

Energy-Driven Systems and Compute

Towards Self-powered Embedded Computing Systems

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20 October 2020

networking/comms

harvester

power conversion

sensors

user

memory

An *energy harvester* is one part of a *system*

compute

application

user interface(s)

actuators

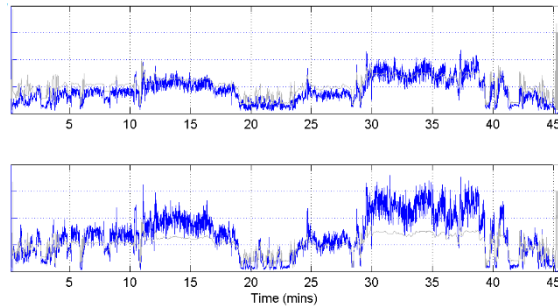
peripherals

design tools

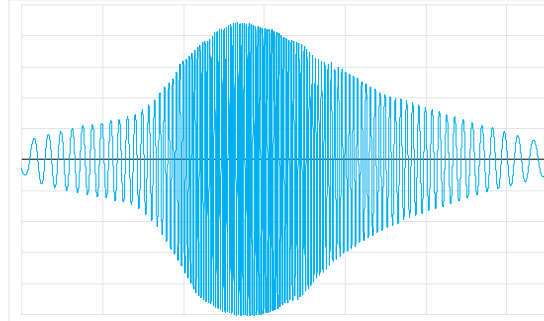
energy storage

ENERGY HARVESTING

varies
temporally

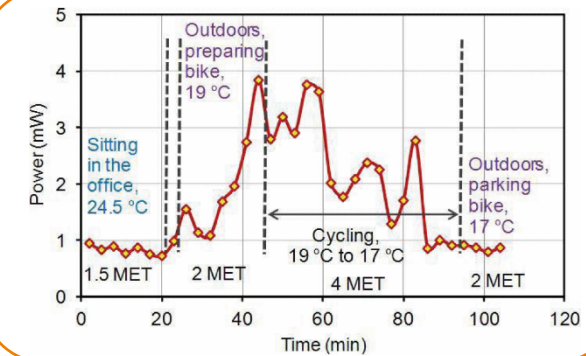


Beeby, S.P. et al. A comparison of power output from linear and non-linear kinetic energy harvesters using real vibration data. Smart Materials and Structures, 22, (7), 075022.



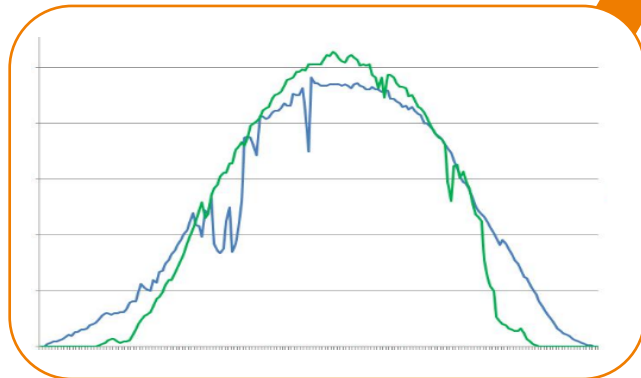
D. Balsamo et al. Hibernus++: a self-calibrating and adaptive system for transiently-powered embedded devices. IEEE TCAD, 1-13.

varies
spatially

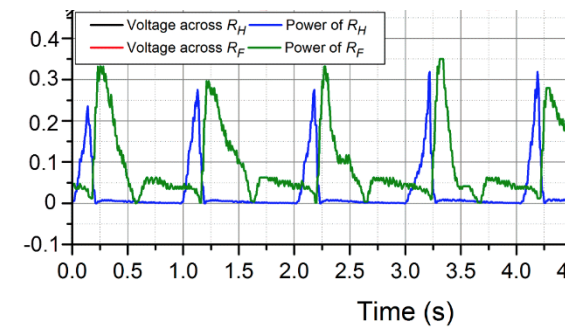


V. Leonov. "Thermoelectric Energy Harvesting of Human Body Heat for Wearable Sensors," IEEE Sensors Journal, vol.13, no.6, pp.2284-91, June 13

