

UNIVERSITY OF SOUTHAMPTON

**TECHNICAL DESIGN METHODOLOGIES
FOR ADVANCED FAST FERRIES**

by

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ABSTRACT

FACULTY OF ENGINEERING AND APPLIED SCIENCE
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The objective of the work has been to establish a technical design methodology for high speed ferries. The research programme comprised the development of a technical design framework for concept design of high speed ferries.

The approach has been to extend and build upon an existing research programme. In particular, this has entailed a fundamental examination and update of the section of the methodology dealing with estimation of dimensions, together with the establishment and manipulation of an effective mass estimate. Improvements and updating in the cost estimate have also been carried out.

Overall, the technical design framework has been established. It uses a flexible modular structure, allowing the quick generation of feasible designs. One of its major characteristics is that it uses a novel area based approach for the generation of a set of main dimensions, based on carrying capacities.

As high speed ferries are a relatively recent development, there is a lack of available systematic data and relevant techniques. Most major calculations are therefore performed using specialised data and tools created in the research programme, together with further modifications and updates. This allows the full investigation of the two most common hull configurations, namely monohulls and catamarans, which currently make up the majority of fast ferries.

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NOMENCLATURE AND UNITS

English Alphabet

A_P	Total passenger area (m^2)
A_S	Seating area (m^2)
A_V	Vehicle area (m^2)
B	Breadth (m)
b	Demihull breadth (m)
C_B	Block coefficient
C_F	Coefficient of frictional resistance (ITTC-57 Correlation line)
C_H	Hull costs (million US\$)
$C_{M/C}$	Monohull / Catamaran total building costs (million US\$)
C_{MA}	Machinery costs (million US\$)
C_O	Outfit costs (million US\$)
C_R	Coefficient of residuary resistance $\left[R_R / 0.5\rho AV^2 \right]$
D_{OA}	Overall depth (m)
E_C	Equipment numeral for catamarans
E_M	Equipment numeral for monohulls
F_N	Froude number
L_{OA}	Length overall (m)
L_{WL}	Length on waterline (m)
N_{CAR}	Number of cars
N_{CREW}	Number of crew
N_{DECK}	Number of decks
N_{PAX}	Number of passengers
P_B	Installed power per propulsion unit (kW)
P_I	Total installed power (kW)
P_S	Total service power (kW)
R	Range (nautical miles)
R_n	Reynolds number (VL/ν)
S	Separation of centrelines of demihulls (m)
SFC	Specific fuel consumption (kg/kW.h)
T	Draught (m)
V_S	Service speed (knot)
W_D	Diesel engine weight (tonne)

W_{GB}	Gearbox weight (tonne)
W_{GT}	Gas turbine weight (tonne)
W_H	Hull weight (tonne)
W_O	Outfit weight (tonne)
W_P	Propulsion weight (W_D (or W_{GT}) + W_{GB} + W_{WJ}) (tonne)
W_{RM}	Remaining machinery weight (tonne)
S_A	Wetted surface area (m^2)
W_{TM}	Total machinery weight (tonne)
W_{WJ}	Water jet weight (tonne).

Greek Alphabet

Δ	Displacement (tonne)
ν	Kinematic viscosity (m^2/s)
ρ	Density (assumed 1.025 t/m^3 for salt water)
∇	Displacement volume (m^3)

Abbreviations Used in the Computer Program & Examples of the Methodology

ABC	Approximate building cost (million US\$)
AP	Total passenger area (m^2)
AS	Seating area (m^2)
AV	Vehicle area (m^2)
B	Breadth (m)
BC	Building cost (million US\$)
BH	Demihull breadth (m)
BHOT	B_H / T
BOT	B / T
CB	Block coefficient
CGB	Gearbox cost (million US\$)
CH	Hull cost (million US\$)
CM	Total machinery cost (million US\$)
CME	Main engine cost (million US\$)
CO	Outfit cost (million US\$)
CP	Propulsion cost (million US\$)
CRM	Remaining machinery cost (million US\$)
CWJ	Water jet cost (million US\$)

D	Depth overall (m)
DIAM	Propeller diameter (m)
DISP1	$\Delta_1 = L_{WL} \times B \times T \times C_B \times \rho$ (for monohulls), $\Delta = 2 \times L_{WL} \times b \times T \times C_B \times \rho$ (for catamarans) (tonne)
DISP2	$\Delta_2 = LS + DWT$ (tonne)
DW	Deadweight (WFL+WFW+WCR+WPAX+WVEH) (tonne)
EFF	Efficiency (η)
FN	Froude number
LB	$L_{WL} \times B$
LOA	Length overall (m)
LOB	L_{WL} / B
LOBH	L_{WL} / B_H
LOD	$L / \nabla^{1/3}$
LS	Lightship (WH+WM+WO) (tonne)
LWL	Length on waterline (m)
NCAR	Number of cars
NCREW	Number of crews
NDECK	Number of decks
NE	Number of engines
NPAX	Number of passengers
PD	Delivery power (kW)
PE	Effective power (kW)
PI	Installed power (kW)
R	Range of vessel (nautical miles)
RN	Reynolds number
RPM	Engine speed (rpm)
S	Separation of centrelines demihulls (m)
SFC	Specific fuel consumption (kg/kW h)
SOL	S / L_{WL}
T	Draught (m)
VS	Service speed (knots)
WCAR	Car weight (tonne)
WCREW	Crew and effects weight (tonne)
WFUEL	Fuel weight (tonne)
WFWPROV	Fresh water and provisions weight (tonne)
WGB	Gearbox weight (tonne)

WH	Hull weight (tonne)
WM	Total machinery weight (tonne)
WME	Main engine weight (tonne)
WO	Outfit weight (tonne)
WP	Propulsor weight (tonne)
WPAX	Passenger and luggage weight (tonne)
WSA	Wet surface area (m ²)

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1. INTRODUCTION

1.1 DEFINITION OF RESEARCH

High speed marine vessels include all those craft used for marine transportation requiring a high cruise speed. In recent years they have received huge attention due to owners increasing demands for achieving faster and more efficient vessels. Designers quest is therefore to obtain suitable innovative designs.

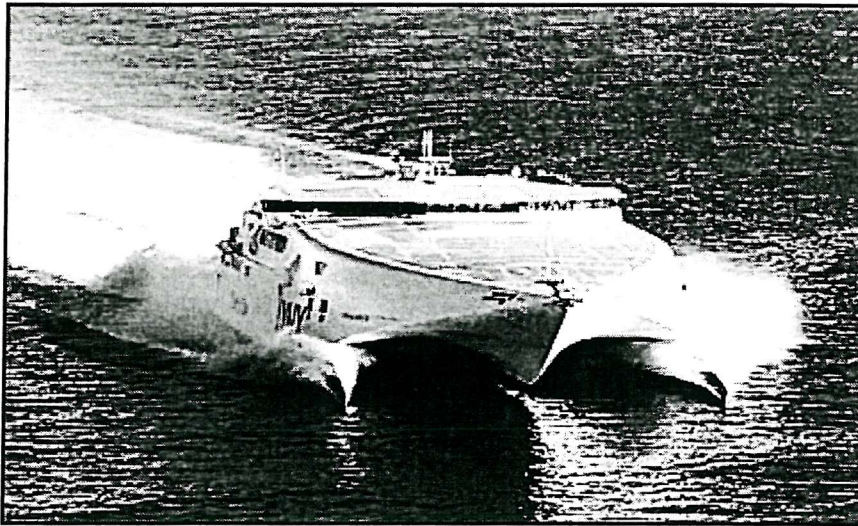


Figure 1.1: A Vehicle-Passenger Catamaran.

The ferry industry has, in the past few years, seen strong competition amongst builders and designers to obtain the best vessel for potential owners which has resulted in many different and varied designs, including hydrofoils, air cushion vehicles, and wing in ground effect craft. However, monohull and catamaran vessels still seem at present to be the most commercially effective.

The process of designing a vessel follows a series of iterations repeated a number of times until a final optimum design is achieved. The initial iterations could be termed the preliminary design of the vessel. From initial parameters defined by the owner, such as maximum payload, cruise speed, or others, the naval architect must determine dimensions for this new design, and develop from there the full design for a vessel. With the rapid increase in the use of high speed vessels it is apparent that there is a need for research in this area. As a result of these developments a research programme was initiated at the University of Southampton, aimed at addressing this subject and defining possible ways of arriving at rationalised solutions.

Previous research, Karayannis [16], was concerned with preliminary technical ship design and decision making processes for high speed displacement vessels. The current work extends this study including the form of data, regressions and formulae that can be used for the initial design estimations of feasible monohull and catamaran high speed ferries.

Figure 1.2 illustrates the overall framework for the whole methodology of the technical design process in the current research programme. The dotted boxes represent issues to be addressed in the future (work ongoing as separate research programmes) out of the scope of this thesis.

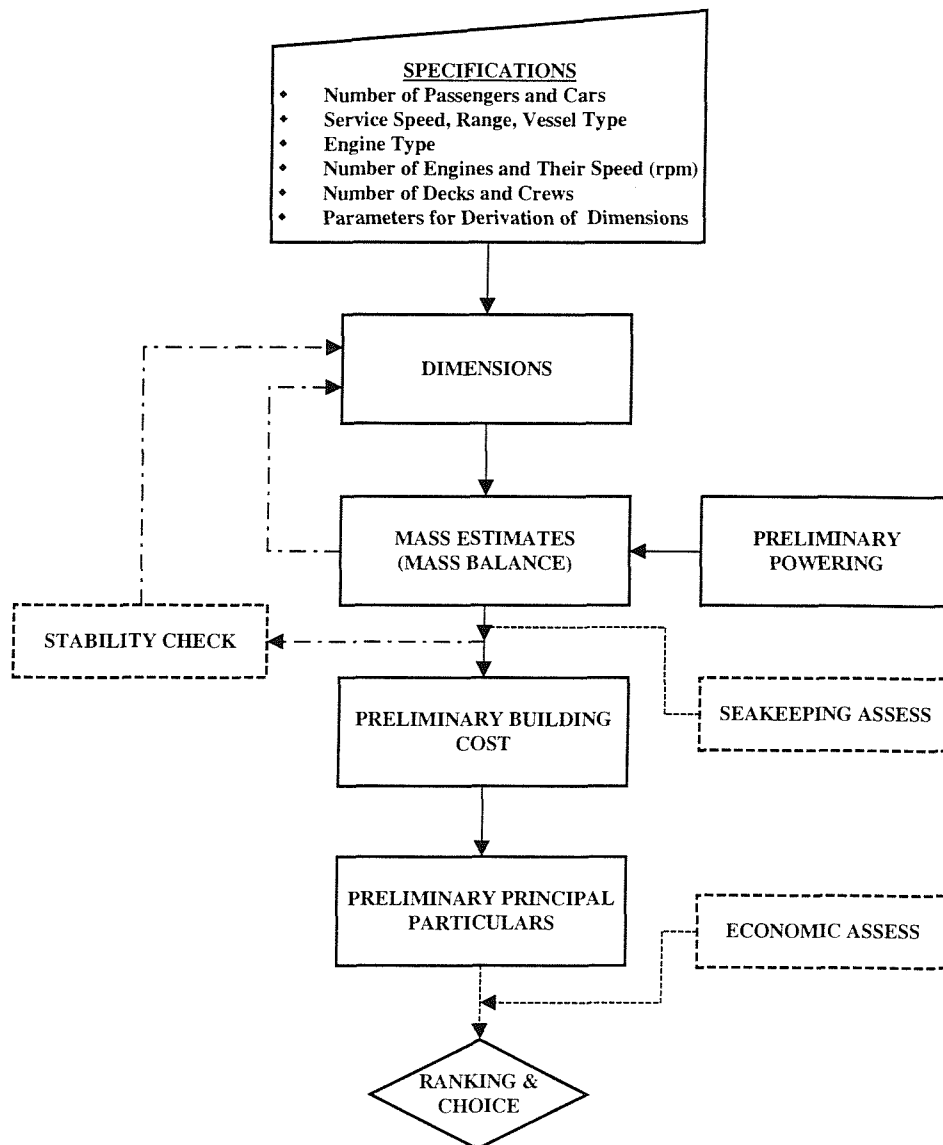


Figure 1.2: Overall Framework Flowpath.

A general methodology for the derivation of dimensions is presented in the chapter 2. The attached source database contains a comprehensive number of fast ferries of current technology operating around the world, as well as proposed new designs. The main objective has been to develop an algorithm for the derivation of main dimensions, which will ensure reliable estimates of initial dimensions employed in the overall design of fast ferries.

The estimation of power is described in chapter 3. The proposed methodology provides reliable results for the initial development of feasible monohull and catamaran high-speed ferry designs as well as an estimation of machinery masses.

Chapter 4 describes in detail the estimation of masses. The approach has been based on a database generated from historical data as well as parametric hull estimates based on classification society rules for parent monohulls and catamarans. Machinery mass data has been assembled together with data for performing outfit mass estimates. These masses and the estimation of total mass are included as feedback in the dimensions algorithm in order to verify a balance of masses, or to modify the dimensions accordingly until a balance is achieved.

A detailed building cost estimation is presented in chapter 5. The chapter contains hull, outfit and machinery costs. Chapter 6 embraces parametric design studies and a discussion of the results whilst chapter 7 draws together conclusions and recommendations.

The generated design database is given in Appendix I.

The design methodology is integrated in a computer program, which contains the main components of the preliminary technical design of a high speed ferry. The program provides main dimensions, estimation of masses, powering and building costs for monohulls and catamarans. A more detailed description of the program is included in Appendix II.

1.2 LITERATURE REVIEW

1.2.1 Background

The principal objective of this work has been to establish a design methodology for high speed ferries. The overall research programme comprises developing a technical design framework for high speed ferries.

The approach has been to extend and build upon the earlier work of Karayannis [16]. In particular, this has entailed a fundamental examination and update of the section of the methodology dealing with estimation of dimensions of fast ferries, together with the establishment of an effective mass estimate. Improvements in the estimate of building costs have also been introduced. Other important contributing topics, such as seakeeping, are to be dealt with in separate but complimentary research programme. These developments have been achieved by means of various references and sources of information which are critically reviewed in the following paragraphs.

Overall, a technical design framework is established. It employs a flexible modular structure, allowing the quick generation of feasible designs which can then be compared using the decision making module for further study.

As high speed ferries are a relatively recent development, available systematic data and relevant design techniques are sparse. Most of the current major calculations are therefore performed using data and tools created within the Department of Ship Science, together with further modifications and updates. Currently, this allows the full investigation of the two most common hull configurations, namely monohulls and catamarans, which make up the majority of fast ferries. In the event that further data becomes available, other investigations could be conducted for different hull configurations using the same methodology. The following paragraphs review published material of particular relevance to the present study.

A description of a parametric design trade-off study and the results of a preliminary design for a 50 knots SES passenger car ferry is given by Joo et al [14]. The parametric analysis presented begins by determining the optimum dimensions and subsystems for an initial set of design requirements. A trade-off study is then conducted to evaluate the influence of changing the design requirements, including variations in design speed, sea state and operational range. Parameters investigated include ship length, ship beam, engine type, propulsor type and type of structural material. This particular study proves that rational designs could be developed for conditions up to sea state 5. Following the trade-off study, a set of final design requirements were established and ship dimensions were selected for further design development. The preliminary design for an SES passenger car ferry currently being developed and some leading particulars of this design were presented in the paper.

A similar approach has been used by Litai [18]. The author gives an introduction to the design, trial and operation of the "Hong Xiang" an SES ferry. Concept analysis and calculations are followed by a model test programme. Several technical features were adopted in the design.

Litai considers the design to be a success, and advocates the implementation of an air cushion catamaran in situations where conventional catamarans had previously been used. The benefits envisaged are those of improved seakeeping ability and economic results.

Kraus et al [17] present a basic cargo catamaran design. The design has been created by means of comparative studies of three chosen systems. Cost and freight rates are both comparative factors to determine the best system. The main dimensions and required freight rates for this vessel are calculated and compared with actual air freight and shipping rates on specific routes.

Trincas et al [28] focus on the analysis of passenger and car traffic moved by shortsea shipping connecting Greece to Italy, using an improved multi-criterial decision making methodology for concept design of fast monohulls. This paper is a useful reference for outfit mass data and should be considered in future analyses.

Trincas et al [29] use a similar design tool as that of Joo et al [14]. It deals with a concept development and feasibility study of a large catamaran designed for the fast sea transport of passengers and vehicles in the medium range Mediterranean routes, intended to be more profitable than present fast monohulls. The concept design was carried out by means of a multi-attribute decision-making procedure to generate and select the best possible solution. Two variants of the selected design, one assuming a gas turbine as a faster solution and the other one assuming a diesel engine for the slower alternative, were then submitted to a feasibility study. An economic trade off study was accomplished to compare the investment worth of the projected catamaran to the 'Aquastrada' fast monohull. It is stated that the feasibility study provides good economic results. As the previous reference, this paper is also a useful source of outfit mass data, and should be taken into account in future studies.

Warren et al [30] concentrate on the choice and installation of water jets from a ship designer's point of view. It is extremely useful to expand knowledge on water jets.

The classical, Watson et al [31], reviews the design methods presented in 1962. It extends the proposed changes in ship design, and suggests some further developments to them. It considers how the relationships between dimensions, the coefficients and quoted approximate formulae have changed and why. This classic early paper is noted mostly for the much used formulae and initial weight estimations for conventional displacement vessels. Although, it was originally developed for conventional vessels, with caution and suitable alterations this work can be adapted for fast vessels as will be shown throughout this work.

1.2.2 Technical Design Studies

1.2.2.1 Creation of Database

An initial database was created employing data obtained from an extensive literature search. The database, included in Appendix I, was generated by modifying and expanding an initial database from a previous research programme, Karayannis [16]. The vast majority of data on existing fast ferries and new constructions as well as proposed new designs was found in journals, mainly from the Fast Ferry International journal, but also Ship and Boat International and Naval Architect journals. Measurements, calculations and manipulation of the original data were required in order to derive sets of comparable vessel data suitable for the database.

A large number of high speed ferries are logged into the database. Most of them are already operating throughout the world, while some are at the stage of construction, or at least completed design. The vessels are divided into two major categories, passenger-only and vehicle-passenger carriers. A secondary distinction is made between monohulls and catamarans. Therefore four separate databases were created, namely for passenger-only monohulls (PM), passenger-only catamarans (PC), vehicle-passenger monohulls (VM) and vehicle-passenger catamarans (VC). It should also be noted that the database concerning catamarans also includes separately the other multihull types even though no algorithms have as yet been developed for them.

All relevant information was included in the databases, namely dimensions, weights, capacities, speed, range, propulsive installations, and other additional information. Furthermore, ratios were derived in order to be used in the design procedure. A significant factor was the availability or not of general arrangement plans since passenger and vehicle areas can have important influence in determining the size of each vessel. Therefore, for the vessels whose general arrangement plans were available, areas were measured and ratios calculated.

The number of vessels in the database (also included in Appendix I) is adequate to allow reliable analysis of the relevant data. The significant features of the data are included in the thesis as tables or design equations.

1.2.2.2 Estimation of Dimensions

An introduction to alternative ways based on modern hull forms, to estimate main dimensions and coefficients in preliminary ship design for conventional ships is given by Guenther [2]. In

this paper, the desired technical characteristics have been achieved with ships of greatly differing lengths. The length is determined from similar ships or from formulae and diagrams derived from a database of similar ships. The resulting length then provides the basis for finding the other main dimensions. Although the technique used in the paper is reasonably accurate, it is not suitable for research dealing with sparse data, such as the present one.

Karayannis et al [15] present systematic data and propose algorithms and formulae, which can be used for investigations of high speed ferry designs of monohull and catamaran configurations. These include initial estimations of technical aspects such as main areas and dimensions, and hull, machinery, outfit and total masses, as well as acquisition costs.

Molland et al [19] develop a global design model for the derivation of the technical and commercial attributes for monohulls and catamarans, together with the investigation of the potential of alternative decision making techniques and the implications of incorporating these into the overall concept exploration framework. Molland et al [20] describe the overall framework as well as details of the design modules and discuss the implications of applying different decision making techniques to select the more suitable vessel type and specification for a specific role.

1.2.2.3 Estimation of Masses

Cordano [5] gives a broad idea of the design criteria adopted in the development of the SES 500 – Fincantieri fast ferry. The author considers some special parameters for a technical selection and summarises these parameters as seakeeping with particular regard to the passenger comfort and transport efficiency. The paper contains costing estimations for construction and operation, and concludes with stating that the resulting design has an optimum size and high speed with a limited power and low operating cost.

Czimmek's [6] work is based on a conceptual design for a large surface effect ship (LSES), which was developed by Newport News Shipbuilding and Dry Dock Company (NNS) with the assistance of Marine Dynamics. Design optimisation and sensitivity studies were performed, using the NNS in-house surface effect ship optimisation program. In order to produce a viable design point, which could be evaluated for productivity and risk, computer-based parametric studies were performed with cushion length, cushion beam and cushion pressure as variables.

Both these last two papers contribute in expanding the understanding of the methodology in concept design.

In Daidola [7], a standard for weight definition and an approach to weight control are presented for modern motor yachts and other craft. It includes a definition of weight and loading conditions for these vessels, which can be related to attainable vessel speeds. The weight control plan addresses concept through detail design, construction, delivery and service life. The author states that the procedure is adaptable to all types of hull structural material. The weight curves developed in this paper are obtained from the regression of vessel data. The paper presents a formal approach to weight control of craft of all types. The author states that, although it may seem a substantial and onerous system to apply to all craft designs, especially where little has been done before, in reality the concepts are few and the analysis and reporting efforts can be tailored to the needs of any project.

Fan et al [10] investigate the options available to the designer dealing with the structure of a high speed vessel, under the current regime of prescriptive classification regulations. Three different classification societies were selected for the investigation. Their conceptual approach to structural design is identified and compared, and detailed scantlings are derived using their rules for a representative fast catamaran. Based on these, a rudimentary comparison of the structural weight of a unit length of midship section is then presented. The paper concludes with a proposal for a new unified philosophy for the design of efficient high speed craft with consistent levels of safety. The feasible design studies from this paper have been included into the current study. The results were very useful when considering mass estimations.

Hughes [12] presents a strategy for achieving a first principles optimum structural design of a ship using modern computer-based tools, and demonstrates its feasibility with a large monohull fast ferry. The paper has two major goals; first of all to present a strategy for achieving a first principles optimum structural design of a ship (especially a high performance ship) using modern computer-based tools and second, to demonstrate the strategy for a large (100 m, 1000 t) monohull fast ferry, first using all aluminium and then adapting the design to be all composite. Two designs are produced with the 'Maestro' program, which is capable of performing optimisation based on trade-off of cost and weight. This particular reference demonstrates how computer-based design tools and a first principles approach can be used to obtain an optimum structural design of a high performance ship such as a fast ferry, and how these tools are evolving to handle composites as well as metals.

The previous research carried out at the University of Southampton, in the Department of Ship Science for preliminary technical fast ferry design and decision making process provides the major basis for the present research programme. Karayannis et al [15, 16, 19, 20] contain the

most useful information in estimation of masses as well as derivation of dimensions. These sources will be mentioned throughout the thesis where necessary.

In Sainz [23], a tool is developed to determine the components of a structural design, and a mass estimate, using the newly created Lloyd's register 'Special Craft' software. The estimations have been carried out only for monohulls and catamarans. This particular reference is a major source of hull mass estimation calculations, and uses a design tool similar to that of Fan et al [10] and Watson et al [31].

Vrontorinakis [29] assesses diesel engines and gas turbines rated for the propulsion of fast ferries through the use of nineteen common operating parameters. Their technical attributes are compared with each other in four power ranges, and in multiple installations specifically for chosen catamarans and monohulls. Elements of propulsors (water jets) are also generally discussed, and the matching requirements are investigated for all cases. It is, in general, an important reference of machinery mass and cost data.

Wood et al [32] provide a major contribution to the database generated in the current research programme, as it contains existing ship data for mass estimation and mass balance calculations. It discusses some of the design issues including the IMO High Speed Craft Code, classification and problems encountered when the British-designed 318 passenger, 45 knot TRICAT ferry was adapted for construction and operation in the United States. The paper also describes some of the design issues involved in implementing the high speed craft within the framework of passenger ferries under 100 GT, including lowering the tonnage to be less than 100 GT, the use of Det Norske Veritas for classification plan approval, and the use of US suppliers of materials and equipment.

1.2.2.4 Estimation of Powering

In the earlier stages of the research programme, Karayannis [16], the calculation of calm water resistance was performed using existing standard series data. The module included data from the NPL Series Bailey [1], Series 64 Yeh [34] and Southampton Extended NPL Molland et al [22] in monohull mode. A new catamaran mode was implemented including Series 64 and Molland et al [21]. Molland includes the catamaran series tested at Southampton, one of the most comprehensive sets of data available. The extension of the analysis to include catamarans, offers a wider range of block coefficients and higher $L/\nabla^{1/3}$ ratios. Detailed information about these particular sources of information is given in the following paragraphs.

A series of high speed monohull model hulls of round bilge shape designed for operation in the Froude number range, $F_N=0.3-1.2$ was tested at NPL Bailey [1]. The monograph presents data that can be used at the early design stages of marine vessels such as heavily loaded workboats, fast patrol craft and small naval ships. Resistance and source limited propulsion data are presented in a simple form enabling predictions to be made of the calm water speed and power requirements for a given design, a worked example is appended to illustrate the process. Stability underway, manoeuvring and seakeeping characteristics are discussed in the light model test results obtained from a representative selection of designs based on the series.

Yeh [34] reports the results of the hull resistance tests of Series 64 models. After preliminary investigation, 27 models of conventional round bilge hull forms were designed, constructed, and tested at the David Taylor Model Basin to gain information for a wide range of length-displacement ratios and speed-length ratio.

In Insel et al [13], a wide range of hull separations was tested and, overall, the experiments covered over 40 model configurations, each over a speed range up to a Froude Number of unity. Molland et al [22] extended the parametric investigation to cover changes in Breadth/Draught ratio (B/T) and a wider range of Length/Displacement ratios ($L/\nabla^{1/3}$).

Molland et al [22] summarizes an experimental investigation into the resistance components in calm water of high speed displacement catamarans with symmetric demihulls. The experimental programme was a development and extension of an earlier work in which a small series of three catamaran models were tested. Total resistance, running trim, sinkage and wave pattern analysis based on multiple longitudinal cut techniques were carried out for ten round bilge hulls derived from the NPL series. The tests were conducted over a Froude number range of 0.2 to 0.1 and separation to length ratios of 0.2, 0.3, 0.4, 0.5 and infinity. The results of the investigation provide a better understanding of the components of catamaran resistance including the influence of hull separation, length-displacement ratio and length-beam ratio over a wide range of Froude numbers.

These two main references on the resistance of high speed displacement catamarans have been used by Buckland [3] to provide data for the NPL and Series 64 round bilge series in an alternative form, using interference factors. Using the references as the sources of data, Buckland produced a rationalised resistance estimate procedure for both catamaran and monohull configurations to be utilized at the preliminary design stage. This procedure has been applied in the current work using the NPL Series for illustration.

Molland et al [21] describe further model tests on a catamaran in calm water with a hull form based on Series 64 round bilge hull form. The model was tested in monohull form and at two hull separations in catamaran configuration, in each case over a speed range up to a Froude number of unity. The information collected and represented in the report contributes to a further understanding of resistance of catamarans and provides resistance data for practical use at the preliminary design stage. The investigation provides an extension to the available resistance data for this vessel type, and the results are broadly similar to those for other round bilge forms. The catamaran/monohull resistance interference factors are also similar to other forms. This offers the potential for the development of general interference factors, which would not have a significant dependence on the particular hull shape.

To summarize, Bailey [1], Yeh [34], Molland et al [21] and [22] provide a wide range of data for round bilge monohulls and catamarans and provide the basis for the powering estimates in the current research programme.

Guenther [11] describes preferred prime mover choices for high speed marine transportation. It also gives details about compact high speed diesel engines and aero-derived gas turbines.

Svensson [24] and [25] provides information on water jets, and the advantages and disadvantages when selecting water jets as propulsors.

1.2.3 Costs Studies

The building cost of a ship is a function of several variable types such as technical, physical, managerial, financial, political and temporal. Its complete estimation calls for inputs from a range of disciplines. From the size of the vessel (L , B , D , T and C_B) and speed, V , the designer can estimate service propulsive power, P , and a first estimate of light displacement, consisting of separate values of steel, outfit and machinery weights. This stage is reached in the normal course of the early design procedure. At this point, given an indication of current labour and material costs, a preliminary costing can be achieved, as will be shown later. The reasons for costing at this early stage are to get an idea of the capital investment involved and to see how the cost might be affected by altering any of the principle variables, when the design is still sufficiently flexible.

The current research reported in this thesis involves costing at the building cost stage. Most of the calculations have been carried out by use of the methodology and data mentioned earlier. Other relevant references for the calculation of building costs are critically reviewed next.

Caryette [4] is a classical and much quoted work, which proposes a method for assessing the approximate capital cost of merchant ships at the very early stages of design. It is intended as a guide to ship designers and others who may wish to know the ship building cost at the beginning of a new project, and how it changes with alterations to principal design variables such as dimensions, weights, powering or carrying capacity. The outcome of the paper was to show that, there is an equation suitable for a wide range of merchant ship types, large or small, fast or slow. The author shows that the dimensions and weights largely determine the steelwork and outfit costs, and powering governs the machinery cost. The method described in this paper has been applied to merchant ships, but its philosophy can be expanded, and its costs adjusted and updated to suit fast ships, or any large marine structure.

Vrontorinakis [29] assesses diesel engines and gas turbines suitable for the propulsion of fast ferries though the use of 19 common operating parameters. Their technical attributes (power, mass, cost, etc.) are compared with each other in four power ranges, and in multiple installations specifically for chosen catamarans and monohulls. Elements of propulsors (water jets) are also generally discussed, and the matching requirements are investigated for all cases. The prime movers are utilized in their speed groups 35, 40 and 47 knots, which include a catamaran and a monohull each. Alternative engine installations are assessed technically, for the specific group requirements, and economically for a ten year period. Both average annual cost and net present value methods are used to choose the best installation for each ship. The thesis concludes by giving information about the advantages and disadvantages of the prime movers, as well as of the alternative engine installations for the catamarans and monohulls. Wright [33] describes the various types of high speed craft (air supported, foil supported, displacement hull, planing hull), and analyzes their suitability for certain passenger routes in different operating environments. The author also compares the transport and commercial efficiencies of a number of existing craft of mixed sizes and services. It concludes with a discussion on the economics of high speed craft service and the many factors that bear upon optimum craft selection for a particular route and operating environment.

1.2.4 General Discussion

A survey of relevant literature on the fields related to this research programme has been critically reviewed. This includes references on the various aspects of design, particularly in the conceptual and preliminary stages.

High speed ferries require a specialised approach to their concept design. This is due to a number of special characteristics these craft possess, mainly; the wide variety of hull configurations and types available for high speed ferry services and the subjective nature of passenger requirements which can affect the commercial potential of high speed ferries.

There is a lack of available historic data or systematic data as well as design tools and techniques for high speed ferries. Existing published data and tools for conventional vessels cannot be directly applied to high speed ferries since they possess distinct characteristics such as lightweight construction materials and different economic parameters. These vessels represent a relatively recent development. There is therefore scope for a systematic design methodology for high speed ferries. The methodology must be both robust and flexible in order to cope with this relatively recent but rapidly developing vessel category.

2. DIMENSIONS

2.1 BACKGROUND

The first step in the ship design process generally entails the calculation of an initial set of main dimensions. Main dimensions can have significant effects on major design aspects of the vessel, such as masses, powering and costs. Determining these main dimensions and ratios is therefore particularly important for the overall design. Historic data provide the starting point in their estimation process. Once a set of these dimensions has been selected it may then be modified if basic aspects such as masses are not adequate.

The main parameter influencing the initial set of main dimensions is the capacity of the vessel. This is obvious since carrying capacity directly affects the overall size of any ship. The use of this main parameter is also desirable from a practical point of view as it is, probably together with speed and range, the more likely basic requirement of a shipowner or an operator.

Karayannis's [16] study revealed that passenger and vehicle capacities seem to be the only parameters influencing the derivation of an initial set of main dimensions. Froude number, as a function of speed, did not show any significant correlation with the main hull ratios, such as L/B , B/T or $L/\nabla^{1/3}$. This can be clearly seen by the data plots of L/B against Froude number in Figures 2.1 and 2.2. The effect of speed on hull coefficients and ratios is therefore not included in the first estimate of dimensions although it is included indirectly in the power estimate and mass balance.

Further analysis of the database made it clear that an area based approach should be applied for the estimation of an initial set of main dimensions, Karayannis [16]. The effect of cargo capacity on main dimensions of the vessel that can be seen in Figures 2.3 to 2.6 follows this approach. All these figures are dealt with in sections 2.1.1 and 2.1.2. An overall description of the approach is described in section 2.2.

Karayannis's method for deriving an initial set of main dimensions was modified to incorporate the estimation of an initial depth (D), which, as will be seen later, increased the accuracy of the preliminary mass calculations. New modified estimated dimensions can then be used to calculate an initial lightship and deadweight for passenger-only monohulls, passenger-only catamarans, vehicle-passenger monohulls and vehicle-passenger catamarans.

As stated earlier, a database including a reasonable number of high speed ferries had been created from the analysis of historic data. The database was modified and extended (around 40%) during the current study. Detailed explanation about the database can be found in Appendix I. The new database coefficient ranges are given in Table 2.1.

2.1.1 Passenger-Only Monohulls and Catamarans Database

The parameters employed during the derivation of initial main dimensions are related to the cargo capacity of the vessels. As mentioned earlier, the estimation method is based on a cargo area based approach. The parameters corresponding to passenger monohulls and catamarans are seating area (A_s), passenger number (N_p), passenger area (A_p) and $L_{WL} \times B$. The following part of this section explains the use of these parameters and how are they included into the study.

A_s/N_p coefficient determines the level of accommodation quality in terms of area provided to passengers. Figures 2.3.a and 2.4.a display the correlation between seating area (A_s) and number of passengers (N_p) for passenger-only monohulls and catamarans respectively. In the database, this coefficient ranges between $A_s/N_p=0.55$ to 0.75 for passenger-only monohulls, and $A_s/N_p=0.55$ to 0.85 for passenger-only catamarans. This is shown in the figures by including the linear $A_s/N_p=0.55$, 0.65 and 0.75 trend lines for passenger-only monohulls and $A_s/N_p=0.55$, 0.70 and 0.85 trend lines for passenger-only catamarans.

The A_s/N_p range is not the same for passenger catamarans and monohulls. The difference could show that the quality of accommodation on passenger catamarans might be higher than on passenger monohulls. This could be caused by fare prices, journey range, or the frequency of use by certain group of passengers.

The coefficient A_p/A_s allows the designer to select the desired amount of additional spaces used by passengers. The correlation between seating area (A_s) and total passenger area (A_p) for passenger-only monohulls and catamarans is included in Figures 2.3.b and 2.4.b respectively. This coefficient varies between $A_p/A_s=1.1$ and 1.3 for both passenger-only monohulls and catamarans. This is reflected in the linear $A_p/A_s=1.1$, 1.2 and 1.3 trend lines.

