Robust Tests for White Noise and Cross-Correlation*

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Abstract

Commonly used tests to assess evidence for the absence of autocorrelation in a univariate time series or serial cross-correlation between time series rely on procedures whose validity holds for i.i.d. data. When the series are not i.i.d., the size of correlogram and cumulative Ljung-Box tests can be significantly distorted. This paper adapts standard correlogram and portmanteau tests to accommodate hidden dependence and non-stationarities involving heteroskedasticity, thereby uncoupling these tests from limiting assumptions that reduce their applicability in empirical work. To enhance the Ljung-Box test for non-i.i.d. data a new cumulative test is introduced. Asymptotic size of these tests is unaffected by hidden dependence and heteroskedasticity in the series. Related extensions are provided for testing cross-correlation at various lags in bivariate time series. Tests for the i.i.d. property of a time series are also developed. An extensive Monte Carlo study confirms good performance in both size and power for the new tests. Applications to real data reveal that standard tests frequently produce spurious evidence of serial correlation.

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Keywords: Serial correlation, cross-correlation, heteroskedasticity, martingale differences.

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1 Introduction

Temporal dependence is one of the primary characteristics of economic and financial data that are measured sequentially over time. In studying such data, estimation of and inference on the serial correlation \( \rho_k = \text{corr}(x_t, x_{t-k}) \) is a common first step in the analysis of time series data \( \{x_t\} \) or regression residuals. For a sample \( x_1, ..., x_n \), estimation of \( \rho_k \) by the sample serial correlation \( \hat{\rho}_k \) for various lags \( k = 1, 2, ... \) and testing whether it is significant dates back to the early years of the twentieth century, primarily to Yule (1926) who introduced the terminology serial correlation. Yule highlighted the need to understand the degree of time persistence in the data prior to applying correlation/regression analysis and characterized this phenomenon as the ‘time correlation problem’ in his earlier Royal Society address (Yule, 1921). To aid analysis, Yule introduced the sample serial correlation \( \hat{\rho}_k \) along with the standard confidence band \( \pm z_{a/2}/\sqrt{n} \) for testing its significance, \( H_0 : \rho_k = 0 \) under the simplifying assumption that the data are identically and independently distributed (i.i.d.), bringing the problem into the existing framework of the Pearson correlation coefficient.

Bartlett (1946) provided a major step forward in a more general analysis by deriving an asymptotic formula, now known as Bartlett’s formula, for \( \text{cov}(\hat{\rho}_j, \hat{\rho}_k) \) for a stationary linear process \( \{x_t\} \) driven by i.i.d. errors. The joint asymptotic distribution of \( \hat{\rho} = (\hat{\rho}_1, ..., \hat{\rho}_m)' \) was given by Anderson and Walker (1964) and was found to be normal with variance-covariance matrix \( n^{-1}W \) where the elements of \( W \) are given by Bartlett’s formula. An important aspect of this formula is that the asymptotic variance matrix depends only on the autocorrelations \( \rho_k \) themselves and not fourth moments, as is the case for sample autocovariances.\(^1\) Hannan and Hyde (1972) relaxed the i.i.d. assumption on the errors and showed that asymptotic normality remains valid under some additional regularity assumptions on the noise.

Besides testing for significant serial correlation at one lag \( k \), it is common to test the cumulative hypothesis \( H_0 : \rho_1 = ... = \rho_m = 0 \) using the portmanteau statistics of Box and Pierce (1970) and Ljung and Box (1978). The Box-Pierce statistic is based on the observation that the matrix \( W \) in the asymptotic distribution of \( \hat{\rho} \) reduces to the identity matrix under the i.i.d. assumption\(^2\) on \( x_t \), while the Ljung-Box statistic entails a slightly better performance in finite samples. They find that for i.i.d and normally distributed data, the cumulative statistics have a \( \chi^2_m \) limit distribution when

\(^1\)The asymptotic variance of \( \hat{\rho}_h \), for instance, is \( n^{-1} \sum_{j=1}^{\infty} (\rho_{h+j} + \rho_{h-j} - 2\rho_h \rho_j)^2 \), a simple derivation of which is given in Phillips and Solo (1992).

\(^2\)In this case \( \text{var}(\hat{\rho}_h) = n^{-1} \sum_{j=1}^{\infty} (\rho_{h+j} + \rho_{h-j} - 2\rho_h \rho_j)^2 = n^{-1} \) as the only non-zero element in the sum occurs when \( j = h \).
applied to raw data and a \( \chi^2_{m-p-q} \) limit distribution when used for residuals of fitted ARMA\((p,q)\) models. They indicated that the normality assumption is not essential for these results.

Concern that these standard tests of \( H_0 : \rho_k = 0 \) and \( H_0 : \rho_1 = \ldots = \rho_m = 0 \) are not suitable under heteroskedasticity or non-independence of uncorrelated noise \( x_t \) was highlighted by Granger and Andersen (1978) and by Taylor (1984). The first paper warned against the use of standard tests in bilinear data and the second raised concerns for testing in models where the \( \{x_t\} \) are heteroskedastic. Taylor (1984) provided a modified standard error for \( \hat{\rho}_k \), resulting in a robust confidence band and a robust \( t \)-statistic \( \tilde{t}_k \), given in (4) below, as well as a robust cumulative statistic, given in (12).

Since then, various authors have modified the statistic \( t_k = \sqrt{n} \hat{\rho}_k \) and/or its cumulative portmanteau versions in similar ways to Taylor (1984) so that they are applicable for testing uncorrelated non-i.i.d. noise in which the covariance matrix \( W \) is diagonal but not the identity – among others, see Diebold (1986), Lo and MacKinlay (1989), Robinson (1991), Francq and Zakoïan (2009), Kokoszka and Politis (2011).

However, the matrix \( W \) is not always diagonal. Practical settings involving economic and financial uncorrelated data \( x_t \) for which a non-diagonal \( W \) is relevant appear in Cumby and Huizinga (1992), Guo and Phillips (2001), Lobato, Nankervis and Savin (2002) and Francq, Roy and Zakoïan (2005). These papers typically assume that \( \{x_t\} \) is stationary and has a martingale difference structure or is strongly mixing. Guo and Phillips (2001) estimated the covariance matrix \( W \) by its empirical counterpart, while the other papers used nonparametric procedures. Taking a different approach Romano and Thombs (1996) and Horowitz, Lobato and Savin (2006) used bootstrap methods to obtain suitable critical values for standard test procedures under the null assumption that the uncorrelated data \( \{x_t\} \) are strongly mixing.

Similar issues arise in testing cross correlation in bivariate time series \( \{x_t, y_t\} \), where interest and early attempts date back over a century, for instance to Hooker (1901). Unsurprisingly, the original work on estimation and testing for zero cross-correlation \( \rho_{xy,k} = \text{corr}(x_t, y_{t-k}) \) relied again on sample cross-correlations based on the theory of the Pearson correlation coefficient. Later studies such as Haugh (1976) and Haugh and Box (1977) examined testing for zero cross-correlation at an individual lag and using cumulative versions of the statistics. For the same reason as in the univariate case, tests for the absence of cross-correlation may be invalidated when the time series are not i.i.d. Corrected versions of the statistics have been examined (e.g., Kyriazidou, 1998, that extend to the bivariate case the univariate results of Cumby and Huizinga, 1992). However, the assumptions used are restrictive, imposing additional technical
conditions and excluding unconditional heteroskedasticity.

Test statistics based on the correlogram either with the standard confidence band $\pm z_{\alpha/2}/\sqrt{n}$ suggested by Yule (1926) or that based on Bartlett’s (1946) formula or the cumulative statistics of Box and Pierce (1970) and Ljung and Box (1978) are all still in extensive use today and are present in most statistical packages. Despite the literature addressing the complications of departures from i.i.d. noise, problems with finite sample performance and complexity of implementation seem to have prevented replacement of these methods with procedures that extend applicability to more general settings. Similarly, cross-correlogram tests are usually implemented with standard confidence bands and the cumulative Haugh-Box test for cross-correlation is rarely reported in applications.

The goal of the present paper is to develop a formulation and method of implementation that will enable testing with both univariate and bivariate time series that is robust to multiple forms of heteroskedastic and dependence departures from i.i.d noise. Our approach is based on extending the original robust test by Taylor (1984) for the absence of correlation at an individual lag and a corresponding cumulative portmanteau test, together with analogous testing procedures for the bivariate case. Taylor’s test for correlation at a specific lag and our cumulative test are both easy to apply and demonstrate good size control for a large class of uncorrelated data covering martingale difference noise of unspecified form with time varying unconditional variance.

The rest of the paper is organized as follows. Section 2 outlines the model, introduces the tests and presents limit theory for the case of univariate time series testing. Section 3 develops corresponding tests for zero cross-correlation in the bivariate case, a problem that has attracted much less attention in the literature in spite of its links to Granger causality testing. Section 4 considers direct testing of the hypothesis that a time series is i.i.d. Various tests of this hypothesis have been used in the literature and often relate to testing the random walk hypothesis using variate differences. Standard tests based on the squared time series have been proposed by McLeod and Li (1983) and Campbell, Lo and MacKinlay (1997, Chapter 2) provide for a brief summary. We suggest testing procedures (both cumulative and individual lag tests) that combine the tests on correlation of the data in levels with absolutes or squared values. Wong and Ling (2005) and Zhu (2013) used similar methods to test for absence of autocorrelation in residuals and absolute (squared) residuals in a general linear model, in particular, of a fitted ARMA-GARCH model. Different from our tests, those tests do not require demeaning of residuals and their asymptotic distributions depend on the parameters of a fitted model. An extensive Monte Carlo study was conducted and the results are
presented in Section 5 with recommended guidelines for practical implementation of the various tests. Section 6 reports an empirical application of the test procedures to financial data. The paper is accompanied by an Online Supplement (Dalla et al., 2019) consisting of two documents. The first (I) contains proofs of all the results in the paper. The second (II) reports the findings of the full Monte Carlo study.

An R package and an EViews add-in (named testcorr) have been created by the authors and are now available to implement all the testing procedures developed in the paper.

