

UNIVERSITY OF SOUTHAMPTON

MAPS AND HYPERMAPS

- OPERATIONS AND SYMMETRY

by

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ABSTRACT

FACULTY OF MATHEMATICAL STUDIES

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Just as a map on a surface is an imbedding of a topological realisation of a graph, a hypermap is an imbedding of a topological realisation of a hypergraph. The algebraic theory of (hyper)maps facilitates both a study of the symmetries of (hyper)maps and a study of the possible imbeddings of (hyper)graphs via an associated set of permutations. In chapter 1 we set out the established algebraic theory of maps on surfaces together with an extension to hypermaps and maps of higher dimension whose topological realisations include all cell decompositions of  $n$ -manifolds.

There is a group of six invertible topological operations on surface maps which includes the well-known duality that interchanges vertices and faces. These operations arise naturally in the algebraic theory, being induced by the outer automorphisms of a certain Coxeter group. In chapter 2 we study the analogous groups of operations on hypermaps and maps of higher dimension.

If the symmetry group of a map on a surface contains both a rotation centred on a face and a rotation centred on a vertex, each cyclically permuting successive incident edges, then the map is said to be regular. If, in addition, there is a symmetry which acts on an edge by interchanging the two incident vertices without interchanging the two incident faces then the map is said to be reflexible. In chapter 3 we consider a weaker version of these symmetry conditions, and in so doing we introduce a class of highly symmetric maps and hypermaps that remains invariant under the operations discussed in chapter 2. We find that every finitely generated group may be regarded as a group of symmetries of some highly symmetric hypermap.

Finally, in chapter 4 we give an application of the algebraic theory to an imbedding problem by classifying those imbeddings of complete graphs whose symmetry group acts transitively on edges.

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## INTRODUCTION

Any imbedding of a connected graph in a connected possibly non-orientable surface, with or without boundary, decomposing that surface into topological open discs, or half discs, can be regarded as a transitive permutation representation of a certain Coxeter group. The concept of an algebraic theory of maps, that is, graph imbeddings of the above type, was presented by Tutte [27] who defined an associated set of permutations acting on the set of doubly directed edges. Firm foundations for this were set down by Bryant and Singerman [5] following a full treatment of the orientable case by Jones and Singerman [15]. We can consider hypergraph imbeddings in the same way. An algebraic theory of orientable hypermaps was first presented by Cori [6]. In [28], Vince considers a more general class of hypermap, to which he associates a transitive permutation representation of a specific Coxeter group. More generally, in [24] Ronan shows that any chamber system over a finite set, as defined by Tits [26], can be regarded as a cell complex. In chapter 1 we set out the established algebraic theory of maps on surfaces together with an extension to hypermaps and maps of higher dimension whose topological realisations include all cell decompositions of  $n$ -manifolds.

There is a group of six invertible topological

operations on surface maps, isomorphic to the symmetric group on three elements, that was first described by Wilson [31] for reflexible maps and later by Lins [19] for all maps. These operations arise naturally in the algebraic theory, being induced by the outer automorphisms of the above Coxeter group, and were presented as such in [16] by Jones and Thornton. In chapter 2 we give generators for, and determine the isomorphism class of, the groups of outer automorphisms of an infinite family of Coxeter groups in order to study the analogous groups of operations on maps of higher dimension. This is done by viewing each Coxeter group as an amalgamated product, in several different ways, and uses induction on the dimension, the inductive step being provided by the determination of the centraliser of any element of finite order. Some light is thrown on the edge twists, or barrings, used by Edmonds [10] in his characterisation of graph imbeddings. Hypermaps are similarly treated.

If the group of symmetries of a map on a surface contains both a rotation centred on a face and a rotation centred on a vertex, each cyclically permuting successive incident edges, then the map is said to be regular. If, in addition, there is a symmetry which acts on an edge by interchanging the two incident vertices without interchanging the two incident faces then the map is said to be reflexible [7]. Every regular map on a non-orientable surface is reflexible. Regular maps have been extensively studied; on the sphere they are

the platonic solids. In chapter 3 we consider a weaker version of these symmetry conditions, and in so doing we introduce a class of highly symmetric maps and hypermaps that remains invariant under the operations discussed in chapter 2. We find that every finitely generated group may be regarded as a group of symmetries of some highly symmetric hypermap.

Finally, in chapter 4 we give an application of the algebraic theory to an imbedding problem. In [1] Biggs showed that the complete graph on  $n$  vertices has a regular imbedding in an orientable surface without boundary if and only if  $n$  is a prime power. The examples he gave were Cayley maps based on the additive groups of finite fields. The symmetry group of any regular imbedding acts transitively on both vertices and edges. In [2] Biggs showed that any imbedding of a complete graph, in an orientable surface without boundary, whose symmetry group acts transitively on vertices can be described as a Cayley map. We classify those imbeddings of complete graphs, in a possibly non-orientable surface without boundary, whose symmetry group acts transitively on edges. This relies on the classifications of 2-homogeneous groups by Ito [12], Zassenhaus [32] and Kantor [17], and includes those surface maps that attain the upper bound on the number of symmetries of an imbedding of a simple graph with  $n$  vertices in a surface without boundary. We find that essentially each can be described as either a Cayley map based on the additive group of a

finite field or as the image of such a map under one of the operations discussed in chapter 2.

# CHAPTER 1

## Maps and Hypermaps

1) First we briefly outline the algebraic theory of maps developed in [5] and [15]. A map  $\mathcal{M}$  is a connected graph  $G$  imbedded (without crossings) in a connected surface  $S$  (possibly non-orientable or with boundary) such that each of the faces of  $\mathcal{M}$  (the connected components of  $S \setminus G$ ) is homeomorphic to an open disc or half disc. To each map  $\mathcal{M}$  we associate a set  $\Omega$  of blades: whenever an edge  $e$  meets a vertex  $v$  we draw on the surface a pair of blades, one on each side of  $e$ . We define three permutations of  $\Omega$  as follows:  $r_2$  transposes each such pair of blades,  $r_0$  sends each blade to the blade at the other end of  $e$  and on the same side of  $e$ , and  $r_1$  transposes pairs of blades with a vertex and face in common; Fig.1 illustrates the effect of these permutations on a blade  $\beta$ . We refer to an orbit of  $\Omega$  under the cyclic subgroup  $\langle r_2 \rangle$  as a dart of the map. (These definitions.

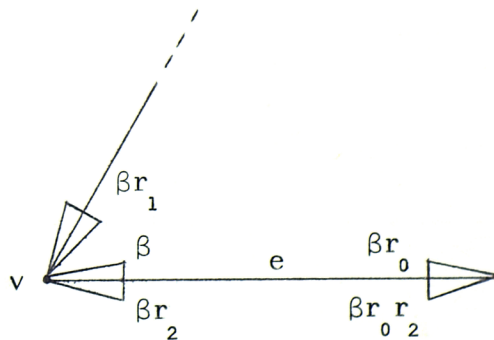


Figure 1

require some slight modifications, allowing  $r_0, r_1, r_2$  or  $r_0 r_2$  to have fixed points on  $\Omega$ , when  $\mathcal{M}$  is on a surface with boundary or when the underlying graph of  $\mathcal{M}$  has free edges. Full details may be found in [5].) Clearly these permutations satisfy the relations

$$r_0^2 = r_1^2 = r_2^2 = (r_0 r_2)^2 = 1,$$

and by the connectedness of  $\mathcal{M}$  they generate a transitive permutation representation of the group

$$\Gamma = \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = (r_0 r_2)^2 = 1 \rangle.$$

Conversely, given a transitive permutation representation of  $\Gamma$  on a set  $\Omega$ , we can reconstruct the map  $\mathcal{M}$ : we define the vertices, edges and faces of  $\mathcal{M}$  to be the orbits in  $\Omega$  of the dihedral subgroups  $\langle r_1, r_2 \rangle$ ,  $\langle r_0, r_2 \rangle$  and  $\langle r_0, r_1 \rangle$  of  $\Gamma$ , with incidence corresponding to non-empty intersection of orbits. We observe that a Petrie polygon of  $\mathcal{M}$  is then an orbit of the subgroup  $\langle r_0 r_2, r_1 \rangle$  as illustrated in Fig. 2. (A more sophisticated approach, described in [5] and [15], is to represent  $\Gamma$  as the

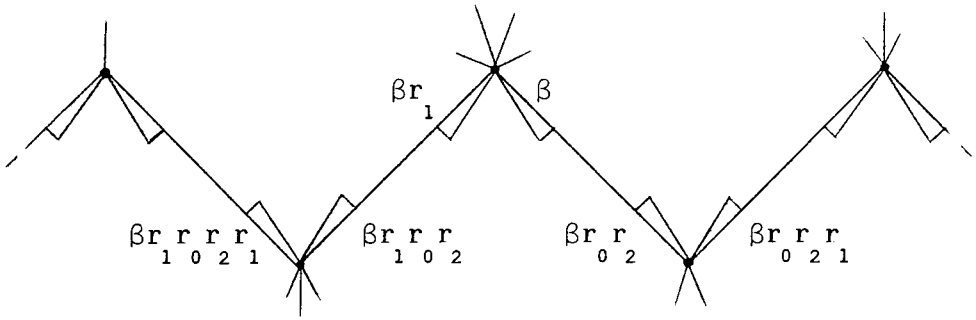


Figure 2



automorphism group of a certain tessellation on a Riemann surface, and to take  $\mathcal{M}$  to be the quotient of this tessellation by a suitable subgroup  $M$  of  $\Gamma$ .) This gives a bijection between maps and transitive permutation representations of  $\Gamma$  (or more strictly between isomorphism classes in each category).

Each map  $\mathcal{M}$  determines a permutation representation which is isomorphic to the action of  $\Gamma$  (by right multiplication) on the cosets  $Mg$  of a subgroup  $M \leq \Gamma$ ; this subgroup  $M$ , the map subgroup associated with  $\mathcal{M}$ , is the stabiliser in  $\Gamma$  of an element of  $\Omega$ , and is uniquely determined up to conjugacy. The automorphism group of the map can be realised as the action of  $N/M$  on the cosets of  $M$  by left multiplication, where  $N$  is the normaliser of  $M$  in  $\Gamma$ . A map is both orientable and without boundary if and only if  $M \leq \Gamma^+$  [5], where  $\Gamma^+$  is the even subgroup of  $\Gamma$ , generated by  $r_0 r_2$  and  $r_1 r_2$ , which we denote by  $X$  and  $Y$  respectively, with presentation

$$\Gamma^+ = \langle X, Y \mid X^2 = 1 \rangle .$$

Two subgroups of  $\Gamma^+$  determine equivalent maps, up to orientation-preserving isomorphism, if and only if they are conjugate in  $\Gamma^+$ . The orientation-preserving automorphism group of such a map can be realised as the action of  $N^+/M$  on the cosets of  $M$  by left multiplication, where  $N^+$  is the normaliser of  $M$  in  $\Gamma^+$ .

2) There is an analogously developed algebraic theory of hypermaps in, for example, [6], [28] and [30]. A hypermap is a map on a surface  $S$  with underlying graph  $G$  satisfying the conditions:

- (i)  $G$  is trivalent,
  - (ii)  $G$  has no looped edges,
  - (iii) no vertex of  $G$  lies on the boundary of  $S$ ,
  - (iv) every free edge of  $G$  meets the boundary of  $S$ ,
- together with a colouring of the faces by  $\{0, 1, 2\}$  such that every edge is bordered by two different coloured faces. Fig. 3 gives an example of a hypermap on a disc.

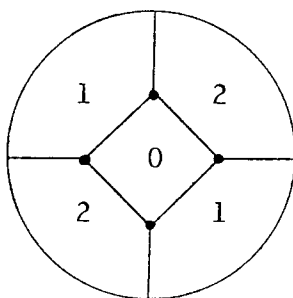


Figure 3

The faces of the map coloured  $0, 1, 2$  are called the hypervertices, hyperedges and hyperfaces respectively, and we refer to an edge that is bordered by both a hypervertex and a hyperedge as a hyperdart.

This definition of a topological hypermap differs slightly from those of [6], [28] and [30]. Cori [6] takes the surface to be orientable and contracts each hyperdart to a point; Walsh [30] also takes an orientable surface, and considers the dual of the two coloured map

formed by contracting each hyperface to a point; Vince [28] allows the surface to be non-orientable and contracts each hypervertex to a point (we refer to this as the underlying two-coloured map). Each represents an imbedding of a topological realisation of a hypergraph. We observe that by expanding vertices and edges we can regard any map on a surface as a hypermap.

To any hypermap we associate a transitive permutation representation of the group

$$G = \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = 1 \rangle$$

by colouring each edge of the underlying map with the complement of the colours of its incident faces. This gives the Schreier coset graph for a subgroup in  $G$ , and thus a transitive permutation representation of  $G$ . In this case the permuted set is the set of vertices of the underlying map.

Conversely, given a transitive permutation representation of  $G$  on a set  $\Omega$ , we can reconstruct a hypermap: we take the Schreier coset graph of the stabiliser in  $G$  of an element in  $\Omega$ , replacing any looped edge by a free edge, then we attach a disc, or half disc, coloured  $c$  to each component formed by the deletion of all edges coloured  $c$ .

Definition 1.1. An algebraic hypermap is a transitive permutation representation  $\rho$  of the group

$$G = \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = 1 \rangle$$



on a set  $\Omega$ .

Definition 1.2. Two algebraic hypermaps  $\rho, \rho'$  are isomorphic if there exists a bijection  $\phi: \Omega \longrightarrow \Omega'$  and a group isomorphism  $\sigma: G\rho \longrightarrow G\rho'$  such that  $r_i \rho \sigma = r_i \rho'$  for all  $i \in \{0, 1, 2\}$  and the following diagram commutes

$$\begin{array}{ccccc}
 \Omega & \times & G\rho & \longrightarrow & \Omega \\
 \phi \downarrow & & \downarrow \sigma & & \downarrow \phi \\
 \Omega' & \times & G\rho' & \longrightarrow & \Omega'
 \end{array}$$

the horizontal arrows representing the group actions.

We shall identify the permutation  $r_i$  with its image  $r_i \rho$  when no confusion is likely, and refer to the elements of  $\Omega$  as hyperblades. The stabiliser in  $G$  of a hyperblade is referred to as a hypermap subgroup.

Many of the results of the algebraic theory of maps go over easily to the algebraic theory of hypermaps. For example, the automorphism group of a hypermap can be realised as the action of  $N/M$  on the cosets of  $M$  by left multiplication, with obvious definitions for  $N$  and  $M$ .

3) More generally, in [28] Vince defines a combinatorial map over a finite set  $I$  to be a connected graph  $\mathcal{G}$ , regular of degree  $|I|$ , whose edges are  $|I|$ -coloured such that no two incident edges are the same colour, and defines an isomorphism of two combinatorial maps to be a colour-preserving graph isomorphism. Clearly combin-

atorial maps are equivalent to Schreier coset graphs  $\mathcal{G}(W, M)$  for groups  $W$ , generated by involutions, and subgroups  $M \leq W$ . We let  $N_W(M)$  denote the normaliser in  $W$  of  $M$ .

Proposition 1.3, [28, 7.5]. If  $\mathcal{G}$  is a combinatorial map with Schreier representation  $\mathcal{G}(W, M)$ , then  $\text{Aut}(\mathcal{G}) \simeq N_W(M)/M$ .

Proof: For each  $u \in N_W(M)$  the function  $f_u : Mg \mapsto Mu^{-1}g$  induces an automorphism of  $\mathcal{G}$ . Hence there is a homomorphism  $\phi : N_W(M) \longrightarrow \text{Aut}(\mathcal{G})$  given by  $u \mapsto f_u$ . Since  $\ker \phi = M$  we have only to show that  $\phi$  is surjective. Let  $f \in \text{Aut}(\mathcal{G})$  and assume that  $f : M \mapsto Mu^{-1}$ . This implies that  $f : Mg \mapsto Mu^{-1}g$  for all  $g \in W$ . Therefore  $f = f_u$ . Moreover,  $u \in N_W(M)$  because for all  $g \in M$  both  $Mu^{-1}g$  and  $Mu^{-1}$  is the image of  $M$  under  $f_u$  ■

4) Finally, motivated by the generalisation of topological maps on surfaces to maps of higher dimension, we consider a third family of combinatorial maps. Suppose that  $\mathcal{M}$  is a cell decomposition of a connected  $n$ -manifold without boundary. Let  $\Delta\mathcal{M}$  be its barycentric subdivision, and label each vertex of  $\Delta\mathcal{M}$  with the dimension of the cell that it represents. We define a set of permutations on the  $n$ -simplices of  $\Delta\mathcal{M}$  as follows. For each  $i \in \{0, 1, 2, \dots, n\}$  each  $(n-1)$ -simplex of  $\Delta\mathcal{M}$  whose vertices are not labelled by  $i$  is contained in precisely two  $n$ -simplices of  $\Delta\mathcal{M}$ . We define  $r_i$  to

be the permutation that transposes each such pair of  $n$ -simplices. Since the boundary of each  $n$ -cell is itself a cell decomposition of a connected  $(n-1)$ -manifold, and each  $(n-1)$ -cell is contained in no more than two  $n$ -cells, there is an inductive proof that if  $j > i+1$  then  $r_i$  and  $r_j$  commute.

Definition 1.4. An  $n$ -dimensional algebraic map is a transitive permutation representation  $\rho$  of the group

$$\Gamma_n = \langle r_0, r_1, \dots, r_n \mid r_i^2 = (r_j r_k)^2 = 1, k > j+1 \rangle$$

on a set  $\Omega$ . Elements of  $\Omega$  are referred to as  $n$ -blades.

Definition 1.5. Two  $n$ -dimensional algebraic maps  $\rho, \rho'$  are isomorphic if there is a bijection  $\phi: \Omega \longrightarrow \Omega'$  and a group isomorphism  $\sigma: \Gamma_n \rho \longrightarrow \Gamma_n \rho'$  such that  $r_i \rho \sigma = r_i \rho'$  for all  $i \in \{0, 1, \dots, n\}$  and the following diagram commutes,

$$\begin{array}{ccccc} \Omega & \times & \Gamma_n \rho & \longrightarrow & \Omega \\ \phi \downarrow & & \downarrow \sigma & & \downarrow \phi \\ \Omega' & \times & \Gamma_n \rho' & \longrightarrow & \Omega' \end{array}$$

the horizontal arrows representing the group actions.

We shall identify the permutation  $r_i$  with its image under  $\rho$  when no confusion is likely, and refer to the stabiliser in  $\Gamma_n$  of an element in  $\Omega$  as a map subgroup.

To each  $n$ -dimensional algebraic map  $\mathcal{M}$  we associate an  $n$ -dimensional cell complex  $\Delta \mathcal{M}$  as follows. Let

$I$  denote the set  $\{0, 1, \dots, n\}$ . For each element  $\beta \in \Omega$ , let  $\Delta\beta$  be an  $n$ -simplex. Arbitrarily assign to each vertex of  $\Delta\beta$  a distinct element of  $I$ . Call the set of elements assigned to a face  $s$  of  $\Delta\beta$  the type of  $s$ . Let  $K$  be the disjoint union of the set  $\{\Delta\beta \mid \beta \in \Omega\}$ . In  $K$  identify two simplices  $s \subseteq \Delta\beta$  and  $s' \subseteq \Delta\beta'$  of the same type  $J$  if and only if  $\beta$  and  $\beta'$  are in the same orbit of the subgroup generated by  $\{r_i \mid i \in I \setminus J\}$ . If  $\sim$  denotes this identification then take  $\Delta\mathcal{M} = K/\sim$ . Thus we have formed the cell complex associated by Ronan [24] to the partitions of the elements of  $\Omega$  into their orbits under the subgroups  $\langle r_i \rangle$  for  $i \in I$ . Intuitively  $\Delta\mathcal{M}$  can be thought of as being built from  $n$ -simplices, one for each element of  $\Omega$ , such that two  $n$ -simplices share a common codimension 1 face if the corresponding points are adjacent in the Schreier coset graph associated with the representation.

We note that  $|\Delta\mathcal{M}|$  is not generally a manifold. For this it would at least be necessary for each orbit of the subgroup generated by  $\{r_i \mid i \in I \setminus \{n\}\}$  to represent a map on an  $(n-1)$ -sphere. This can soon fail for  $n > 2$ . For representations of manifolds by edge-coloured graphs see [9] and [20].

The orbits in  $\Omega$  of the subgroups  $\langle r_j \mid j \in I \setminus \{i\} \rangle$  are called the  $i$ -faces of  $\mathcal{M}$ , with incidence corresponding to non-empty intersection of orbits. Furthermore, as observed by Vince [28, 4.2], there is a partial order on these faces defined as follows: let  $x$  be an  $i$ -face and

$y$  a  $j$ -face of  $\mathcal{M}$  then  $x < y$  if and only if  $x$  is incident with  $y$  and  $i \leq j$ . We need only show that  $<$  is transitive. Suppose that  $y < z$ . It is sufficient to show that  $x \cap z \neq \emptyset$ . Let  $g$  be a finite sequence  $(g_1, g_2, \dots, g_m)$  of elements in  $\{r_\ell \mid \ell \in I \setminus \{j\}\}$  then  $g$  acts on  $\Omega$  in the obvious way and we can choose  $g$  to satisfy the conditions:

- (i)  $xg \cap z \neq \emptyset$ ,
- (ii) of all such sequences  $g$  is minimal with respect to its length  $m$  and,
- (iii) of all such sequences  $g$  is minimal with respect to the length  $t$  of the initial subsequence of elements in  $\{r_\ell \mid \ell \in I, \ell < j\}$ .

We must show that  $m = 0$ . Assume that  $m \neq 0$ . If  $t = 0$  then the first element in  $g$  can be removed, contradicting the minimality of  $m$ . Similarly, if  $r_\ell$  is the last element in  $g$  then  $\ell > j$ . Thus  $1 \leq t < m$  and we can contradict the minimality of  $t$  by interchanging the positions of  $g_t$  and  $g_{(t+1)}$ .



Operations

1) There is a well-known duality for maps on surfaces that interchanges vertices and faces while retaining certain important features such as the automorphism group. Wilson [31] and Lins [19] gave topological descriptions for other similar invertible operations on surface maps which, together with the above duality, generate a group isomorphic to  $S_3$ . In [16] Jones and Thornton showed how these operations arise naturally in algebraic map theory, being induced by the outer automorphism group of  $\Gamma$ . In this chapter we study the analogous groups for hypermaps and maps of general dimension.

2) Suppose that  $\mathcal{M}$  is a cell decomposition of a connected  $n$ -manifold without boundary. Let  $\mathcal{M}^*$  denote the dual map. Cells of dimension  $i$  in  $\mathcal{M}$  are transformed into cells of dimension  $n-i$  in  $\mathcal{M}^*$ . If we consider the relationship between paths in  $\mathcal{M}$  along the graph dual to  $\Delta\mathcal{M}$  and paths in  $\mathcal{M}^*$  along the graph dual to  $\Delta\mathcal{M}^*$  then we see that the duality of maps on manifolds corresponds to a duality of sequences in  $\{r_0, \dots, r_n\}$  that acts by interchanging the symbols  $r_i$  and  $r_{n-i}$ . This duality preserves the set of sequences  $\{r_i^2, (r_j r_k)^2 : |k-j| > 1\}$ . It also preserves the juxtaposition of sequences. Thus we have a duality of elements in  $\Gamma_n$  that preserves group multiplication. In other words, we have a group automorphism of  $\Gamma_n$ . This group automorphism induces the duality of maps on manifolds by its action on map subgroups.

We define an operation on the topological realisation of  $n$ -dimensional algebraic maps to be any transformation induced by the action of a group automorphism of  $\Gamma_n$  on the map subgroups. This definition was first made by Jones and Thornton [16] for maps on surfaces. We define an operation on (topological) hypermaps analogously.



If a map  $\mathcal{M}$  has map subgroup  $M$  then  $\mathcal{M}^\alpha$ , the image of  $\mathcal{M}$  under the operator  $\alpha \in \text{Aut}(\Gamma_n)$ , has map subgroup  $M^\alpha$ . Thus the inner automorphism group  $\text{Inn}(\Gamma_n)$  acts trivially on maps, and so we have an induced action of the outer automorphism group

$$\text{Out}(\Gamma_n) = \text{Aut}(\Gamma_n) / \text{Inn}(\Gamma_n) .$$

Similarly the action of  $\text{Aut}(G)$  induces an action of  $\text{Out}(G)$ . We shall therefore determine the outer automorphisms of  $\Gamma_n$  and  $G$ . These appear to be original results.

