University of Southampton

Towards the Development of an Electoral Count System using Formal Methods

Máiréad Meagher

A thesis submitted in fulfilment for the degree of

Master of Philosophy

in the

Faculty of Engineering and Applied Science

Department of Electronics & Computer Science

November, 2001

UNIVERSITY OF SOUTHAMPTON <u>ABSTRACT</u> FACULTY OF ENGINEERING AND APPLIED SCIENCE ELECTRONICS & COMPUTER SCIENCE <u>Master of Philosophy</u> TOWARDS THE DEVELOPMENT OF AN ELECTORAL COUNT SYSTEM USING FORMAL METHODS by Máiréad Meagher

Techniques which use mathematical principles to develop computer systems are collectively known as Formal Methods. Formal Methods are usually applied to computer systems when correctness and soundness are primarily important.

A system to count votes is an example of such a system. This work includes the specification of, and the full development of part of, such an electoral system. When developing the system, a number of interesting issues arose, the examination of which became a significant part of this work.

The development of a system using formal methods entails taking a specification, written using mathematics and, moving, step by step, towards eventual implementation. We call these steps refinement steps. There are two main kinds of refinement - data refinement where we move from using abstract data in our descriptions to using more concrete data and algorithmic refinement where we introduce programming-like constructs. The traditional strategy is to proceed with data refinement and then with algorithmic refinement. In this thesis a strategy of mixing these approaches is examined, e.g. applying algorithmic refinement first. This strategy is found to be useful and to result in elegant solutions.

A fundamental tenet of refinement is that at each point in the developmental cycle (including the starting specification and the eventual implementation), the user should be unaware of any 'behind the scenes' activity. This means that the interface to the user should not change. However, it may happen that part of the specification is written in terms of parameterised abstract data. Then data refinement will change the interface. This issue is examined in this work and a workaround is provided for checking the correctness of this tricky refinement step.

Two paths of development are used in the work. The first is that of using Z and Morgan's Refinement Calculus. The B Method is then used for the main part of the thesis. The specification of the systems are written in Z and B. The development of parts of each are found in the main body of the text.

Contents

1	Intr	oduct	ion	12
	1.1	Brief I	History of Project	12
	1.2	Relate	ed Work	13
	1.3	Weake	est Precondition	14
	1.4	Refine	ement	15
		1.4.1	Introduction to Refinement	15
		1.4.2	Data Refinement	16
	1.5	Introd	luction to B	17
	1.6	Introd	luction to Z	20
		1.6.1	The Z Specification Notation	20
		1.6.2	Refinement of Z Specifications	21
	1.7	Refine	ment Calculus and The B Method	22
		1.7.1	Morgan's Refinement Calculus	22
		1.7.2	Refinement in The B Method	23
		1.7.3	Differences Between the Two Techniques	24
	1.8	Dot N	otation	25
2	The	Devel	lopment of a Z Specification	26
	2.1	Introd	uction	26
	2.2	Pre-pi	rocessing of Votes	27
		2.2.1	Z Specification of Pre-processing	28
		2.2.2	Approach Taken to Development	29
	2.3	Refine	ment of make_ballot	30
		2.3.1	Data Refinement under Functional Abstraction In-	
			variant	30
		2.3.2	From Z to Specification Statement	30
		2.3.3	From Specification Statement to Code For MakeBallot	33
		2.3.4	Code For Procedure MakeBallot	40
	2.4	Refine	ment of insert	40

		2.4.1	Supporting Definitions	42
		2.4.2	Definition of insert Using Functional Programing	42
		2.4.3	Calculational derivation of pointer algorithms from	
			tree operations	44
		2.4.4	Producing Code from Functional Definition of insert.	45
	2.5	Refine	ment of Pre-processing	48
		2.5.1	From Z to Specification Statement	49
		2.5.2	From Specification Statement to Code for pre-processing	50
	2.6	Moving	g From the Specific to the Generic	51
	2.7	Conclu	isions	52
3	Per	forming	g Algorithmic Refinement before Data Refinement	
	in I	3		54
	3.1	Introdu	uction	54
	3.2	Laws c	of Distribution of Data Refinement	55
	3.3	Examp	bles to Illustrate Laws	56
		3.3.1	Distribution Over Basic Assignment, Using DatRef 1	56
		3.3.2	Distribution Over Generalised Assignment, Using Da-	
			$tRef \ 2 \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots $	56
		3.3.3	Distribution Over Sequence, Using DatRef 3	59
		3.3.4	Distribution Over IF statement, Using $DatRef 4$	59
		3.3.5	Distribution Over the Introduction of a Local Variable	
			using $DatRef 5$	61
		3.3.6	Distribution Over Loop Introduction, Using DatRef 6	62
	3.4	Curren	t Practice with Loop Introduction	64
	3.5	Conclu	sions	64
4	Inte	erface F	Refinement in B	67
	4.1	Introdu	iction	67
	4.2	Operat	ions and Procedures	67
	4.3	Refiner	nent of Procedures in B	69
	4.4	Examp	les of Data Refinement of Procedures	70
		4.4.1	Example 1 - Data Refinement of a Parameter	70
		4.4.2	Example 2 - Data Refinement of a Return Type	71
		4.4.3	Example 3 - Data Refinement of Both Return Type	
			and Parameter	71
	4.5	Workar	ound	72
		4.5.1	Underlying Theory of Workaround	73
		4.5.2	Implementation of Workaround	75
	4.6	Conclus	sions \ldots	76

5	Case Studies in B Development	78
	5.1 Introduction	78
	5.2 Design Issues - B Method and C++'s S.T.L.	78
	5.3 Description of System	80
	5.4 Case Study 1 - Pre–Processing	83
	5.4.1 Development of Make_Ballot	85
	5.4.2 Development of Pre_Process	92
	5.5 Case Study 2 - Setting up First Count	96
	5.6 Conclusions	101
6	Conclusions	105
	6.1 Conclusions	105
	6.2 Future Work	107
\mathbf{A}	Waterford Institute of Technology	
	Academic Council Election	
	Count Rules	110
	A.1 Election Procedures of Academic Members to the Academic	
	Council	110
	A.2 Rules for Academic Council Election (Academic Members)	
	(Abridged Form)	111
	A.3 Rule For Election or Exclusion (RuFEE)	112
	A.3.1 Election \ldots	112
	A.3.2 Exclusion \ldots	112
	A.4 Rules for Academic Council Election (Academic Members) .	113
в	Z Specification of an STV electoral system, specifically	
	Waterford Institute of Technology's Academic Council elec-	100
	tion.	120
	B.1 Introduction	120
	B.2 Global Declarations	121
	B.3 Pre-Processing of Voting Papers	122
	B.3.1 Z Specification of Pre-processing	123
	B.4 Counting of Ballots	124
	B.5 Count Operation	142
\mathbf{C}	Laws used in Refinement Calculus Example	143
D	B Specification of Academic Council count	145
	D.1 Introduction	145

D.2	B Spe	cification	
	D.2.1	Overall Election	
	D.2.2	Global Variables	
	D.2.3	Bags - Paper and Ballot	
	D.2.4	Pre-Processing of Votes	
	D.2.5	Counting Functions	
	D.2.6	Ordering Functions	
	D.2.7	Candidate Balance Functions	
		105	

Bibliography

List of Figures

1.1	Machine M and associated Refinement N	18
2.1 2.2 2.3 2.4	Code for procedure MakeBallotDefinition of InsertGeneric Directed UpdateGeneric Directed Update After First Algorithmic Refinement	$41 \\ 44 \\ 45 \\ 46$
$3.1 \\ 3.2 \\ 3.3$	Data Refinement Laws	57 58
	introduction of loops to be checked using the B-loolkit	60
4.1	Simple Operation Refinement	68
4.2	Operation Refinement with parameter and return value \ldots	68
4.3	Example of refinement of operation with parameter being	
	data refined	71
4.4	Example of refinement of operation with return type being	79
45	Example of refinement of operation with both return type	12
1.0	and parameter being data refined	73
4.6	Structure of Machines for Workaround for Interface Refine-	
	ment The refinement of operation $x \leftarrow first(xseq)$ in MA-	
	CHINE M1, by the operation $y \leftarrow cfirst(yseq)$ in MACHINE	
	M2 can be checked according to the framework above	77
5.1	Mulitset of papers machine	81
5.2	Multiset of ballots machine	82
5.3	Mulitset of ballots machine contd.	83
5.4	Abstract Specification of pre-processing	84
5.5	First Loop Introduction on Make_Ballot	87
5.6	Make_Ballot after the introduction of intermediate variable bb.	88

5.7	Make_Ballot after first data refinement
5.8	Calculating intermediate variable bb
5.9	Data-refined loop for calculating bb
5.10	Algorithmically-refined pre-processing
5.11	Abstract Specification of Setup_First_Count 96
5.12	First Loop Introduction in Setup_First_Count
5.13	First Data Refinement in Setup_First_Count 99
5.14	Second Data Refinement in Setup_First_Count 100
5.15	ConcreteVoteMass Machine
5.16	ConcreteVoteMass Machine contd
5.17	Implementation of Setup_First_Count

Acknowledgements

I would like to take this opportunity to thank my supervisor, Prof. Michael Butler. His generosity, patience, respect and help to me during this time has made working with him a profoundly developmental, rewarding and inspirational experience. He has been truly exceptional.

Thanks are due to the following from W.I.T.: to Paul Barry, Head of Department of P & Q, for his help in timetabling matters, Eric Martin, Head of School of Science, Tony McFeely, Returning Officer of the Academic Council Election Count, and all in Computer Services, for their help in technical matters. Thanks are also due to the Institute Management Committee for their help in facilitating study leave to pursue this study full-time for a short period.

I also acknowledge the help and hospitality I received from members of the DSSE group in the University of Southampton during my trips over there.

Thanks are due to Ib Sorenson of B-Core(UK) Ltd. for his help with the B-Toolkit.

I very much appreciate the help received during this time from Micheál Ó Foghlú, Willie Donnelly, Eamon de Leastar, Michael Brennan, Jimmy McGibney, Richard Lacey, Shane Dempsey, and Gary McManus. Outrageous thanks are due to Kieran Murphy for his 'help' with IAT_EX. (Or, roughly translated, for saving my life.)

My friends have, to my surprise and relief, stuck by me for the last four years. For that and for the various and innumerable kindnesses and support, I thank you all. A special thanks to (not in order of appearance!): Ann Clancy, P.J. Cregg, Claire Keary, Mary Keating, Mary Lyng, Ann Prendergast, Alice McDermott, Eamon Molloy, Laura Murphy, Louis Nevin, Tom O Toole, Ann Prendergast, Richard Vaughan and Cathy Walsh.

My family, as always, have given me support and understanding (and the occasional chance of a 'break' from work!) and many thanks are due to them. To Martin and Philly Meagher, my parents. "Mathematics, rightly viewed, possesses not only truth, but supreme beauty – a beauty cold and austere, like that of sculpture, without appeal to any part of our weaker nature, without the gorgeous trappings of painting or music, yet sublimely pure, and capable of a stern perfection such as only the greatest art can show."

Bertrand Russell

Chapter 1 Introduction

This chapter introduces the reader to the main story of the project contained in this work. Some background information is needed for later chapters, some well-known areas and some conventions used throughout. The areas that are fundamental to this work but well known are briefly dealt with. The discussions are biased towards what we need for this work and as such do not serve as comprehensive guides to these areas. The references given provide such comprehensive coverage.

1.1 Brief History of Project

The plan for this work was based around writing the specification and developing the implementation of the counting system for the Waterford Institute of Technology's Academic Council Election of Academic Members using formal methods. The rules for this election are contained in Appendix A. The plan was to write the specification using Z [30] and develop the implementation using Morgan's Refinement Calculus [23].

The Z specification for this system is presented in Appendix B. An examination of the Z specification will show that the specification relies heavily on the axiomatic-definition style of function specification. The ultimate election count 'operation' (which is the only operation schema in the specification) is specified using calls on the axiomatically defined functions. This style was used as the usual state-based approach of completely separate operation schemas did not suit this type of system. As the development progressed, we found that the Z-specification through Morgan's refinement was not yielding neat solutions. This may have been due to the nature of the original problem (not naturally state-based). This part of the project is

discussed in more detail in Chapter 2.

Because of the inherent difficulties involved, it was decided to switch to the B Method. The B Method incorporates the entire suite of development stages. The re-writing of the Z specification using the B Method was not difficult. The translated specification using the B Method is contained in Appendix D.

When we started looking at the refinement process using the B Method, however, interesting challenges arose. Whereas theoretically it seemed possible and often very desirable to proceed with algorithmic refinement before data refinement, this was not directly supported in the tools available to us. This led to work on the examination of the feasibility and soundness of this seemingly unused approach. This work is reported on in Chapter 3 and in [9].

We adopted the approach of using stateless machines. This meant that the only conduit for data between machines was through operations' parameters and return values. As these operations were originally specified using abstract parameters and return values, the data refinement of these operations led to change of interface of operations. Refinement is interface– preserving in the B Method. This led to a examination of this area and the development of workarounds which is reported in Chapter 4.

We have used parts of the system specified using the B Method and developed them to implementation stage using standard B Method techniques and also the techniques developed during the course of this work. These case studies are presented in Chapter 5.

1.2 Related Work

We look at related work under two headings:

- Specification of voting systems
- Case studies involving data refinement early in the life-cycle.

Specification of voting systems

A voting system is a popular choice for case studies in specification as the rules are already well specified, tried and tested. Proportional Representation (PR) is a system where voters cast their vote 'in order of preference' for a list of candidates, usually in a multi-seat constituency. Single Transferable Vote (STV) is a particular (but usual) variant of PR[11]. Mukherjee

& Wichmann[25] present a full specification of a PR system using STV in VDM[18]. The specification is animated using SML[21] as part of the process of validating the specification. No post–specification development takes place.

Poppleton[26] uses the specification of an STV variant of a PR system, written using Z[30] as a case study to examine functional decomposition in Z. Again, no post-specification development takes place.

Case studies involving data refinement early in the life cycle

We have seen how the relative order of data refinement and algorithmic refinement is an important aspect of this work. This notion is not often discussed. It seems that if practitioners wish to use an order other than data refinement and then algorithmic refinement, (which is the only one directly supported by the B tools(i.e. the B–Toolkit and Atelier–B)) they use the workaround (described in Section 3.4), with the 'layered development' approach as described in Section 1.5.

Fraer presents a case study which looks at the classic Minimum Spanning Tree in [13]. In this case study, both the data structures used in implementation and the algorithm used on them are complex. The algorithm is introduced on the abstract data types to successfully simplify this step. It is implemented using 'layered development', incorporating the workaround approach.

In a case study of a Distributed Load Balancing System[31], Waldén proceeds with some algorithmic refinement before data refinement. The author concludes that the inability to introduce loops at anything but the final stage is restrictive. Again, this problem is solved within the available structures of the B-Toolkit.

In case studies on application of the B-Method to CICS[15], and Railway Signalling Systems[10], the authors use the 'layered design' approach.

In his paper on pointer implementation of tree structures[8], Butler introduces algorithmic refinement before data refinement. The B Method is not used. The resultant technique is used in Chapter 2 of this work.

1.3 Weakest Precondition

Much of the underlying theory used in this work is fundamentally based on the use of Dijkstra's *weakest precondition* [12]. We define what we mean by *weakest precondition* [14]:

Definition 1 wp(S,R) is the set of all states such that execution of S begun in any one of them is guaranteed to terminate in a finite amount of time in a state satisfying R.

So, for example

$$wp('x := x + 1', x < 1) = x < 0$$

We use the notion of *weakest precondition* to define semantics of commands, specifications and even refinement. For commands, for example, if for all postconditions we know which preconditions will guarantee termination satisfying the postcondition, then we say we know the *meaning* or *semantics* of the command.

For example, the semantics of assignment can be defined as follows: For any postcondition $\mathcal A$

$$wp(w := E, \mathcal{A}) \cong \mathcal{A}[w \setminus E]$$

where the formula $\mathcal{A}[w \setminus E]$ can be obtained by replacing in \mathcal{A} all occurrences of w by E.

Semantics of other programming constructs may be found in [23].

1.4 Refinement

In this section, we examine what we mean, intuitively as well as formally, by refinement. As much of the later work deals with data refinement, it is specifically discussed here.

1.4.1 Introduction to Refinement

We deal with systems being developed using Formal Methods. Such systems are originally specified using abstract data types. The eventual implementation will involve concrete data types and algorithms working on these. To get from the abstract specification to the concrete implementation, we repeatedly refine the previous program. Refining a program means making it less abstract whilst preserving the previous refined program's properties. A refined program is observationally indistinguishable from the previous program and is 'at least as good' for the customer. Each successive refinement should move the program towards executability. This is done by

• removing non-determinism

- introducing programming language-like structures (closer to executability)
- replacing abstract data types with concrete data types.

Back & Butler [4] describe refinement as a '...correctness-preserving transformation ... between (possibly abstract, non-executable) programs which is transitive, thus supporting stepwise refinement, and is monotonic with respect to program constructors, thus supporting piecewise refinement'.

We can categorize refinement into two main categories

- Algorithmic refinement
- Data Refinement

Data refinement involves introducing change into the type of data being worked on (introduces concrete data types). Algorithmic refinement involves introducing more concrete programming language-like structures to work on the data, leaving the structure of the data unchanged, e.g. introducing a loop.

More formally, using the theory of weakest pre-condition [12], the following definition of algorithmic refinement holds [23]:

For any commands S and T, we say that S is refined by T, writing $S \sqsubseteq T$, exactly when for all postconditions q we have

$$wp(S,q) \Rightarrow wp(T,q).$$

From this definition, we can see that both a weakening of a pre-condition and a strengthening of post-condition or making a more non-deterministic transition are refinements. A Refinement Calculus based on [23] has been built around the different refinement rules. These rules show how, for example, to correctly introduce algorithmic structure to a specification statement.

1.4.2 Data Refinement

Using the weakest pre-condition theory, we can define what we mean by data refinement [8, 24]. Data refinement involves replacing abstract program variables with concrete program variables, preserving an abstraction relation between them. Let S be a statement with program variables u, a and let T be a statement with variables u, c (a represents the abstract variables that are replaced by the concrete variables c while u represents variables

that are common to both S and T). S is data refined under abstraction relation R, written $S \sqsubseteq_R T$, if the following holds: for all postconditions q not containing c, we have

$$R \wedge wp(S, q) \Rightarrow wp(T, \exists a \bullet R \land q)$$
(1.1)

We also make use of the *least data-refinement* of a statement [32]. Again, let S be a statement with program variables a, and let R be an abstraction relation relating a and c, then the least-refined statement on program variables c which is also a data refinement of S under R is denoted $\mathcal{D}_R^{a,c}[\![S]\!]$. It is the least refined data refinement of S under R. So:

- $S \sqsubseteq_R \mathcal{D}_R^{a,c} \llbracket S \rrbracket$ and
- $S \sqsubseteq_R T$ (T is a data refinement of S)

$$\Rightarrow \mathcal{D}_{R}^{a,c} \llbracket S \rrbracket \sqsubseteq T$$

1.5 Introduction to B

The B Method [1] is a formal method which encompasses the entire lifecycle of the development of a system (theory and tool support). The specification, refinement and implementation phases of the development are represented by sets of Abstract Machines. A machine is an encapsulation of a state (determined by a set of variables) and set of operations. The notation used is Abstract Machine Notation (AMN).

AMN specifies state transitions using generalised substitutions. A generalised substitution is an abstract mathematical programming construct, built up from basic substitutions x := e corresponding to assignments to state variables, via e.g. the following operators:

Operators on Generalised Substitutions	AMN Syntax
$P \mid S$	PRE P THEN S END
@.S	VAR S IN S END
@v.(P ==> S)	ANY v WHERE P THEN S
$S_1; S_2$	$S_1; S_2$ (sequence operator)
$S_1 \mid\mid S_2$	$S_1 \parallel S_2$ (parallel operator)
WHILE E DO S	WHILE E DO S
INVARIANT <i>I</i>	INVARIANT I
VARIANT e	VARIANT e
END	END

MACHINE M	REFINEMENT N
	REFINES M
CONSTANTS f	
PROPERTIES $P(f)$	
VARIABLES u	VARIABLES v
INVARIANT $I(u)$	INVARIANT $J(u, v)$
INITIALISATION $X(u)$	INITIALISATION $Y(u)$
OPERATIONS	OPERATIONS
$Op_i \widehat{=}$	$Op_i \cong$
S;	T;
END	END

Figure 1.1: Machine M and associated Refinement N

Note that the sequence operator $(S_1; S_2)$ is not currently allowed at the specification stage.

Each machine may have an associated REFINEMENT which contains refinements of the operations of the original machine. Each REFINEMENT may, in turn, have an associated REFINEMENT which contains further operation refinement. Eventually a REFINEMENT will have an associated IMPLEMENTATION. This concludes the development process.

The machine M of Fig. 1.1 introduces the (set of) state variables u. There may be a constant relationship between some of these variables. These relationship(s) are contained in the INVARIANT I(u). Each variable must be initialised in the INITIALISATION. These initialisations must not, of course, violate the invariant. The OPERATIONS section contains the specification of the operations of the system, written using AMN.

In this work, we use the CONSTANTS .. PROPERTIES section extensively, due to the style of our specification. Firstly we declare the constants and then give them appropriate properties, e.g. type and further specification. It is used for mathematical functions. e.g.

CONSTANTS double PROPERTIES double $\in \mathbb{N} \to \mathbb{N} \land$ $\forall n.(n \in \mathbb{N} \land double(n) = n * 2)$

Normally, as above, data or state is managed through the manipulation of state variables (u, v). It is, however, possible to have machines with no variables - we call them *stateless* machines. In this case, data is managed through the use of input parameters (*data in*) and return values (*data out*). This is the approach taken in this work.

18

The (set of) state variables v contained in REFINEMENT N in Fig. 1.1 will be linked formally with MACHINE M's set of variables u through the INVARIANT J(u, v).

Operations are refined by introducing v instead of u (data refinement) and by introducing new algorithmic constructs e.g. sequence, alternation (algorithmic refinement). Note that operation refinement is, fundamentally, interface-preserving. This follows from the principle that the user (who has originally specified the operation) should be unaware of any 'behindthe-scenes' refinement activity. From their point of view, they specify an operation with an interface. They expect an implementation of exactly that operation. We have mentioned that we use stateless machines in this work and that this means that we depend on the parameters of and return values from operations to port data. The interfaces to these operations will be specified using abstract data types and the final operations will have interfaces containing data refined concrete data types. We need to have correct refinements between non-interface preserving refinements. This issue is discussed in Chapter 4.

We have discussed the meaning and use of weakest precondition in Section 1.3. When using the B Method, the previously described wp(S, R) is written in the form [S]R.

Refinements must be correct. Using the B Method, when we introduce REFINEMENTs, resulting proof-obligations must be discharged to prove the correctness of the step. The full set of proof-obligations resulting from each introduction is contained in [1]. For instance, one of the main proof obligations for the refinement of operation S from Fig. 1.1 is

$I \wedge J \wedge [S] true \Rightarrow [T] \neg [S] \neg J$ Operation Refinement (1.2)

The Operation Refinement proof-obligation states that for any concrete step of T there is some abstract step of S that establishes the retrieve relation. It is also called the *Sufficient Condition*.

Abrial [1] shows that (1.2) implies (1.1).

Using the B tools, the proof-obligations resulting from a refinement step can be generated. The more trivial of them can be automatically discharged by the tools.

A number of REFINEMENTs are usually necessary before we make the final step of introducing an IMPLEMENTATION. IMPLEMENTATION is a special case of a REFINEMENT, with a few further constraints. The main constraint is that no further refinements can take place. The other main

constraints are to do with independence from other implementations and ensuring that the implementation is concrete. Whereas the introduction of all algorithmic structures is allowed at REFINEMENT stage in the B Method, in practice, no current B tools will allow the introduction of loops before the implementation stage. This seeming anomaly leads us to the work of Chapter 3.

A set of Abstract Machines can be structured using classical techniques, e.g. top-down, by grouping different related parts of the system into different MACHINEs for instance, in the case of the specification. The entire system can be integrated by the use of the INCLUDES, USES, SEES, and IMPORTS clauses. This ability to share other MACHINEs (for example) means that general MACHINEs can be re-used. When using the B Tools, any changes to any of the machines in such a hierarchy will result in the need for the appropriate machines to be re-analysed. Also, when using the B Tools, it is possible to get an overview of the specification and design as presented in a layered horizontal manner [5].

Larger developments are structured using a technique called 'layered development'. The original specification is decomposed into a number of linked subsystem descriptions. The idea is that each subsystem can be refined separately into code, independent of the design choices made in implementing the other subsystems. A subsystem SS1 that makes use of the functionality of another subsystem SS2 only accesses the abstract specification of SS2 and not any of its refinements. Each if the separate refinement sequences are termed subsystem developments. They are the 'layers' in the 'layered system development'.

A full description of the B Method is contained in Abrial [1]. Other useful works are available in [20, 27, 34]

1.6 Introduction to Z

In this work, we are interested in the full formal development of a system. Z [30] is a specification notation. We need to use a separate technique to move towards implementation of the Z specification. In this section, we introduce the Z notation. The alternatives available on how to proceed to refinement are mentioned.

1.6.1 The Z Specification Notation

The formal specification notation, Z, is based on Zermelo-Fraenkel (hence Z) set theory and first-order predicate logic. It was initiated by J.R. Abrial

and developed by the Programming Research Group in Oxford since the 1970's. Z is a method of presenting mathematics in a readable framework. The main Z construct is the *schema* where we draw attention to some things of importance in the system and describe the relationships between elements of that system. For example, if we wish to model a (simple) stock control system, we have

[STOCK] The set of all possible stock items

We have a system state

StockSystem	
$level: STOCK \leftrightarrow \mathbb{N}$	
$carried: \mathbb{P}STOCK$	
$carried = dom \ level$	

The declarations of 'state' variables are above the line. The predicates or 'invariants' of the system are below the line. These describe the relationship between variables that must never be violated. We have operation schemas, which, though syntactically the same as system state schemas, describe the effect of an operation on (imported) systems as defined by their system states.

We may need mathematical functions. To specify these, we use *axiomatic definitions*. Once specified, these functions are globally accessible. For instance, if we wish to specify the *double* function which returns the double of any natural number, we would write it as follows:

$$egin{array}{c} double: \mathbb{N}
ightarrow \mathbb{N} \ \hline orall n: \mathbb{N} ullet \ double(n) = n*2 \end{array}$$

Z is suited to state-based systems. These are systems whose behaviour can be described by the effect of operations on state. If the operations themselves are complex, then the use of mathematical functions, as specified using axiomatic definitions can simplify the operation for the reader. The Z specifications written in Chapter 2 and Appendix B rely heavily on the use of axiomatic definitions.

1.6.2 Refinement of Z Specifications

In his definitive book on Z, [30], Spivey gives an introduction to refinement. A more detailed description of a refinement process applicable to Z specifi-

cations is given by Woodcock & Davies in [33]. Morgan [23] shows how to calculate the program from the specification. His technique (which we refer to as Morgan's Refinement Calculus) is not Z specific but generally useful. King explores the differences between Z and the Refinement Calculus in [19]. In our work (specifically in Chapter 2), we use Morgan's Refinement Calculus to refine systems originally specified using the Z specification notation.

1.7 Refinement Calculus and The B Method

We use two techniques of refinement during this work. These are Morgan's Refinement Calculus and the B Method.

In this section, we briefly describe the two techniques, highlighting the differences between them. We re-visit the topic of their differences in Section 6.1 where we offer some judgements on the relative merits of each approach.

1.7.1 Morgan's Refinement Calculus

A full description of the Refinement Calculus is contained in [23]. What is presented here is a brief description of the technique, concentrating on the strategies involved in the entire life-cycle.

We treat everything as a program, some programs are executable. We repeat refining the program until we reach an executable program.

A program is specified in the form

where

- w is the set of variables whose values may change during program execution
- pre describes the initial state (precondition)
- post describes the final state (postcondition)

The following is a strategy to (starting with a Z specification) choose a refinement path, and derive an implementation.

- 1. Rewrite the Z specification of the operation/function in terms of Morgan's '*program*' (pre, post).
- 2. Introduce more concrete data types. Link abstract and concrete data types using 'retrieve relations'. (This is the data refinement step).
- 3. Attempt to derive a best-guess at a possible, efficient implementation of the operation/function on the concrete data types. This is usually done by guessing a number of possible implementations, and then costing them using techniques as described in, e.g. [2]. Use this to guide the direction of the remainder of our refinement steps. (The advantage of this step is that we now have a structure to aim for and the implementation will be efficient.)
- 4. Restructure (e.g.break up) the program derived in step 2 to guide refinement (according to structure derived in step 3).
- 5. Work on separate '*programs*' until they are executable, using Morgan's Refinement Caclulus [23].

We apply the laws of Refinement Calculus, all of which are contained in [23] and some of which are re-written in Appendix C to the various programs. So, using sequential composition, we break down the program into a number of programs, using top-down design techniques. Each of these programs will be further refined using a separate refinement path by repeatedly applying the laws as 'appropriate'. Note the direction of the effort in this case.

- 1. Choose a law that you think is appropriate.
- 2. Attempt to prove the *proviso* of the rule.
- 3. If the *proviso* has been proven, then the refinement law is applicable and the resulting refinement step is correct.

1.7.2 Refinement in The B Method

We have mentioned that the B Method encompasses the entire lifecycle of system development. So, starting with a specification written using the B Method, we can eventually derive a correct implementation, all within the B Method. A typical strategy of a B development would be as follows:

- 1. Write the original machine which contains the specification, using AMN.
- 2. Guess at an implementation, in the same manner as in the previous section.
- 3. Proceed with refinement, repeatedly making the machine more concrete w.r.t. data and/or algorithmic structure.
- 4. Stop when the machine (now called IMPLEMENTATION) is implementable.

In this case, note the direction of effort. As part of each 'further refinement', the process is :

- 1. Write the refinement based on the previous available machine.
- 2. Attempt to discharge the resulting proof-obligations. If this is possible, then the refinement step is correct.

1.7.3 Differences Between the Two Techniques

Apart from the obvious syntactic differences, the main differences in approach are as follows:

- Direction of Effort: In the case of Z Refinement Calculus, the user must 'guess' which law is applicable, prove the *proviso* and then, if successful, applying the law will result in a correct refinement step. In the case of the B Method, the further refinement is guessed, the resulting proof-obligations are mechanically derived. If these proof-obligations can be discharged, then the refinement is correct.
- Step Sizes: In the extreme case, using the B Method, we could proceed directly from specification to implementation. The resulting proof-obligations could be difficult, but should be possible if the step is a correct refinement. In practice, the steps are chosen to produce more easily discharged proof-obligations. In the case of Morgan's Refinement Calculus, laws are applied one (or in some cases two) at a time.
- **Readability:** In the case of the B Method, the entire 'program' is always together. (During the process, 'chunks' of code may be renamed as operations, but if the operation is appropriately named, the

overall view is still available in one place.) This makes the process clean and readable. When using Morgan's Refinement Calculus, however, the original program, which is usually broken up using sequential composition, takes many separate refinement paths.

1.8 Dot Notation

When using schemas in Z [30], we can access an element of an instance of that schema using the dot notation, e.g.

Coordinate	
$x part : \mathbb{Z}$	
$ypart:\mathbb{Z}$	

If we have *mypoint* : *Coordinate* then we can access *mypoint.xpart* or *mypoint.ypart*.

There is no corresponding notation in the B Method. Using the B Method, if we have *Bcoordinate* == $(\mathbb{Z} \times \mathbb{Z})$ and an instance *bpoint* : *Bcoordinate*.We need functions to return component parts of pairs, for elements of *bpoint*. We have (for instance) two functions. $f_1(bpoint)$ is the xpart of the co-ordinate and $f_2(bpoint)$ is the ypart of the co-ordinate. The definitions of these functions are usually obvious. We introduce (an overloaded) dot notation as syntactic sugar for these functions, so *bpoint.xpart* returns the xpart (or first component) of bpoint, the same as $f_1(bpoint)$ and *bpoint.ypart* returns the ypart (or second component) of *bpoint*, the same as $f_2(bpoint)$. It should be clear from the name of component part (e.g. *xpart*) which component is being accessed. If it is not obvious, it will be clearly stated. We use this syntactic sugar from now on.

Chapter 2

The Development of a Z Specification

2.1 Introduction

In this chapter, we start with a Z specification and formally develop an implementation using Morgan's Refinement Calculus [23] and techniques described in Butler [8]. We produce Pascal–like code.

The sub-system we examine in this chapter is part of the overall system, the counting of votes in an electoral count system. An implementation of a PR system, known as STV, is used [11]. This particular system is based largely on the rules of election for Seanad Éireann [28] and is tailored to count the votes polled to elect the academic elected membership of the Academic Council in Waterford Institute of Technology, Ireland. (Each academic member of staff can vote to elect 13 members from the academic staff). The main modification from the Seanad Éireann rules is the need for gender and school balance in the elected members cohort. The full set of rules as used are available in 'Academic Council Election Rules', Appendix A.

The input to this system is a collection of votes, which are then counted according to our set of rules. The main output of the system is the list of elected candidates. The raw input can contain errors, either accidentally or deliberately introduced by the voter. A decision was taken to specify the counting system based on validated votes (which we call ballots). We therefore need to specify (and implement) this preprocessing of the input. The development of this preprocessing is the subject of this chapter.

2.2 Pre-processing of Votes

At the abstract level, the input is modelled as a sequence of papers where a paper is a partial function from candidate to N and $bag T == T \rightarrow N_1$, where for $b \in bag T$ and $item \in dom(b)$, b(item) returns the number of occurrences of *item* in the bag. This raw input *paper* is processed to become what we term a *ballot*. The operation which deals with this has an abstract specification called *make_ballot*. The preprocessing of the sequence of papers returns a bag of ballots and has an abstract specification of *pre_process*. Not all votes will be valid, so some input will be discarded.

Valid preferences on a paper are that set of preferences that are unique, contiguous and start at one. Duplicate preferences (e.g., two candidates have preference 3 associated with them) are disregarded as are all higher preferences on the paper. A skip in preferences (e.g., the voter expresses preferences 1,2,4,5 but no 3) invalidates all preferences after the skipped preference (in this case, only 1,2 are valid). The ballot holds only valid preferences and uses an injective sequence such that the first element of the sequence is the candidate whose preference was 1, etc. (No other candidate will have been validly assigned preference 1). It may happen that a paper has no valid preferences (e.g., if two candidates are given preference 1), in which case the ballots sequence will be empty. This is termed a spoiled vote and is not added to the (resultant) bag of ballots.