2 Tests for zero correlation

While stationarity is commonly assumed, it is not necessary for testing absence of correlation in a time series. Indeed, for a series \{x_t\} of uncorrelated random variables the condition that the autocorrelation function (ACF) \( \rho_k = \text{corr}(x_t, x_{t-k}) = 0 \) at lag \( k = 1, 2, \ldots \) is well defined for all \( t \) with or without an assumption of stationarity. Its empirical version, the sample autocorrelation \( \hat{\rho}_k \) at the lag \( k \neq 0 \), based on observed data \( x_1, \ldots, x_n \),

\[
\hat{\rho}_k = \frac{\sum_{t=k+1}^{n} (x_t - \bar{x})(x_{t-k} - \bar{x})}{\sum_{t=1}^{n} (x_t - \bar{x})^2}, \quad \bar{x} = \frac{1}{n} \sum_{t=1}^{n} x_t
\]

remains a valid tool for testing for zero correlation at lag \( k \). Such testing does not require assumptions of independence or stationarity of \( \{x_t\} \), thereby enabling a more general approach to testing for white noise uncorrelatedness in data.

There is, of course, a large literature on estimation of the autocorrelation function \( \rho_k \) by \( \hat{\rho}_k \) for stationary times series \( \{x_t\} \). The asymptotic distribution of the sample autocorrelations \( (\hat{\rho}_1, \ldots, \hat{\rho}_m)' \) for a stationary linear process was given by Anderson and Walker (1964) and Hannan and Hyde (1972) and has the form

\[
\sqrt{n}(\hat{\rho}_1 - \rho_1, \ldots, \hat{\rho}_m - \rho_m) \to_d \mathcal{N}(0, W)
\]

where \( W \) is a matrix whose elements are given by Bartlett’s formula. If the \( \{x_t\} \) are i.i.d. random variables, the matrix \( W \) reverts to the identity matrix \( I_m \) and (2) reduces to the standard asymptotic result

\[
\sqrt{n}(\hat{\rho}_1, \ldots, \hat{\rho}_m) \to_d \mathcal{N}(0, I_m)
\]

used for testing \( H_0 : \rho_k = 0 \) at lag \( k \), just as in Yule (1926), with the confidence band
\( \pm z_{\alpha/2}/\sqrt{n} \) for zero correlation at significance level \( \alpha \). Methods based on this procedure are still heavily used and came into prominence following the influential work of Box and Jenkins (1970).

When \( \{x_t\} \) is uncorrelated but not i.i.d. the standard method for testing zero serial correlation based on the asymptotic distribution in (3) generally fails. This was first noted by Granger and Andersen (1978) and Taylor (1984). Taylor (1984) suggested correcting the standard error of \( \hat{\rho}_k \), leading to the robust \( t \)-statistic

\[
\tilde{t}_k = \frac{\sum_{t=k+1}^{n} e_{tk}}{\left( \sum_{t=k+1}^{n} e_{tk}^2 \right)^{1/2}}, \quad e_{tk} = (x_t - \bar{x})(x_{t-k} - \bar{x}),
\]

so that in testing \( H_0 \) the sample autocorrelation \( \hat{\rho}_k \) should be corrected for its variance

\[
\tilde{t}_k = \hat{\rho}_k \tilde{c}_k \to_D N(0, 1), \quad \tilde{c}_k = \frac{\tilde{t}_k}{\hat{\rho}_k}.
\]

This correction leads to a \( \pm z_{\alpha/2}/\tilde{c}_k \) confidence band for zero correlation at lag \( k \).

Taylor showed that \( \tilde{c}_k^{-2} \) is an unbiased estimate of the variance of \( \hat{\rho}_k \) when \( x_t \) has symmetric density but he did not prove the asymptotic normality given in (5). He also suggested a corrected cumulative test, as given in (12) below.

The \( t \)-statistic \( \tilde{t}_k \) takes the form of a self-normalizing sum. Our aim is to establish asymptotic normality for \( \tilde{t}_k \) as well as corresponding cumulative tests in a general setting where the observed data sample \( x_1, ..., x_n \) is a series of uncorrelated random variables that may be dependent and non-stationary. We seek an approach that does not require verification of additional technical assumptions and allows the applied researcher to be somewhat agnostic about the structure and generating mechanism of the uncorrelated data \( x_t \).

In this paper we assume that \( x_t \) satisfies

\[
x_t = \mu + h_t \varepsilon_t,
\]

where \( \{\varepsilon_t\} \) is a stationary ergodic martingale difference (m.d.) sequence with respect to some \( \sigma \)-field filtration \( F_t \) that includes the natural filtration with \( \mathbb{E}[\varepsilon_t|F_{t-1}] = 0 \), \( \mathbb{E}\varepsilon_t^4 < \infty \), \( \mu = \mathbb{E}x_t \) and a deterministic scaling factor \( h_t \equiv h_{tn} \) is a sequence of real numbers for which, as \( n \to \infty \),

\[
\max_{1 \leq t \leq n} h_t^4 = o(\sum_{t=1}^{n} h_t^4), \quad \sum_{t=2}^{n} (h_t - h_{t-1})^4 = o(\sum_{t=1}^{n} h_t^4).
\]

(7)
Then, \( \varepsilon_t \) allows for conditional heteroskedasticity via \( \mathbb{E}[\varepsilon_t^2 | \mathcal{F}_{t-1}] \) and \( h_t \) introduces unconditional heterogeneity over \( t \). For any \( k \neq 0 \), we have

\[
\text{corr}(x_t, x_{t-k}) = \text{corr}(\varepsilon_t, \varepsilon_{t-k}) = 0 \quad \text{for all } t.
\]

Since m.d. variables \( \varepsilon_t \) are uncorrelated, the variables \( x_t \) are also uncorrelated. In simulations involving \( h_t \) we use the examples \( h_t = (t/n) \) and \( h_t = 1 + aI(\tau_1 < t/n \leq \tau_2) \) where \( 0 \leq \tau_1 < \tau_2 \leq 1 \), \( a \neq 0 \) and \( I \) is the indicator function. In general, it is easy to see that the (weak trend) scaling factor \( h_t = v(t/n) \) satisfies (7) if \( v(x), 0 \leq x \leq 1 \), is a piecewise bounded differentiable function with a bounded derivative. Our main example for an ergodic m.d. sequence \( \{\varepsilon_t\} \) is a stationary GARCH noise. More generally, if \( \{\eta_t\} \) is an i.i.d. noise and \( f \) is a measurable function then \( \varepsilon_t = \eta_t f(\eta_{t-1}, \eta_{t-2}, \ldots) \) is a stationary ergodic m.d. sequence (e.g. Stout (1974, Th. 3.5.8), an example being \( \varepsilon_t = \eta_t \eta_{t-1} \).

The statistics \( t_k = \sqrt{n} \hat{\rho}_k, \tilde{t}_k \) and their cumulative versions have been examined by various authors either for raw data or for residuals from some estimated model. In either case, it is common to assume that \( \{x_t\} \) is as in (6) but stronger assumptions on \( (h_t, \varepsilon_t) \) are imposed. Most authors assume that \( h_t = 1 \) and \( \varepsilon_t \) is an m.d. noise of a specific type. A few authors allow \( h_t \) to be deterministic and to vary with \( t \), but require \( \{\varepsilon_t\} \) to be i.i.d. so that the \( x_t \) remain independent. An exception is Lo and MacKinlay (1989) where \( h_t \) is permitted to be time varying and mixing conditions are imposed on \( \{\varepsilon_t\} \) but with restrictive moment conditions that exclude, for example, GARCH data with skewed innovations.

The following result establishes the asymptotic distribution of the \( t \)-statistic \( \tilde{t}_k \) given in (4).

**Theorem 2.1.** Suppose that \( x_1, \ldots, x_n \) is a sample from a sequence given in (6) and the \( h_t \) satisfy (7). Then for any fixed integer \( k \neq 0 \), as \( n \to \infty \),

\[
\tilde{t}_k \to_D \mathcal{N}(0,1). \tag{8}
\]

Moreover, for \( m = 1, 2, \ldots \),

\[
(\tilde{t}_1, \ldots, \tilde{t}_m) \to_D \mathcal{N}(0, R) \tag{9}
\]

where \( R = (r_{jk}) \) is an \( m \times m \) matrix with elements

\[
r_{jk} = \text{corr}(\varepsilon_1 \varepsilon_{1-j}, \varepsilon_1 \varepsilon_{1-k}), \quad j, k = 1, \ldots, m.
\]
By virtue of (8), $\hat{c}_k \hat{\rho}_k \to_D N(0,1)$ where

$$\hat{c}_k = c_k(1 + o_p(1)), \quad c_k := \frac{\sum_{t=1}^n h_t^2}{(\sum_{t=1}^n h_t^4)^{1/2}} \to \infty,$$

(10)

which leads to a $\pm z_{\alpha/2}/\hat{c}_k$ confidence band for zero correlation at lag $k$.

Box and Pierce (1970) and Ljung and Box (1978) suggested the well-known cumulative statistics

$$BP_m = n \sum_{k=1}^m \hat{\rho}_k^2, \quad LB_m = (n + 2)n \sum_{k=1}^m \frac{\hat{\rho}_k^2}{n - k},$$

(11)

for portmanteau testing of the joint null hypothesis $H_0 : \rho_1 = \ldots = \rho_m = 0$. These tests are based on the property (3) of the sample ACF $\hat{\rho}_k$'s showing that under $H_0$ the tests are asymptotically $\chi^2_m$ distributed.

When $\{x_t\}$ is uncorrelated but not i.i.d. and (3) fails these cumulative tests produce size distortions in testing. In turn, Taylor (1984) suggested the corrected-for-variance cumulative statistic

$$\sum_{k=1}^m \tilde{\tau}_k^2$$

(12)

for testing $H_0 : \rho_1 = \ldots = \rho_m = 0$. This formulation corresponds to the diagonal matrix $R = I$ in (9) which holds only when the variables $\omega_j = \varepsilon_1 \varepsilon_{1-j}$ are uncorrelated. Setting $\tilde{\tau} = (\tilde{\tau}_1, \ldots, \tilde{\tau}_m)'$, result (9) of Theorem 2.1 implies that

$$\tilde{\tau}' R^{-1} \tilde{\tau} \to_D \chi^2_m, \quad \tilde{\tau}' \hat{R}^{-1} \tilde{\tau} \to_D \chi^2_m,$$

(13)

for any consistent estimate $\hat{R} \to_p R$ of $R$. The matrix $R$ is positive definite and $R^{-1}$ exists if $\varepsilon_1 \neq 0$ a.s., see Lemma 3.1 below.