We first note the automorphisms  $\theta_n$  and  $\phi_n$  of

$$\Gamma_n = \langle r_0, r_1, \dots, r_n \mid r_i^2 = (r_j r_k)^2 = 1, k > j+1 \rangle$$

defined by  $\theta_n : r_i \mapsto r_{(n-i)}$  and  $\phi_n : r_2 \mapsto r_0 r_2$  where  $\phi_n$  fixes  $r_i$  for all  $i$  other than  $i=2$ . If we let  $H_n$  denote the subgroup  $\langle \theta_n, \phi_n \rangle$  of  $\text{Aut}(\Gamma_n)$  then

$$H_0 = 1 ,$$

$$H_1 = \langle \theta_n \mid \theta_n^2 = 1 \rangle \simeq C_2 ,$$

$$H_2 = \langle \theta_n, \phi_n \mid \theta_n^2 = \phi_n^2 = (\theta_n \phi_n)^3 = 1 \rangle \simeq S_3 ,$$

$$H_n = \langle \theta_n, \phi_n \mid \theta_n^2 = \phi_n^2 = (\theta_n \phi_n)^4 = 1 \rangle \simeq D_4 , \quad n > 2 ,$$

and  $H_n \cap \text{Inn}(\Gamma_n) = 1$ .

We also note that for each  $i \in \{0, 1, \dots, n\}$   $\Gamma_n$  is an amalgamated product  $P(n, r_i)$  of the subgroups  $G_1(n, r_i)$  and  $G_2(n, r_i)$  by the subgroup  $A(n, r_i)$  where if  $R_n$  denotes  $\{r_0, \dots, r_n\}$  then

$$G_1(n, r_i) = \langle R_n \setminus \{r_i\} \mid r_j^2 = (r_k r_\ell)^2 = 1, \ell > k+1 \rangle ,$$



$$G_2(n, r_i) = \langle R_n \setminus \{r_{(i \pm 1)}\} \mid r_j^2 = (r_k r_\ell)^2 = 1, \ell > k+1 \rangle, \\ A(n, r_i) = \langle R_n \setminus \{r_i, r_{(i \pm 1)}\} \mid r_j^2 = (r_k r_\ell)^2 = 1, \ell > k+1 \rangle.$$

If  $W$  is a group generated by a subset of involutions  $S$  then the couple  $(W, S)$  is called a Coxeter system if the following condition is satisfied

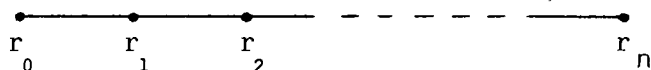
(C) For  $s, s'$  in  $S$  let  $m(s, s')$  be the order of  $ss'$  ;  
let  $I$  be the set of couples  $(s, s')$  such that  $m(s, s')$  is finite. The generating set  $S$  and the relations  $(ss')^{m(s, s')} = 1$  for  $(s, s')$  in  $I$  forms a presentation of the group  $W$ .

It is easy to see, by taking appropriate homomorphisms of  $\Gamma_n$ , that the couple  $(\Gamma_n, R_n)$  is a Coxeter system. We have.

Theorem 2.1, [4, IV.1.8]. If  $(W, S)$  is a Coxeter system then

- (i) For all subsets  $X$  of  $S$ , the couple  $(\langle X \rangle, X)$  is a Coxeter system
- (ii) If  $(X_\alpha)_{\alpha \in A}$  is a family of subsets of  $S$  then
$$\langle \bigcap_{\alpha \in A} X_\alpha \rangle = \bigcap_{\alpha \in A} \langle X_\alpha \rangle. \blacksquare$$

Finally, we draw attention to the representation of  $\Gamma_n$  by a Coxeter graph:



The nodes are to be interpreted as generating involutions for a group whose only other relations come from the commutativity of non-adjacent generators. (Note that we go

against convention in that we do not interpret the cube of a product of adjacent generators as a relation.) Thus, for example, the graph below would be interpreted as  $\Gamma_n \times \Gamma_m$  (or more strictly as being in the same isomorphism class).



In the following we use the notation  $C_W(g)$  and  $Z(W)$  for the centraliser of  $g \in W$  and the centre of  $W$  respectively for any group  $W$ .

Lemma 2.2. There is a bijection between the sets of non-adjacent elements of  $R_n$  and the conjugacy classes of elements of finite order in  $\Gamma_n$ .

Proof: Let  $T$  be those  $n \in \mathbf{N}$  for which any element of finite order in  $\Gamma_n$  is conjugate to a product of non-adjacent elements of  $R_n$ . Clearly  $0 \in T$  and, by the torsion theorem for free products [21, IV.1.6],  $1 \in T$ . Suppose that  $k \geq 2$  and that  $n \in T$  for all  $n < k$ . By the torsion theorem for amalgamated products [21, IV.2.7], any element of finite order in  $\Gamma_k$  is conjugate to an element of either  $G_1(k, r_k)$  or  $G_2(k, r_k)$ . But  $G_1(k, r_k) = \Gamma_{(k-1)}$  and  $G_2(k, r_k) = \Gamma_{(k-2)} \times \langle r_k \rangle$ , and so by hypothesis  $k \in T$ . Suppose that the product of one set of non-adjacent elements is conjugate to the product of another. Then, by abelianisation, the two sets must be equal. ■

Proposition 2.3.  $C_{\Gamma_n}(r_j) = G_2(n, r_j)$  and if  $\{s_1, \dots, s_m\}$  is a set of commuting elements of  $R_n$  then

$$C_{\Gamma_n}(s_1 \dots s_m) \subseteq \bigcap_{i=1}^m C_{\Gamma_n}(s_i) .$$

Proof: Suppose that  $t \in C_{\Gamma_n}(s_1 \dots s_m)$ . Let  $s = s_1 \dots s_m$  and let  $i \in \{1, \dots, m\}$ . Then  $s \in G_2(n, s_i) \setminus A(n, s_i)$ . Let  $t = t_1 \dots t_k$  be in the reduced form of  $P(n, s_i)$  and suppose that  $k \geq 2$ . If  $t_1, t_k \in G_2(n, s_i)$  then  $s^{t_1} \in G_2(n, s_i) \setminus A(n, s_i)$  and  $t_k s \in A(n, s_i)$ . Whence  $t_{(k-1)} t_k s \in G_1(n, s_i) \setminus A(n, s_i)$  and so by the normal form theorem for amalgamated products [21, IV.2.6]  $t^{-1} s t s \neq 1$ . Thus  $t \notin C_{\Gamma_n}(s_1 \dots s_m)$ . If either  $t_1$  or  $t_k$  are in  $G_1(n, s_i)$  then we find a similar contradiction. Whence  $k \leq 1$ . Suppose that  $t \in G_1(n, s_i) \setminus A(n, s_i)$  then again by the normal form theorem  $t^{-1} s t s \neq 1$  and so  $t \notin C_{\Gamma_n}(s_1 \dots s_m)$ . Whence  $t \in G_2(n, s_i)$  and

$$C_{\Gamma_n}(s_1 \dots s_m) \subseteq \bigcap_{i=1}^m G_2(n, s_i) .$$

If we put  $m=1$  and  $s_1 = r_j$  then we have  $C_{\Gamma_n}(r_j) \subseteq G_2(n, r_j)$  and thus  $C_{\Gamma_n}(r_j) = G_2(n, r_j)$  ■

The following proposition can be seen as a corollary to theorem 2.1, but we include a direct proof.

Proposition 2.4. If  $\{s_1, \dots, s_m\}$  is a set of commuting elements of  $R_n$  then  $\bigcap_{i=1}^m C_{\Gamma_n}(s_i) \subseteq \langle V_n\{s_1, \dots, s_m\} \rangle$  where  $V_n\{s_1, \dots, s_m\}$  is the subset of elements of  $R_n$  that commute with every member of  $\{s_1, \dots, s_m\}$ .

Proof: Let  $t \in \bigcap_{i=1}^m C_{\Gamma_n}(s_i)$  and assume that  $t \neq 1$ . Let  $t = t_1 \dots t_k$  be a reduced decomposition of  $t$  with respect to  $R_n$ . Let  $r_i \in \{s_1, \dots, s_m\}$  and suppose that  $t_j = r_{(i+1)}$  for some  $j : 1 \leq j \leq k$ . Then  $t \in C_{\Gamma_n}(r_i) = G_2(n, r_i) \subseteq G_1(n, r_{i+1})$ .

Let  $j(1) < j(2) < \dots < j(p)$  be those  $j$  for which  $t_j = r_{i+1}$ .  
Let  $u_0 = t_1 \dots t_{(j(1)-1)}$ , let  $u_q = t_{(j(q)+1)} \dots t_{(j(q+1)-1)}$   
for all  $q : 0 < q < p$ , and let  $u_p = t_{(j(p)+1)} \dots t_k$ . So  
 $t = u_0 r_{(i+1)} \dots u_p$  where  $u_q \in G_1(n, r_{i+1})$  for all  $q :$   
 $0 \leq q \leq p$ . Suppose that  $u_q \in A(n, r_{i+1})$  for some  $q : 0 < q < p$ .  
Then  $t_{j(q)} u_q t_{j(q+1)} = r_{(i+1)} u_q r_{(i+1)} = u_q$  which contradicts  
the minimality of  $k$ . Thus  $u_q \in G_1(n, r_{i+1}) \setminus A(n, r_{i+1})$   
for all  $q : 0 < q < p$ . Let  $|w|$  denote the length of  $w$   
in  $P(n, r_{i+1})$ . If  $p \geq 2$  then

$$|u_0 r_{(i+1)} u_1 \dots u_{(p-1)} r_{(i+1)} u_p| \geq 2p-1 \geq 3.$$

But  $t \in G_1(n, r_{i+1})$  and so  $|t| \leq 1$ . Whence  $p=1$  and  
 $u_0^{-1} t u_1^{-1} r_{(i+1)} = 1$ . But  $u_0^{-1} t u_1^{-1} \in G_1(n, r_{i+1})$  and  
 $r_{i+1} \in G_2(n, r_{i+1}) \setminus A(n, r_{i+1})$  so  $|u_0^{-1} t u_1^{-1} r_{(i+1)}| \geq 1$   
which contradicts the normal form theorem for amalgamated  
products. Thus there is no  $j$  such that  $t_j = r_{i+1}$ .  
Similarly there is no  $j$  such that  $t_j = r_{i-1}$ . Whence  
 $t_j \in V_n\{s_1, \dots, s_m\}$  for all  $j : 1 \leq j \leq k$ . ■

From propositions 2.3 and 2.4 we have

Lemma 2.5. The centraliser in  $\Gamma_n$  of a product of a set  
of commuting elements of  $R_n$  is presented by the Coxeter  
graph for  $\Gamma_n$  less those nodes adjacent to some element  
of that set. ■

Corollary 2.6.  $Z(\Gamma_n) = 1$  for all  $n > 0$ .

Proof: If  $g \in Z(\Gamma_n)$  then

$$\begin{aligned} g &\in C_{\Gamma_n}(r_0 r_2 r_4 \dots) \cap C_{\Gamma_n}(r_1 r_3 r_5 \dots) \\ &= \langle r_0, r_2, r_4 \dots \rangle \cap \langle r_1, r_3, r_5 \dots \rangle \\ &= 1, \text{ by abelianisation. } \blacksquare \end{aligned}$$

For  $g \in \Gamma_n$  let  $\mu(g)$  be the set of those conjugacy classes  $C$  of elements of order two in  $\Gamma_n$  such that  $ZC_{\Gamma_n}(h) \simeq C_2$ , for all  $h \in C$ , and  $g \in \bigcup_{h \in C} C_{\Gamma_n}(h)$ . By lemma 2.2  $|\mu(g)|$  is finite.

Proposition 2.7. If  $g \in \Gamma_n$  and  $\alpha \in \text{Aut}(\Gamma_n)$  then  $|\mu(g)| = |\mu(g^\alpha)|$ .

Proof:  $C \in \mu(g) \iff C^\alpha \in \mu(g^\alpha)$ .  $\blacksquare$

Proposition 2.8.  $|\mu(r_i)| = |\{r_j \in R_n : j \notin \{2, (n-2), (i \pm 1)\}\}|$  for all  $r_i \in R_n$ .

Proof: By lemmas 2.2 and 2.5  $\{r_j \in R_n : j \notin \{2, (n-2)\}\}$  represents the conjugacy classes  $C$  of elements of order two such that  $ZC_{\Gamma_n}(h) \simeq C_2$  for all  $h \in C$ . Suppose that  $r_j$  is adjacent to  $r_i$ . By abelianisation  $r_i \notin C_{\Gamma_n}(r_j)^{\Gamma_n}$ , and so the conjugacy class of  $r_j$  does not belong to  $\mu(r_i)$ . Conversely, if  $r_j$  is not adjacent to  $r_i$  and  $j \notin \{2, (n-2)\}$  then its conjugacy class does belong to  $\mu(r_i)$ .  $\blacksquare$

Corollary 2.9. If  $|\mu(r_i)| = |\mu(r_n)|$  then  $i \in \{0, 1, 3, (n-3), (n-1), n\}$ .  $\blacksquare$

Lemma 2.10. If  $\alpha \in \text{Aut}(\Gamma_n)$  then there exists  $\alpha_1 \in \langle \Gamma_n, H_n \rangle$  such that  $r_n^{\alpha\alpha_1} = r_n$ .

Proof: If  $n=2$  then let  $W_n = \{r_0, r_2, r_0 r_2\}$  else let  $W_n = \{r_j \in R_n \mid j \notin \{2, (n-2)\}\}$ . By lemmas 2.2 and 2.5  $W_n$  represents the conjugacy classes  $C$  of involutions that satisfy  $ZC_{\Gamma_n}(h) \simeq ZC_{\Gamma_n}(r_n)$  for all  $h \in C$ . Thus  $r_n^{\alpha g} \in W_n$  for some  $g \in \Gamma_n$ . If  $n=2$  then we are done, so we assume that  $n \neq 2$ . By proposition 2.7  $|\mu(r_n)| = |\mu(r_n^{\alpha g})|$  and so by corollary 2.9  $r_n^{\alpha g} = r_i$  for some  $i$  in  $\{0, 1, 3, (n-3), (n-1), n\}$ . Thus  $r_n^{\alpha g \theta_n^\delta} \in \{r_{(n-3)}, r_{(n-1)}, r_n\}$  for some  $\delta \in \{0, 1\}$ .

Let  $P_n$  denote the set of sets of commuting elements of  $R_n$  and, for  $g \in \Gamma_n$ , let  $U(g)$  be the group  $C_{\Gamma_n}(g)$  modulo  $ZC_{\Gamma_n}(g)$ .

Suppose that  $r_n^{\alpha g \theta_n^\delta} = r_{(n-1)}$ . Then  $U(r_n) \simeq U(r_{(n-1)})$ .

If  $n=1$  then  $r_n^{\alpha g \theta_n^{\delta+1}} = r_n$  and we are done.

If  $n=3$  then  $\Gamma_1 \simeq 1$ , which is false.

If  $n > 3$  then  $\Gamma_{(n-2)} \simeq \Gamma_{(n-3)}$ , thus  $|P_{(n-2)}| = |P_{(n-3)}|$ , which is false.

Suppose that  $r_n^{\alpha g \theta_n^\delta} = r_{(n-3)}$ . Then  $U(r_n) \simeq U(r_{(n-3)})$ .

If  $n=3$  then  $r_n^{\alpha g \theta_n^{\delta+1}} = r_n$  and we are done.

If  $n \in \{4, 5\}$  then  $\Gamma_{(n-2)} \simeq \Gamma_1$ , thus  $|P_{(n-2)}| = |P_1|$ , which is false.

If  $n > 5$  then  $\Gamma_{(n-2)} \simeq \Gamma_{(n-5)} \times \Gamma_1$ , thus  $|P_{(n-2)}|$  equals  $|P_{(n-5)}| |P_1|$ , that is,  $3|P_{(n-5)}|$ . But if  $S \in P_{(n-5)}$  then  $S, S \cup \{r_{(n-3)}\}, S \cup \{r_{(n-2)}\}, \{r_{(n-4)}\} \in P_{(n-2)}$ .

Whence  $|P_{(n-2)}| \geq 3|P_{(n-5)}|$  and so again a contradiction. ■



Proposition 2.11.  $\text{Aut}(\Gamma_1) = \langle \Gamma_1, H_1 \rangle$

Proof: Let  $\alpha \in \text{Aut}(\Gamma_1)$ . By lemma 2.10 there exists  $\alpha_1 \in \langle \Gamma_1, H_1 \rangle$  such that  $r_1^{\alpha\alpha_1} = r_1$ . By the torsion theorem for free products there exists  $g \in \Gamma_1$  such that  $r_0^{\alpha\alpha_1 g}$  is in  $\{r_0, r_1\}$ . If  $r_0^{\alpha\alpha_1 g} = r_1$  then  $r_0^{\alpha\alpha_1} \sim r_1 = r_1^{\alpha\alpha_1}$ , whence  $r_0 \sim r_1$ , which can be contradicted by abelianisation. Thus  $r_0^{\alpha\alpha_1} = r_0^{g^{-1}}$  and so there exists  $m \in \mathbb{Z}$  such that  $r_0^{\alpha\alpha_1}$  is  $r_0$  conjugated by  $(r_0 r_1)^m$ . Furthermore there exists  $\delta \in \{0, 1\}$  and  $k \in \mathbb{Z}$  such that  $r_0^{(\alpha\alpha_1)^{-1}} = r_1^\delta (r_0 r_1)^k$ . Thus  $r_0 = \{r_1^\delta (r_0 r_1)^k\}^{\alpha\alpha_1} = r_1^\delta \{(r_1 r_0)^m r_0 (r_0 r_1)^m r_1\}^k$ . By parity  $\delta = 1$ , and so  $k(2m-1) = 1$ . Thus  $|2m-1| = 1$  and  $m \in \{0, 1\}$ . Whence  $\alpha_1 r_1^m = 1$  and we are done. ■

Proposition 2.12. For any two groups  $G$  and  $H$ , if  $\rho \in \text{Aut}(G \times H)$  and  $H^\rho = H$  then  $\rho\pi_G \in \text{Aut}(G)$  where  $\pi_G$  is the natural epimorphism  $\pi_G : G \times H \longrightarrow G$ .

Proof:  $G = (G \times H)^{\pi_G} = (G \times H)^{\rho\pi_G} = G^{\rho\pi_G} \times H^{\rho\pi_G} = G^{\rho\pi_G}$ .

Suppose that for some  $g \in G$  we have  $g^{\rho\pi_G} = 1$ . Then  $g^\rho \in H$  and so  $g \in H^{\rho^{-1}} = H$ . Whence  $g = 1$ . ■

Theorem 2.13.  $\text{Aut}(\Gamma_n)$  is a split extension of  $\text{Inn}(\Gamma_n)$  by  $H_n$ , and thus  $\text{Out}(\Gamma_n) \simeq H_n$ .

Proof: We will show by induction on  $n$  that  $\text{Aut}(\Gamma_n)$  is generated by  $\text{Inn}(\Gamma_n)$  and  $H_n$ . This is clear for the case  $n = 0$ . We saw the case  $n = 1$  in proposition 2.11, and the case  $n = 2$  was proved by Jones and Thornton [16]. We now assume that  $n > 2$  and that  $\text{Aut}(\Gamma_m) = \langle \Gamma_m, H_m \rangle$  for

all  $m < n$ .

Let  $\alpha \in \text{Aut}(\Gamma_n)$ . By lemma 2.10 there exists  $\alpha_1 \in \langle \Gamma_n, H_n \rangle$  such that  $r_n^{\alpha\alpha_1} = r_n$ . Thus  $\alpha\alpha_1$  restricts to an automorphism of  $C_{\Gamma_n}(r_n)$ . By lemma 2.5  $C_{\Gamma_n}(r_n)$  is  $\Gamma_m \times \langle r_n \rangle$ , where  $m = (n-2)$ . So by proposition 2.12  $\alpha\alpha_1\pi \in \text{Aut}(\Gamma_m)$ , where  $\pi$  is the natural epimorphism  $\pi: \Gamma_m \times \langle r_n \rangle \rightarrow \Gamma_m$ . Thus by inductive hypothesis there exists  $h \in H_m$  and  $g \in \Gamma_m$  such that  $r_i^{\alpha\alpha_1} = r_i^{hg} z_i$  for some  $z_i \in \langle r_n \rangle$ ,  $0 \leq i \leq m$ . We note that

$$\begin{aligned} H_m &= \langle \theta_m \rangle \langle \theta_m \phi_m \rangle \\ &= \{1, \theta_m\} \{1, (\theta_m \phi_m), (\theta_m \phi_m)^2, (\theta_m \phi_m)^{-1}\} \\ &= \{1, \theta_m\} \{1, \theta_m \phi_m, \psi_m \phi_m, \theta_m \psi_m\}, \text{ where } \psi_m = \phi_m^{\theta_m}. \end{aligned}$$

Thus there exists  $\beta, \gamma, \delta \in \{0, 1\}$  such that  $h$  is  $\theta_m^\beta \psi_m^\gamma \phi_m^\delta$ . We note that  $\phi_m$  is the restriction of  $\phi_n$  to  $\Gamma_m$ . Thus if  $\alpha_2 = g^{-1} \phi_n^\delta$  then  $r_i^{\alpha\alpha_1\alpha_2} = r_i^{\theta_m^\beta \psi_m^\gamma} z_i$  for  $i: 0 \leq i \leq m$ , and  $r_n^{\alpha\alpha_1\alpha_2} = r_n$ . Now if  $i \notin \{2, m, (n-1), n\}$  then  $|ZC_{\Gamma_n}(r_i)| \leq |ZC_{\Gamma_n}(r_i^{\theta_m^\beta \psi_m^\gamma} z_i)|$ . Whence  $z_i = 1$  for all  $i \notin \{2, m\}$ . If  $\beta = 1$  then  $\alpha\alpha_1\alpha_2: r_0 \mapsto r_m$ . But  $|ZC_{\Gamma_n}(r_0)| \leq |ZC_{\Gamma_n}(r_m)|$  and so  $\beta = 0$ . Thus we have

$$\begin{aligned} \alpha\alpha_1\alpha_2: r_i &\mapsto r_i \text{ for } i: 0 \leq i \leq (n-3) \text{ and } i \notin \{2, (n-4)\} \\ r_2 &\mapsto r_2 z_2 \text{ for } n = 5 \text{ and } n > 6 \\ r_2 &\mapsto r_2^{\psi_m^\gamma} z_2 \text{ for } n = 6 \\ r_m &\mapsto r_m z_m \\ r_{n-4} &\mapsto r_{n-4}^{\psi_m^\gamma} \text{ for } n \neq 6 \\ r_n &\mapsto r_n \end{aligned}$$

which covers all cases except  $i = (n-1)$ .

For  $n > 4$  we have  $|ZC_{\Gamma_n}(r_2)| \neq |ZC_{\Gamma_n}(r_2 r_n)|$ .

Thus  $z_2 = 1$  for  $n = 5$  and  $n > 6$ .

Also  $|ZC_{\Gamma_6}(r_2)| \neq |ZC_{\Gamma_6}(r_2^{\psi_Y} r_6)|$ . Thus  $z_2 = 1$  for  $n = 6$ .

Furthermore  $|ZC_{\Gamma_n}(r_{(n-4)})| \neq |ZC_{\Gamma_n}(r_{(n-4)} r_m)|$ , so without loss of generality  $\gamma = 0$ . Thus if we put  $z_m = r_n^\varepsilon$  and let  $\rho = \alpha \alpha_1 \alpha_2 \psi_n^\varepsilon$  then  $\rho$  fixes  $r_i$  for all  $i \neq (n-1)$ , and so restricts to an automorphism of  $C_{\Gamma_n}(r_{(n-3)} r_{(n-5)} r_{(n-7)} \dots)$ .

