k_{zL} = k_{M} + k_{z} \) in which \( k_{M} = \pi/a \) where a is the lattice constant along the c-axis. The scalar potential is therefore given by
\[ Y = \frac{\alpha \mu_{0} t_{L}}{\rho \omega} e^{ik_{zL} x + ik_{zL} z}, \] (18)
in which \( t_{L} \) is a constant to be determined by application of the appropriate boundary conditions. These modes are subject to the dispersion relation
\[ 0 = \omega_{L}^{2} - \omega(\omega + i \gamma) - \beta_{2}^{2} k_{zL}^{2}, \] (19)

which yields the out-of-plane longitudinal wavevector \( k_{zL} \).

The corresponding electric potential is calculated through the inhomogeneous component of Eq. 11 as
\[ \phi_{L} = -\frac{\alpha}{\rho \epsilon_{0} \omega} \frac{\beta_{2}^{2} / c^{2}}{\omega_{L}^{2} - \omega(\omega + i \gamma)} t_{L} e^{ik_{zL} x} e^{ik_{zL} z}, \] (20)
generating the electric field
\[ E_{L} = -\nabla \phi_{L} = \frac{i \beta_{2}^{2} t_{L}}{\rho \epsilon_{0} \omega} \frac{1 - \epsilon_{\infty}}{\epsilon(\omega, 0)} \times [k_{zL} \hat{x} + k_{zL} \hat{z}] e^{ik_{x} x + ik_{zL} z}, \] (21)

and ionic displacement through Eq. 8
\[ X_{L} = -\frac{\beta_{2}^{2}}{\omega_{L}^{2} - \omega(\omega + i \gamma)} \nabla Y = \frac{i \alpha t_{L}}{\rho \epsilon_{0} \omega} \frac{\beta_{2}^{2} / c^{2}}{\omega_{L}^{2} - \omega(\omega + i \gamma)} \times [k_{zL} \hat{x} + k_{zL} \hat{z}] e^{ik_{x} x + ik_{zL} z}, \] (22)

Finally as a solution to Eq. 5 we consider a TM polarised transverse field, whose magnetic component is given by
\[ H = t_{T} e^{ik_{y} y} e^{ik_{T} x} \hat{y}, \] (23)

where \( t_{T} \) is a constant to be determined by applying the electromagnetic and mechanical boundary conditions and \( k_{zT} \) is the out-of-plane wavevector for the transverse mode. This mode is generated by the vector potential
\[ A = \frac{t_{T}}{\omega^{2} \epsilon_{0} (\omega, k_{T})} [ik_{zT} \hat{x} + ik_{T} \hat{z}] e^{ik_{x} x + ik_{zT} z}, \] (24)

from which we can calculate the auxiliary vector potential
\[ \Theta = \frac{i}{\alpha \omega} \frac{\omega^{2}}{c^{3}} [\epsilon(\omega, k_{T}) - \epsilon_{\infty}] t_{T} e^{ik_{x} x} e^{ik_{zT} y}. \] (25)

Now we are in a position to calculate the transverse electric field
\[ E_{T} = i \omega A = \frac{t_{T}}{\omega \epsilon_{0} (\omega, k_{T})} [k_{zT} \hat{x} - k_{T} \hat{z}] e^{ik_{x} x + ik_{zT} y}, \] (26)
and the transverse component of the material displacement through Eq. [8]

\[
X_T = \frac{1}{\omega^2 - \omega(\omega + i\gamma)} \left[ \beta_T^2 \nabla \times \Theta + i\omega \frac{\alpha}{\rho} A \right],
\]

\[
= \frac{\alpha}{\rho c_0} \omega \left( k_T^2 \hat{x} - k_T^2 \hat{z} \right) \left[ \frac{1}{\epsilon(\omega, k_T)} + \frac{\beta_T^2}{c^2} \omega^2 - \omega(\omega + i\gamma) - \beta_T^2 k_T^2 \right] e^{ik_T z} e^{ik_T z},
\]

Eq. (27)

In the above the out-plane-wavevector for the transverse mode \( k_T \) is given by the root of Eq. (13) and \( k_T = (k_x, 0, k_z) \). In practice as the wavevector of the transverse mode is small, satisfying \( k_T^2 \ll \omega \) it is only necessary to consider this equation in the non-dispersive limit where it reduces to the standard Helmholz equation.