In the specification, the input paper is modelled as a function $Cand \rightarrow \mathbb{N}$ so as to model the physical voting paper as closely as possible. The validated vote (which we call a *ballot*) is modelled as a sequence of *Candidates* in order of the voter's preference. A weight is associated with each *ballot* for counting purposes. At the end of pre-processing the votes, the weight of each *ballot* is 1000. There may be duplicate *ballots*. Obviously, each duplicate is important. What may not be so obvious is that each duplicate *ballot* is dealt with equivalently. It is thus appropriate to model the collection of *ballots* as bags of *ballots* at the end of pre-processing.

The refinement process results in an implementation that takes as input an array of voting papers. The output from the process is a binary search tree where each node contains a *ballot* and the number of times the *ballot* occurs. The binary search tree is used because it is an efficient method of grouping the duplicate ballots.

Our first step is to take the Z specification of the preprocessing of the votes and refine this into specification statements as described in Morgan [23]. Next, we manipulate that specification statement to break it into more manageable statements. Finally, we refine each of the statements using

appropriate techniques.

2.2.1 Z Specification of Pre-processing

We have the following type:

[Candidate] The set of all possible candidates for election.

We also have three global variables:

$no_cands: \mathbb{N}$	The number of candidates nominated for election
	(i.e. the number that appear on the voting paper),
$no_votes: \mathbb{N}$	The number of votes cast,
$no_voters: \mathbb{N}$	The number of eligible voters.

We use the following definitions of Ballot and Paper as follows:

 $Ballot _____ pref : iseq Candidate$ $value : Z ______$ $-1000 \le value \le 1000$

 $Paper == Candidate \rightarrow \mathbb{N}_1$

Note that we are expecting non-zero preferences. Valid preferences on a voting paper start at 1 and are unique, increasing and contiguous. We specify a function which returns the first non-unique, non-contiguous or non-existent preference. This number minus 1 is the number of valid preferences on the voting paper. All preferences between 1 and this number are valid.

$$find_first_hole_or_dup : Paper \rightarrow \mathbb{N}$$

$$find_first_hole_or_dup(paper) =$$

$$min\{n : \mathbb{N} \mid n : 1 \dots no_cands + 1 \land \#paper^{\sim}(\{n\}\}) \neq 1\}$$

The next function takes the voting paper and returns a (valid) Ballot with invalid preferences stripped. This means that, for instance, a spoiled vote will have no valid preferences.

$$\begin{array}{l} make_ballot:Paper \rightarrow Ballot\\ \hline\\make_ballot(paper) =\\ \lhd pref \rightsquigarrow 1 \dots find_first_hole_or_dup(paper) - 1 \lhd paper^{\sim},\\ value \rightsquigarrow 1000 \qquad \triangleright \end{array}$$

28

The following function takes a sequence of voting papers and returns a sequence of Ballots.

$$\frac{makeseqBallots: seq Paper \rightarrow seq Ballot}{makeseqBallots(seqpapers) = map \ make_ballot \ seqpapers}$$

The following function throws away empty ballots. These are invalid papers (or spoiled votes) that were stripped down to empty ballots.

 $\begin{array}{c|c} throwawayempties : seq Ballot \rightarrow seq Ballot\\\hline throwawayempties(fullseq) = \\fullseq \upharpoonright \{b : Ballot \mid b \in ran fullseq \land \#(b.preference) > 0 \bullet b\}\end{array}$

The following function takes in the sequence of voting papers and produces a bag of preprocessed ballots. As a sequence is finite, then items returns a finite bag of Ballots. We call this type *finBagBallot*.

$$\begin{array}{l} pre_process: seq \ Paper \rightarrow finBagBallot\\ \hline\\pre_process(seqpapers) =\\ items(throwawayempties(makeseqBallots(seqpapers))) \end{array}$$

Note that the following definition of map is assumed:

$$map: (X \to Y \times seq X) \to seq Y$$

$$map f s = \{n: 1.. \#s \bullet n \mapsto f(s(n))\}$$

2.2.2 Approach Taken to Development

We examine the problem specification in three parts, using a bottom-up approach.

- 1. make_ballot. The production of a validated *ballot* from an unvalidated *paper*. This is dealt with in Section 2.3.
- 2. **insert**. Insertion of one *ballot* into the binary search tree. We examine this development in Section 2.4.
- 3. pre_process. This part takes the collection of unvalidated *papers*, validates them (using make_ballot) and inserts them (using insert) into the collection of validated *ballots* under certain conditions. We examine this development in Section 2.5

The development of parts 1 and 3 are relatively straightforward using standard techniques. However, in the case of 2, we find that because of the use of a concrete recursive data structure, i.e. binary search trees, it is more appropriate to appeal to functional programming techniques and specifically techniques developed in Butler [8]. These provide the basis for a mechanical approach to refining trees (as defined using recursive functions) to pointer implementations. We examine the three parts separately. We look at the development of part 1 carefully, as an example of standard Morgan's Refinement Calculus. We look at the development of part 2 showing how the Butler technique [8] works. We finally give an overview of the (standard Morgan-type) development of part 3.

The refinement steps which use Morgan's Refinement Calculus [23] reference laws which are included in Appendix C.

2.3 Refinement of make_ballot

2.3.1 Data Refinement under Functional Abstraction Invariant

In this section, we use a special type of data refinement, i.e. where the abstraction invariant is functional. We use the following from from [22]:

The following is always valid where a is the set of abstract variables, c is the set of concrete variables, x the set of common variables and AI is the abstraction invariant:

 $a, x : [pre, post] \sqsubseteq_{AI} c, x : [(\exists a \bullet AI \land pre), (\exists a \bullet AI \land post)]$

Given that AI is functional, this means we can write $AI \equiv a = f(c)$ = 'Using the one point rule'

 $a, x : [a = f(c) \land pre, a = f(c) \land post]$

 \sqsubseteq_{AI} 'If post does not contain any initial variables'

 $c, x : [pre[a \setminus f(c)], post[a \setminus f(c)]]$

We use this law for data refinement where the abstraction invariant is functional. It is called **Law C9** and appears in Appendix C

2.3.2 From Z to Specification Statement

Supporting Definitions

We have used *Paper* and *Ballot* as the abstract models. We now begin to move towards a concrete representation and define two new types, *CPaper*

whose instances will be a concrete representation of *Paper* and *CBallot* whose instances will be a concrete representation of *Ballot*. Note that we use the programming-like structure of a record which we call *rec*.

```
Type CPaper == array [1 .. no\_cands] of

rec

cand:Candidate;

ppref: \mathbb{N};

end;

CBallot == rec

bpref: array[1 .. no\_cands] of Candidate;

value: \mathbb{N};

size: \mathbb{N};

end;
```

Retrieve Relations

The following retrieve relations define the relationship between the abstract(ap) and concrete(cp) Paper and abstract(ab) and concrete(cb) Ballots. cp is an instance of type CPaper and cb is an instance of type CBallot.

$$abs_{p} \stackrel{\widehat{=}}{=} ap = abs(cp) = \{c \mapsto n \mid \exists i : 1 \dots no_cands \bullet cp[i].cand = c \land cp[i].ppref = n\}$$
$$abs_{b} \stackrel{\widehat{=}}{=} ab = abs(cb) = \triangleleft \qquad pref \rightsquigarrow \{n \mapsto cb.pref[n] \mid n \in 1 \dots cb.size\},$$
$$value \rightsquigarrow cb.value \triangleright$$

Calculation of a Specification Statement for make_ballot

We will look at writing a specification statement which refines the *make_ballot* function as specified.

So:

$$ab: [ab = make_ballot(ap)]$$

 \sqsubseteq_R 'Law C9 data refinement (functional)'
 $cb: [abs(cb) = make_ballot(abs(cp))]$

where $R \equiv ap = abs_p(cp) \land ab = abs_b(cb)$ To get to the next step, we wish to strengthen the postcondition, using **Law C8**. If $next_step \Rightarrow abs(cb) = make_ballot(abs(cp))$ then $cb : [abs(cb) = make_ballot(abs(cp))] \sqsubseteq cb : [next_step]$ The technique we use to find a specification statement is to find such a $next_step$. Look at L.H.S. of the equation $abs(cb) = make_ballot((abs(cp)))$

The following implies the equality of L.H.S. and R.H.S.

 $\begin{array}{l} cb.size = HOD \land \\ cb.value = 1000 \land \\ \forall n: 1 \dots cb.size \bullet \exists i: 1 \dots no_cands \bullet \\ cp[i].cand = cb.bpref[n] \land cp[i].ppref = n \end{array}$

This leads to the refinement $cb:[abs(cb) = make_ballot(abs(cp))]$ \Box 'Law C8 strengthen postcondition'

$$\begin{array}{l} cb: [cb.size = \\ min\{no: \mathbb{N} \mid \#\{n \mapsto c \mid \exists i: 1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land n > 0\}(\mid \{no\} \mid) \neq 1\} \\ -1 \land \\ cb.value = 1000 \land \\ \forall n: 1 \dots cb.size \bullet \exists i: 1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land c = cb.bpref[n] \end{array}$$

Note there is no precondition, only postcondition. We introduce a procedure to name this code, called MakeBallot. We will return to this later when all the code has been refined.

 $ab := make_ballot(ap) \sqsubseteq MakeBallot(cb, cp)$ where

 $\begin{array}{l} \textbf{procedure } \textit{MakeBallot}(\textbf{ref } cb:\textit{Ballot}, \textbf{val } cp:\textit{Paper}) \triangleq \\ cb:[cb.size = \\ min\{no:\mathbb{N} \mid \#\{n \mapsto c \mid \exists i:1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land n > 0\}(\mid \{no\} \neq 1\} \\ -1 \land \\ cb.value = 1000 \land \\ \forall n:1 \dots cb.size \bullet \exists i:1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land c = cb.bpref[n] \end{array} \right] \end{array}$

2.3.3 From Specification Statement to Code For MakeBallot

Our first task is to examine the specification statement. A number of intermediate steps are needed for an efficient implementation. We break up the overall program into three smaller programs. An intermediate data structure, b, is used during the stripping of the votes (where duplicates, etc. are 'thrown away'). The first two programs (b:[INIT] and b:[INIT, MID])

deal with the calculation and population of b. The final program, (b:[MID, **END**]) deals with building up the final ballot, cb, from the intermediate b.

b is an array of records. The record contains two fields, *cand* containing a candidate and *no*, containing a number. b[i].cand contains a candidate that appears at preference i in the voting paper (in error, there may be a number of different candidates at this preference). b[i].no contains the number of candidates who have preference i marked against their names. When b is populated from a voting paper, we can strip down to the valid preference by noting that the first b[i].no not equal to 1 is the first non-valid preference. Everything up to this preference is copied into the ballot as valid.

Breaking Down Specification Statement

In this and subsequent sections, we use the following extra notation for w : [pre, post] for clarity, i.e.

$$w: \left[\begin{array}{c} pre \\ post \end{array} \right]$$

Also we label the pre and/or post, for later use, e.g.

$$w: \left[\begin{array}{c} pre \ ({\bf Label 1}) \\ post \ ({\bf Label 2}) \end{array}
ight]$$

Using sequential composition, the original program given in the preceding section is refined to

$$\sqsubseteq$$
 'Law C7 sequential composition'

$$\begin{vmatrix} var \ b \bullet \\ b : \begin{bmatrix} \mathbf{True} \\ b[1].no \dots b[no_cands].no = 0 & (\mathbf{INIT}) \end{bmatrix};$$

$$b: \begin{bmatrix} (INIT) \\ \forall p: 1 \dots no_cands \bullet \exists set indices : \mathbb{PN} \mid \\ set indices = \{n: \mathbb{N} \mid cp[i].ppref = p \land n \in 1 \dots no_cands\} \bullet \\ set indices \neq \emptyset \Rightarrow \\ b[p].no = \#set indices \land \\ \exists i: \mathbb{N} \mid i \in set indices \bullet cp[i].cand = b[p].cand \end{bmatrix};$$

$$cb: \begin{bmatrix} (\mathbf{MID}) \\ cb.size = min\{no: \mathbb{N} \mid \#\{n \mapsto c \mid \exists i: 1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land n > 0\} \\ (\mid \{no\} \mid \neq 1\} - 1 \land \\ cb.value = 1000 \land \qquad (\mathbf{END}) \\ \forall n: 1 \dots cb.size \bullet \exists i: 1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land c = cb.bpref[n] \\ \end{bmatrix} \end{bmatrix}$$

We will take each of the programs in turn, i.e. b:[**True**, **INIT**], b:[**INIT**, **MID**] and cb:[**MID**, **END**]. We look at the refinement of b:[**True**, **INIT**] in detail and give the main structure for the work involved in refining the remaining two programs, i.e. b:[**INIT**, **MID**] and cb:[**MID**, **END**].

Refinement of b:[True, INIT]

$$b: \left[\begin{array}{c} \mathbf{True} \\ b[1].no \dots b[no_cands].no = 0 \quad (\mathbf{INIT}) \end{array} \right]$$

$$\subseteq \mathbf{`Law C7 sequential composition and} \\ \mathbf{Law C4 introduce local variable'} \\ \mid [var k \bullet \\ b, k: [b[1].no \dots b[k-1].no = 0]; \quad (2.1) \\ b, k: [b[1].no \dots b[k-1].no = 0, \\ b[1].no \dots b[k-1].no = 0 \land k = no_cands + 1] \quad (2.2) \\ \mid | \\ (2.1) \subseteq \mathbf{`Law C2 assignment'} \\ k := 1 \\ (2.2) \subseteq \mathbf{`Law C5 iteration} \\ \operatorname{Inv} = b[1].no \dots b[k-1].no = 0, \\ G = k \neq no_cands + 1 \\ \operatorname{Variant} - no_cands + 1 \rightarrow \\ b: [b[1].no \dots b[k-1].no = 0 \land k \neq no_cands, \\ b[1].no \dots b[k-1].no = 0 \land k \neq no_cands, \\ b[1].no \dots b[k-1].no = 0 \land k \neq no_cands, \\ b[1].no \dots b[k-1].no = 0 \land k \neq no_cands, \\ b[1].no \dots b[k-1].no = 0 \land q \\ \end{cases}$$

 $0 \le no_cands + 1 - k < no_cands + 1 - k_0]$ od $\Box \quad `Law C3 \text{ following assignment'}$ $b : [b[1].no .. b[k - 1].no = 0 \land k \ne no_cands + 1,$ $b[1].no .. b[k].no = 0 \land k < k + 1 \le no_cands]; \triangleleft$ k := k + 1 $\Box \quad `As \ k > k + 1 \Rightarrow k > k_0 \Rightarrow 1 \le V < V_0 \text{ '}$ $b : [b[1].no .. b[k - 1].no = 0 \land k \ne no_cands + 1,$ $b[1] .. b[k].no = 0] \triangleleft$ $\Box \quad `Law C1 \text{ assignment'}$ b[k].no := 0

This leads to the following code:

```
| [var k \bullet 
k:= 1; 
do k \neq no_cands +1 \rightarrow 
b[k].no := 0; 
k:= k+1; 
od 
] |
```

Refinement of b:[INIT, MID]

For clarity, b is indexed by 1 to max_pref and cp by 1 to no_cands. These two values are equal as the maximum legal preference is exactly equal to the number of candidates (no 'holes' allowed, i.e. preferences must start at 1 and be contiguous). Thus b:[**INIT**, **MID**] becomes:

 $\begin{array}{c} b: [b[1].no \dots b[max_pref].no = 0, \\ \forall \ p: 1 \dots max_pref \bullet \\ \exists \ set indices = \{si: \mathbb{N} \mid cp[si].ppref = p \land si \in 1 \dots no_cands\} \land \\ b[p].no = \# set indices \land \\ set indices \neq \varnothing \Rightarrow \\ \exists \ i: \mathbb{N} \mid i \in set indices \bullet cp[i].cand = b[p].cand \end{array}$
For clarity, we will name the predicate :

$$\begin{split} P(k) = \forall \ p: 1 \dots max_pref \ | \ k \in 1 \dots no_cands + 1 \bullet \\ \exists \ set indices = \{ si: \mathbb{N} \ | \ cp[si].ppref = p \land si \in 1 \dots k \} \land \\ b[p].no = \# set indices \land \\ set indices \neq \varnothing \Rightarrow \\ \exists \ i: \mathbb{N} \ | \ i \in set indices \bullet cp[i].cand = b[p].cand \end{split}$$

As we will refine this using iteration, with the following Invariant, Guard and Variant:

$$Inv(k) \stackrel{\cong}{=} P(k-1).$$

$$Guard \stackrel{\cong}{=} k \le no_cands$$

$$\neg G = k > no_cands$$

$$(also k \in 1 \dots no_cands+1)$$

$$\Rightarrow \neg G = k = no_cands + 1$$

$$Variant = no_cands + 1 - k$$

└ 'Law C6 leading assignment, followed by Law C5 iteration, followed by Law C3 following assignment '

$$\begin{array}{rcl} \mathbf{MID} & \sqsubseteq & \mid [\textit{ var } k \bullet \\ & k := 1; \\ & \mathbf{do} \ k \le \textit{no_cands} \rightarrow \\ & b : \left[\left| \frac{\textit{Inv}(k) \land G}{\textit{Inv}(k+1)} \right| \right] \triangleleft \\ & k := k+1; \\ & \mathbf{od} \\ & \end{bmatrix} \mid \end{array}$$

Note that there are 2 possibilities for any **k**

1. cp[k].ppref \in 1 .. max_pref (valid preference)

2. cp[k].ppref $\notin 1$.. max_pref (invalid preference)

We apply Law C1 alternation for the next refinement. This leads to the following:

$$\begin{array}{c} \sqsubseteq & \text{`Law C1 alternation on 2 possibilities for k as above'} \\ & \text{if } cp[k].ppref \in 1 \dots max_pref \rightarrow \\ & b: \left[\begin{array}{c} cp[k].ppref \in 1 \dots max_pref \land \\ \hline Inv(k) \\ \hline Inv(k+1) \end{array} \right] \\ & \bigcirc & cp[k].ppref \notin 1 \dots max_pref \rightarrow \\ & b: \left[\begin{array}{c} cp[k].ppref \notin 1 \dots max_pref \land \\ \hline Inv(k) \\ \hline Inv(k) \\ \hline Inv(k+1) \end{array} \right] \\ & \text{fi} \end{array} \end{aligned}$$
 (INVAL)

... \sqsubseteq 'Using standard Refinement Calculus Techniques'

```
\begin{split} \mathbf{if} \ \mathrm{cp}[k].\mathrm{ppref} &\in 1 \dots max\_pref \rightarrow \\ \mathrm{b}[\mathrm{cp}[k].\mathrm{ppref}].\mathrm{no} &:= \mathrm{b}[\mathrm{cp}[k].\mathrm{ppref}].\mathrm{no} + 1; \\ \mathrm{b}[\mathrm{cp}[k].\mathrm{ppref}].\mathrm{cand} &:= \mathrm{cp}[k].\mathrm{cand}; \\ \mathbf{fi} \end{split}
```

(In the case that cp[k].ppref is invalid, (INVAL), the preference is ignored.)

Refinement of cb:[MID, END]

The specification statement is written out, labelling the component parts for ease of use.

$$\begin{split} \mathbf{END} &\equiv cb: [\forall \ p: 1 \dots no_cands + 1 \bullet \\ &\exists \ set indices = \\ &\{si: \mathbb{N} \mid si \in 1 \dots no_cands \land cp[si].ppref = p\} \land \\ &b[p].no = \# set indices \land \\ &b[p].no = \# set indices \land \\ &et indices \neq \varnothing \Rightarrow \\ &\exists \ i: \mathbb{N} \mid i \in set indices \bullet cp[i].cand = b[p].cand, \end{split}$$

$$cb.size = min\{no : \mathbb{N} \mid \\ \#\{n \mapsto c \mid \exists i : 1 \dots no_cands \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land \\ n \in 1 \dots no_cands\} \\ (\mid \{no\} \mid) \neq 1\} - 1 \\ \land \\ \forall n : 1 \dots cb.size \bullet \\ cp[i].cand = c \land cp[i].ppref = n \land c = cb.bpref[n] \\ \land \\ (VALUE) \\ cb.value = 1000]$$

\equiv	'rewrite in terms of components'	
	$cb:[Pre, \mathbf{SIZE} \wedge \mathbf{CAND} \wedge \mathbf{VALUE}]$	
	'sequential composition'	
	$cb: [Pre, Pre \land \mathbf{SIZE}];$	(2.3)
	$cb: [Pre \land \mathbf{SIZE}, \qquad \mathbf{SIZE} \land \mathbf{CAND}];$	(2.4)
	$cb : [SIZE \land CAND, SIZE \land CAND \land VALUE]$	(2.5)

The following refinements are standard but long. We show the results. Take each statement separately:

```
(2.3) \sqsubseteq \ldots \sqsubseteq \ldots \sqsubseteq \ldots| [var k \bullet k:=0; \\ do b[k+1].no = 1 \rightarrow k:=k+1; \\ od; \\ cb.size := k; \\] | (2.4) \sqsubseteq \ldots \sqsubseteq \ldots \sqsubseteq \ldots
```

| [var k •

```
k:=1;

do k \le cb.size \rightarrow

cb.bpref[k] := b[k].cand;

k:= k+1;

od

] |

(2.5) \sqsubseteq

cb.value:= 1000
```

2.3.4 Code For Procedure MakeBallot

Now we can put the component parts of the code in a procedure called MakeBallot as shown in Fig. 2.1. As all instances of k are separate and distinct, we use only one k.

2.4 Refinement of insert

In this section, the operation of inserting an item (a valid *ballot*) into a binary search tree is examined. Each node on the binary search tree needs to hold information of how many duplicate ballots exist, so each node's data part will contain both an information part (containing the ballot information) and a *count* part (holding the number of occurrences of the particular ballot).

In Butler [8], an approach to the derivation of correct algorithms on trees given recursive functions on trees (including insert) is described. This approach is used here. The refinement of insert thus involves two stages. Firstly, the operation insert is defined on a binary search tree (of type *Tree*) using functional programming and recursion techniques, as described in [6] and taking into account the presence of the count (number of copies) part. Importantly, this definition is appropriate for use with [8]. We define the tree structure using recursion. We 'plug-in' the recursive definition according to the technique described in [8], apply the rules and transformations and produce a correct implementation.

```
procedure MakeBallot(ref cb:Ballot; val cp:Paper) \cong
    var k:integer;
    var b: array[1 \dots no\_cands] of
            rec
               no:integer;
               cand: Candidate;
           end;
   \\ Initialisation of intermediate variable b
   k := 1;
   do k \neq no_cands +1 \rightarrow
       b[k].no := 0;
       k := k + 1;
   od
       k := 1;
   \\ Calculating size of valid ballot and transferring to cb.
   do k \leq no_cands \rightarrow
       if cp[k].ppref \in 1 \dots max\_pref \rightarrow
           b[cp[k].ppref].no := b[cp[k].ppref].no + 1;
           b[cp[k].ppref].cand := cp.cand;
       fi;
       k := k+1;
   \mathbf{od}
   k:=0;
   do b[k+1].no = 1 \rightarrow
      k:=k+1;
  od;
  cb.size := k;
  k := 1;
  do k \leq cb.size \rightarrow
          cb.bpref[k] := b[k].cand;
          k := k+1;
  \mathbf{od}
  \setminus Assigning value to weight.
  cb.value := 1000;
```

Figure 2.1: Code for procedure MakeBallot

2.4.1 Supporting Definitions

The type we use for the tree structure in the recursive definition is:

$$BTree \stackrel{\widehat{=}}{=} \epsilon \mid node(Item \times Tree \times Tree)$$

and
$$Item \stackrel{\widehat{=}}{=} Info \times Count$$

Note, we will use the abstraction function bag, bag having the usual meaning. Specifically, when dealing with trees:

$$bag \ \epsilon \ = \ \varnothing \tag{2.6}$$

$$bag(bin((a, b), L, R)) = bag \ L \cup \{a \mapsto b\} \cup bag \ R$$
(2.7)
'doms distinct'

We will move onto an implementation of the tree using the following concrete types Pointer Structures

$$\begin{aligned} \mathbf{Type}\, \textit{TreePtr} &= & \mathrm{POINTER}\,\,\mathrm{TO}\,\,\textit{Node};\\ Data &= & \mathrm{RECORD}\\ & & info:\, CBallot;\\ & & count:\, integer;\\ & & \mathrm{END};\\ Node &= & \mathrm{RECORD}\\ & & root:\, Data;\\ & & Left,\, Right:\, TreePtr;\\ & & \mathrm{END}; \end{aligned}$$

2.4.2 Definition of insert Using Functional Programing

This treatment is based on Bird & Wadler [6]. We define an (insert x t) based on a binary search tree with the usual meanings except that the root information part contains the number of occurrences of the ballot as well as the ballot.

The general definition of insert is

$$bag (insert x t) = bag (t) \uplus \llbracket x \rrbracket$$

and leads to the following: Case t = ϵ

$$bag(insert \ x \ \epsilon) = bag \ \epsilon \uplus \llbracket x \rrbracket$$

= $\emptyset \uplus \llbracket x \rrbracket$
= $\{x \mapsto 1\}$ 'from (2.6)'
= $bag(bin(x, 1), \epsilon, \epsilon)$ 'from (2.7)'
 $\Leftarrow insert \ x \ \epsilon = bin((x, 1), \epsilon, \epsilon)$

Case t $\neq \epsilon$

$$t = node((a, b), L, R)$$

Lemma on \uplus and bags:

 $bag (node((a,b), L, R) \uplus [\![x]\!] = "because of ordering on binary search trees"$

$(bag \ L \uplus \llbracket x \rrbracket \cup \{a \mapsto b\} \cup bag \ R$	x < a
$bag \ L \cup \{a \mapsto b+1\} \cup bag \ R$	x = a
$bag \ L \cup \{a \mapsto b\} \cup (bag \ R \uplus \llbracket x \rrbracket)$	x > a

 $\frac{\text{subcase } x < a}{\text{bag(insert } x \text{ node}(a,b), L, R))}$

$$= bag(node((a, b), L, R)) \uplus [x]$$

$$= `Lemma \uplus'$$

$$(bag L \uplus [x]) \cup \{a \mapsto b\} \cup bag R$$

$$= `Rewrite'$$

$$bag(insert x L) \cup \{a \mapsto b\} \cup bag R$$

$$= `From (2.7)'$$

$$bag (node((a, b), (insert x L), R)$$

$$`Remove bag'$$

$$\Leftarrow insert x node((a, b), L, R) = node((a, b), (insert x L), R)$$

$$insert(x \ \epsilon) = node((x, 1), \epsilon, \epsilon)$$

$$insert(x, node((a, b), L, R)) = \mathbf{if} \ x = a \rightarrow node((a, b + 1), L, R)$$

$$\Box x < a \rightarrow node((a, b), (insert(x \ L), R))$$

$$\Box x > a \rightarrow bode((a, b), L, (insert(x \ R)))$$

$$\mathbf{fi}$$



 $\frac{\text{subcase } x > a}{\text{Proof similar and leads to}}$

$$\Leftarrow insert \ x \ node((a, b), L, R) = node((a, b), L, (insert \ x \ R))$$

 $\underline{subcase \ x = a}$

$$bag(insert \ x \ node((x, b), L, R)) = bag \ (node((x, b), L, R) \uplus \llbracket x \rrbracket)$$

$$= `lemma'$$

$$bag \ L \cup \{x \mapsto b+1\} \cup bag \ R$$

$$= `from \ (2.7)'$$

$$bag(node((x, b+1), L, R))$$

$$= `Remove \ bag'$$

$$\Leftarrow \ insert \ x \ node((x, b), L, R)) = node((x, b+1), L, R)$$

This leads to the definition of insert as shown in Fig. 2.2.

2.4.3 Calculational derivation of pointer algorithms from tree operations

The derivation of correct algorithms involving pointers, especially those originally specified using recursion (e.g. trees) is difficult. A technique has been described in [8] that provides rules that allow recursive functions on trees to be transformed into imperative algorithms on pointers. We call this the 'Butler technique' during this discussion.

Generic Directed Update (UPD):

Where for any t s.t. $Is_Node(t)$, CT(t), CL(t) and CR(t) are mutually exclusive and exhaustive.

Figure 2.3: Generic Directed Update

The approach taken in the paper is as follows: The specification for a generic update on a tree structure is presented. It is shown here as Fig. 2.3. Users of the technique should 'match' the generic terms with the specific terms in the users specific problem. Algorithmic refinement is immediately applied and the generic refinement is presented for the generic update as specified. This refinement is shown here as Fig. 2.4. This is easily rewritten by the user to match the specific problem using the matched terms. A small amount of further refinement is necessary at this point before the introduction of pointers via data refinement. This data refinement is applied through the use of many rules called *pointer-introduction transformations*. These rules are presented based on the generic components of the tree and matching to the specific is again required. Examples of a some transformations are:

As can be seen, application of the transformations is straightforward. From the user's point of view, therefore the only overhead is matching the generic components in the original specification to the specific components of their specific problem. Apart from the extra refinement mentioned directly before the application of data refinement, no further proof is necessary.

2.4.4 Producing Code from Functional Definition of insert

The 'Butler Technique' as described in the previous section is used mechanically in this section to produce code.

Imperative version of Generic Directed Update:

Figure 2.4: Generic Directed Update After First Algorithmic Refinement

We describe the components of the tree as follows:

$$root(node(b, L, R)) \cong b$$
$$left(node(b, L, R)) \cong L$$
$$right(node(b, L, R)) \cong R$$
$$info(x, y) \cong x$$
$$count(x, y) \cong y$$

The recursive definition of insert given in Fig. 2.2 is matched to the generic directed update given in Fig. 2.4 using the following equalities:

$$E1 = node((a, 1), \epsilon, \epsilon)$$

$$CT(t) = a = info(root(t))$$

$$CL(t) = a < info(root(t))$$

$$CR(t) = a > info(root(t))$$

$$E2(node((a, b), L, R)) = node((a, b + 1), L, R)$$

Thus this leads to the following refinement of $\{IsWhole(t_1)\}^1 t_1 := insert(a)$ (t₁), using the above

$$\begin{aligned} & \text{if } t_1 = \epsilon \rightarrow t_1 \coloneqq \text{node}((a,1), \epsilon, \epsilon); \\ & \boxed{ t_1 \neq \epsilon \land a = \inf(\operatorname{root}(t_1) \rightarrow t_1 \coloneqq \text{node}((a,b+1), L, R); \\ & \boxed{ t_1 \neq \epsilon \land a \neq \inf(\operatorname{root}(t_1) \rightarrow t_1 \coloneqq \text{node}((a,b+1), L, R); \\ & \boxed{ t_1 \neq \epsilon \land a \neq \inf(\operatorname{root}(t_1 \land m_1)) \rightarrow t_1 = \epsilon <>; \\ & \text{do } t_1 \land m \neq \epsilon \land a \neq \inf(\operatorname{root}(t_1 \land m_1)) \rightarrow t_1 = t_1 < t_1 < t_1 < t_2 < t_2$$

¹Normally, IsWhole(t_1) will be true when applying this rule. We assume that this is the case.

$$\begin{array}{l} (a < \inf(\operatorname{root}(t_1 \setminus \operatorname{front}(m_1)) \Rightarrow \operatorname{last}(m_1) = \operatorname{left}) \land \\ (a > \inf(\operatorname{root})(t_1 \setminus \operatorname{front}(m_1)) \Rightarrow \operatorname{last}(m_1) = \operatorname{right}) \ \\ \\ \text{if } t_1 \setminus m_1 = \epsilon \to t_1 := t_1[m_1 \setminus \operatorname{node}((a,1), \epsilon, \epsilon)] \\ \\ \hline t_1 \setminus m_1 \neq \epsilon \to \\ \\ \\ \inf((x,y), L, R) := \inf((x,y), L, R)[m \setminus \inf((x, y+1), L, R) / m] \ (2.10) \\ \\ \text{fi }] | \end{array}$$

fi

We need to further examine and refine statements (2.8), (2.9) and (2.10). Then the paths are transformed to pointers, (from [8]) and yields the following code:

```
procedure Insert(val a:CBallot; ref p:TreePtr)
if p = nil \rightarrow new(p); p_1.root, p_1.right, p_1.left := (a,1), nil, nil;
\prod p \neq nil \land a = p_1.root.info \rightarrow p_1.root.count := p_1.root.count+1;
\square p \neq nil \land a \neq p_1.root.info \rightarrow
     || var q_1, r_1 \bullet q_1 := p;
           \mathbf{do} \; q_1 \neq nil \land a \neq q_1 \hat{}.root.info \rightarrow
                if a < q_1.root.info \rightarrow q_1, r_1 := q_1 left, q_1;
               \Box a > q_1.root.info \rightarrow q_1, r_1 := q_1.right, q_1;
                fi
          od
          \mathbf{if} \; q_1 = nil \to
               |||var p_2 \bullet
               new(p); p_2.root, p_2.left, p_2.right:= (a,1), nil, nil;
               if a < r_1.root.info \rightarrow r_1.left, q_1 := p_2, p_2;
               \Box a > r<sub>1</sub><sup>.</sup>root.info \rightarrow r<sub>1</sub><sup>.</sup>right, q<sub>1</sub> := p<sub>2</sub>, p<sub>2</sub>;
               fi
               11
          \prod q_1 \neq nil \rightarrow q_1.root.count := q_1.root.count+1;
          fi
     ]|
fi
```

2.5 Refinement of Pre-processing

In this section, we look at the overall specification of $pre_process$ and refine it using both the work already done on *make_ballot* (see Section 2.3) and *insert* (see Section 2.4). The details of each refinement step are not included as they are standard.