Power / Energy



<http://solar.rainham-kent.co.uk>

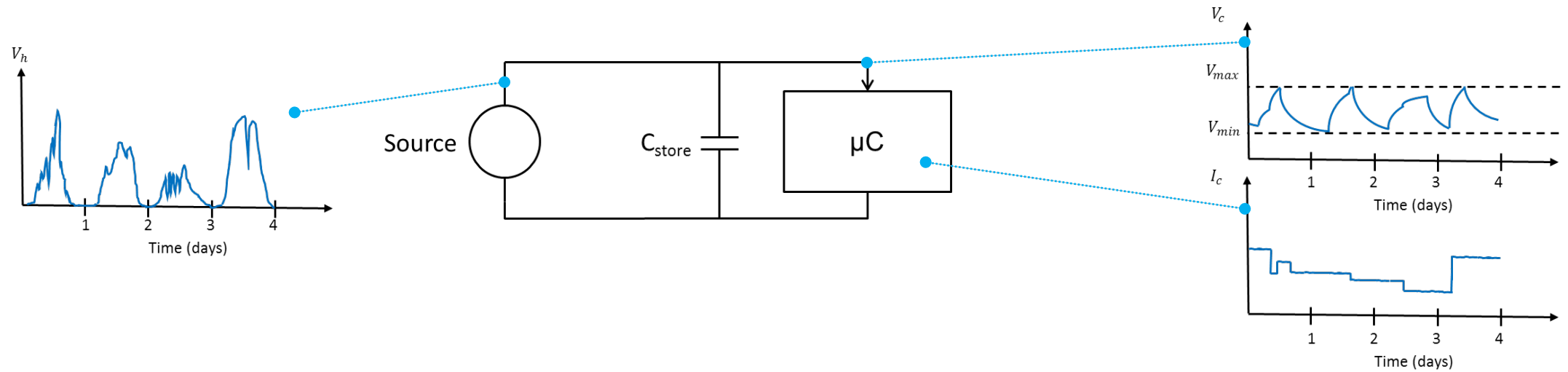


Zhao, J. et al. "A Shoe-Embedded Piezoelectric Energy Harvester for Wearable Sensors," Sensors 2014, 14, 12497-12510.

Highly variable supply + variable consumption!

ENERGY-NEUTRAL COMPUTING

Schematic

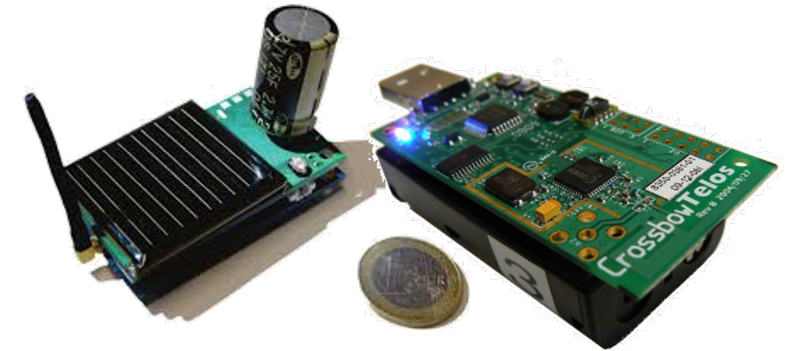


Block Diagram

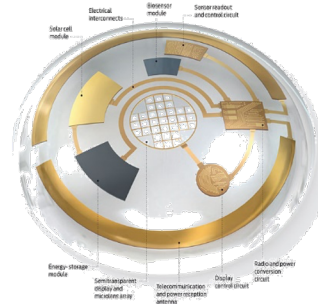


$$\int_{(n-1) \cdot T}^{n \cdot T} P_h(t) dt = \int_{(n-1) \cdot T}^{n \cdot T} P_c(t) dt$$

-
- The block diagram illustrates the system architecture. It features a **Vibration Source** (green oval) connected to an **Analogue Accelerometer (Base)** (blue rectangle). The accelerometer's output passes through **Band-Pass Filters** (blue rectangle) to produce **Waveforms**, which are then sent to the **EFM32 μ Controller** (blue rectangle). The **Vibration Energy Harvester** (green rectangle) provides power to the **Input Power Conditioning** (orange rectangle), which then feeds into the **Storage, Overvoltage Protection & Store V Meas.** (orange rectangle). This storage block outputs **0-4.5V** to the **Actuator Power Supply & Switching** (green rectangle) and **Store V Meas.** (orange rectangle). The **Actuator Power Supply & Switching** block is controlled by a **Tuning Actuator** (green rectangle) via a **2.5V** signal and provides **Actuator Ctrl.** to the **EFM32 μ Controller**. The **Store V Meas.** block outputs **2V** to the **EFM32 μ Controller**. The **EFM32 μ Controller** is also connected to a **Cold Start & Linear Regulator** (orange rectangle) and a **Switching Regulator** (orange rectangle), both of which provide power to the **EFM32 μ Controller**. The **EFM32 μ Controller** is connected to a **Transceiver** (blue rectangle) via an **SPI bus**, which in turn connects to a **Digital Accelerometer** (blue rectangle). A **Temperature Sensor** (blue rectangle) is also connected to the **EFM32 μ Controller**.