As discussed in the Introduction, various authors have examined statistics (4) and (12). However, as noted by Guo and Phillips (2001) (see also Cumby and Huizinga (1992), Lobato et al. (2002) and Francq et al. (2005)) who arrived at (13) under different assumptions on the data generating process $\{x_t\}$, there are sequences $\{x_t\}$ that are uncorrelated but not independent for which the matrix $R$ is not diagonal and therefore the cumulative statistic (12) is invalid. Guo and Phillips (2001) use a similar estimate $\hat{R}$ of $R$ to our estimate given in (14) below. Cumby and Huizinga (1992) and Lobato et al. (2002) use kernel nonparametric methods and Francq et al. (2005) introduce an autoregressive approximation method to estimate $W$ and $R$. These authors all assume stationarity of $\{x_t\}$, thereby excluding unconditional heterogeneity.
We will estimate $R$ by $\hat{R} = (\hat{r}_{jk})$ where $\hat{r}_{jk}$ are sample cross-correlations of the variables $(e_{tj}, t = 1, \ldots, n)$ and $(e_{tk}, t = 1, \ldots, n)$:

$$\hat{r}_{jk} = \frac{\sum_{t=\max(j,k)+1}^{n} e_{tj} e_{tk}}{(\sum_{t=\max(j,k)+1}^{n} e_{tj}^2)^{1/2}(\sum_{t=\max(j,k)+1}^{n} e_{tk}^2)^{1/2}}. \quad (14)$$

To improve the finite sample performance of the cumulative test, we use the thresholded version $\hat{R}^* = (\hat{r}_{jk}^*)$ of $\hat{R}$ where

$$\hat{r}_{jk}^* = \hat{r}_{jk} I(|\tau_{jk}| > \lambda) \quad \text{with} \quad \lambda = 2.576 \quad (15)$$

where $\tau_{jk}$ is a self-normalized $t$-type statistic

$$\tau_{jk} = \frac{\sum_{t=\max(j,k)+1}^{n} e_{tj} e_{tk}}{(\sum_{t=\max(j,k)+1}^{n} e_{tj}^2)^{1/2}(\sum_{t=\max(j,k)+1}^{n} e_{tk}^2)^{1/2}}. \quad (16)$$

Notice that $\hat{R}^*$ is the sample analogue of the variance-covariance matrix of $\tilde{t}$ for which we threshold the off-diagonal elements by checking at the 1% significance level whether they are significant. This is a simpler approach to that undertaken by Cumby and Huizinga (1992), Lobato et al. (2002) or Francq et al. (2005).

The next theorem establishes the asymptotic properties for the cumulative tests

$$Q_m = \tilde{t}' \hat{R}^{-1} \tilde{t}, \quad \tilde{Q}_m = \tilde{t}' \hat{R}^{*-1} \tilde{t} \quad (17)$$

for the joint hypothesis $H_0 : \rho_1 = \ldots = \rho_m = 0$. In the empirical applications and Monte Carlo study described later in the paper we use the cumulative statistic $\tilde{Q}_m$ with the suggested threshold setting $\lambda = 2.576$.

**Theorem 2.2.** Under the assumptions of Theorem 2.1, for any $m = 1, 2, \ldots$ and with any threshold $\lambda > 0$, as $n \to \infty$,

$$\hat{R} \to_p R, \quad \hat{R}^* \to_p R, \quad Q_m \to_D \chi_m^2, \quad \tilde{Q}_m \to_D \chi_m^2. \quad (18, 19)$$

The assumptions of Theorems 2.1 and 2.2 are minimal and less restrictive than those used so far in the literature. They allow for both non-stationarity (unconditional heteroskedasticity) and dependent martingale difference type uncorrelated noise including GARCH type conditional heteroskedasticity.

The test $Q_m$ without thresholding based on property $\hat{R} \to_p R$ suffers some size
distortion in finite samples for moderate and large \( m \) and moderate samples sizes \( n \).

We will show that thresholding has no impact on consistency asymptotically, i.e. for any \( \lambda > 0 \), \( \hat{R}^* \to_p R \), but it will improve finite sample performance in many cases where the off-diagonal elements are either very small or zero, in particular when \( R \) is sparse (see Online Supplement II). The following simple arguments show consistency
\[
\hat{r}_{jk} = \hat{r}_{jk} I(\tau_{jk} \geq \lambda) \to_p r_{jk}.
\]
Indeed, \( \hat{r}_{jk} \to_p r_{jk} \), and \( I(\tau_{jk} \geq \lambda) \to_p 1 \) if \( r_{jk} \neq 0 \).

The objective of thresholding is to improve estimation of \( r_{jk} \) when taking zero values. Here \( \lambda \) plays the role of a critical level in testing the null hypothesis that \( r_{jk} \) (or its numerator) is zero. We recommend using it as a preselected tuning parameter \( \lambda \) which does not depend on \( n \). If \( \tau_{jk} \to_D N(0,1) \), thresholding with \( \lambda = 2.576 \) can be interpreted as testing for \( r_{jk} = 0 \) at a 1% significance level. Use of thresholding has negligible impact on power, which is shown in the Online Supplement II.

As will be apparent in the next section, the assumptions of Theorems 3.1 and 3.2 in the bivariate case render the above methods of analysis valid for a univariate series in a straightforward way. In particular, since any measurable function \( y_t = f(x_t, x_{t-1}, ..., x_{t-k}) \) of a stationary ergodic process \( \{x_t\} \) is also a stationary ergodic process (e.g., Stout (1974, Cor. 3.5.2)), if \( E|y_t| < \infty \) it follows that
\[
E|n^{-1} \sum_{t=1}^{n} y_t - E y_1| \to 0, \quad n \to \infty.
\]

Thus the bivariate series \( \{x_t, y_t\} \) with \( y_t = x_t \) satisfies the conditions of Theorems 3.1 and 3.2 in the following section, which imply the results of Theorems 2.1 and 2.2, and Corollary 3.1 implies (10) above.

### 3 Tests for zero cross-correlation

For bivariate time series \( \{x_t, y_t\} \) we observe data \( x_1, ..., x_n \) and \( y_1, ..., y_n \) and are interested in testing possible cross-correlation between these time series at various lags. Denote by \( \hat{\rho}_{xy,k} \) the \( k \)-th sample cross-correlation estimate of the \( k \)-th cross-correlation \( \rho_{xy,k} = \text{corr}(x_t, y_{t-k}) \) for \( k = 0, 1, ... \)
\[
\hat{\rho}_{xy,k} = \frac{\sum_{t=k+1}^{n} (x_t - \bar{x})(y_{t-k} - \bar{y})}{(\sum_{t=1}^{n} (x_t - \bar{x})^2) (\sum_{t=1}^{n} (y_{t-k} - \bar{y})^2)^{1/2}}, \quad \bar{x} = \frac{1}{n} \sum_{t=1}^{n} x_t, \quad \bar{y} = \frac{1}{n} \sum_{t=1}^{n} y_t.
\]

The asymptotic theory for such sample cross-correlations was given in Hannan (1970). Haugh and Box (1977) developed a test for cross-correlation under the as-
sumption of independent series \( \{x_t\} \) and \( \{y_t\} \). But there is little literature on testing cross-correlation using the sample statistic \( \hat{\rho}_{xy,k} \) when the series are not independent or when they are heteroskedastic. Although in regression analysis the issue of heteroskedasticity has been addressed, graphs of the sample cross-correlations typically display confidence bands based on \( \pm z_{\alpha/2}/\sqrt{n} \), corresponding to the t-statistic

\[
t_{xy,k} = \sqrt{n}\hat{\rho}_{xy,k}
\]  

for testing \( H_0 : \rho_{xy,k} = 0 \) under independence conditions. Further, bivariate analogues of cumulative standard statistics are rarely analyzed and often involve additional tests for the significance of the univariate autocorrelations of \( \{x_t\} \) and \( \{y_t\} \), as in Tsay (2010) for example. In what follows, we examine the Haugh (1976) and Haugh and Box (1977) test for cross-correlation

\[
HB_{xy,m} = n^2 \sum_{k=0}^{m} \frac{\hat{\rho}_{xy,k}^2}{n-k}
\]  

for testing \( H_0 : \rho_{xy,0} = \rho_{xy,1} = \ldots = \rho_{xy,m} = 0 \) which assumes independence of the time series \( \{x_t\} \) and \( \{y_t\} \).

Similar arguments to those of the univariate case in Section 2 show that standard normal and \( \chi^2_m \) approximations for the statistics in (20) and (21) are not always valid for bivariate times series \( \{x_t, y_t\} \) which are not uncorrelated and stationary, independent noises. To provide a more general framework, we assume in this paper that \( \{x_t, y_t\} \) satisfy

\[
x_t = \mu_x + h_t \varepsilon_t, \quad y_t = \mu_y + g_t \eta_t,
\]

where \( \{\varepsilon_t\}, \{\eta_t\} \) are stationary sequences, \( \mathbb{E}\varepsilon_t = \mathbb{E}\eta_t = 0, \mathbb{E}\varepsilon_t^4 < \infty, \mathbb{E}\eta_t^4 < \infty \) and \( h_t, g_t \) are real numbers that satisfy conditions made explicit in Assumption A and Theorem 3.1 below.