2.5.1 From Z to Specification Statement

Supporting Definitions

The input for the entire *pre_process* (abstract) is *seq Paper* and the concrete version is

```
Type CSeqPapers == rec
papers: array[1 .. no_voters] of CPaper;
no_votes:integer;
end
```

Retrieve Relations

Given that cp is of type CSeqPapers,

$$aseqpapers = abs(cp) = \{i : 1 \dots cp.no_votes \bullet i \mapsto cp.papers[i]\}$$

Given ctree is of type BTree and abag is of type bag Ballot and where $t_1 \otimes t_2$ indicates the tree t_1 is a sub-tree of t_2 or 'is-a-component-of', as described in Morgan [23]:

 $abag = abs(ctree) = \{tl, tr : BTree; root : Data \mid (root, tl, tr) \otimes ctree \bullet root.info \mapsto root.count\}$

Calculation of Specification Statement for pre_process

We examine the specification statement for *pre_process*

 $abag : [abag = pre_process(aseqpapers)]$ \sqsubseteq_{abs} $ctree : [abs(ctree) = pre_process(abs(conarrpapers))]$

We now work on the two sides of the equation above as before. This gives us (eventually, using standard techniques including strengthening post-conditions which allows us the extra variables of no_valid and $no_invalid$)

the specification statement:

2.5.2 From Specification Statement to Code for pre-processing

The Invariant for the main loop of this sub-program is:

 $\begin{array}{l} \forall i:1 \dots k-1 \bullet \\ \exists \ cb: \ CBallot \mid MakeBallot(cb, cp.papers[i]) \bullet \ cb.size > 0 \Rightarrow \\ \exists \ root: \ Info; \ tl, tr: \ BTree \mid (root, tl, tr) \otimes \ ctree \land \\ root.info = \ cb \land \\ root.count = \#\{j:1 \dots k-1; \ jb: \ CBallot \mid \\ MakeBallot(jb, cp.paper[j]) \land jb = \ cb \bullet j\} \land \\ no_valid = \#\{i: \mathbb{N} \mid i \in 1 \dots k-1; \ cb: \ CBallot \mid \\ MakeBallot(cb, cp.papers[i]) \land \ cb.size > 0 \bullet i\} \land \\ no_invalid = \#\{i: \mathbb{N} \mid i \in 1 \dots k-1; \ cb: \ CBallot \mid \\ MakeBallot(cb, cp.papers[i]) \land \ cb.size = 0 \bullet i\} \end{cases}$

with Guard = $k \leq cp.no_votes$. Variant = $cp.no_votes - k - 1$ So program as specified in specification statement above is refined by

```
var k:int;

next_b:CBallot;

k:= 0;

no_valid :=0; no_invalid := 0; tree = nil;

do k \leq cp.no_votes \rightarrow

MakeBallot(next_b, cp.papers[k]);

if next_b.size > 0 \rightarrow

Insert(next_b, tree);
```

```
\begin{array}{l} \text{no\_valid} := \text{no\_valid}{+1};\\ \square \text{ next\_b.size} = 0 \rightarrow\\ \text{no\_invalid} := \text{no\_invalid} + 1;\\ \textbf{fi}\\ k := k{+1};\\ \textbf{od} \end{array}
```

2.6 Moving From the Specific to the Generic

Our examination has been based on a specific problem from our case study. If we abstract its generic pattern, we find that the problem is that of a selective mapping, where we process each of a collection of items and insert the processed item into another collection, if a certain condition p holds for the processed item. We have a generic specification for the problem, where s is the original sequence, f is the function which processes the elements of that sequence, the resultant b is a bag of the processed elements using the selective mapping based on the condition p. n is the number of successfully mapped elements:

 $b := items(map \ f \ s) \upharpoonright p); \quad n := \#b$ This has the generic solution: $\Box \dots \sqsubseteq \dots \sqsubseteq$

```
|[ var x \bullet b := \emptyset; n := 0; 
for i=1.. \# s do 
x := f(s[i]); 
if p(x) then 
b := b # [[x]] || 
n := n+1 
fi 
od |||
```

This is an interesting general problem. Another, possibly more useful approach to this problem would be to prove the general solution and move to the specific. This is seen as further work.

2.7 Conclusions

The work in this Chapter consisted of a thorough development starting with a Z-specification. Not all details are presented as many of the refinements are long but standard. The development was broken down into three parts, as described in Sections 2.3 for processing one vote, 2.4 for inserting one processed vote into the tree and 2.5 calls the above procedures in order to process the entire collection of votes and produce a collection of processed votes. During the development of the insertion into the binary search tree, it was found that Morgan's Refinement Calculus did not fit easily with the insertion. This was at least partly due to the fact that the binary search tree is a recursive data structure. We looked at the use of functional programming techniques [6] and applying the Butler [8] technique to the resultant structures. This was found to be very useful and led to a mechanical type solution.

However, at this relatively early stage in the project, we felt that this paradigm (of Z specification followed by Morgan's Refinement Calculus) had caused us difficulties, for example

- the need to use the non-standard Butler technique as the recursive data type caused difficulties.
- there was no tool support available to help with the refinement route. This is seen as a big disadvantage of this paradigm.
- when proofs were long and complex, it was difficult to keep track of the proofs. The proof illustrated in Section 2.3.3 (that of b:[INIT]) is neither long nor complex, but it is not trivial to keep track of each separate path. Neither is it easy to see the overview of the path even when great care is used to present the material.

It should be noted that an interesting property of the Butler technique is that algorithmic refinement takes place before data refinement. This was seen to be successful and pointed the way for further examination of this strategy in general.

These problems led us to look towards and decide on moving to the B Method for the development of our system. The tool support was a major factor. Also the structure of the B machines means that at any point, the entire operation is viewable, at least at the highest level machine.

The case-studies (on parts of the system) using the B Method and different concrete data structures are presented in Chapter 5.

This chapter, therefore, summarises our work done using Morgan's Refinement Calculus [23] and the Butler technique as described in [8]. It is presented as a valid development.

Chapter 3

Performing Algorithmic Refinement before Data Refinement in B

3.1 Introduction

The standard approach in the development of formal systems is to apply data refinement and then proceed with algorithmic refinement on the concrete data types. In this chapter, we investigate the strategy of introducing algorithmic refinement before data refinement. We present the underlying theory of distribution of data refinement over algorithmic structures. The formal treatment is elucidated by the use of simple examples.

This idea of mixing the relative order of algorithmic refinement and data refinement is not new in formal methods in general. In Chapter 2, we use a technique described in [8] which applies algorithmic refinement before data refinement. Nor is this mixing of relative order new in the B Method in particular. It is indeed part of the theory of the B Method [1]. However, it does not seem to be used (directly) in practice. Neither the B-Toolkit nor Atelier-B at present support this approach directly. (The workaround that is currently used in the B-Toolkit is presented in Section 3.4.)

Our treatment of this approach relies on work [8, 16, 32] which simplifies the data refinement step over algorithmically refined programs by providing rules on the distribution of data refinement.

By implementing the strategy of algorithmic refinement before data refinement in the B Method, we get the benefits of the B Method's tool support coupled with a strategy which, it is felt, makes loop introduction and proving easier.

Much of the work in this chapter is based on work presented in [9].

3.2 Laws of Distribution of Data Refinement

Our approach is to, immediately from specification, introduce algorithmic structures. These algorithmic structures are based on abstract data types. Ensuing data refinement, therefore, will be on algorithmic structures.

We have discussed the idea of least data refinement in Section 1.4.2. $(\mathcal{D}_{R}^{a,c} \llbracket S \rrbracket)$ is the least data refinement of S).

Rules for distributing $\mathcal{D}_R^{a,c}$ through the structure of S may be found in [8, 16, 22, 24, 32]. Some of these rules are repeated in Fig. 3.1, rewritten using the notation of the B Method. The first rule $\mathbf{DatRef 1}$ deals with data refinement of a basic assignment statement. DatRef 2 shows the conditions under which nondeterministic assignments may be data refined. DatRef 3 shows that $\mathcal{D}_R^{a,c}$ distributes through sequential composition. The two rules, **DatRef 4** and **DatRef 6** show that $\mathcal{D}_R^{a,c}$ distributes through if-statements and loops provided the guards are equivalent under the abstraction relation. Note that the abstract B loop will normally have an associated variant and invariant. These will not be explicitly carried forward in later refinements as they are only required when the abstract loop is first introduced in a refinement step. The fifth rule, **DatRef 5** deals with the data refinement of blocks with local variables. Note that a_0, c_0 are global to the statement. a_1, c_1 are local to S. The proof obligation $(\forall a_1, c_1 \bullet R) \iff R$ shows that R deals with global variables (a_0, c_0) only. The final proof obligation, $(@a_1 \bullet S) = S$ states that we expect S to initialise a_1 . Note that Q may involve a_0, c_0 as well as a_1, c_1 , but R does not involve a_1, c_1 , only a_0, c_0 .

We will look at the affect of data refinement on a *procedure* in the next chapter, Chapter 4.

We calculate a data refinement of a statement S under R by calculating a refinement of $\mathcal{D}_{R}^{a,c} \llbracket S \rrbracket$. For example, we wish to data refine (under R) the sequential composition represented by S_1 ; S_2 . Given that $\mathcal{D}_{R}^{a,c} \llbracket S_1 \rrbracket \sqsubseteq S'_1$ and $\mathcal{D}_{R}^{a,c} \llbracket S_2 \rrbracket \sqsubseteq S'_2$, and appealing to the data refinement laws of Fig. 3.1, then:

$$S_1; S_2 \sqsubseteq_R \mathcal{D}_R^{a,c} \llbracket S_1; S_2 \rrbracket \sqsubseteq \mathcal{D}_R^{a,c} \llbracket S_1 \rrbracket; \mathcal{D}_R^{a,c} \llbracket S_2 \rrbracket \sqsubseteq S_1'; S_2'$$

So,

$$S_1; S_2 \sqsubseteq_R S_1'; S_2'$$

Some interesting properties of \sqsubseteq and \sqsubseteq_R are:

3 - Performing Algorithmic Refinement before Data Refinement

- $S \sqsubseteq_R T \land T \sqsubseteq U \Rightarrow S \sqsubseteq_R U$
- $\bullet \ S \ \sqsubseteq \ T \ \land \ T \ \sqsubseteq_R \ U \ \Rightarrow \ S \ \sqsubseteq_R \ U$

3.3 Examples to Illustrate Laws

In this section, we illustrate the Data Refinement Laws as presented in Fig. 3.1, using simple examples.

In the first example, we present the MACHINE and REFINEMENT as they would appear. For the remaining examples, we use segments rather than the entire MACHINE or REFINEMENT.

An interesting part of this work is to examine how the practice of applying algorithmic refinement before data refinement compares with the more usual approach of *vice versa*. Whereas we do not attempt, in this work, to *quantitatively* compare both approaches, we attempt intuition-based comparisons in some of the non-trivial examples. We concentrate, however, in illustrating the laws in this section and draw from work presented in [9] to make the comparisons.

3.3.1 Distribution Over Basic Assignment, Using DatRef 1

Example

If we take a very simple assignment of (common variable) xx to an abstract variable aa. The concrete version of the variable is cc. this is shown in Fig. 3.2.

This refinement is correct according to the Data Refinement Law Da-tRef 1, because

 $aa = 2 * cc \Rightarrow aa = 2 * cc$

3.3.2 Distribution Over Generalised Assignment, Using DatRef 2

Example

We look at an example where we non-deterministically assign a member of a set to a variable. The (data) refined version of the set is a sequence, whose range is equal to the original set. The refined program will involve non-deterministically assigning an index of the sequence to an integer variable. Given a type AType, the following makes up the Abstraction Relation

3 - Performing Algorithmic Refinement before Data Refinement

$$\frac{p \land R \Rightarrow E = F}{\mathcal{D}_R^{a,c} \llbracket \{p\} \ u := E \rrbracket \sqsubseteq u := F} \quad (\text{DatRef 1})$$

$$\frac{R \land Q \land p \Rightarrow (\exists a' \bullet ([a, c := a', c']R) \land P)}{\mathcal{D}_R^{a,c} \llbracket \text{ PRE } p \text{ THEN } @a' \bullet (P \implies a := a') \rrbracket \sqsubseteq @c' \bullet (Q \implies c := c')} \quad \text{(DatRef 2)}$$

 $\mathcal{D}_{R}^{a,c}\llbracket S_{1}; S_{2} \rrbracket \sqsubseteq \mathcal{D}_{R}^{a,c}\llbracket S_{1} \rrbracket; \mathcal{D}_{R}^{a,c}\llbracket S_{2} \rrbracket \qquad \textbf{(DatRef 3)}$

 $\mathcal{D}_{R}^{a,c} \llbracket \mathbf{PRE} \ p \ \mathbf{THEN} \ \mathbf{IF} \ G_{1} \ \mathbf{THEN} \ S_{1}$ $\mathbf{ELSE} \ \mathbf{IF} \ G_{2} \ \mathbf{THEN} \ S_{2} \ \dots$ $\mathbf{ELSE} \ \mathbf{IF} \ G_{n} \ \mathbf{THEN} \ S_{n} \ \mathbf{END} \ \rrbracket$ $\sqsubseteq \ \mathbf{IF} \ H_{1} \ \mathbf{THEN} \ \mathcal{D}_{R}^{a,c} \llbracket \ S_{1} \ \rrbracket \dots$ $\mathbf{ELSE} \ \mathbf{IF} \ H_{n} \ \mathbf{THEN} \ \mathcal{D}_{R}^{a,c} \llbracket \ S_{n} \ \rrbracket \ \mathbf{END}$

$$R \Rightarrow (\exists a_1, c_1 \bullet Q)$$

$$(\forall a_1, c_1 \bullet R) \iff R$$

$$(@a_1 \bullet S) = S$$

$$(DatRef 5)$$

 $\mathcal{D}_{R}^{a_{0},c_{0}}\llbracket \mathbf{VAR} \ a_{1} \ \mathbf{IN} \ S \ \mathbf{END} \ \rrbracket \ \sqsubseteq \ \mathbf{VAR} \ c_{1} \ \mathbf{IN} \ \mathcal{D}_{R \wedge Q}^{(a_{0},a_{1}),(c_{0},c_{1})}\llbracket \ S \ \rrbracket \ \mathbf{END}$

$$p \wedge R \Rightarrow G \Longleftrightarrow H$$

(DatRef 6)

57

 $\mathcal{D}_{R}^{a,c}[\![\text{ PRE } p \text{ THEN WHILE } G \text{ DO } S \text{ END }]\!]$ $\sqsubseteq \text{ WHILE } H \text{ DO } \mathcal{D}_{R}^{a,c}[\![S]\!] \text{ END }$

Figure 3.1: Data Refinement Laws



Figure 3.2: Basic Assignment

R,(between abstract xx, ASet and concrete yy, SS):

 $R \stackrel{\widehat{=}}{=} ASet \in \mathbb{P}Atype \land SS \in seq(Atype) \land$ $xx \in Atype \land yy \in 1..card(Aset) \land$ $ran SS = ASet \land card(ASet) = card(SS) \land$ xx = SS(yy)

The original code is

PRE $ASet \neq \emptyset$ THEN ANY xx' WHERE $xx' \in ASet$ THEN xx := xx'END

According to the Data refinement rule, DatRef 2 if

then the following is a refinement.

ANY
$$yy'$$
 WHERE $yy' \in 1..card(SS)$ **THEN**
 $yy := yy'$
END

This is, indeed the case. $(ASet \neq \emptyset \Rightarrow \exists aa' \bullet aa' \in ASet.$ Also $cc' \in 1..card(SS) \Rightarrow [cc := cc'](cc \in 1..card(SS).)$

3.3.3 Distribution Over Sequence, Using DatRef 3

We look a refinement over sequence. We look at the program

$$\begin{array}{l} \mathbf{BEGIN} \\ yy := aa * bb \\ \mathbf{END} \end{array}$$

 $(yy, aa, bb \in \mathbb{N})$. aa and bb are abstract variables and are related to concrete variables, as usual via an abstraction relation. This abstraction relation could (and often would) lead to complex computation for aa and bb. We therefore split the evaluation of the abstract variables by introducing sequence (we assume the existence of t1 and t2 already, $t1, t2 \in \mathbb{N}$). So, the first, algorithmic refinement is:

BEGIN

$$t1 := aa;$$

 $t2 := bb;$
 $yy := t1 * t2$
END

We introduce the (very simple) abstraction relation, R, as: $aa = 2 * ca \land bb = 3 * cb \land ca \in \mathbb{N} \land cb \in \mathbb{N}$

We can therefore distribute the data refinement across the sequence, using **DatRef3**. Noting that

$$\mathcal{D}_{R}^{(aa,bb),(ca,cb)} \llbracket t1 := aa \rrbracket = t1 := 2 * ca \mathcal{D}_{R}^{(aa,bb),(ca,cb)} \llbracket t2 := bb \rrbracket = t2 := 3 * cb$$

and that t1, t2, yy are common variables, then the data refinement of above is:

BEGIN

$$t1 := 2 * ca;$$

 $t2 := 3 * cb;$
 $y := t1 * t2$
END

3.3.4 Distribution Over IF statement, Using DatRef 4

We look at a simple program which checks if a word is present in a dictionary as part of a spell check program. The abstract data model of the dictionary

is a set of words. We wish to represent this as a sequence of words, ordered in some pre-defined order. So the program should establish the following: $(wrd \in dictset \land ans = TRUE) \lor (wrd \notin dictset \land ans = FALSE)$

The full text of the invariants of both machine and refinement (which makes up R, the abstraction relation) is as follows:

Whereas the fact that the sequence is ordered is the main advantage of this refinement (and we specify this in the usual way), the exact ordering method is not of interest to us here.

We immediately introduce an IF statement which refines the original specification. (The proof is trivial and not included). We then apply data refinement to the IF statement.

Introduce IF statement

PRE
$$wrd \in WORD$$
 THEN
IF $wrd \in dictset$ THEN
 $ans := TRUE$
ELSE
 $ans := FALSE$
END

Apply Data Refinement

IF
$$wrd \in ran \ dictseq \ THEN$$

 $ans := TRUE$
ELSE
 $ans := FALSE$
END

The change is correctness-preserving, because, according to the data refinement law ${\bf DatRef}\;4$

 $wrd \in WORD \land$ $dictset = ran \ dictseq \land$ $dictseq \in Ordered(WORD) \Rightarrow wrd \in dictseq \iff wrd \in ran \ dictseq$ and $\mathcal{D}_{R}^{dictset, dictseq} \llbracket ans := TRUE \rrbracket = ans := TRUE$

The alternative approach is to use the data refinement first, i.e. to the postcondition. This gives us a post-condition of:

 $(s \in ran \ dictseq \land ans = TRUE) \lor (s \notin ran \ dictset \land ans = FALSE)$ When we apply algorithmic refinement to this, i.e. introduce the IF..THEN statement, then we get

IF $s \in ran \ dictseq \ \mathbf{THEN}$ ans := TRUE**ELSE**

ans := FALSE

END

We have achieved the same result in both cases.

3.3.5 Distribution Over the Introduction of a Local Variable using DatRef 5

We look at a simple example of a basic assignment within a local variable block. The original program is as follows:

VAR *aa* IN *aa* :=
$$xx$$
 END

We choose a concrete variable cc, with the retrieve relation, R, being cc = 2 * aa. (Both aa and cc are of type N.) This leads us to a refinement of :

VAR
$$cc$$
 IN $cc := 2 * xx$ **END**

We prove this refinement in two steps, first the outer, VAR statement, using Law DatRef 5 and then the inner statement, using DatRef 2.

Using **DatRef 5**, the outer refinement is correct. R is the invariant on global variables. In our case, xx is the only global variable and invariant, R is True. Q is the invariant on the local variables, i.e. aa and cc, and is $cc = 2 * aa \land cc \in \mathbb{N} \land aa \in \mathbb{N}$. S, the statement to be refined is aa := xx The first proof obligation is therefore:

 $True \Rightarrow (\exists aa, cc \bullet cc = 2 * aa \land aa \in \mathbb{N} \land cc \in \mathbb{N})$

This is easily discharged. The second proof obligation is:

 $\forall aa, xx \bullet R \iff R$

and again is easily discharged. The third proof obligation is written

 $(@aa \bullet aa := xx) = aa := xx.$

This again is trivially proven.

Next, we distribute data refinement over the statement S under R using Law **DatRef 2**. In order to do this, we rewrite the statement S as $@aa' \bullet (aa' = xx \Longrightarrow aa := aa')$. This is refined by $@cc' \bullet (cc' = 2*xx \Longrightarrow cc := cc')$

3 - Performing Algorithmic Refinement before Data Refinement

if the following condition holds (DatRef 2): $cc = 2 * aa \land cc \in \mathbb{N} \land aa \in \mathbb{N} \land cc' = 2 * xx \land True$ $\Rightarrow (\exists aa' \bullet ([aa, cc := aa', cc']cc = 2 * aa) \land aa' = xx$ 'Using One-Point Rule' $\Rightarrow [aa, cc := xx, 2 * xx]cc = 2 * aa$ = TrueThis proves that this is a correct refinement.

3.3.6 Distribution Over Loop Introduction, Using DatRef 6

This is one of the most interesting and rewarding examinations. When we mentioned that B-Toolkit or Atelier-B do not fully support algorithmic refinement followed by data refinement, it should be noted that neither support tool allow loop introduction before the implementation stage. (It follows that no further refinement can be applied). There are workarounds possible, and used. An example of such a workaround is described in Section 3.4.

We look at the approach based on the distribution of data refinement over the loop based on abstract data, as specified in **DatRef 6**.

The example we look at has as an abstract variable a finite partial function (which we use as a bag, i.e. $X \to \mathbb{N}$). We wish to produce another, new bag where each element of the domain is processed in some way. Our first data refinement is to refine the partial function to a sequence of pairs of $(X \times \mathbb{N})$. As usual, we look at the approach of seeing the original machine operation applying the loop introduction, and then applying data refinement. The original program looks like:

 $process \in X \rightarrow Y$

BEGIN

. . .

 $newf := \{xx, nn \mid \exists pp.(pp \in dom ff \land xx = process(pp) \land ff(pp) = nn)\}$ END

We immediately introduce a loop, with invariant:

$$LI \stackrel{\frown}{=} newf = \{xx, nn \mid \exists pp.(pp \in processed \land process(pp) = xx \land ff(pp) = nn) \} \land processed \subseteq dom ff$$

variant $card(dom ff - processed)$

```
\begin{array}{l} \textbf{BEGIN} \\ processed, newf := \varnothing, \varnothing; \\ \textbf{WHILE} \ dom \ ff \ - \ processed \ \neq \ \varnothing \ \textbf{DO} \\ \textbf{VAR} \ pp \ \textbf{IN} \\ pp \ :\in \ dom \ ff \ - \ processed; \\ processed \ := \ processed \ \cup \ \{pp\}; \\ newf \ := \ newf \ \cup \ \{process(pp) \ \mapsto \ ff(pp)\} \\ \textbf{END} \\ \textbf{END} \\ \textbf{END} \\ \textbf{END} \end{array}
```

We will now introduce the data refinement to the loop, and we wish to refine the partial function to a sequence containing the pairs, as in the abstraction relation,

This gives us the following loop:

index,
$$ss := 0, \emptyset$$
;
WHILE index < card(ss) **DO**
VAR rr **IN**
 $rr := ss(index);$
index := index + 1;
 $ss := ss^{process(rr.xx)} \mapsto rr.nn];$
END
END

```
This is a refinement because (using Data Refinement Law)

p \land R \Rightarrow dom ff - processed \iff index < card(ss).

Also

\mathcal{D}_{R}^{(ff,processed),(ss,index)}

VAR pp IN

pp : \in dom ff - processed;

processed := processed \cup \{pp\}

END
```

```
 \sqsubseteq index := index + 1 
and
 \mathcal{D}_{R}^{(ff,processed),(ss,index)} \llbracket 
 \mathbf{VAR} \ pp \ \mathbf{IN} 
 pp : \in dom \ ff - processed; 
 newf := newf \cup \{process(pp) \mapsto ff(pp)\} 
 \mathbf{END} \rrbracket 
 \blacksquare 
 \mathbf{VAR} \ rr \ \mathbf{IN} 
 rr := ss(index); 
 ss := ss^{process(rr.xx)} \mapsto rr.nn] 
 \mathbf{END}
```

3.4 Current Practice with Loop Introduction

We have mentioned that current tools do not allow the early introduction of loops using the above techniques (distributing data refinement through abstract loops). There is however a workaround that is currently used [29]. It involves introducing a loop *early* (as we do throughout this work), as an implementation. This *implementation* is based on abstract types. The loop control and loop body (based on abstract types) are separately (data) refined and eventually implemented. By joining the eventual implementation to the 'original' loop implementation, we have the full, data and algorithmically refined and implemented code. The technique is shown in Fig. 3.3.

Whereas this workaround approach is in line with the 'layered development' strategy used in the B Method, it is felt that it does not result in clear intermediate steps. The loop guard and loop body are so logically associated that to separate them in this way seems excessive.

3.5 Conclusions

The techniques discussed in this chapter allow the introduction of loops early in the refinement cycle using laws of distribution of data refinement as shown in Fig. 3.1 and as presented in [9]. This is a sound and clear approach. Workarounds to this approach are currently used, as discussed in Section 3.4 and such machines can be checked using the B-Toolkit. This is an obvious advantage. Another point to be made about the workaround is



 ${\it 3}$ - Performing Algorithmic Refinement before Data Refinement

Figure 3.3: How to introduce loops early. This framework will allow early introduction of loops to be checked using the B-Toolkit.

3 - Performing Algorithmic Refinement before Data Refinement

that there is no room in this approach for further algorithmically refining a loop. This seems reasonable but may require further thought and work.

The approach we suggest is that of allowing data refinement at any stage during development, using the laws as described in this chapter. This is the first time that these laws have been used in this way. It is a cleaner, more elegant approach

Chapter 4

Interface Refinement in B

4.1 Introduction

Refinements on operations in the B Method are interface-preserving [1]. This is fundamental and sensible. Refining operations whose operations are based on abstract data types is thus not supported using standard techniques. In this chapter, we categorize these operations which need special care. We call these special operations *procedures*. We provide a rule which tells us under which conditions non interface-preserving refinements are valid. A workaround is also provided so that this refinement step can be checked by current B tools. Much of the work in this chapter is based on, and develops, work originally presented in [9].

4.2 Operations and Procedures

In this section, we discuss B Method operations in general, and our special *procedures* in particular.

In the B Method, operations allow us to manipulate the state variables. For each operation, we specify the inputs, outputs and its effect on state variables. For example, we can have a simple operation as shown in Fig. 4.1. In this case, only state variable x is affected by the original operation. The refinement is standard and shown. (The proof is standard, straightforward and not shown.) The interface remains unchanged during refinement. The user can use Assign without knowing that concrete y is used instead of abstract x. This is fundamental. The user should never need to be aware of what is happening behind the interface. The user's only concern is that what is delivered is as least as good for the user as what was specified (including

4 - Interface Refinement in B



Figure 4.1: Simple Operation Refinement



Figure 4.2: Operation Refinement with parameter and return value

Assign).

The B Method supports parameterised operations. We categorise these operations according to nature of the parameters.

The first category of operation is that when both return type and parameters are *common variables*, i.e. they do not need to be data refined during development. A simple example is as shown in Fig. 4.2.

In this case, *ret* and *in* remain unchanged during the refinement step. This refinement is thus fully supported by the B Method. Again, the proof is straightforward and not shown.

The next category of operation is that whose return types and parameters are based on abstract data types. In order to implement these operations, we need to data refine (possibly) both the return types and the parameters. This changes the interface, thus violating a fundamental tenet

of the B Method. The user is now aware of the changes necessary during development. There are many practical cases, however, when it is appropriate to specify such operations. One such case is a system which is specified using stateless machines (machines that have no state variables). Parameters are thus the only available conduit for movement of information. The operations are originally specified using abstract data, but as usual must be implemented using concrete data. A change of interface is thus necessary. This change of interface during development is not currently supported using standard techniques.

For the purposes of this work, we categorise these special operations, call them *procedures* and note that they need special care. We define *procedures* as follows:

Definition 2 Procedures are B operations any of whose parameters or return types are based on data types which will change during refinement, according to Rule **ProcRef**.

The rule which tells us under which circumstances a refinement involving a change of interface is correct, stated as Rule **ProcRef** is presented in Section 4.3. It is useful to establish a structure under which such a non-standard refinement can be written and checked using B tools. This workaround and underlying theory are discussed in Section 4.5.

4.3 Refinement of Procedures in B

The following law shows us under which circumstances data refinement of *procedures* is valid.

$$\begin{array}{cccc} a_{2} & \longleftarrow & Aproc(a_{1}) \stackrel{\cong}{=} A\\ c_{2} & \longleftarrow & Cproc(c_{1}) \stackrel{\cong}{=} C\\ & & \mathcal{D}_{R}^{(a_{1},a_{2}),(c_{1},c_{2})} \llbracket A \rrbracket \sqsubseteq C\\ \hline & & \mathcal{D}_{R'}^{(a_{1}',a_{2}'),(c_{1}',c_{2}')} \llbracket a_{2}' & \longleftarrow & Aproc(a_{1}') \rrbracket \sqsubseteq c_{2}' & \longleftarrow & Cproc(c_{1}') \end{array}$$
(ProcRef)

where a, c are formal parameters, a', c' are actual parameters.

This means that the code of the original *procedure* is data refined according to the laws of distribution of data refinement as detailed in Chapter 3. The interface changes and is specified in terms of the concrete data.

4.4 Examples of Data Refinement of Procedures

We look at three examples, one where only the input parameter is data refined, one where only the output parameter is data refined and finally one where both input and output parameter are data refined. In each case there will be either a gluing invariant between the input parameters, a gluing invariant between the return types, or both, depending on which are being data refined. We show the entire machine when some state is being data refined. In the final example, when we use stateless machine, we simply show the operation and specify the gluing invariants separately for clarity. In all cases, we assume that sets X and Y are available via, e.g. the inclusion of a *Global Data* machine.

4.4.1 Example 1 - Data Refinement of a Parameter

The first example takes an operation which returns the position of an (input) element of a sequence. The abstract sequence, s, is one of X, whereas the concrete sequence, sr, is one of Y. So we need to data refine state variables as well as the parameter. The return type is a common variable. The gluing invariant, I_{IN} is $I_{IN} \in Y \to X \land s = map I_{IN} sr$ and relates the parameters xel and yel. Further specification of this partial function is not of interest to us here. It may, for instance, specify a function that *processes* a member of Y to produce a particular X. This is shown in Fig. 4.3.

In order to be able to thus data refine the procedure $pos \leftarrow showpos(xel)$, we use the data refinement law as written in Section 4.3. We need to show that $\mathcal{D}_R^{xel,yel}[\![pos := s^{\sim}(xel)]\!] \sqsubseteq pos := sr^{\sim}(yel)$ where R is the invariant contained in the machine. According to law **DatRef 1** in Chapter 3, this reduces to showing that $R \Rightarrow s^{\sim}(xel) = sr^{\sim}(yel)$, where R is the invariant of the REFINEMENT. The invariant implicitly includes the specification of I_{IN} , but we add that $I_{IN}(yel) = xel$.

$$s^{\sim}(xel) = sr^{\sim}(yel)$$

$$= \exists n \bullet xel \mapsto n \in s^{\sim} \land$$

$$yel \mapsto n \in sr^{\sim}$$

$$= \exists n \bullet n \mapsto xel \in s \land$$

$$n \mapsto yel \in sr^{\sim}$$

$$\Leftarrow xel = I_{IN}(yel) \land sr = map \ I_{IN} \ s$$

Therefore, the refinement as shown is valid.



Figure 4.3: Example of refinement of operation with parameter being data refined

4.4.2 Example 2 - Data Refinement of a Return Type

In this example, illustrated in Fig. 4.4, the return type is data refined and the parameter is a common variable. It uses the same data as Example 1. In this case, the input to the operation is a position (of the sequence) and the output of the operation is the element of the sequence at that position. In the abstract operation this will be an (abstract) element of type X, whereas the concrete operation will return a (concrete) element of type Y. Again, the elements of the sequences are related by a gluing invariant (in this case I_{OUT}) which is the same as the I_{IN} of the previous example.

As with the first example, we need to show that the law for data refinement of *procedures* is obeyed. The proof is similar to that in **Example 1** and not shown.

4.4.3 Example 3 - Data Refinement of Both Return Type and Parameter

In this example, both the return type and parameter are data refined. This is a simple operation which returns the first element of a sequence, provided that the sequence is non-empty. The operation is contained in a stateless machine. In the case of the abstract operation, the first element of a sequence



Figure 4.4: Example of refinement of operation with return type being data refined

of X's is returned. In the data refined version the first element of the corresponding sequence of Y's is returned. We show the gluing invariants separately. I_{IN} is the gluing invariant for the parameters, i.e. the sequences. I_{OUT} shows the correspondence between the elements of the sequence (again, possibly a *process*ing type of function).

$$I_{IN} \stackrel{\widehat{=}}{=} xseq = map \ abs \ yseq$$
$$I_{OUT} \stackrel{\widehat{=}}{=} abs \ \in \ Y \to X \ \land$$
$$x = abs(y)$$

The operations are shown in Fig. 4.5

The proof obligation (from law in Section 4.3) is easily discharged and not shown.

4.5 Workaround

As we have discussed, when a procedure is refined, its interface changes. The B tools do not at present support this non interface-preserving data refinement. In this section, we look at a technique that allows us to check that the data refined procedure is a correct refinement. The workaround is presented in two sections for clarity. In Section 4.5.1, the underlying


Figure 4.5: Example of refinement of operation with both return type and parameter being data refined

theory of the workaround is shown. It is conceptual and uses the example of one machine's operation being refined by another machine's operation. It is however, not directly usable with current B tools. Section 4.5.2 shows, using a simple example, how to use the ideas presented in 4.5.1 to produce a structure which is usable in current B tools.

4.5.1 Underlying Theory of Workaround

Refinements using the rule for procedures discussed in Section 4.3 can be checked with the B tools by using the following technique. Assume we have

$$a_2 \longleftarrow A \operatorname{proc}(a_1) \cong A$$

and
 $c_2 \longleftarrow C \operatorname{proc}(c_1) \cong C$,

where a_1, c_1 are linked by I_{IN} and a_2, c_2 are linked by I_{OUT} . Approc is an operation of machine M_1 and Cproc is an operation of machine M_2 . We want to check that Cproc is a data refinement of Approc. We cannot do this directly. Instead, we construct machines M'_1 and M'_2 respectively with operations Proc' as follows:

In abstract
$$M'_1$$
:
 $c_2 \longleftarrow Proc'(a_1) \widehat{=}$
VAR a_2 **IN** $a_2 \longleftarrow Aproc(a_1)$; $c_2 : I_{OUT}$ **END**
In concrete M'_2 :
 $c_2 \longleftarrow Proc'(a_1) \widehat{=}$

VAR
$$c_1$$
 IN $c_1 : I_{IN}$; $c_2 \leftarrow Cproc(c_1)$ **END**

73

(Note that we use the new notation c: I whose older form was $c: \in \{c \mid I\}$). Now the two operations have the same interface and the tool can be used to check that the 'concrete' *Proc'* is refined by abstract *Proc'*.