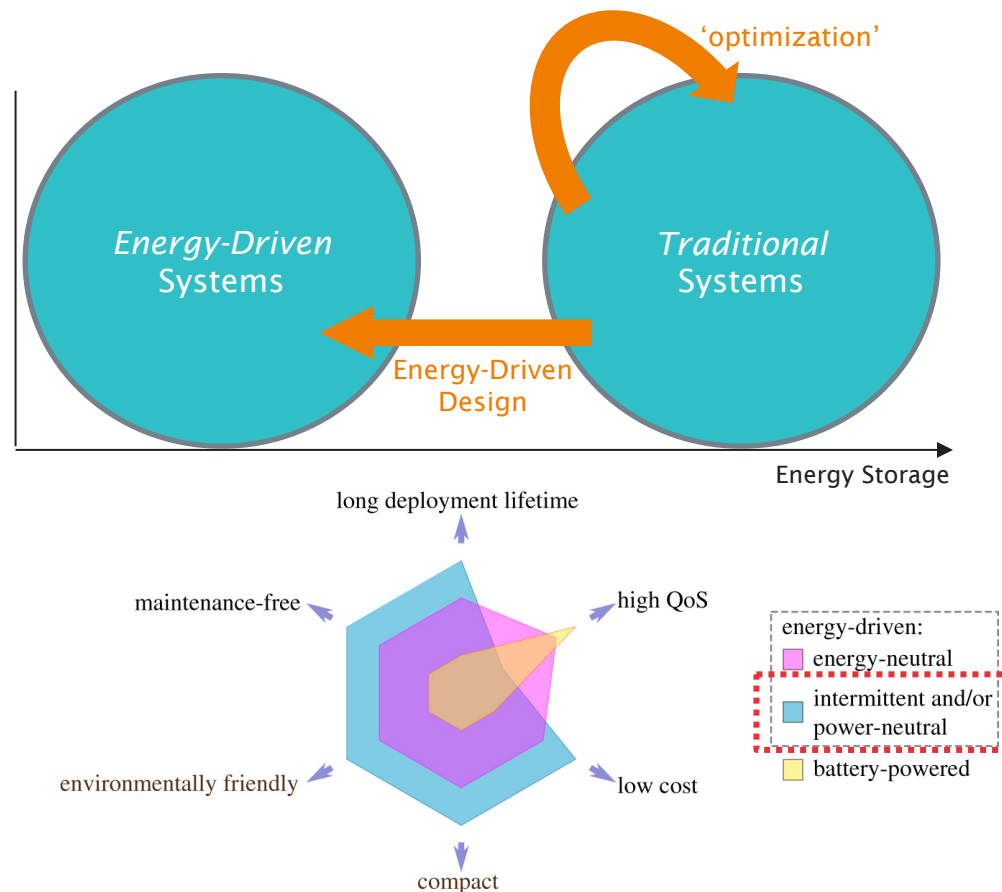
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ENERGY-DRIVEN COMPUTING

- Rethinking the design of EH systems



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Section

Abstract

1. Introduction
2. Energy- and power-neutral computing
3. Intermittent computing systems
4. Unsolved challenges in energy-driven computing
5. Discussion

Data accessibility

Competing interests

Funding

Footnotes

Discussion

Energy-driven computing

Sivert T. Sliper, Oktay Cetinkaya, Alex S. Weddell, Bashir Al-Hashimi and Geoff V. Merrett

Published: 23 December 2019
<https://doi.org/10.1098/rsta.2019.0158>

Abstract

For decades, the design of untethered devices has been focused on delivering a fixed quality of service with minimum power consumption, to enable battery-powered devices with reasonably long deployment lifetime. However, to realize the promised tens of billions of connected devices in the Internet of Things, computers must operate autonomously and harvest ambient energy to avoid the cost and maintenance requirements imposed by mains- or battery-powered operation. But harvested power typically fluctuates, often unpredictably, and with large temporal and spatial variability. Energy-driven computers are designed to treat energy-availability as a first-class citizen, in order to gracefully adapt to the dynamics of energy harvesting. They may sleep through periods of no energy, endure periods of scarce energy, and capitalize on periods of ample energy. In this paper, we describe the promise and limitations of energy-driven computing, with an