The electromagnetic fields in the upper halfspace \( z > 0 \) correspond to a TM polarised plane wave incident from \( z = \infty \). They are given by

\[
E_0 = \frac{e^{ik_{zB} z}}{\varepsilon_0 e_B \omega} \left[ (k_{zB} \hat{x} - k_{zB} \hat{z}) e^{i k_{zB} z} - r(k_{zB} \hat{x} + k_{zB} \hat{z}) e^{-i k_{zB} z} \right],
\]

\[
H_1 = \left[ e^{ik_{zB} z} + r e^{-ik_{zB} z} \right] e^{ik_{zB} x},
\]

where \( r \) is the reflection coefficient and \( k_{zB} \) is the out-of-plane wavevector in the upper halfspace given by

\[
k_{zB} = \sqrt{\epsilon_B \omega^2 - k_x^2}. \tag{29}
\]

Boundary Conditions

We start by applying the standard electromagnetic Maxwell boundary conditions. Continuity of the tangential magnetic field yields

\[
1 + r = t_T, \tag{30}
\]

and that of the tangential electric field gives

\[
\frac{k_{zB}}{e_B} (1 - r) = \frac{k_T}{\epsilon(\omega, k_T)} t_T - \frac{2}{\pi} \frac{\beta_T^2}{k_{zB}^2 \gamma c^2} \left( 1 - \frac{\epsilon_{\infty}}{\epsilon(\omega, 0)} \right) t_L, \tag{31}
\]

where we eliminate the homogeneous electric field by considering in addition its counterpart in the upper halfspace as previously described.

Note that, due to Bragg scattering, in applying boundary conditions we have to deal with the mismatch between a fast oscillating longitudinal mode and the slow oscillating transverse ones. In the spirit of the macroscopic approach we employ, we define the longitudinal field averaged over the unit cell

\[
\langle E_L \rangle = E_{L|x=0} e^{ik_{zB} x} \int_0^\infty \frac{dx}{a} e^{i k_{zB} x} = \frac{2i}{\pi} E_{L|x=0} e^{ik_{zB} x}, \tag{32}
\]

and we utilise this averaged form of the longitudinal field in the calculation of the boundary conditions below. To account for the oscillations of the crystal we also need to apply mechanical boundary conditions. The appropriate choice for a free surface such as that considered here are the continuity of the mechanical forces, or the normal components of the stress tensor. These boundary conditions can be written in the form

\[
\partial X_x / \partial z + \partial X_x / \partial z = 0, \tag{33}
\]

\[
C_{13} \partial X_x / \partial z + C_{13} \partial X_x / \partial z = 0,
\]

where \( C_{13}, C_{33} \) are elastic coefficients of the lattice. Application of the former boundary condition yields

\[
t_H = \frac{1}{k_x^2} \left[ \frac{-2 \beta_T^2}{\epsilon(\omega, 0)} t_T k_{zB} - \frac{t_T}{2} (k_T^2 - k_x^2) \right] \times \left[ \frac{\beta_T^2}{c^2} \omega^2 - \omega(\omega + i\gamma) - \beta_T^2 k_T^2 + \frac{1}{\epsilon(\omega, k_T)} \right],
\]

and combining with the latter condition we can find

\[
t_L = \frac{\pi}{2} t_T \frac{c^2}{\beta_T^2} \left( \frac{2}{\epsilon(\omega, 0)} \right) \times \left[ C_{33} \left( 2 i k_{xL} k_T + (k_x^2 - k_T^2) \right) \right] \frac{C_{13} k_{xL}^2 + C_{33} k_T^4 + i (C_{33} - C_{13}) k_x M k_{xL}}{C_{13} k_{xL}^2 + C_{33} k_T^4 + i (C_{33} - C_{13}) k_x M k_{xL}} \times \left[ \frac{\beta_T^2}{c^2} \omega^2 - \omega(\omega + i\gamma) - \beta_T^2 k_T^2 + \frac{1}{\epsilon(\omega, k_T)} \right]. \tag{35}
\]