Figures 2.3.c and 2.4.c illustrate the relationship between $L_{WL} \times B$ and total passenger area (A_p) for both passenger-only monohulls and catamarans. The obtained regression equations 2.1, 2.2 give a very good correlation between prediction and response (in most cases $R^2 > 0.9$). The value R^2 representing the reliability of the trend line, $R^2=1$ indicating a perfect correlation.

This means that the algorithm is reliable and its outcome can be trusted as a good initial set of dimensions for the current method of estimating mass, hence high values of R^2 are indication of a good fit to data for the equation.

The regression for passenger-only monohulls is given as follows.

$$L_{WL} \times B = 146 + 1.86 \cdot 10^{-3} \cdot A_p^2 \quad R^2 = 0.99 \quad 2.1$$

Whereas the regression for passenger-only catamarans is,

$$L_{WL} \times B = 138 + 0.910 \cdot A_p \quad R^2 = 0.76 \quad 2.2$$

The design algorithm is covered in section 2.2.

2.1.2 Vehicle-Passenger Monohulls and Catamarans Database

The design parameters for vehicle-passenger monohulls and catamarans are seating area (A_s), passenger number (N_p), passenger area (A_p), vehicle number (N_v), vehicle area (A_v) and product $L_{WL} \times B$.

Figures 2.5.a and 2.6.a display correlation between number of passengers (N_p) and seating area (A_s) for vehicle-passenger monohulls and catamarans respectively. This part of the database data ranges between $A_s/N_p=0.9$ to 1.3 for both vehicle-passenger monohulls and catamarans. This is shown in the figures by including the linear $A_s/N_p=0.9$, 1.1 and 1.3 trend lines.

The variation of A_p/A_s coefficient is shown in Figures 2.5.b and 2.6.b for vehicle-passenger monohulls and catamarans. It varies between $A_p/A_s=1.1$ to 1.5 for both vehicle-passenger monohulls and catamarans. This is again shown in the figures with the linear $A_p/A_s=1.1$, 1.3 and 1.5 trend lines.

Figures 2.5.c and 2.6.c display the correlation between number of vehicles (N_v) and vehicle area (A_v) for vehicle-passenger monohulls and catamarans respectively. $L_{WL} \times B$ is then estimated as a function of total passenger and vehicle areas (A_p and A_v). The regressions give again a very good correlation between predictor and response (in most cases $R^2 > 0.9$). The algorithm is therefore reliable enough so as to be used in the mass estimation.

Regression equations for vehicle-passenger monohulls are as follows.

$$A_V = 156 + 10.2 \cdot N_V \quad R^2 = 0.92 \quad 2.3$$

$$L_{WL} \times B = 121 + 0.27 \cdot A_P + 0.60 \cdot A_V \quad R^2 = 0.98 \quad 2.4$$

The corresponding equations for vehicle-passenger catamarans are given as.

$$A_V = 12.4 \cdot N_V \quad R^2 = 0.99 \quad 2.5$$

$$L_{WL} \times B = 471 + 0.55 \cdot A_P + 0.28 \cdot A_V \quad R^2 = 0.80 \quad 2.6$$

The design of the algorithm is explained in section 2.2.

Calculations have been carried out for passenger-only monohulls, passenger-only catamarans, vehicle-passenger monohulls and vehicle-passenger catamarans. The forms of the formulae are the same for each vessel, while the numerical factors vary. The derived formulae and data limits are given in Table 2.2. The table also displays database ranges of main design ratios and particulars of the vessels. These are as follows;

- Separation of centrelines of demihulls, length ratio (S/L)
- Length displacement ratio ($L/\nabla^{1/3}$)
- Breadth, draught ratio (B/T)
- Demihull breadth, draught ratio (b/L)
- Block coefficient (C_B)
- Length overall, length waterline ratio (L_{OA}/L_{WL}).

Table 2.2 also displays the overall depth values for monohulls and catamarans. Estimation of depth is explained in section 2.2.

2.2 ESTIMATION OF MAIN DIMENSIONS

Two design flowpaths were created by Karayannis [20], which illustrated the area-based approach. A new improved version is shown in Figures 2.7.a and 2.7.b, where a mass balance is now included within the procedure for the derivation of dimensions.

In these flowcharts, the number of passengers (N_p) and vehicles (N_v) are the inputs. Seating area (A_S) is calculated as a function of passenger number (N_p), but variations are possible within reasonable limits dictated by the existing data, allowing the designer to select the desired level of seating comfort. In the same way, variations are possible for the passenger-seating area ratio (A_p/A_S) used for the calculation of passenger area (A_p).

A three-stage calculation ($N_p \rightarrow A_S \rightarrow A_p \rightarrow L_{WL} \times B$) was preferred by Karayannis as it allowed more freedom in providing the vessel with the desired level of accommodation quality, in terms of areas provided to passengers. Instead of the three stage procedure used here, a two-stage ($N_p \rightarrow A_p \rightarrow L_{WL} \times B$) or even one stage process ($N_p \rightarrow L_{WL} \times B$) could have been applied. This would make the algorithm much simpler, but would not allow for variations from the default areas.

2.2.1 Passenger-only and Vehicle-Passenger Monohulls

To obtain a solution for L and B, suitable first estimates of the L/B ratio and LxB product are input.

L/B is based on hull hydrostatic and hydrodynamic requirements and assumptions for $L/\nabla^{1/3}$, C_B and B/T;

$$\frac{L}{B} = \left[\left(\frac{L}{\nabla^{1/3}} \right)^3 \times C_B \times \frac{T}{B} \right]^{1/2} \quad 2.7$$

LxB is a function of required passenger and vehicle areas;

$$L \times B = f(A_p, A_v), \quad 2.8$$

where $A_S = f(N_{PAX})$, $A_p = f(A_S)$ and $A_v = f(N_{CAR})$.

Suitable forms of equations 2-7 and 2-8, as well as ranges of the design parameters, can be derived from the data presented in Table 2.2. From this a solution for both length and displacement can be determined as follows;

$$L = \left[(L \times B) \times \left(\frac{L}{B} \right) \right]^{1/2} \quad 2.9$$

B can be determined from L/B , and T from B/T ,

$$\Delta = L_{wl} \times B \times T \times C_B \times \rho \quad 2.10$$

2.2.2 Passenger-only and Vehicle-Passenger Catamarans

In the case of catamarans, instead of the overall beam (B) for the initial calculations, the demihull beam (b) has been used. The separation of the demihull centrelines (S) is used as an additional parameter in the form of an S/L ratio, varied within the range dictated by the data in the database. Overall beam is then simply derived as $B = S + b$. For catamarans, L/B is derived as;

$$\frac{L}{B} = 1 / \left[\frac{S}{L} + \frac{b}{L} \right] \quad 2.11$$

L/b is then derived as;

$$\frac{L}{b} = \left[\left(\frac{L}{\nabla^{1/3}} \right)^3 \times C_B \times \frac{T}{b} \right]^{1/2} \quad 2.12$$

In this case displacement volume (∇) refers to one of the hulls, and the catamaran displacement then becomes;

$$\Delta = 2 \times L_{wl} \times b \times T \times C_B \times \rho \quad 2.13$$

From the equations and database, an initial set of main dimensions of the vessel and the other parameters can be established using mid-range values in Table 2.2 as starting points.

Depth is an important parameter for hull mass estimates and stability calculations, although it has no significance for hydrodynamic performance calculations. In the current work, overall depth, D_{OA} , (including the superstructure) is calculated as a function of B, by using the available data in the database. This study is explained in section 2.3. It should be emphasised

that the overall depth D_{OA} is an approximate value used primarily in the equipment numeral for hull and superstructure mass estimates.

As discussed earlier, the principal hull parameters did not show any reliable trends with speed. Thus, the initial estimate of dimensions is based only on passenger and vehicle requirements. This does create an anomaly in the design procedure in that, for example, a change in speed for a particular design, whilst retaining the same passenger and vehicle requirements, results in a change in propulsive power and machinery mass and hence overall mass balance. This problem is overcome by incorporating a mass balance directly within the procedure for the derivation of dimensions as shown in Figures 2.7.a and 2.7.b.

In the design path, Figures 2.7.a and 2.7.b, suitable values for $L/\nabla^{1/3}$, C_B and B/T are chosen and introduced into equation 2-7. These may then be modified in further design iterations in order to achieve a satisfactory balance of masses. There are several ways in which the parameters may be modified, but an approach which has been found to be efficient and satisfactory is to retain overall constancy of L/B , hence constant L (from equation 2-9), which results in constancy of equation 2-7. Hence for constant L/B , combinations of $L/\nabla^{1/3}$, C_B and B/T within equation 2-7 may be chosen depending on any other design constraints. For example, for fixed ∇ and $L/\nabla^{1/3}$, C_B and B/T can be increased to retain constant ∇ . Allowing a change in ∇ , C_B and $L/\nabla^{1/3}$ may be changed with B/T constant, or B/T and $L/\nabla^{1/3}$ changed with C_B constant or suitable changes to both B/T and C_B . The procedure for catamarans is similar, but using equations 2-11, 2-12 and 2-13. These procedures are demonstrated later in chapter 6 by comparing similar vessel requirements but at different speeds. Details of the mass estimates are given in chapter 4.

The dimension module has been developed to a reliable level. It must be kept in mind, however, that as the method is based on data from existing vessels it may not be safe to use outside the limits of the database, as extrapolations may not be reliable.

The database can be constantly updated and expanded, as new vessels are added to it. This would enhance the strength of the database and, in consequence, that of the method.

2.3 ESTIMATION OF DEPTH

Length, beam, draught and depth are the four main ship dimensions. The existing method was not capable of finding all of them. Only three of these main parameters were obtained, namely length, beam and draught. To complete the estimation of these four main dimensions, a study

carried out for the calculation of an initial depth. Depth is crucial for the derivation of hull mass estimation. A fast ferry's structure is made up of a combination of hull and superstructure. As opposed to conventional cargo ships, the superstructure of a fast ferry takes a big part from the whole structure of the vessel. Depth is therefore a main requirement in the hull mass estimation process. The estimation of hull mass is explained in more detail in section 4.1. In this section the duty of depth is clearer.

Depth has been correlated with overall length, overall beam and draught using data available from the database. Each correlation is repeated for catamarans and monohulls individually. The plots for monohulls are shown in Figures 2.8.a, 2.8.b and 2.8.c, and the plots for catamarans are Figures 2.9.a, 2.9.b and 2.9.c.

Since a fast ferry's superstructure takes the biggest part of the vessel and is built as part of the hull, the overall depth is taken as the height between keel and the highest point of the superstructure. This is illustrated in Figure 10.

From the correlations, the good linear relationship between overall depth and overall beam for both monohulls and catamarans was evident as Figures 2.8.b and 2.9.b show. The plot between overall depth and draught and overall length however, did not show a very good correlation. The data plots look very sparse.

Two equations were obtained from Figures 2.8.b and 2.9.b for monohulls and catamarans as follows;

$$D_{OA} = 4 + 0.6 \cdot B_{OA} \text{ for monohulls} \quad 2.14$$

$$D_{OA} = 4 + 0.44 \cdot B_{OA} \text{ for catamarans} \quad 2.15$$

Predicted results have been obtained from the above regression equations and have then been compared with actual ship depths included in the database. This study was undertaken to test the accuracy of the predicted results against actual data. The predicted results and actual data plots are shown in Figures 2.11.a and 2.11.b for monohulls and catamarans respectively.

A computer program written in FORTRAN has been developed to include all these main components of the concept design of fast ferries, for passenger monohulls, passenger catamarans, vehicle monohulls and vehicle catamarans. More detailed information about this program is given in Appendix II.

Vessel Type	N_P	N_V	Vs (kn)
Passenger-only Monohull	49-925	-	24-60
Passenger-only Catamaran	50-650	-	25-45
Vehicle-Passenger Monohull	400-1800	<450	28-45
Vehicle-Passenger Catamaran	150-1500	<450	28-43

Table 2.1: High Speed Ferry Database Range.

Item	Passenger-only	Passenger-only	Vehicle-Passenger	Vehicle-Passenger
	Monohulls	Catamarans	Monohulls	Catamarans
LxB	$146+1.86 \times 10^{-3} A_P^2$	$138+0.91 A_P$	$121+0.27 A_P+0.60 A_V$	$471+0.55 A_P+0.28 A_V$
A_S/N_P	0.55-0.75	0.55-0.85	0.85-1.25	0.80-1.40
A_P/A_S	1.10-1.30	1.10-1.30	1.15-1.45	1.30-1.70
A_V	-	-	$156+10.2 N_V$	$12.4 N_V$
S/L	-	0.20-0.25	-	0.20-0.25
$L/\nabla^{1/3}$	5.0-7.5	8.0-10.5	6.5-9.0	8.5-11.0
majority	5.5-6.5	8.5-9.5	7.0-8.5	9.5-10.5
B/T	3.5-8.5	-	3.5-7.5	-
Majority	4.0-6.5	-	4.5-6.5	-
b/T	-	1.5-3.0	-	1.5-3.0
D_{OA}	$4+0.6B$	$4+0.44B$	$4+0.6B$	$4+0.44B$
C_B	0.35-0.45	0.40-0.55	0.35-0.45	0.40-0.55
L_{OA}/L_{WL}	1.13-1.15	1.13-1.15	1.13-1.15	1.13-1.15

Table 2.2: Design Equations and Range of Parameters for Derivation of Dimensions.

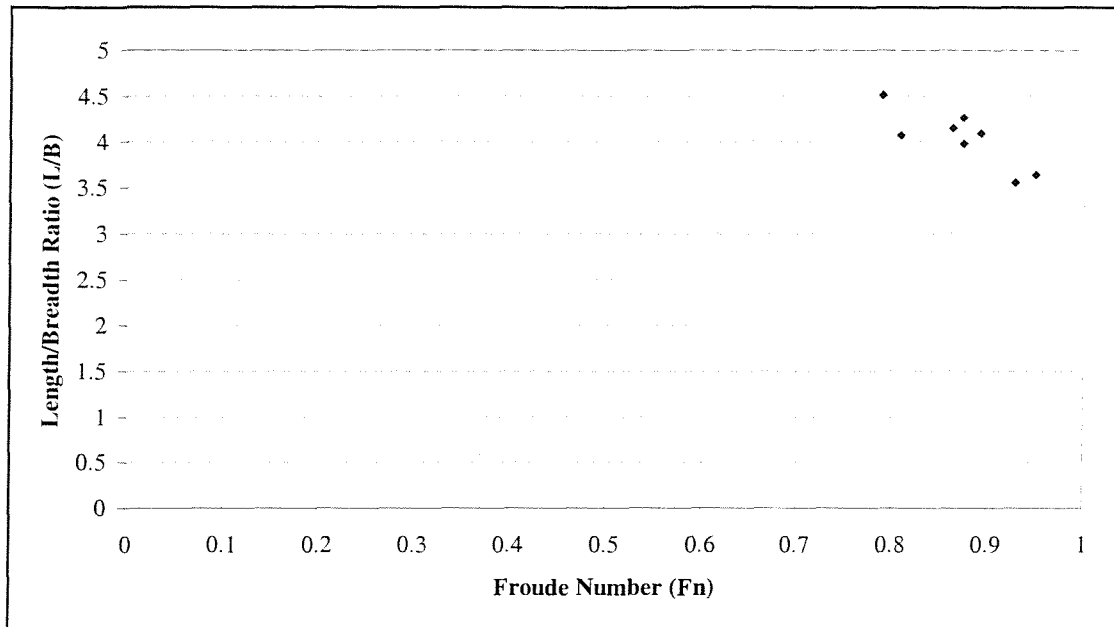


Figure 2.1.a: Relation between Fn and L/B for Passenger-Only Monohulls.

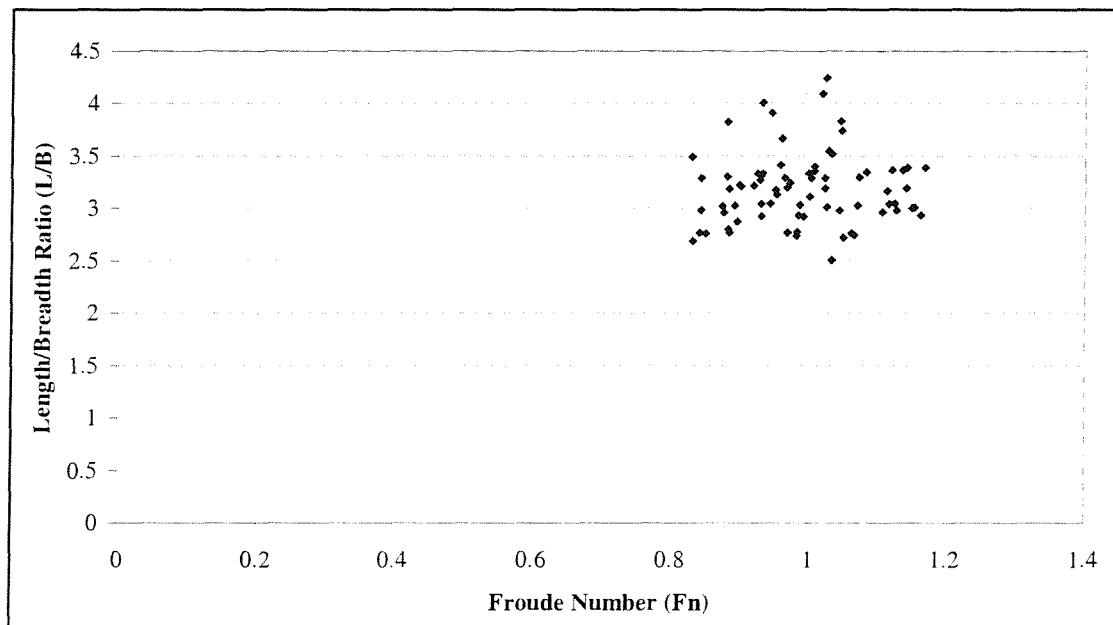


Figure 2.1.b: Relation between Fn and L/B for Passenger-Only Catamarans.

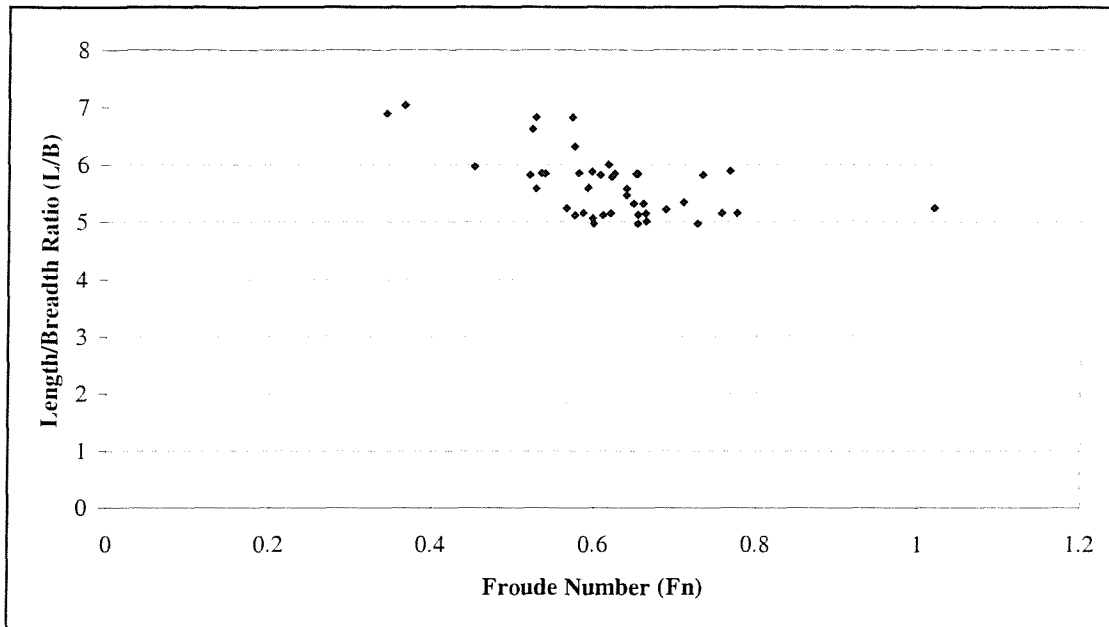


Figure 2.2.a: Relation Between Fn and L/B for Vehicle-Passenger Monohulls.

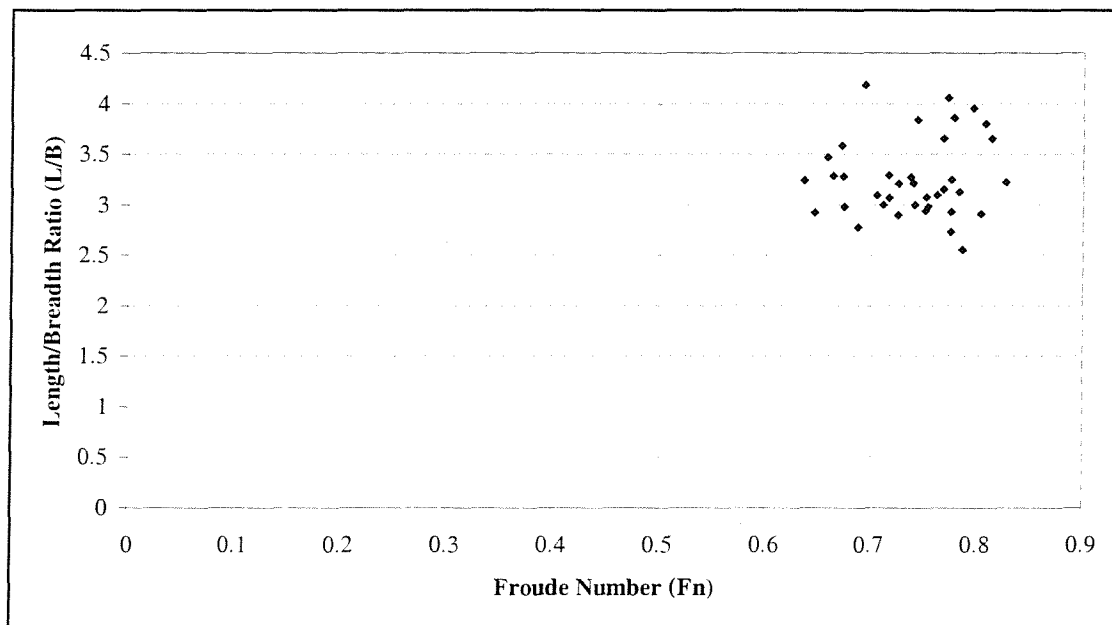


Figure 2.2.b: Relation between Fn and L/B for Vehicle-Passenger Catamarans.

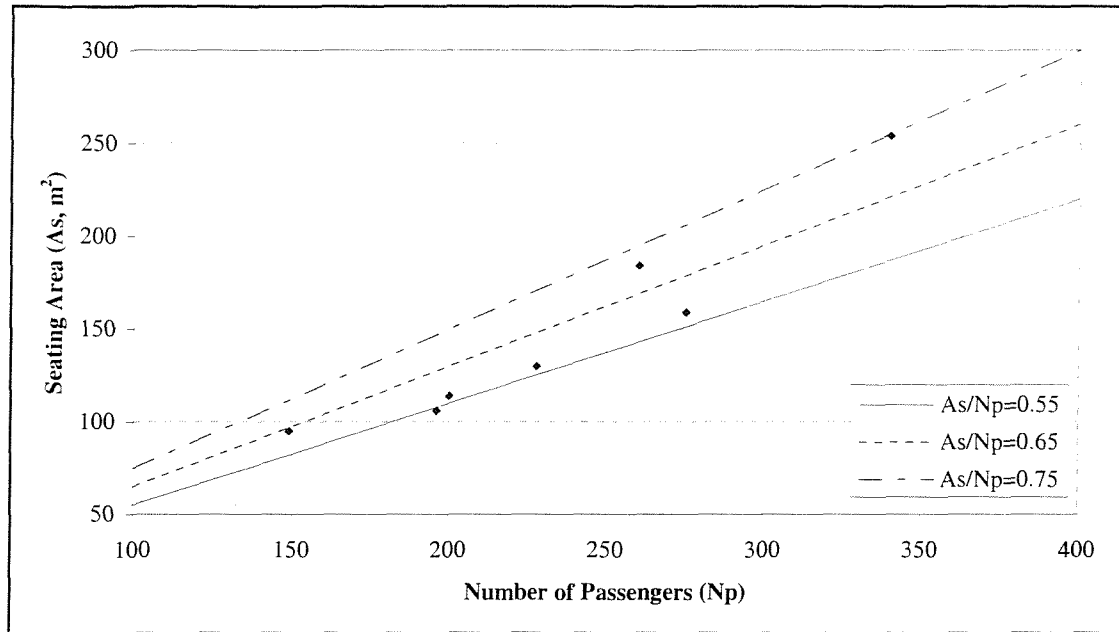


Figure 2.3.a: Data Plots of Dimensions for Passenger-Only Monohulls.

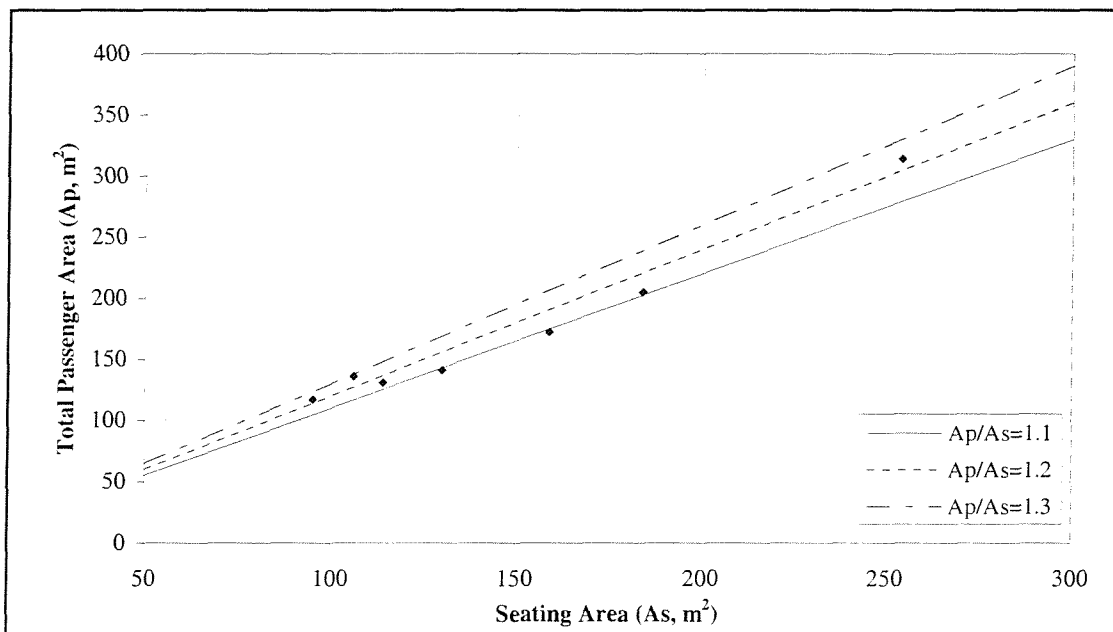


Figure 2.3.b: Data Plots of Dimensions for Passenger-Only Monohulls.

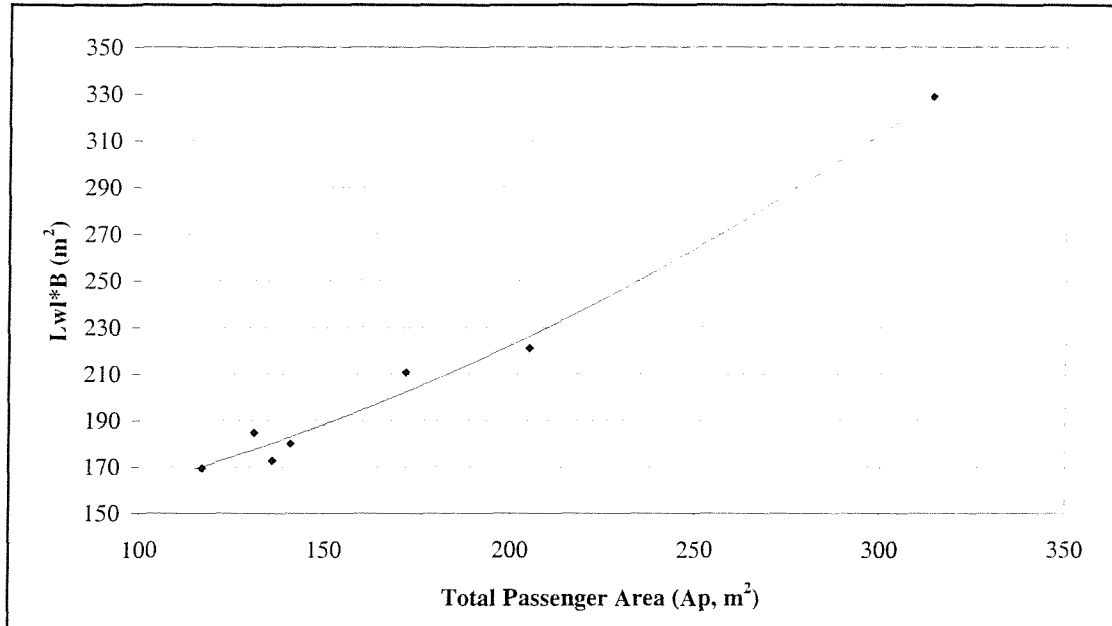


Figure 2.3.c: Data Plots of Dimensions for Passenger-Only Monohulls.

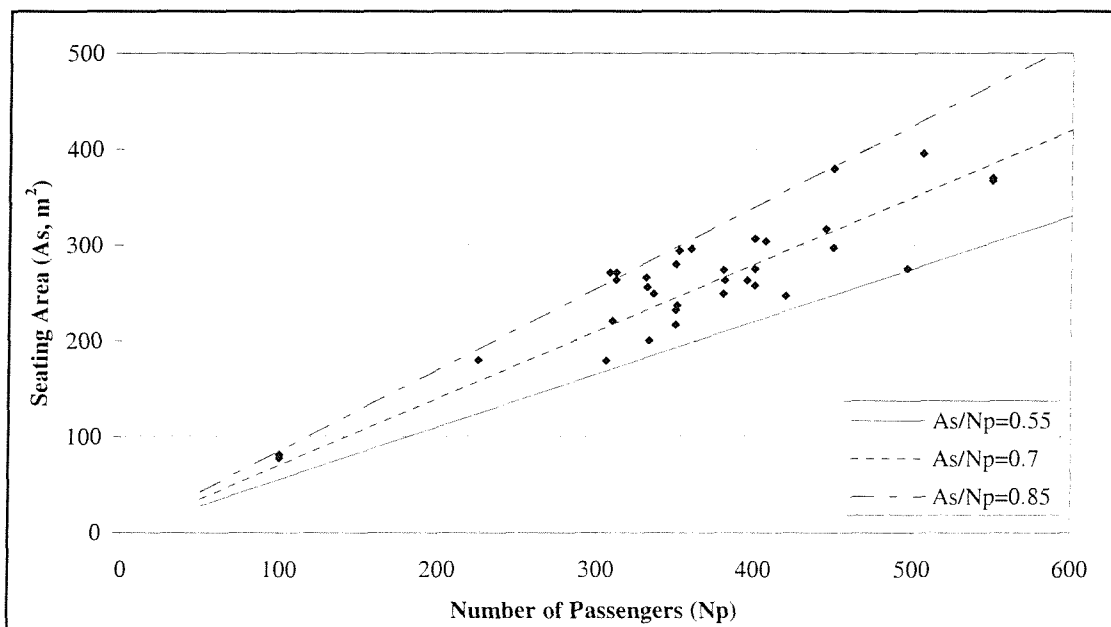


Figure 2.4.a: Data Plots of Dimensions for Passenger-Only Catamarans.

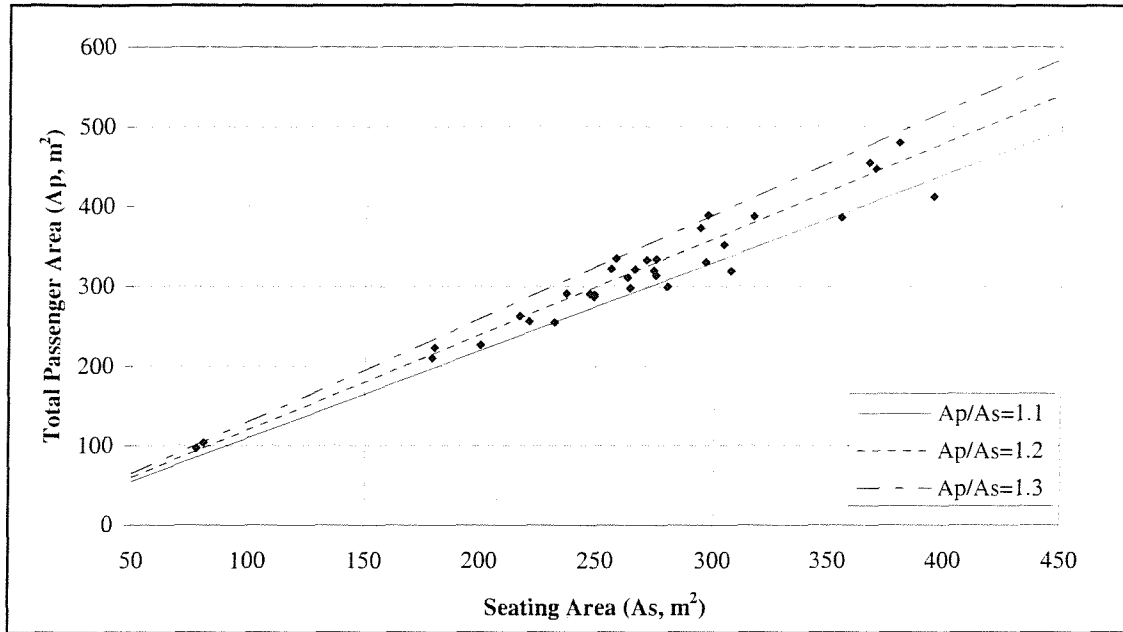


Figure 2.4.b: Data Plots of Dimensions for Passenger-Only Catamarans.