Details References Related Figures

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'Harmonizing energy-autonomous computing and intelligence'
organised and compiled and edited by Rishad Shafik and Alex Yakovlev

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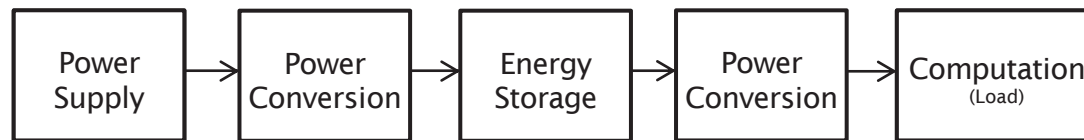
Help

ENERGY-DRIVEN COMPUTING

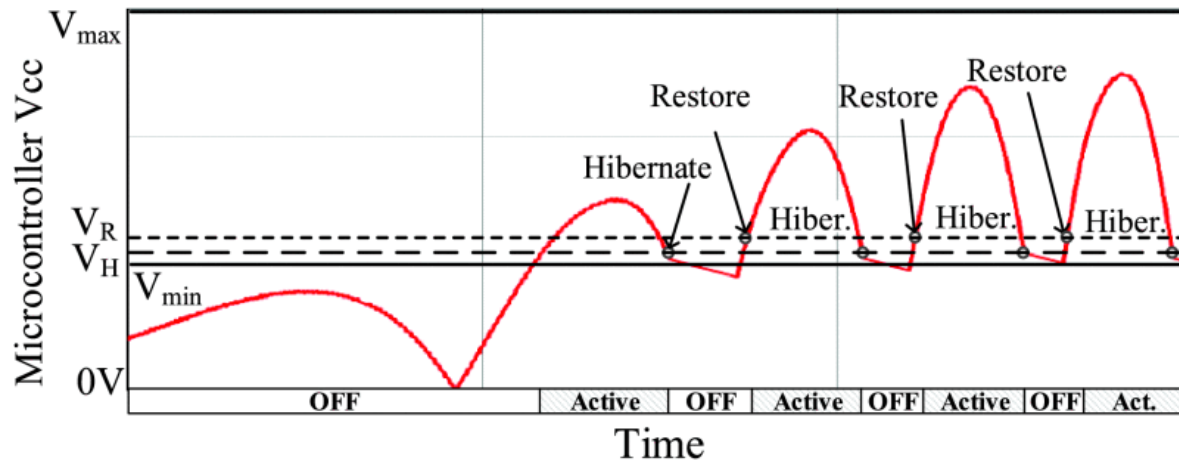


INTERMITTENT COMPUTING

Simplify the system; design for intermittency



Compute across power outages



D. Balsamo, A.S. Weddell, A. Das, A. Rodriguez Arreola, D. Brunelli, B.M. Al-Hashimi, G.V. Merrett, L. Benini, (2016) Hibernus++: a self-calibrating and adaptive system for transiently-powered embedded devices. *IEEE TCAD*, 1-13.

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Battery-Free, Energy-Harvesting Perpetual Machines: The Weird Future of Computing

A new breed of computers could run forever—or at least until long after we're gone

A glimpse into our battery-free future: This modern-day replica of a Game Boy is powered by solar panels and the routine presses of its buttons by the user.

PHOTO: PHOTO ILLUSTRATION BY THE WALL STREET JOURNAL; PHOTO: JASPER DE WINKEL

By [Christopher Mims](#)
Oct. 3, 2020 12:00 am ET

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In the not-too-distant future, technologists say, most computers will be tiny, ubiquitous, and won't ever need new batteries—because they won't have any.