Finally, combining this result with the electromagnetic boundary conditions we can find a single equation whose solution yields the reflectance coefficient of the halfspace.

\[
\frac{k_{zB}}{e_B} (1 - r) = \frac{k_T}{\epsilon(\omega, k_T)} + \Omega, \tag{36}
\]

where

\[
\Omega = \frac{i k_{zB}}{2} \left( \frac{\epsilon(\omega, 0)}{\epsilon_{\infty}} - 1 \right) \times \left[ (C_{33} - C_{13}) (2 i k_{zB} k_T + (k_x^2 - k_T^2)) \right] \left[ \frac{C_{13} k_{xL}^2 + C_{33} k_T^4 + i (C_{33} - C_{13}) k_x M k_{xL}}{C_{13} k_{xL}^2 + C_{33} k_T^4 + i (C_{33} - C_{13}) k_x M k_{xL}} \times \left[ \frac{\beta_T^2}{c^2} \omega^2 - \omega(\omega + i\gamma) - \beta_T^2 k_T^2 + \frac{1}{\epsilon(\omega, k_T)} \right], \tag{37}
\]

leading to the reflectance coefficient

\[
r = \frac{k_{zB}}{k_T} \left( \frac{\epsilon(\omega, k_T)}{\epsilon(\omega, k_T)} - \Omega \right) \frac{k_{zB}}{k_T} \left( \frac{\epsilon(\omega, k_T)}{\epsilon(\omega, k_T)} + \Omega \right. \tag{38}
\]

The result in Eq. (35) has been obtained by considering the solution of an isotropic crystal in Eq. (11).
and then introducing the Bragg scattering of the longitudinal mode along the c-axis. The effect of the Bragg scattering is entirely encoded in $\Omega$ and when its value goes to 0 we recover the standard Fresnel coefficient for TM polarised reflection from an isotropic halfspace

$$r_{\text{TM}}^\text{TM} = \frac{\frac{k_z}{\varepsilon_{\text{M}}}}{\frac{k_{zB}}{\varepsilon_{\text{B}}}} \frac{\frac{k_z}{\varepsilon_{\text{o}}}}{\frac{k_{zT}}{\varepsilon_{\text{TM}}}}$$  \hspace{1cm} (39)

In the case of an uniaxial crystal whose c-axis lies parallel to the x-axis, the effect of the anisotropy can then be reintroduced, to the dominant order, by considering the Fresnel coefficient for a uniaxial crystal, that is by performing in Eqs. (37)-(38) the substitutions

$$k_{zB}^2 \rightarrow \varepsilon_{\parallel}(\omega, k_{\text{T}}) \frac{\omega^2}{\varepsilon^2} = \frac{\varepsilon_{\parallel}(\omega, k_{\text{T}})}{\varepsilon_{\perp}(\omega, k_{\text{T}})} k_{zT}^2$$  \hspace{1cm} (40)

$$\varepsilon(\omega, k_{\text{T}}) \rightarrow \varepsilon_{\parallel}(\omega, k_{\text{T}})$$  \hspace{1cm} (41)

where $\varepsilon_{\parallel}$ ($\varepsilon_{\perp}$) is the dielectric function parallel (perpendicular) to the c-axis.

**Supplementary Note 3: Additional Experimental Data**

In the main body of the manuscript experimental data was presented from two samples with nominal pillar diameters of 300nm and 500nm. For each nominal pillar diameter 6 unique samples were fabricated. Due to variability in the fabrication procedure the frequencies of the optical modes varies slightly between samples. In Fig. 1 we show the reflectance spectra for the samples omitted from the main body of the text. Note that despite the variation in mode frequencies away from the weak LO phonon, every sample nonetheless reproduces the anti-crossing.

Supplementary Figure 1: Reflectance maps for samples of 300nm (1st Column) and 500nm (2nd Column). The rows correspond to different fabrication runs.

**Supplementary References**