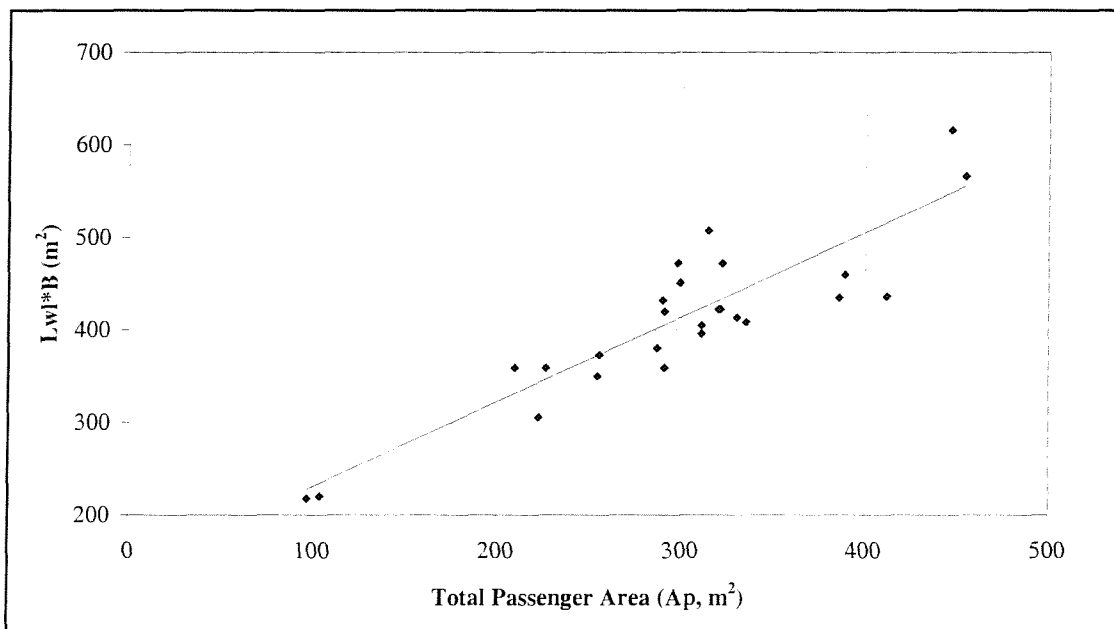


Figure 2.4.c: Data Plots of Dimensions for Passenger-Only Catamarans.

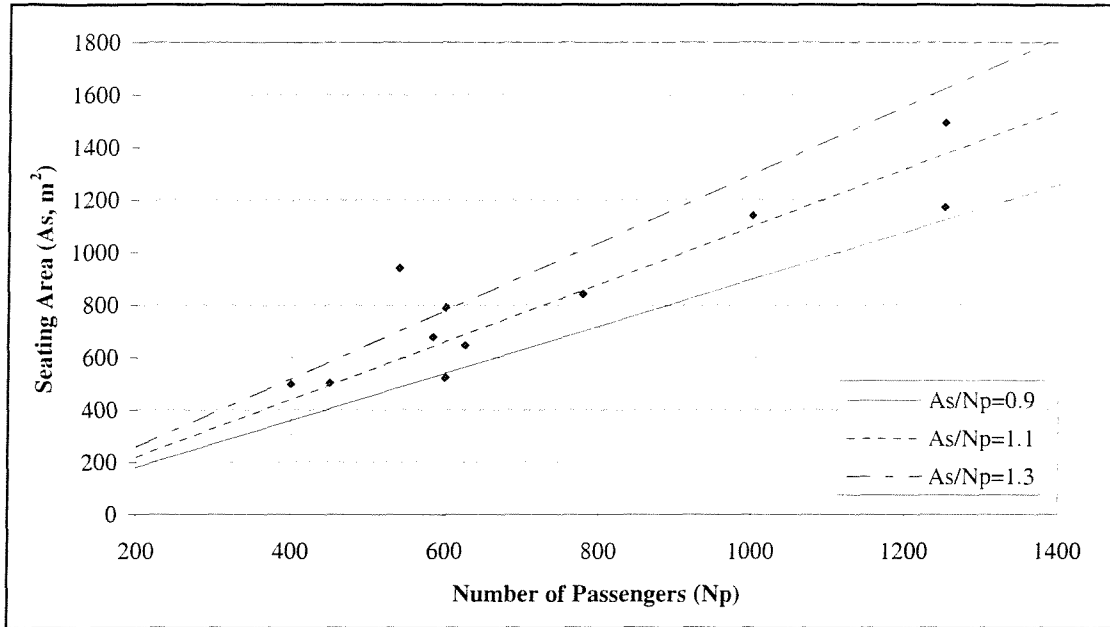


Figure 2.5.a: Data Plots of Dimensions for Vehicle-Passenger Monohulls.

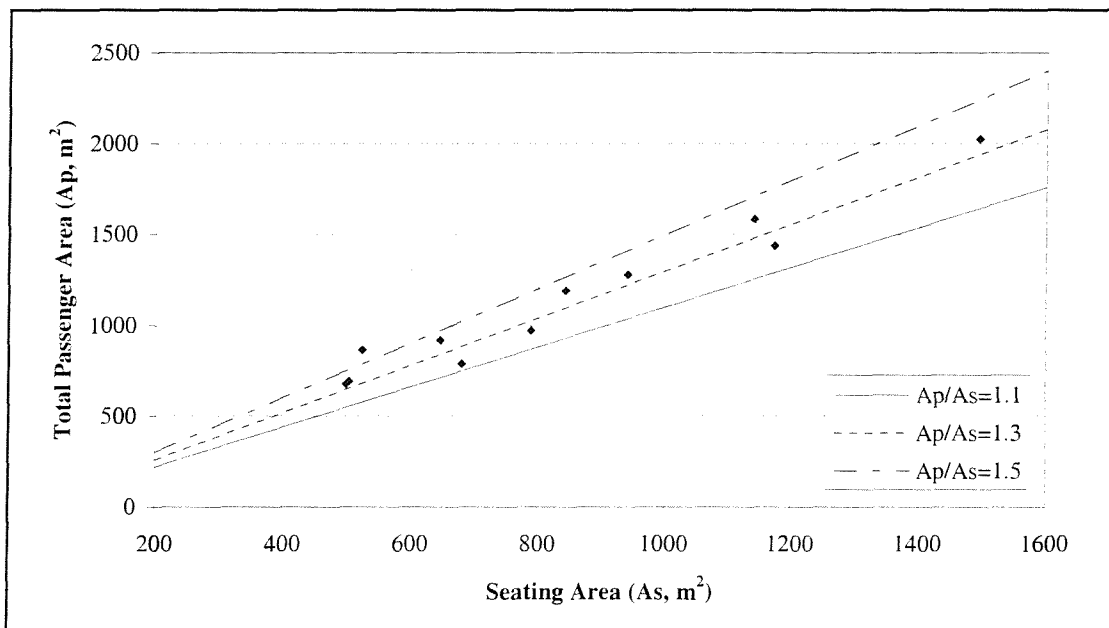


Figure 2.5.b: Data Plots of Dimensions for Vehicle-Passenger Monohulls.

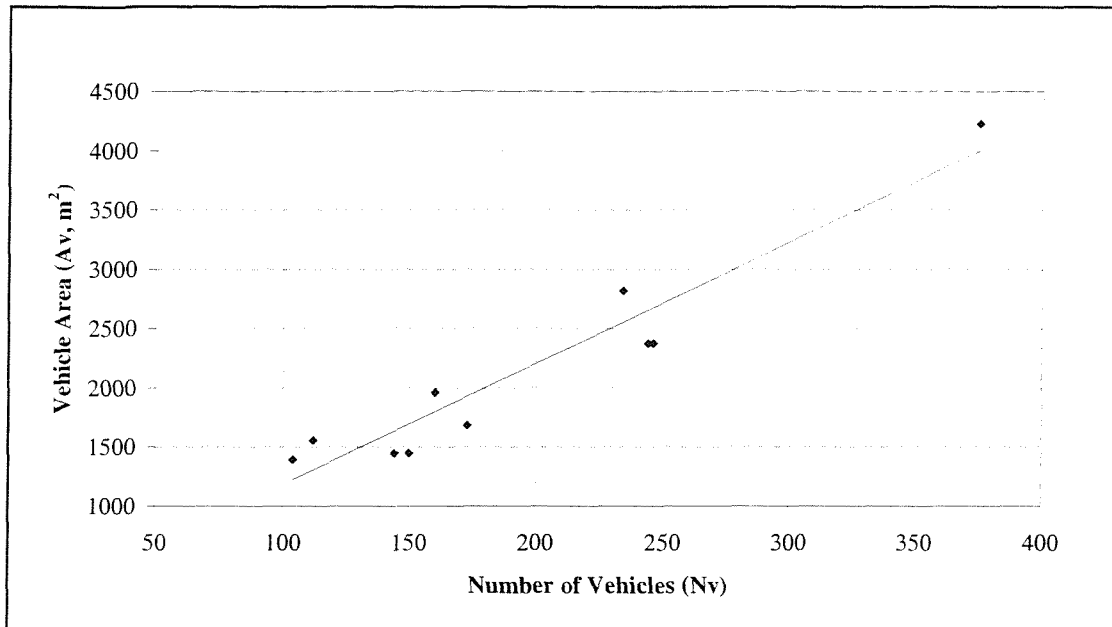


Figure 2.5.c: Data Plots of Dimensions for Vehicle-Passenger Monohulls.

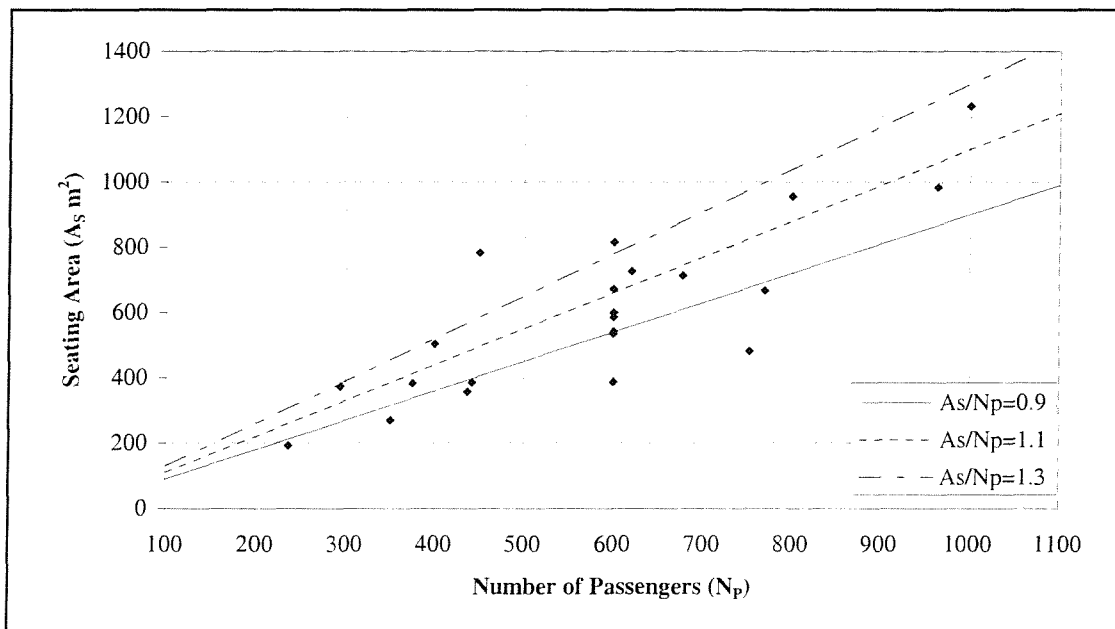


Figure 2.6.a: Data Plots of Dimensions for Vehicle-Passenger Catamarans.

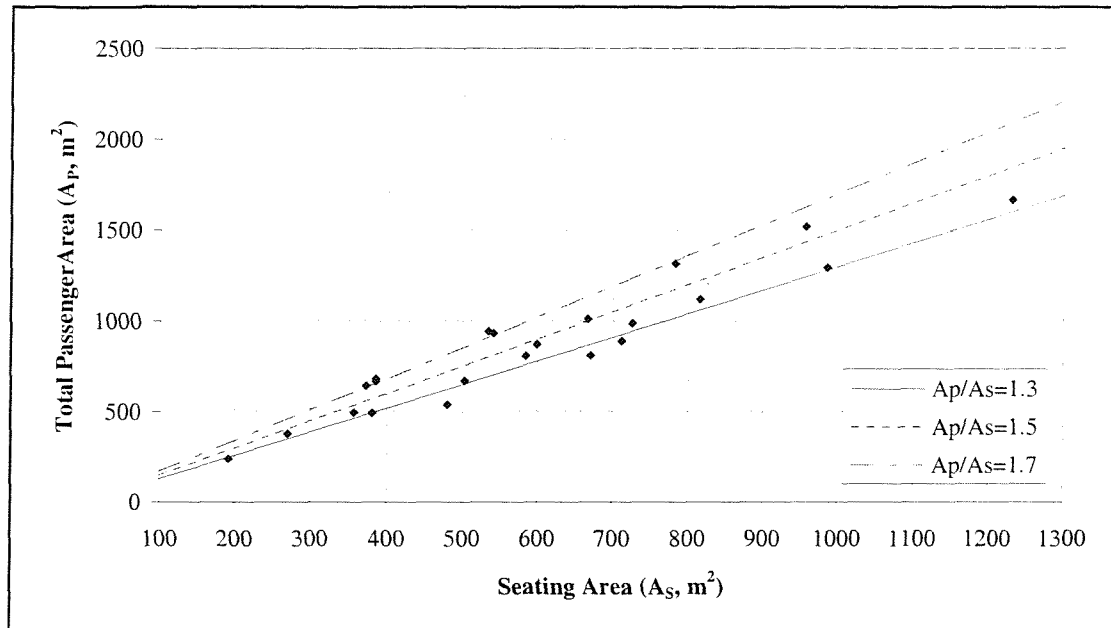


Figure 2.6.b: Data Plots of Dimensions for Vehicle-Passenger Catamarans.

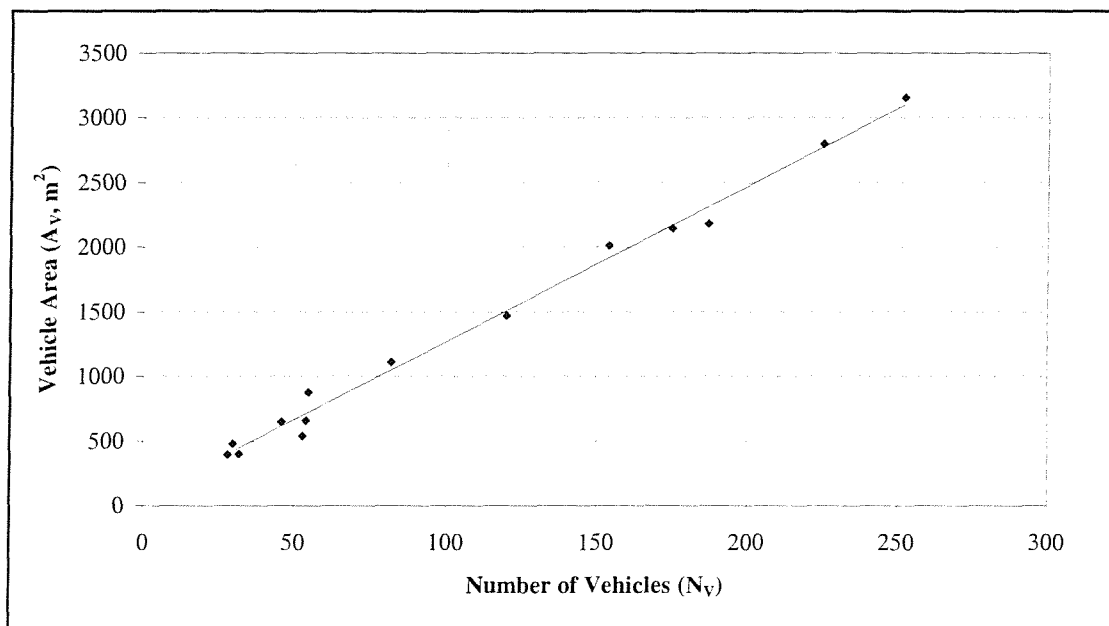


Figure 2.6.c: Data Plots of Dimensions for Vehicle-Passenger Catamarans.

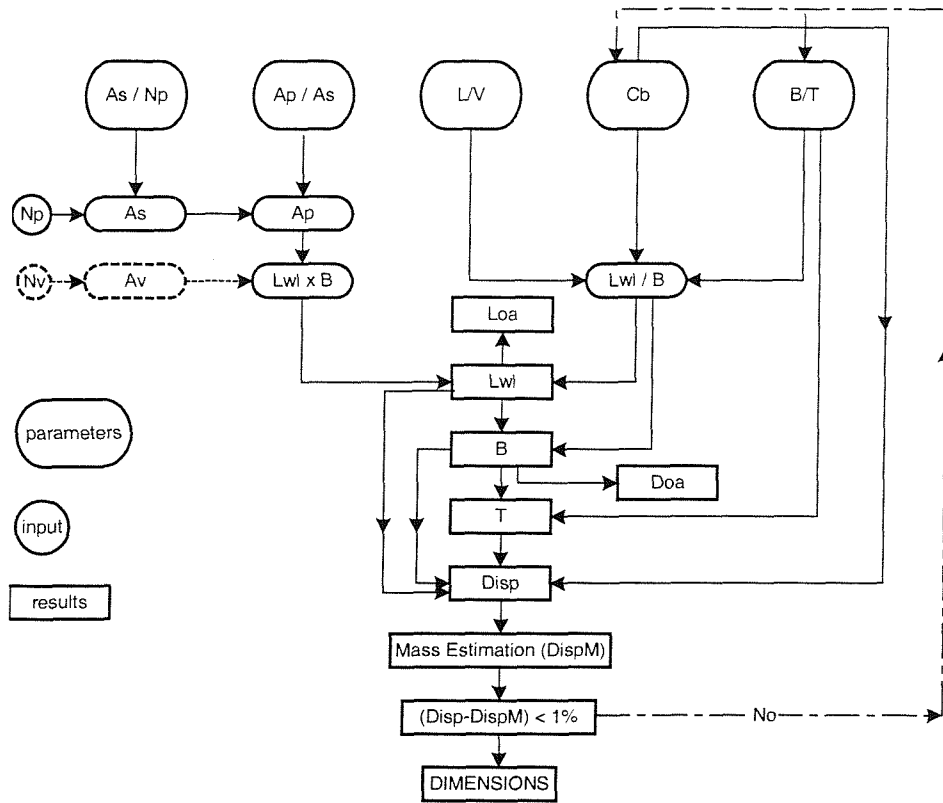


Figure 2.7.a: Flowpath for Initial Estimation of Main Dimensions for Monohulls.

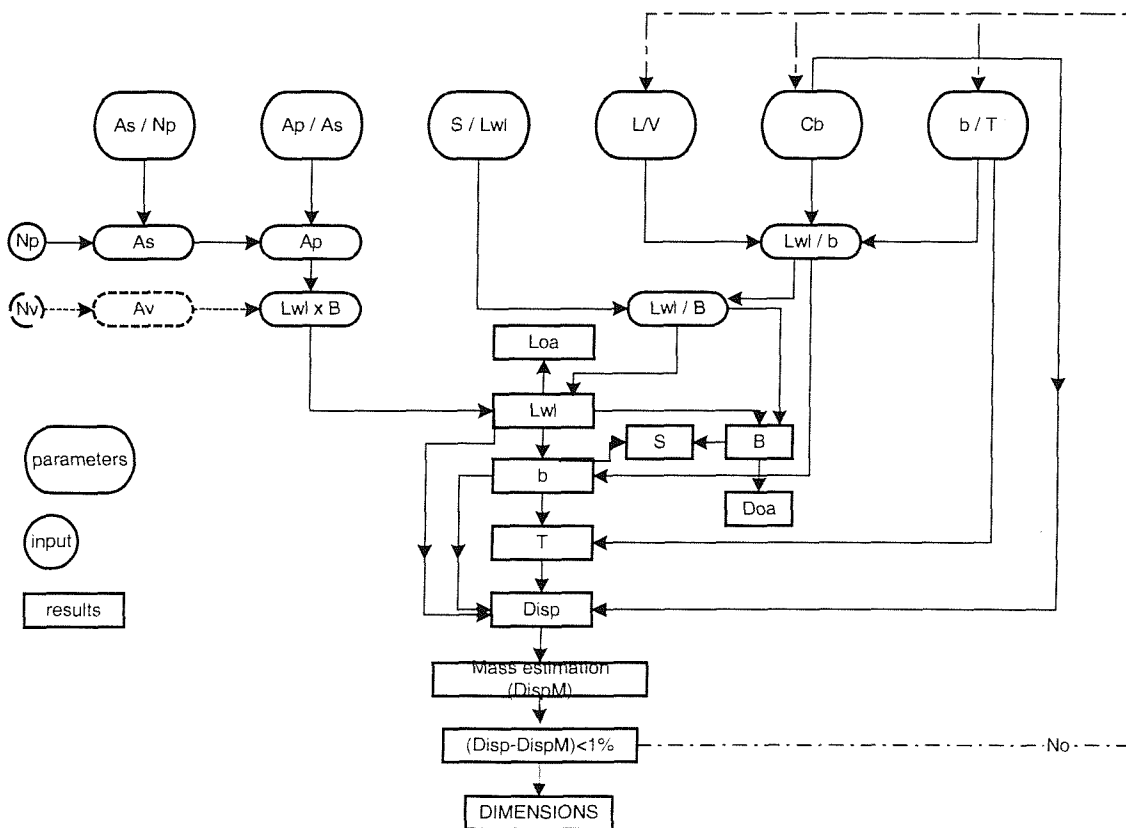


Figure 2.7.b: Flowpath for Initial Estimation of Main Dimensions for Catamarans.

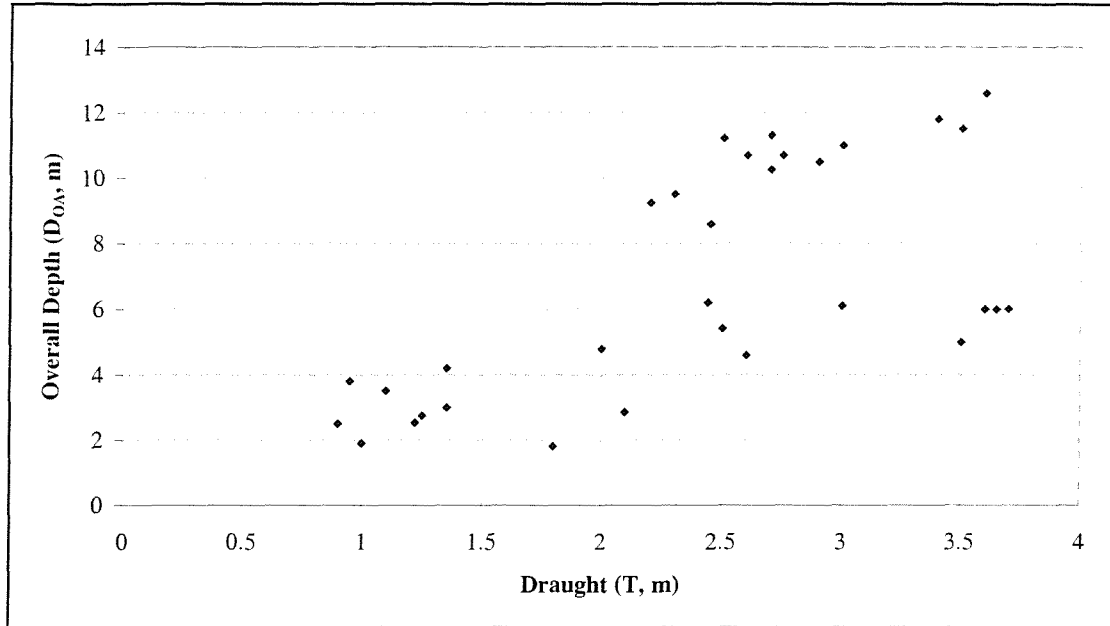


Figure 2.8.a: The Correlation Between Overall Depth and Draught for Monohulls.

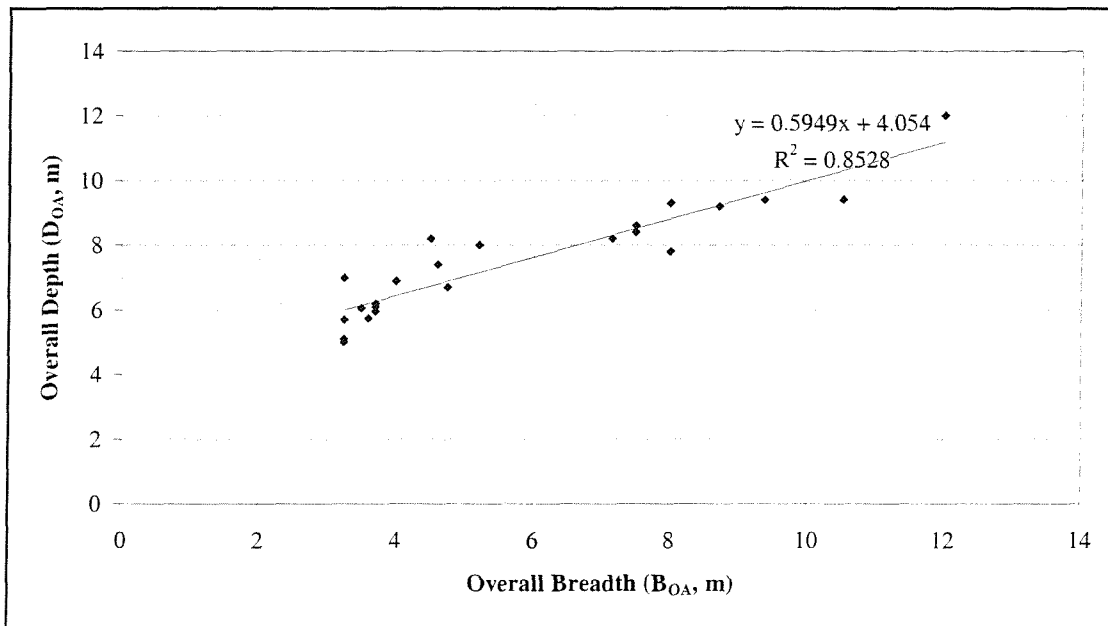


Figure 2.8.b: The Correlation Between Overall Depth and Breadth for Monohulls.

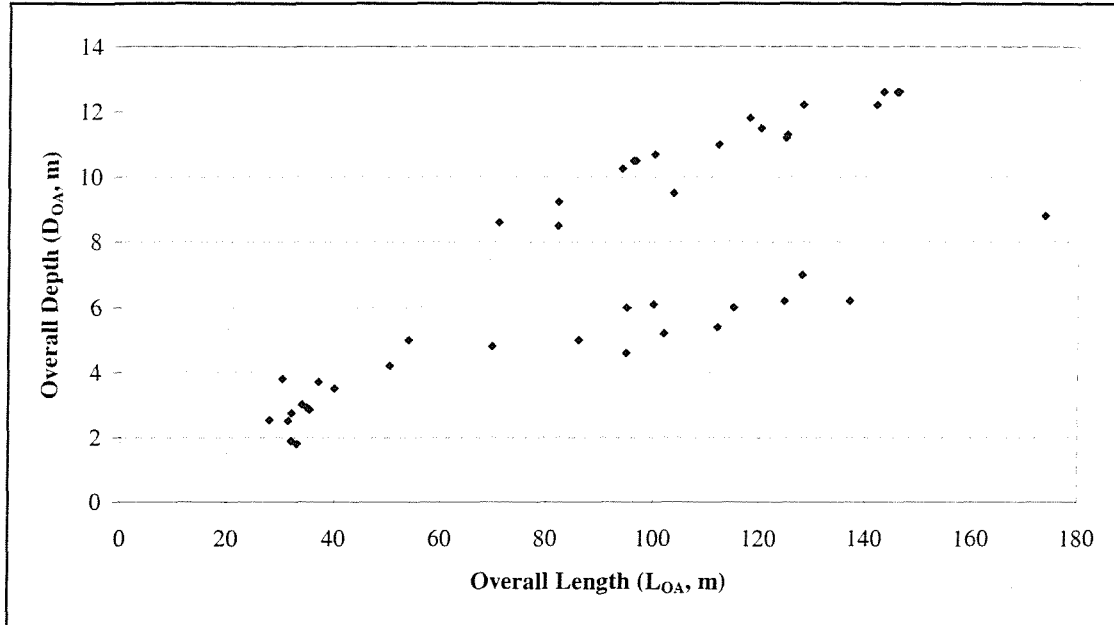


Figure 2.8.c: The Correlation Between Overall Depth and Overall Length for Monohulls.

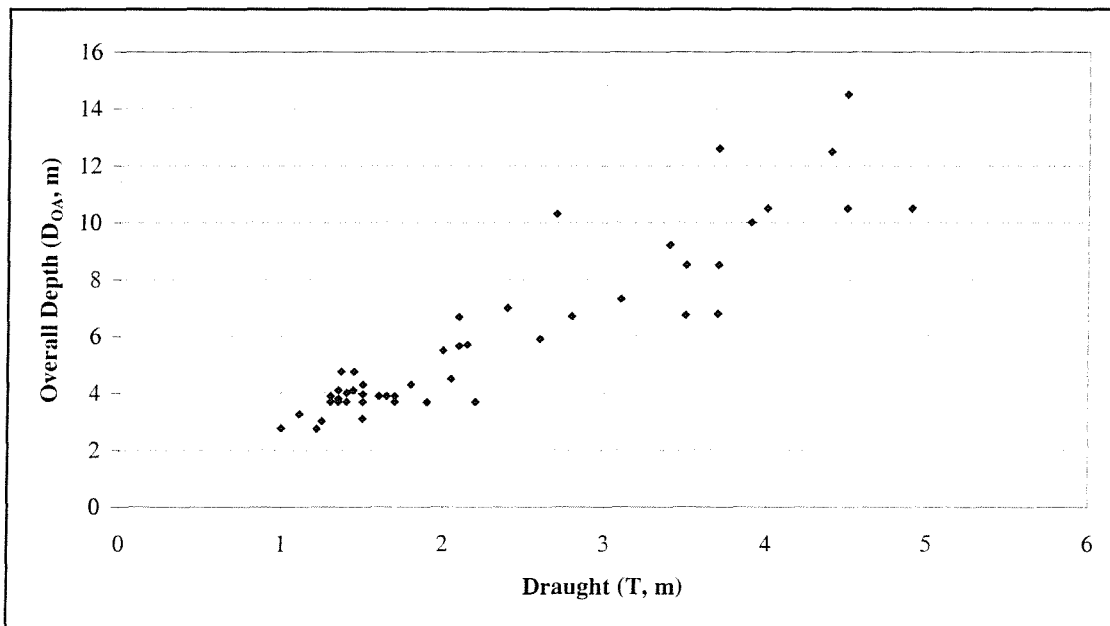


Figure 2.9.a: The Correlation Between Overall Depth and Draught for Catamarans.

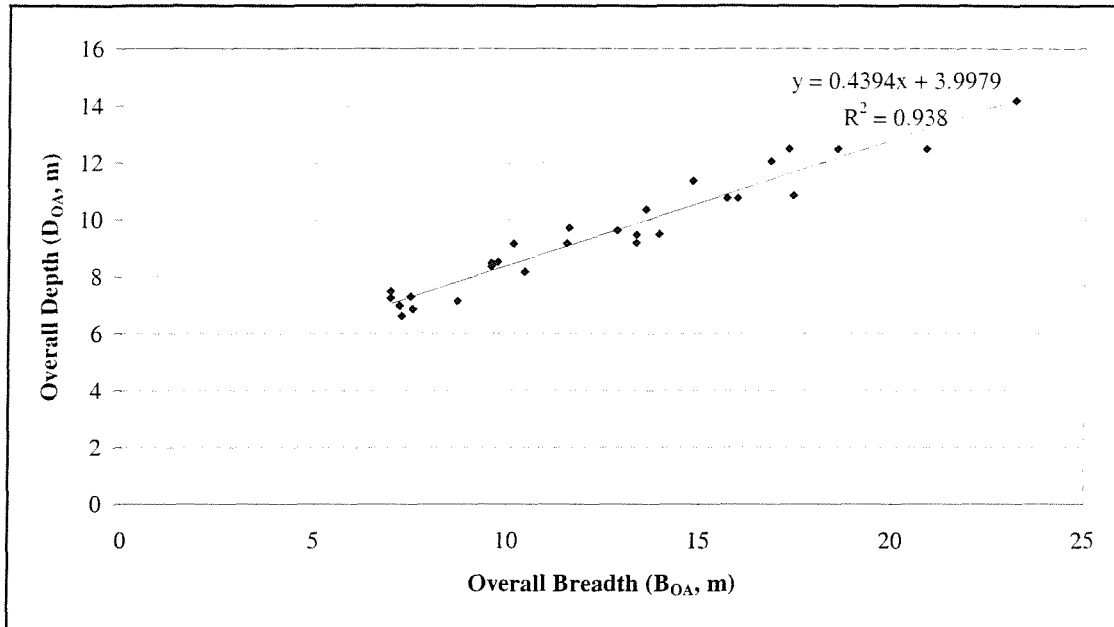


Figure 2.9.b: The Correlation Between Overall Depth and Overall Breadth for Catamarans.

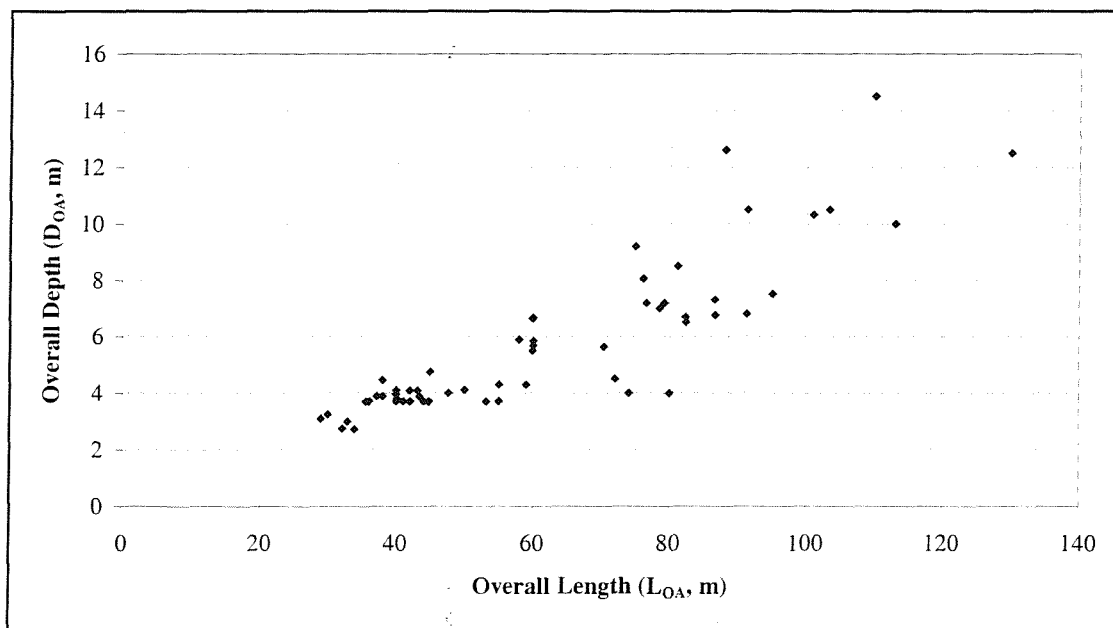


Figure 2.9.c: The Correlation Between Overall Depth and Overall Length for Catamarans.