According to the above structure, showing that the abstract Proc' is refined by the concrete Proc' is equivalent to showing that A is data refined by C under $I_{IN} \wedge I_{OUT}$. To prove this, we need to show that $A \sqsubseteq_{I_{OUT} \wedge I_{IN}} C$ is a 'sufficient condition' for

var a_2 in A; $c_2 : I_{OUT}$ end \sqsubseteq var c_1 in $c_1 : I_{IN}$; C end

Structure of Proof: The proof is shown at two levels. Firstly, the overall structure is shown. One of the steps, which is justified using different techniques (i.e. including weakest precondition calculus) is fully developed separately. Note that when quantifying over all q's during the proof, q is independent of a_1 and $a_2(a_1)$ is input only, and a_2 is a local variable).

var a_2 in A; $c_2 : I_{OUT}$ end \sqsubseteq 'body of var is independent of c_1 ' var a_2, c_1 in A; $c_2 : I_{OUT}$ end \sqsubseteq 'strengthen initialisation' var $a_2, c_1 \mid I_{IN} \land I_{OUT}$ in A; $c_2 : I_{OUT}$ end \sqsubseteq 'assertion can be introduced because of initialisation condition' var $a_2, c_1 \mid I_{IN} \land I_{OUT}$ in $\{I_{IN} \land I_{OUT}\}$; A; $c_2 : I_{OUT}$ end \sqsubseteq 'step ξ ' var $a_2, c_1 \mid I_{IN} \land I_{OUT}$ in C end \sqsubseteq 'C independent of a_2, I_{OUT} independent of c_1 ' var c_1 in $c_1 : I_{IN}$; C end

Next, we look at 'step ξ ' by using wp calculus and the usual definition of $S \subseteq T$ precisely when $wp(S, q) \Rightarrow wp(T, q)$ over all q. Below, assume universal quantification over q:

$$\begin{split} & wp(\mathbf{var} \ a_2, c_1 \mid I_{IN} \land I_{OUT} \ in \ \{I_{IN} \land I_{OUT}\}; \ A; \ c_2 : I_{OUT} \ \mathbf{end}, q) \\ &= `wp \ calculus - \ local \ var' \\ &\forall \ a_2, \ c_1 \mid I_{IN} \land I_{OUT} \bullet wp(\{I_{IN} \land I_{OUT}\}; \ A; \ c_2 : I_{OUT}, q) \\ &= `wp \ calculus - \ sequence' \\ &\forall \ a_2, \ c_1 \mid I_{IN} \land I_{OUT} \bullet wp(\{I_{IN} \land I_{OUT}\}, wp(A, \forall \ c_2 : I_{OUT} \Rightarrow q)) \\ &= `wp \ calculus - \ assertion' \\ &\forall \ a_2, \ c_1 \mid I_{IN} \land I_{OUT} \bullet (I_{IN} \land I_{OUT} \land wp(A, \forall \ c_2 : I_{OUT} \Rightarrow q)) \\ &\Rightarrow \ `since \ A \ \sqsubseteq_{I_{IN} \land I_{OUT}} \ C' \end{split}$$

 $\forall a_2, c_1 \mid I_{IN} \land I_{OUT} \bullet wp(C, \exists a_1, a_2 \bullet I_{IN} \land I_{OUT} \land \forall c_2 : I_{OUT} \bullet \Rightarrow q)$ $\Rightarrow `pred calculus and monotonicity'$ $<math display="block"> \forall a_2, c_1 \mid I_{IN} \land I_{OUT} \bullet wp(C, \exists a_1, a_2 \bullet q)$ $= `a_1, a_2 not in postcondition'$ $<math display="block"> \forall a_2, c_1 \mid I_{IN} \land I_{OUT} \bullet wp(C, q)$ = `wp calculus' $wp(var a_2, c_1 \mid I_{IN} \land I_{OUT} in C end, q)$

This method is therefore sound. The inspiration for this structure was based on properties of data refinement described by von Wright [32]. There, the gluing invariant is represented as a predicate transformer rather than a predicate. Let α be a gluing predicate transformer. It is shown that 'S is data refined by T under α ' is equivalent to:

$$S; \alpha \sqsubseteq \alpha; T,$$

where $S \sqsubseteq T$ is standard algorithmic refinement. Operationally, α can be viewed as a command that (nondeterministically) transforms an abstract state into a concrete state. For standard data refinement, predicate transformer α may be constructed from a gluing invariant I as c: I.

4.5.2 Implementation of Workaround

The description of the workaround above is clear. However, it cannot be implemented directly. This is mainly due to the fact that sequence (;) is not allowed in B machines, at least not presently. To work around this, we specify an original, 'dummy', 'mixed' operation, $c_2 \leftarrow Proc'(a_1)$ without sequence. It is only necessary that this operation may be refined to the operation as written in M'_1 above. This operation is then refined to the operation as written in M'_2 above. We illustrate this structure in Fig. 4.6, using the example procedure already used in Section 4.4.3. We re-use the gluing invariants I_{IN} and I_{OUT} from the example and note that they would appear in the CONSTANTS...PROPERTIES section in the appropriate RE-FINEMENTs.

Having the machines structured as in Fig. 4.6, we can use the workaround described in Section 4.5.1. The two refinements in Fig. 4.6 echo the operations contained in the machines M'_1 and M'_2 in Section 4.5.1 which are in turn refinements of the original 'dummy' operation contained in M3.

The significant property of the 'dummy' operation $y \leftarrow mixedfirst(xseq)$ as originally specified in M3 is that it can be refined by the namesake operation contained in MR3. The workaround, whose underlying soundness was

described in Section 4.5, can be implemented now by checking that M3RR is indeed a refinement of M3R using the B tools directly.

4.6 Conclusions

In this chapter, the use of parameterised operations in B has been examined. The operations which need special care are categorised and named *procedures*. A law is presented to show when the refinement of these procedures is valid. As this is a non-standard strategy, a workaround is presented which allows the user to check the non interface-preserving refinement using the current B tools. This workaround is shown to be sound. 4 - Interface Refinement in B

MACHINE M1: OPERATIONS $x \leftarrow first(xseq) \cong$ PRE $xseq \in seq(X) \land$ $xseq \neq \varnothing$ THEN x := xseq(1)END END MACHINE M2 : OPERATIONS $y \leftarrow cfirst(yseq) \cong$ PRE $yseq \in seq(Y) \land$ $yseq \neq \varnothing$ THEN y := yseq(1)END END

MACHINE M3 : OPERATIONS $y \leftarrow mixedfirstseq(xseq) \cong$ PRE FALSE THEN $y :\in YSet$ END END



Figure 4.6: Structure of Machines for Workaround for Interface Refinement The refinement of operation $x \leftarrow first(xseq)$ in MACHINE M1, by the operation $y \leftarrow cfirst(yseq)$ in MACHINE M2 can be checked according to the framework above.

Chapter 5

Case Studies in B Development

5.1 Introduction

This chapter describes the developmental process of two parts of the overall W.I.T. Academic Council (A.C.) Election system as described in Appendix A and specified in Z in Appendix B and as specified in the B Method's AMN in Appendix D. The two parts of the system which we develop are:

- the pre-processing of votes
- the setting up of the first count

In Chapter 2, we developed (the pre-processing) part of the W.I.T. A.C. Election system from the Z Specification in Appendix B. This was done mostly using Morgan's Refinement Calculus [23]. As discussed in Section 2.7, the development was not straightforward. We decided to approach the development of the system (starting with the same pre-processing part) using the B Method. We took the opportunity to re-examine our choice of concrete data structure and this resulted in a fundamental change thereof.

5.2 Design Issues - B Method and C++'s S.T.L.

Having decided to move to using the B Method, we decided to take a fresh look at our concrete data structure. The development towards the binary search tree was difficult, though its properties led to an efficient implementation. Our new solution needed to be at least as efficient. Our choice of new concrete data structure was contained in the C++ Standard Template Library (S.T.L.). We model (some of) the existing S.T.L. libraries and then only need to refine to the level of the library.

C++ programs call on a large number of functions from the Standard C++ Library. These functions provide essential services such as input and output. Of the many libraries, (currently) 13 constitute the Standard Template Library. These define numerous templates that implement useful and efficient algorithms and the containers that these algorithms can work on. A container is a class that *contains* other objects. An example of a container is a *list*. S.T.L. defines a template for a list, i.e. a list which contains generic items, together with algorithms/functions for inserting, deleting items, etc.

For a fuller discussion of C++ S.T.L., see [7]. There are many very useful on-line tutorials, e.g. [17].

There are many containers in S.T.L.. The container that we choose for our system is called the multiset. The multiset is the most appropriate container to store items where duplicates occur. We use a multiset to model the input (abstractly a bag of *papers*) and the output (abstractly a bag of *ballots*).

They are an efficient mechanism for storing multiple occurrences of items, e.g., an insert into a multiset is of order log N. They are modelled here (as a B Machine) as a sequence of items (in our case a *ballot* or *paper*). In implementation, multisets work by using an ordering function (supplied by the user on instantiation of a multiset). The order of the sequence is defined by a constant X_Order (e.g., *PaperOrder*) which is local to the machine. There is an invariant on the multisets stating that they are always ordered according to this function.

The implementation is not as simple as modelled as we can see from the (supplied) costings of the different operations. A complex 'behind the scenes' structure delivers an efficient mechanism with a simple interface. We model these multisets, and the 'call' of these operations in the development will simply be rewritten as calls to the actual C++ S.T.L. code.

We need two types of multiset machines, the multiset containing concrete papers and the multiset containing concrete ballots. A desired construct would be a generic multiset machine of the form

MACHINE $Multiset(Datatype, X_Order),$

where *Datatype* is the data being stored and X_Order defines the order in which the data part of *Datatype* is sequenced. We could instantiate this machine in both ways. This, however, is not easily done in B because of

the constraints on machine parameters (does not allow functions or complex data types). Inelegant workarounds are possible, but we present two separate machines, *MultisetPapers* (Fig. 5.1) and *MultisetBallots* (Figs. 5.2 and 5.3). Obviously, all multiset machines should have the same operations specified and implemented. The figures present only those operations used specifically for the case studies in this Chapter. The machines use what we will later describe as concrete data types of

 $CPaper \cong iseq(Candidate \times \mathbb{N})$ $CBallot \cong iseq(Candidate)$

5.3 Description of System

The first part of the system that we develop is the pre-processing of votes. This sub-system has been described in Section 2.2. In the treatment of this chapter, we make some changes to the specification of Chapter 2. The first is that we ignore the 'weight' of the ballots. It was felt that this omission made the process clearer for the reader without losing any of the main character of the work. The second change is that we model the input, in this instance as a bag of *papers* rather that as a sequence of *papers*. The third change is that bags are now total functions.

At the abstract level, the input is modelled as a bag of *papers* where $bag T == T \rightarrow \mathbb{N}_1$, where b(item) returns the number of occurrences of *item* in the bag. This raw input *paper* is processed to become what we term a *ballot*. The operation which deals with this has an abstract specification called *Make_Ballot*. The pre-processing of the bag of papers returns a bag of ballots. Not all votes will be valid, so some input will be discarded. The first case study will deal with this overall operation, whose abstract specification is called *Pre_Process* and includes the operation *Make_Ballot*.

The first step (pre-processing of votes into validated ballots) having been completed, we proceed to the counting of the ballots. This is effected through a series of 'counts'. The result of the first count is that each candidate will have 'allocated' to him/her the ballots on which they appear as first preference. Note that because of the pre-processing step, each ballot will have (at least) a first preference. The setting up of this first count (Setup_First_Count) is the subject of our second case study. Note that in the specification, we use stateless machines. We specify the (parameterised) operations using mathematical functions defined in the CONSTANTS and PROPERTIES clauses. The final operation simply calls these functions.

```
MACHINE MulitsetPapers
CONSTANTS
                     PaperOrder
PROPERTIES
     PaperOrder \in \mathbb{P}(seq(CPaper))
                                        /* Set of all Ordered sequences */
VARIABLES
     msetpapers, /* The sequence containing the papers */
     iter /* The multiset iterator, which indicates the current
         position in the multiset. */
INVARIANT
     mset papers \in seq(CPaper) \land
     iter \in 1..card(mset papers) + 1 \land
     mset papers \in PaperOrder
OPERATIONS
     Start \hat{=} iter := 1;
     number \leftarrow Count(paper) \cong
     PRE
         paper \in CPaper
     THEN
         number := card(\{nn \mid nn \in \mathbb{N} \land msetpapers(nn) = paper\}
    END
    paper \longleftarrow GetNext \ \widehat{=}
    PRE
         iterNotAtEnd
    THEN
         paper := msetpapers(iter) \parallel iter := iter + Count(paper);
    END
DEFINITIONS
    iterNotAtEnd \cong (iter \leq card(msetpapers))
```

\mathbf{END}

Figure 5.1: Mulitset of papers machine

```
MACHINE MultisetBallot
CONSTANTS
                      BallotOrder
PROPERTIES
     BallotOrder \in \mathbb{P}(seq(CBallot))
VARIABLES
                    mset ballots
INVARIANTS
     mset ballots \in seq(CBallot) \land
     mset ballots \in Ballot Order
INITIALISATION
     mset ballots := \emptyset
OPERATIONS
     MultiInsert(item, number) \cong
    PRE
          item \in CBallot \land number \in \mathbb{N}
    THEN
         ANY msetballots', aa, bb WHERE
              mset ballots = aa^bb \land
              msetballots' = aa^{n} \mapsto item \mid nn \in 1 \dots number \}^{bb} \wedge
              msetballots' \in BallotOrder
         THEN
              mset ballots := mset ballots'
         END
    END;
    MakeEmpty \cong msetballots := \emptyset;
    number \leftarrow Count(ballot) \cong
    PRE
         ballot \in CBallot
    THEN
         number := card(\{nn \mid nn \in \mathbb{N} \land mset ballots(nn) = ballot\}\}
    END
    ballot \longleftarrow GetNext \cong
    PRE
         iterNotAtEnd
    THEN
         ballot := msetballots(iter) \parallel iter := iter + Count(ballot);
    END
    bb \longleftarrow CurrentBallot \cong
        bb := msetballots(iter);
```

Figure 5.2: Multiset of ballots machine

5 - Case Studies in B Development

Start $\hat{=}iter := 1$;

$$MoveToNextBallot \cong iter := iter + Count(msetballots(iter))$$

END

Figure 5.3: Mulitset of ballots machine... contd.

Part of this case study has been presented as part of [9]. The specification of the *Pre_Process* part has been changed (from the paper) to use bags as total functions and to use a neater specification.

5.4 Case Study 1 - Pre–Processing

The specification of the pre-processing using bags as total functions is as written in Fig. 5.4. The specification use two global functions. The first is a special map function that works on bags, which we call map_b .

 $\begin{array}{ll} map_b \in ((Paper \rightarrow Ballot) \times (bag \ Paper)) \rightarrow bag \ Ballot & \land \\ \forall (ff, bb).(ff \in Paper \rightarrow Ballot \land bb \in bag \ Paper \Rightarrow \\ map_b(ff, bb) = \\ & \lambda \ yy.(yy: Ballot \mid \Sigma xx.(xx \in Paper \land ff(xx) = yy \mid bb(xx)))) \end{array}$

The second is a standard *restrict* function, written for bags (as total functions):

 $\begin{array}{ll} restrict \in (bag \ Ballot \times \mathbb{P}Ballot) \to bag \ Ballot & \land \\ \forall (bb, ss). (bb \in bagBallots \land ss \in \mathbb{P}Ballot \Rightarrow \\ restrict (bb, ss) &= \lambda \ yy. (yy \in Ballot \mid 0) <+ (ss \ \lhd \ bb)) \end{array}$

Before we specify the parameterised operations, we introduce a few types. The raw input is modeled as simply a partial function from *Candidate* to \mathbb{N} . The type is called *Paper*. The validated form of the paper is modelled as an injective sequence of *Candidates* in order of preference. This type is called *Ballot*. In summary, the types are as follows:

$$\begin{array}{l} Paper \cong Candidate \leftrightarrow \mathbb{N} \\ Ballot \cong iseq(Candidate). \end{array}$$

We have a system-wide constant called no_cands and stands for the number of registered candidates. It is an important number as it limits the size of both the *paper* and the *ballot*.

CONSTANTS

make_ballot,
pre_process

PROPERTIES

 $\forall \ bagpapers.(bagpapers \in bag \ Paper \Rightarrow \\ pre_process(bagpapers) = \\ restrict \ (\ (map_b \ (make_ballot, bagpapers) \), \\ \{ ballot \ | \ ballot \in Ballot \ \land card(ballot) > 0 \} \)$

OPERATIONS

 $bagballots \leftarrow Pre_Process(bagpapers) \cong$ **PRE** $bagpapers \in bag Paper$ **THEN** $bagballots := pre_process(bagpapers)$ **END**

Figure 5.4: Abstract Specification of pre-processing

The first part of the first case study illustrates the development of the $Make_Ballot$ operation. The abstract *paper* is a function from *Candidate* to N and, if we invert the function, we have a relation from preferences to candidates at that preference. If we call the lowest non-unique preference $\geq 1 \ first_skip_or_dup(\text{licate})$, i.e., the lowest preference either to appear more that once (duplicate) or not at all (causing a skip in the order of preferences), then it follows that all preferences between 1 and $first_skip_or_dup - 1$ appear exactly once. Thus, if we domain restrict the inverted abstract *paper*'s function between 1 and $first_skip_or_dup - 1$, we have a sequence. This sequence contains the candidates in order of preference and is the abstract *ballot*. This sequence is injective as it is formed from an inverted function. It may happen that all preferences are used 'correctly', i.e., the size of the abstract *ballot* is no_cands . This case is dealt with by the use of $nn \in 1..no_cands + 1$ in the definition of $make_ballot(paper)$.

The rest of the first case study illustrates the development of the *Pre_Process* operation which takes a collection of *ballots*, each returned by the *Make_Ballot* operation, and inserts them into an output bag under certain conditions.

5.4.1 Development of Make_Ballot

The abstract specification of *Make_Ballot* is as follows:

 $aballot \longleftarrow Make_Ballot(apaper) \cong$ **PRE** $apaper \in Paper$ **THEN** $aballot := make_ballot(apaper)$ **END**.

When we substitute for *make_ballot* in the assignment, we get

$$aballot := (1..min(\{nn \mid nn \in 1..no_cands + 1 \land card(apaper^{[\{nn\}]}) \neq 1\}) - 1)$$

$$\lhd apaper^{\sim}.$$

If we let

 $first_skip_or_dup = min(\{nn \mid \in 1..no_cands+1 \land card(apaper^{[\{nn\}]}) \neq 1\}),$

then the above can be rewritten as

 $aballot := (1..first_skip_or_dup - 1) \lhd apaper^{\sim}.$

The R.H.S. of the assignment statement can be simplified, using the definition of \triangleleft to

{ $nn \mapsto cc \mid nn \in 1.. first_skip_or_dup - 1 \land cc \mapsto nn \in apaper$ }.

We explore the two possible paths of development, the style of algorithmic refinement first. We take the following approach on deciding on the shape of our implementation: We guess at a possible implementations. Having this possible implementation means that we have something to aim for which helps us to make decisions during development. Using this approach means that for our case studies, we start with the same specification and expect to arrive at a similar implementation using both styles of development.

Make_Ballot - Algorithmic Refinement Followed by Data Refinement

We look directly for a loop invariant based closely on the structure of the specification, as follows:

$$LI_1 \cong aballot = \{ nn \mapsto cc \mid nn \in 1..so_far - 1 \land cc \mapsto nn \in apaper \}.$$

The guard of the loop is $so_far < first_skip_or_dup$. We introduce the loop shown in Fig. 5.5. Note that $apaper^{\sim}(so_far)$ is well defined since:

 $\begin{array}{l} apaper \in Candidate \rightarrow \mathbb{N} \land so_far < first_skip_or_dup \\ \Rightarrow \quad \forall ii.(ii \in 1.so_far \Rightarrow card(apaper^{\sim}[\{ii\}]) = 1 \\ \Rightarrow \quad 1..so_far \lhd apaper^{\sim} \in \mathbb{N} \Rightarrow Candidate. \end{array}$

Most of the proof obligations generated from the introduction of this loop are easily discharged. We have a close look at the P-Rule [34], i.e., $LI_1 \wedge G \Rightarrow [Body]LI_1$.

 $\begin{array}{l} [aballot(so_far) := apaper^{\sim}(so_far)] \\ [so_far := so_far + 1] \\ (aballot = \{ nn \mapsto cc \mid nn \in 1..so_far - 1 \land cc \mapsto nn \in apaper \}) \end{array}$

 $= [aballot(so_far) := apaper^{\sim}(so_far)]$ $(aballot = \{ nn \mapsto cc \mid nn \in 1..so_far \land cc \mapsto nn \in apaper \})$

$$= (aballot <+ \{so_far \mapsto apaper^{\sim}(so_far)\}) \\ = \{ nn \mapsto cc \mid nn \in 1..so_far \land cc \mapsto nn \in apaper \}$$

```
VAR so_far IN

so_far := 1;

WHILE so_far < first_skip_or_dup DO

aballot(so_far) := apaper~(so_far);

so_far := so_far + 1;

INVARIANT LI<sub>1</sub>

VARIANT first_skip_or_dup - so_far

END

END
```

Figure 5.5: First Loop Introduction on Make_Ballot

The loop requires further refinement as the calculation of $first_skip_or_dup$ and of $apaper^{\sim}(so_far)$ are nontrivial. We construct a local variable, bbwhich has the following value:

$$BB \cong \{1..no_cands \times \{(\bot, 0)\} <+ \\ \{ ii \mapsto (cand, no) \mid ii \in ran(apaper) \land \\ cand \in apaper^{\sim}[\{ii\}] \land \\ no = card(apaper^{\sim}[\{ii\}]) \}.$$

Here \perp represents a special null candidate.

Each pair at position *ii* contains a candidate with preference *ii* associated in *apaper* and the number of candidates at this preference. When this number is 1, the candidate of the pair is the unique candidate at this preference. A pre-condition of the former loop is that bb = BB. We introduce the local variable, *bb* with its property in Fig. 5.6.

We proceed with data refinement on the above loop with the assertion that bb = BB holds. We also take advantage of this refinement step to replace *aballot* by *cballot* using the following simple gluing invariant

 $GI_1 \cong aballot = cballot.$

We proceed as follows: The outermost VAR statement is refined using Law **DatRef 6** from Fig. 3.1. This does not result in any change in the introduced variables, but distributes the data refinement inside the statement. We accordingly apply Law **DatRef 3** from Fig. 3.1 to the sequentially composed statements in the VAR statement. This means that each component statement will be data refined using GI_1 as R. There is no change in the first two statements. The third is more interesting. It is a loop and we apply

```
VAR so\_far, bb IN

so\_far, bb := 1, \emptyset;

bb := BB;

PRE bb = BB THEN

WHILE so\_far < first\_skip\_or\_dup DO

aballot(so\_far) := apaper^{\sim}(so\_far);

so\_far := so\_far + 1;

END

END

END
```

Figure 5.6: Make_Ballot after the introduction of intermediate variable bb.

```
VAR so\_far, bb IN

so\_far, bb := 1, \emptyset;

bb := BB;

WHILE bb(so\_far).no = 1 DO

cballot(so\_far) := bb(so\_far).cand;

so\_far := so\_far + 1;

END

END
```

Figure 5.7: Make_Ballot after first data refinement

Law DatRef 5 from Fig. 3.1. We can show that

 $bb = BB \Rightarrow so_far < first_skip_or_dup = bb(so_far).no = 1 \land bb = BB \Rightarrow apaper^{(so_far)} = bb(so_far).cand.$

The data refined version of Fig. 5.6 is shown in Fig. 5.7.

Next, we refine the calculation of the local variable bb using the loop shown in Fig. 5.8. The loop invariant is:

$$LI_{2} \cong bb = \{1..no_cands \times \{(\bot, 0)\} <+ \\ \{ii \mapsto (cand, no) \mid ii \in ran(processed \lhd apaper) \land \\ cand \in (processed \lhd apaper)^{\sim}[\{ii\}] \land \\ no = card((processed \lhd apaper)^{\sim}[\{ii\}])\} \\ \land \\ processed \subseteq dom(apaper).$$

Again, the main proof is easily discharged.

88

```
VAR processed IN
    bb, processed := 1..no_cands \times \{(\bot, 0)\}, \emptyset;
    WHILE dom(apaper) - processed \neq \emptyset DO
         VAR currcand, index IN
              currcand :\in dom(apaper) - processed;
             index := apaper(currcand);
             bb(index).cand := currcand;
             bb(index).no := bb(index).no + 1;
             processed := processed \cup {currcand}
         END
    INVARIANT
                       LI_2
    VARIANT
                   card(dom(apaper) - processed)
    END
END
```

Figure 5.8: Calculating intermediate variable bb.

We now apply data refinement to the code in Fig. 5.8. We replace an abstract paper, represented as a partial function, by a sequence of *Candidate*, \mathbb{N} pairs.

$$CPaper \in iseq(Candidate \times \mathbb{N}).$$

We use GI_2 to relate these:

 $GI_2 \cong apaper = ran(cpaper).$

Furthermore, we wish to reduce non-determinism. We introduce a new (indexing) variable, so_far . We replace the non-deterministic choice of the next candidate to be processed by the next in sequence of *cpaper*, i.e., $cpaper(so_far)$. The new invariant is:

$$GI_3 \stackrel{\frown}{=} processed = \{c \mid \exists ii \bullet (ii \in 1..so_far - 1 \land cpaper(ii).cand = c)\} \land so_far \in 1..no_cands + 1.$$

We can show that

 $GI_2 \wedge GI_3 \Rightarrow dom(apaper) - processed \neq \emptyset = so_far - 1 \leq card(cpaper)$ $\mathcal{D}[[currcand :\in dom(apaper) - processed]]$ $\sqsubseteq currcand := cpaper(so_far).cand$

- \mathcal{D} [index := apaper(currcand)] \sqsubseteq index := cpaper(so_far).pref
- $\mathcal{D}[\![processed := processed \cup \{ currcand \}]\!] \quad \sqsubseteq \quad so_far := so_far + 1.$

```
VAR so\_far IN

so\_far := 1;

WHILE so\_far \neq card(cpaper) DO

VAR currcand, index IN

currcand := cpaper(so\_far).cand;

index := cpaper(so\_far).pref;

bb(index).cand := currcand;

bb(index).no := bb(index).no + 1;

so\_far := so\_far + 1;

END

END

END
```

Figure 5.9: Data-refined loop for calculating bb

Using the data refinement rules, the loop of Fig. 5.8 (excluding the initialisation of bb) is data-refined by the loop of Fig. 5.9. The initialisation of bb to $1..no_cands \times \{(\bot, 0)\}$ is easily refined by a loop that interates *i* through $1..no_cands$ setting each bb(i) to $(\bot, 0)$. We omit this for reasons of space.

This concludes the development of the concrete version of $Make_Ballot$, which we refer to as C_Make_Ballot , using algorithmic refinement before data refinement.

Make_Ballot - Data Refinement Followed by Algorithmic Refinement

We now visit the more usual approach taken in B developments. We immediately apply data refinement to the abstract specification. We then proceed with algorithmic refinement. We start at the same point and end with the same code using both styles, as discussed in Section 5.4.1. For reasons of space, we simply state the loop invariants without showing the resultant code. The development of the code should be obvious from the statement of the invariants.

We start by showing the result of data refining the operation $Make_Ballot$ using gluing invariants GI_2 and GI_1 . We introduce a name for the data refined $first_skip_or_dup$, called $c_first_skip_or_dup$.

 $c_first_skip_or_dup = \\ min(\{ nn \mid nn \in 1..no_cands + 1 \land card(ran(cpaper)^{\sim}[\{nn\}]) \neq 1 \}.$

 $cballot \longleftarrow C_Make_Ballot(cpaper) \widehat{=}$ PRE $cpaper \in iseq(Candidate \times \mathbb{N})$ THEN $cballot := \{nn \mapsto cc \mid nn \in 1..c_first_skip_or_dup - 1) \land$ $cc \mapsto nn \in ran(cpaper)\}$ END

We use the same structure as in the previous section, but with concrete variables. Similarly, we use an intermediate variable (cb) to help us build up *cballot*. The property for cb is

$$\begin{array}{rcl} cb = 1..no_cands \times \{\bot, 0\} &<+ \\ \{ \ ii \mapsto (cand, no) \ | \ ii \in ran(ran(cpaper)) \land \\ cand \in (ran(cpaper))^{\sim}[\{ii\}] \land \\ no = card((ran(cpaper))^{\sim}[\{ii\}]) \ \}, \end{array}$$

and we introduce a loop to calculate cb using the following loop invariant:

$$LI_4 \stackrel{\widehat{=}}{=} cb = 1..no_cands \times \{\bot, 0\} \iff \{ii \mapsto (cand, no) \mid ii \in ran(ran(1..so_far - 1 \lhd cpaper)) \land cand \in ran(1..so_far - 1 \lhd cpaper)^{\sim}[\{ii\}] \land no = card(ran(1..so_far - 1 \lhd cpaper)^{\sim}[\{ii\}] \land so_far \in 1..no_cands + 1.$$

Note the similarity with LI_2 . The main difference is the use of an index so_far rather than a set *processed*. This increases the complexity of the reasoning slightly at the concrete level.

We need to calculate the initial value of cb (as with bb before) and so present the following loop invariant to calculate the initial value for cb. Note the similarity to I_3 from the previous section.

$$LI_5 \stackrel{\widehat{}}{=} 1..so_far \triangleleft cb = 1..so_far - 1 \times \{(\bot, 0)\} \land so_far \in 1.no_cands + 1.$$

Next, we present the 'main' loop invariant, i.e., to calculate *cballot*.

$$LI_6 \stackrel{\cong}{=} cballot = \{nn \mapsto cc \mid nn \in 1..so_far - 1 \land cc \mapsto nn \in ran(cpaper)\} \land so_far \in 1..no_cands + 1.$$

This is very similar to LI_1 . Using these loop invariants, we derive the same refined code as resulted from the previous section.

The invariants are similar, with the concrete version being slightly more complex. However, we refined to a more deterministic version in one step with the loop introduction step involving LI_4 . When we applied algorithmic refinement first, (see Fig. 5.8), the first loop had more non-determinism.

5.4.2 Development of Pre_Process

Having developed the code for C_Make_Ballot , we move on to the higher level, i.e., the container and how the (abstract) bag of papers gets transformed into the (abstract) bag of ballots. The *Pre_Process* operation is specified in Fig. 5.4. In this section, we look at the concrete data types used for the implementation of this operation. We look at both styles of development as in Section 5.4.1.

Pre_Process - Algorithmic Refinement Followed by Data Refinement

In this section, we apply algorithmic refinement immediately and then proceed with data refinement. We are required to refine:

```
bagballots := pre_process(bagpapers).
```

The main loop invariant is:

```
 \begin{array}{ll} LI_7 & \widehat{=} \\ bagballots = \\ restrict & ((map (make_ballot, restrict(bagpapers, processed)))) \\ & & \{ballot \mid ballot \in Ballot \land card(ballot) > 0\}) \\ & \land \\ processed \subseteq dom(bagpapers). \end{array}
```

Looking at the post-condition of $Pre_Process$, we immediately introduce a loop as shown in Fig. 5.10. It can be shown that all the proof obligations can be discharged.

We now apply data refinement techniques as described in Chapter 3 Section 3.2. *bagballots* is replaced by *msetballots* of the MultisetBallots machine of Figs. 5.2 and 5.3. *bagpapers* is replaced by *msetpapers* of the Multiset-Papers machine of Fig. 5.1. We use the transformations and discharge the proof obligations. The gluing invariant between *bagpapers*, *bagballots* and

```
bagballots \leftarrow Pre_Process(bagpapers) \cong
PRE bagpapers \in bag Paper
THEN
     VAR processed IN
         bagballots, processed := \emptyset, \emptyset;
         WHILE (dom(bagpapers) - processed) \neq \emptyset DO
              VAR pp, bb IN
                  pp :\in (dom(bagpapers) - processed);
                  bb \leftarrow Make\_Ballot(pp);
                  IF card(bb) > 0
                  THEN
                       bagballots :=
                         bagballots \iff \{bb \mapsto bagballots(bb) + bagpapers(pp)\}
                   END;
                  processed := processed \cup \{pp\}
              END
                            LI_7
         INVARIANT
         VARIANT card(dom(bagpapers) - processed)
         END
    END
END
```

Figure 5.10: Algorithmically-refined pre-processing

5 - Case Studies in B Development

msetpapers, msetballots is

$$GI_4 \cong bagpaper = items\{nn \mapsto ap \mid ran(msetpapers(nn)) = ap\} \land bagballots = items(msetballots)$$

One of the main transformations is that of the loop guard. Given

 $GI_5 \cong processed = \{ ap \mid \exists cp \bullet (cp \in mprocessed \land ap = ran(cp)) \},\$

we can show that

 $GI_4 \wedge GI_5 \Rightarrow$ $dom(Papers) - processed \neq \emptyset = ran(msetpapers) - mprocessed \neq \emptyset.$

Within the loop body we use:

$$GI_6 \stackrel{\widehat{=}}{=} pp = ran mp \land$$

 $bagpapers(pp) = card\{nn \mid msetpapers(nn) = pp\} \land$
 $bb = cb.$

The transformations on the statements and expressions using gluing invariant $GI_4 \wedge GI_5 \wedge GI_6$ are then as follows:

This leads to the following program:

 $msetballots \leftarrow C_Pre_Process(msetpapers) \cong$ **PRE** msetpapers \in multisetPapers **THEN** $V\!AR$ mprocessed INmsetballots, mprocessed $:= \emptyset, \emptyset;$ **WHILE** $ran(msetpapers) - mprocessed \neq \emptyset$ **DO** VAR mp, cb IN $mp :\in ran(mset papers) - mprocessed;$ $cb \leftarrow C_Make_Ballot(mp)$; IF card(cb) > 0 THEN $MultiInsert(cb, card\{nn \mid msetpapers(nn) = mp\})$ END: $mprocessed := mprocessed \cup \{mp\};$ END END END END.

Next, we refine the nondeterministic selection of mp in the loop body and become more specific about which member we choose. The refinement step replaces *mprocessed* by *iter* using the following gluing invariant:

 $GI_7 \cong mprocessed = ran(1..iter - 1 \triangleleft msetpapers).$

We can show that

 $GI_7 \Rightarrow ran(mset papers) - m processed \neq \emptyset = iter \leq card(mset papers).$

The refined program is defined in terms of the multiset machines (Fig. 5.1 and Figs. 5.2 and 5.3):

```
\begin{array}{l} MakeEmpty;\\ Start;\\ \textbf{WHILE } iterNotAtEnd \ \textbf{DO}\\ mp \longleftarrow GetNext;\\ cb \leftarrow C\_Make\_Ballot(mp);\\ \textbf{IF } card(cb) > 0 \ \textbf{THEN}\\ MultiInsert(cb, Count(mp))\\ \textbf{END}\\ \textbf{END}\\ \textbf{END}. \end{array}
```

This concludes the first path for *Pre_Process*.

