

# Adaptation in Heterogeneous Multi-core SoCs

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## Motivation for Heterogeneous Multi-core SoCs

The reliance of embedded computing systems is increasing to heterogeneous multi-core SoCs consisting of different types of cores such as CPU and GPU. An example includes the Samsung Exynos 5422 SoC containing a CPU with four ARM cortex-A15 (big) and four ARM Cortex-A7 (LITTLE) cores, and a GPU with 6 ARM Mali-T628 cores [1]. These architectures provide opportunities to exploit distinct features of CPU and GPU cores to meet performance and energy consumption requirements. Further, the cores in these SoCs support dynamic voltage and frequency scaling (DVFS), which can be used to reduce dynamic power consumption ( $P \propto V^2f$ ). This helps to reduce energy consumption if the extra time taken to run the workload at a lower voltage and frequency can be accounted by sufficient reduction in the power consumption.

Open Computing Language (OpenCL) [3] provides an opportunity to write applications that can execute across heterogeneous cores including CPUs and GPUs [6, 8–10]. However, since CPU and GPU cores typically handle task/thread and data level parallelism, respectively, the performance and energy consumption of an application varies when executed onto only CPU, only GPU, or both CPU and GPU cores [17]. The variation depends upon the kind of parallelism dominating the application. Existing studies have shown significant reduction in execution time and energy consumption when an application simultaneously exploits both the CPU and GPU cores with an appropriate partitioning of threads between them [6].

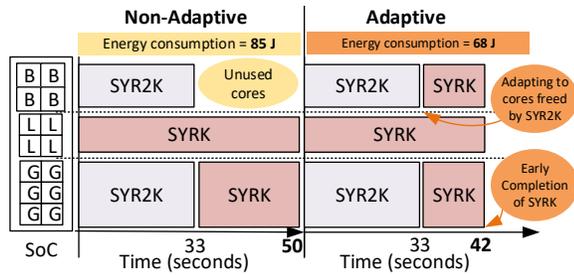
## Related Research and Their Shortcomings

For concurrently executing applications in a heterogeneous multi-core SoC, e.g., image and MP3 decoding with respective frames per second (fps) requirements, energy-efficient runtime management of applications on SoC resources is desired. Several efforts have been made towards this [4, 7, 11, 13, 15]. However, they consider cores having the same instruction

set architecture (ISA), e.g., big and/or LITTLE cores. Usually, they employ Pthreads, which cannot be used to exploit cores of different ISAs such as CPU and GPU. As mentioned earlier, the OpenCL programming model overcomes such limitations, but most of the existing works for embedded systems utilize either the CPU or GPU [12, 14], and there are limited efforts to exploit both at the same time [5, 6]. In [6], only a single application at a time is considered. Concurrent applications are considered in [5], but the mapping (defined as the number of used cores, their types (e.g., big, LITTLE) and operating frequencies) and thread-partitioning (defined as the fraction of threads to be executed on CPU cores) for each application remain fixed, which is identified before starting applications' execution. This indicates no adaptation of the mapping and thread-partitioning during execution. Therefore, due to the lack of adaptation, the freed cores by an application cannot be used by already running applications or to start execution of a waiting application. This could help in improving resource utilisation and/or energy efficiency. Further, for CPU-GPU SoC, the adaptation needs to consider collaboration between CPU and GPU cores processing capabilities for energy efficiency, which is missing. An adaptive approach for CPU-GPU SoC is recently presented [18], but it considers only a single application at a time and only CPU or GPU for application execution.

## Motivational Case Study: Adaptation in CPU-GPU Multi-core SoC

Fig. 1 illustrates the mapping and thread-partitioning process of applications SYR2K and SYRK from Polybench benchmark [16] on the Samsung Exynos 5422 SoC when employing **non-adaptive** (e.g., [5, 6]) and our proposed **adaptive** approaches. At the beginning, SYR2K is started on big (B) and GPU (G) cores and SYRK on LITTLE (L) cores. Since embedded GPU drivers do not support spatially isolated and time multiplexed execution of multiple applications, SYR2K uses all the GPU cores till its completion. Thereafter, SYRK starts using the GPU cores. Both the applications are started with appropriate thread-partitioning between CPU and GPU cores by taking CPU and GPU processing capabilities into account, i.e., by having proper collaboration between CPU and GPU. It can be seen in Fig. 1 that the **non-adaptive** approach leaves



**Figure 1: Adaptation at application completion: Non-adaptive vs. adaptive mapping and thread-partitioning on big (B), LITTLE (L) and GPU (G) cores of Samsung Exynos 5422 multi-core SoC.**

cores unused when SYR2K completes execution. This has resulted in a higher execution time of **50 seconds** for SYRK and a total energy consumption of **85 joule (J)** for both the applications. In contrast, upon completion of SYR2K, the **adaptive** approach performs adaptation (through collaboration between CPU and GPU cores), i.e. remapping SYRK by taking the freed cores into account, and execution is started with a new thread-partitioning that enqueues more threads to CPU cores as it has increased processing capability. This leads to early completion of SYRK at **42 seconds**. As a result of reduced execution time, total energy consumption is reduced to **68 J**.

Adaptation is also beneficial to support a new application when no resource is available by adapting running applications to lower number of cores. The running application that is over performing can be chosen for this purpose. and the freed resources can be used for the new application. This has resulted in timely start of the new application and early completion as well, which results in lower energy consumption.