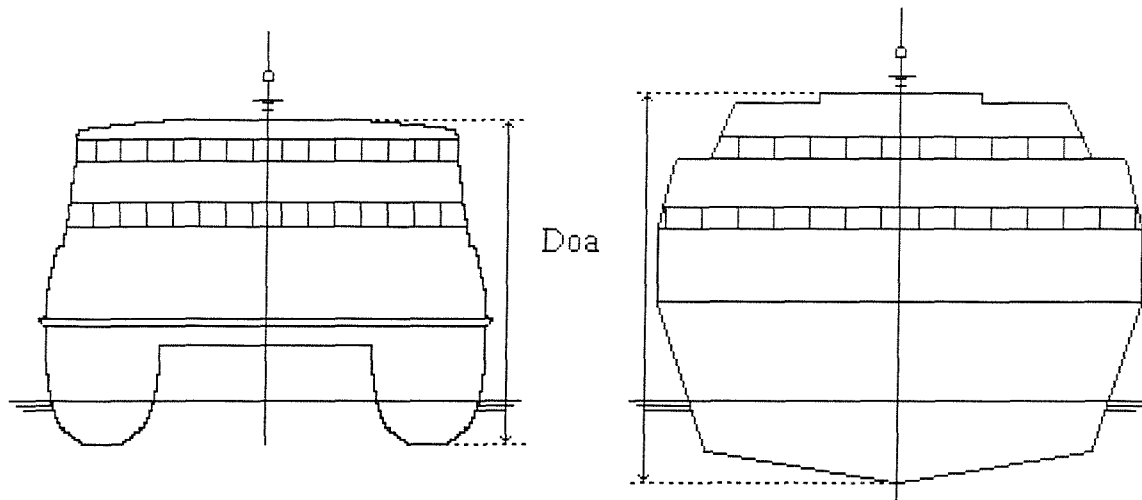


Figure 2.10: Definition of Depth for Catamarans and Monohulls for the Current Study.

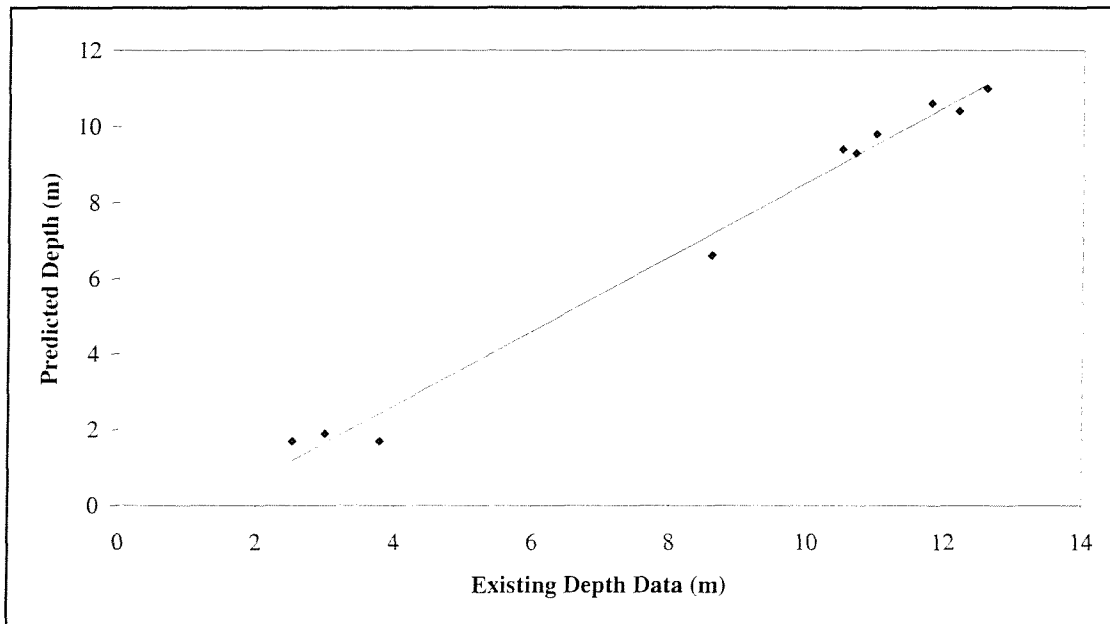


Figure 2.11.a: The Comparison Between Predicted and Existing Depth Data for Monohulls.

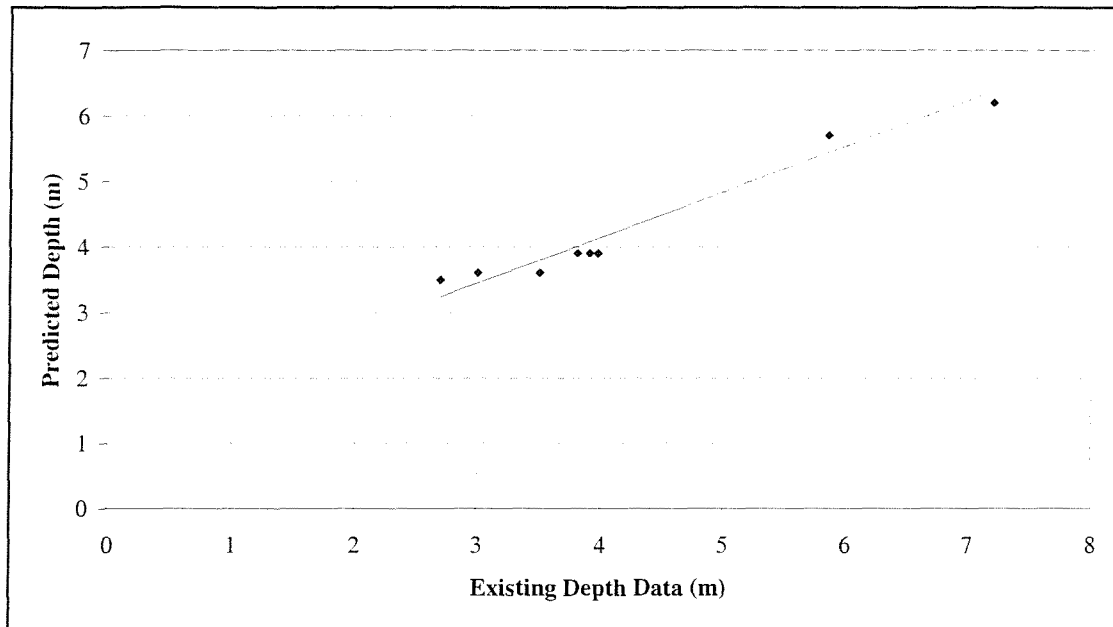


Figure 2.11.b: The Comparison Between Predicted and Existing Depth Data for Catamarans.

3. POWERING

3.1 GENERAL

A reliable power estimate is important in order to provide an estimation of machinery and fuel masses. A reliable database is also essential for carrying out powering estimates but unfortunately information is relatively limited, particularly in the higher speed range. To find suitable data for high speed monohull displacement crafts and multihulls some previous studies have been looked into. These are as follows:

Monohull mode; The NPL Series Bailey [1], Series 64 Yeh [34] and the Southampton Extended NPL Series Molland et al [22]. These collectively provide a good coverage of parameters for powering estimates and they also offer the facility to investigate a reasonable range of fast monohull ferries.

Multihull mode; Systematic resistance data for multihulls is more limited. The catamaran series tested at Southampton Molland et al [22] offers at present one of the most extensive sets of data, and provides a good basis for resistance estimates.

The current work's interest is the estimation of an initial set of main dimensions, masses and costs. The estimation of an initial set of main dimensions was dealt with in the previous chapter. This chapter deals with the estimation of initial power. Information on initial power is fundamental to obtain machinery and fuel masses. Presented databases help in providing an initial power. Presentation of data and the procedure behind this estimation is given in sections 3.2, 3.3 and 3.4.

3.2 PRESENTATION OF DATA

Work on the resistance of high speed displacement monohulls and catamarans has been ongoing over a number of years at the University of Southampton, Insel et al [13] and Molland et al [22], in an effort to improve the understanding of their resistance components and to provide design data.

Molland et al [22] describes a large series of model tests on catamarans in calm water. The experimental programme was a development of the earlier work Insel et al [13] in which a small series of three catamaran models were tested. In Molland et al [22], total resistance, running trim, sinkage and wave pattern analyses were carried out for ten round bilge hull

derived from the NPL Series. The tests were conducted over a Froude Number range of 0.1 to 1.0 and corresponding Reynolds number (R_N) range for the models 0.5×10^6 to 5.5×10^6 with separation to length ratios of 0.2, 0.3, 0.4, 0.5 and infinity.

In an earlier work, Insel et al [13] tested a wide range of hull separations. Overall, the experiments covered over 40 model configurations, each over a speed range up to a Froude Number of unity. Molland et al [22] has extended the parametric investigation to cover changes in breadth/draught ratio (B/T) and a wider range of length/displacement ratios ($L/\nabla^{1/3}$).

These two main works on the resistance of high speed displacement catamarans have been used by Buckland [3] to provide data for the NPL and Series 64 round bilge series in an alternative form, using interference factors. Using these references as the sources of data, Buckland produced a rationalised resistance estimate procedure for both catamaran and monohull configurations to utilize at the preliminary design stage. This procedure has been applied in the current work using the NPL Series for illustration as described in the next section.

3.3 CALM WATER RESISTANCE

The basic presentation of the experimental data from Molland et al [22] was as follows:

$$C_{T_{cat}} = (1 + \beta k) C_F + \tau C_W \quad 3-1$$

where;

C_F is obtained from the ITTC-1957 correlation line.

C_W is the wave resistance coefficient for the demihull in isolation.

$(1+k)$ is the form factor for the demihull in isolation.

β is a viscous interference factor.

τ is the wave resistance interference factor.

It is noted that for the demihull in isolation, $\beta=1$ and $\tau=1$.

Form factors $(1+k)$ for monohulls and form factors for catamarans including viscous interference $(1+\beta k)$ were obtained by deducting the wave pattern resistance from total resistance Insel et al [13] and Molland et al [22]. Various research programmes have been carried out in order to provide guidance as to the selection of a suitable form factor. Due mainly to the lack of definitive values of form factors for high speed displacement craft, the 22nd ITTC in September 1999, recommended the use of $(1+k)=1.0$ and $(1+\beta k)=1.0$ for such

craft Buckland [3]. Buckland [3] and Molland et al [19] state that for practical application, suitable values of form factor can be used. They also mention that these values may be adequately reliable for preliminary estimates of power at the early design stage. These form factor values are summarised in Table 3.1, and depend only on length-displacement ratio ($L/\nabla^{1/3}$), and are independent of hull separation S/L .

From a practical point of view it is not necessary to confine the user to the particular values of $(1+k)$ or $(1+\beta k)$ proposed in Table 3.1. These factors may not necessarily be used directly for design or resistance scaling purposes, but they do provide a broad indication of changes in viscous resistance and viscous interference due to changes in Length/Displacement ($L/\nabla^{1/3}$). Thus they have been applied by the current work.

Buckland [3] took residuary resistance coefficients C_R (derived from $C_T - C_{F_{ITTC}}$) from Insel et al [13] and Molland et al [22]. He then evaluated the relationship between residuary resistance and each design parameter. The effects of each design parameter on C_R are given in Table 3.2.

The relationship between C_R and $L/\nabla^{1/3}$ is sufficiently predictable to form a basis for regression between $F_N=0.4-1.0$. Therefore the data is only regressed between $F_N=0.4-1.0$. It is made sure that for the current work the range of F_N is between 0.4-1.0. This range is 0.6, 0.8 and 1.0 as can be seen in Table 3.3.

The effects of B/T and C_p on C_R have been found to be small in this F_N range, and therefore have not been considered as regression parameters. Buckland [3] has also shown that the effect of S/L on C_R is as significant as a change in $L/\nabla^{1/3}$ ratio, and has been used as a regression parameter. Therefore the regression has been performed at each value of S/L for the catamaran configuration. It should be mentioned that the current work uses the regressions for the NPL Series data and thus will only be directly applicable to these hull forms.

Table 3.3 shows the result of the regression for calculation of C_R in terms of $L/\nabla^{1/3}$ and S/L along with the R^2 value for each trendline fit. The trendline fits can be found in Buckland [3]. This value indicates how well the regression model fits the observed data, and it is seen that good fits are achieved in all but the high speed, low S/L data.

For a chosen speed, an estimate of ship total resistance coefficient can be made using the following relationships. These estimation relationships have been employed in the current study by introducing them into a computer program. The program results in an initial power value for a chosen speed. It is further explained in Appendix II.

For monohulls:

$$C_{T_{ship}} = C_{F_{ship}} + C_{R_{model}} - k(C_{F_{model}} - C_{F_{ship}}), \quad 3-2$$

and for catamarans:

$$C_{T_{ship}} = C_{F_{ship}} + C_{R_{model}} - k\beta(C_{F_{model}} - C_{F_{ship}}). \quad 3-3$$

These are based on the assumption that:

$$C_T = C_F + C_R, \text{ or } C_T = (1+k) \times C_F + C_W. \quad 3-4$$

Model C_F has to be known to use these equations. Based on the model length of 1.6 m for models in Insel et al [13] and Molland [22], a kinematic viscosity for fresh water of 1.14×10^{-6} and using the ITTC correlation line, C_F can be derived as follows;

$$C_F = \frac{0.075}{[\log_{10} R_n - 2]^2} \quad 3-5$$

$$R_n = \frac{V \cdot L}{\nu} \quad 3-6$$

$$L = 1.6 \text{ m.}, \nu = 1.14 \cdot 10^{-6} \text{ m}^2/\text{s}, g = 9.81 \text{ m/s}^2$$

$$\begin{aligned} R_n &= \frac{V \cdot L}{\nu} \times \frac{F_n}{V / \sqrt{g \cdot L}} = \frac{V \cdot L}{\nu} \times \frac{F_n}{V} \times \sqrt{g \cdot L} = \frac{L^{3/2}}{\nu} \times \sqrt{g} \times F_n \\ \Rightarrow R_n &= \frac{1.6^{3/2}}{1.14 \cdot 10^{-6}} \times \sqrt{9.81} \times F_n = 5.56 \cdot 10^6 \times F_n \end{aligned} \quad 3-7$$

$$C_{F_{model}} = \frac{0.075}{[\log_{10}(F_n \times 5.56 \times 10^6) - 2]^2} \quad 3-8$$

Once the $C_{T_{ship}}$ has been calculated, the total ship resistance can be calculated using the following equation;

$$R_{T_{ship}} = C_{T_{ship}} \cdot 0.5 \cdot \rho_{SW} \cdot V_{ship}^2 \cdot W_{SA} \quad 3-9$$

Wetted surface area may be calculated using a wetted surface coefficient (C_S), which is derived from breadth-draught ratio (B/T) and block coefficient (C_B) using regression formulae provided for the NPL and Series 64 forms Karayannis [16]. As a further approximation, the Denny Mumford formula gives reasonable results and is used in the current approximate estimate. The following formulae provide the wetted surface area of the vessel [the first is for monohull configurations and the second is for catamarans).

$$\begin{aligned} W_{SA} &= (1.7 \times L_{WL} \times T) + (\nabla / T) \\ W_{SA} &= 2 \times [(1.7 \times L_{WL} \times T) + (L_{WL} \times b \times C_B)] \end{aligned} \quad 3-10$$

Hence, using equation 3-9 the total ship resistance of the vessel can be calculated. Effective power P_E is then calculated directly as $R_T \cdot V_S$.

3.4 PROPULSION

The efficiency of an engineering operation is generally defined as the ratio of the useful work or power obtained to that expended in carrying out the operation.

In the case of a ship the useful power obtained is that used in overcoming the resistance to motion at a certain speed, which is represented by the effective power P_E .

Mechanical efficiencies, gear losses and shaft transmission losses all vary from ship to ship, according to the type of machinery and general layout. It is difficult to define the hydrodynamic efficiency of a hull propeller combination in terms of such an overall propulsive efficiency.

A more meaningful measure of efficiency of propulsion is the ratio of the useful power obtained, P_E , to the power actually delivered to the propeller, P_D . This ratio has been given the name quasi-propulsive coefficient, and is defined as:

$$\eta_D = \frac{P_E}{P_D} \quad 3-11$$

$$P_E = R_T \cdot V_S \quad 3-12$$

$$P_D = \frac{R_T \cdot V_S}{\eta_D} \quad 3-13$$

$$\eta_D = \eta_H \cdot \eta_B = \eta_H \cdot \frac{\eta_B}{\eta_O} \cdot \eta_O \quad 3-14$$

The overall efficiency can then be established, as follows:

$$\eta_D = \eta_H \cdot \eta_R \cdot \eta_O \quad 3-15$$

where η_H is defined as the hull efficiency, η_R is the relative rotative efficiency and η_O as the open water efficiency.

The required total installed power (P_I) is estimated assuming a margin for resistance increases due to hull roughness, fouling and weather. In the present work, for design purposes, a margin of 15% resistance increase due to hull roughness, fouling and weather is assumed. Hence:

$$P_D = P_E / \eta_D \text{ and } P_I = P_D \times 1.15. \quad 3-16$$

An overall propulsive efficiency (η_D) is calculated, leading to an estimate of the required installed power. At present, the overall efficiency is based on that for water jets which are the most widely used propulsion systems for high speed ferries.

Thus, resistance and propulsion calculations can be performed for any selected speed, allowing any desired operational speed to be investigated.

More detailed information about water jets and the calculation of overall propulsive efficiency is given in the following section.

3.4.1 Water Jets

The basic operating principle of the water jet is similar to that of the propeller. The propelling

force is generated by adding momentum to the water by accelerating a certain flow of water in an astern direction. In the water jet, water from beneath the vessel is fed through an inlet duct to an inboard pump, usually mounted at the transom, which adds head to the water. This head is then used to increase the velocity when the water passes through an outlet nozzle into the ambient atmospheric pressure. Deflecting the jet by means of a manoeuvring gear, usually hydraulically operated, generates steering and reversing forces Svensson [24,25].

In the case of water jets, overall efficiency in the current work is estimated from available statistical data from manufacturers Karayannis [16]. This is shown in Figure 3.1 and an approximate relationship that was found to fit the data adequately is as follows:

$$\eta_D = \frac{1}{1 + \left(\frac{16.8}{V_s (kn)} \right)} \quad 3-17$$

As before, delivered power is then calculated directly as:

$$P_D = P_E / \eta_D \quad 3-18$$

3.5 SUMMARY

Assessing different research studies and using their results and database, the estimation of initial power is achieved. The current study is useful to find a power value at the preliminary ship design stage. For a chosen speed estimation of an initial power will help for the derivation of machinery and fuel masses and also costs.

The current estimation method is for monohulls and catamarans, but future study can be carried out to estimate the initial power of different hull configurations.

A computer program has been written to perform the powering calculations, for both monohulls and catamarans, by calculating main dimensions, masses and costs of a ship. The program incorporates routines for resistance calculations based on the regression equations for the systematic series for propulsive efficiency equation 3-17. The program is fully described in Appendix II.

$L/\nabla^{1/3}$	Form Factors	
	Monohull (1+k)	Catamaran (1+ β k)
6.3	1.35	1.48
7.4	1.21	1.33
8.5	1.17	1.29
9.5	1.13	1.24

Table 3.1: Typical Form Factor Values.

Parameter	B/T	$L/\nabla^{1/3}$	C_P	S/L
Effect on C_R	5-10% change	40-50% change	5-10% change	0-40% change
Predictability	Poor	Good	Poor	Poor

Table 3.2: Effect of Each Parameter on C_R (NPL Series).

Froude Number (F_n)	0.6	0.8	1.0
Monohull	$1702 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-2.96}$	$533 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-2.58}$	$122 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-1.96}$
R^2	0.991	0.982	0.950
S/L=0.3	$1774 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-2.87}$	$180 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-1.97}$	$48 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-1.41}$
R^2	0.974	0.955	0.852
S/L=0.2	$5084 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-3.30}$	$130 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-1.82}$	$22 \cdot \left(\frac{L}{\nabla^{1/3}}\right)^{-1.06}$
R^2	0.973	0.932	0.782

Table 3.3: NPL Series Residuary Resistance Coefficient ($C_R \times 10^3$).

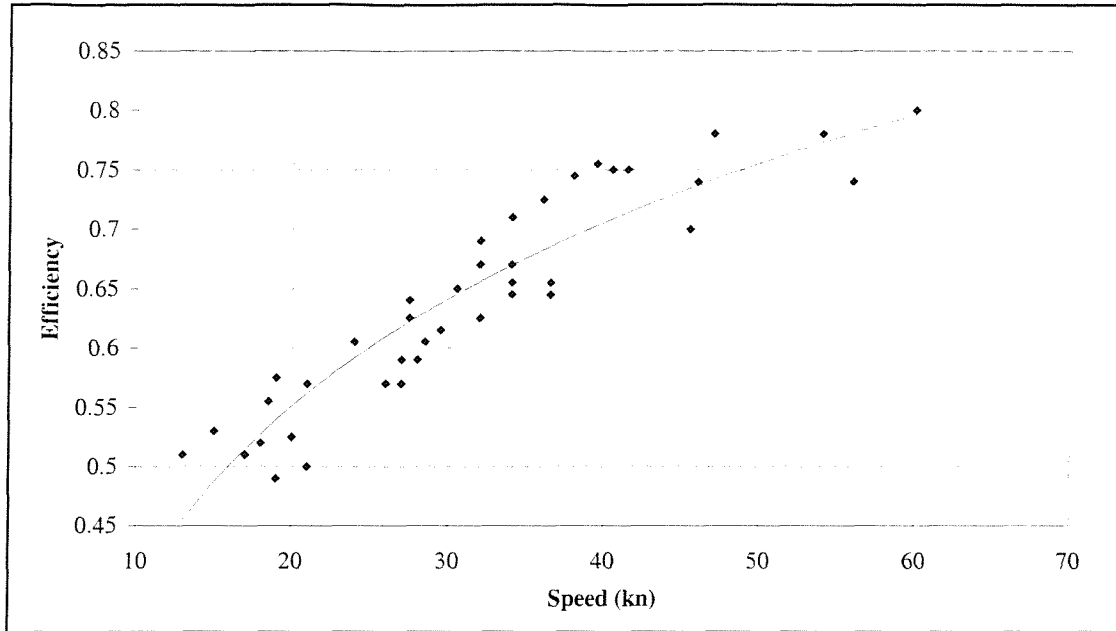


Figure 3.1: Overall Water jet Efficiency.

4. MASSES

4.1 GENERAL

One of the most important design factors in concept design is the estimation of the mass of the craft. Small changes in mass may have a significant effect on vessel performance, particularly for high speed craft. Therefore, estimating mass as accurately as possible is important for an effective and economic design.

It is often difficult to carry out an accurate mass estimation at the preliminary design stage because of the lack of data. Some of the data used for the calculations in the current work are from real ships, while other ships have been created from classification society rules. To carry out all the estimations, empirical methods are adopted. The following sections describe the techniques used in the empirical method developed in the current study.

For the estimation method, ship mass is divided into two major parts, lightship and deadweight. The further breakdown of masses is shown in Figure 4.1. Lightship is subsequently divided into three parts namely hull, outfit and machinery masses. Deadweight comprises cargo, crew, provisions and fuel weights.

The following sections describe the methods developed for estimating each of these masses. Section 4.2 covers hull mass, section 4.3 outfit mass, section 4.4 machinery mass and, finally section 4.5 deals with deadweight.

4.2 HULL MASS

4.2.1 Background

The structural design of high speed ferries can be seen as a crucial part in their design since any changes in mass can result in decreases or increases in powering and costs. Also, the importance of structural mass is reflected in that it can comprise up to 35% of the vessel's full mass.

The main purpose of this part of the research has been to estimate the preliminary structural mass of fast monohulls and catamarans. Structural mass includes the weight of all the platings, stiffeners, brackets, welds, etc. which comprise the structure of a vessel.

Several methods have been developed in the past to determine the hull structural mass of conventional hulls. Two of these methods are investigated in the current research, Taggart [26] and Watson et al [31]. Watson & Gilfillan's method is the most widely used for the preliminary structural mass of conventional displacement ships. This method is also used in the current work with a careful adaptation for fast ferries and is described in more detail later.

The most difficult part of the current study is finding reliable mass data. For business secrecy reasons it has been extremely difficult to obtain any real data from ship builders or operators. The only data obtained this way was under the promise of keeping its source secret. For this reason the current method has been developed mainly with generated data.

Some data for hull mass estimation is obtained from Sainz [23]. Sainz developed ship data by using Lloyd's Register classification society rules for small craft. A number of assumptions and calculations were undertaken to generate data. A software package has been developed by Lloyd's Register which carries out these processes automatically.

The process may be described in simple terms as firstly designing a typical midship section for a hull using a set of rules from a classification society. From this a mass per metre can be achieved for a position amidships and the distribution of weight along the length of the craft can later be determined, thereby establishing the total mass of the vessel. The approach parametrically investigates the hull mass estimates for several vessels of different dimensions.

For monohulls, two data sources were used for the structural design of the vessels. The first of these was the 'Mestral car ferry' concept design. Taking this initial design and varying its principal particulars, new vessel designs were developed. Five vessels were designed in a range from 50 to 150 metres, the length range of most of the new high speed marine vessels. This variation in length involved a new set of dimensions for beam, depth, etc., for each design.

The second data source for monohulls is an article from the fourth international conference on fast sea transportation, Hughes [12], where a strategy is presented for achieving a first principles optimum structural design of a ship using modern computer based tools.

The further part of the monohull structural design involved slight variations on the length and beam of the vessels. An investigation was performed to determine how the effect of keeping the load area of the decks constant would influence the final structural mass. Keeping the factors of length and beam constant make the load carrying ability of the vessels also constant. The investigation was performed on 50, 75, 100, 125, and 150 metre hulls and L/B variants of

4.5 to 7.0, to obtain an indication of the effect of these changes. These values can be seen in table 4.1. Total new designs were performed for these variations in length and beam. The parameters which are influenced directly by changes in length and beam were modified, although most dimensions were left intact. The work task developed for the monohull vessels is shown diagrammatically in Figure 4.2.

The structural design of catamarans also relied on Sainz [23] for its final completion. It was assumed that the range in the case of catamarans would be up to 100 metres in length as the number of catamaran vessels above this value was very limited, with only a few prospective designs. The new dimensions for the newly developed designs were again derived from initial built vessel data acquired for the catamaran ships.

In the case of catamarans, three lengths, each with three hull separation ratios were investigated. The catamaran study used basic ship lengths of 50 m, 75 m and 100 m with S/L variants from 0.20 to 0.26. The technique used for estimating the hull mass of catamarans was similar to that of monohulls. The work task is shown diagrammatically in Figure 4.3 and the results are shown in Table 4.2.

4.2.2 Presentation of Hull Mass

A practical empirical approach involves developing formulae to represent the hull mass estimates. Many examples of empirical formulae exist to determine the mass of a hull. A commonly used formula for the estimation of hull mass for displacement vessels built in steel is that suggested by Watson et al [31]. The original formula used for the mass of structure estimation is;

$$W_{STRUCTURE} = W_{S7} \times [1 + 0.5 \times (C_B - 0.7)] \quad 4-1$$

The value of the block coefficient (C_B) for the new design is inserted here, and W_{S7} can be estimated from;

$$W_{S7} = K \times E^{1.36} \quad 4-2$$

with values of K for various ship types given in Figure 4.4, in the case of displacement monohull ferries, where E is the equipment numeral, the value of K for steel hulls is in the range $0.024 < K < 0.037$.

The value for equipment numeral (E) can be estimated from the following formula, which is commonly used for all varieties of displacement ships;

$$E = L \times (B + T) + 0.85 \times L \times (D - T) + 0.85 \times \sum l_1 h_1 + 0.75 \times \sum l_2 h_2 \quad 4-3$$

where l_1 and h_1 are the length and height of full width erections, and l_2 and h_2 are the length of houses. However, as fast ferries generally do not possess these separate types of erections, the last two terms of equation 4-3 would not be applicable.

Watson and Gilfillan [31] obtained values for the hull mass of typical vessels and plotted a graph showing the numeral value E against the net steel mass, showing a good relationship between these, and that the equipment numeral is appropriate in the determination of steel mass. This can be seen in Figure 4.4.

These empirical formulae are of great use in the first steps of design for traditional commercial displacement vessels. They provide a quick and immediate method of determining an approximate mass of the structural components of a hull. Next section explains the adaptation of these formulae to fast ferries.

4.2.3 Design Equations

The ship data created by employing Sainz's work [23] and that obtained from ship builders and written sources for high speed craft, are presented in terms of equipment numeral E . It is considered that although the method was originally developed for conventional vessels, a careful adaptation can make it suitable for high speed monohull and catamaran forms.

On this basis, the equipment numerals for monohulls and catamarans are obtained using equations 4-4 and 4-4. The different dimensions employed are described in Figure 4.5. In the equations, D_{OA} is taken as the depth overall including the superstructure.

$$E_M = L_{OA} \times (B + T) + 0.85 \times L_{OA} \times (D_{OA} - T) \quad 4-4$$

$$E_C = 2 \times L_{OA} \times (b + T) + 0.85 \times L_{OA} \times (D_{OA} - T) + 1.6 \times L_{OA} \times (B - 2b) \quad 4-5$$

In advocating the use of such an approach it can be noted that the numeral E is effectively a function of the total surface area of the ship, with a weighting for the portion above the waterline ($D-T$) (Figure 4.5). The weighting is currently left at the original value of 0.85 due to the lack of enough detailed data to suggest otherwise. In the case of catamarans, the third term

in the equipment numeral is a function of the added area due to the cross structure. The weighting of 1.6 in this case was derived from the parametric study of the influence of hull spacing on mass described earlier.

Available hull mass data is plotted against numeral E for both monohulls and catamarans. Equipment numeral is calculated for each ship based on the equations 4-4 and 4-5. Plots of total hull mass (hull and superstructure) in aluminium alloy for monohulls and catamarans to a base of equipment numeral are shown in Figures 4.6 and 4.7. Suitable fits to the data are found to be as follows;

$$\text{Hull Mass for Monohulls} \quad W_{HM} = 0.032 \cdot E_M^{1.2} \quad 4-6$$

$$\text{Hull Mass for Catamarans} \quad W_{HC} = 0.00064 \cdot E_C^{1.7}, (E_C \leq 3025) \quad 4-7$$

$$W_{HC} = 0.39 \cdot E_C^{0.9}, (E_C > 3025) \quad 4-8$$

The regression line for monohulls is reasonably good, considering the lack of data and the difficulty to get real ship data. It can be thought that the lack of real ship data may not make the correlation reliable, but the data obtained from parametric design study is the only way to approach an estimation of preliminary hull mass of fast ferries. On this basis it is believed that the correlation is acceptable.

Of commercial confidentiality reasons the existing ship data for catamaran hull mass shown in Figure 4.7 cannot be referenced. These actual ship values made it clear that that the Lloyd's Register classification society rules based estimates for small catamarans (Figure 4.7) are very high. Reasons for this are not clear, although no effort was made in the rules based approach to adopt a low mass structure. Based on this, two individual relationships were created for large and small catamarans. For large catamarans, the parametric study results are found to be acceptable since they correlate well with the ship data. However, for small catamarans, as is mentioned above, the developed data did not show good correlation with the ship values. Thus, available ship values had to be eased in the parametric design study results. These two curves fit the equations 4-7 and 4-8 with particular E numerals.

The data and its presentation provide a good starting point for the hull mass estimate. It is believed that as more data becomes available the method offers a good basis and opportunity for further development and refinement.

4.3 OUTFIT MASS

Outfit mass is divided into two parts in the current study. These are namely accommodation weight and remaining outfit weight. Accommodation weight is the most significant component of the outfit mass and is initially estimated by using a mass per unit area, which is explained in the following part of this section.

Accommodation weight includes lounges, dining rooms, self-service areas, air type seats, reception foyer, corridors, galley, toilets and cabins. These allow an initial estimation to be made based on total passenger and vehicle area. Average mass per unit area for components of accommodation is given as follows. Data has been derived from Karayannis [16].

Saloons, dining rooms, self service areas, Pullman seat areas, reception, foyers: 85 kg/m²,

Refrigeration: 151 kg/m²,

Toilet and shower rooms: 185 kg/m²,

Cabins (crew): 176/176/202 kg/m² (1/2/4 beds),

Wheel house: 1300 kg/unit area,

Chart room: 350 kg/unit area,

Radio room: 450 kg/unit area.

Corridors: 60kg/m²,

Galleys: 135 kg/m².

From all these detailed mass per unit area information, standard accommodation weight (W_{ACC}) can be found as;

$$W_{ACC} = x \times A_p \quad 4-9$$

where passenger area is:

$$A_p = f(L_{OA} \times B) = y \times L_{OA} \times B \quad 4-10$$

From these results, accomodation weight can be estimated as;

$$W_{ACC} = x \times f(L_{OA} \times B) = x \times y \times L_{OA} \times B \quad 4-11$$

Remaining outfit mass including any equipment not included in the machinery mass may, as a first approximation, be assumed as a linear function of overall length and breadth. This linear

function represents the area of the remaining outfit. Therefore remaining outfit mass can be derived from a formula such as;

$$W_{REM} = f(L_{OA} \times B) = z \times L_{OA} \times B \quad 4-12$$

The above results led the outfit mass per deck to be estimated using equation 4-13. To find the outfit mass for the whole ship, the obtained outfit mass per deck should be multiplied by the number of decks (N_{DECK}) as seen in equation 4-14.

$$\begin{aligned} W_O &= W_{ACC} + W_{REM} \\ W_O &= (x \times y \times L_{OA} \times B) + (z \times L_{OA} \times B) \\ W_O &= [(x \times y) + z] \times L_{OA} \times B \\ n &= (x \times y) + z \\ W_O &= n \times L_{OA} \times B \end{aligned} \quad 4-13$$

$$W_O = n \times L_{OA} \times B \times N_{DECK} \quad 4-14$$

where n is derived from detailed lightship data. It is very hard to obtain detailed lightship data. Few data was found or could be estimated to obtain a suitable n value. All values and data can be seen in Table 4.3.

All the values derived from the available data are shown in Table 4.3. Typical values of n for an approximate preliminary estimate of total outfit mass per deck (for both monohulls and catamarans) were found to be around 0.027.

The above calculations lead to an approximate formula for outfit mass as follows;

$$W_O = 0.027 \times L_{OA} \times B_{OA} \times N_{DECK} \quad 4-15$$

A more accurate outfit mass based on equations 4-13 could be developed once more data for fast ferries became available.

4.4 MACHINERY MASS

4.4.1 Background

The current study divides the overall machinery mass into two major components. These are the propulsion machinery and the auxiliary or remaining part of the machinery. The principal components of propulsion machinery are the main engines (diesel engine or gas turbine), gearboxes and propulsors (propeller or water jet), Guenther [11]. The remaining part of the machinery installation includes generators, pumps, piping and other auxiliary equipment. Figure 4.8 summarizes these components in a flowchart.

Machinery mass has been assembled into a set of data including the main machinery components suitable for high speed craft including medium and high speed diesels, gas turbines, water jets and gearboxes, Warren [30]. The data allows the overall mass of the propulsion system to be estimated with some confidence based on installed power. On the other hand, published data on the remaining part of the machinery mass is limited, hence it is currently calculated as a function of the overall propulsion mass.