CONSTANTS

 $setup_first_count$

PROPERTIES

OPERATIONS

 $Setup_First_Count \cong$ **BEGIN** $vm := setup_first_count(bagballots)$ **END**

Figure 5.11: Abstract Specification of Setup_First_Count

5.5 Case Study 2 - Setting up First Count

The second case study looks at setting up the first count. For this case study, we use state variables and the main operation is parameterless. The specification is written in Fig. 5.11 and is part of a machine that has as state the variables vm and bagballots. The setting up of the first count entails associating each (validated) ballot with that ballot's first preference candidate at count one.

The abstract *vm* is a *VoteMass*. *VoteMass* is the (abstract) structure type to hold the details of the counts. It is defined as:

 $VoteMass \cong Candidate \implies (\mathbb{N} \implies bag \ Ballot)$

bagballots is of type *bag Ballot* and contains the validated ballots from the previously described pre-processing.

The first step is to immediately introduce a loop with the following Loop

```
Setup\_First\_Count \cong
VAR processed IN
     vm, processed := \emptyset, \emptyset;
     WHILE (dom(bagballots) - processed) \neq \emptyset DO
         VAR bb, cand IN
              bb :\in (dom(bagballots) - processed);
              cand := bb(1);
              vm(cand)(1) := vm(cand)(1) \cup
                            \{bb \mapsto bagballots(bb)\}
              processed := processed \cup \{bb\}
         END
    INVARIANT
                        LI_8
    VARIANT
                    card(dom(bagballots) - processed)
    END
END
```

Figure 5.12: First Loop Introduction in Setup_First_Count

Invariant:

 $LI_8 \cong \\ \forall \ cand : all candidates \bullet \\ vm(cand)(1) = restrict(bagballots, \{bb \mid bb(1) = cand \land bb \in processed\}) \land \\ processed \subseteq dom(bagballots).$

This leads to the program in Fig. 5.12. The proof-obligations are discharged but not shown as they are standard.

Next, we proceed with data refinement. We proceed with data refinement in two stages, for clarity. Firstly, we data refine our vm to a less abstract vmpos. The second data refinement step is to data refine vmpos to a more concrete cvm.

We proceed with the first data refinement. *vmpos* has the following type:

 $VoteMassPos \cong Candidate \rightarrow (\mathbb{N} \rightarrow \mathbb{PN})$

vmpos holds the positions of (or pointers to) the *ballots* in the *msetballots* instead of the actual *ballots* from before. So the gluing invariant is as follows:

 $GI_8 \cong \\ \forall (cand, count).(cand \in dom \ vm \land count \in dom(vm(cand)) \bullet \\ vmpos(cand)(count) = \\ \{ place \mid msetballot(place) \in dom \ vm(cand)(count) \} \end{cases}$

The next gluing invariant GI_9 specifies a new *cprocessed*. Whereas *processed* is the set of *ballots* that have been dealt with, *cprocessed* is corresponding set of positions (in *msetballots*) of the *ballots* that have been dealt with. So the gluing invariant is:

 $GI_9 \cong cprocessed = \{nn \mid msetballots(nn) \in processed\}$

We distribute this set of data refinements across the code of the program of Fig. 5.12.

 \mathcal{D} processed := \emptyset $cprocessed := \emptyset$ $\mathcal{D}[vm := \emptyset]$ $vmpos := \emptyset$ $\mathcal{D}[\![dom \ bagballots \ - \ processed \neq \varnothing]\!]$ ____ $1..card(msetballots) - cprocessed \neq 0$ $\mathcal{D}[\![bb] :\in (dom \ bagballots - processed)]\!]$ $newpos :\in (1 \dots card(msetballots) - cprocessed);$ bb := msetballots(newpos) $\mathcal{D}[\![vm(cand)(1) \cup \{bb \mapsto bagballots(bb)\}]\!]$ \square $vmpos(cand)(1) := vmpos(cand)(1) \cup$ $\{nn \mid msetballots(nn) = bb\}$ $\mathcal{D}[\![processed := processed \cup \{bb\}]\!]$ $cprocessed := cprocessed \cup \{nn \mid msetballots(nn) = bb\}$

The resultant program is given in Fig. 5.13 and is part of a machine which includes *vmpos* and *msetballots* as state. This program is less abstract, but still contains a non-deterministic choice of the next ballot to be processed. This non-determinism can be removed by the use of a further data refinement, introducing a *counter* called *iter*, so the next ballot to be chosen is the next available in *msetballots*.

 $GI_{10} \stackrel{\widehat{=}}{=} cprocessed = 1 \dots iter - 1 \land$ $iter \in 1 \dots card(msetballots) + 1$

We distribute this data refinement across the code of the program of Fig. 5.13



as follows:

 $\mathcal{D}[\![cprocessed := \emptyset]\!]$ iter := 1 \mathcal{D} [1.. card(msetballots) - cprocessed $\neq \emptyset$] $iter \leq card(msetballots)$ \mathcal{D} [*newpos* : \in (1.. card(msetballots) - cprocessed); bb := msetballots(newpos)newpos := iter;bb := msetballots(newpos)bb := msetballots(iter) $\mathcal{D}[\![cprocessed := cprocessed \cup \{nn \mid msetballots(nn) = bb\}]\!]$ $iter := iter + card(\{nn \mid msetballots(nn) = bb\})$

This leads to the less non-deterministic, data refined program as written in Fig. 5.14.

Our next data refinement introduces our final concrete data structure. It uses sequences. These sequences will be implemented using linked lists. The concrete data structure cvm is of the type $C_VoteMass$, defined as follows:

 $C_{-}VoteMass \cong seq(Candidiate \times seq(\mathbb{N} \times seq(\mathbb{N})))$

Associated with each candidate is a sequence, each element of which contains a count number and the sequence of positions of ballots associated

```
Setup_First_Count \widehat{=}

VAR iter IN

vmpos, iter := \emptyset, 1;

WHILE (iter \leq card(msetballots)) DO

VAR bb, cand IN

bb := msetballots(iter);

cand := bb(1);

vmpos(cand)(1) := vmpos(cand)(1) \cup

\{nn \mid msetballots(nn) = bb\}

iter := iter + card(\{nn \mid msetballots(nn) = bb\})

END

END

END
```

Figure 5.14: Second Data Refinement in Setup_First_Count

with this candidate at this count. As it may not be obvious how to access each of the elements of cvm, we use the following (where i is the position in the sequence of our candidate of interest):

cvm(i). cand yields the candidate of interest.

cvm(i). countlist yields the sequence or 'list' of counts for our candidate of interest.

cvm(i).countlist(j).countnumber yields the count number which is at position j of the sequence associated with our candidate of interest.

cvm(i).countlist(j).countballots yields the sequence of positions of the ballots associated with the candidate of interest at position j of the sequence. The gluing invariant between *vmpos* and *cvm* is as follows:

```
GI_{11} \stackrel{\widehat{=}}{=} \forall (i, j, cand, count). (i \in 1...no\_cands \land j \in 1...no\_cands \land cand = cvm(i).cand \land count \in dom(ran \ cvm(i).countlist(j)) \land vmpos(cand)(count) = ran(ran \ cvm(i).countlist(j)) (countnumber))
```

We introduce the machine ConcreteVoteMass in Figs. 5.15 and 5.16 and use a strategy similar to that used in the Multiset machines from before. We define the machine with operations which will be useful to us for this problem. The next data refinement is then to rewrite the operation *Setup_First_Count* in terms of the ConcreteVoteMass machine. This machine, which is based

on sequences, would be implemented using linked lists, using techniques as described in [20]. This refinement path is not shown.

In the ConcreteVoteMass machine, we use the mathematical function *makeseq* which returns an injective sequence from a set as specified in the following way:

 $\forall ss.(ss \in iseq \mathbb{N} \land makeseq(ran ss) = ss)$

This leads to an implementation defined in terms of the MultisetBallot machine (Figs. 5.2 and 5.3) and the ConcreteVoteMass Machine (Figs. 5.15 and 5.16). This implementation is shown in Fig. 5.17.

5.6 Conclusions

The two case studies completed above have illustrated techniques discussed in earlier chapters. Specifically, we have employed the technique of applying algorithmic refinement as a first step throughout. This has led to clear solutions and straightforward proofs in most circumstances. We also applied the technique of data refining interfaces as needed because of some of the operations' interfaces being based on abstract data types.

Interface refinement was used on both of the high-level operations in the case studies, i.e. *Pre_Process* and *Setup_First_Count*. We applied a further interface refinement in the first case study - *Pre_Process*. A clue as to when we need interface refinement within the operations can be found in the abstract specification. Well structured specifications are clear and hide complex parts by appropriately naming small parts of the specifications. This can be implemented by the use of mathematical functions (in the CONSTANTS. PROPERTIES part of the MACHINE), e.g. the *make_ballot* function led to the *Make_Ballot* procedure. When this non-flat structure is used, this is our hint that the implementation of overall specification may have an internal call to an operation. Because the mathematical function has been defined in terms of data that will have to change, we deal with them as *procedures* as defined in Section 4.2.

Note the structure of both our (high level) abstract specifications in the case studies, in Figs. 5.4 and 5.11. In the case of *Pre_Process*, the function *pre_process* calls another function, *make_ballot*. An operation *Make_Ballot* (a *procedure*) uses the function *make_ballot*. The operation is refined, using interface refinement.

```
MACHINE Concrete VoteMass
 VARIABLES cvm
 INVARIANTS cvm \in C_VoteMass
 INITIALISATION Initcom
 OPERATIONS
 Initcvm \widehat{=}
     ANY ss WHERE
         dom(ran(s)) = all candidates \land
         card(s) = card(allcandidates)
     THEN
         cvm := ss
     END;
bb \leftarrow CountExists(count, cand) \cong
     PRE
         count \in \mathbb{N} \land cand \in all candidates
     THEN
         bb := BOOL(count \in dom(ran (ran cvm)(cand))))
    END;
pos \leftarrow FindCandIndex(cand) \cong
    PRE
         cand \in all candidates
    THEN
         ANY ii WHERE
             cvm(ii).cand = cand
         THEN
             pos := ii
         END
    END;
pos \leftarrow FindCountIndex(count, cand) \cong
\mathbf{PRE}
    count \in \mathbb{N} \land cand \in all candidates
THEN
    ANY ii WHERE
         cvm(FindCandIndex(cand)).countlist(ii).count = count
    THEN
        pos := ii;
    END
END;
```



 $InsertNewCount(count, cand) \cong$ PRE $count \in \mathbb{N} \land cand \in all candidates \land$ $\neg CountExists(count, cand)$ THEN **ANY** candindex **WHERE** candindex = FindCandIndex(cand)THEN cvm(candindex).countlist := $cvm(candindex).countlist[count \mapsto []]$ END

END

 $InsertNewBallots(count, cand, startpos, number) \cong$ PRE $count \in \mathbb{N} \land cand \in all candidates \land$ $startpos \in 1 \dots card(mset ballots) \land$ $startpos + number \leq card(msetballots) \land$ CountExists(count, cand) THEN ANY candindex, countindex, ii WHERE $candindex = FindCandIndex(cand) \land$

```
countindex = FindCountIndex(cand, count)
THEN
    cvm(candindex).countlist(countindex).countballots :=
    cvm(candindex).countlist(countindex).countballots
    ^{makeseq(startpos .. startpos + number - 1)}
END
```

END;

DEFINITIONS

 $C_VoteMass \cong seq(Candidate \times seq(\mathbb{N} \times seq(\mathbb{N})))$

Figure 5.16: ConcreteVoteMass Machine.. contd.

5 - Case Studies in B Development

```
SetupFirstCount \cong
    Initcvm;
            /* Go to start of Ballots */
    Start;
    WHILE iterNotAtEnd DO
        VAR bb, cand IN
            bb \leftarrow CurrentBallot;
            cand := bb(1);
            IF CountExists(1, cand)
            THEN
                 InsertNewBallot(1, cand, iter, num);
            ELSE
                 InsertNewCount(1, cand);
                 InsertNewBallot(1, cand, iter, num)
            END
            MoveToNextBallot;
        END
   END
```

Figure 5.17: Implementation of Setup_First_Count

In the case of *Setup_First_Count*, the specification is flat. No further operations are used, so no further interface refinement is required.

It may be noted that the overall structure of the process is cleaner and neater in this chapter than in the earlier Chapter 2 where a case study was examined. This may be due to the more appropriate technique having been used. It is probably more due to the fact that the work done in this chapter was attempted later than that of the earlier chapter. Therefore, more experience was brought into the work of this chapter.

104

Chapter 6

Conclusions

6.1 Conclusions

We have described, using examples, how to apply data refinement after algorithmic refinement in B. We have used laws on distribution of data refinement to implement the former approach based on [8, 16, 22, 24, 32].

We make some comparisons, albeit intuitive, between developments using both the standard approach of data refinement first and *vice versa*. Some tentative conclusions on these comparisons are:

- Invariants tend to be simpler when the loop is introduced immediately, i.e. before data refinement. This leads to slightly easier reasoning when proving the loop.
- In some cases, the removal of non-determinism in the 'choice of next element to be processed' in the loop was more elegant in the case of algorithmic refinement first. This may have been due to that fact that data refinement was introduced in two stages, (after loop introduction) firstly maintaining, and then eliminating non-determinism. The 'twostage proof' was not as complex as the 'all-in-one' version of the data refinement first.

We suggest that this developmental style of algorithmic refinement before data refinement is (at least) worthy of examination. We suggest that this approach be seen as an alternative to the more standard approach. It is sometimes (but not always) appropriate. It may not be appropriate, for example, when the algorithmic structure is determined more by the concrete data structures than the abstract data structures. Also, it may often be useful to mix approaches, i.e., perform some algorithmic refinement then some

6 - Conclusions

data refinement, more algorithmic refinement etc. More work needs to be done to formulate a set of heuristics on when either approach is appropriate.

There are many ways to data refine an abstract data type, depending on style and priorities of implementation. In general there are fewer abstract data types used in developments than concrete data types. Developers should find that it is easier and quicker to gain proficiency in the introduction of algorithmic structures on the fewer number of abstract data types than in the introduction of same with concrete data types. Loop introduction, the proof obligations of which are difficult to discharge, is an example of where the developer can build up a useful set of solution patterns more quickly on loops involving abstract data types than on loops working on concrete data types.

At present, neither the B-Toolkit nor Atelier-B fully support algorithmic refinement before implementation stage. The extensions suggested are to support this activity by incorporating the Data Refinement Laws (e.g. those mentioned in Fig. 3.1) and allowing algorithmic refinement during the refinement stage.

Presently, refinement (sensibly) must be interface-preserving. As discussed in Chapter 4 and illustrated in the case studies, however, in some cases it is necessary. A rule for allowing us to introduce a correct refinement step involving interface refinement is presented in Section 4.2. This allows us to progress soundly. However, as this rule is not presently implemented in the B-Toolkit, we present a workaround for checking non interface-preserving refinements in the B-Toolkit in Section 4.5.

We used C++'s S.T.L. during development of the case studies. The motivation for its use is presented in Section 5.2. Whereas the limited nature of the case studies meant that we did not fully develop the idea, we found that the resulting efficiency from using S.T.L. and its data types was a good enough reason to explore the area.

We used the idea of overloaded dot notation in Section 5.4.1. This allows us to access elements of a pair conveniently and is syntatic sugar for the Zlike fst and snd functions. We found this to be useful.

During both case studies, we used the approach of early in the development guessing a possible implementation. We use this to guide us through the development path as discussed in Section 1.7.

We discussed the main technical differences between Morgan's Refinement Calculus and the B Method in Section 1.7. We now draw some comparisons between each technique.

• Firstly, let us look at the B Method. The developer can see the en-

6 - Conclusions

tire operation together, albeit with possibly some operation/function calls, no matter at what stage the development is. The context is always clear. However, when using Morgan's Refinement Calculus, the program is broken up (using sequential composition) and each piece is separately refined. When developing a program of any reasonable complexity, this leads to many different paths. It becomes quite difficult to keep track of the paths. It is also tricky to have an overview on the development process throughout. The development of Section 2.3.3 is a short one but it is not easy to see the development path at a glance. This is particularly problematic when novice users are using this approach.

- In the B Method, it is possible (albeit not necessary or usual) to go directly, in one step from specification to implementation. The proofobligations would then have to be discharged (assuming automatic generation of proof obligations by the B-Toolkit). This is not a practical approach for anything but the simplest of systems as usually such proof obligations would be difficult to discharge. However it does nicely illustrate the difference between the two approaches. It is completely up to the user to drive the entire process in the case of Morgan's Refinement Calculus.
- We have mentioned tool support in our presentation of motivations for moving towards using the B Method. There is no commercially available tool support for Morgan's Refinement Calculus. The availability of tool support is a significant advantage for the B Method. It is hard to envisage any real-world systems being developed without such significant tool support.

6.2 Future Work

The work as presented leads us to suggest a number of different areas for future work.

In this work, we have presented a new approach to refinement, i.e. algorithmic refinement before data refinement. We have not thoroughly examined when this approach is better or more appropriate. (We discuss it at an intuitive level). We have not explored under what criteria 'better' or 'more appropriate' could be decided. It would be useful to examine this area more closely. Perhaps an examination of the types and numbers of proof-obligations generated in each case would be a starting point. This

6 - Conclusions

could lead to a quantifiable way of judging the relative merits of different developments which would be very useful.

We have used S.T.L. as the target code and environment in the Case Studies. We discussed why we decided on S.T.L. in Chapter 5. The main benefit of using S.T.L. is that the algorithms and data structures work well to give us efficient implementations. We make the (sensible) assumption that whereas C++ including S.T.L. are not formally proven, we assume them to be correct as they are widely used and thus exhaustively tested.

Future work in this area would be to specify all of S.T.L. libraries in the B Method, so that all the S.T.L. is available to the formal practitioner easily. The development of 'design patterns' of problems which lead to S.T.L. implementations could lead to re-use of some specification - to - code, bringing with it with the usual benefits of re-use of proofs, etc.

In this work, we started using Z specification and developing the implementation using Morgan's Refinement Calculus [23]. As discussed, this did not work well. We then moved on to work with the B Method [1] which worked better and which we used for the remainder of the work. It would be interesting to compile a comprehensive description of the differences between these two approaches to refinement. An examination of when each is more appropriate would also be interesting.

Our strategy when developing sub-systems was to look at the specific problem and develop that. Another approach would be to solve generic problems or subsystems and re-use these generic solutions to particular problems. We have looked at one generic problem, that of 'selective mapping' and shown the generic solution, in Section 2.6. Further work could be done on abstracting the generic patterns of more of the problems that we have dealt with in this work. This generic problems could then be solved, resulting in useful problem patterns with available solutions.

The original plan of this work was to implement the counting of votes in an electoral system, the rules of which are presented in Appendix A. The specification is presented, both in the Z notation (Appendix B) and using the B Method (Appendix D).

As the work progressed, we moved from our original paradigm of Z specification followed by Morgan's Refinement Calculus to the B Method. Although we were satisfied that the B Method was the appropriate choice for development, its use led us to examine a number of areas, the results of which are presented in Chapter 3 and Chapter 4.

This meant that there was a shift in emphasis away from 'pure' implementation. Consequently, the full system as specified has not been fully implemented. An obvious area of future work is to fully implement the
6 - Conclusions

voting system. This would be interesting as:

- a number of very interesting challenges arose from a careful examination of the issues arising out of the development of what was a small part of this real-life system. The development of the remainder of the system and similar careful examination could, we believe, raise more interesting points.
- as a system for counting votes is a mission-critical system, Formal Methods is a very appropriate developmental technique. It would act as a useful real-life example. It may have commercial value as currently there are plans to computerise part of the Irish General Election.

Appendix A

Waterford Institute of Technology Academic Council Election Count Rules

A.1 Election Procedures of Academic Members to the Academic Council

- 1. The number of members to be elected shall be thirteen.
- 2. There shall be a minimum of 40% or 6 candidates from each gender. (We call this the 'gender constraint'). This is a legal requirement.
- 3. There shall be a minimum of two persons from each of the four schools elected subject to there being sufficient candidates. (We call this the 'school constraint')
- 4. There shall be a minimum of one person from the Department of Adult Education elected subject to there being sufficient candidates. (We call this the 'department constraint')
- 5. In considering the counting of votes, the rules as set down in Rules for Academic Council Election (Academic Members) will be used. An abridged form is seen below.

A.2 Rules for Academic Council Election (Academic Members) (Abridged Form)

- 1. All valid papers are grouped by first preference votes and candidates are ordered in descending order of first preferences. Each vote is given a weight of 1000.
- 2. The quota is calculated quota = (number of valid votes * 1000)/(number of vacancies + 1) + 1
- 3. If, at the end of any count, a candidate has a total weight of votes greater than the quota, check should that candidate be elected (see Section A.3). If this is not allowed, then exclude the candidate according to rule 7. If it is allowed to elect the candidate, deem the candidate to be elected and distribute the candidate's surplus in the following manner
- 4. If the candidate's votes come from first preferences only, then transfer all votes according to rule 6.
- 5. If the candidates votes come from a mixture of first preferences and transfers, then transfer the last bundle to be transferred according the rule 6.
- 6. Calculate the total weight of transferable votes. If the total weight of transferable votes is greater then surplus, transfer each vote in the bundle (to the continuing candidate indicated as the next available preference) with a decreased weight,

newweight =

old weight * (surplus/total weight of transferable papers)

If the total weight of transferable votes is less than or equal to the surplus, transfer all votes in bundle with same weight as before.

7. If, at the end of any count, no candidate has reached the quota and there are more continuing candidates than vacancies, a candidate must be excluded. Working backwards from the candidates with the lowest vote weight, check can the candidate be excluded (see Section A.3). If this candidate's exclusion is allowed by RuFFE, then distribute the transferable votes, leaving the weights unchanged. If the candidate cannot be excluded (see Section A.3), check the next lowest candidate and so on. For candidates that cannot be excluded, do not exclude,



do not elect. These candidates will eventually be elected, without necessarily reaching the quota.

8. STOP when either the number of elected candidates = 13 or (more likely) the number of elected candidates + number of continuing candidates = 13. At this point all continuing candidates may be deemed to be elected.

A.3 Rule For Election or Exclusion (RuFEE)

For this rule, a candidate is seen as belonging to a subset of candidates, either elected, continuing or excluded.

A.3.1 Election

When a candidate reaches or exceeds the surplus, before deeming that candidate to be elected, it must be checked that the following condition holds:

If the candidate is elected and this brings the number elected to n, there is a subset of the continuing candidates, of size 13 - n which, if elected will ensure that the set of 13 elected candidates will obey the gender, school and department constraints.

If this is the case, then the candidate is deemed to be elected.

If this is not the case, the candidate will not be elected as his/her election will disallow the possibility of the 13 candidates including him/her ever obeying the gender, school, and department constraints. Furthermore, the candidate is excluded and his/her votes will be transferred as per rule 7 (abridged rules).

A.3.2 Exclusion

If a candidate needs to be excluded in order to proceed (there being no surplus available), starting at the lowest candidate, check that the following condition holds:

If the candidate is removed from the set of continuing candidates and placed in the set of excluded candidates, there is a subset of continuing candidates, of size 13 - n (n = the number if elected candidates) that, if elected, will ensure that the set of 13 elected will obey the gender, school and department constraints.

If this condition holds, then exclude the candidate and proceed to transfer the candidate's votes as per rule 7 (abridged rules).

Academic Council Election - Count Rules

If this condition does not hold this means that it will be necessary to elect this candidate (eventually) to ensure that the final set of elected candidates obey the gender and school constraints. Do not exclude the candidate. Do not elect the candidate. The candidate will be elected without necessarily reaching the quota.

If because of this rule, the lowest candidate cannot be excluded, proceed to find the next lowest candidate and apply the rule to check if this candidate can be excluded. If not go to the next lowest candidate and so on.

A.4 Rules for Academic Council Election (Academic Members)

- 1. The Academic Council election returning officer shall reject any ballot papers that are invalid.
- 2. The Academic Council election returning officer shall then ascertain the number of first preferences recorded on the ballot papers for each candidate, and shall then arrange the candidates on a list (hereinafter called the order of preferences) in the order of the number of first preferences recorded for each candidate, beginning with the candidate for whom the greatest number of first preferences is recorded. If the number of first preferences recorded for any two or more candidates (hereinafter called 'equal candidates') is equal, the Academic Council election returning officer shall ascertain the number of second preferences recorded on all the ballot papers for each of the equal candidates, and shall arrange the equal candidates as amongst themselves on the order of preferences in the order of the second preferences recorded for each such candidate, beginning with the candidate for whom the greatest number of second preferences is recorded. If the number of first and second preferences recorded for any two or more equal candidates is equal, the Academic Council election returning officer shall, in like manner, ascertain the number of third preferences recorded on all the ballot papers for each of such last-mentioned equal candidates, and arrange such candidates on the order of preferences accordingly, and so on until all the candidates are arranged in order on the order of preferences. If the number of first, second, third, and all other preferences recorded for any two or more equal candidates is equal the Academic Council election returning officer shall determine by lot the order in which such candidates are to be arranged on the order of

preferences.

- 3. The Academic Council election returning officer shall then arrange the valid ballot papers in parcels, according to the order of preferences.
- 4. For the purpose of facilitating the processes prescribed by these Rules, each valid ballot paper shall be deemed to be of the value of one thousand.
- 5. The Academic Council election returning officer shall then count the number of ballot papers in each parcel, and in accordance with the preceding Rule credit each candidate with the value of the valid ballot papers on which a first preference has been recorded for such candidate.
- 6. The Academic Council election returning officer shall then add together the values in all the parcels and divide the full total value by a number exceeding by one the number of vacancies to be filled. The result increased by one, any fractional remainder being disregarded, shall be the value sufficient to secure the return of a candidate. This value is in this Schedule called the 'quota'.
- 7. If, at the end of any count or at the end of the transfer of any parcel, or sub-parcel of an excluded candidate or of a candidate deemed not to be a continuing candidate, the value credited to a candidate is equal to or greater than the quota, that candidate shall, subject to the provisions of the subsequent Rules and RuFEE(Rule for Election or Exclusion), be deemed to be elected.
- 8. If at the end of any count the value credited to a candidate is greater than the quota and the election of the candidate obeys RuFEE, the surplus of the candidate(in this Rule referred to as the elected candidate) shall be transferred to the continuing candidate or candidates indicated on the voting papers in the parcel or sub-parcel of the elected candidate according to the next available preferences recorded thereon, and the following provisions shall apply to the making of such transfer:
- 9. If the value credited to the elected candidate arises out of original votes only, the Academic Council election returning officer shall examine all the ballot papers in the parcel of the elected candidate and shall arrange the transferable papers therein in sub-parcels according to the next available preferences recorded thereon and shall make a separate sub-parcel of the non-transferable papers;

- (a) If the value credited to the elected candidate arises partly out of original and partly out of transferred votes or out of transferred votes only, the Academic Council election returning officer shall examine the ballot papers contained in the sub-parcel last received by the elected candidate and shall arrange the transferable papers therein in further sub-parcels according to the next available preferences recorded thereon and shall make a separate sub-parcel of the non-transferable papers:
- (b) In either of the cases referred to in the foregoing sub-paragraphs (a) and (b) the Academic Council election returning officer shall ascertain the number of ballot papers and their total value in each sub-parcel of transferable papers and in the sub-parcel of non-transferable papers;
- (c) If the total value of the papers in all the sub-parcels of transferable papers is equal to or less than the said surplus, the Academic Council election returning officer shall transfer each sub-parcel of transferable papers to the continuing candidate indicated thereon as the voter's next available preference, each paper being transferred at the value at which it was received by the elected candidate, and where the said total value is less than the said surplus) the non-transferable papers shall be set aside as not effective. at a value which is equal to the difference between the said surplus and the said total value;
- (d) If the total value of the papers in all the sub-parcels of transferable papers is greater than the said surplus, the Academic Council election returning officer shall transfer each paper in such sub-parcel of transferable papers to the continuing candidate indicated thereon as the voter's next available preference, and the value at which each paper shall be transferred shall be ascertained by dividing the surplus by the total number of transferable papers, fractional remainders being disregarded except that the consequential loss of value shall be noted on the result sheet;
- (e) A surplus which arises on the completion of any count shall be dealt with before a surplus which arises at a subsequent count;
- (f) When two or more surpluses arise out of the same count, the largest shall be first dealt with and the others shall be dealt with in the order of their magnitude;
- (g) If two or more candidates have an equal surplus arising out of the same count, the surplus of the candidate credited with the

greatest value at the earliest count at which the values credited to those candidates were unequal shall be first dealt with, and where the values credited to such candidates were equal at all counts, the Academic Council election returning officer shall deal first with the surplus of the candidate who is highest in the order of preferences, subject to RuFEE.

- 10. (a) If at the end of any count no candidate has a surplus and one or more vacancies remain unfilled, the Academic Council election returning officer shall exclude the candidate (in this Rule referred to as the excluded candidate) then credited with the lowest value subject to RuFEE and shall transfer his/her papers to the continuing candidates respectively indicated on the ballot papers in the parcel or sub-parcels of the excluded candidate as the voter's next available preference, and shall credit such continuing candidates with the value of the papers so transferred, and the following provisions shall apply to the making of such transfer:
 - (b) The parcel containing original votes shall first be transferred, the transfer value of each paper being one thousand;
 - (c) The sub-parcels containing transferred votes shall then be transferred in the order in which and at the value of which the excluded candidate obtained them;
 - (d) For the purpose of determining whether a candidate is a continuing candidate the transfer of each parcel or sub-parcel shall be regarded as a separate count;
 - (e) In the transfer of each parcel or sub-parcel, a separate sub-parcel shall be made of the non-transferable papers which shall be set aside at the value at which the excluded candidate obtained them
 - (f) If, when a candidate has to be excluded under this Rule, two or more candidates are each then credited with the same value and are lowest regard shall be had to the total value of original votes credited to each of those candidates and the candidate with the smallest such total value shall be excluded, and where such total values are equal regard shall be had to the total value of votes credited to each of those candidates at the earliest count at which they had unequal values, and the candidates with the smallest such total value at that count shall be excluded, and if those candidates were each credited with the same total value of

votes at all counts that one of those candidates who is lowest in the order of preferences shall be excluded, subject to RuFFE.

- 11. On every transfer made under these Rules, each sub-parcel of papers transferred shall be placed on top of the parcel or sub-parcel (if any) of papers of the candidate to whom the transfer is made and that candidate shall be credited with the value ascertained in accordance with these Rules of the papers so transferred to him/her.
- (a) If at the end of any count the number of candidates deemed to be elected is equal to the number of vacancies to be filled, no further transfer shall be made.
 - (b) When at the end of any count the number of continuing candidates is equal to the number of vacancies remaining unfilled, the continuing candidates shall thereupon be deemed to be elected.
 - (c) When the last vacancies can be filled under this Rule, no further transfer shall be made.
- 13. At the end of every count the Academic Council election returning officer shall record on a result sheet in the prescribed form the total of the values credited to each candidate at the end of that count and also the value of the non-transferable papers not effective on that count and the loss of value on that count owing to disregard of fractions.
- 14. While the votes are being counted the ballot papers shall so far as it is practicable be kept face upwards and all proper precautions shall be taken by the Academic Council election returning officer for preventing the numbers on the backs of the ballot papers being seen.
- 15. (a) Any candidate or his/her agent may, at the conclusion of any count, request the Academic Council election returning officer to re-examine and recount all or any of the ballot papers dealt with during that count, and the Academic Council election returning officer shall forthwith re-examine and recount accordingly the ballot papers indicated.
 - (b) The Academic Council election returning officer may at his/her discretion recount ballot papers either once or more often in any case in which he/she is not satisfied as to the accuracy of any count.

- (c) Nothing in this Rule shall make it obligatory on the Academic Council election returning officer to recount the same parcel of ballot papers more than once.
- 16. In these Rules:
 - (a) The expression 'continuing candidate' means any candidate not deemed to be elected and not excluded;
 - (b) The expression 'first preference' means the figure '1' standing alone, the expression 'second preference' means the figure '2' standing alone in succession to the figure '1', and the expression 'third preference' means the figure '3' standing alone in succession to the figures '1' and '2' set opposite the name of any candidate, and so on;
 - (c) The expression 'next available preference' means a second or subsequent preference recorded in unique consecutive numerical order for a continuing candidate, the preference next in order on the ballot paper for candidates already deemed to be elected or excluded being ignored;
 - (d) The expression 'transferable paper' means a ballot paper on which, following a first preference, a second or subsequent preference is recorded in numerical order for a continuing candidate;
 - (e) The expression 'non-transferable paper' means a ballot paper
 - i. on which no second or subsequent preference is recorded for a continuing candidate; or
 - ii. on which the names of two or more candidates (whether continuing or not) are marked with the same number, and are next in order of preference; or
 - iii. on which the name of the candidate next in order of preference (whether continuing or not) is marked by a number not following consecutively after some other number on the voting paper or by two or more numbers; or
 - iv. which is void for uncertainty;
 - (f) the expression 'original vote' in regard to any candidate means a vote derived from a ballot paper on which a first preference is recorded for that candidate;
 - (g) The expression 'transferred vote' in regard to any candidate means a vote derived from a ballot paper on which a second or subsequent preference is recorded for that candidate;

- (h) The expression 'surplus' means the number by which the total value of the votes, original and transferred, credited to any candidate exceeds the quota;
- (i) The expression 'count' means (as the context may require) either
 - i. All the operations involved in the counting of the first preferences recorded for candidates; or
 - ii. All the operations involved in the transfer of the surplus of an elected candidate; or
 - iii. All the operations involved in the transfer of the votes of an excluded candidate; or
 - iv. The transfer in pursuance of these Rules of the papers of a candidate deemed not to be a continuing candidate;
- (j) The expression 'deemed to be elected' means deemed to be elected for the purpose of counting, but without prejudice to the declaration of the result of the election;
- (k) The expression 'determine by lot' means determine in accordance with the following directions, that is to say:

the names of the candidates concerned, having been written on similar slips of paper, and the slips having been folded so as to prevent identification and mixed and drawn at random, the candidates concerned shall as amongst themselves be arranged on the order of preferences in the order in which the slips containing their names are drawn, beginning with the candidate whose name is on the slip drawn first.

Appendix B

Z Specification of an STV electoral system, specifically Waterford Institute of Technology's Academic Council election.