Notice that \( \rho_{xy,k} = \text{corr}(x_t, y_{t-k}) = \text{corr}(\varepsilon_t, \eta_{t-k}) \). However, when \( \rho_{xy,k} = 0 \), the standard normal approximation for \( t_{xy,k} \) may not hold because of the presence of heteroskedasticity in \( \{x_t\} \) and \( \{y_t\} \) or dependence between the two uncorrelated series. For that reason, in order to develop a robust test of \( H_0 : \rho_{xy,k} = 0, k \geq 0 \), we define the following robust t-statistic

\[
\tilde{t}_{xy,k} = \frac{\sum_{t=k+1}^{n} e_{xy,tk}}{(\sum_{t=k+1}^{n} e_{xy,tk}^2)^{1/2}}, \quad e_{xy,tk} = (x_t - \bar{x})(y_{t-k} - \bar{y}).
\]
Our objective is to establish the asymptotic normality

$$\tilde{t}_{xy,k} = \hat{\rho}_{xy,k} \hat{c}_{xy,k} \to D N(0,1), \quad \hat{c}_{xy,k} = \frac{\tilde{t}_{xy,k}}{\hat{\rho}_{xy,k}}$$  \hspace{1cm} (24)$$

for \( k \geq 0 \) such that \( \text{corr}(\varepsilon_t, \eta_{t-k}) = 0 \). This correction leads to a \( \pm z_{\alpha/2} / \hat{c}_{xy,k} \) confidence band for zero cross-correlation \( \rho_{xy,k} \) at lag \( k \).

As we see below, (24) requires the first series \( \{x_t\} \) to be an uncorrelated noise or, more specifically, an m.d. sequence. In what follows, we first allow the uncorrelated series \( \{x_t\} \) and \( \{y_t\} \) to be mutually dependent, and subsequently examine the case where they are mutually independent. Test consistency is considered last.

Clearly, for (24) to hold, we need additional assumptions on \( \{\varepsilon_t, \eta_t\} \). The conditions below are formulated in terms of the product series \( \omega_{tk} := \varepsilon_t \eta_{t-k}, k \geq 0 \).

**Assumption A.** For \( j,k \geq 0 \), \( \{\omega_{tk}\}, \{\omega_{tj}\omega_{tk}\} \) are stationary sequences, \( \mathbb{E}\omega_{tk}^2 < \infty \), and

$$\mathbb{E}\left| n^{-1} \sum_{t=1}^{n} \omega_{tj}\omega_{tk} - \mathbb{E}[\omega_{tj}\omega_{tk}] \right| \to 0, \quad n \to \infty. \hspace{1cm} (25)$$

The weights \( h_t, g_t \) satisfy the following conditions: setting \( q_n = \sum_{t=1}^{n} h_t^2 g_t^2 \),

$$\max_{t=1, \ldots, n} h_t^4 = o(q_n), \quad \left( \sum_{t=1}^{n} h_t^4 \right)^{1/2} \left( \sum_{t=2}^{n} (g_t - g_{t-1})^4 \right)^{1/2} = o(q_n), \hspace{1cm} (26)$$

$$\max_{t=1, \ldots, n} g_t^4 = o(q_n), \quad \left( \sum_{t=1}^{n} g_t^4 \right)^{1/2} \left( \sum_{t=2}^{n} (h_t - h_{t-1})^4 \right)^{1/2} = o(q_n).$$

These conditions lead to a transparent asymptotic theory. It can be shown that robust testing procedures remain valid for a large class of non-smooth scaling factors \( h_t \) and \( g_t \) that meet these conditions.

**I: The case of mutually dependent series \( \{x_t\} \) and \( \{y_t\} \).**

First, we assume that \( x_t \) and the lagged variables \( y_{t-k} \) are uncorrelated but not mutually independent. For example, suppose that in (22) \( \{\varepsilon_t\} \) is an m.d. sequence with respect to some \( \sigma \)-field \( \mathcal{F}_t \), and \( \eta_{t-k} \) is \( \mathcal{F}_{t-1} \) measurable. Then \( \varepsilon_t \eta_{t-k} \) is also an m.d. sequence so that \( \mathbb{E}[\varepsilon_t \eta_{t-k}|\mathcal{F}_{t-1}] = 0 \), and thus \( \text{corr}(x_t, y_{t-k}) = 0 \).

Bivariate series \( x_t \) and \( y_{t-k} \) can be uncorrelated at some lags, say \( k = m_0, \ldots, m \) where \( 0 \leq m_0 \leq m \), and correlated at other lags, say \( k = 0 \). The next theorem establishes the multivariate limit distribution of the vector \( (\tilde{t}_{xy,m_0}, \ldots, \tilde{t}_{xy,m}) \) when
\[ \text{corr}(x_t, y_{t-k}) = 0 \text{ for } k = m_0, \ldots, m. \] Subsequently, we use this vector to test the hypothesis \( \text{corr}(x_t, y_{t-k}) = 0 \), \( k = m_0, \ldots, m \). To show asymptotic normality for the statistic \( \tilde{t}_{xy,k} \) based on the centered variables \( x_t - \bar{x} \) and \( y_t - \bar{y} \) we make the following assumption.

**Assumption B.** The autocovariance functions \( \text{cov}(\varepsilon_t, \varepsilon_{t-k}) = \gamma_{\varepsilon,k} \), \( \text{cov}(\eta_t, \eta_{t-k}) = \gamma_{\eta,k} \) of the stationary sequences \( \{\varepsilon_t\} \) and \( \{\eta_t\} \) satisfy the following covariance summability conditions

\[ \sum_k |\gamma_{\varepsilon,k}| < \infty, \quad \sum_k |\gamma_{\eta,k}| < \infty. \tag{27} \]

These conditions are clearly satisfied by white noise/m.d. sequences \( \{\varepsilon_t\} \) or \( \{\eta_t\} \).

**Theorem 3.1.** Suppose that \( \{x_t, y_t\} \) in (22) satisfy Assumptions A, B and (26).

If \( \{\varepsilon_t\eta_{t-k}\}, k = m_0, \ldots, m \) (0 \( \leq m_0 \leq m \)) are m.d. sequences with respect to the same \( \sigma \)-field \( \mathcal{F}_t \), with \( \mathbb{E}[\varepsilon_t\eta_{t-k}|\mathcal{F}_{t-1}] = 0 \), then, as \( n \to \infty \),

\[ (\tilde{t}_{xy,m_0}, \ldots, \tilde{t}_{xy,m}) \to_D \mathcal{N}(0, R_{xy}) \tag{28} \]

where \( R_{xy} = (r_{xy,jk})_{j,k=m_0,\ldots,m} \) is a matrix with elements

\[ r_{xy,jk} = \text{corr}(\varepsilon_{1-j}, \varepsilon_{1-k}). \]

In particular, \( \tilde{t}_{xy,k} \to_D \mathcal{N}(0, 1) \) for \( k = m_0, \ldots, m \).

Simulations confirm that the test for zero cross-correlation at individual lag \( k = 0, 1, 2, \ldots \) based on \( \tilde{t}_{xy,k} \) is well sized in finite samples for numerous lags when \( \{x_t\} \) is serially uncorrelated and \( \{y_t\} \) is serially uncorrelated or series of dependent random variables.

Theorem 3.1 implies that \( \hat{c}_{xy,k}\hat{\rho}_{xy,k} \to_D \mathcal{N}(0, 1) \) for \( k = m_0, \ldots, m \). The Corollary below shows that the “standard error” \( \hat{c}_{xy,k}^{-1} \hat{\rho}_{xy,k}/\tilde{t}_{xy,k} \) has a deterministic asymptotic form. This implies that the robust non-rejection region \( \pm z_\alpha/\hat{c}_{xy,k} \) of the null hypothesis of a lag \( k \) zero correlation at the \( \alpha \) significance level can be interpreted as a \( 1 - \alpha \) confidence interval for zero correlation. For this result we employ some additional assumptions on the scaling factors \( \{h_t, g_t\} \) and the autocovariograms of the stationary sequences \( \{\varepsilon^2_t\} \) and \( \{\eta^2_t\} \):

\[ \max_{t=1,\ldots,n} h_t^2 = o(\sum_{t=1}^n h_t^2), \quad \max_{t=1,\ldots,n} g_t^2 = o(\sum_{t=1}^n g_t^2), \quad \text{cov}(\varepsilon^2_k, \varepsilon^2_0) \to 0, \quad \text{cov}(\eta^2_k, \eta^2_0) \to 0 \text{ as } k \to \infty. \tag{29} \]
Corollary 3.1. Let (29) and the assumptions of Theorem 3.1 hold. Then,

\[
\hat{c}_{xy,k} = \left( \sum_{t=1}^{n} h_{t}^{2} e_{t}^{2} \sum_{t=1}^{n} g_{t}^{2} \sum_{t=1}^{n} \left( \frac{\varepsilon_{1}^{2} \eta_{1,t-k}}{E[\varepsilon_{1}^{2} \eta_{1,t-k}^{2}]} \right) \right)^{1/2} \left( 1 + o_{p}(1) \right)
\]  

(30)

We next consider cumulative tests. First, note that the matrix \( R_{xy} \) in (28) is positive definite and \( R_{xy}^{-1} \) exists if \( \varepsilon_{1} \neq 0 \) a.s.; see Lemma 3.1 below. The convergence (28) implies

\[
\tilde{t}_{xy} R_{xy}^{-1} \tilde{t}_{xy} \rightarrow_{D} \chi_{m-m_{0}+1}^{2}
\]  

where \( \tilde{t}_{xy} = (\tilde{t}_{xy,m_{0}}, ..., \tilde{t}_{xy,m})' \). (31)

For testing the cumulative hypothesis \( H_{0} : \rho_{xy,m_{0}} = ... = \rho_{xy,m} = 0 \), we suggest the following standardized statistics

\[
Q_{xy,m} = \tilde{t}_{xy}' \hat{R}_{xy}^{-1} \tilde{t}_{xy}, \quad \tilde{Q}_{xy,m} = \tilde{t}_{xy}' \hat{R}_{xy}^{*^{-1}} \tilde{t}_{xy},
\]  

(32)

where \( \hat{R}_{xy} = (\hat{r}_{xy,jk})_{j,k=m_{0},...,m} \) and \( \hat{R}_{xy}^{*} \) are consistent estimates of the matrix \( R_{xy} \). We define

\[
\hat{r}_{xy,jk} = \frac{\sum_{t=\max(j,k)+1}^{n} e_{xy,tj} e_{xy,tk}}{\left( \sum_{t=\max(j,k)+1}^{n} e_{xy,tj}^{2} \right)^{1/2} \left( \sum_{t=\max(j,k)+1}^{n} e_{xy,tk}^{2} \right)^{1/2}}, \quad j, k = i, ..., m.
\]  

(33)

To improve the finite sample performance of the cumulative test, we suggest the thresholded version \( \hat{R}_{xy}^{*} = (\hat{r}_{xy,jk}^{*})_{j,k=m_{0},...,m} \) of \( \hat{R}_{xy} \) where

\[
\hat{r}_{xy,jk}^{*} = \hat{r}_{xy,jk} I(|\tau_{xy,jk}| > \lambda) \quad \text{with} \quad \lambda = 2.576
\]  

(34)

and \( \tau_{xy,jk} \) is a t-statistic constructed as

\[
\tau_{xy,jk} = \frac{\sum_{t=\max(j,k)+1}^{n} e_{xy,tj} e_{xy,tk}}{\left( \sum_{t=\max(j,k)+1}^{n} e_{xy,tj}^{2} e_{xy,tk}^{2} \right)^{1/2}}.
\]  

(35)

Just as in the univariate case, \( \hat{R}_{xy}^{*} \) is the sample analogue of the variance-covariance matrix of \( \tilde{t}_{xy} \) where we threshold its off-diagonal elements by checking at the 1% level whether they are significant. In our simulations and applications we set \( \lambda = 2.576 \), but in theory other threshold values \( \lambda > 0 \) can be used.