In the initial stages of ship design, one of the important factors to choose is the suitable machinery. Especially, for fast craft the effect of propulsion is crucial. Some of these effects are listed below;

- Size (physical dimensions),
- Mass,
- Fuel consumption,
- Need for multiple installations and/or gearboxes.

Further factors, which can affect operating costs, are;

- Lubricating oil consumption,
- Reliability,
- Operational flexibility,
- Quick starting,
- Range of operation,
- Number of crew members,
- Maintenance costs.

All of the above effects are important, however some of them are crucial for fast craft. This is the case of the total machinery mass. An estimate is required at the initial stages of the design process. Big deviations from this initial assumption may result in future problems. Apart from changes in performance parameters and other engine properties, it might have an important effect on the final vessel's physical dimensions. For all these reasons, finding a method to estimate the initial machinery mass is considered to be vitally important. The current study deals with the preliminary estimation of main engine, propulsor, gearbox and remaining machinery weights. These are covered in the following sections.

4.4.2 Principal Components of Propulsion Machinery

The factors and parameters, generally used to characterize engine operation are;

- The engine's performance over its operating range and size,
- The engine's fuel consumption within this operating range and the cost of the required fuel type,
- Noise and air pollutant emissions within the operating range,
- The initial cost of the engine and its installation,
- The reliability and durability of the engine, its maintenance requirements, and how these affect engine availability and operating costs.

In addition to the above parameters engines specifically made for fast ferry applications are compared according to their load distribution Vrontorinakis [29]. Comparisons are performed considering that a fast ferry engine operates for up to 90% of the time at full load and only 10% of the time at less than 50% power.

Naturally in every application one of the primary requirements for an engine is to satisfy the power needs. This condition in fast ferries, not only has to be satisfied adequately, but it must also be achieved in confined spaces and by using the least mass. The main objective therefore is to achieve an increase in power to mass, and power to bulk volume ratios, in order to install more power in a given space, or to reduce the dimensions of the machinery room.

Another primary requirement for an engine is the fuel consumption. In engine tests, the fuel consumption is measured as a mass flow rate per unit time. A more useful parameter is the specific fuel consumption (sfc) which is fuel flow rate per unit power output. It measures how efficiently an engine is using the fuel supplied to produce work.

Low values of specific fuel consumption are obviously desirable. For diesel engines, typical best values are lower than 270 g/kWh, and in large engines this can go below 200 g/kWh. Vrontorinakis [29]. It is a measure of the engine's efficiency. This value is also used for the calculation of fuel mass in the current research.

Engine mass and bulk volume for a given rated power are important in many applications. This is especially important in the area of fast ferries, since the best engine could be impossible to use, if it simply cannot fit inside narrow catamaran demihulls. Two parameters useful for comparing these attributes from one engine to another are;

$$\text{Specific Mass} = \text{Engine Mass} / \text{Rated Power}$$

$$\text{Specific Volume} = \text{Engine Volume} / \text{Rated Power}$$

4.4.2.1 Total Mass Estimation for Diesel Engines

Dry engine mass (manufacturer's catalogues) excludes the necessary fluids, lubricating oil and cooling water. It also excludes other heavier and equally important accessories for a specific application, such as the gearbox, the water jet and other auxiliary machinery (pumps, coolers, etc.). Most engines in these high speed ranges discussed for fast ferry applications would need to utilize a gearbox to transmit the output power to the water jets or around bends etc. Although coolers, pumps, fluids and others are absolutely necessary in all applications, their mass is definable within the overall estimation. A detailed weight database of most available engines is presented in Vrontorinakis [29]. Based on this data, Figure 4.9 has been produced for diesel engine mass. The correlation between diesel engine weight and power/engine speed ratio can be summarized as follows;

$$W_D = 6.82 \times \left(\frac{P_I}{n} \right)^{0.85} \text{ tonnes (R}^2=0.913) \quad \mathbf{4-16}$$

where P_I is the delivered power to per propulsion unit, and n is the engine speed (rpm).

It should be noted that since equation 4-16 is non linear, it has to be applied for each engine unit.

4.4.2.2 Total Mass Estimation for Gas Turbines

Apart from diesel engines as prime movers for fast ferries, gas turbines are the other alternative,

either alone or combined with a diesel.

There are two main types of gas turbines namely the aero derivative and the heavy duty industrial. The former type usually comprises parts of a jet engine, somewhat down-rated with regard to temperature and power, acting as a hot gas generator supplying energy to a specially designed output turbine connected to the propulsion gearing.

As aircraft gas turbines are designed primarily for flying, the emphasis for fast ferry applications has to be on maintaining minimum size and mass, with restricted frontal area. However, these engines operate at higher-pressure cycles and burn expensive fuel, something not very desirable for marine applications in general.

The industrial gas turbine in turn, does not have so much emphasis on mass reduction, but has more emphasis on machine life and reduction on maintenance. The outcome is a more robust engine with inevitably higher mass, and bulk volume. For these reasons, the heavy-duty turbine is not offered for marine service, unless editions and developments in the cycle refine it.

Gas turbines consist of three parts:

1. Gas generator (produces hot gas), consists of compressor stages, combustion chambers and compressor turbine stages,
2. Power turbine,
3. Module.

For various reasons, marine gas turbines benefit from being in dedicated modules. When mass is considered, gas turbines have the ability to be able to include their auxiliaries in this contained platform, and offer advantages such as, structural support, ease of mounting, shock protection and others.

The mass of the turbine increases proportionally to the power output, just as diesel engines. Specific fuel consumption decreases along with the power increase. Based on Vrontorinakis [29] data was plotted in Figure 4.10. Gas turbines mass can be obtained using equation 4-17.

$$W_{GT} = 3.0 + 0.00056 \cdot P_i \text{ tonnes (R}^2=0.917) \quad \mathbf{4-17}$$

where P_i is the installed power per propulsion unit.

Again, the weight formula has to be applied for each gas turbine.

4.4.2.3 Total Mass Estimation for Propulsors

One of the most important differences between fast ferry propulsion and conventional ship propulsion is created by the prime mover itself. No matter if it is a high or medium speed diesel engine or gas turbine, they all operate at high rotational speeds for a propulsor to cope directly and deliver the expected power. The accepted solution, is to use a reduction gearbox, which will bridge the speed difference, but at the same time add more weight, lower the transmission efficiency, increase bulk volume and complexity, and ultimately increase costs.

The propulsion device in turn, is almost always a water jet for fast speed applications, since among other advantages they prove to be more efficient at speeds over 25-30 knots than conventional propellers. Another very important aspect of water jets, is that they weigh less than propeller installations. Water jet mass data correlated with installed power (P_I) is shown in Figure 4.10. The main trend is represented by equation 4-18.

$$W_{WJ} = 0.00018 \times P_I^{1.18} \text{ tonnes (R}^2=0.966) \quad \mathbf{4-18}$$

P_I represents the installed power per propulsion unit.

Again as in previous sections the obtained equation is non linear and has therefore to be applied for each propulsor independently.

4.4.2.4 Total Mass Estimation for Gearboxes

Large amounts of data were found for gearboxes suitable for fast ferries, Vrontorinakis [29]. The data was processed to find an initial mass estimate of the gearboxes for fast ferries. The relationship between maximum power and the total weight of the gearboxes has been correlated in figure 4.12 to estimate an initial weight. Regression from this correlation is summarized in equation 4-19 with a satisfactory reliability of $R^2=0.80$.

$$W_{GB} = 0.00348 \times P_I^{0.75} \text{ tonnes} \quad \mathbf{4-19}$$

P_I is the installed power per propulsion unit. The estimation must be multiplied by the number of propulsion units to obtain the total gearbox weight.

Since the weight formula of gearbox is non linear, it has to be applied for each propulsion unit.

4.4.3 Principal Components of Remaining Machinery

Research was carried out initially to find suitable data for each of the remaining machinery parts to make the estimation of the remaining part of the machinery mass (W_{RM}) as reliable as possible. Detailed search to obtain generator, pump, pipe and other auxiliary mass data was performed. It was only possible to attain some generator mass data. Pumps, piping and other auxiliary mass data was not available. An alternative solution was therefore required to estimate the remaining part of the machinery mass. It was decided that the remaining part of the machinery installation weight could be estimated as a function of the total propulsion mass (W_P) as shown in equation 4-20. It is clear that the amount of the remaining machinery installed on board is dependent on the sizes of the main engine, propulsor and the gearbox. Therefore, the idea of remaining machinery mass being a function of the total propulsion machinery mass was plausible.

$$\begin{aligned} W_P &= W_D(W_{GT}) + W_{WJ} + W_{GB} \\ W_{RM} &= f(W_P) \end{aligned} \quad 4-20$$

Propulsion mass data was gathered for high speed ferries from Joo et al [14] and Trincas et al [28]. These values can be seen in Table 4.4. It was very difficult to assess the type of function between the total propulsion mass and the remaining machinery mass since the available data was scarce. To keep the estimation simple, a linear relationship between these two masses was obtained. Thus, the remaining machinery mass found to be represented by equation 4-21.

$$W_{RM} = n \times W_P \quad 4-21$$

The value n is based on available data and a sequence of mass balances for high-speed craft. A number of calculations was carried out to find a suitable n value. An example from these calculations is shown below to better explain the process. The particular example's data is taken from Trincas et al [28]. The remaining calculations were undertaken in the same way. The average of the n values was then obtained. Values ranged from 0.64 to 0.45, with its final value being around 0.55. A suitable approximation of the remaining machinery mass was therefore that expressed in equation 4-22.

$$W_{RM} = 0.55 \times W_P \quad 4-22$$

4.4.4 Total Machinery Mass

Total machinery mass estimation was completed taking into account the different aspects and techniques detailed in the previous sections. The total machinery mass is then calculated as the sum of the main engine, propulsor, gearbox and the remaining machinery masses in equation 4-23.

$$\begin{aligned} W_{TM} &= W_p \times 1.55 \\ W_{TM} &= [W_D (\text{or } W_{GT}) + W_{GB} + W_{WJ}] \times 1.55 \end{aligned} \quad 4-23$$

4.4.5 Summary

A method for the initial estimation of fast ferries total machinery weight has been generated. It is believed that the results can be accepted to be reliable with some degree of confidence.

Different engine modes and propulsors can be applied to the method in future to further expand its capabilities. Engine modes would account for the fact that some fast ferries contain diesel and gas turbines together as their main power suppliers. Also, a second propulsor such as a propeller could be added to the method.

It is clear that lack of data could cause some inaccuracy on the present results, but this does not invalidate the overall idea and methodology. Furthermore, the addition of more data in the future will enable a refinement of all the methods employed.

4.5 DEADWEIGHT

4.5.1 Background

Deadweight is defined as the difference between the load displacement and the lightweight. It is an important part of the whole vessel mass and can be estimated fairly accurately, since it is possible to obtain information for its components such as cargo, fuel, water, crew, effects, etc. In the context of the present research it is assumed to include the following:

- Passengers and luggage
- Vehicles
- Crew and effects
- Water and provisions

- Fuel and lubricating oil
- Ballast, cargo and others.

Deadweight estimation can only be carried out when the main operational requirements of the vessel are defined or assumed. These include speed, range and capacity. The mass per passenger, crew, luggage, effects and per vehicle is applied as typical standard values, as described in the next section.

4.5.2 Principal Components of Deadweight Mass

Standard values for components of deadweight mass are detailed in Table 4.5 from Karayannis [16]. The table shows the standard values for passenger, luggage, vehicle, crew, effects, water, provisions, fuel, lubricating oil and others weights.

Passenger and luggage weight is calculated by multiplying standard per person and luggage weight by number of passengers. The same method is applied to the vehicles and crew and effects.

The mass of water and provisions required are estimated by using typical daily consumption per person on board. This number then multiplied by the number of people on board.

Fuel and lubricating oil masses are calculated by using a relationship which is a function of service power, speed, consumption and range. The equations of principal components of deadweight are given in Table 4.6. The given equations show the basic relation between all these parameters. It is clear that the amount of fuel need to be stored on board is related to the effective power, specific fuel consumption, service speed and range of the vessel. A 9% for generator diesel and lubricating oil allowance is made together with a margin of 10%.

New deadweight values have been generated by using the equations in Table 4.7. These values have been compared against real ship data to measure the reliability of the current study's results. The comparisons are given in Table 4.7 and Figure 4.13. Figure 4.13 shows that the estimation is reliable for an initial set of calculations for deadweight. Only two parts of the real ship data and estimated value show reasonable correlation. For preliminary estimation purposes these two parts are acceptable.

4.5.3 Summary

Details of the estimation of masses which make up the total ship mass have been given in the previous sections. This allows the application of initial mass estimates to achieve a balance between masses and suitable dimensions, as described in chapter 2. They will then be employed for the building of cost estimates in chapter 5.

L_{OA} (m)	45	50	55	75	95	100	105	125	145	150	155
B (m)	9.83	8.85	8.04	12.6	15.86	15.07	14.35	19	23.06	22.3	21.58
D_{OA} (m)	9.18	9.18	9.18	11.14	13	13	13	15	16.7	16.7	16.7
T (m)	1.78	1.78	1.78	2.16	2.52	2.52	2.52	2.9	3.24	3.24	3.24
E	805.5	846	886.1	1680	2592	2650	2707	4023	5473	5547	5621
Wh (t)	121.5	125	129.1	249.3	384.8	399.3	409.6	654.6	981.7	984.7	1020

Table 4.1: Designed Monohulls for Hull Mass Estimation ($L_{OVERALL} \times B$ is constant).

L_{OA} (m)	50			75			100		
B (m)	13.8	15.2	16.9	22.72	24.26	25.88	28.9	30.2	31.8
B/2	6.9	7.6	8.45	11.36	12.13	12.94	14.45	15.4	15.9
S/L	0.209	0.222	0.238	0.218	0.239	0.26	0.196	0.224	0.258
D_{OA} (m)		9.68		15.42	15.34	15.44		19.36	
T (m)		1.88			2.83			3.8	
B (m)		4		6.37	6.34	6.38		8	
E	1384	1460	1587	3305	3476	3661	5618	5813	6053
W_h (t)	255	274	310	564	601	631	915	943	987

Table 4.2: Designed Catamarans for Hull Mass Estimation ($L_{OVERALL} \times B$ is constant).

N_{DECK}	L_{OA}	B_{OA}	W_{OUTFIT}	n	Reference
2	97.95	19.70	100.07	0.026	Joo et al [15]
2	109.50	29.50	180.00	0.028	Trincas et al [31]
2	80.24	20.18	87.59	0.027	Joo et al [15]
2	45	11.8	27.71	0.026	Wood et al [35]
2	50	11.8	33.95	0.029	Wood et al [35]
2.5	104.65	16.44	200.08	0.026	Trincas et al [30]

Table 4.3: Calculation of Outfit Mass.

$W_{\text{PROPULSION}}$ (t)	W_{REST} (t)	n	Reference
190.39	121.5	0.64	Joo et al [15]
177.82	98.25	0.55	Joo et al [15]
100	45	0.45	Trincas et al [32]

Table 4.4: Remaining Machinery Mass Estimation.

Passenger & Luggage	Passenger = 75 kg/person Luggage = 30 kg/person
Vehicles	1000 kg/car
Crew & Effects	Crew = 75 kg/person Effects = 60 kg/person
Water & Provisions	Drinking water = 20 kg/person.day Hygiene = 120 kg/person.day Provisions = 10 kg/person.day
Fuel & Lubricant	Fuel oil = $P_S \cdot \text{SFC} \cdot (R/V_S)$ Diesel oil = Fuel oil · 6% Lubricant oil = Fuel oil · 3% Margin = 10%

Table 4.5: Principal Components of Deadweight.

Passenger & Luggage	$W_{PAX} = 0.105 \times N_{PAX}$ tonnes
Crew & Effects	$W_{CREW} = 0.135 \times N_{CREW}$ tonnes
Cars	$W_{CAR} = 1.0 \times N_{CAR}$ tonnes
Fuel & Lubricant oil	$W_F = [P_S \times \text{SFC} \times (R/V_S) \times 1.09 \times 1.10] / 1000$ tonnes
Fresh water&Provisions	$W_{FW} = 0.150 \times N_{PAX} \times (R/V_S) \times (1/24)$ tonnes

Table 4.6: Suitable Formulae for the Principal Components of Deadweight.

N_{PAX}	N_{CAR}	N_{CREW}	R (nm)	P_1 (kW)	V_S (kn)	DW_{real} (t)	Reference
367	0	5	200	5740	27	64	FFI May'95
794	190	5	350	22000	36	373	FFI June'95
696	100	5	500	29830	40	314	FFI December'95
400	60	5	310	12000	35	155	FFI March&April'96
446	52	5	200	32200	52	142	FFI December'97
351	42	5	100	10840	39	77-102	FFI January&February'96
1200	219	5	300	33900	36.5	448-574	FFI April'97
700	140	5	500	28320	35	360-450	FFI April'97
500	148	5	500	24000	37	200-320	FFI July&August'96
1800	460	5	300	88000	40	800-1200	FFI March&April'96
1500	425	5	295	44000	35	709-1185	FFI June'95

Table 4.7: Deadweight Estimation Compared with Actual Ship Data (FFI stands for Fast Ferry International).

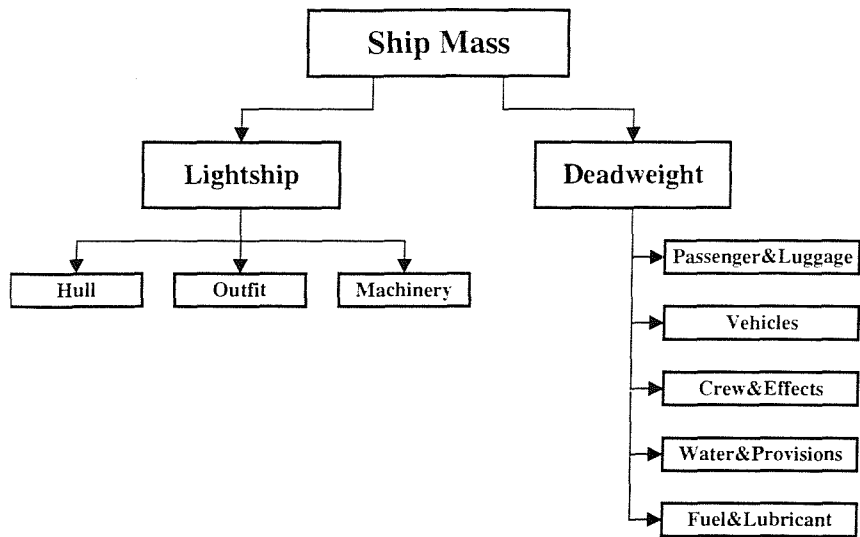


Figure 4.1: Breakdown of Ship Mass.

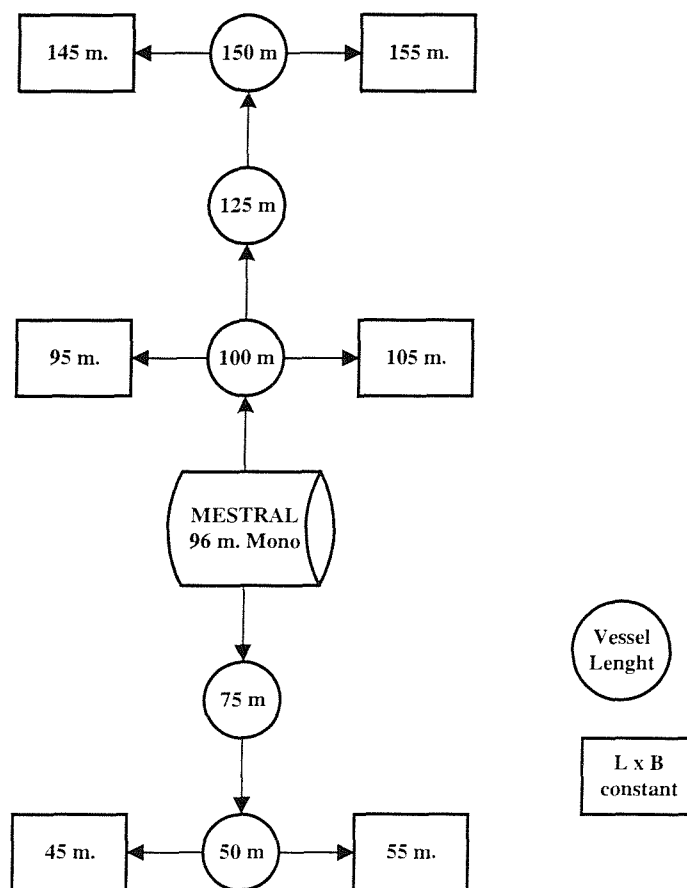


Figure 4.2: Work Task Developed for Monohull Hull Mass Estimation.

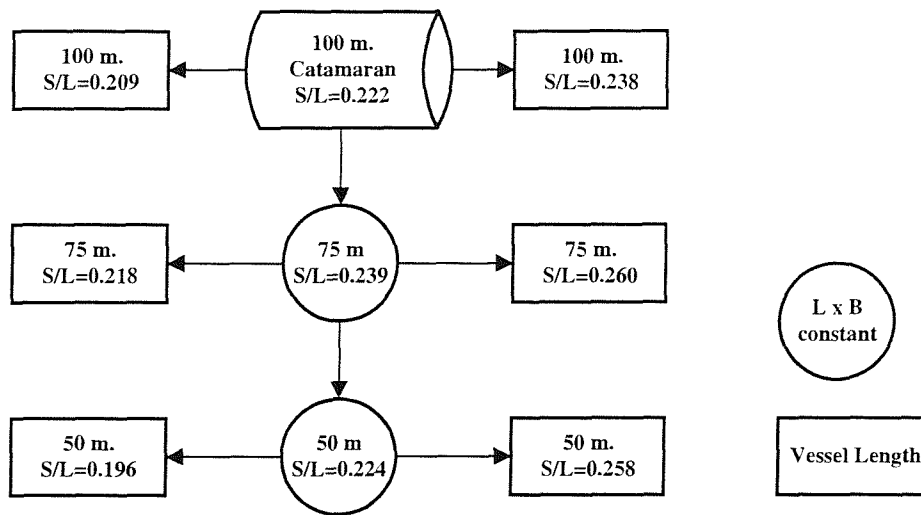


Figure 4.3: Work Task Developed for Catamaran Hull Mass.

Ship Type	K	E
Tankers	0.029-0.035	1500<E<40000
Chemical tanker	0.036-0.037	1900<E<2500
Bulk carrier	0.029-0.032	3000<E<15000
Open type bulk	0.033-0.040	6000<E<13000
Container	0.033-0.040	6000<E<13000
Cargo	0.029-0.037	2000<E<7000
Refrig.	0.032-0.035	E≅5000
Coasters	0.027-0.032	1000<E<2000
Offshore supply	0.041-0.051	800<E<1300
Tugs	0.044	350<E<450
Trawler	0.041-0.042	250<E<1300
Research vessel	0.045-0.046	1350<E<1500
Ferries	0.024-0.037	2000<E<5000
Passenger	0.037-0.038	5000<E<15000

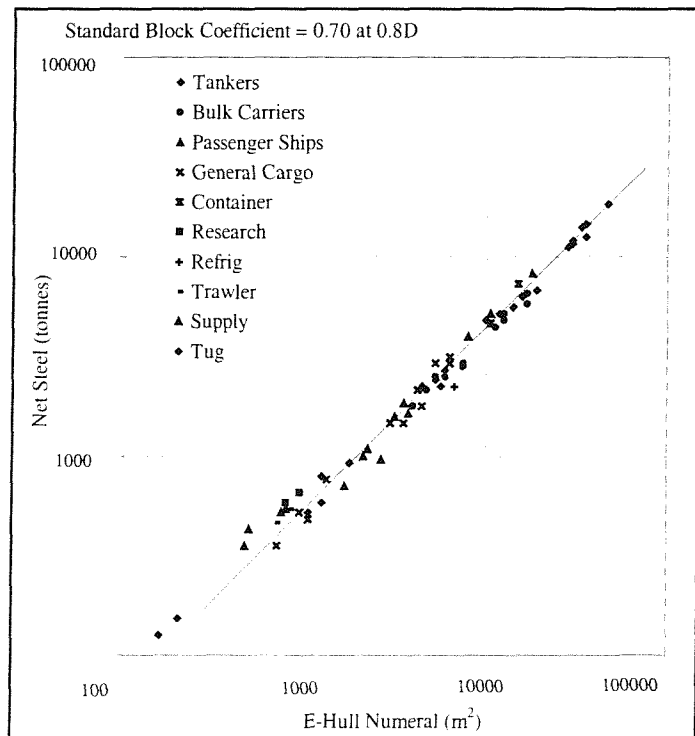


Figure 4.4: Relationship Between Equipment Numeral and Net Steel.

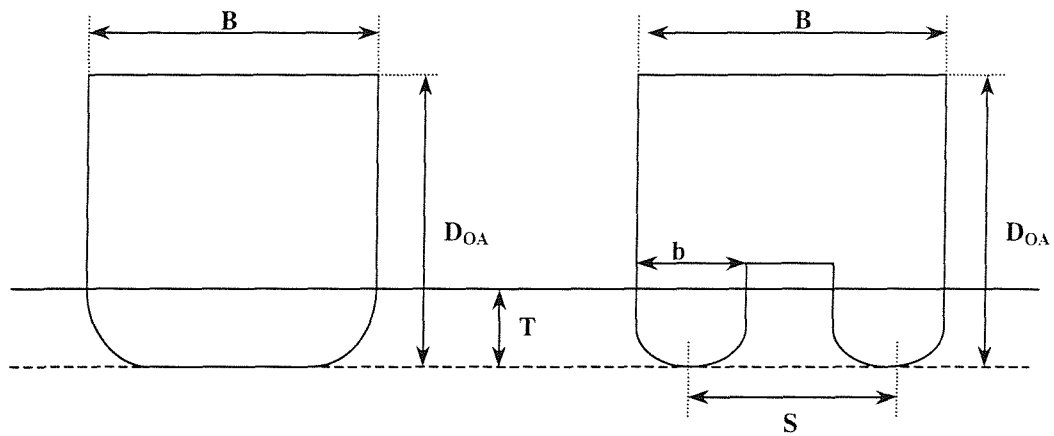


Figure 4.5: Midship Section of a Monohull and a Catamaran.

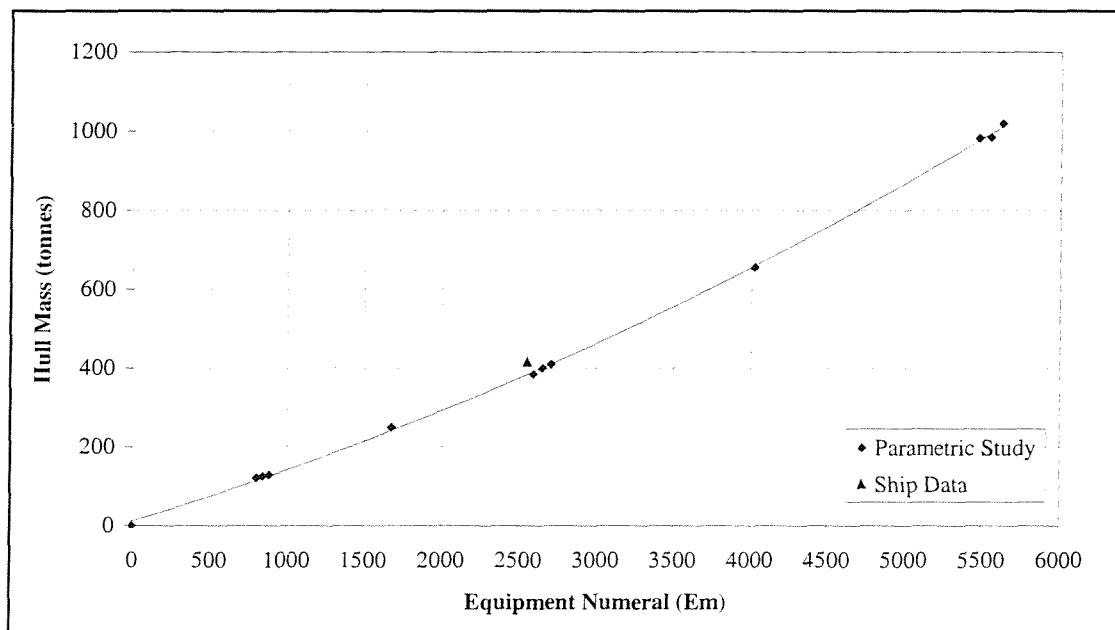


Figure 4.6: Monohull Hull Mass Data.

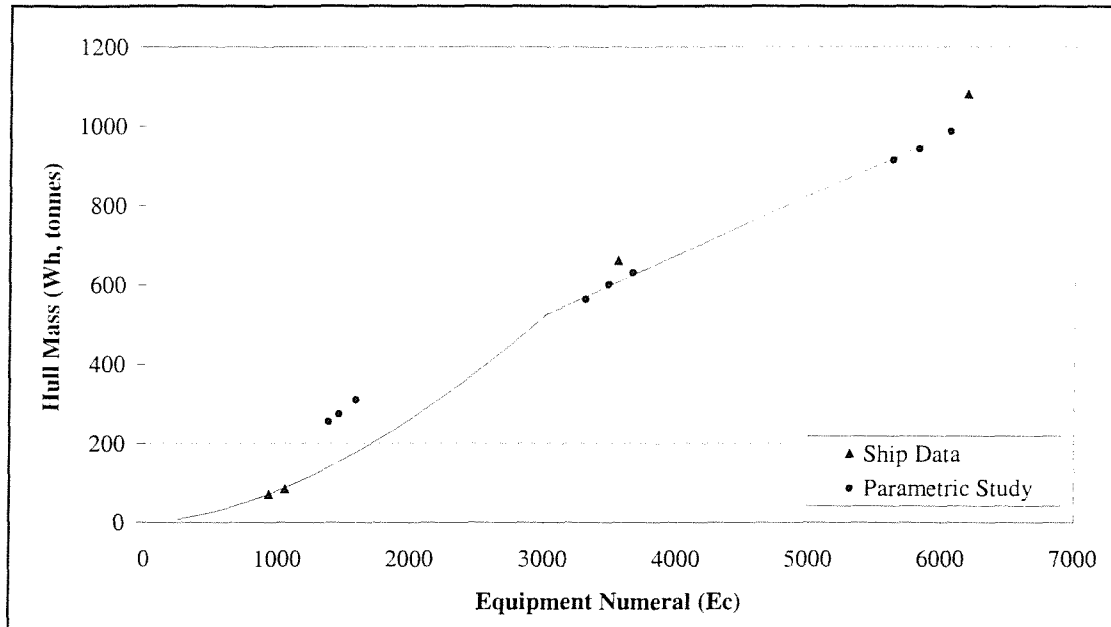


Figure 4.7: Catamaran Hull Mass Data.

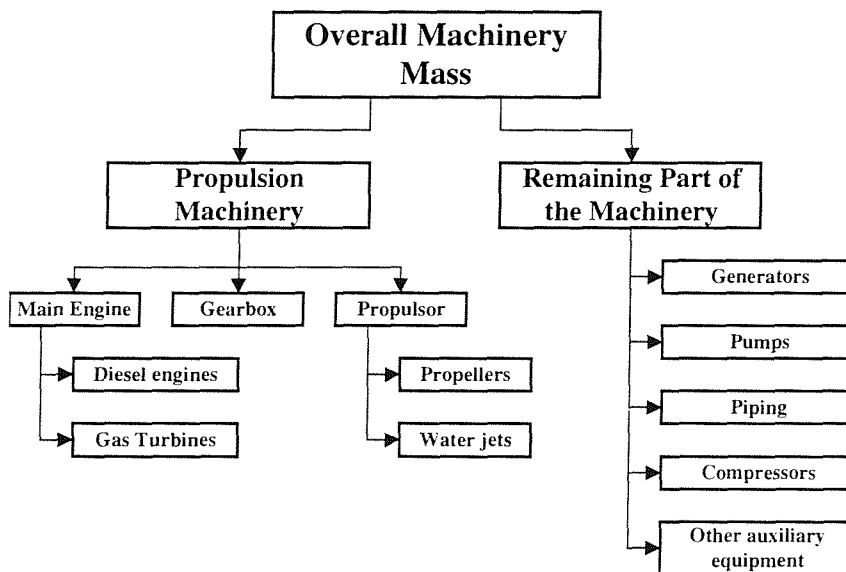


Figure 4.8: Principal Components of Overall Machinery Mass.

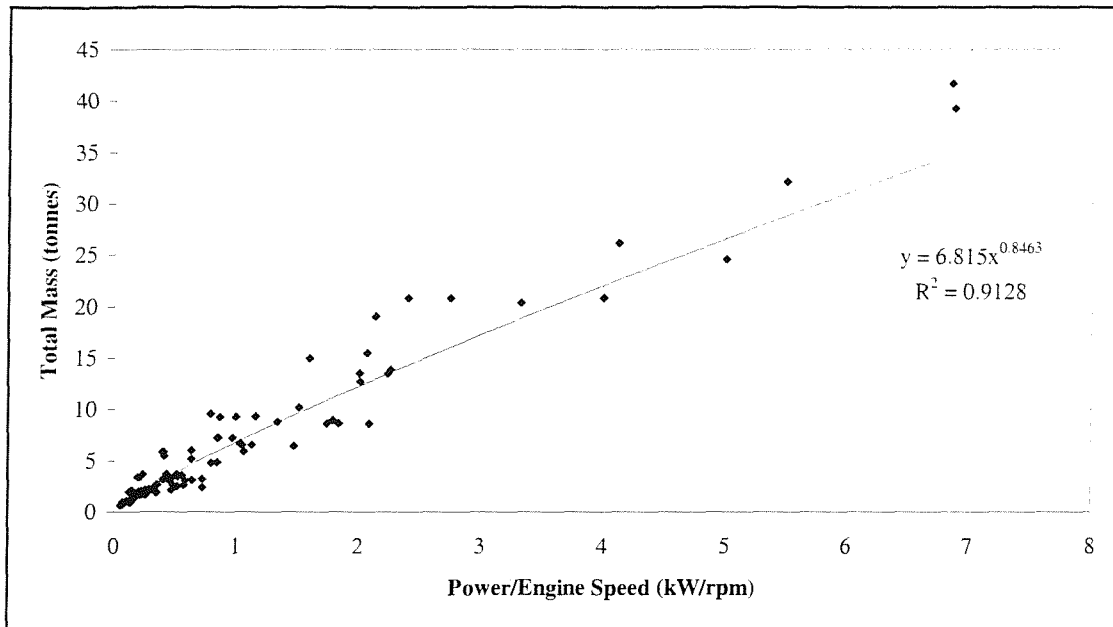


Figure 4.9: Diesel Engine Mass Data.