B.1 Introduction

This documents contains a specification for the process of counting the votes polled in a STV electoral system. The particular system used is based largely on the rules of election for Seanad Eireann, the upper house of parliament in Ireland. These rules have been modified for use in the election of academics for the Waterford Institute of Technology's Academic Council Election. The main modification needed is to take into account the need for gender and school balance in the elected members cohort. The full set of rules are available in the document 'Academic Council Rules'.

This document breaks up the specification into a number of parts

- Global declarations
- Operations needed to pre-process voting papers this gets rid of spoiled votes, strips off any duplicates at the 'end' of the vote and produces a neater 'Ballot' which is processed.

- Operations needed to count the votes, transfer votes from elected members, eliminated, choosing next count's activities, etc. .
- System state and overall operation of count.

B.2 Global Declarations

The first basic type is that of CAND which contains the information for each candidate. This will be used as part of a more used Candidate type.

[CAND]

There must be a minimum 40% from each gender in the elected cohort. There must also be an (aspirational) minimum from each school. There must be as part of candidates information, values indicating to which gender and school candidate belongs. The following free types are declared:

GENDER ::= male | female SCHOOL ::= science | engineering | business | humanities

The schema Candidate will be used throughout the specification.

_Candidate _____ cand : CAND gender : GENDER school : SCHOOL

The process of changing what is known as 'voting papers' (input as a sequence of papers, each of which is a function from Candidate to that Candidates preference) to what are known as Ballots is described in the next section. The Ballot schema includes the preference sequence and the Ballot's value or weight.

Ballot	
$preference: ext{iseq} Candidate \ value: \mathbb{Z}$	
$-1000 \le value \le 1000$	

As it is necessary to record duplicate ballots, bags of ballots are used throughout the specification. For some operations, the finiteness of these bags are necessary, so the following is used throughout to indicate a bag of ballots:

 $finBagBallot == \{B : bag Ballot \mid dom B \in \mathbb{F} B\}$

A number of shorthand types are defined that will be used throughout the specification. The main function throughout the specification is declared as VoteMass. This is a function which links a Candidate with Bags of Ballots for each count. It resembles the physical model, where a pigeonhole structure is used and a Candidate's ballots from different counts are separated with labelled sheets. FunctBag describes each candidate's pile of ballots. The model to hold nontransferable votes, NonTransfers, is simply a pile of ballots, separated by count.

 $VoteMass == Candidate \leftrightarrow (\mathbb{N} \leftrightarrow finBagBallot)$ FunctBag == $\mathbb{N} \leftrightarrow finBagBallot$ NonTransfers == $\mathbb{N} \leftrightarrow finBagBallots$ Paper == Candidate $\leftrightarrow \mathbb{N}$

B.3 Pre-Processing of Voting Papers

It is assumed that voting papers which are the main input to the count process can be described as a function from Candidate to a natural number. The input of voting papers will be in a sequence (this is a straighforward way of modelling the physical input - if this seems that this could lead to a breach of the secretness of the poll, then this can be further examined)

These papers are pre-processed, which involves

- 1. getting rid of spoiled votes
- 2. stripping away any preferences that are non-contigous or duplicated, leaving the leading preferences intact.

For valid papers, the preference part is changed to a sequence (this is possible, because now preferences are contigious and non-duplicated). The Ballot type emcompasses this. A value (sometimes known as weight) is also associated with a Ballot.

B.3.1 Z Specification of Pre-processing

Note that we are expecting non-zero preferences. Valid preferences on a voting paper start at 1 and are unique, increasing and contiguous. We specify a function which returns the first non-unique, non-contiguous or non-existent preference. This number minus 1 is the number of valid preferences on the voting paper. All preferences between 1 and this number are valid.

$$\begin{array}{l} find_first_hole_or_dup: Paper \rightarrow \mathbb{N} \\ \hline find_first_hole_or_dup(paper) = \\ min\{n: \mathbb{N} \mid n: 1 \dots no_cands + 1 \land \#paper^{\sim}(|\{n\}|) \neq 1\} \end{array}$$

The next function takes the voting paper and returns a (valid) Ballot with invalid preferences stripped. This means that, for instance, a spoiled vote will have no valid preferences.

$$\begin{array}{l} make_ballot: Paper \rightarrow Ballot\\ \hline\\make_ballot(paper) = \\ \lhd pref \rightsquigarrow 1 \ .. \ find_first_hole_or_dup(paper) - 1 \lhd paper^{\sim},\\ value \rightsquigarrow 1000 \triangleright \end{array}$$

The following function takes a sequence of voting papers and returns a sequence of Ballots.

 $\frac{makeseqBallots: seq Paper \rightarrow seq Ballot}{makeseqBallots(seqpapers) = map make_ballot seqpapers}$

This function throws away empty ballots. These are invalid papers(or spoiled votes) that were stripped down to empty ballots.

$$throwawayempties : seq Ballot \rightarrow seq Ballot$$
$$throwawayempties(fullseq) = fullseq \upharpoonright \{b : Ballot \mid b \in ran fullseq \land \#(b.preference) > 0 \bullet b\}$$

The following function takes in the sequence of voting papers and produces a bag of preprocessed ballots. As a sequence is finite, then items returns a finite bag of Ballots. We call this type finBagBallot.

 $\begin{array}{l} pre_process: seq \ Paper \rightarrow finBagBallot\\ \hline\\pre_process(seqpapers) =\\ items(throwawayempties(makeseqBallots(seqpapers))) \end{array}$

Note that the following definition of map is assumed:

$$\begin{array}{|c|c|c|c|c|c|} map: (X \to Y \times seq \ X) \to seq \ Y \\ \hline map \ f \ s = \{n: 1 \dots \#s \bullet n \mapsto f(s(n))\} \end{array}$$

Back to old stuff

This can be called as $Ballots = pre_process(Allpapers?)$ where allpapers is an input which is a sequence of the unprocessed papers.

It may be necessary to record the spoiled votes in certain circumstances.

 $\begin{array}{l} spoiled_votes : seq \ Paper \rightarrow seq Paper \\ \hline \forall \ all papers : seq \ Paper \bullet \\ spoiled_votes(all papers) = \\ all papers \\ \left\{ paper : \ Paper \mid \ find_first_hole_or_dup(paper) = 1 \end{array} \right\}$

B.4 Counting of Ballots

This section deals with the operations to transfer votes, choose next candidate to deal with etc. These operations will be used in the final section in the schema operation count.

There are some standard bag functions that will be needed to deal with bags of ballots.

bagvalue will used to calculate the total value of a bag of ballots.

 $bagvalue : finBagBallot \rightarrow \mathbb{N}$ bagvalue[]] = 0 $\forall b : Ballot; n : \mathbb{N}_1 \bullet$ $bagvalue \{b \mapsto n\} = b.value * n$ $\forall B1, B2 : finBagBallot \bullet$ $bagvalue(B1 \uplus B2) = bagvalueB1 + bagvalueB2$

bagrange is a bag union generic function that takes a function from some generic type to a bag of ballots and returns a bagunion of the the range of the function.

 $\begin{array}{c} = [X] \\ \hline bagrange : (X \implies finBagBallot) \implies finBagBallot \\ \hline bagrange = \llbracket \\ \forall x : X; B : finBagBallot \bullet \\ bagrange\{x \mapsto B\} = B \\ \forall f, g : X \implies finBagBallot \mid disjoint \langle \operatorname{dom} f, \operatorname{dom} g \rangle \bullet \\ bagrange(f \cup g) = (bagrange f) \uplus (bagrange g) \end{array}$

The next stage is building up the operations for counting the ballots. To count the total number of valid votes, totalcount is used.

 $\begin{array}{l} totalCount : finBagBallots \rightarrow \mathbb{N} \\ \hline \\ \forall Ballots : finBagBallots \bullet \\ totalCount(Ballots) = bagvalue \ Ballots \end{array}$

When counting votes, we need to total a candidates Ballots:

 $totalvaloffunct : (FunctBag \times \mathbb{N}) \to \mathbb{N}$ $\forall countno : \mathbb{N}; candfunct : FunctBag \bullet$ totalvaloffunct(candfunct, countno) = $bagvalue(bagrange(1 .. countno) \lhd candfunct)$

A function is required to calculate the total weight of candidates at a given count. This value, when added to non-transferables and loss of weight is constant for each count because votes and values of votes are travelling around within the 'count mass' and do not leak.

 $\begin{array}{l} totalweight of Candidates: (\mathbb{N} \times VoteMass \times \mathbb{P} \ Candidate) \rightarrow \mathbb{Z} \\ \hline \forall \ count: \mathbb{N}; \ vm: VoteMass; \ ; \ c: \ Candidate \bullet \\ totalweight of Candidates(count, vm,) = 0 \\ \forall \ count: \mathbb{N}; \ vm: VoteMass; \ c: \ Candidate \bullet \\ totalweight of Candidates(count, vm, \{c\}) = \\ totalvaloffunct(vm \ c, \ count) \\ \forall \ count: \mathbb{N}; \ vm: \ VoteMass; \ S1, S2: \mathbb{P} \ Candidate \bullet \\ totalweight of Candidates(count, vm, S1 \cup S2) = \\ totalweight of Candidates(count, vm, S1) + \\ totalweight of Candidates(count, vm, S2) \end{array}$

weightatcount totals the weight of transferred ballots and non-transferables at this count, i.e. the traffic at a particular count. Note that this does not

include 'loss of value' (value lost due to remainders). This will be calculated in an invariant by stating that weight at each count + loss of value = 0.

$$\begin{array}{l} weight at count : (\mathbb{N} \times VoteMass \times FunctBag) \rightarrow \mathbb{Z} \\ \hline \forall \ count : \mathbb{N}; \ vm : VoteMass; \ nontrans : FunctBag \bullet \\ weight at count(count, vm, nontrans) = \\ bagvalue \ bagrange\{c : Candidate \mid c \in \operatorname{dom} vm \land \\ count \in \operatorname{dom}(vm \ c) \bullet vm \ c \ count\} \\ + bagvalue(nontrans \ count) \end{array}$$

findquota calculates the quota which is the minimum number of votes a candidate must have (normally) to be elected. (A candidate may in certain circumstances be elected without reaching the quota).

 $\begin{array}{l} findquota: finBagBallot \times \mathbb{N} \to \mathbb{N} \\ \hline \forall Ballots: finBagBallot; \ no_seats: \mathbb{N} \bullet \\ findquota(Ballots, no_Seats) = \\ (totalcount(Ballots) \ div \ (no_seats + 1)) + 1 \end{array}$

In the W.I.T. Academic Council election, there are gender and school constraints (see Rules of Election). Briefly, this means that there must be at least 40% of each gender (this currently translates to 5 out of 12) and a minimum (currently 2 out of 12) from each of the four schools. The gender minimums are statutory and it is assumed that on embarking on a count that the condition holds that there are at least the minimum number of candidates from each gender running for election. (In practice, it is the duty of the returning officer to ensure that this is the case and the election process cannot take place until the matter is resolved).

Whereas the gender minimums are statutory, the school balance are more aspirational. Under the condition that there are not sufficient candidates to satisfy the school minimum as laid down in minSchool?, the minimum becomes the number of candidates available. The following functions calculate the minimum number from each school to be used for checking the school balance later.

 $\mathit{findsciencemin}: \mathbb{P} \mathit{Candidate} \times \mathbb{N} \to \mathbb{N}$

 $\begin{array}{l} \forall \ AllCandidates: \mathbb{P} \ Candidate; \ minschool: \mathbb{N} \bullet \\ findsciencemin(AllCandidates, minschool) = \\ min(\#\{c: \ Candidate \mid c \in AllCandidates \land c.school = science\}, \\ minschool) \end{array}$

 $\begin{array}{l} findbusinessmin: \mathbb{P} \ Candidate \times \mathbb{N} \to \mathbb{N} \\ \hline \forall \ AllCandidates: \mathbb{P} \ Candidate; \ minschool: \mathbb{N} \bullet \\ findbusinessmin(AllCandidates, minschool) = \\ min(\#\{c: \ Candidate \mid c \in AllCandidates \wedge c.school = business\} \\ , minschool) \end{array}$

findengineeringmin : \mathbb{P} Candidate $\times \mathbb{N} \to \mathbb{N}$

 $\forall AllCandidates : \mathbb{P} Candidate; minschool : \mathbb{N} \bullet$ findengineeringmin(AllCandidates, minschool) = min(#{c : Candidate | c \in AllCandidates \land c.school = engineering}, minschool)

findhumanitiesmin : \mathbb{P} Candidate $\times \mathbb{N} \to \mathbb{N}$

 $\begin{array}{l} \forall \ AllCandidates : \mathbb{P} \ Candidate; \ minschool : \mathbb{N} \bullet \\ findhumanitiesmin(AllCandidates, minschool) = \\ min(\#\{c: \ Candidate \ | \ c \in \ AllCandidates \land \ c.school = \ humanities\}, \\ minschool) \end{array}$

We now define the function to check the gender balance. This will be called e.g.

 $(continuing, elected) \in GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates)$

The gender and school constraints are ensured as follows: Before a candidate is elected or eliminated the following check is made: Is there a subset of continuing candidates, when added to the already elected candidates will make up a cohort of size no_seats so that the cohort obeys the gender and school constraints. When eliminating a candidate, the candidate could be needed, e.g. the Candidate could be one of only two candidates from a particular school (where 2 is the minimum form each school). Election of a particular candidate could make it impossible to achieve this balance (e.g. if the minimum from each gender is 5 out of 12 candidates, if the system elects the eight candidate from either gender this will destroy any possiblilty of being able to achieve the balance.)

 $GenandSchoolBalanced : (\mathbb{N} \times \mathbb{N} \times \mathbb{N} \times \mathbb{P} Candidate) \rightarrow$ $\mathbb{P}(\mathbb{P} \ Candidate \times \mathbb{P} \ Candidate)$ \forall mingen, minschool, no_seats : \mathbb{N} ; AllCandidates : \mathbb{P} Candidate • $GenandSchoolBalanced(mingen, minschool, no_seats, Candidates) =$ $\{ continuing, elected : \mathbb{P} Candidate \mid$ $continuing \subset AllCandidates \land$ $elected \subseteq AllCandidates \land disjoint \langle elected, continuing \rangle \land$ $#elected + #continuing = no_seats \land$ $\#\{c: Candidate \mid c \in AllCandidates \land c.gender = male \bullet c\} \geq$ mingen \land $\#\{c: Candidate \mid c \in AllCandidates \land c.gender = female \bullet c\} \geq$ mingen \wedge $\#\{c: Candidate \mid c \in AllCandidates \land c.school = science \bullet c\} \ge$ findsciencemin(AllCandidates, minschool) \land $\#\{c: Candidate \mid c \in AllCandidates \land c.school = business \bullet c\} >$ $findbusinessmin(AllCandidates, minschool) \land$ $\#\{c : Candidate \mid c \in AllCandidates \land c.school = engineering \bullet c\} \geq$ findengineeringmin(AllCandidates, minschool) \land $\#\{c : Candidate \mid c \in AllCandidates \land c.school = humanities \bullet c\} \geq$ $findhumanitiesmin(AllCandidates, minschool) \bullet$ (continuing, elected)}

To order continuing candidates, we follow the rules as specified in the rules for ordering(see Election Rules). If two candidates are tied when all tests are carried out, i.e. they have equal number of first preferences, second preferences etc., then the order is imposed randomly or, as described, by 'drawing by lot'. This is specified by defining a sequence whose range is the set of elements who need to be ordered.

 $\begin{array}{l} draw_by_lot: \mathbb{P} \mathbb{N} \leftrightarrow \operatorname{seq} \mathbb{N} \\ \hline \forall setof cands: \mathbb{P} \mathbb{N} \mid \\ \exists sx: \operatorname{seq} \mathbb{N} \mid \operatorname{ran} sx = setof cands \wedge \# setof cands = \# sx \bullet \\ draw_by_lot(setof cands) = sx \end{array}$

A function is defined to take in a votemass, the current count and the set of candidates to be ordered and returns the sequence of candidates in

order. The set of candidates are assumed to be continuing as a different ordering is needed on elected candidates.

Inorder : (VoteMass $\times \mathbb{N} \times \mathbb{P}$ Candidate) \rightarrow seq Candidate $\forall vm : VoteMass; count : \mathbb{N}; setcands : \mathbb{P} Candidate$ \exists orderedseq : seq Candidate | ran orderedseq = setcands • $\forall i, j : \text{dom orderedseg} \mid i < j \bullet$ ((totalvaloffunct(vm orderedseq i, count) > $totalvaloffunct(vm \ orderedseq \ j, count)) \lor$ (totalvaloffunct(vm orderedseg i, count) = $totalvaloffunct(vm orderedseq j, count) \land$ $((\exists c : \mathbb{N} \mid 1 \dots count \bullet))$ totalvaloffunct(vm orderedseq i, c) > $totalvaloffunct(vm \ orderedseq \ j, c) \land$ $\forall ic: c+1 \dots count \bullet$ totalvaloffunct(vm orderedseq i, ic) = $totalvaloffunct(vm \ orderedseq \ j, ic)) \lor$ $(\forall c: 1 \dots count \bullet)$ totalvaloffunct(vm orderedseg i, c) = $totalvaloffunct(vm \ orderedseq \ j, c) \land$ $drawbylot(\{i, j\}) = \langle i, j \rangle)))) \bullet$ Inorder(vm, count, seteands) = orderedseq

A candidate is deemed to be elected at the earliest possible opportunity, i.e. at the first count which the candidates combined value of ballots is over or equal to the quota. At this point it can be decided whether the candidate should be elected or eliminated, depending on the gender and school constraints. It is necessary to know the number of the count when the candidate reached the quota for the first time.

 $\begin{array}{l} \textit{firstcountover}: (\textit{VoteMass} \times \textit{Candidate} \times \textit{finBagBallots} \times \mathbb{N}) \rightarrow \mathbb{N} \\ \hline \forall \textit{vm}:\textit{VoteMass}; \textit{cand}:\textit{Candidate}; \textit{Ballots}:\textit{FinBagBallots}; \\ \textit{no_seats}:\mathbb{N} \mid \\ \exists n:\mathbb{N} \bullet \\ \textit{totalvaloffunct}(\textit{vm} \textit{cand}, n-1) < \textit{findquota}(\textit{Ballots}, \textit{no_seats}) \land \\ \textit{totalvaloffunct}(\textit{vm} \textit{cand}, n) \geq \textit{findquota}(\textit{Ballots}, \textit{no_seats}) \bullet \\ \textit{firstcountover}(\textit{vm}, \textit{cand}, \textit{Ballots}, \textit{no_seats}) = n \end{array}$

When deciding which candidate to process next, if there are a number of candidates who have reached the quota, *getnextoverquota* returns that candidate.

getnextoverquota: $(VoteMass \times \mathbb{N} \times \mathbb{P} Candidate \times finBagBallots \times \mathbb{N} \times \mathbb{N} \times \mathbb{N})$ \rightarrow Candidate $\forall vm : VoteMass; count : \mathbb{N}; Ballots : finBagBallots; no_seats : \mathbb{N}$ \exists overegguota : \mathbb{P} Candidate; sequeregguota : seqCandidate | $overquota = \{c : Candidate \mid$ $c \notin dealtwith(vm, count - 1, AllCandidates, Ballots,$ $no_seats, mingen, minschool)) \land$ $totalvaloffunct(vm \ c, count) \geq$ $findquota(Ballots, no_seats)\} \land$ ran seqovereqquota = overeqquota \wedge $\forall i, j : \text{dom sequereq quota} \mid i < j \bullet$ (firstcountover(vm, sequerequota i, Ballots, no_seats) < $first count over(vm, sequence quota j, Ballots, no_seats)) \lor$ $(first count over(vm, sequence quota i, Ballots, no_seats) =$ $first count over(vm, sequence quota j, Ballots, no_seats)) \land$ $\exists prevcontseq : seqCandidate \mid$ prevcontseq = Inorder(vm,firstcountover(vm, sequerequota i, $Ballots, no_seats) - 1,$ $overequota) \bullet$ $prevcontseq^{(sequerequota i)} <$ $prevcontseq^{(seqoverequota j))}$ • getnextoverquota(vm, count, Ballots, AllCandidates, $no_seats, mingen, minschool) =$ head sequerequota

If there are no candidates over quota to be dealt with, the next option is to find the next suitable candidate for elimination. The lowest candidate in the order of continuing candidates is the first to be checked (gender and school balance wise), next lowest and so on until the first lowest candidate is found to obey the school and gender balance checks.

 $getnexttoexclude : \mathbb{P} Candidate \times VoteMass \times$ $\mathbb{N} \times \mathbb{P}$ Candidates $\times \mathbb{N} \times \mathbb{N} \times \mathbb{N}$ \rightarrow Candidate \forall continuing, AllCandidates : \mathbb{P} Candidateslvm : VoteMass; *count*, *mingen*, *minschool*, *no_seats* : \mathbb{N} | $\exists contseq : seq Candidate; pos : 1 . . #contseq |$ ran contseq = continuing \wedge $contseq = Inorder(vm, count, contseq) \land$ $(continuing \setminus \{contseq \ pos\},\$ ran electedseq(vm, count, AllCandidates, mingen, minschool, no_seats)) \in $GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates) \land$ $\neg \exists opos : pos + 1 \dots \# contseq \bullet$ $(continuing \setminus \{contseg opos\},\$ ran electedseq(vm, count, AllCandidates, mingen, minschool, no_seats)) \in GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates) • getnexttoexclude(continuing, vm, count, AllCandidates, $mingen, minschool, no_seats) =$ conseq pos

A list of candidates who have been processed (on at each count) is needed at certain stages in the specification. *dealtwith* produces a set of such candidates. It calls *findnextcand* which itself calls *dealtwith* but on an earlier count.

 $\begin{array}{l} dealtwith: (VoteMass \times \mathbb{N} \times \mathbb{P} \ Candidate \times finBagBallot \times \mathbb{N} \times \mathbb{N} \times \mathbb{N}) \\ & \rightarrow \mathbb{P} \ Candidate \\ \hline \forall vm: VoteMass; \ count: \mathbb{N}; \ AllCandidates: \mathbb{P} \ Candidate; \\ Ballots: finBagBallots; \ no_seats, mingen, minschool: \mathbb{N} \mid \\ \exists \ dealtw: \mathbb{P} \ Candidate \mid \\ & \forall i: 1 \dots count \bullet \\ findnextcand(vm, i, ran \ contseq(vm, \ count, AllCandidates), \\ & \ AllCandidates, Ballots, \ no_seats, \ mingen, \ minschool) \in \\ & \ dealtw \land \\ & \# \ dealtw = \ count \bullet \\ & \ dealtwith(vm, \ count, AllCandidates, Ballots, \ no_seats, \\ & \ mingen, \ minschool)) = \\ & \ dealtw \end{array}$

findnextcand decides which is the next appropriate action, elect or eliminate a candidate and calls the appropriate operations.

findnextcand: (VoteMass $\times \mathbb{N} \times \mathbb{P}$ Candidate \times finBagBallots \times $\mathbb{N} \times \mathbb{N} \times \mathbb{N}$ \rightarrow Candidate $\forall vm : VoteMass; count : \mathbb{N}; AllCandidates : \mathbb{P} Candidate;$ Ballots : finBagBallots; $no_seats, mingen, minschool : \mathbb{N} \bullet$ findnextcand(vm, count, AllCandidates, Ballots, no_seats, mingen, minschool) =if $\{c: Candidate \mid totalvaloffunct(vm \ c, count) >$ findquota(no_seats, Ballots)} $\langle dealtwith(vm, count - 1, etc) \neq$ getnextoverquota(vm, count, AllCandidates, Ballots, *no_seats*, *mingen*, *minschool*) elsegetnexttoexcude(vm, count, AllCandidates, Ballots, no_seats, mingen, minschool)

To find a candidate's surplus, the quota and candidates present vote is needed.

 $\begin{array}{l} find surplus: VoteMass \times Candidate \times finBagBallots \times \mathbb{N} \twoheadrightarrow \mathbb{N} \\ \forall vm: VoteMass; \ cand: Candidate; \ Ballots: finBagBallots; \\ no_seats: \mathbb{N} \bullet \\ find surplus(vm, cand, Ballots, no_seats) = \\ let \ totalvote = \ totalvaloffunct(vm \ max \ dom \ vm \ cand); \\ quota = \ find quota(Ballots, no_seats) \\ in \ totalvote - \ quota \\ end \end{array}$

A function is needed to return the next preference candidate on a Ballot. This candidate must be a continuing candidate. There may be no such candidate (in this case the Ballot is deemed to be non-transferable). Note that the preference part of the Ballot is injective.

 $\begin{array}{l} nextpref: (Ballot \times Candidate \times \mathbb{P} \ Candidate) \leftrightarrow Candidate \\ \hline \forall \ b: Ballot; \ currcand : Candidate; \ continuing : \mathbb{P} \ Candidate \ | \\ \#(((b.preference^{(currcand)} \dots \# b.preference) \ b.preference) \ | \\ continuing) > 0 \bullet \\ nextpref(b, \ currcand, \ continuing) = \\ head(((b.preference^{(currcand)} \dots \# b.preference) \\ \ | \ b.preference) \ | \ continuing) \end{array}$

When a candidate's ballots are being transferred, it is always the last set of ballots(only), modelled as a bag of ballots, that was assigned to the candidate that is transferred. To prepare for this, the following function takes the bag of ballots last assigned to the current candidate and returns a function from Candidate to a bag of ballots where this function defines where each ballot should transfer to, if that place exists. The value of each Ballot is not changed here.

 $\begin{array}{l} preparetransbag: finBagBallots \times Candidate \times \mathbb{P} \ Candidate \\ & \rightarrow (Candidate \rightarrow finBagBallots) \\ \hline \\ \forall \ lastbag: finBagBallots; \ currcand: Candidate; \\ continuing: \mathbb{P} \ Candidate \ | \\ \exists \ candwithbags: \ Candidate \rightarrow finBagBallots \bullet \\ & \forall \ b: \ Ballot; \ n: \mathbb{N} \ | \\ & b \mapsto n \in lastbag \land \\ & (b, \ currcand, \ continuing) \in dom \ nextpref \bullet \\ & b \mapsto n \in \ candwithbagscurrcandnextpref \ (b, \ currcand, \ continuing) \bullet \\ & preparetransbag(lastbag, \ currcand, \ continuing) = \ candwithbags \end{array}$

For transferring purposes, it is handy to have a function that returns the bag of ballots which is non-transferable, given the current set of continuing candidates.

```
\begin{array}{l} \textit{nontransferables}: \textit{finBagBallots} \times \textit{Candidate} \times \mathbb{P} \textit{ Candidate} \rightarrow \\ \textit{finBagBallots} \\ \hline \forall \textit{lastbag}: \textit{finBagBallots}; \textit{ currcand}: \textit{Candidate}; \\ \textit{continuing}: \mathbb{P} \textit{Candidate} \mid \\ \exists \textit{nontransfers}: \textit{finBagBallots} \mid \\ \forall \textit{b}: \textit{Ballot}; \textit{n}: \mathbb{N} \mid \\ & b \mapsto n \in \textit{lastbag} \land \\ & (\textit{b}, \textit{currcand}, \textit{continuing}) \notin \textit{dom} \textit{nextpref} \bullet \\ & b \mapsto n \in \textit{nontransfers} \bullet \\ & \textit{nontransferables(lastbag}, \textit{currcand}, \textit{continuing}) = \textit{nontransfers} \\ \end{array}
```

The following function returns the bag of ballots to be transferred. This will be used for calculation of transferweight.

 $\begin{aligned} transferables : finBagBallots \times Candidate &\times \mathbb{P} \ Candidate \to \\ finBagBallots \\ \hline \forall \ lastbag : finBagBallots; \ currcand : Candidate; \\ continuing : \mathbb{P} \ Candidate \mid \\ \exists \ transfers : finBagBallots \mid \\ \forall \ b : Ballot; \ n : \mathbb{N} \mid \\ b \mapsto n \in \ lastbag \land \\ (b, \ currcand, \ continuing) \in \ dom \ nextpref \bullet \\ b \mapsto n \in \ transfers \bullet \\ transferables(\ lastbag, \ currcand, \ continuing) = \ transfers \end{aligned}$

Throughout the transfer process, it is often necessary to change the values of each ballot in a bag of ballots by a given factor. The following function effects this change.

```
\begin{array}{l} changeweight: finBagBallot \times \mathbb{N} \leftrightarrow finBagBallots \\ \forall \ bag: finBagBallots; \ factor: \mathbb{N} \mid \\ \exists \ changedbag: finBagBallots \mid \\ \forall \ b: Ballot; \ n: \mathbb{N} \mid b \mapsto n \in bag \bullet \\ \exists \ b': Ballot \bullet \\ b'.value = \ b.value * factor \land \\ b'.preference = \ b.preference \bullet \\ b' \mapsto n \in changebag \bullet \\ changeweight(bag, factor) = changedbag \end{array}
```

The following function transfers the ballots last received by the candidate. The weight of transferred votes depends primarily on whether nontransferables need to be dealt with. Non-transferables may need to be 'partially' transferred. The elected candidate should be left with a weight exactly equal to the quota. This means that the candidates receiving ballots will get ballots with a fraction of the weight of the original ballot. The transfer weight is defined below.

transferelected : $(Candidate \times VoteMass \times NonTransfers \times \mathbb{N} \times$ $finBagBallots \times \mathbb{N} \times \mathbb{P}$ Candidate) \rightarrow (VoteMass \times NonTransfers) let $lastbag == vm \ currcand \ max(dom vm \ currcand);$ transferbag == preparetransbag(lastbag, currcand, continuing);weighted transferbag =changeweight(transferbag, surplus div transferablevalue); $surplus == findsurplus(vm, currcand, Ballots, no_seats);$ transferable = transferables(lastbag, currcand, continuing);transferable value == bagvalue(transferables);nontransferables == nontransferables(lastbag, currcand, continuing);nontransaway =changeweight(nontransferables, (-1 * (surplus - transferable))divbaqvalue(nontransferables))); nontranstont = changeweight(nontransaway, -1);transnont =changeweight(transferables, ((surplus * -1) div transferablevalue));transisnt = changeweight(transferables, -1)in \forall currcand : Candidate; vm : VoteMass; nt : NonTransfers; count : \mathbb{N} ; $Ballots: fin BagBallots; no_seats: \mathbb{N}; continuing: \mathbb{P} Candidate$ $\exists vm' : VoteMass; nt' : NonTransfers \bullet$ (let transferbag' if surplus < transferable= weighted transferbagelse = transferbagin $\forall c : Candidate \mid c \in \text{dom transferbag}$ $vm' \ c = vm \ c \cup \{count \mapsto transferbag' \ c\}$ end) \wedge $\{c : Candidate \mid c \in \text{dom transferbag}\} \cup \{currcand\} \triangleleft vm' =$ $\{c: Candidate \mid c \in \text{dom transferbag}\} \cup$ $\{currcand\} \triangleleft vm \land$ $((surplus \geq transferablevalue \land$ $vm' \ currcand = vm \ currcand \cup \{count \mapsto transnont\} \land$ $nt = nt') \lor$ (surplus < transferable value \wedge $vm' \ currcand = vm \ currcand \cup \{count \mapsto (transisnt \uplus nontransaway)\}$ $nt' = nt \cup \{count \mapsto nontranstont\})$ $transferelected(currcand, vm, nt, count, Ballots, no_seats, continuing) =$ (vm', nt')end

When a candidate is eliminated, the ballots are transferred to the next preference candidate, if they exist, or to non-transferables. The weights of the ballots remain the same as the eliminated candidates total will be 0 at the end of the operation.