If we let  $G$  be the subgroup  $\langle r_n, r_{(n-1)} \rangle$  and  $H$  the subgroup  $\langle r_{(n-3)}, r_{(n-5)}, r_{(n-7)}, \dots \rangle$  then  $C_{\Gamma_n}(r_{(n-3)} r_{(n-5)} r_{(n-7)} \dots) = G \times H$  and  $H^\rho = H$ . So by proposition 2.12  $\rho \pi_G \in \text{Aut}(G)$ . Now  $r_n^{\rho \pi_G} = r_n$  so we can deduce from the proof of proposition 2.11 that  $r_{(n-1)}^{\rho \pi_G}$  is  $r_{(n-1)}$  conjugated by  $r_n^\delta$  for some  $\delta \in \{0, 1\}$ . Whence  $(r_{(n-1)})^\rho = (r_{(n-1)})^{r_n^\delta} h = (r_{(n-1)} h)^{r_n^\delta}$  for some  $h \in H$ . Thus  $\rho r_n^\delta$  multiplies  $r_{(n-1)}$  by  $h$  and fixes all other  $r_i$ . If  $n = 3$  then  $h = r_0^\eta$  for some  $\eta \in \{0, 1\}$  and so  $\rho r_n^\delta \phi_n^\eta = 1$ . Whence  $\alpha \in \langle \Gamma_n, H_n \rangle$ .

If  $n > 3$  then  $ZC_{\Gamma_n}(r_{(n-1)} h) \simeq ZC_{\Gamma_n}(r_{(n-1)}) \simeq C_2$ . Thus  $h = 1$  and  $\rho r_n^\delta = 1$ . Whence again  $\alpha \in \langle \Gamma_n, H_n \rangle$ . It follows that  $\text{Aut}(\Gamma_n) = \langle \Gamma_n, H_n \rangle$  for all  $n$ . ■

We now consider the group

$$G = \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = 1 \rangle.$$

Theorem 2.14. If  $S_3$  is the group of automorphisms of  $G$  induced by the permutations of  $\{r_0, r_1, r_2\}$  and  $\phi$  is the automorphism that conjugates  $r_2$  by  $r_0$  then  $\text{Aut}(G)$  is generated by  $S_3$  and  $\phi$ , and  $\text{Out}(G) \simeq \text{PGL}(2, \mathbb{Z})$ .

Proof: If  $\alpha \in \text{Aut}(G)$  then, by the torsion theorem for free products, for all  $i \in \{0, 1, 2\}$  there exists  $j$  such that  $r_i^\alpha \sim r_j$ . Thus  $\alpha$  restricts to an automorphism of  $G^+$ . If  $x = r_0 r_1$  and  $y = r_1 r_2$  then  $\{x, y\}$  is a free basis for  $G^+$ , whence  $G^+$  is a free group of rank 2  $F_2$ .

Consider the natural composite map

$$\theta : \text{Aut}(G) \rightarrow \text{Aut}(G^+) = \text{Aut}(F_2) \rightarrow \text{Aut}(F_2/F_2') \simeq \text{GL}(2, \mathbb{Z}) \rightarrow \text{PGL}(2, \mathbb{Z}),$$

where  $F_2'$  denotes the commutator subgroup of  $F_2$ .

We analogise the proof of lemma [21, I.4.5] which states that the kernel of the natural map from  $\text{Aut}(F_2)$  onto  $\text{GL}(2, \mathbb{Z})$  is  $\text{Inn}(F_2)$ .

For  $\{i, j, k\} = \{0, 1, 2\}$  let  $\sigma_i$  be the automorphism that transposes  $r_j$  and  $r_k$ , and let  $\phi_{ij}$  be the automorphism that conjugates  $r_i$  by  $r_j$ . If  $R_1$  is the matrix  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ ,  $R_2$  the matrix  $\begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix}$  and  $R_3$  the matrix  $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$  then  $\bar{R}_1, \bar{R}_2, \bar{R}_3$  generate  $\text{PGL}(2, \mathbb{Z})$  with defining relations

$$\bar{R}_1^2 = \bar{R}_2^2 = \bar{R}_3^2 = (\bar{R}_1 \bar{R}_2)^3 = (\bar{R}_1 \bar{R}_3)^2 = 1,$$

where  $\bar{R}_i$  denotes the image of  $R_i$  in  $\text{PGL}(2, \mathbb{Z})$  [7, 7.2].

We have

$$x = r_0 r_1 \xrightarrow{\phi_{01}} r_1 r_0 \xrightarrow{\sigma_1} r_1 r_2 \xrightarrow{\phi_{01}} r_1 r_2 = y$$

$$y = r_1 r_2 \xrightarrow{\phi_{12}} r_1 r_2 \xrightarrow{\sigma_2} r_1 r_0 \xrightarrow{\phi_{01}} r_0 r_1 = x$$

$$x = r_0 r_1 \xrightarrow{\sigma_2} r_1 r_0 = x^{-1}$$

$$y = r_1 r_2 \xrightarrow{\sigma_2} r_0 r_2 = xy$$

$$x = r_0 r_1 \xrightarrow{\phi_{01}} r_1 r_0 = x^{-1}$$

$$y = r_1 r_2 \xrightarrow{\phi_{12}} r_1 r_2 = y.$$

Whence if  $a_1 = \phi_{01} \sigma_1 \phi_{01}$  ,  $a_2 = \sigma_2$  and  $a_3 = \phi_{01}$  then  $\bar{R}_i = a_i \theta$  for all  $i \in \{1, 2, 3\}$  , and so  $\theta$  is onto.

We have  $\sigma_i^2 = \phi_{ij}^2 = 1$  , whence  $a_1^2 = a_2^2 = a_3^2 = 1$  .

$$\begin{aligned} \text{Furthermore } (a_1 a_2)^3 &= (\phi_{01} \sigma_1 \phi_{01} \sigma_2)^3 = (\phi_{01} \phi_{21} \sigma_1 \sigma_2)^3 = (r_1 \sigma_1 \sigma_2)^3 \\ &= r_1 \sigma_1 \sigma_2 r_1 \sigma_1 \sigma_2 r_1 \sigma_1 \sigma_2 = r_1 r_2 (\sigma_1 \sigma_2)^2 r_1 \sigma_1 \sigma_2 \\ &= r_1 r_2 r_0 (\sigma_1 \sigma_2)^3 = r_1 r_2 r_0 \in \text{Inn}(G) \end{aligned}$$

$$\text{and } (a_1 a_3)^2 = (\phi_{01} \sigma_1)^2 = \phi_{01} \sigma_1 \phi_{01} \sigma_1 = \phi_{01} \phi_{21} \sigma_1^2 = r_1 \in \text{Inn}(G) .$$

Let  $\mathcal{R}$  be the set of defining relations for  $\text{PGL}(2, \mathbb{Z})$  and  $F_3$  the free group with basis  $\{x_1, x_2, x_3\}$  and homomorphisms  $\pi, \rho$  defined by  $\pi : x_i \mapsto a_i$  and  $\rho : x_i \mapsto \bar{R}_i$  . We have

$$\text{Ker}(\theta) \subseteq (\text{Ker}(\rho))\pi = \bar{\mathcal{R}}(x_1, x_2, x_3)\pi \subseteq \bar{\mathcal{R}}(a_1, a_2, a_3) \subseteq \text{Inn}(G) ,$$

where  $\bar{\mathcal{R}}$  denotes the normal closure of  $\mathcal{R}$  . Moreover,

$$\begin{aligned} x &= r_0 r_1 \xrightarrow{r_0} r_1 r_0 = x^{-1} \\ y &= r_1 r_2 \xrightarrow{r_0} r_0 r_1 r_2 r_0 = xy^{-1}x^{-1} \\ x &= r_0 r_1 \xrightarrow{r_1} r_1 r_0 = x^{-1} \\ y &= r_1 r_2 \xrightarrow{r_1} r_2 r_1 = y^{-1} \\ x &= r_0 r_1 \xrightarrow{r_2} r_2 r_0 r_1 r_2 = y^{-1}x^{-1}y \\ y &= r_1 r_2 \xrightarrow{r_2} r_2 r_1 = y^{-1} \end{aligned}$$

Whence  $\text{Ker}(\theta) = \text{Inn}(G)$  , and so  $\text{Out}(G) \simeq \text{PGL}(2, \mathbb{Z})$  . Moreover,

$$\text{Aut}(G) = \text{PGL}(2, \mathbb{Z})\theta^{-1} = \langle \bar{R}_1, \bar{R}_2, \bar{R}_3 \rangle \theta^{-1} = \langle a_1, a_2, a_3 \rangle \text{Inn}(G)$$

and so  $\text{Aut}(G)$  is generated by  $S_3$  and  $\phi$  . ■

3) We now consider the topological interpretation of some of these outer automorphisms. Clearly  $\theta_2$  corresponds to the well-known duality for surface maps, interchanging vertices and faces. Furthermore, the automorphism  $\phi_2$ , which interchanges vertices and Petrie polygons, corresponds to Wilsons opposite operator [31] which is described as follows: make a directed cut along each edge and then rejoin corresponding sides in opposing directions. We illustrate this in Fig. 4.

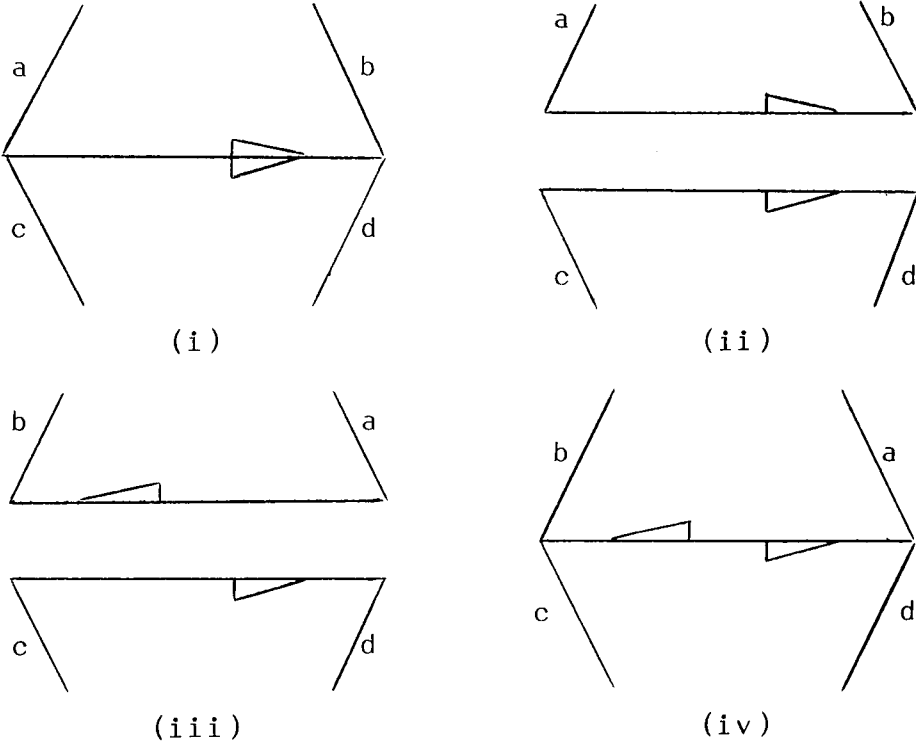


Figure 4

Clearly  $S_3$  acts on hypermaps by permuting the hypervertices, edges and faces. We now verify that  $\phi$  is the result of applying  $\phi_2$  to the underlying two-coloured

map.

To any hyperblade  $\beta$  of a given hypermap we associate a blade  $\beta'$  of the underlying two-coloured map drawn on the incident edge coloured 0 at the incident (contracted) face coloured 0 and on the same side as the incident face coloured 2 (see Fig. 5) .

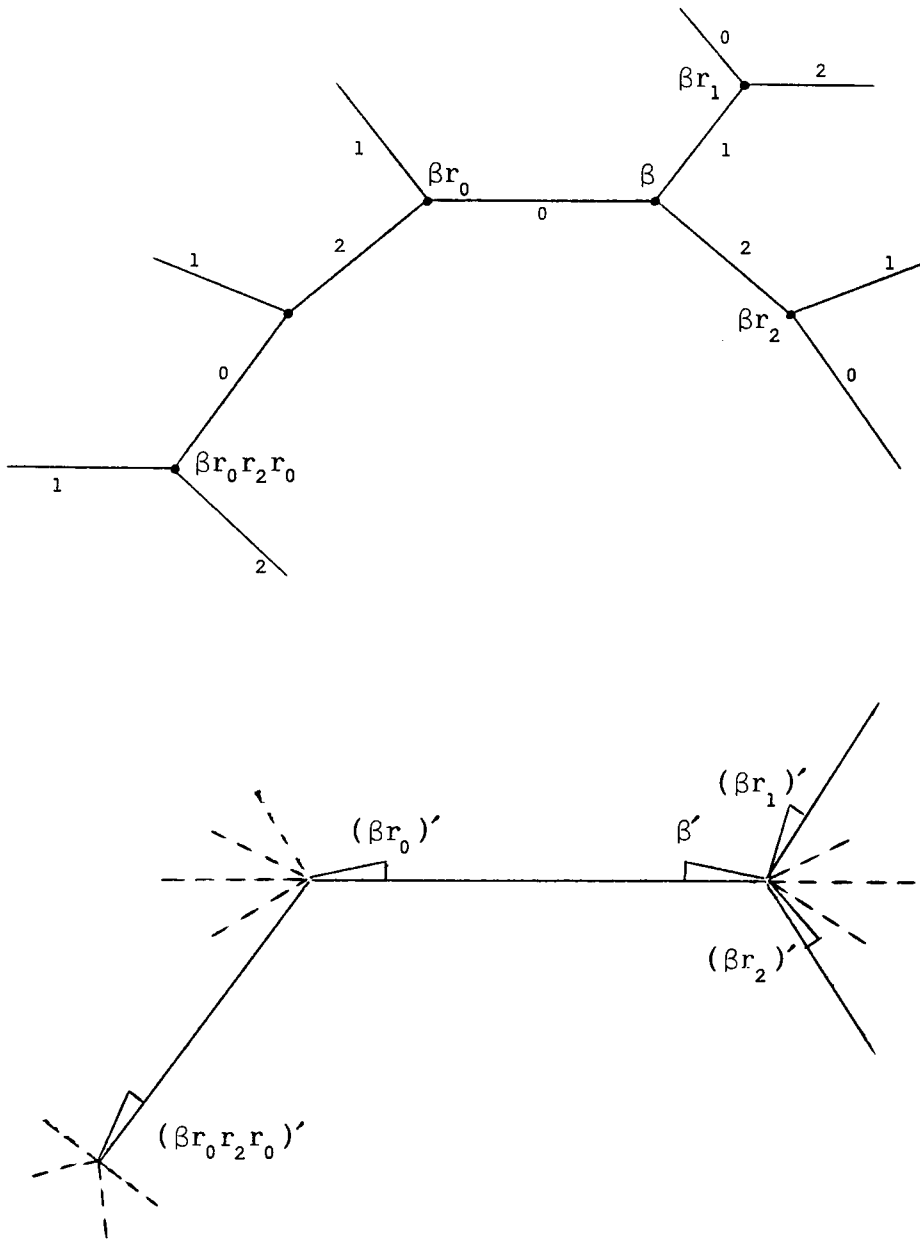


Figure 5

Then under  $\phi_2$  we have

$$(\beta r_0)' = \beta' r_0 \mapsto \beta' r_0 = (\beta r_0)'$$

$$(\beta r_1)' = \beta' r_1 \mapsto \beta' r_1 = (\beta r_1)'$$

$$(\beta r_2)' = \beta' r_2 r_1 r_2 \mapsto \beta' r_0 r_2 r_1 r_0 r_2 = (\beta r_0 r_2 r_0)'$$

thus the action of  $\phi_2$  is equivalent to that of  $\phi$ .

It may be of interest to note that the automorphism  $\psi_2 = \phi_2^{\theta_2}$ , which interchanges faces and Petrie polygons, leaving the underlying graph unchanged, may be topologically described, for a map with neither free edges nor boundary, as follows: remove a disc from each face of the map, then make a directed cut across each edge, rejoin in opposing directions and finally attach a disc to each boundary component. In Fig. 6(i)-6(iv) we show each stage of this operation on the usual imbedding of the complete graph on four vertices on a sphere, Fig. 6(iv) represents a cube which is to be antipodally identified.

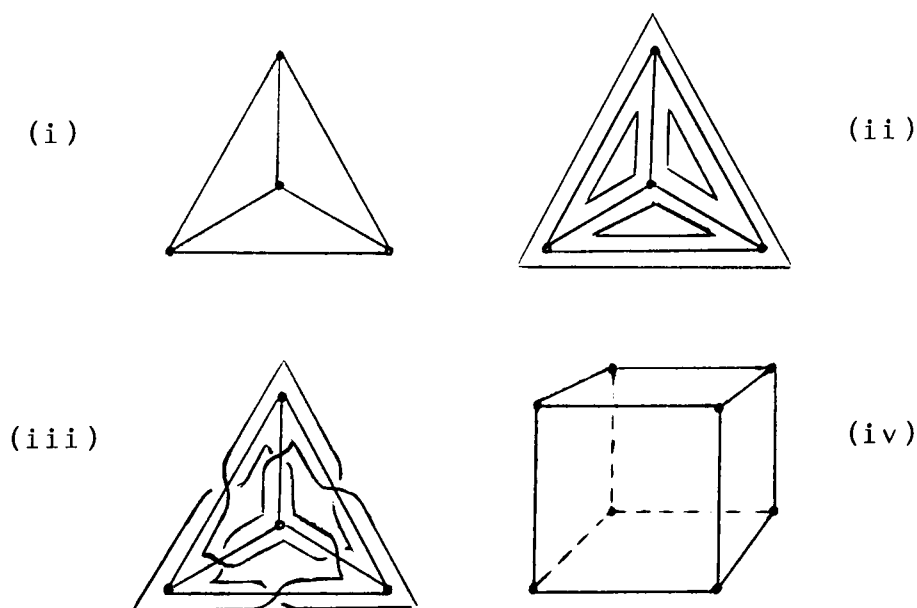


Figure 6



This operation **restricts** locally to the single edge twists used by Edmonds [10] in his characterisation of graph imbeddings. Every imbedding of a graph without free edges in a surface without boundary may be described in the following way: for each vertex of the graph give a cyclic ordering to the incidences of edges, thus orientably imbedding the graph [8], and then to each edge assign the value 1 or 0 according to whether or not it is to be twisted.

Analogously we consider the operation induced by the automorphism of  $G$   $\psi = \phi^\theta$  where  $\theta$  transposes the symbols  $r_0$  and  $r_2$ . Thus  $\psi$  conjugates  $r_0$  by  $r_2$ . Topologically, for a hypermap without boundary,  $\psi$  has the following description: remove each hyperface of the hypermap, then make a directed cut along each hyperdart, rejoin in opposing directions and finally attach a disc to each boundary component. In Fig. 7 we show each stage of this operation on a simple example.

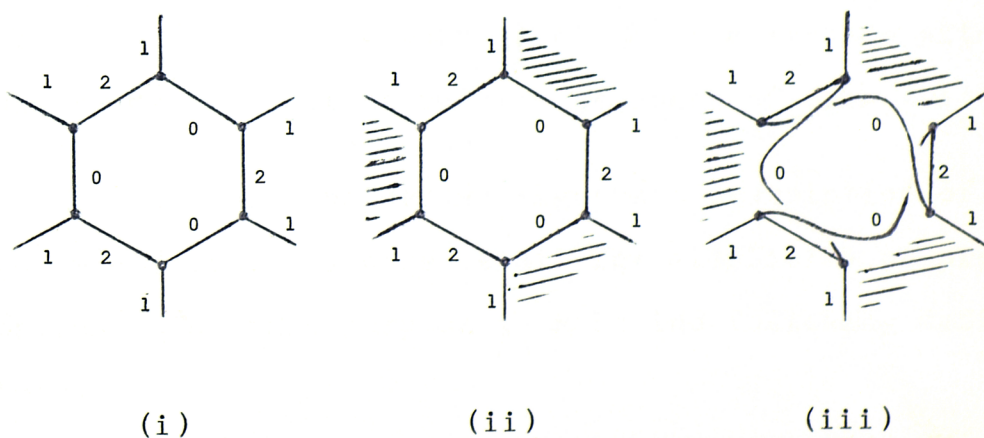


Figure 7

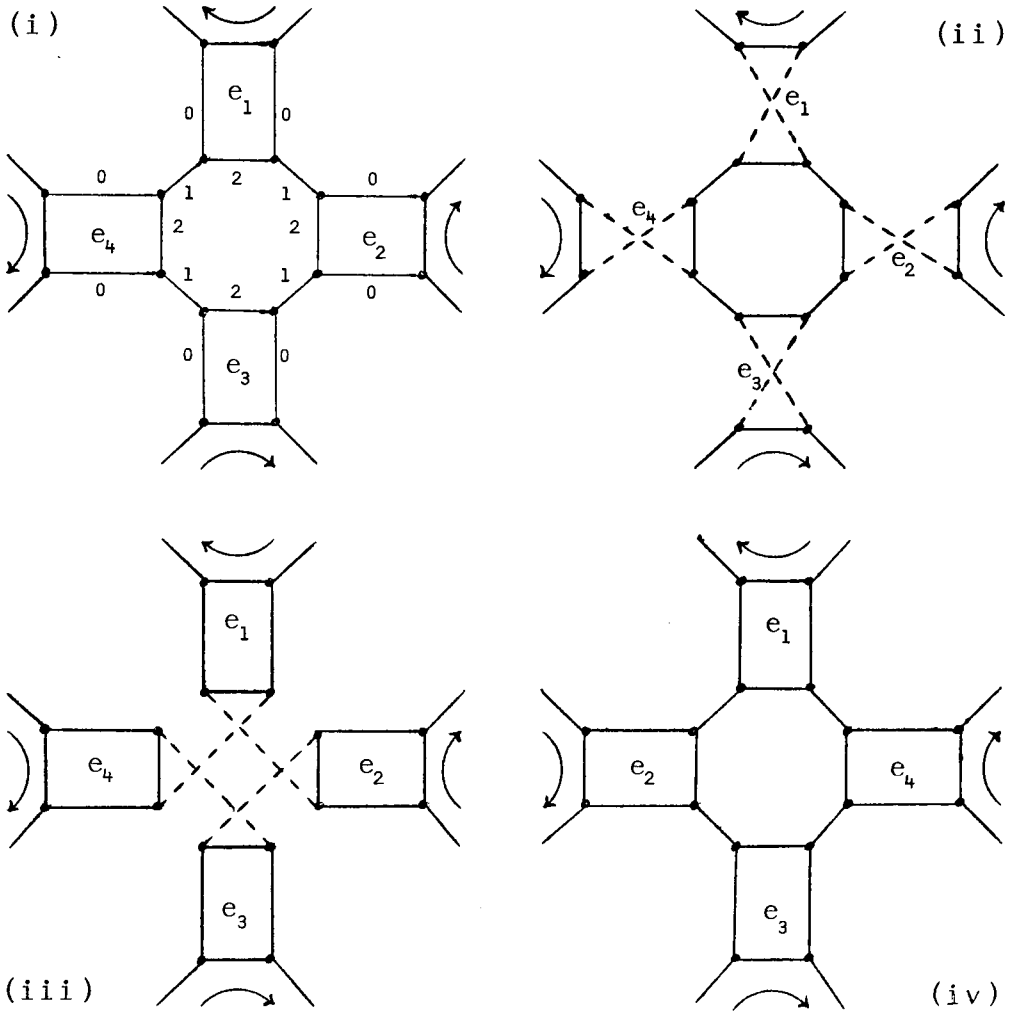
In fact a hyperdart twist corresponds to an edge twist of the underlying bipartite map considered by Walsh [30]. It is readily verified that every imbedding of a hypergraph in a surface without boundary may be described as follows: for each edge of the hypergraph give a cyclic ordering to the incidences of vertices and for each vertex give a cyclic ordering to the incidences of edges, thus orientably imbedding the hypergraph, finally to each vertex-edge incidence assign the value 1 or 0 according to whether or not it is to be twisted. (In essence we have defined the orbits of  $\langle r_0, r_2 \rangle$  and  $\langle r_1, r_2 \rangle$  in the Schreier coset graph, and then specified how they are to be identified.)