In summary, adaptation (remapping and repartitioning) at application arrival and completion brings several benefits such as the exploitation of freed cores, addition of a new application when no core is available and early completion of applications by exploiting freed cores, which also leads to low energy consumption (Power  $\times$  time).

## Challenges

To perform energy-efficient collaborative adaptation (remapping and thread-repartitioning) of executing applications while satisfying their performance requirements, the following key challenges need to be addressed:

- Since OpenCL enqueues all application threads between CPU and GPU before starting execution, with no track of executed threads over time, online thread-partitioning is not possible. To enable this, threads can be grouped into several equal size chunks, and

enqueueing and partitioning done at chunk level. However, it imposes challenges to identify the best number of chunks (each chunk contains the same number of threads) so that the cores are neither starved nor overfed from threads.

- Upon an application completion, identifying the energy saving benefits of adaptation (to higher number of cores) for each executing application by considering timing and energy overheads.
- Upon an application arrival, energy-efficient and performance satisfying adaptation (to lower number of cores) of executing applications to facilitate performance satisfying execution of the arrived application.
- Collaboration between CPU and GPU is required by identifying their processing capabilities at various adaptation points such that balanced execution can be performed.

## Contributions

To address the above-mentioned challenges, we have made the following contributions:

- (1) To reduce adaptation overhead, for each application, energy-efficient mapping and thread-partitioning when using a different number of CPU core are explored at design-time and stored for using at run-time, as shown in Figure 2. Additionally, the best number of chunks for each application is also explored at design-time and execution starts by feeding chunks to CPU and GPU continuously by collaborating on their processing capabilities.
- (2) A collaborative adaptation approach that performs an energy-efficient mapping and thread-partitioning between CPU and GPU cores for concurrent applications, and applies energy optimizing adaptations (remapping and thread-repartitioning) at application completion and arrival through CPU and GPU collaboration, as shown in Figure 3.
- (3) Implementation and experimental validity of the proposed approach on an Odroid-XU3 platform [2] (contains a state-of-the-art multi-core SoC prevalent in tablet/smart-phone devices).

## Experimental set-up

Odroid-XU3 platform containing Samsung Exynos 5422 heterogeneous multi-core SoC [1], running Ubuntu Linux Kernel 3.10.96 has been used to evaluate the proposed adaptive approach that runs on one of the big (Cortex-A15) cores. Energy consumption is computed by measuring the power values from on-board power sensors of Odroid-XU3 every

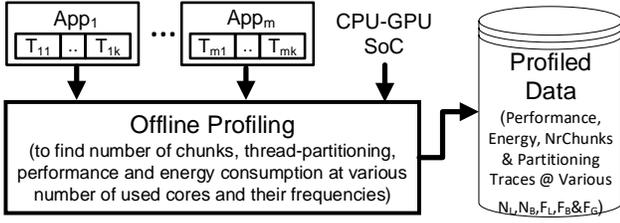


Figure 2: Offline profiling.

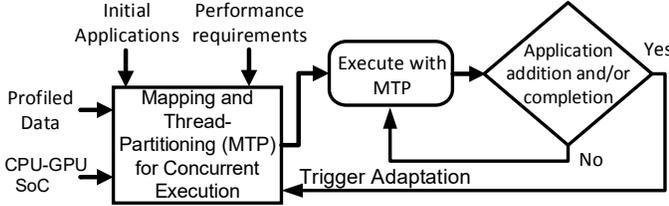


Figure 3: Adaptive mapping and thread-partitioning.

100ms. A power measurement circuitry present in the SoC estimates the power as: voltage  $\times$  current, where four real time current/voltage sensors are used for four power domains: big, LITTLE, GPU and DRAM. This allows us to compute energy consumption of all the software components, e.g., adaptive algorithm, profiled data, OS, drivers, applications, etc., running in the SoC. The applications considered for evaluation are CORRELATION (CR), SYR2K (S2), SYRK (SR), COVARIANCE (CV), 2MM (2M), 2DCONV (2D), GEMM (GE) and MVT (MV), which are available in Polybench benchmark [16]. Each application has a fixed number of work-groups and a randomly assigned performance requirement. The applications are considered in various random mixes to make a representative set of concurrent applications and any of them can be added to the SoC at run-time. Such scenarios can be observed in a mobile phone where user tries to run more applications at the same time, e.g., internet browser and mp3 player, and jpeg decoding at the next moment.

## Results

As a sample result, Figure 4 provides the energy consumption results when our approach and other closely related approaches are employed for different run-time scenarios, e.g. two and three concurrent applications. It can be observed that our approach achieves lower energy consumption compared to existing approaches. This is due to beneficial adaptations at an application completion, where freed cores are allocated to the currently running application, if beneficial. Additionally, performance improvements are achieved, which cannot be shown due to space limitation.

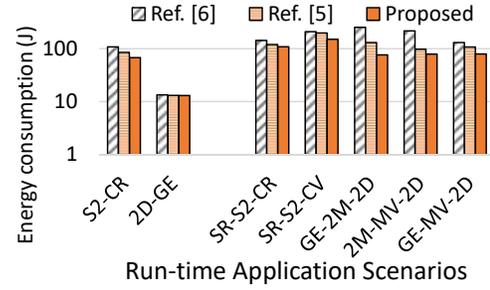


Figure 4: Energy consumption by various approaches for different run-time scenarios: two and three concurrent applications.

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