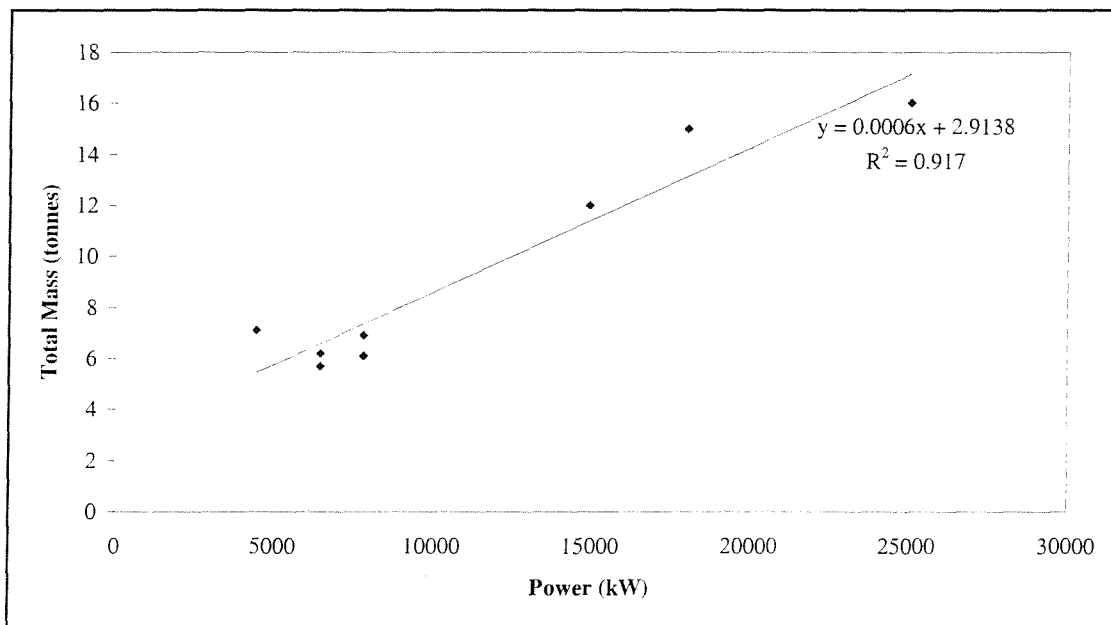


Figure 4.10: Gas Turbine Mass Data.

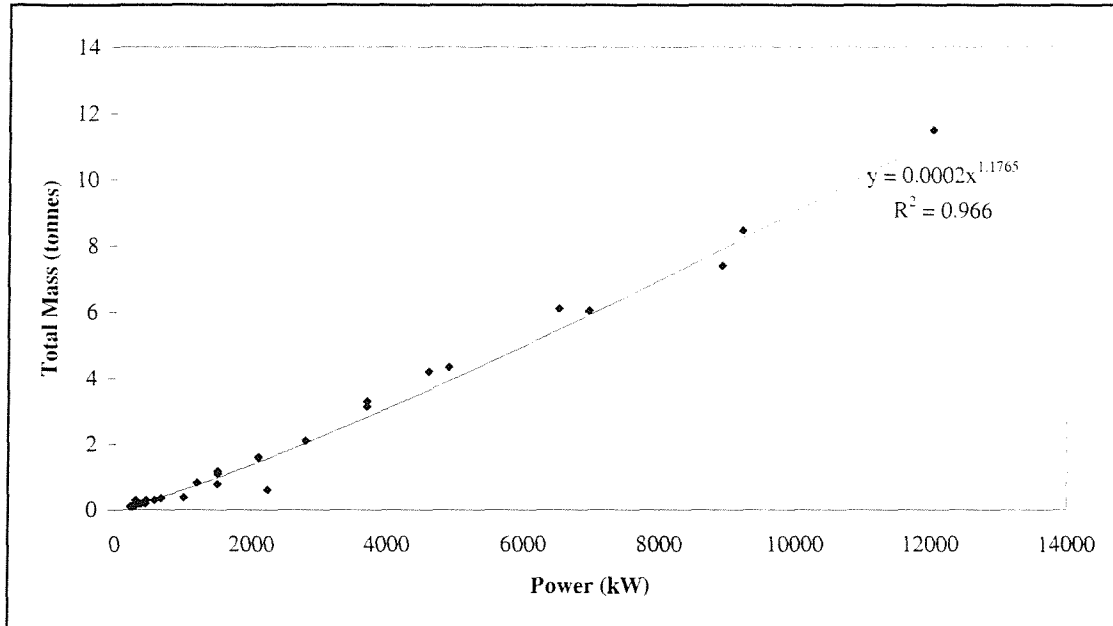


Figure 4.11: Water Jet Mass Data.

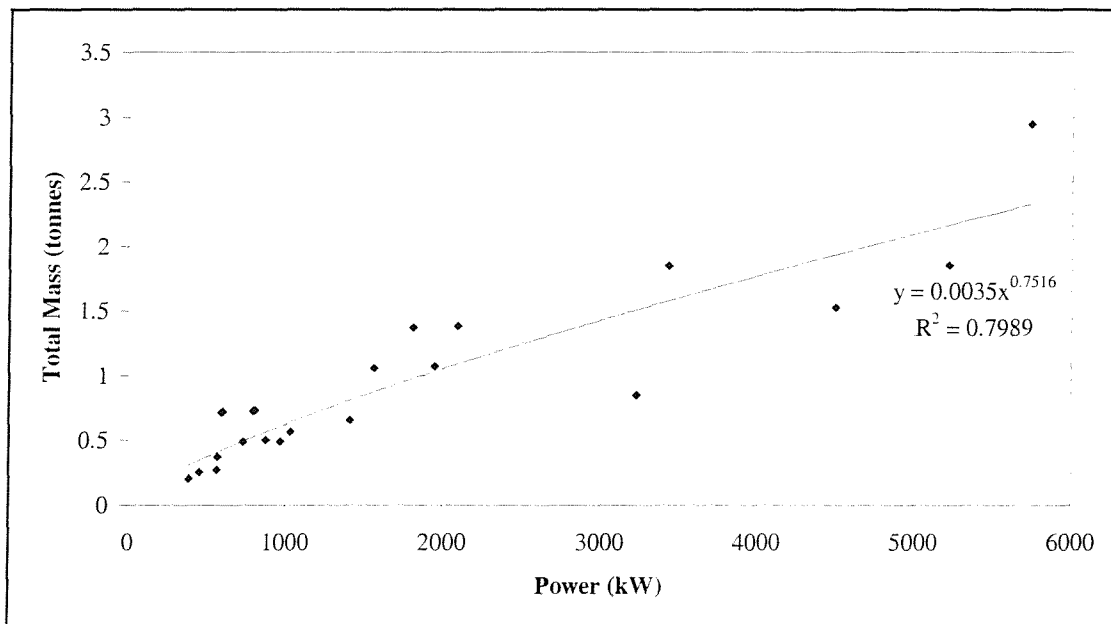


Figure 4.12: Gearbox Mass Data.

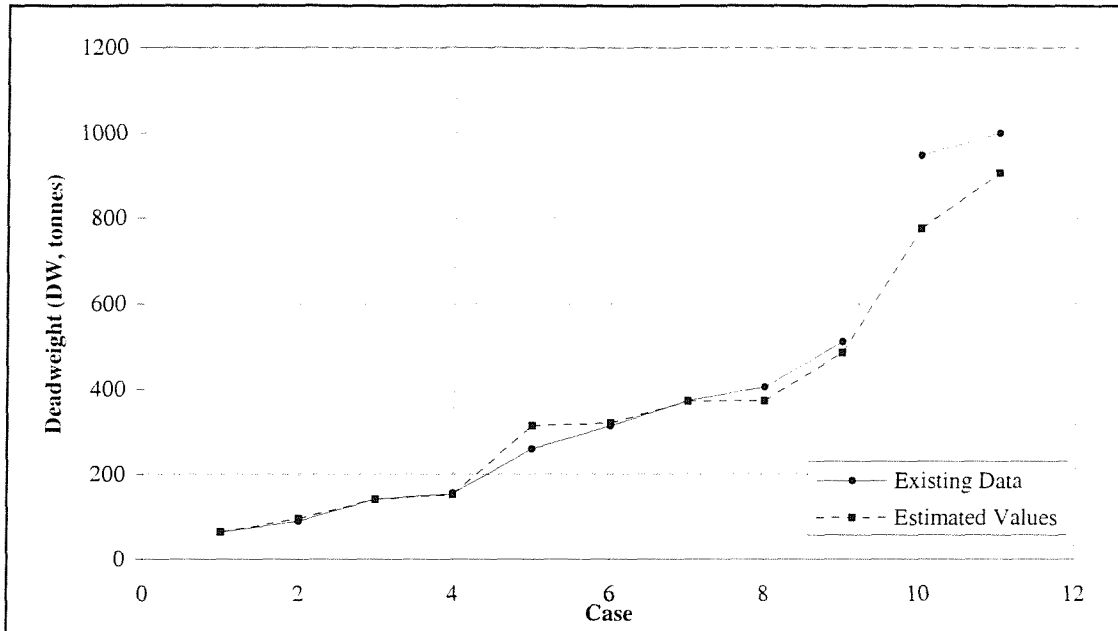


Figure 4.13: Deadweight Comparison.

5. COSTS

5.1 GENERAL

In order to assess the commercial viability of high speed ferries, it is important to be able to estimate the costs related to such vessels as accurately as possible at the very early design stages.

The analysis presented herewith focuses on building costs. Estimates of running costs should not normally present problems once the operational requirements are known. The design and construction of high speed vessels involves innovative techniques and technologies. As a result, traditional approaches commonly used for estimating building costs used in conceptual and preliminary design studies, such as that developed by Caryette [4], may not be directly applicable for such craft, at least quantitatively. The approaches presented in this section have therefore been specifically developed for high speed vessels.

5.2 APPROXIMATE OVERALL BUILDING COST

As it is stated in chapter 2, carrying capacity is the major initial requirement for a new high speed ferry design in the current research study. At the same time speed is likely to be the second major initial requirement for a new high speed ferry design. They both directly influence the size of the vessel and the machinery installation, which are significant factors affecting a vessel's building cost.

In an earlier work, Karayannis [16], in order to provide rapid initial estimates, developed relationships for building cost calculations based on these parameters. The analyses were based on actual acquisition costs found for existing high speed ferries in relevant literature such as Lloyd's List, Fast Ferry International and other professional journals. It revealed that adequate correlations could be obtained for these parameters. The resulting regression formulae are given as follows:

$$C_M = -37.6 + 0.0115 \cdot N_p + 0.121 \cdot N_v + 1.230 \cdot V_s \text{ MUSS, } R^2=0.96 \quad \mathbf{5-1}$$

$$C_C = -18.4 + 0.0294 \cdot N_p + 0.111 \cdot N_v + 0.445 \cdot V_s \text{ MUSS, } R^2=0.89 \quad \mathbf{5-2}$$

where C_M and C_C represent the building costs (million United States Dollars) for monohulls and catamarans respectively.

As discussed in Molland et al [19] the correlation are satisfactory, although some problems exist for small vessels, which suggests that the formulae should be used with caution at the lower end of the size range. Apart from this exception, agreement of calculated values with real prices is generally reliable. Therefore, data obtained from Karayannis [16] is adequate and is used in the present study cost estimation method with some updates and alterations, which are clarified in the following sections.

5.3 DETAILED COSTS

5.3.1 General

The development of detailed calculations entails breaking down the total building costs into the hull, outfit and machinery costs. Also, the further division of each of these components into materials/equipment and labour was also investigated in the current work. As it is understandable, such investigations are particularly important in concept design studies since every little item included in the whole estimation will provide more accurate final results. Detailed calculations of hull, machinery and outfit costs are described below.

5.3.2 Hull Cost

The estimate of hull cost is mostly based on the hull mass. It is also constructed as a function of the labour costs. Beside these two factors, a 10% material scrap value is assumed, and is added to the total hull cost. Some data have been obtained from shipbuilders on the basis of commercial confidentiality. These data are shown in Table 5.1, and provides suitable values for the material and labour rates to be used in equation 5-3. The data has been obtained from a fast ferry shipbuilding company and asked not to be referenced regarding their secrecy reasons.

$$C_H = (W_H \times M \times 1.10) + (W_H \times LT \times LC) \text{ US\$} \quad 5-3$$

where M is the material cost per tonne, LT is the labour hour per tonne and LC is the labour cost per hour. The first part of the equation calculates the material and scrap material values whilst the latter part determines the labour cost. The price of aluminium alloy is 5250US\$ per tonne, whilst mild steel costs 900 US\$ per tonne. Labouring time for simple structure is approximately 600 hours per ton and 900 hours per ton for complex structure. The definitions of simple and complex structures are explained in the following paragraph. Labour costs an average of 30 US\$ an hour.

The labour hours have a range covering simple to complex structures. A monohull can be considered as a simple structured vessel. On the other hand a catamaran represents a complex structured ship, the simple reason being that a catamaran has got two thin demihulls and an extra structure between two hulls, which may be time consuming and difficult to manufacture.

From all above information, an estimation method of initial hull cost for high speed ferries has therefore been developed which is considered to be acceptable for preliminary estimates.

5.3.3 Outfit Cost

The estimate of outfit cost is based on a limited amount of available data. For the time being, an overall outfit cost (C_o) estimate, based on outfit mass (W_o), is proposed as follows. This value is derived from Karayannis [16] and has been updated according to the percentage of the inflation for each year.

$$C_o = 22,000 \times W_o \text{ US\$} \quad 5-4$$

5.3.3 Machinery Cost

The total machinery costs are made up from main engines (diesel engines and gas turbines), gearboxes and water jets together with the further costs. The further costs are a function of propulsion equipment costs, associated with the remaining equipment and the overall labour costs associated with the machinery installation.

It is assumed that the demand for passengers and cars to be transported always equals the full capacity of the vessel. For this reason the analysis had been carried out with the full displacement service speed and fuel consumption.

The overall factors that have been taken into account for a correct evaluation of the machinery costs are the following:

- Main engine capital cost as given by engine suppliers including installation, two days torsion vibrations tests, trials, and guarantee.
- Costs of gearboxes, water jets controls etc. according to prices obtained by manufacturers or suppliers.

All prices are quoted in United States Dollars (US\$). It should be mentioned that prices given by manufacturers and suppliers can be subject to large changes, depending on the special circumstances on each occasion. Engine manufacturers for example are willing to significantly reduce their listed engine price in order to ensure a future spare parts customer. Other reasons for price reductions are greater quantities purchased, and/or services ensured. Therefore, the prices given are average list prices, depending on place, time and customer, as well as on successful negotiations.

Relevant initial cost data, Vrontorinakis [29] has been displayed versus installed power in Figures 5.1 to 5.4. Regressions from the relevant figures are presented in Table 5.2.

The cost of the remaining items of machinery such as generators, pumps together with the overall auxiliary costs was found to be of the order of 40% of the propulsion machinery cost. This number was been generated by a sequence of cost balances.

Initially, a number of ship data was obtained from the database, Then, their hull, outfit, main engine, water jet and gearbox costs were estimated according to the equations developed in the current study. Equations 5-1 and 5-2 were used to estimate the overall building cost of each vessel. The estimated hull, outfit and machinery costs were subtracted from the estimated building cost to obtain the remaining machinery cost. Mean value of the ratio remaining machinery cost/propulsion cost was found to be 0.40. The end products can be observed from Table 5.3.

Consequently, total machinery cost can be summarized by equation 5-5.

$$C_{TM} = [C_D(C_{GT}) + C_{GB} + C_{WJ}] \times 1.40 \quad 5-5$$

where C_D corresponds to diesel engine, C_{GT} to gas turbine, C_{GB} to gearbox and C_{WJ} to water jet costs.

5.4 OVERALL BUILDING COST

After obtaining all the detailed estimates, the total building cost for monohulls (C_M) and catamarans (C_C) may now be summarized. The resultant formula is that presented in equation 5-6.

$$C_M(C_C) = C_H + C_O + C_{TM}$$

5-6

It should be noted that when developing a database of costs and assessing its reliability, published ship acquisition costs will have been influenced by other effects such as assumed profit levels, multiple builds, commissioning and delivery charges and how badly a shipyard may need an order.

Data for detailed costing, particularly that relating to remaining machinery costs, is sparse. Broad assumptions and data generated by sequences of cost balances have therefore been used in places. However, it is considered that the proposed equations will provide a reasonable estimate of overall cost, together with a good indication of relative levels between components costs and changes in component costs as a result of design changes. This makes the equations particularly suitable for use in preliminary design and concept investigations.

Material (M)	Aluminium Alloy	5250 US\$/tonne
	Mild Steel	900 US\$/tonne
Labour Time(LT)	Simple Structure	600 hours/tonne
	Complex Structure	900 hours/tonne
Labour Cost (LC)		30 US\$/hour

Table 5.1: Rates of Materials and Labour Costs dated March 1999.

Diesel Engines	$C_D = 0.0003 \times P_i - 0.0423$ million US\$	$R^2=0.992$
Gas Turbines	$C_{GT} = (0.0004 \times P_i) - (4 \cdot 10^{-9} \times P_i^2)$ million US\$	$R^2=0.999$
Gearboxes	$C_{GB} = (2 \cdot 10^{-5} \times P_i) - (3 \cdot 10^{-10} \times P_i^2)$ million US\$	$R^2=0.982$
Water jets	$C_{WJ} = 0.0031 \times P_i^{0.61}$ million US\$	$R^2=0.871$

Table 5.2: Costs of Propulsion Units.

Case	1	2	3	4	5	6	7	8	9	10
L_{OA}	54	31	24.55	54.46	95	95	96	102	124.7	82
B_{OA}	9	3.7	6.5	9.3	16	17.4	16.2	15	18.7	14
T	1.4	0.85	1.2	1.4	2.6	3.65	2.9	3.05	2.44	2.2
D_{OA}	5	2.5	2.5	4.45	4.6	6	10.5	5.2	6.2	9.25
V_S	35	33.5	26	38	36	35	35	37	38	40
N_{ENGINE}	2	3	3	3	2	2	2	2	3	2
N_{DECK}	2	1	1	2	2	2	2	2	2	2
P_I	3000	2370	1830	6960	24000	23200	26000	24000	24000	16000
N_{PAX}	100	190	135	410	600	626	600	500	1250	600
N_{CAR}	-	-	-	-	173	160	188	148	238	70
CH	2.07	0.40	0.48	2.06	6.66	7.76	8.89	7.07	11.48	6.21
CO	0.58	0.07	0.10	0.60	1.81	1.96	1.85	1.82	2.77	1.36
CP	2.65	3.21	2.54	8.57	17.84	17.29	19.21	17.84	26.76	12.28
BC	6.6	5.79	4.07	13.86	34.51	32.01	37.40	31.57	52.31	26.97
CRM	1.31	2.12	0.96	2.63	8.20	5.0	7.45	4.83	11.30	7.12
Ratio	0.47	0.58	0.38	0.31	0.44	0.29	0.39	0.27	0.40	0.54
Reference	PM12b	PM31	PM35	PM38	VM6a	VM10a	VM16c	VM28	VM7c	VM15c

Table 5.3: Costs of Remaining Machinery (please see nomenclature for the abbreviations).

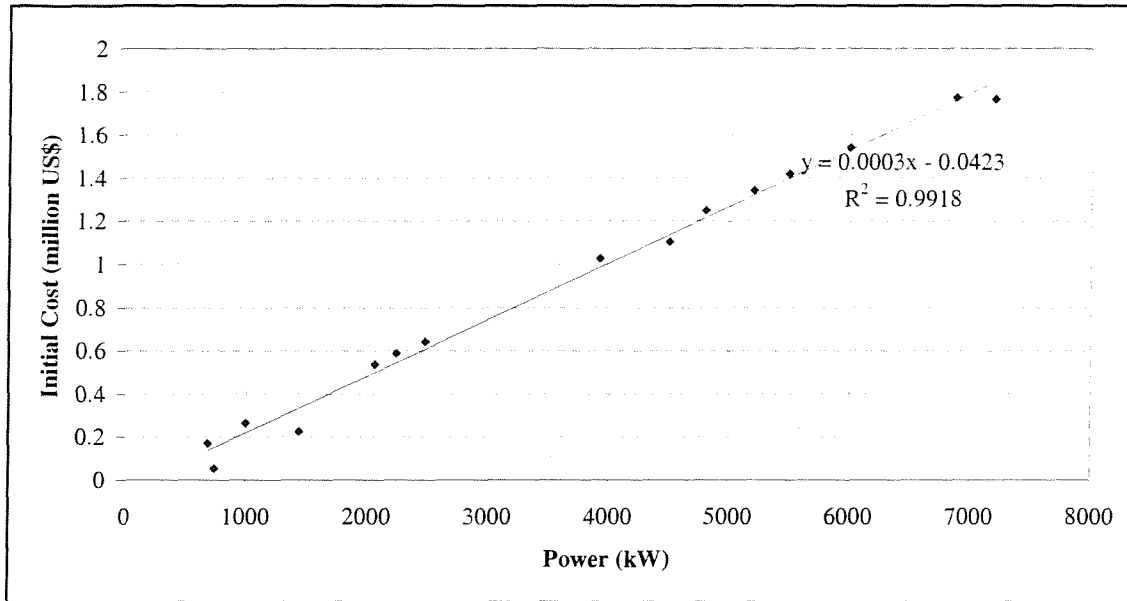


Figure 5.1: Diesel Engine Initial Cost Calculations.

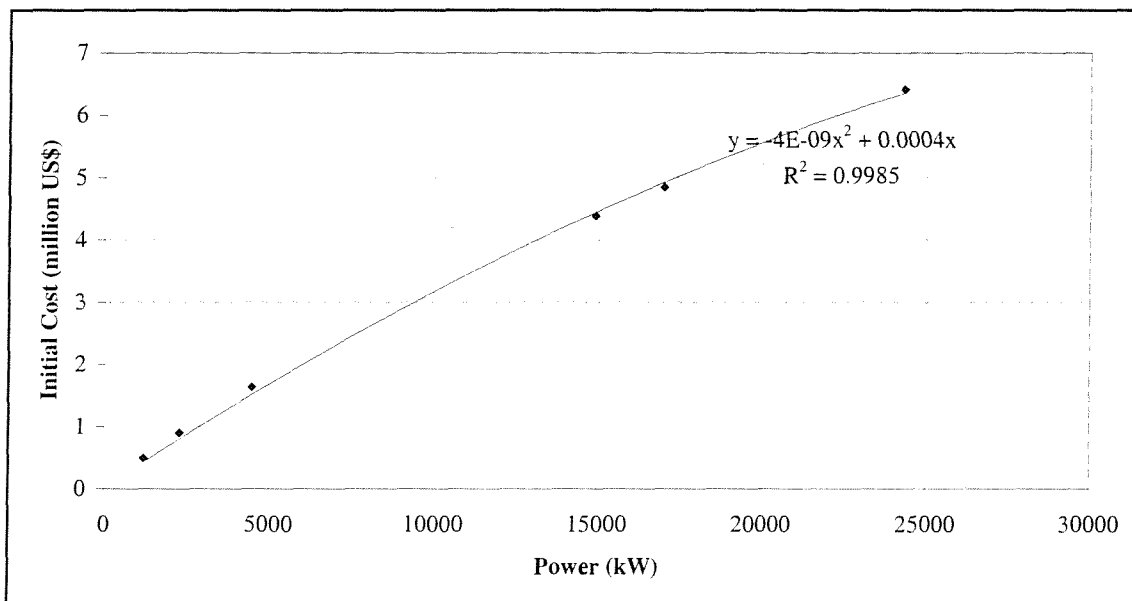


Figure 5.2: Gas Turbine Initial Cost Calculations.

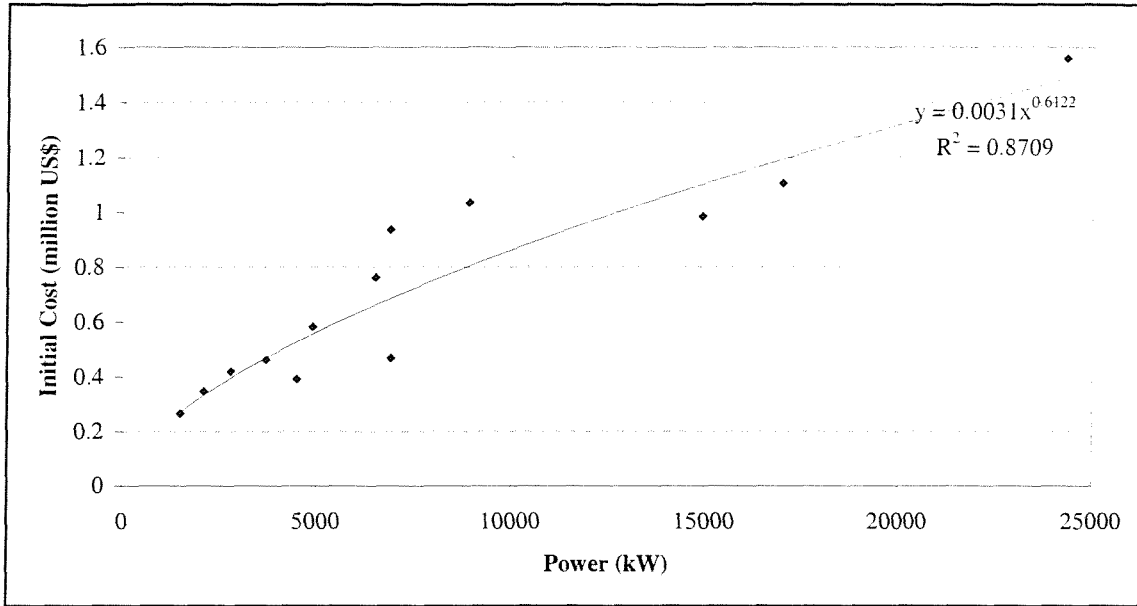


Figure 5.3: Water Jet Initial Cost Calculations.

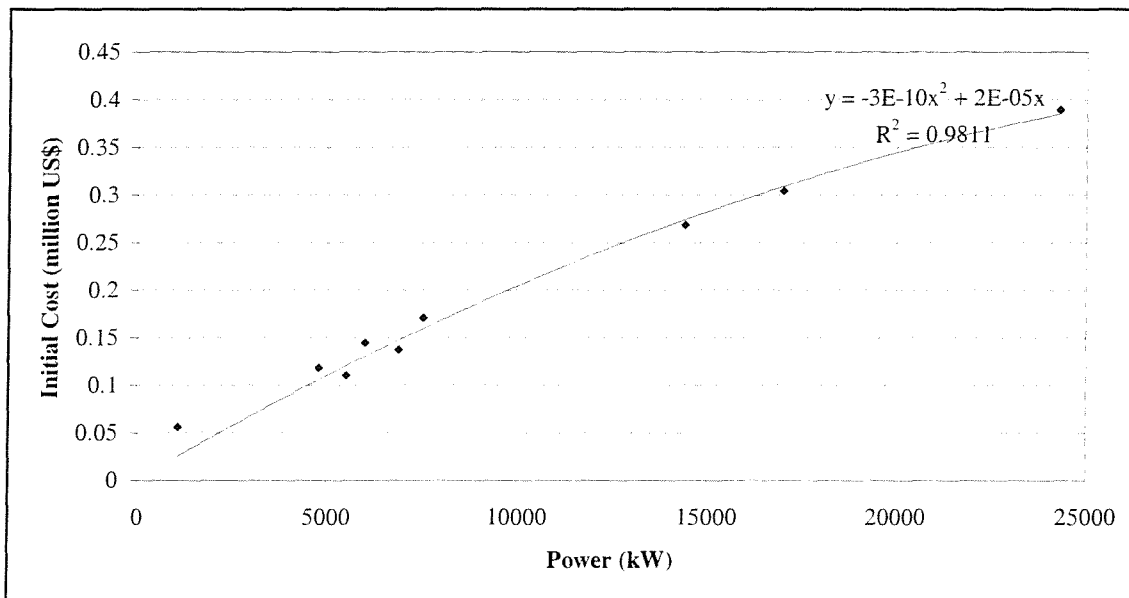


Figure 5.4: Gearbox Initial Cost Calculations.

6. EXAMPLES OF THE METHODOLOGY

6.1 GENERAL

Example designs, which have been generated by applying the methodologies explained in this thesis, are presented in order to demonstrate their feasibility. Two major cases are discussed separately, namely passenger-only and vehicle-passenger vessels. This allows the generation of both small and large vessel designs to be performed. For each of these two categories monohull and catamaran designs are generated, illustrating the use of the methodologies for these two major vessel categories. Two engine and one propulsor type have been used namely diesel, gas turbine and water jet. Each case is estimated for three different service speeds in order to demonstrate the mass balance study as discussed in section 2.2. Hence five examples are carried out resulting in fifteen designs, and these are designated as follows:

Example A: Passenger-only monohull vessel, Diesel main engine, Water jet propulsor.

Example B: Passenger-only catamaran vessel, Diesel main engine, Water jet propulsor.

Example C: Vehicle-passenger monohull vessel, Diesel main engine, Water jet propulsor.

Example D: Vehicle-passenger catamaran vessel, Diesel main engine, Water jet propulsor.

Example E: Vehicle-passenger catamaran vessel, Gas Turbine main engine, Water jet propulsor.

Products of these examples are presented and commented in section 6.2 while an overall view discussed in section 6.3.

Another important issue investigated in this part of the study are the three different methods of changing hull parameters to achieve a mass balance, described earlier in this thesis (chapter 2).

These methods are listed as:

Method 1 Constant $L/\nabla^{1/3}$ and modified C_B and B/T .

Method 2 Constant B/T and modified C_B and $L/\nabla^{1/3}$.

Method 3 Constant C_B and modified B/T and $L/\nabla^{1/3}$.

The outcome of this investigation can be seen in Example F. More detailed explanation can be found in section 6.2.6.

Lastly, Example G illustrates the application of different passenger comfort levels for two designs. This is also outlined in chapter 2.

6.2 RESULTS

6.2.1 Example A

Example A results, Table 6.1, show good correlation with the ship data, which is taken from Appendix I coded as PM4. The particular ship data provides good agreement with the study, and this can be clearly seen in the Figures 6.1.

First figure shows the similarity of some of the main dimensions against the ship data. As it is clear that there is a significant similarity between cases and the actual data.

Later figure presents the installed power changes with the gradually increased service speed. The power increases with speed as would be expected. The ship data is slightly higher than the example, this can be caused by the fact that the ship A is finer, so it would require less power to do the same speed, but this is only an assumption.

Fuel mass is little higher in the ship data. This should be a reason of the bigger installed power. On the other hand the fresh water mass is very low in the actual ship data. This might be caused by a watermaker. Most fast ferries have watermakers on board. There is no need for big tanks of water if the fresh water supplier is a watermaker. This stops the extra weight on board which is a very important issue for any ship, but especially for fast ships.

6.2.2 Example B

Example B demonstrates a good relationship with the ship data, Table 6.2, which is originally taken from Appendix I, PC10c.

Overall main dimensions display a good closeness. It is easy to see this with the Figures 6.2.

Installed power does not exhibit a good correspondence like the rest of data, and the reasons for this are unclear.

It appears to be the fuel mass is very much like the example. On the other hand fresh water mass seemed to be giving the same indication as previous example that, there is likely to be a watermaker installed on board.

6.2.3 Example C

Example C presents an acceptable agreement with the ship data, Table 6.3, which is gained from Appendix I, VM33.

Overall main dimensions exhibit satisfactory results. Figure 6.3 displays the results in a bar chart, which makes it easy to visualise the outcomes.

Installed power does not show a particularly good match. It is possible that the ship data engine is not as efficient as the engine Example C. That is why to produce 34 knots service speed actual ship needs more installed power than Example C ship. This is only one reason from many.

Unfortunately, no detailed deadweight data were available, but the given total deadweight demonstrates a satisfactory similarity with the example.

6.2.4 Example D

Example D represents a complete match with the existing ship data, see Table 6.4. The data adopted from Appendix I, VC3.

Main dimensions correlates very well with the VC3. It is possible to see the good correlation in Figure 6.4. The slight difference between the lengths might have been caused by the fact that the existing data has less cargo on board.

Existing ship's installed power is moderately less than the example. Considering that the existing ship is a smaller vessel a decrease in the power can be predicted.

Fuel mass and the total deadweight shows a good comparison. On the other hand fresh water mass seems to have some miscorrelation which is likely to be due to an installed watermaker.

Overall the examples demonstrates very satisfactory results, noting that these are preliminary values.

6.2.5 Example E

This study offers the best comparison of all the other examples, Table 6.5. The existing ship data is from Appendix I, VC11.

All the dimensions display reasonable correspondence, except the draught. It appears to be the existing ship's draught is very small. The fact is that with this draught and given displacement the ship's block coefficient can approximately be estimated as 0.76. This value is too large for a catamaran hull form as it is appreciated. As it is stated early in this thesis (chapter 2, Table 2.2) that the block coefficient for this type of vessel varies between 0.40 to 0.55. Therefore, 0.76 cannot be considered as a correct block coefficient.

This means that whether the given draught or displacement is not accurate. It should also be mentioned that considering the size of the ship draught seems very low, which means it might well be no-load draught. This size vessel should draw (full load) around 3.8 to 4.5 metres. This also shows that the estimated value presents approximately a true value.

The power displays good similarity with the available ship data. The concern is the deadweight of the existing vessel. It is heavier than the estimated value. Also, the displacement of the existing vessel is higher about 300 kg. It seems to be the estimated deadweight somehow is low, and this causes the total displacement to be low too. Considering that this estimation is a preliminary design few not very close results should not cause a problem.

All comparison of the results can be seen in Figures 6.5.

6.2.6 Example F : Investigation of Mass Balance

Example F illustrates the application of alternative mass balance methodologies, using either constant $L/\nabla^{1/3}$, B/T or C_B . Choice of these options may depend on limitations on length, breadth or draught or acceptable C_B for powering purposes.

A generated ship has been mass balanced with three different methods individually, and shown in Table 6.6. For each method, the altered parameters' fonts have been formatted in bold and underlined to be recognised. It is clear that only the method 2 kept all the initial estimated dimensions as it is, and the rest of the derivatives changed little comparing with the other two

methods' results. For illustrative purposes, for the rest of the generative designs only method 2 is used.

In Examples A to D, for convenience, C_B was varied and the other two variables held constant, which results in the main dimensions of the ship remaining unaltered. This method has been imported into the software, therefore the mass balance can be created easily, and efficiently.

6.2.7 Example G : Investigation of Passenger Comfort Levels

It is apparent that when applied to parametric concept exploration exercises, other parameters can also be varied such as levels of passenger comfort using different seating areas as shown in Example G, see Table 6.7.

Two vessels have been included in the particular example. These are one passenger-only monohull and one vehicle-passenger monohull. Each vessel has two versions with different A_s/N_p and A_p/A_s ratios. As explained earlier in this thesis, these are the parameters which alter passenger comfort. Case1 for passenger-only monohull uses less seating and passenger area per passenger, whilst Case2 has more area to improve passenger comfort. Improvement in the passenger comfort affects the dimensions of the vessel since bigger vessels require bigger engines and most importantly costs increase. A more clear picture can be drawn in Figures 6.6.a and 6.6.b.

This study makes it clear that passenger comfort should be controlled with care.

6.3 DISCUSSION OF RESULTS

In each of Examples A to D, three cases have been created. Cases1 are the original designs, Cases2 and Cases3 are speed-varied versions of the first design. These last two cases have been created to demonstrate the mass balance with speed change. Speed change causes differences on the machinery, fuel, fresh water weight, building cost and power. These differences from the original ship sometimes cause an imbalance between the first and the second displacements. The problem is solved employing the mass balance procedure outlined in section 2.