We note that if we fix a vertex of an oriented surface map with neither free edges nor boundary and twist each incident edge then we reverse the cyclic ordering of incident edges at that vertex whilst preserving the orientability of the map (see Fig. 8). It follows that if  $\mathcal{G}$  is a graph without free edges whose vertices are at most tri-valent then any two imbeddings of  $\mathcal{G}$  in a surface without boundary are equivalent under a sequence of edge twists.

4) We now consider an algebraic description of an edge twist, omitting some detail for simplicity of presentation. For this purpose we make the following definitions.

Let  $\theta$  be the natural homomorphism from the free group  $F_3$  generated by  $\{r_0, r_1, r_2\}$ , which we denote

Figure 8



by  $R$ , onto  $\Gamma$  and let  $\mathcal{G}$  be any finite graph without free edges, with spanning tree  $T$ , imbedded as a map  $\mathcal{M}$  in a surface without boundary. Let  $M$  denote the stabiliser in  $\Gamma$  of a blade  $\beta$  of  $\mathcal{M}$  and let  $\mathcal{G}(M)$  denote the Schreier coset graph for  $M$  in  $\Gamma$  with respect to  $R$ . We denote edge sets and vertex sets by the letters  $E$  and  $V$  respectively.

For  $v \in VG(M)$  let  $e(v)$  denote the supporting edge of the associated blade in  $\mathcal{M}$ , and let  $T(M)$  be the subgraph of  $G(M)$  with identical vertex set such that if  $v_1, v_2$  are  $i$ -adjacent in  $G(M)$  then they are  $i$ -adjacent in  $T(M)$  unless one of the following holds:

- (i)  $i = 2$  and  $e(v_1) = e(v_2) \in T$
- (ii)  $i = 0$  and  $e(v_1) = e(v_2) \notin T$
- (iii)  $i = 1$  and  $M \in \{v_1, v_2\}$

Clearly  $T(M)$  is a spanning tree for  $G(M)$ . Infact every vertex apart from  $M$  and  $Mr_1$  has valency 2 in  $T(M)$ . We let  $U(M)$  be the Schreier transversal for the pre-image of  $M$  in  $F_3$  determined by  $T(M)$  and let  $X(M)$  denote the generating set for  $M$  determined in the usual way by  $U(M)$ , as presented in [21, II.4.1] for example. If  $w \in F_3$  then  $w$  has a unique reduced decomposition  $\underline{w}$  with respect to  $R^{\pm 1}$ . Let  $\hat{\underline{w}}$  be the corresponding sequence in  $R$  (produced by changing negative powers to positive powers). We note that if  $u \in U(M)$  then  $\hat{u} = u$  and  $r_2$  is never adjacent to  $r_0$  in  $\underline{u}$ .

Given  $e \in EG$  we will define functions  $f_e$  from  $U(M)$  onto  $U(M_e)$  and  $g_e$  from  $X(M)$  onto  $X(M_e)$  such that  $f_e$  fixes the identity element,  $M_e$  is the stabiliser in  $\Gamma$  of a blade  $\beta_e$  in the imbedding  $\mathcal{M}_e$  of  $G$  obtained from  $\mathcal{M}$  by twisting  $e$  and the following diagram commutes, where  $\text{darts}(G)$  is the set of directed edges of  $G$ ;  $\text{darts}(G(M))$  is the set of orbits of  $\langle r_2 \rangle$  in  $VG(M)$ ;  $\phi(\mathcal{M}, \beta)$  and  $\phi(\mathcal{M}_e, \beta_e)$  are induced by the natural

$$\begin{array}{ccc}
\text{darts}(\mathcal{G}) & \xrightarrow{\text{id.}} & \text{darts}(\mathcal{G}) \\
\downarrow \phi(\mathcal{M}, \beta) & & \downarrow \phi(\mathcal{M}_e, \beta_e) \\
\text{darts}(\mathcal{G}(\mathcal{M})) & \xrightarrow{\psi_e} & \text{darts}(\mathcal{G}(\mathcal{M}_e))
\end{array}$$

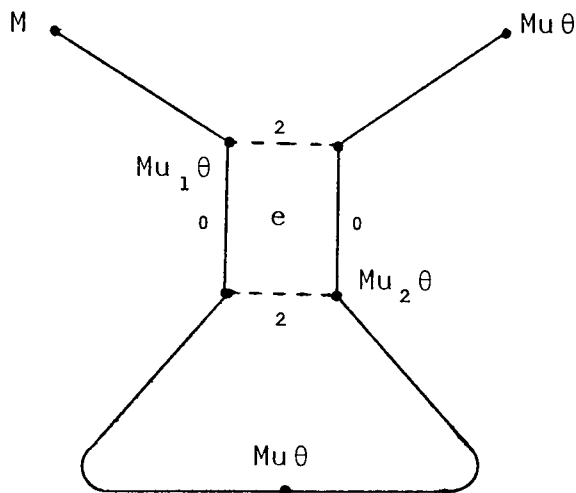
identifications of blades in  $\mathcal{M}$  and  $\mathcal{M}_e$  with  $V\mathcal{G}(\mathcal{M})$  and  $V\mathcal{G}(\mathcal{M}_e)$  respectively; and, for  $u \in U(\mathcal{M})$ ,  $\psi_e$  sends the dart  $\text{Mu}\theta\langle r_2 \rangle$  of  $\mathcal{G}(\mathcal{M})$  to the dart  $\text{M}_e u f_e \theta\langle r_2 \rangle$  of  $\mathcal{G}(\mathcal{M}_e)$ . Thus we assume that in specifying an edge of  $\mathcal{G}$  we specify an orbit of  $\langle r_0, r_2 \rangle$  in  $V\mathcal{G}(\mathcal{M})$ .

For  $e \in E\mathcal{G}$  we define a function  $f_e$  from  $U(\mathcal{M})$  into  $F_3$  as follows. For  $u \in U(\mathcal{M})$  let  $S_e(u)$  denote the set of initial sequences  $\underline{u}_1$  of  $\underline{u}$  such that  $\underline{u}_1 r_0$  is also an initial sequence of  $\underline{u}$  and  $\text{Mu}_1 \theta \in e$ . Thus  $S_e(u)$  has at most two elements and  $e \in T$  if and only if  $S_e(u)$  is non-empty for some  $u \in U(\mathcal{M})$ . There are three cases to consider.

- (i) If  $S_e(u)$  is empty then define  $u f_e$  to be  $u$ .
- (ii) If  $S_e(u)$  consists of a single element  $\underline{u}_1$  then there is a unique element  $u_2 \in U(\mathcal{M})$  such that  $\text{Mu}_1 \theta r_0 r_2 = \text{Mu}_2 \theta$ . Define  $u f_e$  to be  $(u_1 r_0 u_2^{-1} u)^\wedge$ .
- (iii) If  $S_e(u)$  has two elements then let  $\underline{u}_1$  be the shorter and  $\underline{u}_2$  the longer. Define  $u f_e$  to be  $(u_1 r_0 u_2^{-1} u_1 r_0 u_2^{-1} u)^\wedge$ .

Fig. 9 gives an example of the latter two cases.

Figure 9



For  $e \in E\mathcal{G}$  we define a function  $g_e$  from  $X(M)$  into  $\Gamma$  as follows. First note that any reduced decomposition of  $w$  in  $\Gamma$  with respect to  $R$  is largely determined by the normal form of  $w$  in  $\Gamma$  considered as a free product of the groups

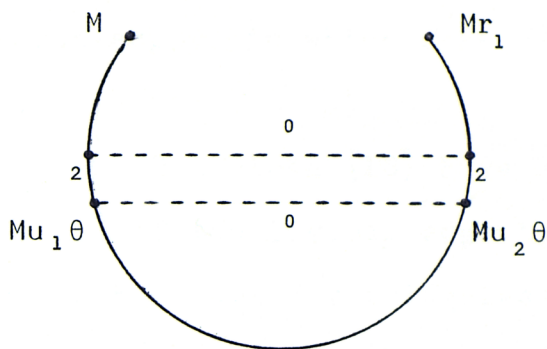
$$\langle r_1 \mid r_1^2 = 1 \rangle \text{ and } \langle r_0, r_2 \mid r_0^2 = r_2^2 = (r_0 r_2)^2 = 1 \rangle ,$$

and recall that if  $u \in U(M)$  then  $r_2$  cannot be adjacent to  $r_0$  in  $\underline{u}$ . If  $x \in X(M)$  then there exists  $u_1, u_2 \in U(M)$  and  $r_i \in R$  such that  $(\underline{u}_1 r_i \underline{u}_2^{-1})^\wedge$  is a reduced decomposition of  $x$  with respect to  $R$  and  $\underline{u}_1$  has maximal length. It follows from the above remarks that  $u_1, u_2$  and  $r_i$  are unique. Fig. 10 gives an example. If  $i = 0$  and  $Mu_1 \theta \in e$  then define  $xg_e$  to be  $(u_1 f_e) r_0 (u f_e)^{-1} \theta$  where  $u$  is the unique element in  $U(M)$  such that  $Mu_1 \theta r_0 r_2$  is  $Mu \theta$ , otherwise define  $xg_e$  to be  $(u_1 f_e) r_i (u_2 f_e)^{-1} \theta$ .

Finally, let  $M_e$  denote the subgroup generated



Figure 10



by  $X(M)g_e$ . Then  $M_e$  is the stabiliser in  $\Gamma$  of a blade  $\beta_e$  in the imbedding  $\mathcal{M}_e$  of  $\mathcal{G}$  obtained from  $\mathcal{M}$  by twisting  $e$ ,  $f_e$  is a function from  $U(M)$  onto  $U(M_e)$  and  $g_e$  is a function from  $X(M)$  onto  $X(M_e)$  such that  $f_e$  fixes the identity element,  $\psi_e$  is well-defined and the above diagram commutes.

In fact it is not hard to see now that  $M$  is a free group of rank  $|E\mathcal{G}| + 1$ . An intuitive proof of this is as follows. Since  $\mathcal{M}$  has neither boundary nor free edges  $M$  is torsion free by the torsion theorem for free products and so  $M$  is a free group by the Kurosh subgroup theorem for free products [21, III.3.6]. Suppose that a subset  $S$  of  $X(M)$  is a free basis for  $M$  such that  $S \cap \{x, x^{-1}\}$  is empty for some  $x \in X(M)$ . Consider the reduced decomposition  $(\underline{u}_1 r_i \underline{u}_2^{-1})^\wedge$  for  $x$  with respect to  $R$  with  $u_1, u_2 \in U(M)$ ,  $r_i \in R$  and  $\underline{u}_1$  maximal. Let  $w$  be any element of  $\langle S \rangle$  and let  $\underline{w}$  be any reduced decomposition of  $w$  with respect to  $R$ . By considering  $\mathcal{G}(M)$  we see that there is no initial sequence  $\underline{w}_1 r_i$  of

$\underline{w}$  such that  $Mw_1 = Mu_1\theta$  and so  $\underline{u}_1r_i$  cannot be an initial sequence of  $\underline{w}$ , whence  $x \notin \langle S \rangle$ . Thus if  $x \in X(M)$  then  $S \cap \{x, x^{-1}\}$  is non-empty, in which case clearly  $S$  is of order  $|E\mathcal{G}| + 1$ .

Little and Ringeisen [18] have shown some interest in the use of topological edge twists to prove the double cover conjecture for bridgeless graphs, that is, that in every bridgeless graph one can find a family  $C$  of cycles such that each edge appears in exactly two cycles of  $C$ . Clearly this is equivalent to imbedding the graph in a surface without boundary such that each edge borders precisely two faces.

If  $e \in E\mathcal{G}$  then  $e$  is a bridge of  $\mathcal{G}$  if and only if  $e$  is in every spanning tree  $T$  of  $\mathcal{G}$ . The two ways in which an edge may be monofacial are illustrated in Fig. 11.

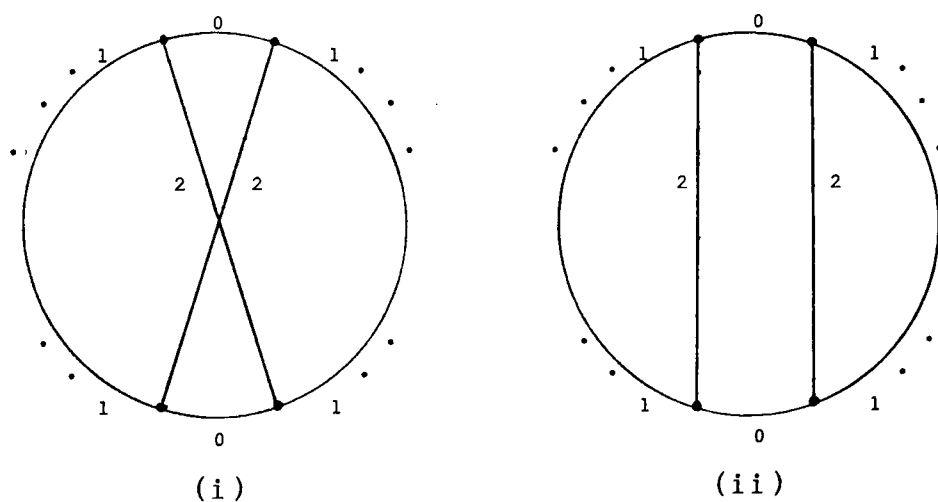


Figure 11



It is clear that in the first case there is an edge twist that strictly decreases the number of monofacial edges without changing their type. For  $\mathcal{M}$  orientable Little and Ringel showed that in the second case there is a sequence of edge twists that strictly decreases the number of monofacial edges of an imbedding of a bridgeless graph.

Algebraically,  $\mathcal{M}$  has  $m$  monofacial edges of the second type where  $m$  is one quarter of the number of cosets of  $M$  containing  $(r_1 r_0)^n r_2 r_0$  for some  $n \in \mathbb{N}$ . Infact it is sufficient to prove the double cover conjecture for cubic graphs  $G$  and, as we have seen, any two imbeddings (without boundary) of  $G$  in this case are equivalent under a sequence of edge twists.

5) In [29] Vince defines an operator on combinatorial maps called the  $\beta$ -dual. Let  $W$  be a group generated by involutions  $r_0, r_1, \dots, r_n$  and let  $G$  be the Schreier coset graph for some subgroup of  $W$ . Call a word  $w$  in  $W$  an involution if every path of type  $w^2$  is closed. Let  $\beta = \{w_i \mid i \in \{0, 1, \dots, n\}\}$  be an indexed set of involutions. Define a new  $\{0, 1, \dots, n\}$ -labelled graph  $G_\beta$  as follows. The point set of  $G_\beta$  is that of  $G$ , and two points are  $i$ -adjacent in  $G_\beta$  if and only if they are connected by a path of type  $w_i$  in  $G$ . If  $G_\beta$  is connected then it is a combinatorial map which is called the  $\beta$ -dual of  $G$ . It is clear that the operations induced by the outer automorphisms of  $\Gamma_n$  and  $G$  are equivalent to  $\beta$ -duals.

In [31] Wilson constructed an operator  $H_j$ . If  $j$  is relatively prime to the valency of each vertex of a surface map then  $H_j$  fixes the underlying graph and redefines the faces to be  $j$ th order holes, that is, cyclic sequences of edges, each two consecutive ones sharing a vertex, so that at each vertex the adjacent edges subtend  $j$  faces on one side, either the right or the left but consistently throughout. These operations were interpreted algebraically in [16] as being induced by the outer automorphisms of the group

$$\Gamma[2, m, \infty] = \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = (r_0 r_1)^2 = (r_1 r_2)^m = 1 \rangle$$

that fix  $r_0$  and  $r_2$  and send  $r_1$  to  $(r_1 r_2)^{(j-1)} r_1$ , where  $j$  is relatively prime to  $m$ .

The set of reflexible surface maps and hypermaps, that is, those that are in some sense most symmetric, is closed under the operations induced by the outer automorphisms of  $\Gamma$  and  $G$ . In the next chapter we consider the symmetry of surface maps and hypermaps and introduce a class of highly symmetric surface maps and hypermaps, containing the reflexible ones, that is also closed under all such operations.



## CHAPTER 3

### Symmetry

1) In this chapter we restrict our attention to surface maps and hypermaps of high symmetry. We start with some definitions.

A map  $\mathcal{M}$  is reflexible [7], [16] if  $\text{Aut}(\mathcal{M})$  acts transitively on the set of blades. If  $\mathcal{M}$  is orientable and without boundary and the subgroup of orientation-preserving automorphisms  $\text{Aut}^+(\mathcal{M})$  acts transitively on the set of darts then  $\mathcal{M}$  is regular [7], [15]. A map  $\mathcal{M}$  is all-symmetric if  $\text{Aut}(\mathcal{M})$  acts transitively on the vertices, edges and faces. If  $\mathcal{M}$  is either reflexible or regular then  $\mathcal{M}^\alpha$  is all-symmetric for every operation  $\alpha$  (induced by an automorphism of  $\Gamma$ ). We define such a map to be highly-symmetric (which we abbreviate to H.S.). If  $H$  is a subgroup of  $\Gamma$  then  $\mathcal{M}$  is H-symmetric if  $\text{Aut}(\mathcal{M})$  acts transitively on  $H$ -orbits of blades under the action of  $\Gamma$  as a permutation group.

Reflexible, regular, all-symmetric, highly-symmetric and  $H$ -symmetric hypermaps are defined similarly.

Proposition 3.1. A map is  $H$ -symmetric if and only if  $NH = \Gamma$  where  $N$  is the normaliser in  $\Gamma$  of the map subgroup.

Proof: If  $\mathcal{M}$  is a map with map subgroup  $M$  then  $\text{Aut}(\mathcal{M})$  acts transitively on  $H$ -orbits if and only if for any  $g \in \Gamma$  there exists  $u \in N_\Gamma(M)$  such that  $Mu^{-1}H = MgH$ , that is,  $g \in NH$ . ■



The analogous proposition for hypermaps, replacing  $\Gamma$  by  $G$ , is similarly proved.

It follows that a map or hypermap is reflexible if and only if the (hyper)map subgroup is a normal subgroup of  $\Gamma$  or  $G$  respectively, and a map or hypermap is regular if and only if the (hyper)map subgroup is a normal subgroup of  $\Gamma^+$  or  $G^+$  respectively.

We call the Schreier coset graph (with respect to  $\{r_0, r_1, r_2\}$ ) of any subgroup of  $\Gamma$  a  $\Gamma$ -graph. If  $H$  is a subgroup of  $\Gamma$  then an  $H$ -symmetric  $\Gamma$ -normaliser is any subgroup  $N$  such that  $NH = \Gamma$ , and an  $H$ -symmetric  $\Gamma$ -graph is the Schreier coset graph of an  $H$ -symmetric  $\Gamma$ -normaliser. So a map is  $H$ -symmetric if and only if its map subgroup is normalised by an  $H$ -symmetric  $\Gamma$ -normaliser, that is, by a node stabiliser of an  $H$ -symmetric  $\Gamma$ -graph.

If  $D$  is the  $\Gamma$ -graph of a subgroup  $N$  of  $\Gamma$  and  $\alpha \in \text{Aut}(\Gamma)$  then we denote the  $\Gamma$ -graph of  $N^\alpha$  by  $D^\alpha$  and identify the nodes of  $D$  with those of  $D^\alpha$  in the obvious way.

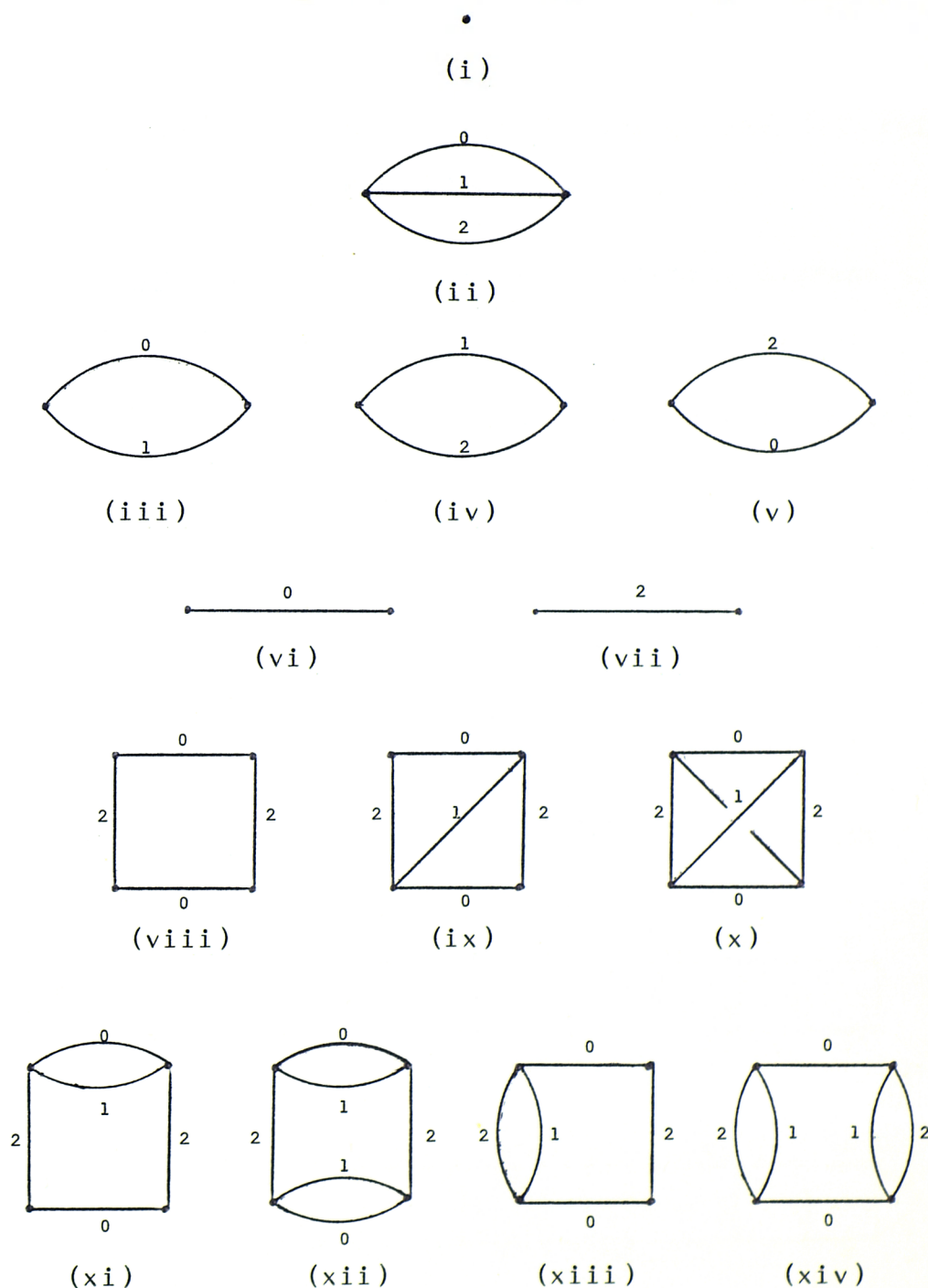
We make analogous definitions for hypermaps, replacing  $\Gamma$  by  $G$ .

2) We now look at  $H$ -symmetric  $\Gamma$ -graphs and  $G$ -graphs for some choices of  $H$ . We note that an edge of a map is an orbit of the dihedral subgroup  $H = \langle r_0, r_1 \mid r_0^2 = r_1^2 = (r_0 r_1)^2 = 1 \rangle$  of order 4. When  $H$  is defined in this way we read "edge-symmetric" for " $H$ -symmetric". Thus a map  $\mathcal{M}$  is edge-symmetric by definition if and only if  $\text{Aut}(\mathcal{M})$  acts transitively on edges. By the remarks of the above section, a map is edge-symmetric if and only if its map subgroup is normalised by a node stabiliser of an edge-symmetric  $\Gamma$ -graph. By definition, an edge-symmetric  $\Gamma$ -graph is the Schreier coset graph



of any subgroup  $N$  satisfying  $NH = \Gamma$ . It follows that if  $\mathcal{G}$  is a graph whose edges are coloured by  $\{0, 1, 2\}$  then  $\mathcal{G}$  is an edge-symmetric  $\Gamma$ -graph if and only if there is a closed walk along four edges (not necessarily distinct, and possibly looped) coloured alternately 0 and 2 which spans the vertices of  $\mathcal{G}$ . We are free to choose the action of  $r_i$  on the cosets. Fig. 12 thus gives all possible edge-symmetric  $\Gamma$ -graphs (with loops omitted).