The limit theory of these statistics for testing cross-correlation between two serially uncorrelated time series at cumulative lags is given in the following result.
Theorem 3.2. Under the assumptions of Theorem 3.1, for any $\lambda > 0$, as $n \to \infty$,

\[
\begin{align*}
\hat{R}_{xy} & \to_p R_{xy}, \quad \hat{R}^*_{xy} \to_p R_{xy}, \\
Q_{xy,m} & \to_D \chi^2_{m-m_0+1}, \quad \hat{Q}_{xy,m} \to_D \chi^2_{m-m_0+1}.
\end{align*}
\]  

(36)  

(37)

Simulations show that if both \{\textit{x}_t\} and \{\textit{y}_t\} are serially uncorrelated the robust cumulative test $\hat{Q}_{xy,m}$ based on the thresholded estimate $\hat{R}^*_{xy}$ with parameter $\lambda = 2.576$ in most cases corrects adequately for size, whereas for large $m$ the cumulative test based on $Q_{xy,m}$ suffers some size distortion. We note that in simulations for large values of $m$ the statistic $\hat{Q}_{xy,m}$ may sometimes be negative since the matrix $\hat{R}^*_{xy}$ is not necessarily positive definite.

Different from the univariate case, Assumption A is employed to avoid assuming ergodicity of the stationary sequence \{\textit{e}_t, \textit{e}_{t-j}, \textit{y}_{t-k}\}, which implies (25), see Stout (1974, Corollary 3.5.2). In general, ergodicity of the separate sequences \{\textit{e}_t\} and \{\textit{y}_t\} does not necessarily imply ergodicity of \{\textit{e}_t, \textit{e}_{t-j}, \textit{y}_{t-k}\} and thus (25). Property (25) alone is sufficient for the proofs to hold.

Theorem 3.1 assumes \{\textit{e}_t, \textit{y}_{t-k}\} to be an m.d. sequence. This is a weak assumption and allows for various types of dependence between the sequences \{\textit{e}_t\} and \{\textit{y}_t\}. For example, if \{\textit{e}_t\} is an m.d. sequence with $E[\textit{e}_t|\mathcal{F}_{t-1}] = 0$ and $\textit{y}_t = g(\textit{e}_t, \textit{e}_{t-1}, \ldots)$ is a measurable function of $\textit{e}_s$, $s \leq t$, then \{\textit{e}_t, \textit{y}_{t-k}\} is an m.d. sequence with respect to $\mathcal{F}_t$ for $k \geq 1$, so that

$$E[\textit{e}_t, \textit{y}_{t-k}|\mathcal{F}_{t-1}] = \textit{y}_{t-k}E[\textit{e}_t|\mathcal{F}_{t-1}] = 0.$$  

Simulations show that both the modified tests $\tilde{t}_{xy,k}$ and $\tilde{Q}_{xy,m}$ for zero cross-correlation (at individual and cumulative lags) manifest good size control when \{\textit{x}_t\} and \{\textit{y}_t\} are series of uncorrelated variables with time varying variances, and when they are mutually uncorrelated but not necessarily independent. The standard tests $t_{xy,k}$ and $HB_{xy,m}$ require the series \{\textit{x}_t\} and \{\textit{y}_t\} to be mutually independent stationary uncorrelated noises. The test $\tilde{t}_{xy,k}$ at individual lags also achieves good size control when the lagged series is correlated, whereas the standard test $t_{xy,k}$ requires independence of \{\textit{x}_t\} and \{\textit{y}_t\} for good performance.

The next result verifies the existence of $R^{-1}_{xy}$. For $z = (z_1, \ldots, z_m)$, $m \geq 1$ define $\text{Cov}(z) = (\text{cov}(z_j, z_k))$ and $\text{Corr}(z) = (\text{corr}(z_j, z_k))$.

Lemma 3.1. Let \{\textit{y}_t\} be a stationary sequence with $E\textit{y}_t = 0$, $0 < E\textit{y}^2_t < \infty$, autocovariance sequence $\gamma_\textit{y}(h) = E(\textit{y}_t\textit{y}_{t-h})$, and spectral density $f_\textit{y}(x)$, $x \in [-\pi, \pi]$. Then:
(i) $\text{Cov}(\eta)$ and $\text{Corr}(\eta)$ are positive definite for any $\eta = (\eta_1, ..., \eta_m)$; and

(ii) if $z_j = \varepsilon_1 \eta_{1-j}$, $Ez_j = 0$, $Ez_j^2 < \infty$ for $j \geq 1$ and $\varepsilon_1 \neq 0$ a.s. then $\text{Cov}(z)$ and $\text{Corr}(z)$ are positive definite for any $z = (z_1, ..., z_m)$.

II: The case of mutually independent series $\{x_t\}$ and $\{y_t\}$.

If $\{x_t\}$ and $\{y_t\}$ are mutually independent, then $\text{corr}(x_t, y_{t-k}) = 0$ and $\text{corr}(y_t, x_{t-k}) = 0$ for $k \geq 0$. Properties (28) and (37) of the test statistic $\tilde{t}_{xy,k}$ for an individual lag and the corresponding cumulative test statistic are preserved if the series $\{x_t\}$ is an uncorrelated m.d. sequence while $\{y_t\}$ may be sequence of dependent variables.

**Theorem 3.3.** Assume that $\{x_t, y_t\}$ in (22) satisfy Assumptions A, B and (26) and $\{x_t\}$ and $\{y_t\}$ are mutually independent. Suppose $\{\varepsilon_t\}$ in (26) is an m.d. sequence. Then, for any $0 \leq m_0 \leq m$, as $n \to \infty$,

\[
\begin{align*}
\tilde{t}_{xy} &= (\tilde{t}_{xy,m_0}, ..., \tilde{t}_{xy,m})' \to_D N(0, R_{xy}), \\
\tilde{t}_{yx} &= (\tilde{t}_{yx,m_0}, ..., \tilde{t}_{yx,m})' \to_D N(0, R_{yx}),
\end{align*}
\]

where $R_{xy} = R_{yx} = R_y = (r_{y,jk})$ and $r_{y,jk} = \text{corr}(y_j, y_k)$, $j, k = m_0, ..., m$.

In particular, $\tilde{t}_{xy,k} \to_D N(0, 1)$ for any lag $k = -1, 0, 1, \ldots$. Moreover,

\[
\begin{align*}
Q_{xy,m} &\to_D \chi^2_{m+1}, \quad \tilde{Q}_{xy,m} \to_D \chi^2_{m+1} \\
\tilde{t}_{yx}^2 \tilde{R}_{xy}^{-1} &\frac{\tilde{t}_{yx}}{\tilde{R}_{xy}} \to_D \chi^2_{m-m_0+1}, \quad \tilde{t}_{yx}^2 \tilde{R}_{xy}^{* -1} \tilde{t}_{xy} \to_D \chi^2_{m-m_0+1}
\end{align*}
\]

where $\tilde{R}_{xy}$ and $\tilde{R}_{xy}^*$ are defined as above in (33) and (34) with $m_0 = 0$.

Consistent estimates $\tilde{R}_{xy}$ and $\tilde{R}_{xy}^*$ of $R_{xy} = R_y$ require the first variable $\{x_t\}$ to be an uncorrelated m.d. sequence. Notice that $\tilde{R}_{yx} \to_p I \neq R_{yx} = R_y$. Hence, applying the test $\tilde{Q}_{yx,m}$ instead of $\tilde{t}_{yx}^2 \tilde{R}_{xy}^{* -1} \tilde{t}_{xy}$ in (40) when the lead series $\{y_t\}$ is dependent may lead to significant size distortions.

**Remark 3.1.** Testing for cross-correlations, the robust cumulative test $\tilde{Q}_{xy,m}$ is well sized in simulations when both $\{x_t\}$ and $\{y_t\}$ are serially uncorrelated but suffers size distortions after a few lags when one of the series is serially correlated. Clearly, thresholding does not improve the estimate of $R_{xy,m}$ sufficiently in finite samples when $R_{xy,m}$ is not sparse as in Theorem 3.3 and the robust test $\tilde{Q}_{xy,m}$ produces correct size only for a few low lags (see Figure 3(c)). Size can be distorted for all lags when the lead series is dependent (see Theorem 3.3). Hence, in applied work we recommend using the robust cumulative test $\tilde{Q}_{xy,k}$ in cases when both series are serially uncorrelated.
Finally, if the time series \( \{x_t\} \) and \( \{y_t\} \) are mutually independent but neither \( \{x_t\} \) nor \( \{y_t\} \) is white noise, the standard normal approximation for \( \tilde{t}_{xy,k} \) does not generally hold. In such cases, even if
\[
\tilde{t}_{xy,k} \to_D \mathcal{N}(0, \sigma_{xy}^2)
\]
the variance \( \sigma_{xy}^2 = \sum_{j=-\infty}^{\infty} \text{corr}(\varepsilon_0, \varepsilon_j)\text{corr}(\eta_0, \eta_j) \) is not unity, as shown in the following result.