As stated earlier, the influence of speed on building costs can be clearly seen. It was, however, found that the approximate building costs for smaller vessels were unreliable, and hence have

been omitted. This is believed to be a question of lack of data, and can therefore be improved in the future as soon as more data become available.

Overall, comparisons of these vessels with existing high speed ferries indicate that the methodologies presented in this research programme generate realistic and feasible designs. It is clear that it is difficult to find complete ship data. Comparisons, therefore, should be approached taking this into account and thus allow for certain leeway in the results. Considering this, it is believed that the examples are reliable and feasible.

Some examples and existing ship data might have apparent differences. This may be due to variation in passenger comfort. Therefore, the deviation between the true and created ship might be quite larger than expected. This should also be approached with taking the passenger comfort level into account.

As noted elsewhere, for reliable results, input data should be used with caution, and input parameters within the limits of the database shown in Tables 2.1 and 2.2.

	Case I	Case II	Case III	Ship Data
Vessel Type	PM	PM	PM	PM
Engine Type	Diesel	Diesel	Diesel	Diesel
Propulsor	Water Jet	Water Jet	Water Jet	-
A_S/N_{PAX}	0.60	0.60	0.60	-
A_P/A_S	1.15	1.15	1.15	-
NPAX	400	400	400	450
VS	33	35	37	36
LOA	45.4	45.4	45.4	48.0
LWL	39.9	39.9	39.9	39.5
B	7.2	7.2	7.2	7.9
T	1.6	1.6	1.6	1.3
D	8.3	8.3	8.3	-
CB	0.40	0.41	0.42	-
AS	240	240	240	-
AP	276	276	276	-
LOD	7.00	6.95	6.90	7.20
BOT	4.5	4.5	4.5	6.1
NE	2	2	2	3
RPM	1800	1800	1800	-
PD	3850	4262	4746	-
PE	2551	2880	3264	-
PI	4427	4902	5458	6000
R	300	300	300	-
NCREW	20	20	20	-
NDECK	2	2	2	2
WH	77.5	77.5	77.5	-
WO	17.7	17.7	17.7	-
WM	33.6	36.8	40.5	-
WPAX	42	42	42	-
WFUEL	8.3	8.9	9.5	10.9
WFWPROV	4.6	4.3	4.1	1.5
WCREW	2.7	2.7	2.7	-
BC (milUS\$)	5.5	5.7	6.1	-
ABC (milUS\$)	-	-	-	-
LS	129	132	136	-
DW	61	61	62	-
DISP1	189	193	198	-
DISP2	190	193	198	-

Table 6.1: Example A.

	Case I	Case II	Case III	Ship Data
Vessel Type	PC	PC	PC	PC
Engine Type	Diesel	Diesel	Diesel	Diesel
Propulsor	Water Jet	Water Jet	Water Jet	-
A_S/N_{PAX}	0.65	0.65	0.65	0.59
A_P/A_S	1.20	1.20	1.20	1.18
NPAX	400	400	400	420
VS	33	35	37	37.5
LOA	42.2	42.2	42.2	40.0
LWL	37.0	37.0	37.0	35.6
B	11.4	11.4	11.4	10.1
BH	3.3	3.3	3.3	-
T	1.6	1.6	1.6	1.5
D	9.0	9.0	9.0	-
S	8.1	8.1	8.1	-
CB	0.51	0.52	0.54	-
AS	260	260	260	247
AP	312	312	312	291
LOD	7.96	7.89	7.80	-
BHOT	2	2	2	-
SOL	0.22	0.22	0.22	-
NE	2	2	2	2
RPM	1800	1800	1800	-
PD	4582	5212	6102	-
PE	3036	3521	4196	-
PI	5269	5993	7017	4000
R	250	250	250	-
NCREW	10	10	10	-
NDECK	2	2	2	2
WH	81.5	81.5	81.5	-
WO	26.0	26.0	26.0	-
WM	39.3	44.0	50.7	-
WPAX	42	42	42	-
WFUEL	8.3	9.1	10.2	10.1
WFWPROV	3.8	3.6	3.4	1.5
WCREW	1.4	1.4	1.4	-
BC (milUS\$)	7.1	7.5	8.1	-
ABC (milUS\$)	-	-	-	-
LS	147	152	158	-
DW	59	59	60	-
DISP1	204	208	216	-
DISP2	206	211	218	-

Table 6.2: Example B.

	Case I	Case II	Case III	Ship Data
Vessel Type	VM	VM	VM	VM
Engine Type	Diesel	Diesel	Diesel	Diesel
Propulsor	Water Jet	Water Jet	Water Jet	-
A_S/N_{PAX}	0.95	0.95	0.95	-
A_P/A_S	1.20	1.20	1.20	-
NPAX	650	650	650	600
NCAR	150	150	150	160
VS	36	38	40	34
LOA	100.9	100.9	100.9	100.0
LWL	88.5	88.5	88.5	89.4
B	15.1	15.1	15.1	16.0
T	2.0	2.0	2.0	3.0
D	13.0	13.0	13.0	-
CB	0.35	0.36	0.36	-
AS	618	618	618	-
AP	741	741	741	-
LOD	9.00	8.95	8.91	7.77
BOT	7.4	7.4	7.4	5.3
NE	4	4	4	4
RPM	2000	2000	2000	-
PD	13142	14543	16028	-
PE	8961	10085	11288	-
PI	15114	16724	18433	26000
R	500	500	500	-
NCREW	50	50	50	-
NDECK	4	4	4	-
WH	414	414	414	-
WO	164	164	164	-
WM	102	111	122	-
WPAX	68	68	68	-
WCAR	150	150	150	-
WFUEL	45	48	51	-
WFWPROV	11	11	10	-
WCREW	6.8	6.8	6.8	-
BC (milUS\$)	24.6	26	27	-
ABC (milUS\$)	32.3	34.8	37.2	-
LS	679	689	699	-
DW	298	300	303	310
DISP1	973	989	1002	-
DISP2	976	986	1004	-

Table 6.3: Example C.

	Case I	Case II	Case III	Ship Data
Vessel Type	VC	VC	VC	VC
Engine Type	Diesel	Diesel	Diesel	Diesel
Propulsor	Water Jet	Water Jet	Water Jet	-
A_S/N_{PAX}	1.10	1.10	1.10	1.17
A_P/A_S	1.40	1.40	1.40	1.36
NPAX	650	650	650	620
NCAR	150	150	150	152
VS	36	38	40	36
LOA	82.7	82.7	82.5	76.6
LWL	72.5	72.5	72.4	68.0
B	21.3	21.3	21.3	22.2
BH	6.8	6.8	6.8	6.3
T	2.8	2.8	2.8	3.0
D	13.4	13.4	13.4	-
S	14.5	14.5	14.5	15.9
CB	0.45	0.46	0.46	-
AS	715	715	715	726
AP	1001	1001	1001	987
LOD	8.50	8.47	8.43	8.50
BHOT	2.40	2.40	2.40	2.10
SOL	0.20	0.20	0.20	0.23
NE	4	4	4	4
RPM	1250	1250	1250	-
PD	23724	25454	27319	-
PE	16176	17651	19239	-
PI	27283	29272	31417	22800
R	400	400	400	300
NCREW	50	50	50	-
NDECK	3	3	3	-
WH	580	580	580	-
WO	142	142	142	-
WM	232	248	264	-
WPAX	68	68	68	-
WCAR	150	150	150	-
WFUEL	65	67	69	77
WFWPROV	9	8.6	8.1	4
WCREW	6.8	6.8	6.8	-
BC (milUS\$)	32.6	33.6	34.7	-
ABC (milUS\$)	33.4	34.3	35.2	-
LS	955	970	986	-
DW	317	318	321	360
DISP1	1273	1302	1302	-
DISP2	1272	1288	1307	-

Table 6.4: Example D.

	Case I	Case II	Case III	Ship Data
	VC	VC	VC	VC
Vessel Type	Gas Turbine	Gas Turbine	Gas Turbine	Gas Turbine
Engine Type	Water Jet	Water Jet	Water Jet	-
Propulsor	1.10	1.10	1.10	-
A_S/N_{PAX}	1.40	1.40	1.40	-
A_P/A_S	1500	1500	1500	1500
NPAX	440	440	440	440
NCAR	35	37	39	37
VS	119.4	119.4	119.4	120.0
LOA	104.7	104.7	104.7	105.5
LWL	31.2	31.2	31.2	36.0
B	8.2	8.2	8.2	-
BH	4.1	4.1	4.1	2.6
T	17.7	17.7	17.7	-
D	23.0	23.0	23.0	-
S	0.44	0.45	0.45	-
CB	1650	1650	1650	-
AS	2310	2310	2310	-
AP	9.05	9.0	9.0	-
LOD	2.0	2.0	2	-
BHOT	0.22	0.22	0.22	-
SOL	4	4	4	4
NE	47645	51927	56283	-
PD	32193	35712	39338	-
PE	54792	59716	64726	60000
PI	700	700	700	700
R	150	150	150	-
NCREW	8	8	8	-
NDECK	1148	1148	1148	-
WH	805	805	805	-
WO	288	312	337	-
WM	157.5	157.5	157.5	-
WPAX	440	440	440	-
WCAR	232	243	254	-
WFUEL	37.5	35.5	33.7	-
WFWPROV	20.3	20.3	20.3	-
WCREW	71.1	71.7	72.4	-
BC (milUS\$)	89.7	90.7	91.5	-
ABC (milUS\$)	2241	2266	2291	-
LS	940	950	960	1433
DW	3181	3230	3230	3500
DISP1	3181	3216	3250	3500
DISP2				

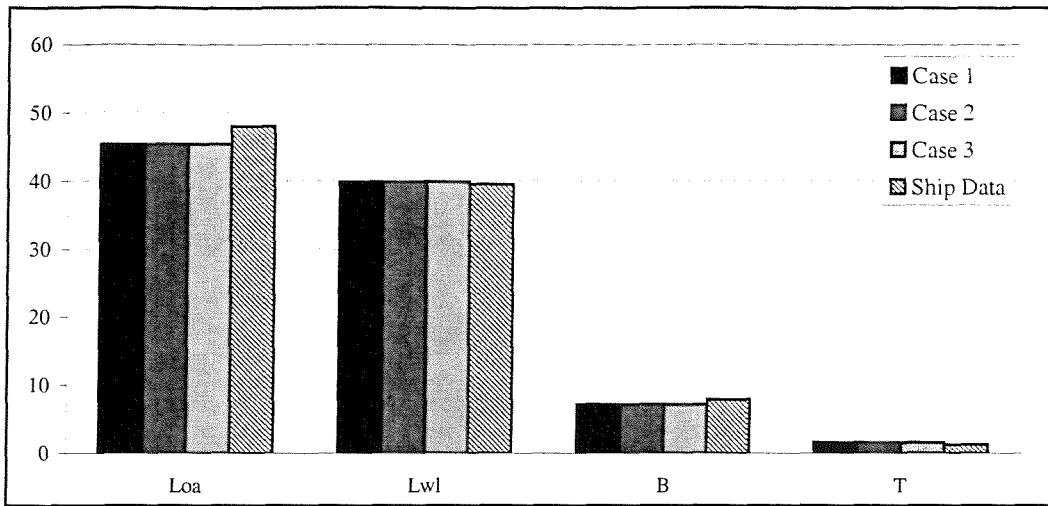
Table 6.5: Example E.

	Generated Ship	Method 1	Method 2	Method 3
Vessel Type	PM	PM	PM	PM
Engine Type	Diesel	Diesel	Diesel	Diesel
Propulsor	Water Jet	Water Jet	Water Jet	-
A_S/N_{PAX}	0.60	0.60	0.60	0.60
A_P/A_S	1.15	1.15	1.15	1.15
NPAX	500	500	500	500
VS	36	40	40	40
LOA	46.4	46.4	46.4	46.4
LWL	40.7	40.7	40.7	40.7
B	9.0	9.0	9.0	9.0
T	1.8	1.5	1.8	2.0
D	9.4	9.4	9.4	9.4
CB	0.37	0.45	0.39	0.37
AS	300	300	300	300
AP	345	345	345	345
LOD	6.5	6.5	6.39	6.30
BOT	5	6.08	5	4.55
NE	2	2	2	2
RPM	1800	1800	1800	1800
PD	5905	7464	7264	7926
PE	4026	5257	5115	5582
PI	6791	8584	8353	9115
R	500	500	500	500
NCREW	20	20	20	20
NDECK	2	2	2	2
WH	98	98	98	98
WO	23	23	23	23
WM	49	61	59	64
WPAX	53	53	53	53
WFUEL	15	17	17	18
WFWPROV	8.7	7.8	7.8	7.8
WCREW	2.7	2.7	2.7	2.7
BC (milUS\$)	7.0	8.0	7.8	8.3
ABC (milUS\$)	-	-	-	-
LS	170	181	180	185
DW	83	85	85	86
DISP1	252	252	265	276
DISP2	253	266	265	271

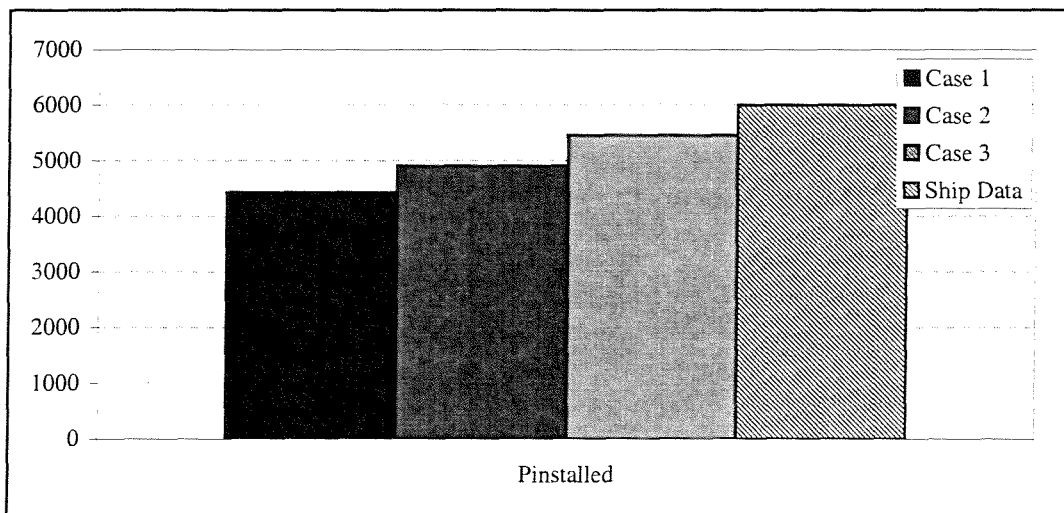
Table 6.6: Example F.

	PM	PM	VM	VM
A_S/N_{PAX}	0.55	0.75	0.85	1.25
A_P/A_S	1.10	1.30	1.15	1.45
NPAX	400	400	650	650
NCAR	-	-	150	150
VS	35	35	38	38
LOA	42.8	55.5	98.7	104.1
LWL	37.5	48.7	86.6	91.3
B	6.8	8.8	15.1	15.9
T	1.5	2.0	2.3	2.4
D	8.1	9.3	13.0	13.5
CB	0.44	0.31	0.35	0.33
AS	220	300	553	813
AP	242	390	635	1178
LOD	6.77	7.64	8.50	8.69
BOT	4.50	4.50	6.50	6.50
NE	2	2	4	4
RPM	1800	1800	1250	1250
PD	3706	6906	16665	18903
PE	2504	4666	11556	13108
PI	4262	7942	19165	21738
R	300	300	1000	1000
NCREW	20	20	100	100
NDECK	2	2	4	4
WH	68	119	404	455
WO	16	26	161	179
WM	33	57	170	190
WPAX	42	42	68	68
WCAR	-	-	150	150
WFUEL	5.7	10.6	80.2	91.0
WFWPROV	4.3	4.3	21.4	21.4
WCREW	2.7	2.7	13.5	13.5
BC (milUS\$)	4.7	8.2	28.1	31.6
ABC (milUS\$)	-	-	34.8	34.8
LS	116	202	734	823
DW	58	63	353	365
DISP1	174	265	1084	1188
DISP2	174	265	1087	1188

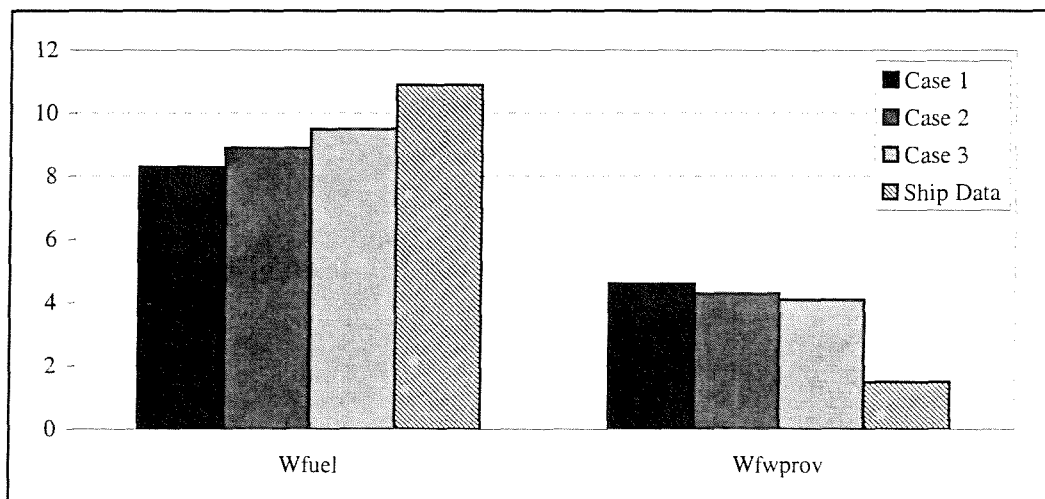
Table 6.7: Example G.



Dimensions (L_{OA} , L_{WL} , B, T)

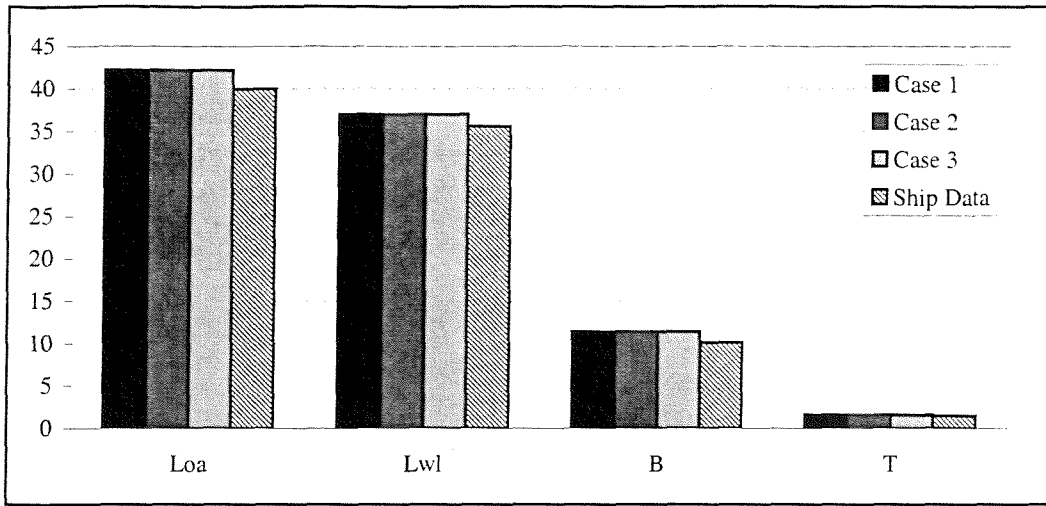


Installed Power (P_1)

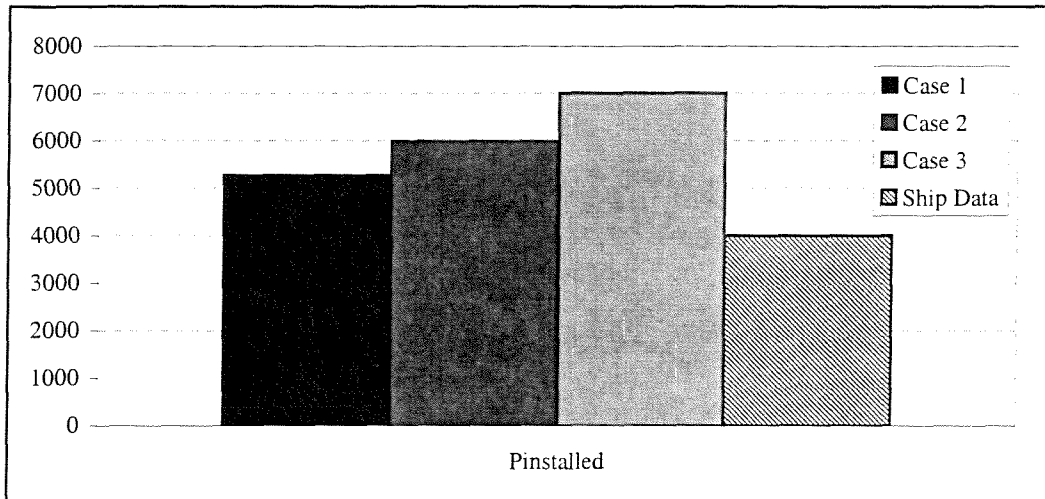


Masses (W_{FUEL} , W_{FWPROV})

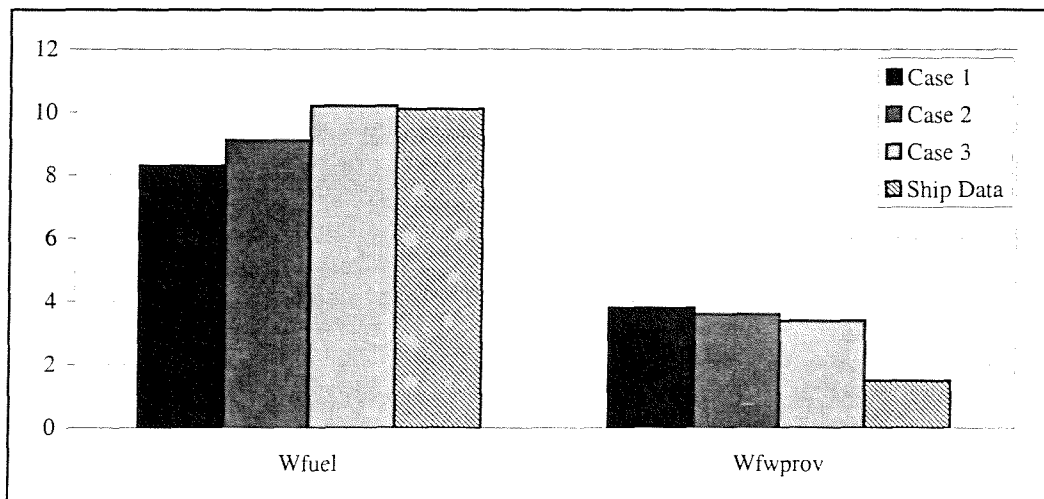
Figures 6.1: Comparison of Design Study A against Ship Data



Dimensions (L_{OA} , L_{WL} , B, T)

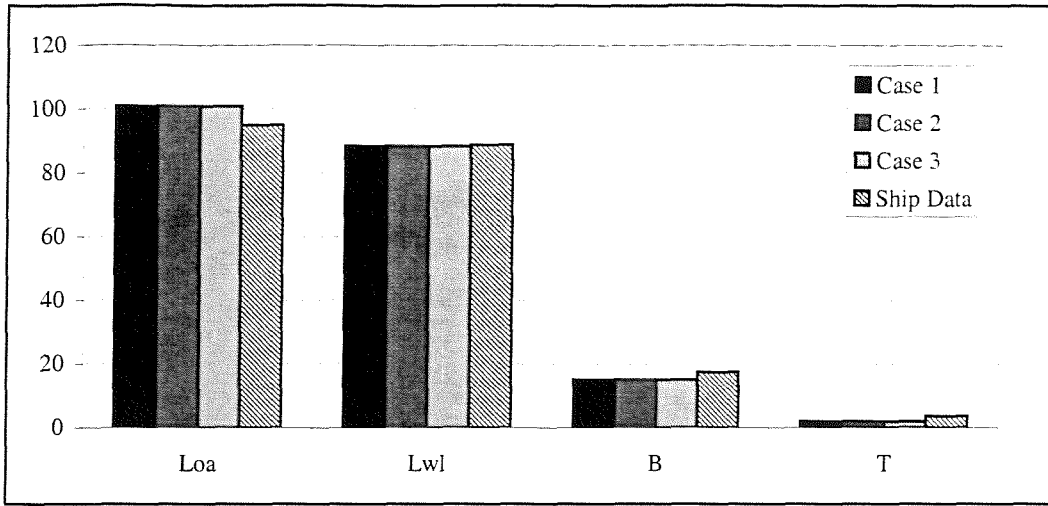


Installed Power (P_1)

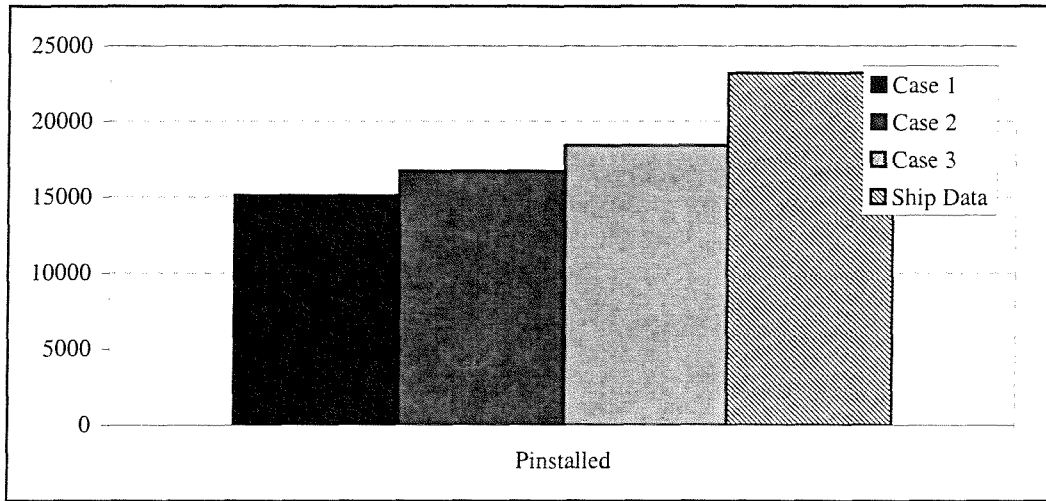


Masses (W_{FUEL} , W_{FWPROV})

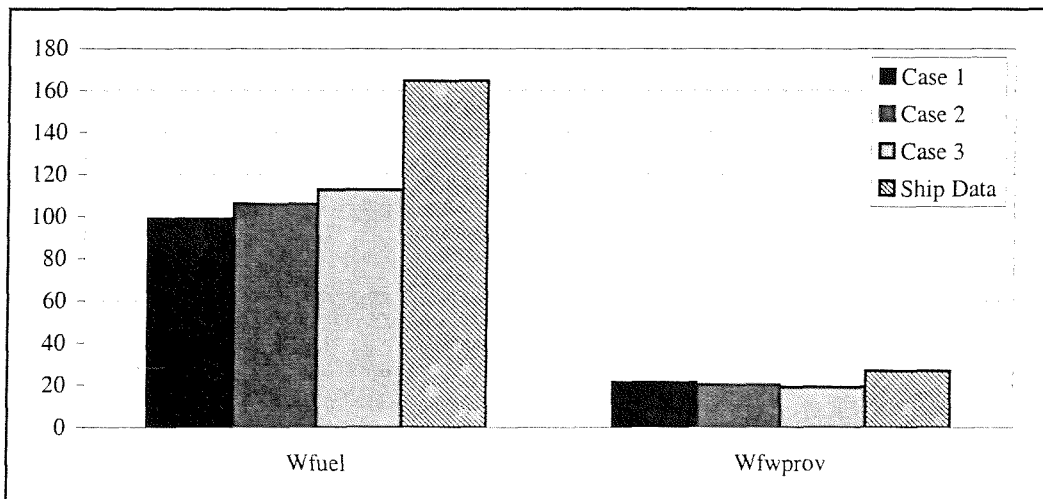
Figures 6.2: Comparison of Design Study B against Ship Data.



Dimensions (L_{OA} , L_{WL} , B, T)

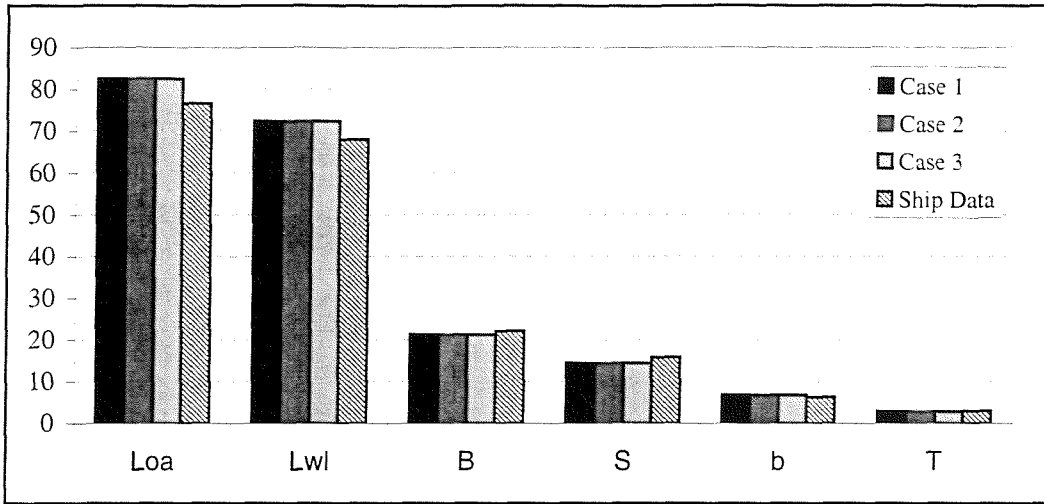


Installed Power (P_i)

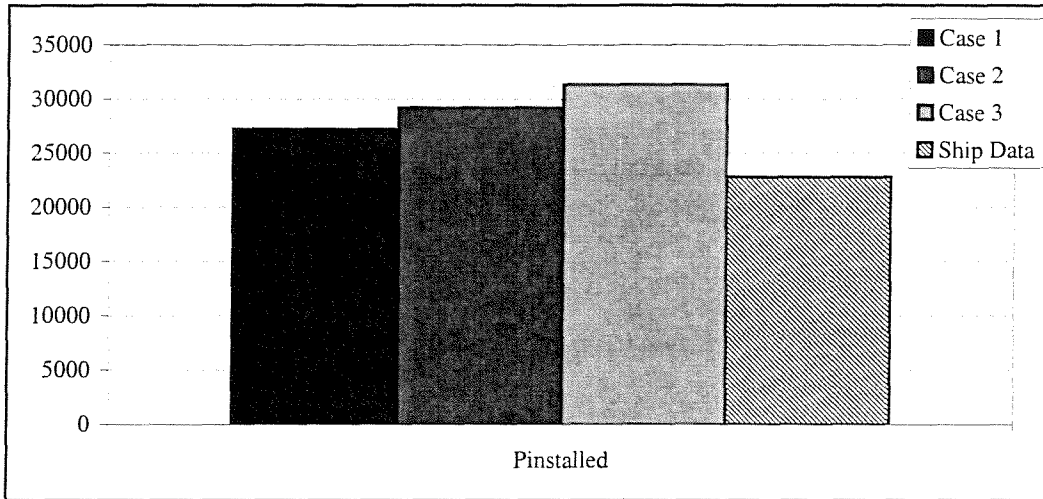


Masses (W_{FUEL} , W_{FWPROV})

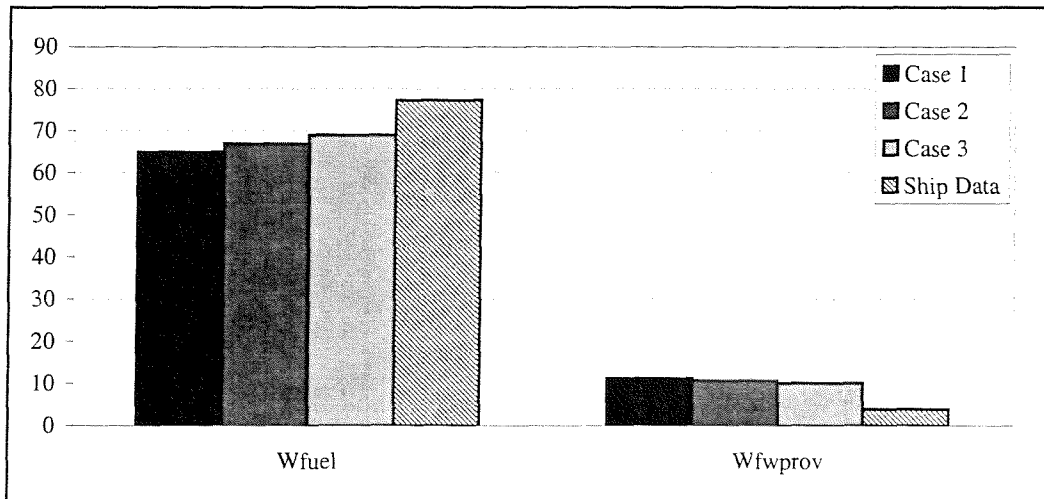
Figures 6.3: Comparison of Design Study C against Ship Data.