Figure 12



We immediately observe the following.

Theorem 3.2.<sup>[13]</sup> If  $\mathcal{M}$  is an edge-symmetric map on a surface and  $\text{Aut}(\mathcal{M})$  acts transitively on at least one of the set {vertices, faces, Petrie polygons} then  $\text{Aut}(\mathcal{M})$  acts transitively on at least two of that set. ■

We also observe that the only all-symmetric  $\Gamma$ -graphs are graphs (i), (ii), (iii), (iv), (v), (ix), and (x) and that the only highly-symmetric  $\Gamma$ -graphs are graphs (i), (ii), (iii) and (iv) of Fig.12 .

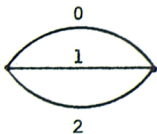
Theorem 3.3. There exists an all-symmetric G-graph on any number of nodes.

Proof: For any natural number  $n$  one of the following is an all-symmetric G-graph on  $n$  nodes. ■

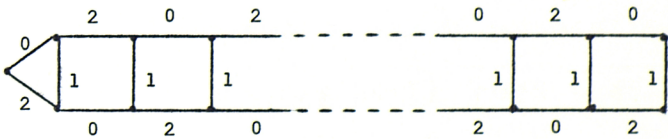
$n = 1$



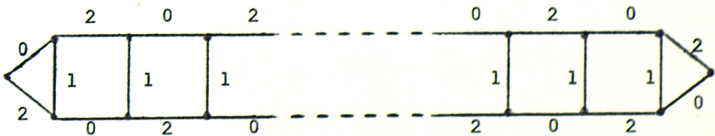
$n = 2$



$n \text{ odd } > 2$



$n \text{ even } > 3$



We now consider the existence of highly-symmetric G-graphs.

For  $\{i, j, k\} = \{0, 1, 2\}$  if  $x$  and  $y$  are nodes of a G-graph that are connected by an  $\{i, j\}$ -path, that is, a path whose edges are coloured either  $i$  or  $j$ , then let  $d_k(x, y)$  denote the length of a shortest  $\{i, j\}$ -path from  $x$  to  $y$ .

Proposition 3.4. If  $D$  is an H.S. G-graph on  $n > 2$  nodes and  $k \in \{0, 1, 2\}$  then  $d_k(x, x r_k)$  is even for all nodes  $x$ .

Proof: If not then there exists an integer  $p$  such that

$$x r_k = x(r_i r_j)^p r_i(r_j r_i)^p \quad \text{where } \{i, j, k\} = \{0, 1, 2\}.$$

$$\text{If } y = x(r_i r_j)^p \text{ then } y(r_j r_i)^p r_k(r_i r_j)^p = y r_i.$$

However, there exists  $\alpha \in \text{Aut}(G)$  sending  $(r_j r_i)^p r_k(r_i r_j)^p$  to  $r_k$  and fixing both  $r_i$  and  $r_j$ .

Whence in  $D^\alpha$  we have  $y r_k = y r_i$ , and so  $D^\alpha$  is not all-symmetric, which contradicts the choice of  $D$ . ■

Proposition 3.5. If  $D$  is an H.S. G-graph on  $n > 2$  nodes and  $i \in \{0, 1, 2\}$  then  $r_i$  has no fixed points in  $D$ .

Proof: Suppose that there exists  $i \in \{0, 1, 2\}$  such that

$x r_i = x$  for some node  $x$ . If  $\{i, j, k\} = \{0, 1, 2\}$  then  $x r_k \neq x$  else  $D$  is not all-symmetric. By proposition 3.4

there exists an integer  $p : 0 < 2p \leq (n-1)$  such that

$$x r_k = x(r_j r_i)^p \quad \text{and so} \quad x r_i r_k r_i = x(r_j r_i)^p r_i. \quad \text{We now choose}$$

$\alpha \in \text{Aut}(G)$  sending  $r_i r_k r_i$  to  $r_k$  and fixing both  $r_i$  and  $r_j$ . Then in  $D^\alpha$  we have  $x r_i = x$  and  $x r_k = x(r_j r_i)^p r_i$ ,

and so  $d_k(x, x r_k) = (2p-1)$ . Whence  $D^\alpha$  cannot be highly-

symmetric, which contradicts the choice of  $\mathcal{D}$ . ■

Corollary 3.6. If  $\{i, j, k\} = \{0, 1, 2\}$  then there is a spanning  $\{i, j\}$ -cycle in every H.S. G-graph on  $n > 2$  nodes, thus  $n$  is even. ■

For  $\{i, j, k\} = \{0, 1, 2\}$  if  $x, y$  and  $z$  are nodes of an H.S. G-graph on  $n > 2$  nodes then let  $d_k^+(x, y)$  denote a directed distance from  $x$  to  $y$  along the  $\{i, j\}$ -cycle. Clearly  $d_k^+(x, y) + d_k^+(y, z) \equiv d_k^+(x, z) \pmod{n}$  and  $d_k^+(x, x r_k)$  is even.

Proposition 3.7. If  $\mathcal{D}$  is an H.S. G-graph on  $n > 2$  nodes and  $k \in \{0, 1, 2\}$  then  $d_k^+(x, x r_k) \equiv 2 \pmod{4}$  for all nodes  $x$ .

Proof: Let  $\{i, j, k\} = \{0, 1, 2\}$ . Then  $d_k(x, x r_k)$  is even and so there exists an integer  $p$  such that  $x r_k = x(r_i r_j)^p$ . Furthermore  $d_i^+(x, x r_i r_j)$  is odd and so we have

$$d_i^+(x, x(r_i r_j)) + d_i^+(x(r_i r_j), x(r_i r_j)^2) + \dots + d_i^+(x(r_i r_j)^{p-1}, x(r_i r_j)^p) \equiv d_i^+(x, x r_k)$$

modulo  $n$ . Now the left hand side is the sum of  $p$  odd terms but  $d_i^+(x, x r_k)$  is odd and  $n$  is even. Thus the left hand side must be odd. Whence  $p$  is odd. ■

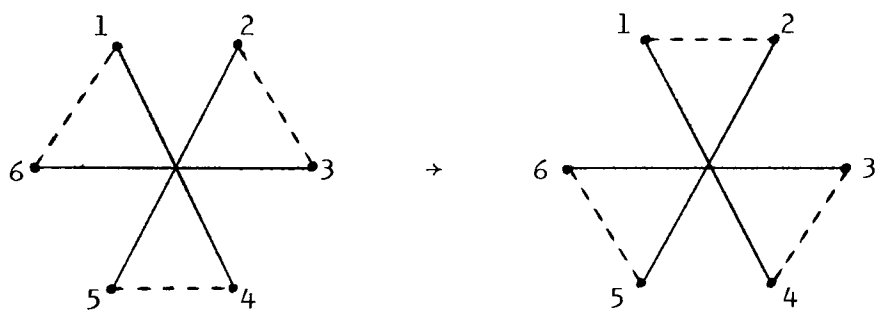
Corollary 3.8. If  $\mathcal{D}$  is an H.S. G-graph on  $n > 2$  nodes then  $n \equiv 0 \pmod{4}$ .

Proof:  $n = d_k^+(x, x r_k) + d_k^+(x r_k, x r_k^2) \dots$  ■



We need some more definitions. An alternating m-gon is a cycle on  $m$  nodes  $\{1, 2, \dots, m\}$  whose edges connect vertices of different parity. Let  $t_m$  be the permutation  $(1\ 2\ \dots\ m)$  and for  $\{x, y\} \subseteq \{1, 2, \dots, m\}$  let  $\{x, y\}t_m$  be the pair  $\{xt_m, yt_m\}$ . A good alternating m-gon is one whose edges can be coloured alternately red and blue such that the union of the blue edges with the images of the red edges under  $t_m$  is again an alternating m-gon. An example of a good alternating hexagon is given in Fig. 13.

Figure 13



Proposition 3.9. If there exists an H.S. G-graph  $D$  on  $n > 2$  nodes then there exists a good alternating  $\frac{1}{2}n$ -gon.

Proof: Let  $\{i, j, k\} = \{0, 1, 2\}$  and let  $x$  be a distinguished node of  $D$ . Colour a  $k$ -edge with vertex  $y$  blue if  $d_k(x, y)$  is even, else colour it red. If we contract each  $i$ -edge  $\{x(r_i r_j)^p, x(r_i r_j)^p r_i\}$  for  $p \in \{1, 2, \dots, \frac{1}{2}n\}$  to a point  $v_p$ , with index to be read modulo  $\frac{1}{2}n$ , then  $\{v_1, v_2, \dots, v_{\frac{1}{2}n}\}$ , together with the  $k$ -edges, forms a  $\frac{1}{2}n$ -gon with edges coloured alternately blue and red. Similarly, if we contract each  $j$ -edge  $\{x(r_i r_j)^p r_j, x(r_i r_j)^p\}$

for  $p \in \{1, 2, \dots, \frac{1}{2}n\}$  to a point  $w_p$ , with index to be read modulo  $\frac{1}{2}n$ , then  $\{w_1, w_2, \dots, w_{\frac{1}{2}n}\}$ , together with the  $k$ -edges, forms a  $\frac{1}{2}n$ -gon with edges coloured alternately blue and red. Furthermore, for  $p \in \{1, 2, \dots, \frac{1}{2}n\}$  there exists  $q = q(p)$  and  $r = r(p)$  where both  $q$  and  $r$  are odd such that  $x(r_i r_j)^p r_k = x(r_i r_j)^{(p+q)}$  and  $x(r_i r_j)^p r_i r_k = x(r_i r_j)^{(p+r)} r_i$ . Correspondingly,  $\{v_p, v_{(p+q)}\}$  and  $\{w_p, w_{(p+q)}\}$  are coloured blue whilst  $\{v_p, v_{(p+r)}\}$  and  $\{w_{(p+1)}, w_{(p+r+1)}\}$  are coloured red. Whence by identifying  $v_p$  with  $w_p$  it is clear that  $\{v_1, v_2, \dots, v_{\frac{1}{2}n}\}$ , together with the  $k$ -edges, forms a good alternating  $\frac{1}{2}n$ -gon. ■

Proposition 3.10. There are no good alternating  $m$ -gons such that  $m \equiv 0 \pmod{4}$ .

Proof: Suppose that we have a good alternating  $m$ -gon such that  $m \equiv 0 \pmod{4}$ . Let  $r$  be the permutation of nodes that transposes the vertices of red edges and  $b$  that which transposes the vertices of blue edges. Then we may write  $r = (a_1 a_2)(a_3 a_4) \dots (a_{m-1} a_m)$  and  $b = (a_2 a_3)(a_4 a_5) \dots (a_m a_1)$ . Let  $s$  be the permutation  $(a_1 a_2 \dots a_m)$  and  $t$  the permutation  $(1 2 \dots m)$ . For all  $x \in \{1, 2, \dots, m\}$  there exists an integer  $p$  such that  $a_x t = a_x (rb)^p r$  since all three of  $t, r$  and  $b$  change parity of node. But  $r$  and  $b$  change parity of index, and so  $t$  changes parity of index. Furthermore, the images of the red edges under  $t_m$  are clearly the orbits of  $r^t$ .

Thus  $t$  is an  $m$ -cycle that changes parity of indices and is such that  $br^t$  is the product of two  $\frac{1}{2}m$ -cycles, fixing parity of indices. We note that  $b = r^s$  and that  $a_x r = a_x s^{-1}$  for  $x$  even, otherwise  $a_x r = a_x s$ .

Whence for  $x$  even we have

$$a_x r^s r^t = a_x s^{-1} r s t^{-1} r t = a_x s^{-1} s s t^{-1} s^{-1} t = a_x s t^{-1} s^{-1} t.$$

Thus  $st^{-1}s^{-1}t \mid_{\text{even indices}}$  is a  $\frac{1}{2}m$ -cycle.

But this is the product of  $st$ ,  $t^{-2}$ ,  $s^{-2}$  and  $st$ , each of which fixes parity of index.

Whence  $st^{-1}s^{-1}t \mid_{\text{even indices}} \in A_{\frac{1}{2}m}$ , the alternating group permuting  $\frac{1}{2}m$  symbols, and so  $\frac{1}{2}m$  must be odd, which contradicts the choice of  $m$ . ■

Corollary 3.11. If  $D$  is an H.S.  $G$ -graph on  $n > 2$  nodes then  $n \equiv 4 \pmod{8}$ . ■

For  $n \equiv 0 \pmod{4}$  consider a set of  $n$  points labelled  $a_r, b_r, c_r, d_r$  where  $r$  ranges from 1 to  $\frac{1}{4}n$ , with indices to be read modulo  $\frac{1}{4}n$ . For integers  $p$  and  $q$  we define a  $G$ -graph  $D_{n,p,q}$  on  $n$  nodes by

$$\begin{array}{lll} a_r r_0 = b_r & b_r r_1 = c_r & a_r r_2 = c_{(r+p)} \\ c_r r_0 = d_r & d_{(r-1)} r_1 = a_r & b_r r_2 = d_{(r+q)} \end{array}$$

Clearly the nodes of  $D_{n,p,q}$  are covered by a  $\{0, 1\}$ -path. The set of nodes of the longest  $\{0, 2\}$ -path through  $a_r$  is

$$\{a_{(r+u(p-q))}, b_{(r+u(p-q))}, d_{(r+q+u(p-q))}, c_{(r+q+u(p-q))} \mid u \in \mathbb{Z}\}.$$

Whence the nodes of  $\mathcal{D}_{n,p,q}$  are covered by a  $\{0, 2\}$ -path  
if  $(\frac{1}{4}n, (p-q)) = 1$ .

The set of nodes of the longest  $\{1, 2\}$ -path through  $a_r$  is

$$\{a_{(r+u(p+q+1))}, d_{(r-1+u(p+q+1))}, b_{(r-1-q+u(p+q+1))}, \\ c_{(r-1-q+u(p+q+1))} \mid u \in \mathbb{Z}\}.$$

Whence the nodes of  $\mathcal{D}_{n,p,q}$  are covered by a  $\{1, 2\}$ -path  
if  $(\frac{1}{4}n, (p+q+1)) = 1$ .

Proposition 3.12. If  $\{i, j, k\} = \{0, 1, 2\}$  then  $\mathcal{D}_{n,p,q}$  is  
invariant under the automorphism  $\phi_{ij}$ .

Proof: Consider the relabelling

$$a'_r = c_{(1-r)}, \quad b'_r = d_{(-r)}, \quad c'_r = a_{(1-r)}, \quad d'_r = b_{(-r)}.$$

We have

$$\begin{aligned} a'_r(r_1 r_0 r_1) &= c_{(1-r)}(r_1 r_0 r_1) = d_{(-r)} = b'_r \\ c'_r(r_1 r_0 r_1) &= a_{(1-r)}(r_1 r_0 r_1) = b_{(-r)} = d'_r \\ b'_r r_1 &= d_{(-r)} r_1 = a_{(1-r)} = c'_r \\ d'_{(r-1)} r_1 &= b_{(1-r)} r_1 = c_{(1-r)} = a'_r \\ a'_r r_2 &= c_{(1-r)} r_2 = a_{(1-r-p)} = c_{(r+p)}' \\ b'_r r_2 &= d_{(-r)} r_2 = b_{(-r-q)} = d_{(r+q)}' \end{aligned}$$

Whence  $\mathcal{D}_{n,p,q}$  is invariant under  $\phi_{01}$ .

Consider the relabelling

$$a'_r = d_{(q-p-r)}, \quad b'_r = c_{(-r)}, \quad c'_r = b_{(-r)}, \quad d'_r = a_{(q-p-r)}.$$

We have

$$\begin{aligned}
a'_r(r_2 r_0 r_2) &= d_{(q-p-r)}(r_2 r_0 r_2) = c_{(-r)} = b'_r \\
c'_r(r_2 r_0 r_2) &= b_{(-r)}(r_2 r_0 r_2) = a_{(q-p-r)} = d'_r \\
b'_r r_1 &= c_{(-r)} r_1 = b_{(-r)} = c'_r \\
d_{(r-1)} r_1 &= a_{(q-p-r+1)} r_1 = d_{(q-p-r)} = a'_r \\
a'_r r_2 &= d_{(q-p-r)} r_2 = b_{(-p-r)} = c_{(r+p)}' \\
b'_r r_2 &= c_{(-r)} r_2 = a_{(-p-r)} = d_{(r+q)}' .
\end{aligned}$$

Whence  $D_{n,p,q}$  is invariant under  $\phi_{02}$  .

Consider the relabelling

$$a'_r = d_{(-r)} , \quad b'_r = c_{(-r)} , \quad c'_r = b_{(-r)} , \quad d'_r = a_{(-r)} .$$

We have

$$\begin{aligned}
a'_r r_0 &= d_{(-r)} r_0 = c_{(-r)} = b'_r \\
c'_r r_0 &= b_{(-r)} r_0 = a_{(-r)} = d'_r \\
b'_r r_1 &= c_{(-r)} r_1 = b_{(-r)} = c'_r \\
d_{(r-1)} r_1 &= a_{(1-r)} r_1 = d_{(1-r)} = a'_r \\
a'_r(r_0 r_2 r_0) &= d_{(-r)}(r_0 r_2 r_0) = b_{(-r-p)} = c_{(r+p)}' \\
b'_r(r_0 r_2 r_0) &= c_{(-r)}(r_0 r_2 r_0) = a_{(-r-q)} = d_{(r+q)}' .
\end{aligned}$$

Whence  $D_{n,p,q}$  is invariant under  $\phi_{20}$  .

To complete the proof we note that  $\phi_{ij}\phi_{kj} = r_j$  and that every G-graph is invariant under  $\text{Inn}(G)$  . ■

Corollary 3.13. If  $(\frac{1}{4}n, (p-q)) = (\frac{1}{4}n, (p+q+1)) = 1$  then

$D_{n,p,q}$  is highly-symmetric.

Proof: By theorem 2.14 the automorphisms  $\phi_{ij}$  generate a normal subgroup of  $\text{Aut}(G)$  with complement  $S_3$  , thus

$D_{n,p,q}^{\text{Aut}(G)} \subseteq D_{n,p,q}^{S_3}$  . Furthermore, since  $D_{n,p,q}$  is all-sym-

metric, each of  $D_{n,p,q}^{S_3}$  is all-symmetric. ■

Theorem 3.14. There exists an H.S. G-graph on  $n$  nodes if and only if  $n \in \{1, 2\}$  or  $n \equiv 4 \pmod{8}$ .

Proof: By corollary 3.11 we need only show existence.

The coset graphs of  $G$  and  $G^+$  in  $G$  give H.S. G-graphs on 1 and 2 nodes, and, by corollary 3.13,  $D_{n,1,0}$  is highly-symmetric for  $n \equiv 4 \pmod{8}$ . ■

Theorem 3.15. The number of equivalence classes of H.S. G-normalisers of index  $n \equiv 4 \pmod{8}$  under  $\text{Aut}(G)$  tends to infinity with  $n$ .

Proof: We note that  $D_{n,p,q}$  and  $D_{n',p',q'}$  denote the same labelled graph if and only if  $n = n'$  and  $(p-p') \equiv (q-q') \equiv 0$  modulo  $\frac{1}{4}n$ . Whence we reduce the suffices  $p, q$  modulo  $\frac{1}{4}n$ . If  $D_{n,p,q}$  and  $D_{n',p',q'}$  denote the same unlabelled graph then there is a symmetry  $\rho$  of the  $\{0, 1\}$ -cycle such that  $D_{n,p,q}^\rho$  has the same labelling as  $D_{n',p',q'}$ . If  $\rho$  is a rotational symmetry then  $D_{n,p,q}^{\rho^2}$  has the same labelling as  $D_{n,p,q}$ . Whence the unlabelled graph denoted by  $D_{n,p,q}$  has at most 4 notations. Furthermore, we have that  $D_{n,p,q}^{\text{Aut}(G)} \subseteq D_{n,p,q}^{S_3}$ , and so each unlabelled graph lies in an orbit of size at most 6. Whence there are at least  $|T_n| / 24$  equivalence classes under  $\text{Aut}(G)$  of H.S. G-graphs on  $n \equiv 4 \pmod{8}$  nodes where  $T_n$  is the set of ordered pairs  $(p, q)$  such that  $1 \leq p, q < \frac{1}{4}n$  and  $(\frac{1}{4}n, (p-q)) = (\frac{1}{4}n, (p+q+1)) = 1$ . Thus it only remains to show that  $|T_n|$  tends to infinity with  $n$ .

For any real number  $x$  let  $[x]$  denote the greatest integer less than or equal to  $x$ .  
Let  $\ell(n) = [\log_2(\frac{1}{4}n)]$  and let  $Q_n$  be the set of pairs  $\{2^m, (\frac{1}{4}n - 2^m)\}$  where  $m$  is any integer between 1 and  $\ell(n)$ .  
Then  $|Q_n| = \ell(n)$ . Furthermore, if  $\{p, q\} \in Q_n$  then  $1 \leq p, q \leq \frac{1}{4}n$  and  $(\frac{1}{4}n, (p-q)) = (\frac{1}{4}n, (p+q+1)) = 1$ . Whence  $|T_n| \geq 2|Q_n| = 2\ell(n) > 2(\log_2(\frac{1}{4}n) - 1)$ , and so  $|T_n|$  tends to infinity with  $n$  as required. ■

Proposition 3.16. Every H.S.  $G$ -normaliser  $N$  of index  $n > 2$  is a free group of rank  $(\frac{1}{2}n + 1)$ .

Proof:

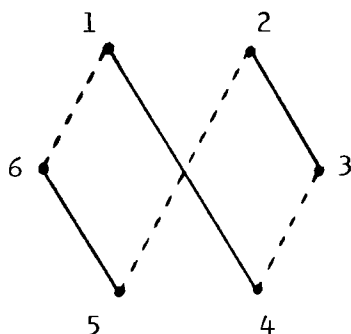
Let  $U = \{1, r_0, r_0 r_1, \dots, (r_0 r_1)^{(\frac{1}{2}n - 1)} r_0\}$   
and  $B = \{u r_2 \overline{u r_2}^{-1} \mid u \in U\} \cup \{(r_0 r_1)^{\frac{1}{2}n}\}$

where, for  $g \in G$ ,  $\overline{g}$  is the unique element of  $U$  satisfying  $Ng = N\overline{g}$ . Then  $B$  clearly generates  $N$  (see for example [21, II.4.1]). Moreover, by considering the coset graph of  $N$  in  $G$  and applying the normal form theorem for free products [21, IV.1.2], it is clear that  $B'$  is a free basis for  $N$  of size  $(\frac{1}{2}n + 1)$  where  $B'$  is any subset of  $B$  satisfying  $|\{b, b^{-1}\} \cap B'| = 1$  for all  $b \in B$ . ■

Corollary 3.17. Every finitely generated group can be regarded as a group of automorphisms of some highly-symmetric hypermap. ■

We finish by giving one more property of an H.S. G-graph. We call an alternating  $m$ -gon very good if its edges can be coloured alternately red and blue such that the union of the blue edges with the images of the red edges under  $t_m^\ell$  is again an alternating  $m$ -gon for all natural numbers  $\ell$ . The example given in Fig. 13 is very good, whilst Fig. 14 shows a good alternating hexagon that is not very good.

Figure 14



By the method of proof of proposition 3.10 it can be shown that very good alternating  $m$ -gons correspond to cyclic permutations  $t$  of  $\{a_1, \dots, a_m\}$  of length  $m$  that change parity of index and are such that the restriction of  $st^{-\ell}(-1)^\ell t^\ell$  to symbols of even index is a  $\frac{1}{2}m$ -cycle for all natural numbers  $\ell$ , where  $s$  is the permutation  $(a_1 \dots a_m)$ .

If  $D$  is an H.S. G-graph on  $n > 2$  nodes then let  $C$  be the alternating  $\frac{1}{2}n$ -gon obtained by contracting the  $i$ -edges as described in the proof of proposition 3.9.



Proposition 3.18.  $C$  is very good.