**Proposition 3.1.** Assume that \( \{x_t, y_t\} \) in (22) satisfy Assumptions A, B and (26). Suppose that sequences \( \{x_t\} \) and \( \{y_t\} \) are mutually independent. Then, for any \( k \geq 0 \),
\[
\tilde{t}_{xy,k} = s_{nk} + o_p(1), \quad n \to \infty, \tag{41}
\]
where \( \mathbb{E}s_{nk} = 0 \), \( \text{var}(s_{nk}) \to \sigma_{xy}^2 = \sum_{j=-\infty}^{\infty} \text{corr}(\varepsilon_0, \varepsilon_j)\text{corr}(\eta_0, \eta_j) \). For the definition of \( s_{nk} \) see (23) in the proof in Online Supplement I.

**III: Test consistency.**

To conclude this section we show that the test for correlation at lag \( k \) based on \( \tilde{t}_{xy,k} \) is consistent when \( \text{corr}(x_t, y_{t-k}) \neq 0 \). To do so, we make some further assumptions on the components \( \omega_{tk} = \varepsilon_t \eta_{t-k} \) and \( (h_t, g_t) \) of \( \{x_t, y_t\} \) in (22).

**Assumption C.** \( \{\omega_{tk}\} \) is a stationary sequence whose covariances satisfy the summability condition
\[
\sum_{j=-\infty}^{\infty} |\text{cov}(\omega_{1k}, \omega_{jk})| < \infty, \tag{42}
\]
and \( (h_t, g_t) \) are such that
\[
\sum_{t=k+1}^{n} |h_t(g_t - g_{t-k})| = o(\sum_{t=1}^{n} h_t g_t), \quad q_n^{-1/2} \sum_{t=1}^{n} h_t g_t \to \infty, \tag{43}
\]
where \( q_n = \sum_{t=1}^{n} h_t^2 g_t^2 \), as defined earlier.

Condition (42) is a standard weak dependence condition on the covariances of the sequence \( \{\omega_{tk}\} \), and condition (43) is satisfied by many weight sequences \( (h_t, g_t) \) that induce unconditional heterogeneity in the series over time, such as linear time trends.

**Theorem 3.4.** Let \( \{x_t, y_t\} \) be as in (22) and Assumptions A, B, C and (26) hold. Suppose that for some \( k \geq 0 \), \( \text{corr}(x_t, y_{t-k}) \neq 0 \). Then, as \( n \to \infty \),
\[
\tilde{t}_{xy,k} = \frac{(\sum_{t=1}^{n} h_t g_t)}{(\sum_{t=1}^{n} h_t^2 g_t^2)^{1/2} (\mathbb{E}[\varepsilon_1^2 \eta_{1-k}^2])^{1/2}} (1 + o_p(1)). \tag{44}
\]
Consistency of the tests follow directly from (44) in view of (43).

**Remark 3.2.** Our results cover as a special case the test for zero Pearson correlation \( r \) between two variables \( x \) and \( y \), which is the cross-correlation \( \rho_{xy,0} \) at lag \( k = 0 \) between \( x \) and \( y \). When samples of \( x \) and \( y \) are selected randomly and do not have the same variance, the test for \( r = 0 \) based on the standard test statistic \( \hat{t}_{xy,0} \) is susceptible to size distortions whereas the robust test \( \tilde{t}_{xy,0} \) remains well-sized.

### 4 Tests for the i.i.d. property

In this section we examine a simple test for the i.i.d. property of a time series \( \{x_t\} \) based on a sample \( x_1, ..., x_n \). Campbell et al. (1997, Chapter 2) provide a brief exposition of this approach for use in financial econometrics. We assume that

\[
x_t = \mu + \varepsilon_t \tag{45}
\]

where \( \{\varepsilon_t\} \) is a sequence of i.i.d. random variables with \( \mathbb{E}\varepsilon_t = 0, \mathbb{E}\varepsilon_t^2 < \infty \). Denote \( \rho_{x,k} = \text{corr}(x_t, x_{t-k}) \) and define

\[
\rho_{|x|,k} = \text{corr}(|x_t - \mu|, |x_{t-k} - \mu|), \quad \rho_{x^2,k} = \text{corr}((x_t - \mu)^2, (x_{t-k} - \mu)^2).
\]

Clearly, if \( \{x_t\} \) is i.i.d., then \( \rho_{x,k} = \rho_{|x|,k} = \rho_{x^2,k} = 0 \) for \( k \neq 0 \). With this approach, the problem of testing the i.i.d. property of the time series \( \{x_t\} \) is reduced to testing for the absence of correlation in \( \{x_t\} \) and \( \{|x_t - \mathbb{E}x_t|\} \), or alternatively in \( \{x_t\} \) and \( \{(x_t - \mathbb{E}x_t)^2\} \). Other tests involving nonparametric density estimation (e.g., Gretton and Györfi, 2010) are available but are considerably more complex in their implementation. The present approach has the benefit of simplicity and makes use of the test machinery developed earlier.

Our test statistics combine the levels of the data \( \{x_t\} \) and either absolute \( \{|x_t - \bar{x}|\} \) or squared \( \{(x_t - \bar{x})^2\} \) deviations from the sample mean \( \bar{x} \). We denote by \( \hat{\rho}_{x,k}, \hat{\rho}_{|x|,k} \) and \( \hat{\rho}_{x^2,k} \) the sample correlation (1) computed using the data \( x_t, |x_t - \bar{x}| \) and \( (x_t - \bar{x})^2 \), respectively. Define

\[
\tau_{x,k} = \frac{n}{(n-k)^{1/2}} \hat{\rho}_{x,k}, \quad \tau_{|x|,k} = \frac{n}{(n-k)^{1/2}} \hat{\rho}_{|x|,k}, \quad \tau_{x^2,k} = \frac{n}{(n-k)^{1/2}} \hat{\rho}_{x^2,k}.
\]

Denote \( r_{\varepsilon,|\varepsilon|} = \text{corr}(\varepsilon_1, |\varepsilon_1|), r_{\varepsilon,\varepsilon^2} = \text{corr}(\varepsilon_1, \varepsilon_1^2) \), and set
\[ V_{x|x} = \begin{pmatrix} 1 & r_{\varepsilon,|\varepsilon|}^2 \\ r_{\varepsilon,|\varepsilon|}^2 & 1 \end{pmatrix}, \quad V_{x,x}^2 = \begin{pmatrix} 1 & r_{\varepsilon,\varepsilon^2}^2 \\ r_{\varepsilon,\varepsilon^2}^2 & 1 \end{pmatrix}. \]

The next theorem establishes the joint distribution for the statistics \( \tau_{x,k}, \tau_{x|z,k} \) and \( \tau_{x,k}, \tau_{x^2,k} \).

**Theorem 4.1.** Let \( x_1, ..., x_n \) be a sample from an i.i.d. sequence (45). If \( \tau_{x^2,k} \) is employed, assume in addition that \( \mathbb{E}\varepsilon_1^2 < \infty \). Then for \( m \geq 1 \),

\[
(t_{x,1}, t_{x|z,1}, ..., t_{x,m}, t_{x|z,m}) \rightarrow_D \mathcal{N}(0, V_{x|x|,2m}),
\]

\[
(t_{x,1}, t_{x^2,1}, ..., t_{x,m}, t_{x^2,m}) \rightarrow_D \mathcal{N}(0, V_{x,x^2,2m})
\]

where \( V_{x|x|,2m} = \text{diag}(V_{x|x|}, ..., V_{x|x|}) \) and \( V_{x,x^2,2m} = \text{diag}(V_{x,x^2}, ..., V_{x,x^2}) \) are \( 2m \times 2m \) block-diagonal matrices. In particular, for \( k \geq 1 \),

\[
(t_{x,k}, t_{x|z,k}) \rightarrow_D \mathcal{N}(0, V_{x|x}), \quad (t_{x,k}, t_{x^2,k}) \rightarrow_D \mathcal{N}(0, V_{x,x^2}).
\]

Observe that \( V_{x|x|,2m} = I, V_{x,x^2,2m} = I \) are identity matrices if the \( \{\varepsilon_t\} \) have a symmetric distribution, since then \( r_{\varepsilon,|\varepsilon|} = r_{\varepsilon,\varepsilon^2} = 0 \). In general, the non-diagonal elements \( r_{\varepsilon,|\varepsilon|}^2 \) and \( r_{\varepsilon,\varepsilon^2}^2 \) in the matrices \( V_{x|x|,2m} \) and \( V_{x,x^2,2m} \) are likely to be small. Hence, the standard normal limit \( \mathcal{N}(0, I) \) may be a good approximation in (46) and (47) in finite samples. This suggests the following approximation

\[
\sum_{k=1}^{m} (\tau_{x,k}^2 + \tau_{x|z,k}^2) \sim \chi^2_{2m}, \quad \sum_{k=1}^{m} (\tau_{x,k}^2 + \tau_{x^2,k}^2) \sim \chi^2_{2m},
\]

which is easy to use in applied work. Good performance of the latter statistics is confirmed by simulations in the Monte Carlo study.