 $transfereliminated: (Candidate \times VoteMass \times NonTransfers \times$ $\mathbb{N} \times \mathbb{P}$ Candidiate) \rightarrow (VoteMass, NonTransfers) let $lastbag = vm \ currcands \ max(dom \ vm \ currcand);$ transferbag = preparetransbag(lastbag, currcand, continuing);in \forall currcand : Candidate; vm : VoteMass; nt : NonTransfers; count : \mathbb{N} ; $continuing: \mathbb{P} Candidate$ $\exists vm': VoteMass, nt': NonTransfers |$ $(\forall c : Candidate \mid c \in \text{dom transferbag} \bullet$ $vm' \ c = vm \ c \cup \{count \mapsto transferbag \ c\} \land$ $\forall c : Candidate \mid c \notin \text{dom transferbag} \cup \{currcand\} \bullet$ $vm' c = vm c \wedge$ vm' curreand = vm curreand \cup $\{count \mapsto changeweight(vm \ currcand(count - 1), -1)\} \land$ $((nontransferables(lastbag, currcand, continuing) \neq)$ \wedge nt' = nt \cup {count \mapsto nontransferables}) \vee $(nontransferables(lastbag, currcand, continuing) =) \land nt' = nt))) \bullet$ transfereliminated(currcand, vm, nt, count, continuing) = (vm', nt')

The next function returns the sequence of elected candidates, at a particular count.

```
electedseq: VoteMass \times \mathbb{N} \times \mathbb{P} \ Candidate \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \rightarrow
            seq Candidate
\forall vm : VoteMass; count : \mathbb{N}; AllCandidates : \mathbb{P} Candidate;
      mingen : \mathbb{N}; minschool : \mathbb{N}; no_seats : \mathbb{N}
\exists dealtwithoverquota, elected dealtwith, overquotanot dw,
      tobeelected : seq Candidate |
      dealtwith over quota =
                 squash\{c: Candidate; cnt: \mathbb{N} \mid cnt: 1... count - 1 \land
                 findnextcand(vm, cnt) = c \land
                 totalvaloffunct(vm \ c, cnt) \ge findquota(Ballots, no\_seats) \bullet
                  cnt \mapsto c
     ran elected dealt with \subseteq ran dealt with overquota \land
     elected dealtwith = dealtwith overquota \upharpoonright ranelected dealtwith \land
     (\forall i: 1 \dots \# elected dealt with \bullet
           (AllCandidates)
     dealtwith(vm, i - 1, AllCandidates, Ballots, no_seats, mingen, minschool),
           ran(1 .. \triangleleft electeddealtwith))
     \in GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates) \land
     \neg \exists other cans : \mathbb{P} Candidate \mid
           othercands \subseteq (ran dealtwithoverquota \setminus ran elected dealtwith) \wedge
           \#othercands > 0 \bullet
           \exists oseq : seq Candidate \mid ran oseq = ran elected dealt with \cup other cands \bullet
           \forall i:1.. \# oseq \bullet
           (AllCandidates \setminus
     dealtwith(vm, i - 1, AllCandidates, Ballots, no_seats, mingen, minschool)
     ran(1 \dots i \triangleleft electeddealtwith))
     \in GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates) \land
     ran overquotanotdw \cap dealtwith(vm, count, AllCandidates, Ballots,
                 no\_seats, mingen, minschool) = \land
     \forall c : ranoverguotanotdw \bullet
           totalvaloffunct(vm \ c, count) \geq findquota(Ballots, no\_seats) \land
     overquotanotdw =
          Inorder(vm, count, AllCandidates\
                dealtwith(vm, count - 1, AllCandidates, Ballots,
    no\_seats, mingen, minschool)) \land
    ran tobeelected \subseteq overquotanotdw \land
    tobe elected = over quotanot dw \upharpoonright ran to be elected \land
    \forall i:1 \dots \# to be elected \bullet
          (AllCandidates \setminus
          dealtwith((vm, i, AllCandidates, Ballots, no_seats, mingen, minschool),
    ran elected dealtwith \cup ran(1 \dots i \triangleleft tobe elected)) \in
          GenandSchoolBalanced(minschool, mingen, no\_seats, AllCandidates) \land
    \neg \exists more : \mathbb{P} Candidate \mid more \subseteq ran overquotanotdw \setminus ran to be elected \land
                #more > 0 \bullet
    \exists oseq : seq Candidatd \mid ran oseq = ran to be elected \cup more \bullet
```

A function is defined to order continuing candidates at a particular count:

 $\begin{array}{l} contseq: VoteMass \times \mathbb{N} \times \mathbb{P} \ Candidate \rightarrow seq \ Candidate \\ \hline \forall vm: VoteMass, count: \mathbb{N}; \ AllCandidates : \mathbb{P} \ Candidates \ | \\ \exists \ continuing: \mathbb{P} \ Candidates; \ cseq: seq \ Candidates \ | \\ continuing = \ AllCandidates \ | \\ \{c: \ Candidate; \ cnt: 1 \dots count - 1 \ | \\ c = \ findnextcand(vm, cnt, AllCandidates, Ballots, \\ no_seats, mingen, minschool) \bullet c \ | \\ \cup \{c: \ Candidate \ | \\ totalvaloffunct(vm \ c, count) \ge \\ findquota(Ballots, no_seats) \ | \\ contseq(vm, count, Ballots, no_seats) = cseq \end{array}$

The following function chooses the next candidate to deal with and either elects (and transfers) or eliminates (and transfers).

```
electoreliminate: (Candidate \times VoteMass \times NonTransfers \times \mathbb{N} \times
     \mathbb{P} \ Candidate \times finBagBallot \times \mathbb{N} \times \mathbb{N} \times \mathbb{N}) \rightarrow
           (VoteMass \times NonTransfers)
\forall cand : Candidate; vm : VoteMass; nt : NonTransfers; count : \mathbb{N};
      AllCandidates : \mathbb{P} Candidate; Ballots : finBagBallots;
     mingen, minschool, no\_seats : \mathbb{N}
let continuing = ran contseq(vm, count, AllCandidates);
     elected = ran electedseq(vm, count, AllCandidates, Ballots,
           mingen, minschool, no_seats)
in
(vm', nt') =
     if
     ((continuing))
\{cand\}, elected \cup \{cand\}\} \in
     GenandSchoolBalanced(mingen, minschool, no_seats, AllCandidates) \land
     totalvaloffunct(vm \ cand, count) \ge findquota(Ballots, no\_seats))
     then
          transferelected(cand, vm, nt, count, Ballots, no_seats, continuing)
     else
          transfereliminated(cand, vm, nt, count, Ballots, no_seats, continuing)
end
```

The election count process will terminate if

- 1. The number of elected candidates is equal to the number of seats to be filled.
- 2. The number of elected candidates + the number of continuing candidated is equal to the number of number of seats to be filled.

The following function take as input the number of seats to be filled and returns each possible set of pairs of (elected, continuing) sets of candidates which will lead to termination of the process.

 $\begin{array}{l} finished: \mathbb{N} \to \mathbb{P}(\mathbb{P} \ Candidate \times \mathbb{P} \ Candidate) \\ \hline \forall \ no_seats: \mathbb{N} \bullet \\ finished(no_seats) = \\ \{selected, scont: \mathbb{P} \ Candidate \mid \\ \#selected = no_seats \bullet (selected, scont) \} \\ \cup \\ \{selected, scont: \mathbb{P} \ Candidate \mid \\ \#scont + \#selected = no_seats \bullet (selected, scont) \} \end{array}$

This function recursively calls itself until the count is finished, i.e. as defined above.

 $election_count$: ($VoteMass \times NonTransfers \times \mathbb{N} \times$ $finBaqBallots \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times \mathbb{P} \ Candidate) \rightarrow$ $(VoteMass \times NonTransfers)$ $\forall vm : VoteMass; nt : NonTransfers; i : \mathbb{N}, Ballots : finBagBallots;$ mingen, minschool, no_seats : \mathbb{N} ; AllCandidates : \mathbb{P} Candidate • election_count(vm, nt, i, Ballots, mingen, minschool, no_seats, AllCandidates) let continuing == ran contseq(vm, i, AllCandidates); $elected == ran \ elected \ seq(vm, i, AllCandidates, Ballots,$ mingen, minschool, no_seats); next cand == findnext cand()in $if(elected, continuing) \in finished(no_seats)$ else let(vm', nt') =electoreliminate (findnextcand (vm, i, AllCandidates, Ballots, no_seats, mingen, minschool), vm, nt, i, AllCandidates, Ballots, mingen, minschool, no_seats) in $election_count(vm', nt', i + 1, Ballots, mingen, minschool,$ *no_seats*, *AllCandidates*)

This will be called as

 $(votemass!, non_transferables!) = election_count(setupfirstcount(Ballots), 2)$

setupfirstcount takes the pre-processed ballots and 'deals them out' according to their first preferences. No weight change is needed.

 $\begin{array}{l} setup first count : fin Bag Ballots \times \mathbb{P} \ Candidate \rightarrow Vote Mass \\ \hline \forall Ballots : fin Bag Ballots; \ All Candidates \mid \\ \exists vm' : Vote Mass \mid \\ \forall b : Ballot; \ n : \mathbb{N} \mid b \mapsto n \in Ballots \bullet \\ \exists_1 \ c : \ Candidate \mid c \in All Candidates \land head \ b.preference = c \bullet \\ b \mapsto n \in vm' \ c \ 1 \bullet \\ setup first count (Ballots, All Candidates) = vm' \end{array}$

B.5 Count Operation

Finally, the operation for counting is defined.

```
Count.
 VotingPapers? : seq(Candidate \rightarrow \mathbb{N})
 AllCandidates? : \mathbb{P} Candidate
mingen?, minschool, no\_seats : \mathbb{N}
Ballots! : finBagBallots
votemass!: VoteMass
non\_transferables!: Non Transfers
loss\_of\_value : \mathbb{N} \to \mathbb{N}
segelected! : seq Candidate
elected! : \mathbb{P} Candidate
spoiled\_votes! : seq(Candidate \rightarrow \mathbb{N})
Ballots! = pre_process(VotingPapers?)
(votemass!, non_transferables!) =
      election_count(setupfirstcount(Ballots!, AllCandidates!), 2,
      Ballots!, mingen?, minschool?, no_seats)
spoiled_votes! = spoiledvotes(VotingPapers?)
sequence d! = electdseq(votemass!, max(dom{c : Candidate})
                            c \in \text{dom } votemass! \bullet
                 votemass!})
           , AllCandidates?, Ballots!, mingen?, minschool?, no_seats)
\forall i: 1 \dots max \operatorname{dom} \{ c: Candidate \mid c \in \operatorname{dom} votemass! \bullet votemass! c \} \bullet
     weightatcount(i, votemass!, AllCandidates?)
     +loss_of_value \ i=0
```

Appendix C

Laws used in Refinement Calculus Example

The following laws are adapted from Morgan [23] Appendix C - Summary of Laws. These laws are used in the development of a program, when introducing algorithmic refinement using Morgan's Refinement Calculus in Chapter 2. They are re-numbered for clarity and they appear in alphabetical order

Law C1 <u>alternation</u> If $pre \Rightarrow GG$, then w : [pre, post] \sqsubseteq if ($i \bullet G_i \to w : [G_i \land pre, post]$) fi Law C2 <u>assignment</u> If $pre \Rightarrow post[w \backslash E]$, then $w, x : [pre, post] \sqsubseteq w := E$ Law C3 <u>following assignment</u> For any term E, w, x : [pre, post] $\sqsubseteq w, x : [pre, post]$ $\sqsubseteq w, x : [pre, post[x \backslash E]];$ x := E

Law C4 <u>introduce local variable</u> If x does not occur in w, pre or post then $w : [pre, post] \sqsubseteq | [var x : T; and inv \bullet w, x : [pre, post]] |$ Law C5 *iteration*

Let *inv*, the *invariant*, be any formula; let V, the *variant*, be any integervalued expression. Then, if G is the *Guard* and $inv \wedge \neg G \Rightarrow post$ then

w : [inv, post] $\sqsubseteq \text{ do } G \rightarrow$ $w : [inv \land G, inv \land (0 \leq V < V_0)]$ od

Law C6 leading assignment

For disjoint w and x, $w, x := E, F[w \setminus E] = w := E; x := F$

Law C7 sequential composition

For any formula *mid*, where neither *mid* or *post* contain initial variables: $w : [pre, post] \sqsubseteq w : [pre, mid]; w : [mid, post]$

Law C8 strengthen postcondition If $post' \Rightarrow post$, then $w : [pre, post] \sqsubseteq w : [pre, post']$

The following law is adapted from Morgan & Vickers [22] and deals with a special kind of data refinement, i.e. when the abstraction invariant(R) is functional. The justification is found in 2.3.1

Law C9 data refinement(functional)

If $R \equiv \overline{a = f(c)}$ (functional) (*a* is abstract, *c* is concrete) and when the postcondition does not refer to initial variables:

 $a:[pre, post] \sqsubseteq_R c:[pre[a \setminus f(c)], post[a \setminus f(c)]]$
Appendix D

B Specification of Academic Council count

D.1 Introduction

This appendix contains the specification of the counting system of the Academic Council voting system. The rules of this system are written in Appendix A. There are slight differences in this specification to the parts of the system as specified in the Case Studies of Chapter 5. The main difference is that the ballot in this case contains a weight whereas in the Case Study this is not the case. As the original value of the weight is always 1000 and during refinement it was spotted that it was unnecessary and wasteful to hold the ballots' weight at the start. However, this change has not been pulled through to this specification.

This specification is presented as a valid specification, written using B's AMN. We present the MACHINEs. The order in which they are presented follows a top-down approach. The driving operation is contained in the *Election* MACHINE which is presented first. The order of presentation of Machines is as follows:

- $\bullet \ Election$
- Global Variables
- Bool_TYPE
- BallotBag
- PaperBag

- P_Prepare_Ballots
- Counts
- CountingFunctions
- GetNextCandidate
- OrderingFunctions
- FindBalanceMins

D.2 B Specification

D.2.1 Overall Election

MACHINE Election

/*This machine contains the main driving operation of the system. countvotes returns the results of the election.*/

SEES

GlobalVariables, OrderingFunctions, BallotBag, Bool_TYPE, Countingfunctions, FindBalanceMins, GetNextCandidate, Counts, P_Prepare_Ballots

VARIABLES Votes,

no_seats, min_genpercent, min_gen, min_school, min_dept, Candidates, Result

INVARIANT

 $\begin{array}{l} \textit{Votes} \in \textit{BagPapers} \land \\ \textit{no_seats} \in \mathbb{N} \land \\ \textit{min_genpercent} \in \mathbb{N} \land \\ \textit{min_gen} \in \mathbb{N} \land \\ \textit{(no_seats > 0 \Rightarrow \textit{min_gen} = \\ min(\{nn \mid nn \in \mathbb{N} \land nn > \textit{no_seats} * \textit{min_genpercent}/100\}) \land \\ \textit{no_seats} = 0 \Rightarrow \textit{min_gen} = 0) \land \\ \textit{min_school} \in \mathbb{N} \land \\ \textit{min_dept} \in \textit{DEPARTMENT} \rightarrow \mathbb{N} \land \\ \textit{Candidates} \in \textit{SetCandidates} \land \\ \textit{Result} \in \textit{iseq}(\textit{Candidate} * ACT) \end{array}$

INITIALISATION

 $\begin{array}{l} Votes := \varnothing \mid \mid \\ no_seats := 0 \mid \mid \\ min_genpercent := 0 \mid \mid \\ min_gen := 0 \mid \mid \\ min_school := 0 \mid \mid \\ min_dept := DEPARTMENT \times \{0\} \mid \mid \\ Candidates := \varnothing \mid \mid \\ Result := <> \end{array}$

OPERATIONS

```
\begin{array}{l} enterdata \ \widehat{=} \\ \textbf{BEGIN} \\ Votes :\in Paper \leftrightarrow \mathbb{N} \mid \mid \\ no\_seats :\in \mathbb{N} \mid \mid \\ min\_genpercent :\in \mathbb{N} \mid \mid \\ min\_school :\in \mathbb{N} \mid \mid \\ min\_dept :\in DEPARTMENT \rightarrow \mathbb{N} \\ \textbf{END}; \end{array}
```

```
Results \longleftarrow countvotes \ \widehat{=}
```

/* This is the main driving operation of the system. The Results contain a sequence of pairs, each pair containing a Candidate and the action associated with that Candidate. The order of the sequence indicates the order that the actions took place. All required information is contained here. */

BEGIN

ANY Ballots **WHERE**

 $Ballots \in BagBallots \land Ballots = P_prepare_ballots(Votes)$ THEN

ANY firstvm, quota **WHERE**

 $firstvm \in VoteMass \land quota \in \mathbb{N} \land$

 $firstvm = Setup_First_Count(Ballots, Candidates) \land$

 $quota = Find_Quota(Ballots, no_seats)$

THEN

ANY vm, nt, dw **WHERE**

 $vm \in VoteMass \land nt \in NonTransfers \land dw \in DealtWith \land$ $vm \mapsto nt \mapsto dw =$

 $Election_Count(firstvm, \emptyset, \emptyset, 2, Ballots, Candidates, min_gen, min_school, min_dept, no_seats, quota)$

THEN Results := dwEND END END END

END

D.2.2 Global Variables

MACHINE Global Variables

DEFINITIONS

 $\begin{array}{l} Candidate == NAME \times GENDER \times SCHOOL \times DEPARTMENT;\\ SetCandidates == \mathbb{P}(Candidate);\\ VoteMass == Candidate \leftrightarrow (\mathbb{N} \leftrightarrow BagBallots);\\ Paper == Candidate \leftrightarrow \mathbb{N};\\ DealtWith == iseq(Candidate \times ACT);\\ NonTransfers == \mathbb{N} \leftrightarrow BagBallots;\\ MinDept == DEPARTMENT \rightarrow \mathbb{N};\\ BagPapers == Paper \leftrightarrow \mathbb{N}_1;\\ Paper == Candidate \leftrightarrow \mathbb{N};\\ Ballot == seq(Candidate) \times \mathbb{N} \times SIGN;\\ BagBallots == Ballot \leftrightarrow \mathbb{N}_1\end{array}$

SETS

NAME; /*deferred until candidates officially entered */ GENDER = {male, female}; SCHOOL = {engineering, business, science, humanities}; DEPARTMENT = {adult_ed, other};

/* As adult_ed is the only special case, I ignore the department of others, except to state that they are not in adult_ed. If an other department is similarly prescribed, then this department can be added in. If the condition for adult_ed is dropped, then simply change the mapping of adult_ed to zero (in deptmin) or change candidates to other. */ $ACT = \{elect, exclude\};$

 $SIGN = \{pos, neg\}$

CONSTANTS

school, gender, name, department

PROPERTIES

$$\begin{split} school \in Candidate &\rightarrow SCHOOL \land \\ gender \in Candidate &\rightarrow GENDER \land \\ name \in Candidate &\rightarrow NAME \land \\ department \in Candidate &\rightarrow DEPARTMENT \land \\ \forall (nn, gg, ss, dd).(nn \in NAME \land gg \in GENDER \land \\ &ss \in SCHOOL \land dd \in DEPARTMENT \Rightarrow \\ &school(nn, gg, ss, dd) = ss \land \\ &gender(nn, gg, ss, dd) = gg \land \\ &name(nn, gg, ss, dd) = nn \land \\ &department(nn, gg, ss, dd) = dd \\ &) \end{split}$$

END

MACHINE Bool_TYPE /* This machine simply introduces the boolean type*/

SETS $BOOL = \{FALSE, TRUE\}$

END

D.2.3 Bags - Paper and Ballot

MACHINE BallotBag

/* These operations are specific to the structure , based on bags of ballots. We will use these during the count */

SEES

Global Variables

INCLUDES

GenericBag(Ballot)

CONSTANTS

preferences, value, sign, valueballot, signballot, plus_minus, bagvalue, bagrange, totalballotvalue

PROPERTIES

 $\begin{array}{l} preferences \in Ballot \rightarrow seq(Candidate) \land \\ value \in \mathbb{N} \times SIGN \rightarrow \mathbb{N} \land \\ sign \in \mathbb{N} \times SIGN \rightarrow SIGN \land \\ value ballot \in Ballot \rightarrow \mathbb{N} \land \\ sign ballot \in Ballot \rightarrow SIGN \land \\ \forall (pref, val, sgn).(pref \in seq(Candidate) \land val \in \mathbb{N} \land sgn \in SIGN \Rightarrow (\\ preferences(pref \mapsto val \mapsto sgn) = pref \land \\ value(val \mapsto sgn) = val \land \\ sign(val \mapsto sgn) = sgn \land \\ value ballot(pref \mapsto val \mapsto sgn) = val \land \\ sign ballot(pref \mapsto val \mapsto sgn) = sgn)) \end{array}$

```
plus\_minus \in ((\mathbb{N} \times SIGN) \times (\mathbb{N} \times SIGN)) \rightarrow (\mathbb{N} \times SIGN) \land
 \forall (B1, B2).(B1 \in \mathbb{N} \times SIGN \land B2 \in \mathbb{N} \times SIGN \Rightarrow (
       (\exists (val, sgn). (val \in \mathbb{N} \land sgn \in SIGN \land
             ((sign(B1) = pos \land sign(B2) = pos \land
             val = value(B1) + value(B2) \land sqn = pos) \lor
             (sign(B1) = neg \land sign(B2) = neg \land
             val = value(B1) + value(B2) \land sqn = neq) \lor
             (sign(B1) = pos \land sign(B2) = neq \land
             value(B1) >= value(B2) \land
             val = value(B1) - value(B2) \land sgn = pos) \lor
             (sign(B1) = pos \land sign(B2) = neq \land
             value(B1) < value(B2) \land
             val = value(B2) - value(B1) \land sqn = neq) \lor
                   (sign(B1) = neg \land sign(B2) = pos \land
                   value(B1) >= value(B2) \land
             val = value(B1) - value(B2) \land sgn = neg) \lor
             (sign(B1) = neg \land sign(B2) = pos \land
             value(B1) < value(B2) \land
             val = value(B2) - value(B1) \land sqn = pos)) \land
 plus\_minus(B1, B2) = val \mapsto sqn)))))
 bagvalue \in BagBallots \rightarrow \mathbb{N} \times SIGN \land
 bagvalue() = 0 \mapsto pos \land
\forall (bballot, nn).(bballot \in Ballot \land nn \in \mathbb{N}_1 \Rightarrow
      bagvalue(bballot \mapsto nn) = valueballot(bballot) \times nn \mapsto signballot(bballot)) \land
      \forall (ABaqBallots, BBaqBallots).
            (ABagBallots \in BagBallots \land BBagBallots \in BagBallots \Rightarrow (
            bagvalue(bagplus(ABagBallots, BBagBallots)) =
                  plus_minus(bagvalue(ABagBallots), bagvalue(BBagBallots))
      ))
Λ
bagrange \in (\mathbb{N} \twoheadrightarrow BagBallots) \twoheadrightarrow BagBallots \land
bagrange(\{\}) = \{\} \land
\forall (ABaqBallots, nn). (ABaqBallots \in BaqBallots \land nn \in \mathbb{N} \Rightarrow (
      bagrange(nn \mapsto ABagBallots) = ABagBallots)) \land
      \forall (ff, gg).
            (ff \in \mathbb{N} \to BagBallots \land gg \in \mathbb{N} \to BagBallots \land
            dom ff \cap dom \ gg = \emptyset \Rightarrow
      bagrange(ff \cup qq) = bagplus(bagrange(ff), bagrange(qq))
)
```

 \wedge

 $\begin{aligned} totalballotvalue &\in BagBallots \rightarrow \mathbb{N} \times SIGN \land \\ \forall ABagBallots.(ABagBallots \in BagBallots \Rightarrow \\ totalballotvalue(ABagBallots) = bagvalue(ABagBallots)) \end{aligned}$

MACHINE PaperBag

SEES

Global Variables

CONSTANTS

Paper_count, Paper_tcount, Paper_bagplus, Paper_bagminus

PROPERTIES

 $Paper_count \in BagPapers \leftrightarrow (Paper > - >> NAT) \land$ $\forall bq.(bq \in (BaqPapers) \Rightarrow$ $Paper_count(bq) = \lambda xx.(xx \in Paper \mid 0) < +bq)$ Λ $Paper_tcount \in ((BagPapers) \times Paper) \rightarrow NAT \land$ / * total function version of count */ $\forall (bq, xx) . (bq \in (BaqPapers) \land xx \in Paper \Rightarrow$ $Paper_tcount(bq \mapsto xx) = (Paper_count(bq))(xx))$ Λ $Paper_bagplus \in (BagPapers) \times (BagPapers) \leftrightarrow (BagPapers) \land$ $Paper_bagminus \in (BagPapers) \times (BagPapers) \rightarrow (BagPapers) \land$ $\forall (abag, bbag, xx). (abag \in (BagPapers) \land bbag \in (BagPapers) \land xx \in Paper \Rightarrow$ $Paper_tcount(Paper_bagplus(abag, bbag), xx) =$ $Paper_tcount(abag, xx) + Paper_tcount(bbag, xx) \land$ $Paper_tcount(Paper_bagminus(abag, bbag), xx) =$ $max(\{Paper_tcount(abag, xx) - Paper_tcount(bbag, xx), 0\}))$

VARIABLES

pbag

INVARIANT

 $pbag \in BagPapers$

INITIALISATION

 $pbag := \emptyset$

OPERATIONS

 $nn \leftarrow bagcount \hat{=}$

 $\begin{array}{l} \mathbf{BEGIN}\\ nn:=\mathit{card}(\mathit{pbag})\\ \mathbf{END}\\ \mathbf{END} \end{array}$

D.2.4 Pre-Processing of Votes

MACHINE *P_Prepare_Ballots* (*no_cands*)

SEES

GlobalVariables , BallotBag , PaperBag

CONSTANTS

 $P_prepare_ballots$, $P_make_bag_ballots$, $P_{throwaway_empties}$, P_make_ballot . P_find_first_hole_or_dup **PROPERTIES** $P_{find_first_hole_or_dup \in Paper \rightarrow \mathbb{N} \land$ $\forall paper$. ($paper \in Paper \Rightarrow$ $P_{find_first_hole_or_dup} (paper) =$ min ({ $nn \mid nn \in 1 \dots no_cands + 1 \land$ card (paper $^{-1}$ [{ nn }]) $\neq 1$ })) Λ $P_make_ballot \in Paper \rightarrow Ballot \land$ $\forall paper . (paper \in Paper \Rightarrow$ preferences (P_make_ballot (paper)) = 1 ... P_find_first_hole_or_dup (paper) - 1 \triangleleft paper $^{-1} \land$ valueballot (P_make_ballot (paper)) = 1000 \wedge $signballot (P_make_ballot (paper)) = pos)$ Λ $P_throwaway_empties \in BagBallots \rightarrow BagBallots \land$ $\forall \ bballot \ . \ (\ bballot \in BagBallots \Rightarrow$ $P_{throwaway_empties}$ (bballot) = $\{bb \mid bb \in dom (bballot) \land preferences (bb) = \emptyset \} \triangleleft bballot)$ \wedge $P_make_bag_ballots \in BagPapers \rightarrow BagBallots \land$ $\forall \ bpapers \ . \ (\ bpapers \in BagPapers \Rightarrow$ $P_make_bag_ballots$ (bpapers) = $\{bb, nn \mid bb \in Ballot \land nn \in \mathbb{N}_1 \land$ $\exists pp$. ($pp \in \text{dom}$ (bpapers) $\land bb =$ $P_make_ballot (pp) \land nn = bpapers (pp)) \}$

 \wedge

 $\begin{array}{l} P_prepare_ballots \in BagPapers \rightarrow BagBallots \land \\ \forall \ bpapers \ . \ (\ bpapers \in BagPapers \Rightarrow \\ P_prepare_ballots \ (\ bpapers \) = \\ P_throwaway_empties \ (\ P_make_bag_ballots \ (\ bpapers \) \) \) \end{array}$ $\begin{array}{l} \textbf{VARIABLES} \end{array}$

VARIABLE

allvotes, procballots

INVARIANT

 $\begin{array}{l} allvotes \, \in \, BagPapers \, \wedge \\ procballots \, \in \, BagBallots \end{array}$

INITIALISATION

 $\begin{array}{l} allvotes := \varnothing ~|| \\ procballots := \varnothing \end{array}$

OPERATIONS

 $procballots \longleftarrow processvotes \cong$ **BEGIN** $procballots := P_prepare_ballots (allvotes)$ **END END**

D.2.5 Counting Functions

MACHINE Counts SEES

GlobalVariables, OrderingFunctions, BallotBag, BooLTYPE, Countingfunctions, FindBalanceMins, GetNextCandidate

CONSTANTS

Change_Weight, Change_All_Weights, Do_Transferencel, Transfer_Excluded, next, Do_a_count , Non_Transferables , Transferables, Transfer_Elected, Prepare_Transbag, Find_Surplus, Next_Pref, Setup_First_Count, Finished, Election_Count , Add_Action

PROPERTIES

 $\begin{array}{l} Change_Weight \in BagBallots \times \mathbb{N} \to BagBallots \land \\ \forall (\ bag \ , \ factor \) \ . (\ bag \in BagBallots \land \ factor \in \mathbb{N} \Rightarrow \\ \exists \ changedbag \ . (\ changedbag \in BagBallots \land \\ \forall (\ bb \ , \ nn \) \ . (\ bb \in Ballot \land \ nn \in \mathbb{N} \land bb \mapsto nn \in bag \Rightarrow \\ \exists \ bb" \ . (\ bb" \in Ballot \land \\ valueballot \ (\ bb" \) = valueballot \ (\ bb \) \times factor \land \\ preferences \ (\ bb" \) = preferences \ (\ bb \) \land \\ signballot \ (\ bb" \) = signballot \ (\ bb \) \land \\ bb" \mapsto nn \in changedbag \) \) \end{array}$

 $\begin{array}{l} Change_Weight (bag , factor) = changedbag \)) \\ \land \\ Change_All_Weights \in (Candidate \leftrightarrow BagBallots) \times \mathbb{N} \rightarrow \\ & (Candidate \leftrightarrow BagBallots) \wedge \\ \forall (transbag , factor) . (transbag \in Candidate \leftrightarrow BagBallots \wedge \\ & factor \in \mathbb{N} \Rightarrow \\ \exists weightedbag . (weightedbag \in Candidate \leftrightarrow BagBallots \wedge (\\ & \forall (cc , bb) . (cc \in dom (transbag) \wedge bb \in ran (transbag) \wedge \\ & cc \mapsto bb \in transbag \Rightarrow \\ & \exists bb" . (bb" \in BagBallots \wedge \\ & bb" \in Change_Weight (bb , factor) \wedge \\ & cc \mapsto bb" \in weightedbag)) \wedge \\ Change_All_Weights (transbag , factor) = weightedbag))) \end{array}$

 $Do_Transferencel \in Candidate \times VoteMass \times NonTransfers$ $\times \mathbb{N} \times \mathbb{N} \times SetCandidates \rightarrow$ $VoteMass \times NonTransfers \land$ \forall ($\mathit{currcand}$, vm , nt , count , $\mathit{subcount}$, $\mathit{continuing}$) . ($currcand \in Candidate \land vm \in VoteMass \land nt \in NonTransfers \land$ $count \in \mathbb{N} \land subcount \in \mathbb{N} \land continuing \in SetCandidates \Rightarrow$ \exists (currbag , transferbag , nontransfers , vm" , nt"). ($currbag \in BagBallots \land$ $transferbag \in Candidate \leftrightarrow BagBallots \land$ $vm" \in VoteMass \land nt" \in NonTransfers \land$ currbaq = vm (currcand) (subcount) \wedge $transferbag = Prepare_Transbag (currbag , currcand , continuing) \land$ nontransfers = Non_Transferables (currbag, currcand, continuing) \wedge $\forall \ cand \ . \ (\ cand \in \mathsf{dom} \ (\ transferbag \) \Rightarrow$ $count \in dom (vm (cand)) \land$ vm" (cand) = vm (cand) \cup { count \mapsto transferbag (cand) } \vee $(count \notin dom (vm (cand)) \land$ vm" (cand) = vm (cand) \Leftrightarrow { count \mapsto bagplus (vm (cand) (count) , transferbag (cand)) $\}$)) \land \forall cand . (cand \in Candidate \land cand \in dom (vm) \land $cand \notin dom (transferbag) \Rightarrow$ vm" (cand) = vm (cand) \wedge (count \in dom (nt) \land nontransfers $\neq \varnothing \land$ $nt^{"} = nt \cup \{ count \mapsto bagplus (nt (count), nontransfers) \} \lor$ $(count \in \mathbb{N} \land count \notin dom (vm (currcand)) \land$ nontransfers $\neq \emptyset \land nt^{"} = nt \cup \{ count \mapsto nontransfers \}) \lor$ $(nontransfers = \emptyset \land nt" = nt))) \land$ $Do_Transferencel (currcand, vm, nt, count, subcount, continuing) =$ $vm'' \mapsto nt''$)) \wedge

 $Transfer_Excluded \in Candidate \times VoteMass \times NonTransfers \times$ $DealtWith \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times SetCandidates \rightarrow$ $VoteMass \times NonTransfers \land$ \forall (currcand, vm, nt, dw, count, subcount, quota, all candidates). ($currcand \in Candidate \land vm \in VoteMass \land nt \in NonTransfers \land$ $dw \in DealtWith \land count \in \mathbb{N} \land subcount \in \mathbb{N} \land quota \in \mathbb{N} \land$ $all candidates \in SetCandidates \Rightarrow$ \exists (continuing, maxsubcount). (continuing \in SetCandidates \land (continuing =all candidates dom (ran ($1 \dots count - 2 \triangleleft dw$)) - $\{ cc \mid cc \in all candidates \land$ value (totalvaloffunct (vm (cc), count - 1)) \geq quota } \wedge $maxsubcount = \max(dom(vm(currcand))) \land$ ($subcount > maxsubcount \land$ $\exists vm$ ". (vm" $\in VoteMass \land$ ($vm'' = vm \Leftrightarrow \{ currcand \mapsto$ vm (currcand) \cup $\{ count \mapsto$ Change_Weight (bagrange (vm (currcand)), 1) } } ^ Transfer_Excluded (currcand , vm , nt , dw , count , subcount , quota, all candidates) = $vm" \mapsto nt$)) \lor ($subcount \leq maxsubcount \land$ $\exists (vm", nt")$. $(vm" \in VoteMass \land nt" \in NonTransfers \land$ $vm" \mapsto nt" = Do_Transferencel (currcand , vm , nt , count ,$ subcount, continuing) \wedge Transfer_Excluded (currcand , vm , nt , dw , count , subcount , quota, all candidates) = $Transfer_Excluded$ (currcand , vm", nt", dw, count, next (subcount , dom (vm (currcand))) , quota , allcandidates))))))))

Λ

```
\begin{array}{l} next \in \mathbb{N} \times \mathbb{P} (\mathbb{N}) \to \mathbb{N} \land \\ \forall ( \ currno \ , \ set \ ) \ . \ ( \ set \in \mathbb{P} (\mathbb{N}) \land currno \in \mathbb{N} \land currno \in set \Rightarrow \\ \exists \ nextno \ . \ ( \ nextno \in set \cup \{ \ \max ( \ set \ ) + 1 \ \} \land \\ currno \ . \ nextno = \{ \ currno \ , \ nextno \ \} \land \\ next \ ( \ currno \ , \ set \ ) = nextno \ ) \ ) \end{array}
```

 $Do_a_count \in VoteMass \times \mathbb{N} \times DealtWith \times SetCandidates \times$ NonTransfers \times BagBallots $\times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times MinDept \times \mathbb{N} \rightarrow$ $VoteMass \times NonTransfers \times DealtWith \land$ \forall (vm , count , dealt_with , all candidates , non_transfers , bballots , no_seats, mingen, minschool, mindept, quota). ($vm \in VoteMass \land count \in \mathbb{N} \land dealt_with \in DealtWith \land$ $all candidates \in SetCandidates \land non_transfers \in NonTransfers \land$ $bballots \in BagBallots \land no_seats \in \mathbb{N} \land mingen \in \mathbb{N} \land$ $minschool \in \mathbb{N} \land mindept \in MinDept \land quota \in \mathbb{N} \Rightarrow$ \exists (continuing , cand , act , $vm^{"}$, $nt^{"}$, $dw^{"}$). (continuing \subset all candidates \land cand \in all candidates \land act \in ACT \land $vm" \in VoteMass \land nt" \in NonTransfers \land dw" \in DealtWith \land$ continuing =all candidates dom (ran ($1 \dots count - 2 \triangleleft dealt_with$)) - $\{ cc \mid cc \in all candidates \land$ value (totalvaloffunct (vm (cc), count - 1)) \geq quota } \wedge $cand \mapsto act =$ Find_Next_Cand (vm, count, dealt_with, allcandidates, bballots, no_seats, mingen, minschool, mindept, quota) \wedge ($act = elect \land$ $vm" \mapsto nt" = Transfer_Elected (cand , vm , non_transfers ,$ count, quota, continuing) V ($act = exclude \land$ $vm" \mapsto nt" =$ Transfer_Excluded (cand , vm , non_transfers , dealt_with , count, min (dom (vm (cand))), quota, all candidates))) \land $dw" = dealt_with \leftarrow (cand \mapsto act) \land$ Do_a_count (vm, count, dealt_with, allcandidates, non_transfers, bballots, no_seats, mingen, minschool, mindept, quota) = $vm" \mapsto nt" \mapsto dw"$))