Proof: If  $x$  is the distinguished node used to construct  $C$  then

$\{v_p, v_q\}$  is a blue edge of  $C^{\sigma_k \phi_{ji}}$   
 $\Leftrightarrow \{x(r_i r_j)^p, x(r_i r_j)^q\}$  is a  $k$ -edge of  $D^{\sigma_k \phi_{ji}}$   
 $\Leftrightarrow \{x(r_i r_j)^p, x(r_i r_j)^q\}$  is a  $k$ -edge of  $D$   
 $\Leftrightarrow \{v_p, v_q\}$  is a blue edge of  $C$ , and

$\{v_p, v_q\}$  is a red edge of  $C^{\sigma_k \phi_{ji}}$   
 $\Leftrightarrow \{x(r_i r_j)^p r_i, x(r_i r_j)^q r_i\}$  is a  $k$ -edge of  $D^{\sigma_k \phi_{ji}}$   
 $\Leftrightarrow \{x(r_j r_i)^p r_i, x(r_j r_i)^q r_i\}$  is a  $k$ -edge of  $D^{\sigma_k}$   
 $\Leftrightarrow \{x(r_i r_j)^p r_j, x(r_i r_j)^q r_j\}$  is a  $k$ -edge of  $D$   
 $\Leftrightarrow \{v_{(p-1)}, v_{(q-1)}\}$  is a red edge of  $C$ .

Whence  $C^{(\sigma_k \phi_{ji})^\ell}$  is the union of the blue edges of  $C$  with the images of the red edges of  $C$  under  $t_m^\ell$ .

Furthermore, since the image of  $D$  under  $(\sigma_k \phi_{ji})^\ell$  is highly-symmetric, the image of  $C$  under  $(\sigma_k \phi_{ji})^\ell$  is an alternating  $\frac{1}{2}n$ -gon. ■

The final chapter demonstrates the possibility of classifying imbeddings with prescribed symmetry. We shall classify the edge-symmetric imbeddings of complete graphs in surfaces without boundary.

## CHAPTER 4

### Complete Maps

1) If  $\mathcal{M}$  is an imbedding of a simple graph with  $n$  vertices in a possibly non-orientable surface, without boundary, then its automorphism group acts semi-regularly on the set of blades, so has order at most four times the number of edges, being at most  $2n(n-1)$ . This bound is attained if and only if  $\mathcal{M}$  is a reflexible imbedding of a complete graph, thus we can regard such imbeddings as the most symmetric surface maps. Similarly, the regular imbeddings of complete graphs can be regarded as the most symmetric orientable surface maps.

In [1] Biggs showed that the complete graph on  $n$  vertices  $K_n$  has a regular imbedding if and only if  $n$  is a prime power. The examples he gave were Cayley maps based on the additive groups of finite fields, using the multiplicative action of a primitive element to generate the rotation.

Any reflexible or regular imbedding is also both vertex- and edge-symmetric. In [2] Biggs showed that any orientable vertex-symmetric imbedding of a complete graph in a surface without boundary can be described as a Cayley map. The aim of this chapter is to classify the edge-symmetric imbeddings of complete graphs in surfaces without boundary.

2) For motivation we start with an example of an orientable edge-symmetric non-regular imbedding of  $K_7$ . In fact we shall see later that this is unique. Consider the imbedding given in Fig.16 of  $K_7$  in an orientable surface of genus 3. There are three heptagonal faces, labelled 1, 2 and 3, and seven triangular faces. We have a rotation of order seven about the centre of a heptagonal face that cyclically permutes the vertices, and the stabiliser of each vertex is generated by a rotation of order 3. The imbedding is clearly edge-symmetric since the automorphism group is transitive on the edges incident with the centrally depicted vertex. In fact, if we regard the triangular faces as hyperedges and the heptagonal faces as hyperfaces then we have one of the two regular imbeddings of the Fano plane (see Fig.15) regarded as a hypergraph [25]. The other is similarly related to the unique regular imbedding of  $K_7$  on a torus [30].

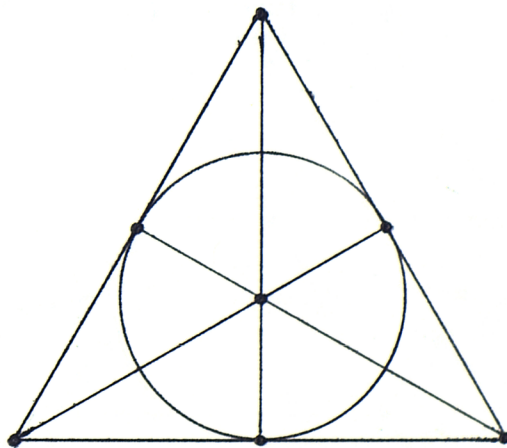
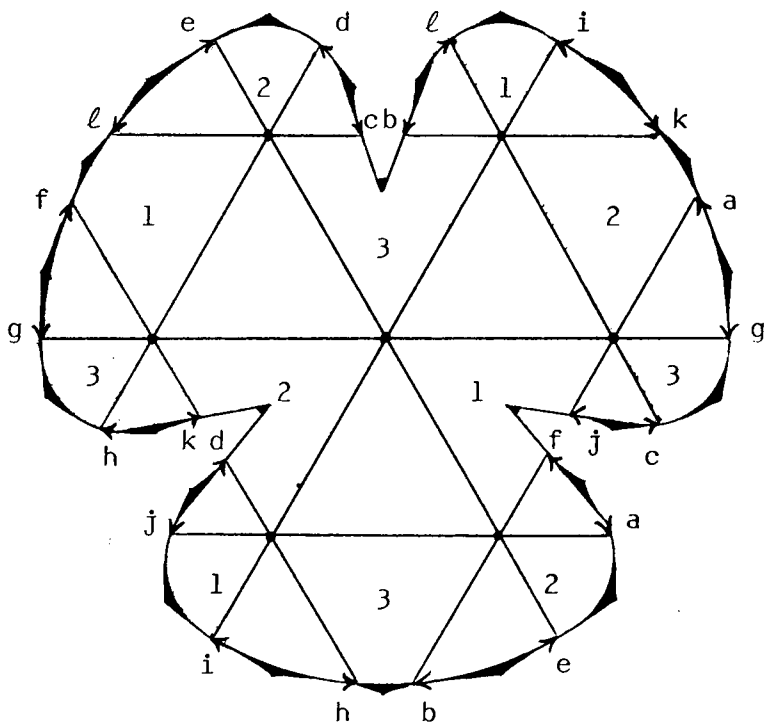
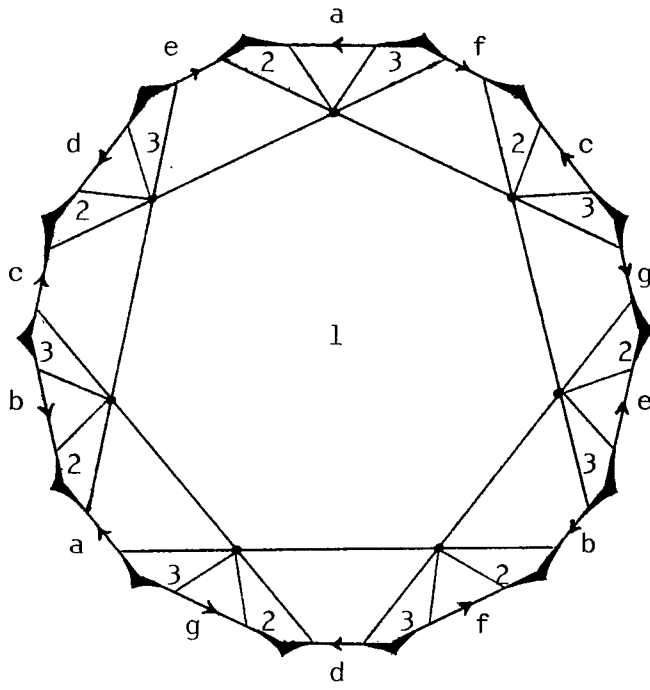


Figure 15

Figure 16





3) By considering the possible Euler characteristics of the underlying surfaces it is easy to see that the only imbeddings of  $K_n$  for  $n \leq 3$  in surfaces without boundary are the usual imbeddings in a sphere and the imbedding of  $K_3$  in a projective plane obtained by antipodally identifying a spherical imbedding of a graph with six 2-valent vertices. Furthermore, each of these are reflexible imbeddings. We thus assume that  $n > 3$ .

Let  $M$  be an edge-symmetric imbedding of  $K_n$  with map subgroup  $M$  normalised in  $\Gamma$  by  $N$ . The coset graph of  $N$  in  $\Gamma$  must be one shown in Fig. 12, and so  $[\Gamma : N]$  is either 1, 2 or 4. We may faithfully represent the map automorphism group  $A$  as a 2-homogeneous permutation group of order

$$[N : M] = [\Gamma : M] / [\Gamma : N] = 2n(n-1)/[\Gamma : N]$$

acting on the vertex set  $V$ . We note that if  $A$  has even order then it acts 2-transitively.

If  $[\Gamma : N] = 1$  then  $N$  has graph (i) of Fig. 12 and  $A$  is a 2-transitive group of degree  $n$  and order  $2n(n-1)$ . In [12] Ito shows that such a group either has a regular normal subgroup or  $n$  is 6 and the group is isomorphic to  $A_5$  or  $n$  is 28 and the group is isomorphic to a split extension of  $SL(2,8)$  by  $C_3$ . We will make use of Ito's methods later.

If  $[\Gamma : N] = 2$  then  $A$  is a sharply 2-transitive group. By Zassenhaus's Theorem [32] (see also [11, 20.7.1]) we can identify the action of any such group with that of  $AGL(1, F)$  on some near field  $F$ , with  $|F| = |V| = n$ . In particular  $A$  is Frobenius and so a vertex stabiliser cannot be dihedral [23, 18.1]. If  $v$  is the vertex of the blade stabilised by  $M$  then

$$A_v \cong M \{ \langle r_1, r_2 \rangle \cap N \} / M$$

Thus the graph of  $N$  is either (ii) or (iv) of Fig. 12. In which case  $A_v$  is abelian and can be identified with  $F^*$ , that is,  $F \setminus \{0\}$ , and hence  $F$  is a field  $GF(n)$  where  $n$  is a prime power  $p^e$ .

If  $[\Gamma : N] = 4$  then  $A$  is a sharply 2-homogeneous group. By a classification of Kantor [17] we can identify the action of any such group with the transitive action of a subgroup of index 2 in  $AGL(1, F)$  on a near field  $F$  where  $|F| = |V| = n = p^e \equiv 3 \pmod{4}$ . This is done in such a way that if  $G$  denotes the group  $AGL(1, F)$  then  $A_0$  is centralised by a element of  $G_0 \setminus A_0$ . Since  $A$  acts transitively on vertices we have  $\Gamma = N \langle r_1, r_2 \rangle$  and so the graph of  $N$  is none of (viii), (xiii), (xiv) of Fig. 12. Furthermore,  $A_0$  has odd order and so cannot be dihedral. Whence, since

$$A_0 \simeq M \{ \langle r_1, r_2 \rangle \cap N \} / M$$

the graph of  $N$  is neither (ix) nor (xi) of Fig. 12. Thus the graph of  $N$  is either (x) or (xii) of Fig. 12. In which case  $A_0$  is abelian and can be identified with a subgroup of index 2 in  $F^*$ . Moreover,  $A_0$  is centralised by an element of  $G_0 \setminus A_0$ . By identifying  $G_0$  with  $F^*$  we see that  $F^*$  is abelian. Hence  $F$  is a field  $GF(n)$ .

Thus we have shown that the coset graph of  $N$  in  $\Gamma$  is one of (i), (ii), (iv), (x) and (xii) of Fig. 12. In cases (ii) and (iv)  $A$  is isomorphic to the group  $AGL(1, F)$  where  $F = GF(n)$  and  $n = p^e$ . In cases (x) and (xii)  $A$  is isomorphic to the unique subgroup of index 2 in  $AGL(1, F)$  where  $F = GF(n)$  and  $n = p^e \equiv 3 \pmod{4}$ .

We recall the graph-preserving operation  $\psi$  that is induced by the automorphism of  $\Gamma$  that multiplies  $r_0$  by  $r_2$ . This preserves the subgroup  $\langle r_0, r_2 \rangle$ , whose orbits are edges, and so  $\psi$  preserves edge-symmetry. If  $M$  is an edge-symmetric imbedding of  $K_n$  with map subgroup  $M$  normalised in  $\Gamma$  by  $N$  where  $N$  has coset graph (iv) then  $M^\psi$  is an edge-symmetric imbedding of  $K_n$  with map subgroup  $M^\psi$  normalised in  $\Gamma$  by  $N^\psi$  where  $N^\psi$  has coset graph (ii), and vice versa. Similarly, if  $N$  has coset graph (x) then  $N^\psi$  has coset graph (xii), and vice versa.



It follows that either  $\mathcal{M}$  or  $\mathcal{M}^\psi$  has map subgroup normaliser with coset graph (i), (ii) or (xii) of Fig. 12 where  $\psi$  is the graph-preserving operation induced by the outer automorphism of  $\Gamma$  that multiplies  $r_0$  by  $r_2$ .

If  $N$  has graph (i) then  $N = \Gamma$  and  $\mathcal{M}$  is reflexible. If  $N$  has graph (ii) then  $N = \Gamma^+$  which is presented by  $\langle X, Y \mid X^2 = 1 \rangle$  where  $X = r_0 r_2$  and  $Y = r_1 r_2$  thus  $\mathcal{M}$  is regular. If  $N$  has graph (xii) then  $N = \Gamma^{++} = \langle P, Z \mid - \rangle$  where  $P = Y^2$  and  $Z = Y^{-1} X$ , and so  $\mathcal{M}$  is orientable. We shall call any orientable imbedding such that  $N^+ = \Gamma^{++}$  a type 3 imbedding.

4) The following classification of the reflexible imbeddings of  $K_n$  in surfaces without boundary was first given in [13].

Theorem 4.1. Reflexible imbeddings of  $K_n$  in surfaces without boundary exist only for  $n=1, 2, 3, 4$  and  $6$ , and they are: the usual imbeddings in a sphere for  $n=1, 2, 3$  and  $4$ ; the spherical imbedding of the graph with six 2-valent vertices, the cube and the icosahedron, with antipodal points identified in each case to give imbeddings in the projective plane for  $n=3, 4$  and  $6$  respectively; finally, the orientable imbedding of the 1-skeleton of the icosahedron formed by applying Wilson's operation  $H_2$  to the icosahedron is antipodally identified to give a reflexible imbedding of  $K_6$  in a non-orientable surface of genus 5.

Proof: It's easy to check that the above maps are reflexible imbeddings of complete graphs. We now verify that these are the only reflexible imbeddings of complete graphs in surfaces without boundary.

We have already seen that the theorem is true for  $n \leq 3$ . For  $n > 3$  suppose that  $M$  is a reflexible imbedding of  $K_n$ . We make use of Ito's methods, the basic idea being to count the number of involutions in  $A$ . Let  $v$  and  $w$  be vertices, let  $H = A_v$  and  $K = A_{(v,w)}$ . Then  $H \approx D_{(n-1)}$ , generated by reflections  $r$  and  $t$ , and  $K \approx C_2$ , generated by  $t$ , with actions illustrated in Fig. 17. Furthermore, there exists a reflection  $\ell$  that transposes  $v$  and  $w$ , and commutes with  $t$ . By its double transitivity we may decompose  $A$  into the disjoint union  $A = H + H\ell H$ . If  $h_1 \in H$  then



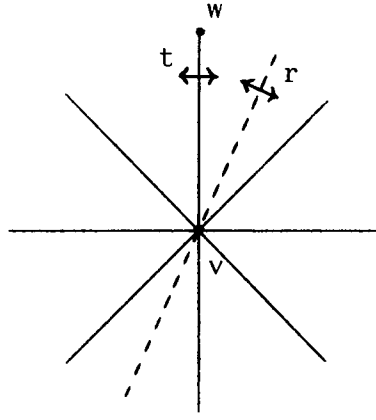


Figure 17

$$H\ell h_1 = H\ell \Leftrightarrow \ell h_1 \ell \in H \Leftrightarrow \ell h_1 \ell(v) = v \Leftrightarrow h_1(w) = w \Leftrightarrow h_1 \in K .$$

So the number of residue classes of the form  $H\ell h_1$  is  $|H|/|K| = (n-1)$  . Suppose that  $h_2 \in H$  . Then

$$(h_2 \ell h_1)^2 = 1 \Rightarrow h_2 \ell h_1 h_2 \ell h_1(v) = v \Leftrightarrow h_1 h_2 \ell h_1(v) = \ell h_2^{-1}(v) \Leftrightarrow h_1 h_2(w) = w \Leftrightarrow h_1 h_2 \in K \Leftrightarrow h_2 \in \{h_1^{-1}, h_1^{-1}t\} .$$

Thus the double coset  $H\ell H$  is itself a disjoint union of  $(n-1)$  right cosets of the form  $H\ell h_1$  , where  $h_1 \in H$  , each containing just two involutions. Thus there are  $2(n-1)$  involutions in  $H\ell H$  .

We now take the cases  $n$  odd and  $n$  even separately. For  $n$  odd there are  $n$  involutions in  $H$  and so  $n+2(n-1)$  involutions in  $A$  . Each stabiliser contains  $\frac{1}{2}(n+1)$  involutions with exactly one fixed point, that is, that lie in no other stabiliser. Thus we have at least  $\frac{1}{2}n(n+1)$  involutions, and so  $n+2(n-1) \geq \frac{1}{2}n(n+1)$  , giving  $n \leq 4$  , and thus a contradiction. For  $n$  even there are  $(n-1)$  involutions in  $H$  , so  $3(n-1)$  involutions

in  $A$ . The number of involutions with exactly two fixed points equals the number of edges, that is,  $\frac{1}{2}n(n-1)$ , so  $3(n-1) \geq \frac{1}{2}n(n-1)$ , giving  $n=4$  or  $6$ . We now examine these possibilities.

Let there be  $f$  faces, each an  $m$ -gon. For  $n=4$  the Euler characteristic of the underlying surface is  $4-6+f$  and so  $f \leq 4$ . We see that  $A \leq S_4$  and that  $r_1 r_0$  acts as a rotation of edges around a face. Thus  $r_1 r_0$  has order  $m$  in  $S_4$  and so  $m \leq 4$ . But  $fm$  is just twice the number of edges, that is,  $12$ , and so  $f \geq 3$ . If  $f=4$  then  $(r_1 r_2)^3, (r_1 r_0)^3 \in M$  and we are looking for  $\bar{M}$  such that

$$\begin{aligned} \bar{M} &\trianglelefteq \Gamma[2,3,3] \\ &= \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = (r_2 r_0)^2 = (r_1 r_2)^3 = (r_1 r_0)^3 = 1 \rangle \\ &\simeq S_4 \end{aligned}$$

But  $|\Gamma/M| = 2n(n-1) = 24 = |S_4|$  and so  $\bar{M} = 1$ . If  $f=3$  then we are looking for  $\bar{M}$  such that

$$\begin{aligned} \bar{M} &\trianglelefteq \Gamma[2,3,4] \\ &= \langle r_0, r_1, r_2 \mid r_0^2 = r_1^2 = r_2^2 = (r_2 r_0)^2 = (r_1 r_2)^3 = (r_1 r_0)^4 = 1 \rangle \\ &\simeq S_4 \times C_2 \end{aligned}$$

But  $|\Gamma/M| = 24$  and so  $|\bar{M}| = 2$ . Therefore  $\bar{M} = Z(\Gamma[2,3,4])$  and so in either case  $\bar{M}$ , and thus  $M$ , is uniquely determined. Whence there are at most two reflexible imbeddings of  $K_4$ .

If  $n=6$  then  $A$  cannot have a regular normal subgroup since  $n$  is not a prime power [3, 1.7.6]. We

now show that  $A$  must be simple. Suppose that  $L$  is a proper normal subgroup of  $A$ . Clearly  $L$  is transitive and thus  $L_v$  is a normal subgroup of  $A_v \cong D_5$  of order either 2 or 5. If  $|L_v| = 2$  then  $L_v \leq Z(D_5)$  against  $Z(D_5) = 1$ . If  $|L_v| = 5$  then  $L$  is sharply 2-transitive and  $n$  would have to be a prime power by Zassenhaus' classification. Thus  $A$  is simple of order 60, and so  $M$  is the kernel of an epimorphism from  $\Gamma$  to  $A_5$ .

We need only look for images of  $r_0, r_1, r_2$  in  $A_5$  that form a generating set  $T$  of  $A_5$  up to automorphism of  $A_5$ . Hence we treat conjugation by  $S_5$  as an equivalence. We see that  $T$  contains two commuting involutions and we can assume that these are  $(12)(34)$  and  $(13)(24)$ . The third element must move 5, and we can assume that it fixes 4 (else conjugate by  $(14)(23), (24)(13)$  or  $(34)(12)$ ) so it is one of  $(12)(35), (13)(25)$  or  $(15)(23)$ . Conjugation by  $(23)$  identifies the first two choices, so there are only two possibilities for  $T$ , namely  $\{(12)(34), (13)(24), (12)(35)\}$  and  $\{(12)(34), (13)(24), (15)(23)\}$ . In the first case commutativity and orders of elements imply that:  
 $r_1 \mapsto (12)(35)$  ;  $r_2 \mapsto (13)(24)$  ;  $r_0 \mapsto (12)(34)$ .  
 In the second case commutativity implies that  $r_1 \mapsto (15)(23)$ , and then conjugation by  $(23)$  fixes  $(15)(23)$  while transposing the other two, so either choice of images for  $r_2$  and  $r_0$  will give the same kernel. Thus there are at most two reflexible imbeddings of  $K_6$ . ■

5) From now on we let  $G$  denote the group  $\text{AGL}(1, F)$  where  $F = \text{GF}(n)$  and  $n = p^e$ . Thus  $G$  is generated by the functions  $s_a : f \mapsto af$ ,  $t_b : f \mapsto f+b$  such that  $a, b \in F$  with  $a$  non-zero. We let  $\mathcal{P}$  be the set of primitive elements of  $F$  and let  $Q = F \setminus \{0\}$ . Then  $\mathcal{P}^2 = \{a^2 \mid a \in \mathcal{P}\}$  and  $Q^2 = \{b^2 \mid b \in Q\}$ . Finally, let  $H$  denote the unique subgroup of  $G$  of index 2 for  $n \equiv 3 \pmod{4}$  consisting of the functions  $f \mapsto b^2 f + c$  for  $b \in Q$ ,  $c \in F$ .

The following classification and description of the regular imbeddings of  $K_n$  for  $n > 3$  was first given in [14]. We use the same methods to classify and describe the type 3 imbeddings of  $K_n$  for  $n > 3$ .

If  $M \subseteq N^+ = \Gamma^+$  then  $M$  is the kernel of an epimorphism from  $\Gamma^+$  to  $G$ , sending  $(X, Y)$  to  $(x, y)$  where  $o(x) = 2$  and  $o(y) = (n-1)$ . Moreover, we now show that such kernels must give rise to imbeddings of  $K_n$ . Since  $G$  acts transitively on vertices, the number of vertices is  $[G : G_v] = [G : \langle y \rangle] = n$ , and the number of edges is just half the order of  $G$ . So we need only check that these maps have neither loops nor multiple edges. If loops exist then all edges are loops, against the connectedness of the graph. If there is a multiple edge then all edges are multiple and so for some  $i, j \neq 0$  modulo  $(n-1)$  we have  $xy^i xy^j$  fixing a dart, and hence it is the identity in  $G$ . Hence  $y^{(i+j)} = x^{-1} y^{-i} x y^i$  lies in the commutator subgroup, and thus the translation subgroup  $T$ , of  $G$  and therefore has order dividing  $|T| = n$ . However,  $y$  has order  $(n-1)$  so  $y^{(i+j)} = 1$ .

Thus  $y^i$  commutes with  $x$  and so lies in the centre of  $G$ ; this is the trivial subgroup (since  $n > 2$ ), so  $i \equiv 0$  modulo  $(n-1)$ , against our hypothesis.