To verify the i.i.d. property of \( \{x_t\} \), we test at individual lags and cumulatively for the absence of correlation in levels \( \{x_t\} \) and absolute values \( \{|x_t - \mathbb{E}x_t|\} \) via the following null hypotheses

\[
H_0: \rho_{x,k} = 0, \rho_{x|z,k} = 0 \text{ at individual lag } k \geq 1,
\]

\[
H_0: \rho_{x,k} = 0, \rho_{x|z,k} = 0 \text{ for } k = 1, ..., m \text{ for } m \geq 1 \text{ (cumulative)}
\]

using respectively the statistics

\[
J_{x|x|,k} = \frac{n^2}{n-k}(\hat{\rho}_{x,k}^2 + \hat{\rho}_{x|z,k}^2), \quad C_{x|x|,m} = \sum_{k=1}^{m} J_{x|x|,k}.
\]

Alternatively, we may test for the absence of correlation in levels \( \{x_t\} \) and squares
\{(x_t - \mathbb{E}x_t)^2\} via the hypotheses
\begin{align*}
H_0 & : \rho_{x,k} = 0, \rho_{x^2,k} = 0 \text{ at individual lag } k \geq 1, \\
H_0 & : \rho_{x,k} = 0, \rho_{x^2,k} = 0 \text{ for } k = 1, \ldots, m \text{ (cumulative)}
\end{align*}
using respectively the statistics
\begin{align*}
J_{x,x^2,k} &= \frac{n^2}{n-k}(\hat{\rho}_{x,k}^2 + \hat{\rho}_{x^2,k}^2), \\
C_{x,x^2,m} &= \sum_{k=1}^{m} J_{x,x^2,k}.
\end{align*}
(51)

If an i.i.d. time series \(\{x_t\}\) has a symmetric distribution, then Theorem 4.1 shows that, as \(n \to \infty\),
\begin{align*}
J_{x,|x|,k}, J_{x,x^2,k} & \to D \chi^2_2, \\
C_{x,|x|,m}, C_{x,x^2,m} & \to D \chi^2_{2m}.
\end{align*}
(52)

Simulations confirm that the \(\chi^2_{2m}\) distribution provides a good approximation also for i.i.d. time series \(x_t\) with non-symmetric distributions that do not exhibit severe skewness. Simulations show that these tests have good power in the presence of dependence, conditional heteroskedasticity or non-stationarity when \(\mathbb{E}x_t\) or \(\text{Var}(x_t)\) varies with time.

Related to these results, we recall that some standard tests are already in the literature as mentioned in the Introduction. Notably, convergence for the cumulative test statistic
\[\sum_{k=1}^{m} \frac{n^2}{n-k} \hat{\rho}_{x^2,k}^2 \to P \chi^2_m\]
based on squares \(x_t^2\) of an i.i.d. sequence was established by McLeod and Li (1983). The present tests involve both levels and absolute values or both levels and squares. Similar tests for residuals of a fitted ARMA-GARCH model were used by Wong and Ling (2005) and Zhu (2013). Different from our testing procedures, residual based tests do not require demeaning and their asymptotic distribution may depend on the parameters of a fitted model.

5 Monte Carlo experiments

This section presents Monte Carlo findings on the finite sample performance of the standard and robust tests for zero correlation given in Sections 2 and 3 and the tests for the i.i.d. property given in Section 4. We use a variety of models for \(\{x_t\}\) and \(\{x_t, y_t\}\), sample sizes \(n = 100, 300, 1000\) and the experiments each involve 5,000 replications. We evaluate the rejection frequency (in \%) of the test statistics at significance level \(\alpha = 5\%\) using the asymptotic critical values and power is not size corrected. The
standard test $t_k$ and the robust $\tilde{t}_k$ are based on 1.96 critical values, respectively. Figures 1-5 report rejection frequencies (size and power) for a subset of models for $n = 300$ and $k, m = 0, 1, 2, ..., 30$ lags. The full findings for $n = 300$ are given in the Online Supplement II of this paper to which readers are referred for complete details and results for $n = 100, 1000$ are available upon request.

Figures 1 and 2 report size and power of the tests for zero correlation based on the statistics $\tilde{t}_k$, $t_k$, $\tilde{Q}_m$ with $\lambda = 2.576$ and $LB_m$. Figure 1 shows that the standard statistic $t_k$ and the cumulative $LB_m$ statistic have distorted size when the data are non-i.i.d., see e.g. models (b)-(d). The accumulation of the $t$-test size distortion in the $LB_m$ test is evident at all lags. On the other hand, the robust statistics $\tilde{t}_k$ and $\tilde{Q}_m$ achieve the nominal size of $\alpha = 5\%$ for all models in Figure 1. For the i.i.d. data in model (a) the standard and robust methods give similar results as expected. Figure 2 displays test power. The results show some loss in power for the robust test statistics compared to the standard tests. All tests show spurious power when the data $x_t$ is uncorrelated but has time varying mean, see models (c)-(d).

Figures 3 and 4 report test results for zero cross-correlation for bivariate time series $\{x_t\}$ and $\{y_t\}$ based on the statistics $\tilde{t}_{xy,k}$, $t_{xy,k}$, $\tilde{Q}_m$ with $\lambda = 2.576$ and $HB_m$. When series of independent variables $\{x_t\}$ and $\{y_t\}$ are heteroskedastic but jointly independent, as in Figure 3 model (a), the robust statistics produce correct size whereas the standard tests are all oversized. When the time series $\{x_t\}$ and $\{y_t\}$ are uncorrelated but not mutually independent, as in model (b), the robust statistics give correct size whereas the standard ones over-reject. When $\{x_t\}$ and $\{y_t\}$ are mutually independent, but one of the two has either autocorrelation or time varying mean, as in models (c) and (d), then both the standard and robust tests at individual lag give the correct size, but the cumulative tests tend to become oversized. The latter outcome was unexpected, as the theory of Section 3 for model (c) would suggest the cumulative tests would be well-sized. It seems that $\hat{R}_{xy,m}^*$ does not estimate well the non-sparse autocorrelation matrix $R_y$ of $y_t$ for this moderate sample size, especially for bigger lags $m$. When the time series are cross-correlated, as in Figure 4 models (a)-(b), we observe similar power across the standard and robust statistics, with some loss in power at bigger lags for the robust cumulative statistic. In Figure 4 models (c)-(d), the time series $\{x_t\}$ and $\{y_t\}$ are jointly independent but we observe spurious power, when both of them have autocorrelation, like in (c) and as suggested by theory, or when both of them have time varying mean, as in (d).

Figure 5 reports the test results for the i.i.d. property using the statistics $J_{x|x,k}$, $J_{x,x^2,k}$ and $C_{x|x,m}$, $C_{x,x^2,m}$. The size of the tests at individual lags and the size of the cumu-
relative tests are satisfactory in model (a), and we observe good power in discriminating the non-i.i.d. models (b)-(d). In particular, the statistics based on the absolute values have overall similar or better power properties than those based on the squares.

Some general conclusions from the simulation study are as follows. First, we find that in testing for correlation or for the i.i.d. property, tests at individual lag $k$ perform well at all lags. The cumulative tests with $\lambda = 2.576$ perform overall well at most lags, with tiny distortions at the bigger lags. This conclusion is based on the Monte Carlo size properties of our tests for the models considered in the Online Supplement II. Second, we note that one needs to test for a constant mean prior to applying the univariate (both standard and robust) tests for absence of correlation. Third, for bivariate tests it is useful to check for constant mean (e.g. using the Bai and Perron (1998) test for multiple structural breaks) as well as for serial correlation in each time series prior to applying the tests. Fourth, the findings indicate that our tests for the i.i.d. property based on the $\chi^2_{2m}$ approximation perform well unless the distributions are extremely skewed.

**Remark 5.1.** The theory and Monte Carlo study suggest the following:

(i) In testing for autocorrelation the series needs to have constant mean.

(ii) In testing for cross-correlation each of the series needs to have constant mean and to be serially uncorrelated when applying the portmanteau type statistics or at least one when applying the $t$-type tests.

(iii) The values $\lambda = 1.96, 2.576$ are good candidates for the threshold in the robust portmanteau statistics, with $\lambda = 2.576$ performing better at relatively large lags.
Figure 1: Size. Rejection frequencies (in %) at $\alpha = 5\%$ of robust (red line) $\tilde{t}_k$ and standard (grey line) $t_k$ tests (left) and robust (red line) $\tilde{Q}_m$ and standard (grey line) $LB_m$ cumulative tests (right) at lags $k, m = 1, 2, ..., 30$. $\varepsilon_t \sim \text{iid } \mathcal{N}(0, 1)$.
Figure 2: Power. Rejection frequencies (in %) at $\alpha = 5\%$ of robust (red line) $\tilde{t}_k$ and standard (grey line) $t_k$ tests (left) and robust (red line) $\tilde{Q}_m$ and standard (grey line) $LB_m$ cumulative tests (right) at lags $k, m = 1, 2, ..., 30$. $\varepsilon_t \sim \text{iid } \mathcal{N}(0, 1)$.

(a) $x_t = 0.2x_{t-1} + \varepsilon_t$

(b) $x_t = r_t^2, r_t = \sigma_t \varepsilon_t, \sigma_t^2 = 1 + 0.2r_{t-1}^2 + 0.7\sigma_{t-1}^2$

(c) $x_t = I(t/n > 0.5) + \varepsilon_t$

(d) $x_t = (h_t \varepsilon_t)^2, h_t = 1 + I(t/n > 0.5)$
Figure 3: Size. Rejection frequencies (in %) at $\alpha = 5\%$ of robust (red line) $\tilde{t}_{xy,k}$ and standard (grey line) $t_{xy,k}$ tests (left) and robust (red line) $\tilde{Q}_{xy,m}$ and standard (grey line) $HB_{xy,m}$ cumulative tests (right) at lags $k,m = 0,1,\ldots,30$. $\varepsilon_t, \eta_t \sim \text{iid } N(0,1)$, $\{\varepsilon_t\}, \{\eta_t\}$ independent.

(a) $x_t = h_t \varepsilon_t$, $y_t = h_t \eta_t$, $h_t = 1 + I(t/n > 0.5)$

(b) $x_t = \varepsilon_t$, $y_t = \exp(z_t) \eta_t$, $z_t = 0.7 z_{t-1} + \varepsilon_t$

(c) $x_t = \varepsilon_t$, $y_t = 0.7 y_{t-1} + \eta_t$

(d) $x_t = m_t + \varepsilon_t$, $y_t = h_t \eta_t$, $m_t = I(t/n > 0.5)$, $h_t = 1 + I(t/n > 0.5)$
Figure 4: Power. Rejection frequencies (in %) at $\alpha = 5\%$ of robust (red line) $\tilde{t}_{xy,k}$ and standard (grey line) $t_{xy,k}$ tests (left) and robust (red line) $\tilde{Q}_{xy,m}$ and standard (grey line) $HB_{xy,m}$ cumulative tests (right) at lags $k, m = 0, 1, ..., 30$. $\varepsilon_t, \eta_t \sim$ iid $\mathcal{N}(0, 1)$, $\{\varepsilon_t\}, \{\eta_t\}$ independent.