INTERMITTENT COMPUTING

Compute/Memory

- Self calibration for runtime threshold optimisation (*hibernus++*)
- Adaptive restore based on EH properties (*hibernus++*)
- Efficient state retention (Selective Policies, *ManagedState*)
- Fine-grained power adaption (*PowerNeutrality*)

Peripherals/Sensors/Communication

- Hibernation and restore of external peripheral state (*RESTOP*)
- Support for communication and mesh networking

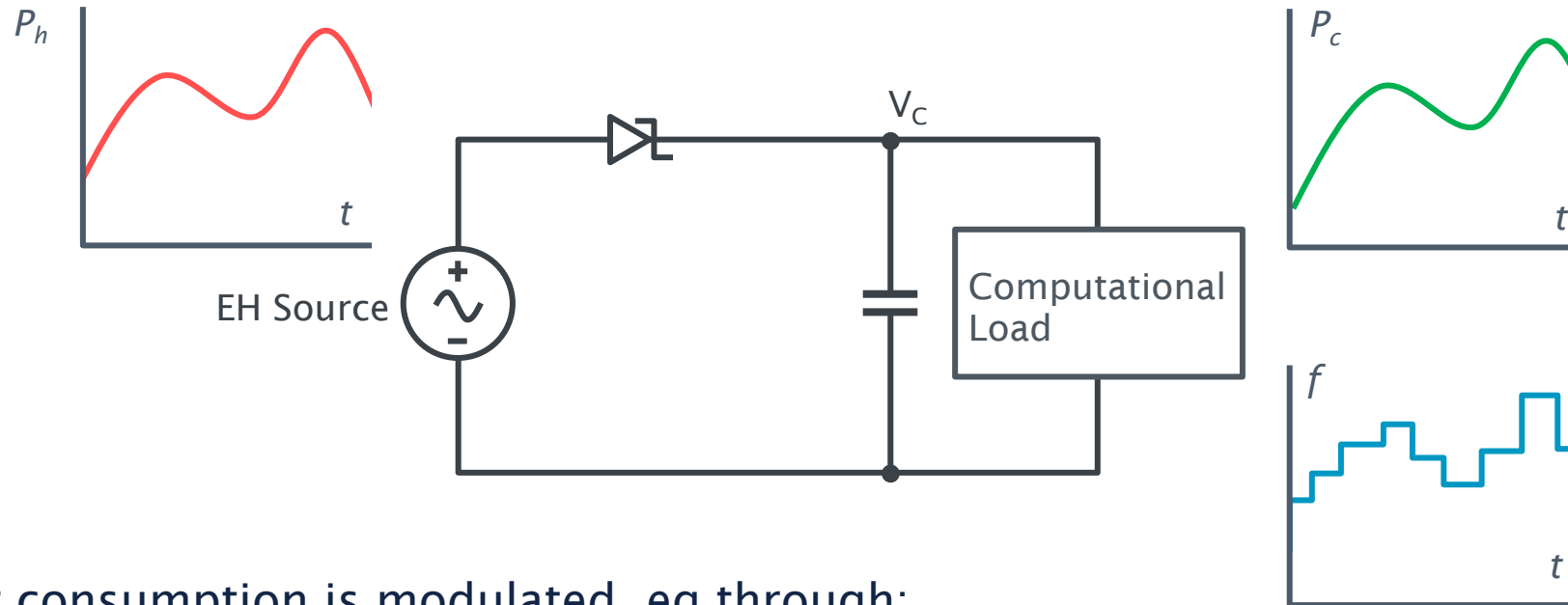
Applications/Users/Interfaces/Design Tools

- Application case studies, e.g. cycle computer, fitness monitor, wall clock, etc
- Design tools, e.g. *ENSPECT*, *FUSED*, Device Sizing, Support for *Arm Mbed*