If  $M \subseteq N^+ = \Gamma^{++}$  then  $M$  is the kernel of an epimorphism from  $\Gamma^{++}$  to  $H$ , sending  $(Z, P)$  to  $(z, \rho)$  where  $o(\rho) = \frac{1}{2}(n-1)$ . Moreover, we now show that such kernels must give rise to imbeddings of  $K_n$ . Since  $H$  acts transitively on vertices the number of vertices is  $[H : H_v] = [H : \langle \rho \rangle] = n$ , and the number of edges is exactly the order of  $H$ . So we need only check that these maps have neither loops nor multiple edges. As in the regular case, there can be no loops. If there is a multiple edge then all edges are multiple and so  $XY^iXY^j \in M \subseteq \Gamma^{++}$  for some  $i, j \not\equiv 0 \pmod{(n-1)}$  since the valency of the vertices must be  $(n-1)$ , there being  $\frac{1}{2}n(n-1)$  edges and  $n$  vertices. If  $i$  is even then so is  $j$ , in which case  $z^{-1}\rho^{\frac{1}{2}i}z\rho^{\frac{1}{2}j}$  is the identity in  $H$ . Hence  $\rho^{\frac{1}{2}(i+j)} = z^{-1}\rho^{-\frac{1}{2}i}z\rho^{\frac{1}{2}i}$  lies in the commutator subgroup, and thus in the translation subgroup  $T$ , of  $H$  and therefore has order dividing  $|T| = n$ . However,  $\rho$  has order dividing  $(n-1)$  and so  $\rho^{\frac{1}{2}(i+j)} = 1$ . Thus  $\rho^{\frac{1}{2}i}$  commutes with  $z$  and so lies in the centre of  $H$ ; this is the trivial subgroup, so  $\frac{1}{2}i \equiv 0 \pmod{\frac{1}{2}(n-1)}$ , against our hypothesis. If  $i$  is odd then so is  $j$ , in which case  $z^{-1}\rho^{\frac{1}{2}(i-1)}z^{-1}\rho^{\frac{1}{2}(j-1)}$  is the identity in  $H$ . Now  $o(\rho) = \frac{1}{2}(n-1)$  and so  $\rho \notin T$ . Thus  $\rho$  has a fixed point and so, by conjugation, we can assume that  $\rho$  fixes  $0$ . Then  $\rho = s_a^2$  and  $z^{-1} = s_b^2 t_c$  for some  $a, b, c \in Q$ , and so  $z^{-1}\rho^{\frac{1}{2}(i-1)}z^{-1}\rho^{\frac{1}{2}(j-1)} = s_d^2 t_u$  where  $u$  is a non-zero mult-

iple of  $a^{(i-1)}b^{-2} + 1$ , against  $-1 \notin Q^2$ .

Two regular maps are +isomorphic, that is, there is an orientation-preserving isomorphism between them, if and only if they have the same map subgroup. If  $M$  is the kernel of an epimorphism from  $\Gamma^+$  to  $G$ , sending  $(X,Y)$  to  $(x,y)$  where  $o(x)=2$  and  $o(y)=(n-1)$  and  $M'$  is a second such kernel, then  $M=M'$  if and only if  $[x,y] = [x',y']$ , where square brackets denote the equivalence class under group automorphisms. It follows that the equivalence classes under orientation-preserving isomorphisms of regular imbeddings of  $K_n$  are in one-to-one correspondence with the equivalence classes under automorphisms of  $G$  of

$$\Sigma = \{ (x,y) \in G \times G \mid G = \langle x,y \rangle, o(x)=2 \text{ and } o(y)=(n-1) \}.$$

Two type 3 imbeddings with associated map subgroups  $M$  and  $M'$  are +isomorphic if and only if  $M'$  is one of  $\{M, M^Y\}$ . We note that  $Z^{Y^{-1}} = XY^{-1} = Z^{-1}P^{-1}$  and that  $P^{Y^{-1}} = P$ . If  $M$  is the kernel of an epimorphism from  $\Gamma^{++}$  to  $H$ , sending  $(Z,P)$  to  $(z,\rho)$  where  $o(\rho)$  is  $\frac{1}{2}(n-1)$ , and  $M'$  is a second such kernel, then  $M'=M$  if and only if  $[z',\rho'] = [z,\rho]$ , and  $M'=M^Y$  if and only if  $[z',\rho'] = [z^{-1}\rho^{-1}, \rho]$ . Furthermore, the normaliser of  $M$  in  $\Gamma^+$  is strictly larger than  $\Gamma^{++}$  if and only if  $M=M^Y$ . For  $(z,\rho), (z',\rho') \in H \times H$  we define  $[z,\rho], [z',\rho']$  to be Y-paired if and only if  $[z',\rho'] = [z^{-1}\rho^{-1}, \rho]$ . It is easy to see that this is a well-defined symmetric relation. We define a Y-pairing to be proper if it does not self-

pair an equivalence class. It follows that the equivalence classes under orientation-preserving isomorphisms of type 3 imbeddings of  $K_n$  are in one-to-one correspondence with the proper Y-pairs of equivalence classes under automorphisms of  $H$  of

$$\Sigma' = \{ (z, \rho) \in H \times H \mid H = \langle z, \rho \rangle \text{ and } o(\rho) = \frac{1}{2}(n-1) \} .$$

We now classify the equivalence classes under automorphisms of  $G$  of  $\Sigma$  for  $n > 1$ . If  $y \in G$  has order  $(n-1) > 1$  then  $y \notin T$  and so has a fixed point, and so is conjugate by an element of  $T$  to an element of  $G_0$ . Thus if  $(x, y) \in \Sigma$  then  $[x, y] = [s_c t_b, s_a]$  for some  $a, b, c \in Q$ . Now  $t_b$  is conjugate by an element of  $G_0$  to  $t_1$ . Thus  $[x, y] = [s_c t_1, s_a]$ . Moreover,  $o(x) = 2$  and  $o(y) = (n-1)$  if and only if  $c = -1$  and  $a \in \mathcal{P}$ . Let  $x_0 = s_{-1} t_1$ , let  $a \in \mathcal{P}$  and let  $m = 0$  or  $\frac{1}{2}(n-1)$  as  $n$  is even or odd, so that  $a^m = -1$ . Then  $\langle x_0, s_a \rangle$  contains all non-trivial translations

$$t_{a^i} = s_a^{(m-i)} x_0 s_a^i ;$$

thus it contains  $T$  and  $G_0$  which together generate  $G$ , so  $(x, y) \in \Sigma$  if and only if  $[x, y] = [x_0, s_a]$  for some  $a \in \mathcal{P}$ .

Let  $\text{Gal}(F)$  denote the Galois group of  $F$  over its prime field  $F_0 = \text{GF}(p)$ ; then each  $\theta \in \text{Gal}(F)$  induces an automorphism  $\bar{\theta}$  of  $G$ , sending each element  $s_a t_b$  to  $s_{a^\theta} t_{b^\theta}$ . Clearly  $\bar{\theta}$  fixes  $x_0 = s_{-1} t_1$ .

Lemma 4.2. Let  $a, a' \in \mathcal{P}$ . Then  $[x_0, s_a] = [x_0, s_{a'}]$  if and only if  $a$  and  $a'$  are conjugate under  $\text{Gal}(F)$ .

Proof: If  $a' = a^\theta$  for some  $\theta \in \text{Gal}(F)$  then  $\bar{\theta}$  sends  $(x_0, s_a)$  to  $(x_0, s_{a'})$ .

Conversely, suppose that  $\alpha \in \text{Aut}(G)$  fixes  $x_0$  and sends  $s_a$  to  $s_{a'}$ . Since  $a, a' \in \mathcal{P}$  we have  $a' = a^i$  for some  $i$  coprime to  $(n-1)$ . The function  $\theta: F \rightarrow F$ ,  $f \mapsto f^i$ , restricts to an automorphism of the multiplicative group  $F^*$ , taking  $a$  to  $a'$ ; we shall show that  $\theta$  is also an automorphism of the additive group of  $F$ , and hence an element of  $\text{Gal}(F)$ , as required.

We must show that  $(f_1 + f_2)^\theta = f_1^\theta + f_2^\theta$  for all  $f_1, f_2 \in F$ . Since  $0^\theta = 0$ , we can assume that  $f_1, f_2 \neq 0$ . If  $f_1 + f_2 = 0$  then  $(f_1 + f_2)^\theta = 0$  and

$$f_1^\theta + f_2^\theta = f_1^i + f_2^i = f_1^i + (-f_1)^i = f_1^i(1 + (-1)^i) = 0$$

(since if  $i$  is even then so is  $n$ ); hence we can assume that  $f_1 + f_2 \neq 0$ .

For any integers  $j, k, \ell$  consider the word

$$W(g, h) = h^{(m-j)} g h^{(j+m-k)} g h^{(k-\ell)} g h^{(\ell+m)}.$$

We see that  $W(x_0, s_a)$  is a composite translation  $t_b$  where  $b = a^j + a^k - a^\ell$ . Since  $s_{a'} = s_a^i$ , if we replace  $h$  by  $h^i$  and use the fact that  $im \equiv m \pmod{(n-1)}$ , then we see that  $W(x_0, s_{a'}) = t_{b'}$  where  $b' = a^{ij} + a^{ik} - a^{i\ell}$ .

Since  $f_1, f_2, f_1 + f_2 \neq 0$ , we have  $f_1 = a^j$ ,  $f_2 = a^k$  and  $f_1 + f_2 = a^\ell$  for suitable integers  $j, k$  and  $\ell$ ;



in the above notation this gives  $b = 0$ , so that  $W(x_0, s_a)$  is the identity in  $G$  and hence (applying  $\alpha$ ) we have  $W(x_0, s_{a'}) = 1$ . Thus  $b' = 0$ , so  $a^{ij} + a^{ik} = a^{i\ell}$ , that is,  $f_1^\theta + f_2^\theta = (f_1 + f_2)^\theta$ . ■

Let  $\mu$  be the homomorphism from  $G$  to  $F^*$  sending  $s_a t_b$  to  $a$  ( $a \in F^*, b \in F$ ), then

Corollary 4.3. Two pairs  $(x, y), (x', y') \in \Sigma$  are equivalent under  $\text{Aut}(G)$  if and only if  $\mu(y)$  and  $\mu(y')$  are conjugate under  $\text{Gal}(F)$ . ■

Remark. In fact these arguments show that every automorphism of  $G$  is the composition of an inner automorphism and a "field automorphism"  $\bar{\theta}$ ; in other words,  $\text{Aut}(G)$  can be identified with the group  $\text{AFL}(1, F)$  of transformations  $f \mapsto af^\theta + b$  ( $a \in F^*, b \in F, \theta \in \text{Gal}(F)$ ) acting by conjugation on its normal subgroup  $G$ .

If  $n = p^e$  ( $p$  prime) then  $\text{Gal}(F)$  is cyclic of order  $e$ , being generated by the Frobenius automorphism  $f \mapsto f^p$ ; thus  $\text{Gal}(F)$  has  $\phi(n-1)/e$  orbits of size  $e$  on  $P$ , and so

Theorem 4.4. [4] For each prime power  $n = p^e$  there are  $\phi(n-1)/e$  orientation-preserving isomorphism classes of regular imbeddings of  $K_n$ . ■

We now classify the equivalence classes under automorphisms of  $H$  of  $\Sigma'$  for  $n > 3$ . If  $\rho \in H$  has order  $\frac{1}{2}(n-1)$  then  $\rho \notin T$  and so has a fixed point, so is

conjugate by an element of  $T$  to an element of  $H_0$ . Thus if  $(z, \rho) \in \Sigma'$  then  $[z, \rho] = [s_c^2 t_b, s_a^2]$  for some  $a, b, c \in Q$ . Now  $G$  normalises  $H$  and  $t_b$  is conjugate by an element of  $G_0$  to  $t_1$ . Thus  $[z, \rho] = [s_c^2 t_1, s_a^2]$ . Moreover,  $\rho$  has order  $\frac{1}{2}(n-1)$  if and only if  $a^2 \in \rho^2$ . Furthermore, if  $a^2 \in \rho^2$  then  $\langle s_c^2 t_1, s_a^2 \rangle$  contains  $t_1$  and so, since without loss of generality  $a \in \rho$ , contains all non-trivial translations

$$t_{a^i} = (s_a^2)^{-\frac{1}{4}i(n+1)} t_1^{(-1)^i} (s_a^2)^{\frac{1}{4}i(n+1)} ;$$

thus it contains  $T$  and  $H_0$  which together generate  $H$ , so  $(z, \rho) \in \Sigma'$  if and only if  $[z, \rho] = [s_c^2 t_1, s_a^2]$  for some  $a \in \rho, c \in Q$ .

As in the regular case, each  $\theta \in \text{Gal}(F)$  induces an automorphism  $\bar{\theta}$  of  $H$ . Clearly  $\bar{\theta}$  fixes  $t_1$ .

Lemma 4.5. Let  $a, a' \in \rho$  and  $c, c' \in Q$ . Then

$[s_c^2 t_1, s_a^2] = [s_{c'}^2 t_1, s_{a'}^2]$  if and only if  $(c^2, a^2)$  and  $((c')^2, (a')^2)$  are conjugate under  $\text{Gal}(F)$ .

Proof: If  $(a')^2 = (a^2)^\theta$  and  $(c')^2 = (c^2)^\theta$  for some  $\theta$  in  $\text{Gal}(F)$ , then  $\bar{\theta}$  sends  $(s_c^2 t_1, s_a^2)$  to  $(s_{c'}^2 t_1, s_{a'}^2)$ .

Conversely, suppose that  $\alpha \in \text{Aut}(H)$  sends  $(s_c^2 t_1, s_a^2)$  to  $(s_{c'}^2 t_1, s_{a'}^2)$ . Then  $\alpha$  fixes both  $H_0$  and  $T$  (since  $T$  is characteristic in  $H$ ), and so  $\alpha$  fixes  $t_1$ . Since  $a, a' \in \rho$  we have  $a' = a^i$  for some  $i$  coprime to  $(n-1)$ . The function  $\theta: F \rightarrow F, f \mapsto f^i$  restricts to an automorphism of the multiplicative group  $F^*$ , taking  $(c^2, a^2)$  to  $((c')^2, (a')^2)$ ; we shall show that

$\theta$  is also an automorphism of the additive group of  $F$ , and hence an element of  $\text{Gal}(F)$ , as required.

We must show that  $(f_1 + f_2)^\theta = f_1^\theta + f_2^\theta$  for all  $f_1, f_2 \in F$ . As in the regular case, we can assume that  $f_1, f_2, f_1 + f_2$  are all non-zero.

For any integers  $j, k, \ell$  consider the word

$$W(g, h) = h^{\lambda_1} g^{\lambda_2} h^{\lambda_3} g^{\lambda_4} h^{\lambda_5} g^{\lambda_6} h^{\lambda_7},$$

where  $\lambda_1 = -\frac{1}{4}j(n+1)$ ;  $\lambda_2 = (-1)^j$ ;  $\lambda_3 = \frac{1}{4}(j-k)(n+1)$ ;  $\lambda_4 = (-1)^k$ ;  $\lambda_5 = \frac{1}{4}(k-\ell)(n+1)$ ;  $\lambda_6 = (-1)^\ell$ ;  $\lambda_7 = \frac{1}{4}\ell(n+1)$ .

We see that  $W(t_1, s_a^2)$  is a composite translation  $t_b$  where  $b = a^j + a^k - a^\ell$ . Since  $(s_a)^2 = s_a^{2i}$ , if we replace  $h$  by  $h^i$  and use the fact that  $i$  is odd then we see that  $W(t_1, s_a^2) = t_{b'}$  where  $b' = a^{ij} + a^{ik} - a^{i\ell}$ .

Since  $f_1, f_2, f_1 + f_2 \neq 0$  we have  $f_1 = a^j$ ,  $f_2 = a^k$ ,  $f_1 + f_2 = a^\ell$  for suitable integers  $j, k$  and  $\ell$ ; in the above notation this gives  $b = 0$  so that  $W(t_1, s_a^2)$  is the identity in  $H$ , and hence (applying  $\alpha$ ) we have  $W(t_1, s_a^2) = 1$ . Thus  $b' = 0$  so  $a^{ij} + a^{ik} = a^{i\ell}$ , that is,  $f_1^\theta + f_2^\theta = (f_1 + f_2)^\theta$ . ■

Corollary 4.6. Two pairs  $(z, \rho), (z', \rho') \in \Sigma'$  are equivalent under  $\text{Aut}(H)$  if and only if  $(\mu(z), \mu(\rho))$  and  $(\mu(z'), \mu(\rho'))$  are conjugate under  $\text{Gal}(F)$ . ■

Remark. These arguments in fact show that for  $n > 3$   $\text{Aut}(H)$  can also be identified with the group  $\text{AFL}(1, F)$ .

If  $(z, \rho) \in \Sigma'$  then  $[z', \rho'] = [z^{-1}\rho^{-1}, \rho]$ , where

$(z', \rho') \in \Sigma'$ , if and only if  $(\mu(z'), \mu(\rho'))$  and  $(\mu(z)^{-1} \mu(\rho)^{-1}, \mu(\rho))$  are conjugate under  $\text{Gal}(F)$ . Thus  $[z, \rho]$  is self  $Y$ -paired if and only if  $\mu(z)^2 = \mu(\rho)^{-1}$ , which has precisely one solution for  $\mu(z) \in Q^2$ , and so:

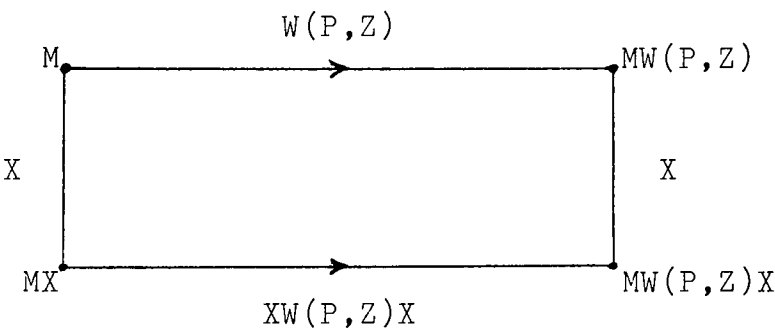
Theorem 4.7. For each prime power  $n = p^e \equiv 3 \pmod{4}$  greater than 3 there are  $\frac{1}{4}(n-3)\phi(n-1)/e$  orientation-preserving isomorphism classes of type 3 imbeddings of  $K_n$ . ■

By identifying  $\Gamma^+/M$  with  $G$  we have the coset graphs of  $M$  in  $\Gamma^+$  corresponding to the regular imbeddings of  $K_n$  with vertices, edges and faces corresponding to orbits of  $\langle Y \rangle$ ,  $\langle X \rangle$  and  $\langle Z \rangle$  respectively, and incidence given by non-empty intersection. This gives an orientable map, which we shall denote by  $\mathcal{M}(x, y)$ , and we have  $\mathcal{M}(x, y) \simeq^+ \mathcal{M}(x', y')$ , that is, there is an orientation-preserving isomorphism between them, if and only if  $\mu(y)$  and  $\mu(y')$  are conjugate under  $\text{Gal}(F)$ . Each  $^+$ isomorphism class contains a map  $\mathcal{M}(x, y)$  with  $x = x_0$  and  $y = s_a$  for some  $a \in \mathcal{P}$ ; if we denote this map by  $\mathcal{M}(a)$  then we have:

Theorem 4.8. The regular imbeddings of  $K_n$  ( $n > 1$ ) are  $^+$ isomorphic to the maps  $\mathcal{M}(a)$  where  $a$  is a primitive element of  $\text{GF}(n)$ . We have  $\mathcal{M}(a) \simeq^+ \mathcal{M}(a')$  if and only if  $a$  and  $a'$  are conjugate under  $\text{Gal}(F)$ . ■

By identifying  $\Gamma^{++}/M$  with  $H$  and by using the automorphism of  $\Gamma^{++}$  induced by conjugation by  $X$ , we can

construct the coset graphs of  $M$  in  $\Gamma^+$  corresponding to the type 3 imbeddings of  $K_n$ , as illustrated below, with vertices, edges and faces corresponding to orbits of  $\langle XZ^{-1} \rangle$ ,  $\langle X \rangle$  and  $\langle Z \rangle$  respectively, and incidence given by non-empty intersection.



This gives an orientable map, which we shall denote by  $\mathcal{M}(\rho, z)$ , and we have  $\mathcal{M}(\rho, z) \simeq^+ \mathcal{M}(\rho', z')$  if and only if  $(\mu(\rho'), \mu(z'))$  is conjugate under  $\text{Gal}(F)$  to either  $(\mu(\rho), \mu(z))$  or  $(\mu(\rho), \mu(z^{-1}\rho^{-1}))$ . Each  $^+$ isomorphism class contains a map  $\mathcal{M}(\rho, z)$  with  $\rho = s_a^2$  and  $z = s_c^2 t_1$  for some  $a \in \mathcal{P}$ ,  $c \in \mathcal{Q}$ ; if we denote this map by  $\mathcal{M}(a, c)$  then we have:

Theorem 4.9. The type 3 imbeddings of  $K_n$  are  $^+$ isomorphic to the maps  $\mathcal{M}(a, c)$  where  $a$  is a primitive element of  $\text{GF}(n)$  and  $c \in \text{GF}(n) \setminus \{0\}$  such that  $c^4 \neq a^{-2}$ . We have  $\mathcal{M}(a, c) \simeq^+ \mathcal{M}(a', c')$  if and only if  $((a')^2, (c')^2)$  is conjugate under  $\text{Gal}(F)$  to either  $(a^2, c^2)$  or  $(a^2, a^{-2}c^{-2})$ . ■

We can give an alternative description of  $\mathcal{M}(a)$  as one of the Cayley maps introduced by Biggs [2] (see also [3]). Let  $g \in G$  be given by

$$g = s_b t_c : f \mapsto bf + c$$

where  $b, c \in F$  and  $b \neq 0$ . Then the coset  $g \langle y \rangle$ , consisting of the elements

$$gy^i : f \mapsto a^i(bf + c),$$

contains a unique translation  $t_{c/b}$  (with  $a^i = b^{-1}$ ), so we label the vertex corresponding to  $g \langle y \rangle$ , via the identification of  $G$  with  $\Gamma^+/M$ , with the element  $v = c/b \in F$ ; this gives a bijection between  $V$  and  $F$ . Now

$$gx : f \mapsto -bf + (1-c)$$

and 
$$gyx : f \mapsto -abf + (1-ac)$$

are associated with vertices labelled  $(1-c)/(-b) = v - b^{-1}$  and  $(1-ac)/(-ab) = v - a^{-1}b^{-1}$  respectively; thus if we put  $a^{-1} = u$  then the vertices adjacent to  $v$  are labelled with the elements of  $F \setminus \{v\} = v + F^*$  in the cyclic order

$$v+1, v+u, v+u^2, \dots, v+u^{(n-2)}$$

corresponding to the orientation around  $v$ . We therefore have:

Theorem 4.10. The regular imbeddings of  $K_n$  ( $n > 1$ ) are  $^+$ isomorphic to the Cayley maps  $\mathcal{M}(F, F^*, r)$  where  $F = GF(n)$  as an additive group, the generating set for  $F$  is  $F^* = F \setminus \{0\}$ , and  $r$  is the cyclic permutation

$$s_u : f \mapsto uf$$

of  $F^*$  for some primitive element  $u$  of  $F$ ; two such maps are  $+$ isomorphic if and only if the corresponding primitive elements are conjugate under  $\text{Gal}(F)$ . ■

We can also give an alternative description of  $\mathcal{M}(a, c)$  as a Cayley map. Let  $h \in H$  be given by

$$h = s_b^2 t_d : f \mapsto b^2 f + d$$

where  $b, d \in F$  and  $b \neq 0$ . Then the coset  $h \langle \rho \rangle$  consisting of the elements

$$h \rho^i : f \mapsto a^{2i} (b^2 f + d)$$

contains a unique translation  $t_{d/b^2}$  (with  $a^{2i} = b^{-2}$ ) so we label the  $\langle Y \rangle$ -orbit of the coset  $h \in \Gamma^{++}/M$  corresponding to  $h$  with the element  $v = d/b^2 \in F$ . This gives a bijection between  $V$  and  $F$ . Now

$$\text{MUX} \langle Y \rangle = \text{MUXY} \langle Y \rangle = \text{MUZ}^{-1} \langle Y \rangle$$

and 
$$\text{MUY}^2 X \langle Y \rangle = \text{MUY}^2 XY \langle Y \rangle = \text{MUY}^2 Z^{-1} \langle Y \rangle .$$