(a) $x_t = \sigma_{x,t}\varepsilon_t$, $y_t = \sigma_{y,t}\varepsilon_t$, $\sigma^2_{x,t} = 1 + 0.2x^2_{t-1}$, $\sigma^2_{y,t} = 1 + 0.2y^2_{t-1} + 0.7\sigma^2_{y,t-1}$

(b) $x_t = h_t \varepsilon_t$, $y_t = x_t + x_{t-1} + x_{t-2} + h_t \eta_t$, $h_t = 1 + I(t/n > 0.5)$

(c) $x_t = 0.7x_{t-1} + \varepsilon_t$, $y_t = 0.7y_{t-1} + \eta_t$

(d) $x_t = m_t + \varepsilon_t$, $y_t = m_t + \eta_t$, $m_t = I(t/n > 0.5)$
Figure 5: Size and power. Rejection frequencies (in %) at $\alpha = 5\%$ of $J_{x,|x|,k}$ (red line) and $J_{x,x^2,k}$ (grey line) tests (left) and $C_{x,|x|,m}$ (red line) and $C_{x,x^2,m}$ (grey line) cumulative tests (right) at lags $k, m = 1, 2, \ldots, 30$. $\varepsilon_t \sim \text{iid } \mathcal{N}(0, 1)$.

\[(a)\] $x_t = \varepsilon_t$

\[(b)\] $x_t = r_t$, $r_t = \sigma_t \varepsilon_t$, $\sigma_t^2 = 1 + 0.2 \sigma_{t-1}^2 + 0.7 \sigma_{t-1}^2$

\[(c)\] $x_t = I(t/n > 0.5) + \varepsilon_t$

\[(d)\] $x_t = (1 + I(t/n > 0.5))\varepsilon_t$
6 Empirical application

We report an application of these methods to financial market data covering the period 2008-18. Both the standard and robust tests for absence of correlation are used. We analyze univariate time series of daily returns \( \{x_t\} \) of the FTSE100 index and the bivariate series \( \{x_t, y_t\} \) of the daily returns of the FTSE100 index and gold price.\(^3\) Graphical inspection of the data suggests that the means of both the FTSE100 and gold returns are likely constant.

The results of the univariate analyses are shown in Figures 6 and 7. Panel (a) of Figure 6 contains the correlogram \( \hat{\rho}_k \) (AC) for lags \( k = 1, 2, ..., 10 \) along with 95% and 99% confidence bands (CBs) for insignificant correlation, the standard CBs are based on \( \pm z_{\alpha/2}/\sqrt{n} \) and the robust on \( \pm z_{\alpha/2}(\hat{\rho}_k/\hat{\tau}_k) \) at significance levels \( \alpha = 5\%, 1\% \). Panel (b) reports the values of the standard \( LB_m \) and robust \( \tilde{Q}_m \) cumulative statistics with threshold \( \lambda = 2.576 \) for lags \( k = 1, 2, ..., 30 \) along with their asymptotic critical values at significance levels \( \alpha = 5\%, 1\% \). The CBs of the standard test for correlation at individual lags show evidence of serial correlation at lags \( k = 2, 5 \) at the 1% and at lags \( k = 3, 4 \) at the 5%. The latter is magnified in the \( LB_m \) cumulative test. However, in agreement with the robust CBs, the evidence of serial correlation is insignificant at all individual lags at the 5% level. As such, the cumulative hypothesis of no correlation is not to be rejected by the cumulative test \( \tilde{Q}_m \). To test for the i.i.d. property of \( x_t \), we evaluated the statistics \( J_{x, |x|, k}, J_{x, x^2, k}, C_{x, |x|, m} \) and \( C_{x, x^2, m} \), which are shown in Figure 7. Evidently, this hypothesis is strongly rejected. We therefore conclude that the daily returns of the FTSE100 index during 2008-18 are uncorrelated, but strong evidence affirms that the series is not i.i.d.

The results of bivariate testing are shown in Figure 8. Just as the FTSE100 returns were found to be uncorrelated, similar analysis (not reported here) confirms uncorrelatedness of the gold returns. Panels (a) and (c) contain the cross-correlograms \( \hat{\rho}_{xy,k} \) and \( \hat{\rho}_{yx,k} \) (CC) for lags \( k = 0, 1, ..., 10 \) along with the standard 95% and 99% confidence bands, based on \( \pm z_{\alpha/2}/\sqrt{n} \) and the robust ones based on \( \pm z_{\alpha/2}(\hat{\rho}_{xy,k}/\hat{\tau}_{xy,k}) \) and \( \pm z_{\alpha/2}(\hat{\rho}_{yx,k}/\hat{\tau}_{yx,k}) \) at significance levels \( \alpha = 5\%, 1\% \). In Panels (b) and (d), we report the standard \( HB_{xy,m}, HB_{yx,m} \) and robust \( \tilde{Q}_{xy,m}, \tilde{Q}_{yx,m} \) cumulative statistics with threshold \( \lambda = 2.576 \) for lags \( k = 0, 1, ..., 30 \) and their asymptotic critical values at

\(^3\)The data are sourced from YahooFinance for the FTSE100 index and from the Federal Reserve Bank of St.Louis for the London Bullion Market Association (LBMA) gold price. Both prices are in British pounds. The FTSE100 index is measured at the market closing at 4:30 GMT. The gold price is at 3:00 GMT. Returns are calculated as first differences of log-prices. Missing observations are deleted.
the \( \alpha = 5\%, 1\% \). Standard inference suggests evidence of significant contemporaneous cross-correlation \( \rho_{xy,0} \) at 1\%, as well as cross-correlation \( \rho_{xy,k} \) for lags \( k = 2, 8 \) at 1\% and \( \rho_{yx,k} \) for leads \( k = 5 \) at 1\% and for \( k = 8, 9 \) at 5\% between FTSE100 and gold returns \( x_t \) and \( y_t \). The cumulative hypothesis of zero cross-correlation is rejected at 1\% for all \( m \) by standard tests \( HB_{xy,m}, HB_{yx,m} \). However, the robust CBs do not produce as much evidence of significant cross-correlation. We do find evidence from the robust tests of contemporaneous cross-correlation \( \rho_{xy,0} \) for \( k = 0 \) at 5\%, as well as cross-correlation \( \rho_{xy,k} \) for lags \( k = 2 \) at 5\% and \( k = 8 \) at 1\% and \( \rho_{yx,k} \) for lead \( k = 5 \) at the 5\% between FTSE100 and gold returns \( x_t \) and \( y_t \). Subsequently, using modified test statistics the cumulative hypothesis of zero cross correlation is rejected when \( m = 0 \) at the 5\%. Furthermore, when the FTSE100 return \( x_t \) is leading the hypothesis of zero cross-correlation is rejected at 5\% for some \( m \) and when it is lagging the hypothesis of zero cross-correlation is not rejected at 5\% for all \( m \). Overall, these results indicate evidence that the daily returns of the FTSE100 index and gold during 2008-18 have contemporaneous cross-correlation at \( k = 0 \) but not at different leads and lags for \( k \geq 1 \).

Figure 6: FTSE100 daily returns, 2008-2018. Correlogram

(a) AC \( \hat{\rho}_k \), standard (grey) and robust (red) CB for non-significance of correlation at lags \( k = 1, 2, ..., 10 \).

(b) Standard (grey) \( LB_m \) and robust (red) \( \tilde{Q}_m \) cumulative tests at lags \( m = 1, 2, ..., 30 \).
Figure 7: FTSE100 daily returns, 2008-2018. I.i.d. test

(a) $J_{x|z,k}$ (red), $J_{x,x^2,k}$ (grey) tests at lags $k = 1, 2, ..., 10$.

(b) $C_{x|z,m}$ (red) and $C_{x,x^2,m}$ (grey) tests at lags $m = 1, 2, ..., 30$.

Figure 8: FTSE100 ($x$) and gold ($y$) daily returns, 2008-2018. Cross-correlogram

(a) CC $\hat{\rho}_{xy,k}$, standard (grey) and robust (red) CB for non-significance of cross-correlation at lags $k = 0, 1, ..., 10$.

(b) Standard (grey) $HB_{xy,m}$ and robust (red) $\bar{Q}_{xy,m}$ cumulative tests at lags $m = 0, 1, ..., 30$.

(c) CC $\hat{\rho}_{yx,k}$, standard (grey) and robust (red) CB for non-significance of cross-correlation at lags $k = 0, 1, ..., 10$.

(d) Standard (grey) $HB_{yx,m}$ and robust (red) $\bar{Q}_{yx,m}$ cumulative tests at lags $m = 0, 1, ..., 30$. 

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7 Conclusions

The procedures developed in this paper belong to a class of econometric tests that robustify existing procedures to take account of realistic features of economic and financial data. Tests for zero autocorrelation and zero cross-correlation are among the fundamental starting points in analyzing time series and they are methods that have remained in common use since influential work by Box and Jenkins (1970) and others. The validity of standard procedures of testing is fragile to latent dependencies and non-stationarities that are well known to be present in much economic and financial data. The methods and limit theory in the present paper correct for such fragilities and in doing so complement and generalize earlier work to accommodate such dependencies. The Monte Carlo experiments corroborate the validity of the proposed methods and provide guidelines for practitioners in implementing the new procedures. The empirical application to financial return data demonstrates the utility of these methods in taking account of latent dependencies and thereby avoiding potentially spurious inferences about autocorrelation and cross-correlations in such data. In subsequent work, we plan to adapt the test procedures developed in this paper to models that involve an evolving mean function and a stochastic heterogeneity factor \( h_t \). We plan to show that robust testing procedures remain valid for scaling factors \( h_t \) that do not satisfy the specific smoothness condition (7). Such results naturally involve a more complex correlation matrix \( R \) which depends on \( \{h_t\} \).

References


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