www.transient.ecs.soton.ac.uk

POWER NEUTRAL COMPUTING

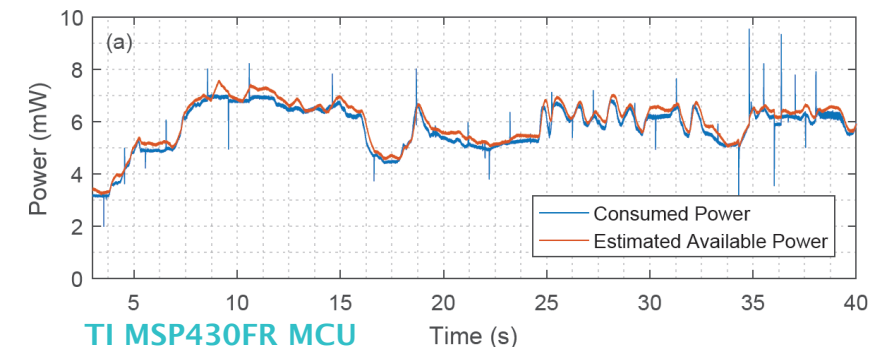
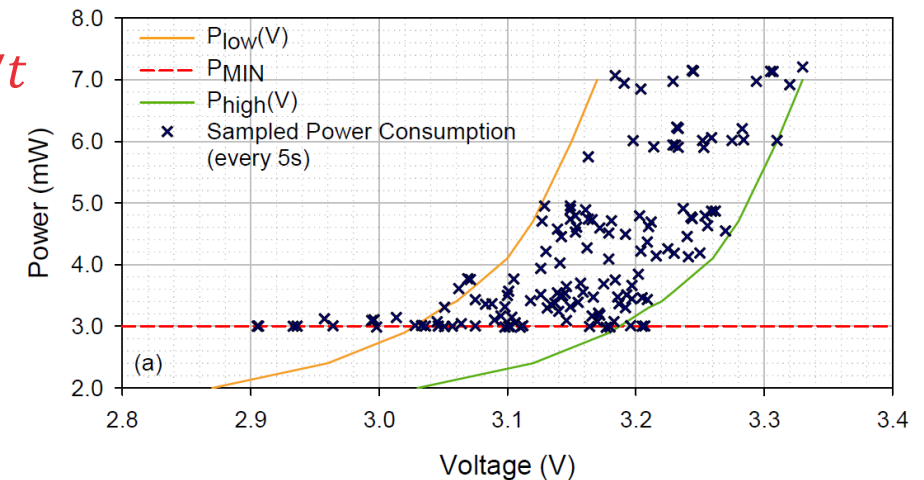
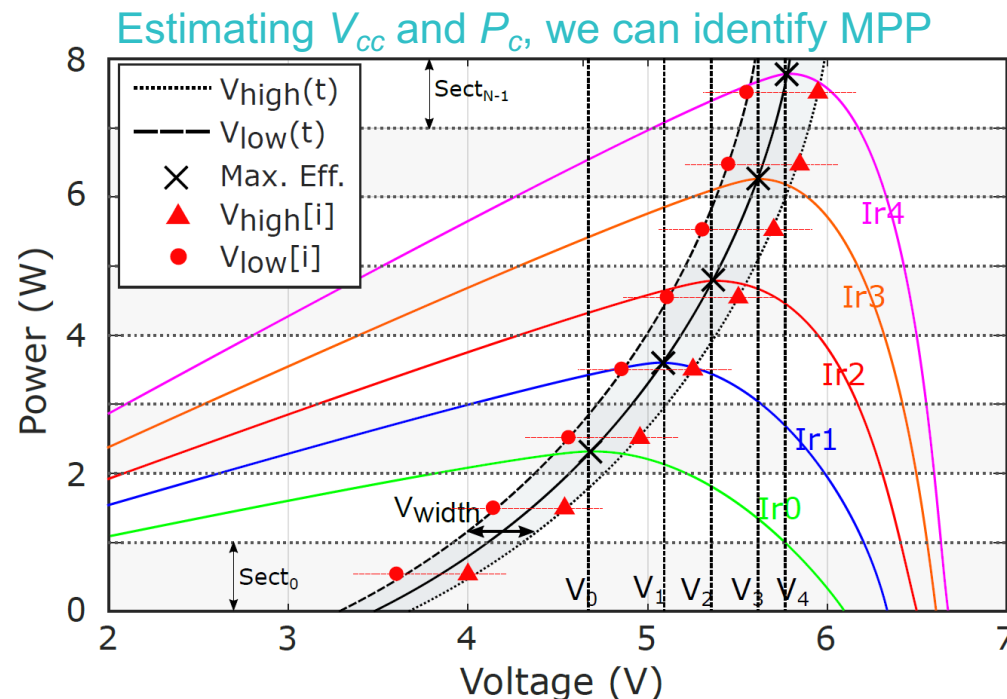
- In Power-Neutral computing, $P_c(t) \cong P_h(t)$
- We can approximate power-neutral behaviour if $V_c(t) \approx k, \forall t$



- Power consumption is modulated, eg through:
 - Core frequency and/or voltage
 - Power gating processor elements

POWER NEUTRAL COMPUTING

- What happens if V_C remains constant ($V_C(t) \approx k, \forall t$)?
- MPPT approaches are needed as $V_C(t) \neq V_{H_MPP}(t), \forall t$
- ‘Software-only’ MPPT modulates k : $V_C(t) = V_{H_MPP}(t)$



DISCUSSION

- We need to rethink the way that we design self-powered *systems*
- Progress is being made across all aspects of the system, but a wide range of challenges still exist



YOUR QUESTIONS

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