Furthermore, the cosets  $\text{MUZ}^{-1}$ ,  $\text{MUYX}$ ,  $\text{MUY}^2 Z^{-1}$  correspond to the elements

$$\begin{aligned} h_z^{-1} : f &\mapsto c^{-2} b^2 f + c^{-2} (d-1) \\ h_{\rho z} : f &\mapsto c^2 a^2 b^2 f + (c^2 a^2 d + 1) \\ h_{\rho z}^{-1} : f &\mapsto c^{-2} a^2 b^2 f + c^{-2} (a^2 d - 1) \end{aligned}$$

and so have vertices labelled  $(d-1)/b^2 = v - b^{-2}$ ,  $(c^2 a^2 d + 1)/c^2 a^2 b^2 = v + c^{-2} a^{-2} b^{-2}$  and  $(a^2 d - 1)/a^2 b^2 = v - a^{-2} b^{-2}$  respectively. Thus if we let  $u = a^{-1}$  and let

$j$  be such that

$$-a^{-2}c^{-2} = u^j \quad (*)$$

then since

$$\begin{aligned} c^4 = a^{-2} &\Rightarrow u^j = -c^2 = -(\sqrt{a^{-2}} \cap Q^2) = a^{-1} = u \\ &\Rightarrow c^4 = (-a^{-2}u^{-j})^2 = a^{-4}u^{-2} = a^{-2} \end{aligned}$$

we have that  $u^j$  ranges over all odd powers of  $u$  except  $u$  itself as  $c^2$  takes all values in  $Q^2$  except that value for which  $c^4 = a^{-2}$  and the vertices adjacent to  $v$  are labelled with the elements of  $F \setminus \{v\} = v + F^*$  in the cyclic order

$$v-1, v-u^j, v-u^2, v-u^{(j+2)}, v-u^4, v-u^{(j+4)}, \dots, v-u^{(j+n-3)}.$$

Furthermore, if  $((a')^{2\theta}, (c')^{2\theta}) = (a^2, a^{-2}c^{-2})$  where  $a, a' \in P$  and  $c, c' \in Q$  for some  $\theta \in \text{Gal}(F)$  and both

$$-a^{-2}c^{-2} = a^{-j} \quad (1)$$

and  $-(a')^{-2}(c')^{-2} = (a')^{-k} \quad (2)$

then  $a = (a')^\theta$ , and thus (applying  $\theta$  to (2)) we have  $-c^{-2} = a^k$  and so  $j+k \equiv 2 \pmod{(n-1)}$  by (1). We therefore have:

Theorem 4.11. The type 3 imbeddings of  $K_n$  are <sup>+</sup>isomorphic to the Cayley maps  $\mathcal{M}(F, F^*, r)$  where  $F = \text{GF}(n)$  as an additive group, the generating set for  $F$  is  $F^* = F \setminus \{0\}$ , and  $r$  is the permutation of  $F^*$  defined by



$$\begin{aligned} r|_{Q^2} &= s_u^{(2-j)} : f \mapsto u^{(2-j)} f \\ r|_{Q \setminus Q^2} &= s_u^j : f \mapsto u^j f \end{aligned}$$

for some primitive element  $u$  of  $F$  and odd integer  $j : 1 < j < (n-1)$ . Furthermore, if we denote such a map by  $\mathcal{M}(u, j)$  then  $\mathcal{M}(u', k) \simeq^+ \mathcal{M}(u, j)$  if and only if  $u'$  and  $u$  are conjugate under  $\text{Gal}(F)$ , and either  $k \equiv j$  or  $k \equiv (2-j) \pmod{(n-1)}$ . ■

The various regular imbeddings  $\mathcal{M} = \mathcal{M}(a)$  and  $\mathcal{M}' = \mathcal{M}(a')$  of  $K_n$  are related as follows by Wilson's operations. Since  $a, a' \in \mathcal{P}$ , we have  $a' = a^i$  for some  $i$  coprime to  $(n-1)$ , so  $\mathcal{M}'$  is obtained from  $\mathcal{M}$  by using  $y' = s_a^i$  instead of  $y = s_a$  to describe the rotation of edges around each vertex; in other words,  $\mathcal{M}'$  is the map  $H_i(\mathcal{M})$ . Similarly, if  $\mathcal{M}(a, c)$  is a type 3 imbedding of  $K_n$  then  $H_i$  induces the representation

$$\begin{aligned} P &\mapsto P^i \mapsto \rho^i = s_a^{2i} \\ Z = Y^{-1}X &\mapsto P^{\frac{1}{2}(1-i)} Z \mapsto \rho^{\frac{1}{2}(1-i)} Z = s_a^{(1-i)} s_c^2 t_1 \end{aligned}$$

corresponding to the map  $\mathcal{M}(a^i, a^{\frac{1}{2}(1-i)} c)$ ; in other words,  $H_i(\mathcal{M}(u, j)) = \mathcal{M}(u^i, (j-1)/i + 1)$ , by (\*), giving the new rotation

$$\begin{aligned} r'|_{Q^2} &: f \mapsto u^{(i-j+1)} f \\ r'|_{Q \setminus Q^2} &: f \mapsto u^{(i+j-1)} f \end{aligned} \quad .$$

We now consider which of the regular and type 3 imbeddings of  $K_n$  have map subgroup normalisers not contained in  $\Gamma^+$ . In the regular case such imbeddings

would be reflexible, and so, as we have seen, this happens if and only if  $n \leq 4$ . Furthermore, since the only node stabilisers of graphs (i), (ii), or (xii) of Fig. 12 or their images under  $\psi$  to contain  $\Gamma^{++}$  are those of (i), (ii) and (xii) it follows that every map subgroup normaliser of a type 3 imbedding of  $K_n$  is contained in  $\Gamma^+$ . Thus for  $n > 4$  no regular or type 3 imbedding of  $K_n$  is isomorphic to its own mirror image.

We now examine some of the topological features of these imbeddings for  $n \geq 4$ . If  $\mathcal{M}$  is a regular imbedding of  $K_n$  then each face has the same number of sides, namely the order of  $y^{-1}x$  in  $G$ ; this number is  $(n-1)$  unless  $n \equiv 3 \pmod{4}$ , in which case it is  $\frac{1}{2}(n-1)$ , so the number of faces of  $\mathcal{M}$  is  $n$  or  $2n$ , from which it follows that  $\mathcal{M}$  has genus  $\frac{1}{4}(n-1)(n-4)$  or  $\frac{1}{4}(n^2 - 7n + 4)$  respectively (as in [3]). Since none of  $x, y, xy$  are in the commutator subgroup of  $G$  it follows that the length of each Petrie path in  $\mathcal{M}$  is twice the order of the commutator  $x^{-1}y^{-1}xy$  in  $G$ , that is,  $2p$ , whence  $\mathcal{M}^\psi$  has Euler characteristic  $n - \frac{1}{2}n(n-1) + \frac{1}{2}n(n-1)/p$ . For  $n$  odd this is odd and so  $\mathcal{M}^\psi$  is non-orientable. We note that  $r_1 r_0$  acts as a rotation of edges around a face and so for  $n$  even  $(r_1 r_0)^{(n-1)} \in M$ . Then  $(r_1 r_0 r_2)^{(n-1)} \in M^\psi$  and so  $M^\psi \not\leq \Gamma^+$ , whence  $\mathcal{M}^\psi$  is non-orientable. So  $\mathcal{M}^\psi$  is non-orientable of genus  $2 - n + \frac{1}{2}n(n-1)(p-1)/p$ .

If  $\mathcal{M} = \mathcal{M}(u, j)$  is a type 3 imbedding of  $K_n$  then there are two orbits of faces, of sizes  $F_1$  and  $F_2$  say, containing  $M\langle Z \rangle$ , of valency  $\alpha$  say, and  $MX\langle Z \rangle$ ,

of valency  $\beta$  say, respectively. Thus the two faces incident with any of the  $\frac{1}{2}n(n-1)$  edges are in different orbits, and we have  $F_1\alpha = F_2\beta = \frac{1}{2}n(n-1)$ . Now  $\alpha$  is the order of  $z$  in  $H$ , and  $\beta$  is the least positive integer such that  $MXZ^\beta = MX$ , that is, such that  $MXZ^\beta X = M$ . Equivalently,  $M(PZ)^{-\beta} = M$ , whence  $\beta$  is the order of  $\rho z$  in  $H$ . By (\*) we have  $\mathcal{M}(u, j) \simeq^+ \mathcal{M}(a, c)$  where  $a = u^{-1}$  and  $-a^{-2}c^{-2} = a^{-j}$ , that is,  $c^2 = -a^{(j-2)}$ . Whence  $z = s_c^2 t_1 = s_a^{(j-2+\frac{1}{2}(n-1))} t_1$ . Thus if  $2-j \equiv \frac{1}{2}(n-1) \pmod{(n-1)}$  then  $\alpha = p$  else  $\alpha = \frac{1}{2}(n-1)/(n-1, 2-j)$ . Furthermore,  $\rho z = s_a^{(j+\frac{1}{2}(n-1))} t_1$  and so if  $j \equiv \frac{1}{2}(n-1) \pmod{(n-1)}$  then  $\beta = p$  else  $\beta = \frac{1}{2}(n-1)/(n-1, j)$ . From which it follows that  $\mathcal{M}$  has  $F$  faces where if either  $j \equiv \frac{1}{2}(n-1)$  or  $2-j \equiv \frac{1}{2}(n-1) \pmod{(n-1)}$  then  $F = n + \frac{1}{2}n(n-1)/p$  else  $F = n\{(n-1, j) + (n-1, 2-j)\}$ . Thus  $\mathcal{M}$  has genus  $g$  where if either  $j \equiv \frac{1}{2}(n-1)$  or  $2-j \equiv \frac{1}{2}(n-1) \pmod{(n-1)}$  then  $g = \frac{1}{4}(n-1)\{n(p-1) - 4p\}/p$  else  $g = \frac{1}{4}n\{(n-3) - 2(n-1, j) - 2(n-1, 2-j)\} + 1$ .

There is just one orbit of Petrie paths in  $\mathcal{M}$ . Suppose that  $M(X^{-1}Y^{-1}XY)^\gamma X^{-1}Y^{-1} = M$  for some integer  $\gamma$ . Then  $\rho z \in \langle z\rho z \rangle$  whence  $z \in \langle z\rho z \rangle$ , and so  $H \subseteq \langle z\rho z \rangle$ , against  $H$  being non abelian. Whence the length of each Petrie path is  $2\gamma$  where  $\gamma$  is the order of  $z\rho z$  in  $H$ , giving  $\frac{1}{2}n(n-1)/\gamma$  Petrie paths in all. Now  $\mu(z\rho z) = c^4 a^2 = a^{2(j-1)}$  and so  $\mu(z\rho z) \neq 1$ . Whence  $\gamma = (n-1)/(n-1, 2(j-1))$ . It follows that  $\mathcal{M}^\psi$  has Euler characteristic  $\chi$  where  $\chi = n - \frac{1}{2}n(n-1) + \frac{1}{2}n(n-1, 2(j-1))$ , which is odd. Thus  $\mathcal{M}^\psi$  is non-orientable of genus  $\frac{1}{2}n\{(n-3) - (n-1, 2(j-1))\} + 2$ .

It is to be noted that these more obvious topological features do not therefore determine the isomorphism class of the imbedding. We have, however, proved the following:

Theorem 4.12. The orientable non-regular edge-symmetric imbeddings of  $K_n$  in surfaces without boundary are precisely the type 3 imbeddings. ■

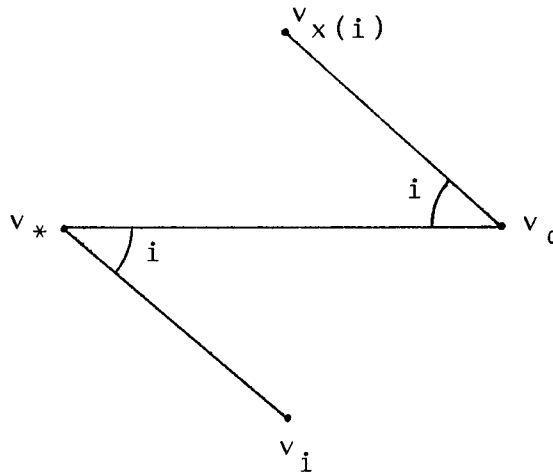
6) We now give a simple algorithm to determine whether two given edge-symmetric imbeddings of  $K_n$  (drawn on polygons in  $\mathbb{R}^2$  with sides identified, for instance) are isomorphic.

We have seen that an edge-symmetric imbedding of  $K_n$  is reflexible if and only if  $n=1, 2, 3, 4$  or  $6$ . Furthermore, the isomorphism class of any reflexible imbedding of  $K_n$  is determined by its Euler characteristic. If we do not have a reflexible imbedding then we may use standard techniques to determine the orientability of the surface (see for example [22] in the case of a polygonal representation), and so, by applying the topological operation  $\psi$  if necessary, we need only determine whether two orientable non-reflexible edge-symmetric imbeddings of  $K_n$  are isomorphic. We may easily determine which such imbeddings are regular (by considering the symmetries induced by  $X$  and  $Y$ , for instance), and so, since the mirror image of a given orientable imbedding is readily obtainable, we need only give algorithms to determine whether two imbeddings of  $K_n$  that are either

both regular or both of type 3 are  $^+$ isomorphic. We now do this.

Given any dart  $(v_*, v_0)$  of a regular imbedding of  $K_n$  the orientation of the map gives a cyclic ordering  $(v_0, v_1, \dots, v_{(n-2)})$  to the vertices adjacent to  $v_*$  and there is a unique map automorphism  $X_{v_*, v_0}$  sending  $(v_*, v_0)$  to  $(v_0, v_*)$  which is a half rotation of the map about the centre of the edge  $\{v_*, v_0\}$  and which induces a permutation  $x_{v_*, v_0}$  of the index set  $\{*, 0, 1, \dots, (n-2)\}$ . By definition  $x_{v_*, v_0} : (*, 0) \mapsto (0, *)$  and its action on  $\{1, \dots, (n-2)\}$  is illustrated by Fig. 18, where  $x_{v_*, v_0}$  has been abbreviated to  $x$ .

Figure 18



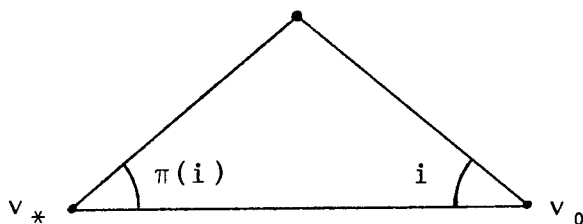
Conversely,  $x_{v_*, v_0}$  completely determines the map, for if  $y$  is the permutation  $y = (0 1 \dots (n-2))^{-1}$  then  $x_{v_*, v_0}$  and  $y$  generate the map automorphism group  $A$  and the kernel of the epimorphism  $\theta : \Gamma^+ \rightarrow A$ ,  $X \mapsto x_{v_*, v_0}$ ,  $Y \mapsto y$  is a map subgroup.

If  $\phi$  is a map  $^+$ isomorphism between two regular

imbeddings  $\mathcal{M}$  and  $\mathcal{M}'$  with distinguished darts  $(v_*, v_0)$  and  $(v'_*, v'_0)$  then for some map<sup>+</sup> automorphism  $\alpha$  we have  $\phi \circ \alpha : (v_*, v_0) \mapsto (v'_*, v'_0)$ . Thus a necessary and sufficient condition for two regular imbeddings  $\mathcal{M}$  and  $\mathcal{M}'$  with distinguished darts  $(v_*, v_0)$  and  $(v'_*, v'_0)$  to be<sup>+</sup> isomorphic is that  $x_{v'_*, v'_0} = x_{v_*, v_0}$ .

If  $\tau$  is the permutation of  $\{1, \dots, (n-2)\}$  that sends  $i$  to  $(n-1-i)$  then we can clearly replace the role of  $x$  in the above condition by  $\pi = \tau \circ x$ . Furthermore, by definition  $\pi_{v_*, v_0} : (*, 0) \mapsto (0, *)$  and by Fig. 19, where  $\pi_{v_*, v_0}$  has been abbreviated to  $\pi$ , the action of  $\pi_{v_*, v_0}$  on  $\{1, \dots, (n-2)\}$  can easily be read off by inspection of any map.

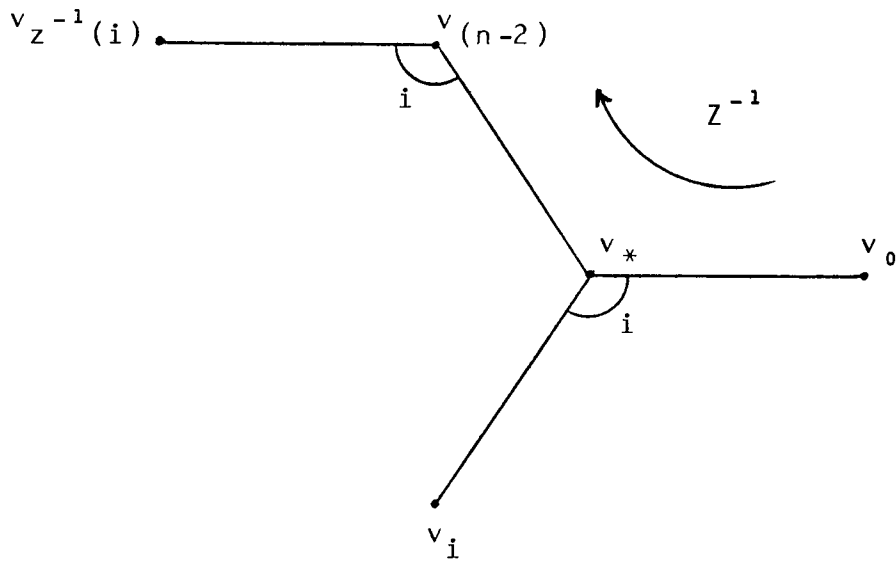
Figure 19



Given any dart  $(v_*, v_0)$  of a type 3 imbedding of  $K_n$  the orientation of the map gives a cyclic ordering  $(v_0 v_1 \dots v_{(n-2)})$  to the vertices adjacent to  $v_*$ , and there is a unique map automorphism  $Z_{v_*, v_0}^{-1}$  that sends  $(v_*, v_0)$  to  $(v_{(n-2)}, v_*)$  which rotates the map about the centre of the face  $(\dots v_0 v_* v_{(n-2)} \dots)$  and which induces a permutation  $z_{v_*, v_0}^{-1}$  of the index set  $\{*, 0, 1, \dots, (n-2)\}$ . By definition  $z_{v_*, v_0}^{-1}$  sends

$(*,0)$  to  $((n-2),*)$  and its effect on  $\{1, \dots, (n-2)\}$  is illustrated by Fig. 20 , where  $z_{v_*, v_0}^{-1}$  is abbreviated to  $z^{-1}$ .

Figure 20



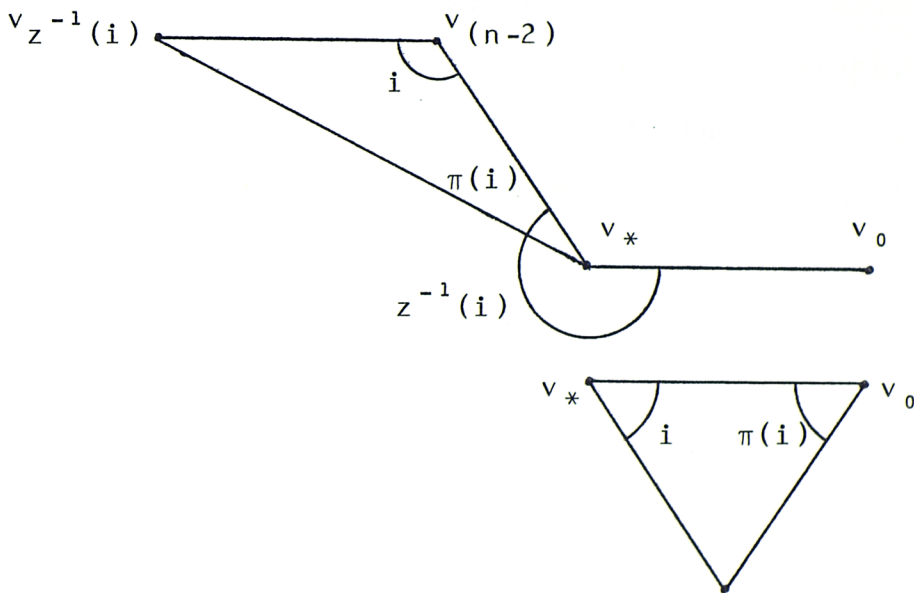
Conversely,  $z_{v_*, v_0}^{-1}$  completely determines the map, for if  $\rho$  is the permutation  $y^2$  then  $z_{v_*, v_0}$  and  $\rho$  generate the map automorphism group  $A$  and the kernel of the epimorphism  $\theta : \Gamma^{++} \rightarrow A$ ,  $Z \mapsto z_{v_*, v_0}$ ,  $P \mapsto \rho$  is a map subgroup.

If  $\phi$  is a map  $^+$ isomorphism between two type 3 imbeddings  $\mathcal{M}$  and  $\mathcal{M}'$  with distinguished darts  $(v_*, v_0)$  and  $(v'_*, v'_0)$  then for some map  $^+$ automorphism  $\alpha$  we have that  $\phi \circ \alpha : (v_\delta(*), v_\delta(0)) \mapsto (v'_*, v'_0)$  where  $\delta$  is some permutation of  $\{*, 0\}$ . Thus a necessary and sufficient condition for two type 3 imbeddings  $\mathcal{M}$  and  $\mathcal{M}'$  with distinguished darts  $(v_*, v_0)$  and  $(v'_*, v'_0)$  to be  $^+$ isomor-

phic is that  $z_{v_*, v_0}^{-1} \in \{z_{v_*, v_0}^{-1}, z_{v_0, v_*}^{-1}\}$ .

We can clearly replace the role of  $z^{-1}$  in the above condition by  $\pi = \tau \circ y^{-1} \circ z^{-1}$ . Furthermore, by definition  $\pi_{v_*, v_0} : (*, 0) \mapsto (0, *)$  and by Fig. 21, where  $z_{v_*, v_0}^{-1}$  and  $\pi_{v_*, v_0}$  have been abbreviated to  $z^{-1}$  and  $\pi$ , the action of  $\pi_{v_*, v_0}$  on  $\{1, \dots, (n-2)\}$  for any distinguished dart  $(v_*, v_0)$  can easily be read off by inspection of any map.

Figure 21



It is not hard to see that this sort of algorithm has more general applications. For example, suppose that  $\mathcal{M}$  and  $\mathcal{M}'$  are regular imbeddings of any simple graph  $\mathcal{G}$  with  $n$  vertices. Then for any distinguished directed edge of  $\mathcal{G}$ , from vertex  $w$  to vertex  $v$  say,  $\Gamma^+$  acts as a group of symmetries of  $\mathcal{M}$  and  $\mathcal{M}'$ :  $X$  rotates the maps about the centre of the edge  $\{v, w\}$  and  $Y$  rotates the



maps about  $v$ , sending  $\{v, w\}$  to the first edge met in a positive direction. Furthermore, there is a subset  $T$  of  $\Gamma^+$  of order  $n$  such that the vertex set of  $G$  is the image set of  $v$  under the action of  $T$  as a set of symmetries of  $\mathcal{M}$ . If the same cannot be said of  $T$  applied as a set of symmetries of  $\mathcal{M}'$  then the two imbeddings are non-isomorphic, else we label both copies of the vertex set by  $T$  in the obvious way. Then  $\mathcal{M}$  and  $\mathcal{M}'$  are isomorphic if and only if the vertex permutations induced by  $X$  and  $Y$  as symmetries of  $\mathcal{M}$  are the same as those induced by  $X$  and  $Y$  as symmetries of  $\mathcal{M}'$ . Of course, in the special case when  $G$  is a complete graph, taking  $T = \{1, X, XY, \dots, XY^{(n-2)}\}$  means that the permutation induced by  $Y$  is independent of the imbedding, and thus the algorithm simplifies considerably.

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