Λ

 $Transfer_Elected \in Candidate \times VoteMass \times NonTransfers \times$ $\mathbb{N} \times \mathbb{N} \times SetCandidates \rightarrow$ $VoteMass \times NonTransfers \land$ \forall (currcand , vm , nt , count , quota , continuing) . $(\ currcand \in Candidate \land vm \in VoteMass \land nt \in NonTransfers \land$ $count \in \mathbb{N} \land quota \in \mathbb{N} \land continuing \in SetCandidates \Rightarrow$ \exists (lastc, lastbag, transferbag, weighted transferbag, surplus, transferables, transferablevalue, nontransferables, nontransaway, nontranstont, transnont, transisnt, transferbag", vm", nt"). $(lastc \in \mathbb{N} \land lastc = max (dom (vm (currcand)))) \land$ $lastbag \in BagBallots \land$ lastbag = vm (currcand) (lastc) \land $transferbag \in Candidate \rightarrow BagBallots \land$ $transferbag = Prepare_Transbag$ (lastbag , currcand , continuing) \land weighted transfer bag \in Candidate \rightarrow Bag Ballots \land weighted transferbag =Change_All_Weights (transferbag, surplus / transferablevalue) \land $surplus \in \mathbb{N} \land$ $surplus = Find_Surplus (vm (currcand), quota) \land$ $transferables \in BagBallots \land$ $transferables = Transferables (lastbag , currcand , continuing) \land$ $transferable value \in \mathbb{N} \land$ $transferable value = value (bagvalue (transferables)) \land$ nontransferables =Non_Transferables (lastbag, currcand, continuing) \wedge nontransaway =Change_Weight (nontransferables , $1 \times (surplus - transferable value) /$ value (baqvalue (nontransferables))) \wedge $nontranstont = Change_Weight (nontransaway, 1) \land$ transnont =Change_Weight (transferables, surplus $\times 1$ / transferablevalue) \wedge $transisnt = Change_Weight (transferables, 1) \land$ $vm" \in VoteMass \land nt" \in NonTransfers \land$

```
\textit{transferbag"} \in \textit{Candidate} \, \nleftrightarrow \, \textit{BagBallots} \, \wedge \,
                  ( surplus < transferable value \land
                  transferbaq" = weightedtransferbaq \lor
                  (surplus \geq transferable value \land transferbag" = transferbag)) \land
            \forall \ cand . ( cand \in \mathsf{dom} \ ( \ transferbag" \ ) \Rightarrow
                  vm'' ( cand ) = vm ( cand ) \cup
                                         { count \mapsto transferbag" ( cand ) } ) \land
                       \{ cand \mid cand \in dom ( transferbag ) \} \cup
                       \{ currcand \} \triangleleft vm" =
                       \{ cand \mid cand \in dom ( transferbag ) \}
                       \cup \{ currcand \} \triangleleft vm \land
            ( surplus > transferablevalue \land
            vm" ( currcand ) =
                             vm (currcand) \cup \{count \mapsto transnont\} \land
            nt = nt" \lor
            ( surplus < transferable value \land
            vm" ( currcand ) =
                             vm ( currcand ) \cup
                             { count \mapsto bagplus (transist, nontransaway) } \land
           nt^{"} = nt \cup \{ count \mapsto nontranstont \} ) ) \land
      Transfer_Elected ( currcand , vm , nt , count , quota , continuing ) =
           vm" \mapsto nt"))
     Λ
Prepare\_Transbag \in BagBallots \times Candidate \times SetCandidates \rightarrow
```

 $(Candidate \leftrightarrow BagBallots) \land \\ \forall (inbag, currcand, continuing). \\ (inbag \in BagBallots \land currcand \in Candidate \land \\ continuing \in SetCandidates \Rightarrow \\ \exists nextcandbag. (nextcandbag \in Candidate \leftrightarrow BagBallots \land \\ \forall (ballot, nn). \\ (ballot \in Ballot \land nn \in \mathbb{N} \land ballot \mapsto nn \in inbag \land \\ ballot \mapsto currcand \mapsto continuing \in dom (Next_Pref) \Rightarrow \\ ballot \mapsto nn \in \\ nextcandbag (Next_Pref (ballot, currcand, continuing))) \land \\ \\ Prepare_Transbag (inbag, currcand, continuing) = nextcandbag))$

 \wedge

 $Find_Surplus \in FunctBag \times \mathbb{N} \to \mathbb{N} \land$ \forall (fbag, quota). (fbag \in FunctBag \land quota \in \mathbb{N} \Rightarrow $Find_Surplus (fbag, quota) =$ quota value (totalvaloffunct (fbag , max (dom (fbag))))) Λ $Next_Pref \in Ballot \times Candidate \times SetCandidates \leftrightarrow Candidate \land$ \forall (ballot, currcand, continuing). (ballot \in Ballot \land $currcand \in Candidate \land continuing \in SetCandidates \land$ $(preferences (ballot))^{-1} (currcand) + 1 ...$ card (preferences (ballot)) \triangleleft preferences (ballot) \triangleright continuing $\neq \varnothing \Rightarrow$ \exists (preference, available). (preference \in iseq (Candidate) \land available $\in \mathbb{N} \rightarrow$ Candidate \land $preference = preferences (ballot) \land$ available =preference $^{-1}$ (currcand) + 1 ... card (preference) \lhd preference \triangleright continuing \land Next_Pref (ballot , currcand , continuing) = available (min (dom (available)))))

 $Transferables \in BagBallots \times Candidate \times SetCandidates \rightarrow$ $BagBallots \land$ $Non_Transferables \in BagBallots \times Candidate \times SetCandidates \rightarrow$ $BagBallots \land$ \forall (inbag, currcand, continuing). ($inbag \in BagBallots \land currcand \in Candidate \land$ $continuing \in SetCandidates \Rightarrow$ \exists (transfers, nontransfers). ($transfers \in BagBallots \land nontransfers \in BagBallots \land$ \forall (ballot , nn). ($ballot \in Ballot \land nn \in \mathbb{N} \land ballot \mapsto nn \in inbag \Rightarrow$ $ballot \mapsto currcand \mapsto continuing \in$ dom (*Next_Pref*) \land $ballot \mapsto nn \in transfers \lor$ ($ballot \mapsto currcand \mapsto continuing \notin$ dom (*Next_Pref*) \land $ballot \mapsto nn \in nontransfers)) \land$ Transferables (inbag, currcand, continuing) = transfers \wedge $Non_Transferables$ (inbag, currcand, continuing) = nontransfers)) Λ

 $\begin{array}{l} Setup_First_Count \in BagBallots \times SetCandidates \rightarrow VoteMass \land \\ \forall (\ bagballots \ , \ allcandidates \) \ . \\ (\ bagballots \in BagBallots \land \ allcandidates \in SetCandidates \Rightarrow \\ \exists \ vm" \ . (\ vm" \in VoteMass \land \\ \\ \forall (\ ballot \ , nn \) \ . (\ ballot \in Ballot \land nn \in \mathbb{N} \land \\ \\ ballot \mapsto nn \in bagballots \Rightarrow \\ \\ \exists \ cand \ . (\ cand \in allcandidates \land \\ \\ \\ first (\ preferences (\ ballot \)) = cand \land \\ \\ \\ ballot \mapsto nn \in vm" (\ cand \) (\ 1 \) \) \land \\ \\ Setup_First_Count (\ bagballots \ , \ allcandidates \) = vm" \) \end{array}$

 \wedge

 $Finished \in DealtWith \times SetCandidates \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times$ $MinDept \rightarrow BOOL \land$ \forall (dealt_with , all candidates , count , no_seats , mingen, minschool, mindept). $(dealt_with \in DealtWith \land allcandidates \in SetCandidates \land$ $count \in \mathbb{N} \land no_seats \in \mathbb{N} \land mingen \in \mathbb{N} \land$ $minschool \in \mathbb{N} \land mindept \in MinDept \Rightarrow$ \exists (elected , excluded , res) . ($elected \in SetCandidates \land excluded \in SetCandidates \land$ $res \in BOOL \land$ elected = $\{ cand \mid cand \in Candidate \land \}$ $\exists ii . (ii \in 1 .. count - 2 \land$ fst (dealt_with (ii)) = cand \wedge snd (dealt_with (ii)) = elect) } \land excluded ={ cand | cand \in Candidate \land $\exists ii . (ii \in 1 .. count - 2 \land fst (dealt_with (ii)) = cand \land$ snd (dealt_with (ii)) = exclude) } \land (card (elected) = $no_seats \lor$ $(card (all candidates) - card (excluded) = no_seats \land$ balancepossible (allcandidates , elected , allcandidates - excluded - elected, no_seats, mingen , minschool , mindept) = TRUE) \land $res = TRUE \lor$ (card (elected) < $no_seats \land$ (card (allcandidates) - card (excluded) > $no_seats \lor$ balancepossible (allcandidates, elected, allcandidates - excluded - elected, no_seats, mingen , minschool , mindept) = FALSE) \land res = FALSE)) \land Finished (dealt_with , allcandidates , count , no_seats , mingen, minschool, mindept) = res))

Λ

 $\begin{array}{l} Add_Action \in \mathsf{iseq} \ (\ Candidate \) \times ACT \rightarrow \mathsf{iseq} \ (\ Candidate \ \times ACT \) \land \\ \forall \ (\ scand \ , \ act \) \ . \ (\ scand \ \in \mathsf{iseq} \ (\ Candidate \) \land \ act \ \in ACT \Rightarrow \\ \exists \ otherscand \ . \ (\ otherscand \ \in \mathsf{iseq} \ (\ Candidate \ \times ACT \) \land \\ \forall \ cand \ . \ (\ otherscand \ \in \mathsf{iseq} \ (\ Candidate \ \times ACT \) \land \\ \forall \ cand \ . \ (\ cand \ \in \mathsf{ran} \ (\ scand \) \Rightarrow \\ otherscand \ (\ scand \ ^{-1} \ (\ cand \) \) = \ cand \ \mapsto \ act \) \land \\ Add_Action \ (\ scand \ , \ act \) = \ otherscand \) \) \end{array}$

 \wedge

```
Election\_Count \in VoteMass \times NonTransfers \times DealtWith \times \mathbb{N} \times
           BagBallots \times SetCandidates \times \mathbb{N} \times \mathbb{N} \times MinDept \times \mathbb{N} \times \mathbb{N} \rightarrow
           VoteMass \times NonTransfers \times DealtWith \land
\forall (vm, nt, dw, count, bagballots, all candidates, mingen, minschool,
   mindept, no_seats, quota).
     (vm \in VoteMass \land nt \in NonTransfers \land dw \in DealtWith \land
     count \in \mathbb{N} \land bagballots \in BagBallots \land
     all candidates \in Set Candidates \land mingen \in \mathbb{N} \land minschool \in \mathbb{N} \land
     mindept \in MinDept \land no\_seats \in \mathbb{N} \land quota \in \mathbb{N} \Rightarrow
           (Finished(dw, allcandidates, count, no_seats,
                      mingen, minschool, mindept) = TRUE \land
           (\exists (continuing, elected)).
                 (continuing \in SetCandidates \land elected \in SetCandidates \land
                 continuing = all candidates - dom(ran(1..count - 1 \lhd dw)) -
                 \{cc \mid cc \in all candidates \land
                            value(totalvaloffunct(vm(cc), count - 1)) >= quota \} \land
                elected = \{ cand \mid cand \in Candidate \land \exists ii. (ii \in 1... count \land
                                       fst(dw(ii)) = cand \wedge
                                       snd(dw(ii)) = elect) \land
                \exists dw''.(dw'' \in Dealt With \land
                      ((card(elected) = no\_seats \land dw'' = dw) \lor
                       (card(elected) < no\_seats \land
                       card(elected) + card(continuing) = no\_seats \land
                      dw'' = dw \frown
                           Add_Action(rev(Put_in_order(vm, count, continuing,
                                 all candidates, bagballots, card(all candidates))), elect) \land
          Election_Count(vm, nt, dw, count, bagballots, allcandidates,
                      mingen, minschool, mindept, no\_seats, quota) =
                vm \mapsto nt \mapsto dw''
          ))))
          (Finished(dw, allcandidates, count, no_seats,
                     mingen, minschool, mindept) = FALSE \land
          (\exists (vm'', nt'', dw'').
               (vm'' \in VoteMass \land nt'' \in NonTransfers \land dw'' \in DealtWith \land
                     Do_a_count(vm, count, dw, allcandidates, nt, bagballots,
                                 no\_seats, mingen, minschool, mindept, quota) =
                           vm'' \mapsto nt'' \mapsto dw'' \wedge
```

)

)

$$\begin{split} Election_Count(vm, nt, dw, count, bagballots, allcandidates, \\ mingen, minschool, mindept, no_seats, quota) = \\ Election_Count(vm'', nt'', dw'', count + 1, bagballots, allcandidates, \\ mingen, minschool, mindept, no_seats, quota)))) \end{split}$$

MACHINE Countingfunctions

/* This contains functions to count the total value of a candidate's votes and a function to calculate the quota $^{\ast}/$

SEES

 $Global Variables \ , \\ Ballot Bag$

CONSTANTS

totalvaloffunct , $Find_Quota$

PROPERTIES

 $\begin{array}{l} totalvaloffunct \in FunctBag \times \mathbb{N} \to \mathbb{N} \times SIGN \land \\ \forall (\ countno \ , \ candfunct \) \ . (\ countno \ \in \mathbb{N} \land \ candfunct \ \in FunctBag \Rightarrow \\ totalvaloffunct \ (\ candfunct \ , \ countno \) = \\ & bagvalue \ (\ bagrange \ (\ 1 \ . \ countno \ \lhd \ candfunct \) \) \) \\ \land \\ Find_Quota \ \in BagBallots \times \mathbb{N} \to \mathbb{N} \land \\ \forall \ (\ ballots \ , \ no_seats \) \ . \ (\ ballots \ , \ no_seats \) = \\ & (\ bagvalue \ (\ ballots \) \) \ / \ (\ no_seats + 1 \) + 1 \) \end{array}$

Cross-references

IS
3
3
3

DEFINITIONS

 $\begin{array}{rcl}FunctBag & == & \mathbb{N} \ \leftrightarrow \ BagBallots;\\CandsBallots & == & \mathbb{N} \ \leftrightarrow \ (\ \mathbb{N} \ \leftrightarrow \ BagBallots \)\\ \textbf{END}\end{array}$

Cross-references for Countingfunctions

BagBallots	Global Variables	DEFINITIONS
BallotBag		MACHINE
Global Variables		MACHINE
SIGN	Global Variables	SETS
bagrange	BallotBag	CONSTANTS
bagvalue	BallotBag	CONSTANTS
BallotBag		CONSTANTS

D.2.6 Ordering Functions

MACHINE GetNextCandidate

SEES

GlobalVariables, OrderingFunctions, BallotBag, Bool_TYPE, Countingfunctions, FindBalanceMins

CONSTANTS

fst, snd, First_count_over, Get_next_over_quota, Get_next_to_exclude, Find_Next_Cand

PROPERTIES

 $\begin{aligned} & fst \in (Candidate \times ACT) \rightarrow Candidate \land \\ & snd \in (Candidate \times ACT) \rightarrow ACT \land \\ & \forall (cc, ac).(cc \in Candidate \land ac \in ACT \Rightarrow \\ & fst(cc \mapsto ac) = cc \land \\ & snd(cc \mapsto ac) = ac) \\ & \land \\ & First_count_over \in VoteMass \times Candidate \times \mathbb{N} \rightarrow \mathbb{N} \land \\ /^*Partial function - only applicable when candidate is over quota*/ \\ & \forall (vm, cand, quota, no_cands). \\ & (vm \in VoteMass \land cand \in Candidate \land quota \in \mathbb{N} \land no_cands \in \mathbb{N} \Rightarrow \\ & First_count_over(vm, cand, quota) = \\ & min(\{nn \mid nn \in \mathbb{N} \land \\ & value(totalvaloffunct(vm(cand), nn)) >= quota\}) \\ &) \end{aligned}$

Λ

)

```
Get\_next\_over\_quota \in (VoteMass \times \mathbb{N} \times SetCandidates \times
                       SetCandidates \times BagBallots \times \mathbb{N} \times \mathbb{N} \times
                       \mathbb{N} \times \mathbb{N} \times MinDept \times SetCandidates \times
                       SetCandidates \times \mathbb{N})
                  \rightarrow (Candidate \times ACT) \wedge
\forall (vm, count, overquota, allcands, bballots, no_cands,
   quota, mingen, minschool, mindept, elected, continuing, no_seats).
      (vm \in VoteMass \land count \in \mathbb{N} \land overquota \in SetCandidates \land
      all cands \in SetCandidates \land bballots \in BagBallots \land
     no\_cands \in \mathbb{N} \land quota \in \mathbb{N} \land mingen \in \mathbb{N} \land
     minschool \in \mathbb{N} \land mindept \in MinDept \land elected \in SetCandidates \land
     continuing \in SetCandidates \land no\_seats \in \mathbb{N} \Rightarrow
           (\exists (fcountover, earliest, cand, do).
                 (fcountover \in Candidate \rightarrow \mathbb{N} \land
                 fcountover = \lambda \ candi.(candi \in overquota \mid
                             First\_count\_over(vm, candi, quota)) \land
                 earliest = min(ranfcountover) \land
                 cand = last(Put_in_order(vm, earliest, overquota,
                             allcands, bballots, no\_cands)) \land
                 do \in ACT \land
                       ((balance possible (all cands, elected \cup cand,
                             continuing - cand, no_seats, mingen,
                            minschool, mindept) = TRUE \land
                       do = elect)
                       \vee
                      (balance possible (all cands, elected \cup cand,
                            continuing - cand, no_seats, mingen,
                            minschool, mindept) = FALSE \land
                      do = exclude)) \land
     Get_next_over_quota(vm, count, overquota, allcands, bballots,
                 no_cands, quota, mingen, minschool, mindept, elected,
                 continuing, no\_seats) =
                 cand \mapsto do
    ))
```

Λ

 $Get_next_to_exclude \in (VoteMass \times \mathbb{N} \times$ $SetCandidates \times SetCandidates \times SetCandidates \times$ $BagBallots \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times MinDept) \rightarrow$ $(Candidate \times ACT) \land$ /*need to insist on balance*/ \forall (*vm*, *count*, *elected*, *continuing*, *allcands*, *bballots*, *no*_*cands*, no_seats, mingen, minschool, mindept). $(vm \in VoteMass \land count \in \mathbb{N} \land elected \in SetCandidates \land$ $continuing \in SetCandidates \land allcands \in SetCandidates \land$ $bballots \in BagBallots \land no_cands \in \mathbb{N} \land no_seats \in \mathbb{N} \land$ $mingen \in \mathbb{N} \land minschool \in \mathbb{N} \land mindept \in MinDept \Rightarrow$ $\exists ordered.(ordered \in seq(Candidate) \land$ ordered = Put_in_order(vm, count, continuing, allcands, bballots, no_cands) \land $\exists pos.(pos \in 1.. card(ordered) \land$ $\forall pp.(pp \in 1 \dots pos \Rightarrow$ balancepossible(allcands, elected, continuing - ordered(pp), no_seats, mingen, $minschool, mindept) = FALSE) \land$ balancepossible(allcands, elected, continuing - ordered(pos), no_seats, mingen, minschool, mindept) = $TRUE \land$ Get_next_to_exclude(vm, count, elected, continuing, allcands, bballots, $no_cands, no_seats, mingen, minschool, mindept) =$ $ordered(pos) \mapsto exclude$))

Λ

 $Find_Next_Cand \in (VoteMass \times \mathbb{N} \times DealtWith \times$ $SetCandidates \times BagBallots \times \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times$ $MinDept \times \mathbb{N} \to$ $(Candidate \times ACT) \land$ $\forall (vm, count, dealt_with, all candidates, bballots, no_seats,$ mingen, minschool, mindept, quota). $(vm \in VoteMass \land count \in \mathbb{N} \land dealt_with \in DealtWith \land$ $all candidates \in SetCandidates \land bballots \in BagBallots \land$ $no_seats \in \mathbb{N} \land mingen \in \mathbb{N} \land minschool \in \mathbb{N} \land$ $mindept \in MinDept \land quota \in \mathbb{N} \Rightarrow$ $(\exists (overguota, continuing, elected, cand, ac).$ $(overguota \in SetCandidates \land$ $continuing \in SetCandidates \land cand \in Candidate \land$ $ac \in ACT \land elected \in SetCandidates \land$ $overquota = \{ cc \mid cc \in all candidates \land$ value(totalvaloffunct(vm(cc), count - 1)) $>= quota\}$ $dom(ran(1 \dots count - 1 \triangleleft dealt_with)) \land$ continuing =all candidates $dom(ran(1 \dots count - 1 \triangleleft dealt_with)) \{cc \mid cc \in all candidates \land$ value(totalvaloffunct(vm(cc), count - 1)) $>= quota \} \land$ $elected = \{ cand \mid cand \in Candidate \land$ $\exists ii.(ii \in dom \ dealt_with \land$ $fst(dealt_with(ii)) = cand \land$ $snd(dealt_with(ii)) = elect) \land$ $((overquota \neq \emptyset \land$ $cand \mapsto ac =$ $Get_next_over_quota(vm, count - 1, overquota,$ allcandidates, bballots, card(allcandidates), quota, mingen, minschool, mindept, elected, continuing, $no_seats)) \lor$ $(overquota = \emptyset \land$ $cand \mapsto ac =$ $Get_next_to_exclude(vm, count - 1, elected,$ continuing, allcandidates, bballots, card(allcandidates), *no_seats*, *mingen*, *minschool*, *mindept*)

)) ^

$Find_Next_Cand(vm, count, dealt_with, allcandidates, bballots, no_seats, mingen, minschool, mindept, quota) = cand \mapsto ac))$

) END /* Machine GetNextCandidate*/

MACHINE

 ${\it Ordering Functions}$

SEES

Bool_TYPE, BallotBag, GlobalVariables, Countingfunctions, FindBalanceMins

CONSTANTS

VoteMassatPref, Order_of_Preferences, Put_in_order

PROPERTIES

 $\begin{array}{l} \textit{VoteMassatPref} \in \textit{BagBallots} \times \textit{SetCandidates} \times \mathbb{N} \rightarrow \textit{VoteMass} \land \\ \forall (\textit{bballots}, \textit{allcandidates}, \textit{preference}).(\textit{bballots} \in \textit{BagBallots} \land \\ & \textit{allcandidates} \in \textit{SetCandidates} \land \textit{preference} \in \mathbb{N} \Rightarrow \\ \exists \textit{vm}.(\textit{vm} \in \textit{VoteMass} \land \\ & \forall (bb, nn).(bb \in \textit{Ballot} \land nn \in \mathbb{N} \land bb \mapsto nn \in \textit{bballots} \Rightarrow \\ & \exists \textit{cand}.(\textit{cand} \in \textit{allcandidates} \land \\ & \textit{preferences}(bb)(\textit{preference}) = \textit{cand} \land \\ & bb \mapsto nn \in \textit{vm}(\textit{cand})(1)) \land \\ & \textit{VoteMassatPref}(\textit{bballots}, \textit{allcandidates}, \textit{preference}) = \textit{vm}))) \end{array}$

Λ
$Order_of_Preferences \in BagBallots \times SetCandidates \times \mathbb{N} \rightarrow$ $iseq(Candidate) \land$ /* After the first count, the ballots are arranged in 'order of preferences' according to "Rules for Academic Council Election (Academic Members)" Rule 2. This order of preference is used later in case of ties between candidates. */ $\forall (bballots, all candidates, no_cands).(bballots \in BagBallots \land$ $all candidates \in SetCandidates \land no_cands \in \mathbb{N} \Rightarrow$ \exists orderedseq.(orderedseq \in iseqCandidate \land ran orderedseq = allcandidates \land $\forall (ii, jj).(ii \in dom \ orderedseq \land jj \in dom \ orderedseq \land ii < jj \Rightarrow$ $(\exists pref.(pref \in 1...no_cands \land$ /* pref is the first time there's a diffence*/ (value(totalvaloffunct(VoteMassatPref(bballots, all candidates, pref)(orderedseq(ii)), 1)) >value(totalvaloffunct(VoteMassatPref(bballots, allcandidates, pref)(orderedseq(jj)), 1))) $\forall pp.(pp \in 1 \dots pref - 1 \Rightarrow$ (value(totalvaloffunct(VoteMassatPref(bballots, all candidates, pp)(orderedseq(ii)), 1)) =value(totalvaloffunct(VoteMassatPref(bballots, allcandidates, pp)(orderedseq(jj)), 1)))))) /* If all equal, 'draw lots' */ $(\forall pp.(pp \in 1 \dots no_cands \Rightarrow)$ (value(totalvaloffunct(VoteMassatPref(bballots, all candidates, pp)(orderedseq(ii)), 1)) =value(totalvaloffunct(VoteMassatPref(bballots, allcandidates, pp)(orderedseq(jj)), 1))))) $)/*or*/\wedge$ $Order_of_Preferences(bballots, allcandidates, no_cands) = orderedseq$))

 \wedge

B Specification

 $Put_in_order \in (VoteMass \times \mathbb{N} \times SetCandidates \times$ $SetCandidates \times BagBallots \times \mathbb{N}) \rightarrow$ $iseq(Candidate) \land$ \forall (*vm*, *count*, *setcands*, *allcands*, *bballots*, *no_cands*). $vm \in VoteMass \land count \in \mathbb{N} \land setcands \in SetCandidates \land$ $all cands \in SetCandidates \land ballots \in BagBallots \land no_cands \in \mathbb{N} \Rightarrow$ \exists orderedseq.(orderedseq \in iseq(Candidate) \land ran orderedseq = setcands \wedge $\forall (ii, jj).(ii \in dom \ orderedseq \land jj \in dom \ orderedseq \land ii < jj \Rightarrow$ (value(totalvaloffunct(vm(orderedseq(ii)), count)) <value(totalvaloffunct(vm(orderedseg(jj)), count))) \mathbf{V} (value(totalvaloffunct(vm(orderedseq(ii)), count)) = $value(totalvaloffunct(vm(orderedseq(jj)), count)) \land$ $(\exists disting_c.(disting_c \in 1.. count \land)$ $value(totalvaloffunct(vm(orderedseq(ii)), disting_{-}c)) <$ $value(totalvaloffunct(vm(orderedseq(jj)), disting_c)) \land$ $\forall cc.(cc \in 1..disting_c - 1 \Rightarrow$ value(totalvaloffunct(vm(orderedseq(ii)), cc)) =value(totalvaloffunct(vm(orderedseq(jj)), cc))))) V $(\forall cc.(cc \in 1..count \Rightarrow$ value(totalvaloffunct(vm(orderedseq(ii)), cc)) =value(totalvaloffunct(vm(orderedseq(jj)), cc))) Λ *Order_of_Preferences(bballots, allcands, no_cands)* (orderedseq(ii)) <Order_of_Preferences(bballots, allcands, $no_cands)$ (orderedseq(jj))))) ^ $Put_in_order(vm, count, setcands, allcands, bballots, no_cands) =$ orderedseq))

END

B Specification

D.2.7 Candidate Balance Functions

${\bf MACHINE} {\it FindBalanceMins}$

SEES

 $GlobalVariables, Bool_TYPE$

CONSTANTS

findschoolmin, num_from_school, num_f rom_g ender, balancepossible

PROPERTIES

```
findschoolmin \in (SetCandidates \times SCHOOL \times \mathbb{N}) \rightarrow \mathbb{N} \land
\forall (AllCandidates, cschool, minschool).(AllCandidates \in SetCandidates \land
            cschool \in SCHOOL \land
            minschool \in \mathbb{N} \Rightarrow
      findschoolmin(AllCandidates, cschool, minschool) =
            min(\{card\{cc \mid cc \in AllCandidates \land school(cc) = cschool\},\
                  minschool})
      )
Λ
num\_from\_school \in (SetCandidates \times SCHOOL) \rightarrow \mathbb{N} \land
\forall (cands, sch).(cands \in SetCandidates \land sch \in SCHOOL \Rightarrow
     num_from_school(cands, sch) =
           card(\{cc \mid cc \in cands \land school(cc) = sch \})
)
Λ
num\_from\_gender \in (SetCandidates \times GENDER) \rightarrow \mathbb{N} \land
\forall (cands, gen).(cands \in SetCandidates \land gen \in GENDER \Rightarrow
     num_from_gender(cands, gen) =
           card(cc \mid cc \in cands \land gender(cc) = gen)
     )
\wedge
```

```
balance possible \in (SetCandidates \times SetCandidates \times SetCandidates \times
                       \mathbb{N} \times \mathbb{N} \times \mathbb{N} \times MinDept) \rightarrow
           BOOL \land
\forall(AllCandidates, elected, continuing, no_seats, mingen, minschool, mindept).
     (AllCandidates \in SetCandidates \land
     elected \in SetCandidates \land continuing \in SetCandidates \land
     no\_seats \in \mathbb{N} \land mingen \in \mathbb{N} \land minschool \in \mathbb{N} \land
     mindept \in MinDept \Rightarrow
           balancepossible(AllCandidates, elected, continuing, no_seats,
                 mingen, minschool, mindept) =
           bool(
                 \exists to be elected. (to be elected \in SetCandidates \land
                 to be elected \not\in continuing \ \land
                 card(elected) + card(tobe elected) = no\_seats \land
                 \forall gen.(gen \in GENDER \Rightarrow
                      num\_from\_gender(elected \cup tobeelected, gen) >= mingen) \land
                      \forall sch.(sch \in SCHOOL \Rightarrow
                            num_from_school(tobe elected \cup elected, sch) >=
                      findschoolmin(AllCandidates, sch, minschool)) \land
                \forall dpt.(dpt \in DEPARTMENT \Rightarrow
                      card(\{cc \mid cc \in elected \cup tobeelected \land
                                  department(cc) = dpt\}) >=
                      max(mindept(dpt), 0))
                )
          ) /*bool */
```

)

Bibliography

- J.-R. Abrial. The B-Book: Assigning Programs to Meanings. Cambridge University Press, 1996.
- [2] Aho, Upcroft & Ullman. The Design and Analysis of Computer Algorithms. Addison-Wesley, 1974.
- [3] R.J.R. Back. Correctness Preserving Program Refinements: Proof Theory and Applications. Tract 131, Mathematisch Centrum, Amsterdam, 1980.
- [4] R.J.R. Back & M.J. Butler. Fusion and simultaneous execution in the refinement calculus. *Acta Informatica*, 35:921-949, 1998.
- [5] B-Core(UK)Ltd, B-Toolkit User's Manual, B-Core(UK) Ltd. 1997.
- [6] R. Bird & P. Walder, Introduction to Functional Programming, Prentice Hall, 1988.
- [7] U. Breyman. Designing Components with the C++ STL: A New Approach to Programming. Addison Wesley, 1998.
- [8] M.J. Butler. Calculational Derivation of Pointer Algorithms from Tree Operations. Science of Computer Programming, 33 (1999) 221-260.
- [9] M.J. Butler & M. Meagher. Performing Algorithmic Refinement before Data Refinement in B. In Conference Proceedings - ZB2000:Formal Specification and Development in Z and B, pages 324 - 343, Lecture Notes in Computer Science, 1878, Springer, 2000.
- [10] B. Dehbonei & F. Mejia. Formal Development of Safety-critical Software Systems in Railway Signalling. In M.G. Hinchey & J.P. Bowen, editors, *Applications of Formal Methods*, Prentice Hall, 1995.

- [11] Derbyshire & Derbyshire. Political Systems of the World (2nd Edition). Oxford Helicon, 1996. ISBN 185 986 1148.
- [12] E.J. Dijkstra. A Discipline of Programming . Prentice-Hall, 1976.
- [13] R. Fraer. Minimum Spanning Tree. In E. Sekerinski & K. Sere, editors. Program Development by Refinement. Case Studies using the B Method. Formal Approaches to Computing and Information Technology. Springer, 1998.
- [14] D. Gries. The Science of Programming. Texts and Monographs in Computer Science, Springer, 1989.
- [15] J.P. Hoare.Application of the B-Method to CICS. In M.G. Hinchey & J.P. Bowen, editors, Applications of Formal Methods, Prentice Hall, 1995.
- [16] C.A.R Hoare, He Jifeng, and A. Sampaio. Normal form approach to compiler design. Acta Informatica, 30:701-739, 1993.
- [17] http://www.sgi.com/Technology/STL
- [18] C.B. Jones, Systematic Software Development using VDM (2nd Edition), Prentice Hall, 1990.
- [19] S. King. Z and the refinement calculus. In D. Bjorner, C.A.R. Hoare and H. Langmaack, editors, VDM'90:VDM and Z – Formal Methods in Software Development, Kiel, volume 428 of Lecture Notes in Computer Science. Springer, 1990.
- [20] K. Lano. The B Language and Method A Guide to Practical Formal Development. Formal Approaches to Computing and Information Technology. Springer, 1996.
- [21] D. MacQueen, R. Harper & R. Milner. Standard ML. Technical Report ECS-LFCS-86-2, Department of Computer Science, University of Edinburgh, 1986.
- [22] C.C. Morgan & T. Vickers, editors. On the Refinement Calculus. Formal Approaches to Computing and Information Technology. Springer, 1994.
- [23] C.C. Morgan. Programming from Specifications (2nd Edition). Prentice-Hall, 1994.
- [24] J.M. Morris. Laws of data refinement. Acta Informatica, 26:287–308, 1989.

- [25] P. Mukherjee & B.A. Wichmann. STV: A Case Stuy in VDM. National Physical Laboratory, Teddington, UK, 1993.
- [26] M.R. Poppleton. The Single Transferable Voting System: Functional Decomposition in Formal Specification. From - Conference Proceedings – IWFM'97 1st Irish Workshop in Formal Methods, Pages 1 - 18, 1997.
- [27] K.A. Robinson. Introduction to the B Method. From *Program Development by Refinement*, E. Sekerinski and K. Sere(Eds), Springer, 1999.
- [28] Seanad Éireann. Seanad General Election, February 1993, Government Publications, 1993.
- [29] I. Sorenson to M. Meagher Private Correspondence(e-mail), 12/11/99.
- [30] J. Michael Spivey. The Z Notation: a Reference Manual. Prentice Hall, 2nd edition, 1992.
- [31] M. Waldén. Distributed Load Balancing. In E. Sekerinski & K. Sere, editors. Program Development by Refinement. Case Studies using the B Method. Formal Approaches to Computing and Information Technology. Springer, 1998.
- [32] J. von Wright. The lattice of Data Refinement. Acta Inform., 31 (2) (1994) 105–135.
- [33] J. Woodcock & J. Davies. Using Z, Specification, Refinement and Proof, Prentice Hall, 1996.
- [34] J.B. Wordsworth. Software Engineering with B. Addison-Wesley, 1996.