Dimensions (L_{OA} , L_{WL} , B, S, b, T)

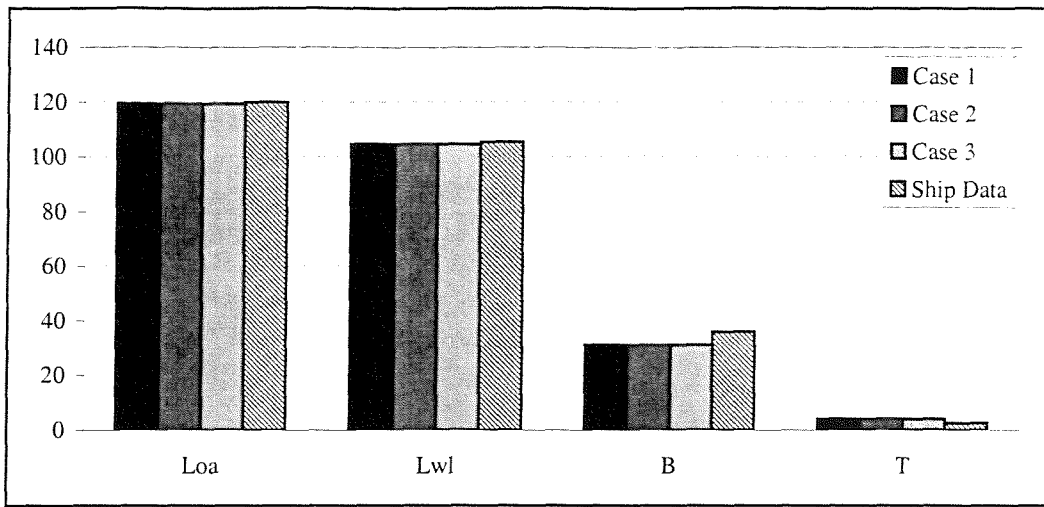
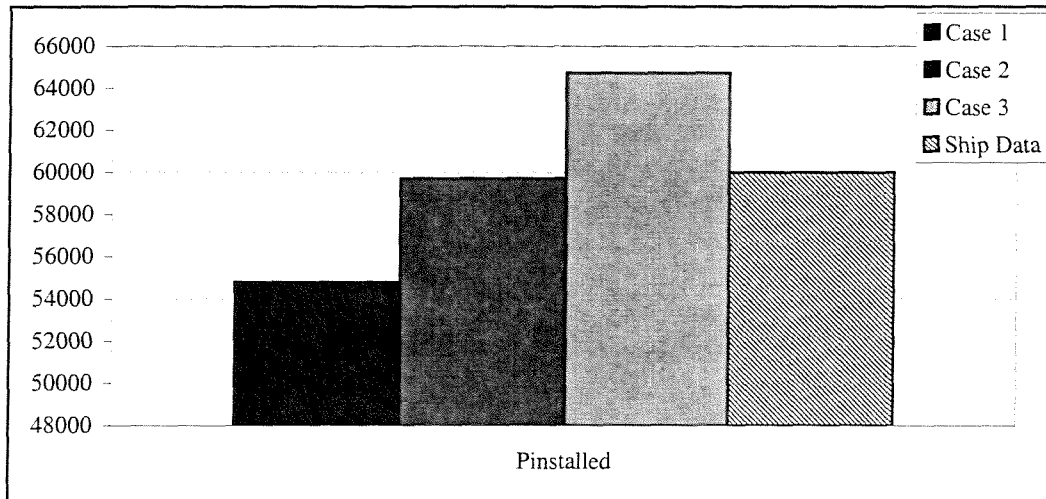
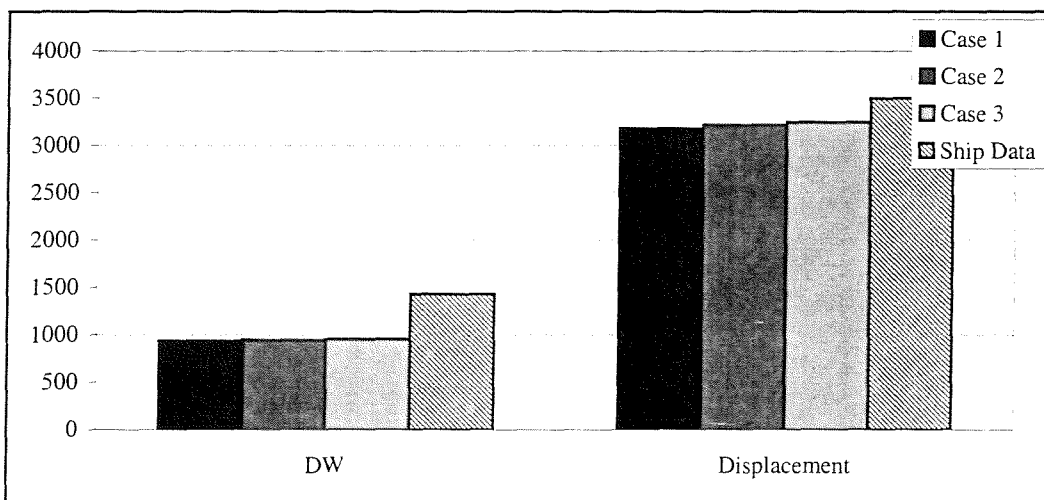


Installed Power (P_1)



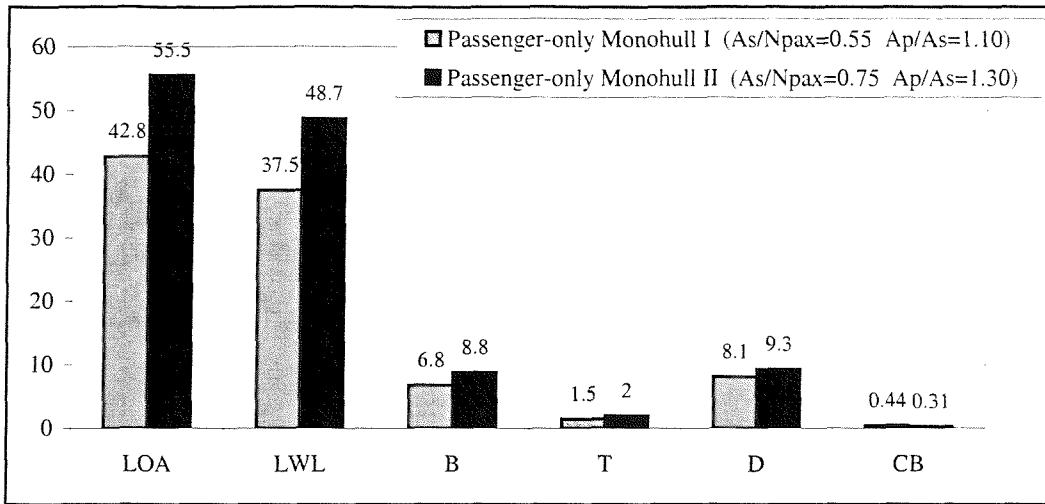
Masses (W_{FUEL} , W_{FWPROV})

Figures 6.4: Comparison of Design Study D against Ship Data.

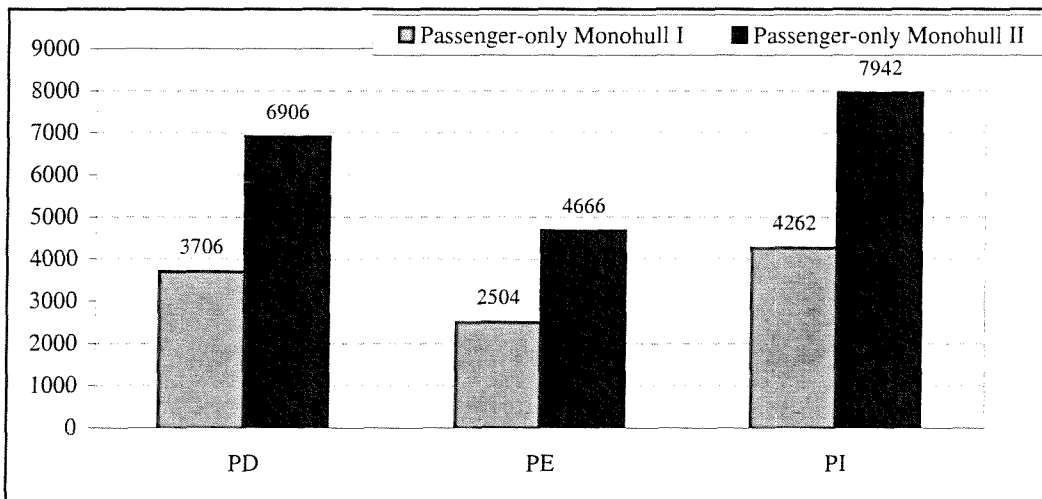
Dimensions (L_{OA} , L_{WL} , B, T)Installed Power (P_I)

Masses (DW, Displacement)

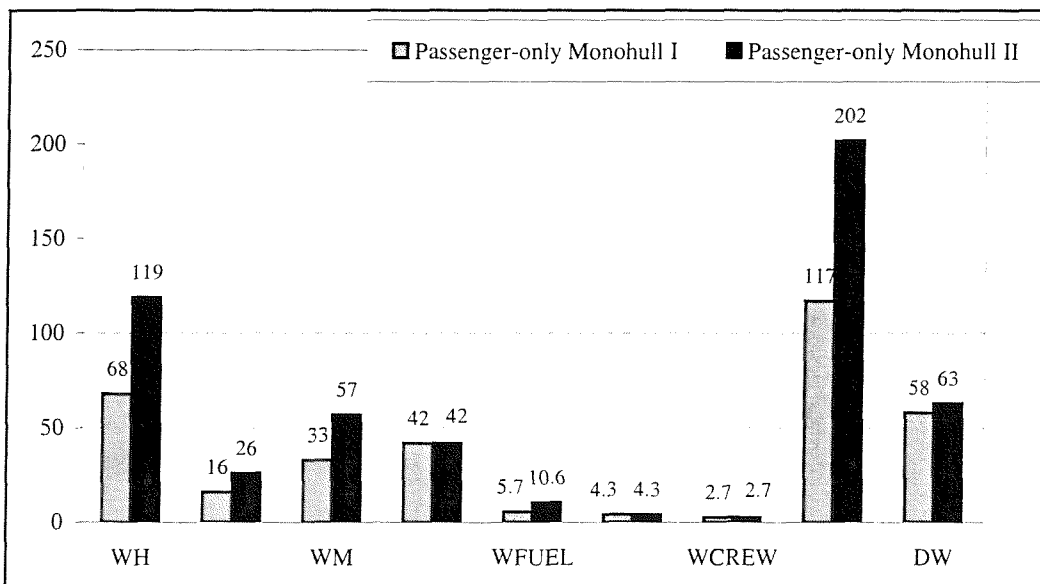
Figures 6.5: Comparison of Design Study E against Ship Data.



$N_{PAX} = 400, V_S = 35$ knots

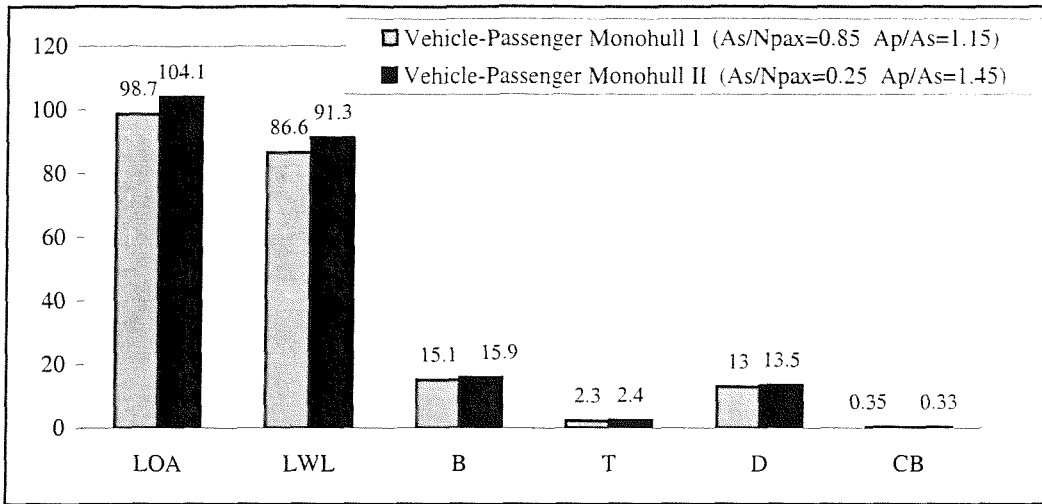


$N_E = 2, RPM = 1800$

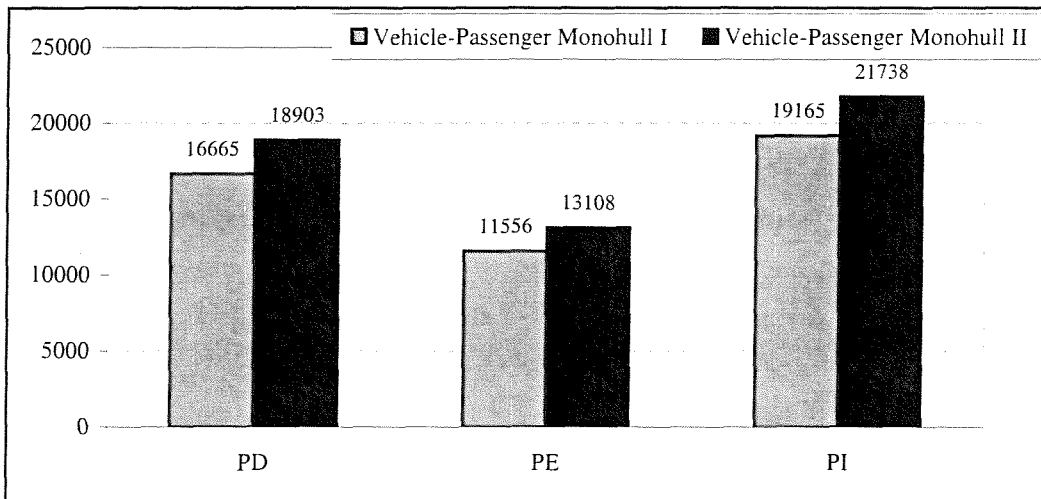


Masses

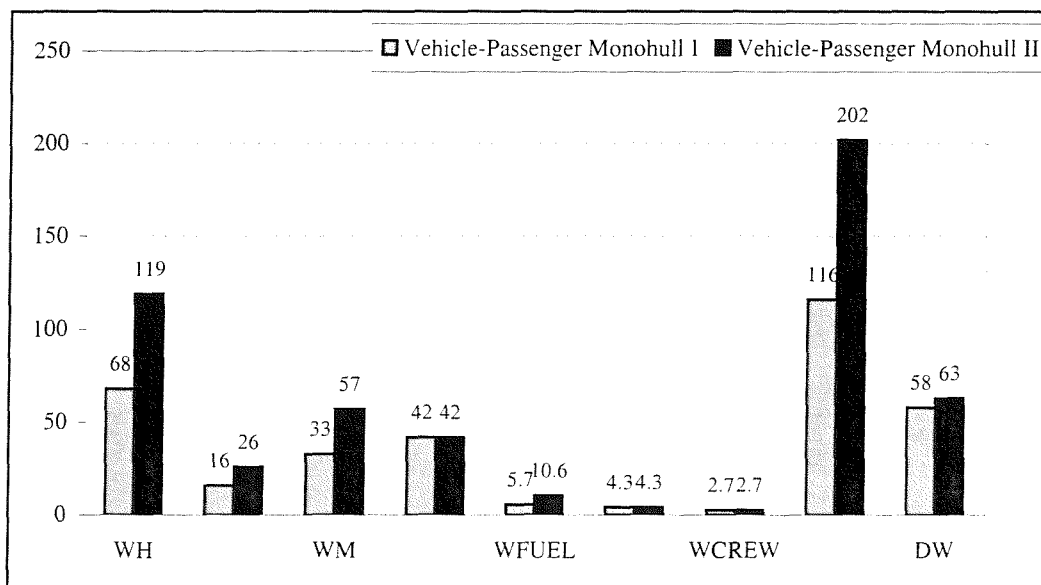
Figures 6.6.a: Effect of Comfort Levels, Design Study G.



$N_{PAX} = 650, N_{CAR} = 150, V_S = 35$ knots



$N_E = 4, RPM = 1250$



Masses

Figures 6.6.b: Effect of Comfort Levels, Design Study G.

7 CONCLUSIONS

7.1 INTRODUCTION

This final section reassesses the thesis main results and conclusions. Firstly, the significance of the present work is examined. Secondly, the concept of a further work process is then detailed in section 7.3. Finally, the main contributions and achievements are briefly outlined.

7.2 GENERAL DISCUSSION

- A technical design methodology has been developed and described which can be satisfactorily applied to the generation of principal particulars of fast ferries at the concept design stage. The methodology has been included in a computer based design program. Data and equations are presented in the thesis which facilitate the estimation of dimensions, powering, masses and building costs at the preliminary design stage. The procedure is suitable for high speed monohulls and catamarans which currently make up the majority of fast ferries. The scope of the current model would be enhanced with the inclusion of other multihulls, such as SES, SWATH and hybrid vessels, which offer the potential for further research.
- Background work associated with collecting and establishing the data and equations presented in the thesis indicates that it can be difficult to obtain, process and/or establish design data of adequate quality, particularly in the cases of masses and building costs. For this reason, caution should be exercised when using the data and equations, which should be only applied within the data range and for the correct vessel type.
- Complete calculations of a set of reliable, realistic and feasible main dimensions can be performed for high speed monohull and catamaran ferries. The methodology offers flexibility in the hull ratios and passenger comfort (such as seating and overall area per passenger).
- Approximate powering calculations offer reasonably reliable results for monohull and catamaran round bilge hulls. It would be desirable to enhance the scope of the powering module by including other hull types and more detailed calculations. At present, an approximation to water jet efficiency is used. Future work should focus on including the efficiencies of propellers and other propulsors.

- It is considered that the presented mass estimations offer reliable results. However, there is a general lack of reliable data for high speed vessels, which can restrict the quality of the estimations.
- Detailed calculations of building costs indicate that relatively reliable estimates of total cost can be obtained. The approximate estimates of building costs were not so reliable, particularly for small vessels. The overall costing procedures would benefit from improvements in the estimates of outfitting cost.
- Examples of the methodology have been used to demonstrate the scope of the technical design procedures. The resulting designs are found to be feasible and realistic, and suitable for further use in concept exploration and decision making methodologies.
- It is considered that, based on the data currently available, the methodology and design equations presented provide adequately reliable first estimates at the preliminary design stage. They should prove particularly useful for parametric concept exploration studies. It is also considered that the methodology developed and presented offers a good basis on which to build and develop further estimating techniques.

7.3 FURTHER WORK

The need for further work is important in order to improve some areas of the current methodologies and hence improve the overall accuracy of estimation of the design. These can be noted as follows;

- Enlargement of the database for the existing type of the vessels and calculations.
- Include different hull forms in the database.
- Include different types of propulsors along with engine configurations.
- Investigate the mass balance methods.
- Stability check on the overall design process.

7.4 SUMMARY

The work in this thesis can be summarised as follows;

- A robust method for estimation of initial set of main dimensions of fast ferries.

- A rigorous approach to calculate the installed power of fast ferries.
- A set of equations to estimate preliminary masses and costs of fast ferries.
- A computer program to create new designs efficiently.
- A comparison between results and existing ship data.
- Overall, creating a set of initial dimensions, power, masses and costs of four types of fast ferries with only few input variables.

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APPENDIX I

A1. DATABASE

A1.1. BACKGROUND

Appendix I contains information about the assembled database. An initial simpler database was first designed during earlier research, Karayannis [17]. This has been updated, expanded and modified during the current research programme until April 2000.

A1.2. GENERAL DESCRIPTION

The database includes over three hundred different vessels which have been recorded on four main spreadsheets representing the four major vessel categories, namely passenger-only monohulls (PM), passenger-only catamarans (PC), vehicle-passenger monohulls (VM) and vehicle-passenger catamarans (VC). The two catamaran databases also include all the different hull forms (SWATHs, SESs, wavepiercers and foil-assisted catamarans). For these hull types, relevant data are too few to analyse, and for this reason full analysis has been performed only for monohulls and conventional catamarans as it is mentioned earlier on this thesis.

In the spreadsheets, each row represents one vessel and each column represents different relevant information. Each column is often named as an abbreviation in order to accommodate as much information as possible. These abbreviations are described in Table A1.

The database has been focused on technical aspects such as main dimensions, seating and cargo areas, capacities, machinery installations, masses, some operational aspects and costs. Some of these values have been estimated from the general arrangement drawings, these are also described in Table A1.

The database has been developed in order to assist the generation of feasible and realistic technical designs for previous, current and future research studies. It is believed that it is an excellent tool great use for its purposes and can be easily updated and developed.

The relevant spreadsheets are presented as hardcopies at the end of this appendix. It should be mentioned that apparent lack of formatting is due to the fact that they were not designed to be used as printed spreadsheets. Therefore, they are also affixed at the end of the thesis in electronic format so as to be observed easily.

COLUMN	DESCRIPTION
Ship Code	<p>Each vessel has been given a code to be recognised. There are mainly four different types of codes for four types of vessels, namely passenger-only monohull (PM), passenger-only catamaran (PC), vehicle-passenger monohull (VM) and vehicle-passenger catamaran (VC). Also, there are other vessel types for future studies, these are; passenger-only foil (PF), passenger-only SES (PS), passenger-only wavepiercer (PW), passenger-only SWATH (PSW), vehicle-passenger SES (VS) and vehicle-passenger wavepiercer (VW). Each vessel has a number immediately after the vessel type code.</p> <p>In some cases, different variants of the same design have been found often with slightly different characteristics from one operator to another. These are logged separately with the same number and with a lower case letter, such as PM1a and PM1b.</p>
Des./Cons./ Yard	Designer, constructor or shipyard of the vessel whichever have been found.
L _{OA}	Overall length (m).
L _{BP}	Length between perpendiculars (m).
L _{WL}	Length on waterline (m).
B	Moulded and/or overall breadth (m). 'Mld' stands for moulded and 'oa' for overall.
D	Moulded and/or overall depth (m). 'Mld' stands for moulded and 'oa' for overall.
T	Draught (m).
b	Breadth of demihulls (m). This is given only for multihulls.
S	Separation of centrelines demihulls (m). This is given only for multihulls.
DWT	Deadweight (tonne).
DW Distribution	<p>Detailed deadweights can be found in this column. These are represented as abbreviations and given as follows;</p> <p>Passenger (pax), fuel (f), fresh water (fw), luggage (lug), crew (cr), lubricating oil (lo), provisions (pro), bicycles (bike), store (str).</p>
LS	Lightship (tonne).
Δ	Displacement (tonne).
GRT	Gross tonnage (tonne).
NT	Net tonnage (tonne).
Fuel	Fuel capacity on board (lt).
Fresh Water	Fresh water capacity on board (lt).
Other	Any other capacities (lt) and weights (t) have been found. Cargo and store are

Capacities, Weights	taken as weights and always united as tonne. The rest of the capacities units are all given as litre. These are represented as abbreviations and given as follows; Diesel oil (do), fuel oil (fo), lubricating oil (lo), hydraulic oil (ho), sewage (sew), sewage treatment (sew trt), bilge (bil), oily bilge (obil), sullage (sul), cargo (crg), store (str), black water (bw), grey water (gw), dirty oil (doil), reserve osmosis (rosm), container (con), bicycle (bike).
Pax	Number of passengers.
Pax Distribution	It gives information on the passenger distribution. Abbreviations used in this column are as follows; Upper deck (ud), main deck (md), upper deck bow (udb), upper deck lounge (udl), upper deck saloon (uds), main deck saloon (mds), upper saloon (us), main saloon (ms), aft saloon (as), bow saloon (bs), forward saloon (fs), forward lounge (fl), upper external (ue), very important person (VIP), upper saloon (us), lower saloon (ls), main bow saloon (mbs), main aft saloon (mas), bow saloon (bs), upper deck external (ude), forward deck external (fde), internal (in), top deck (top) external (ex).
Crew	Number of crew.
Cars	Number of cars.
V_s	Service speed (knots).
V_M	Maximum speed (knots).
SFC	Specific fuel consumption (units are given for each data individually).
RPM	Revolutions per minute for main engine (rpm).
Range	Range of the vessel (nautical miles).
Propulsion Plant	Column supplies information about the main propulsion plant. These are as follows; Main engine type, number of engines and installed power (kW). Main engine type is presented as abbreviations, namely diesel engine (D) and gas turbine (G).
Auxiliary Power	It provides data on auxiliary plant of the vessel. They can be summarised as follows; Number of engines, installed power (kW else it is noted next to the value) and revolutions per minute (rpm).
Propulsor	This column includes propulsor type and number. For example; 2wj stands for two water jets and 2prop two propellers.
GA	It indicates the availability of the vessel's general arrangement. '*' means that general arrangement is obtainable from the given reference.
Page	This is the page number of the relevant reference which has the data been taken from.

Source	It is the source of the data. There are several magazines and publications which most of the data have been gathered from. These are Fast Ferry International (FF), Ship and Boat (SB), Naval Architect (NA), and International conference on fast sea transportation (FAST'Year). Roman numbers present the month of the year. Example; FF/III'96 represents Fast Ferry International magazine's March 1996 edition.
BC million	Available building cost values. The units are noted next to the value.
ESTIMATED VALUES	
$F_{n_{M/WL}}$	Froude Number (based on waterline length and service speed).
L_{OA}/B	Overall length and breadth ratio.
L_{WL}/B	Waterline length and breadth ratio.
A_S (m ²)	Seating area.
A_S/p (m ²)	Seating area and number of passengers ratio.
A_P (m ²)	Passenger area.
A_P/p (m ²)	Passenger area and number of passengers ratio.
A_P/A_S	Passenger area and Seating area ratio.
B/T	Breadth and Draught ratio.
$L_{WL} * B$	Waterline length and breadth product.
∇	Underwater volume of the vessel.
$L_{WL}/\nabla^{1/3}$	Waterline length and underwater volume ratio.

Table A1.1: Database description.

A1.3. CONTRIBUTIONS

The major contributions of this thesis to the database can be summarised as follows;

- There has been an increase of 39% in the number of vessels and extra information columns have been included. These are as follows; Demihull breadth for multihulls, Deadweight distribution, Net tonnage, Lightship, Crew number, Specific fuel consumption, RPM of main engine, Auxiliary power details (number of engines, power, and rpm), Propulsor details (number and type), Building cost, Page of the source.
- All the vessel data after September 1998 have been included to the database during the current research programme.



- Database format has been altered to make it easy to understand, and use. All the abbreviations are made to a uniform standard, which makes it easier to use. Where it is necessary columns have been expanded. The font has been uniformed.
- A detailed table has been created to give all the details of the database and meanings of the abbreviations.
- Passenger distribution, Other capacities data columns have been edited in more detail.
- Some calculations have been undertaken to find out separation between demihulls, Froude number, Displacement volume, L/B, S/L, B/T, L×B, b/T, L/b products.

Approximate vessel data have been entered to the database during the current work can be summarised as following table.

Vessel Type	Contributions		Total	Percentage of the Current Contributions
	Current Research	Previous Research		
PM	33	108	141	33 %
VM	15	28	43	54 %
PC	10	60	70	17 %
VC	63	120	183	53 %
Total	121	316	437	39 %

Table A1.2: Contributions to the database from the current study.

Ship Code	Des/Cons./Yard	L _{oa} (m)	L _{pp} (m)	L _{wl} (m)	B (m)	D (m)	T (m)	DWT (t)	LS (t)	Δ (t)	GRT	Fuel (t)	Fresh Water (t)	Other Capacities (t) / Weights (t)	Pax	Pax Distribution	Crew	V _s (kn)	V _M (kn)	
PM1	Westport	28.90		24.55	6.90			1.65				11350	1 x 1130		149				28.0	
PM2	WaveMaster	33.00		28.40	6.50	1.80		1.80				10000	1000		200				32.5	
PM3	Pelmatic	31.00	26.50	26.50	6.50	mld		1.20				3000	450		149				34.0	
PM4	Pelmatic	48.00	39.50	39.50	7.90	mld		1.30				13000	1500		450				36.0	
PM5	Oceanfast	31.90		27.70	6.50	1.90	mld	1.00				6000	1000		228				28.0	
PM6	Oceanfast	40.00		34.60	9.50	3.50	mld	1.10				10000	1500		340				30.0	
PM7	WaveMaster	35.40		31.60	7.00	mld	2.85	mld	2.10			5800	600		260				34.0	
PM8	WaveMaster	31.50		26.60	6.50	mld	2.50	mld	0.90	85		6000	1000	sul 600	196				28.0	
PM9	Aluminium Craft	35.00		30.12	7.40		2.90								250				27.0	
PM10	Aluminium Craft	37.00		31.84	8.00		3.70								350				30.0	
PM11	Aluminium Craft	32.00		28.50	7.40		2.75		1.25		229	2 x 2000	1 x 1000		275				26.0	
PM12a	Almaz/Agent/Sukhot	54.00			9.00	5.00						15000	1500		400				50.0	
PM12b	Almaz/Agent/Sukhot	54.00			9.00	5.00						22000	1500		400				55.0	
PM12c	Almaz/Agent/Sukhot	54.00			9.00	5.00						23000	1500		400				60.0	
PM13	Marinteknik	35.00		7.50				1.20							200	178 + 22 up			32.0	
PM14	Penguin	34.00		7.40		3.00		1.35							230	200 + 30 up			32.0	
PM15	FBM	70.00		65.00	13.50			2.00							650-800				33.0	
PM16	FBM	45.00		42.00	8.80			1.50							500				35.0	
PM17	FBM	35.00		32.65	7.00			1.1-1.8							170-210				33.0	
PM18	Semo	28.00	25.50	7.20	ea	2.53		1.22				4500	1000		194	92 + 42 as + 60 up			32.0	
PM19a	Rodriguez	50.46		43.00	9.20	ea	4.20	1.35	57			32000			511	106 + 290 mld + 115 up			29.0	
PM19b	Rodriguez	50.46		43.00	7.7,8,8	4.20		1.35	56	127.6	183.6	28000	15000		500	134ls + 158mbs + 106ams + 102us	6		28.5	
PM20	Lürssen-Werft	69.80	62.00	10.40	4.80			2.00							925	158 dn + 428 + 339 up			38.0	
PM21	Derecktor / NGA	32.50		8.50				1.20							160				35.0	
PM22a	Derecktor / NGA	36.40		8.50				1.60							150				30.0	
PM22b	Derecktor / NGA	36.40		8.50				1.60							150				40.0	
PM23	Cowstar	33.50		28.42	6.85	ea		1.32							150				28.0	
PM24	WaveMaster	30.30		25.20	6.50	mld	3.80	mld	0.95			5600	1000	sul 750	260	172 + (76+12) up			30.0	
PM25a	Westport	30.50		6.90				1.50							191	116 + (13+62) up			30.0	
PM25b	Westport	29.00		6.90				1.50							150	102 + 48 up			28.0	
PM26	Marinteknik	45.00		39.20	8.90	mld		1.30				11350	1125		149				30.0	
PM27	Allen Marine	19.50		3.90				0.45				30000	2000	to 1000	550	112bs + 212as + 111us + 115ud			32.0	
PM28	Tenix Fast Ferry Designs	45.00		39.70	8.50			1.60	45		27	1 x 1900	1 x 152		49				32	
PM29	Tenix Fast Ferry Designs	67.00		58.40	10.00			1.75				4000	1000		450				30.0	
PM30	SBF Shipbuilders	31.00		26.60	6.50	mld		1.50							900				30.0	
PM31	SBF Shipbuilders	31.00		27.00	3.70	mld		0.85				5000	1000		238	167 ms + 25 us + 16 md + 30 ud			30.0	
PM32	WaveMaster	37.40		31.30	8.00	ea	3.00	mld	2.45			8000	1000		190	146 ms + 42 us + 2 md			33.5	
PM33	WaveMaster	50.00		42.50	9.00	mld		2.00	30			10000	1000	sul 750	272	100 mbs + 72 mas + 82 us + 18 ud			24.0	
PM34	SBF Shipbuilders	35.00		31.70	7.00	mld		1.90				10000	1000	to 500 + sew 1000	324				30.0	
PM35	OC'EA Fast Ferry	24.55	23.50	20.00	6.50	mld	2.50	1.20	15.8		100	5000	1000		312	207 ms + 105 us			32	
PM36	OC'EA Fast Ferry	27.60	27.30	23.70	7.00	mld	2.65	1.40	18.8			to 250	1000		135	80 md + 55 ude	3,4		30.0	
PM37	OC'EA Fast Ferry	30.00		27.20	5.50	mld	2.50	2.10	11.8			to 250	1000		90	30 md + 60 ude	2		30	
PM38	Rodriguez Cantieri Naval	54.46		46.70	9.30	4.45		1.40				100	4400	1000	to 250	410	230 md + 180 ud			38

Ship Code	SFC	RPM	Range (ton)	Propulsion Plant (kW)	Auxiliary Power (kW)	Propulsor	GA	Page	Source	Fin _{swell}	L _{swell} / B	L _{swell} / B	A _c (m ²)	A ₀ /p (m ²)	A _c (m ²)	A ₀ /p (m ²)	A ₀ /A _c	B/T	L _{swell} * B	∇	L _{swell} /V ^{1/3}
PM1				D 2 x 1287			*		FF / I-II '95		3.980	3.558	95.000	0.638	117.000	0.785	1.232	4.182	169.395	111.801	5.096
PM2			450	D 2 x 1240			*		FF / III '95		3.851	4.369	114.000	0.570	131.000	0.655	1.149	3.611	184.600	132.912	5.565
PM3				2 x 1500			*		FF / IV '95		4.769	4.077						5.417	172.250	82.680	6.083
PM4				3 x 2000			*		FF / IV '95		6.076	5.000						6.077	312.050	162.266	7.242
PM5			150	D 3			*		FF / VII-VIII '95	0.936	4.908	4.262	130.000	0.570	141.000	0.618	1.085	6.500	180.050	72.020	6.658
PM6			300	D 2			*		FF / VII-VIII '95	1.005	4.211	3.642	254.000	0.747	314.000	0.924	1.236	8.636	328.700	144.628	6.592
PM7			420	D 2 x 970			*		FF / XII '95		5.057	4.514	184.000	0.708	205.000	0.788	1.114	3.333	221.200	185.808	5.538
PM8			360	D 3 x 660			*		FF / XII '95		4.846	4.092	106.000	0.541	136.000	0.694	1.283	7.222	172.900	62.244	6.712
PM9				D 3			*		FF / I-II '96		4.730	4.070							222.888	0.000	
PM10				D 2 x 1940			*		FF / I-II '96		4.625	3.980							254.720	0.000	
PM11			180	D 3 x 620			*		FF / I-II '96	0.800	4.324	3.851	159.000	0.578	172.000	0.625	1.082	5.920	210.900	105.450	6.032
PM12a			400	D 4 x 2000			*		FF / III-IV '96		6.000										
PM12b			400	D 2 x 5000			*		FF / III-IV '96		6.000										
PM12c			400	D 2 x 5600			*		FF / III-IV '96		6.000										
PM13				D 3 x 735			*		FF / XII '96		4.667							6.250			
PM14				D 4 x 610			*		FF / XII '96		4.595							5.481			
PM15							*		SB / V '96	0.713	5.185	4.815						6.750	877.500		
PM16				D 2			*		F	0.887	5.114	4.773						5.867	369.600		
PM17				D 2/3			*		F	0.949	5.003	4.664							238.550		
PM18				D 2 x 1470			*		FF / IV '97		3.889							5.902			
PM19a				D 2 x 2000			*		FF / VI '97	0.726	5.485	4.674						6.815	395.600	179.122	7.628
PM19b	232 g/kWh	1975	280	D 2 x 2000	2 x 100		*		FF / V '99	0.714										179.122	7.628
PM20			550	D 4 x 3805			*		FF / V '97		6.712							5.200			
PM21				D 2 x 1500			*		FF / V '97		3.824							7.083			
PM22a				D 2 x 610			*		FF / V '97		4.282							5.313			
PM22b				D 4 x 610			*		FF / V '97		4.282							5.313			
PM23				D 2 x 735			*		FF / IX '97		4.891	4.149						5.189	194.677		
PM24			250	D 3 x 660			*		FF / IX '97	0.981	4.662	3.877						6.842	163.800		
PM25a				D 2 x 1950			*		FF / V '98		4.420										
PM25b			1835	D 2 x 1460			*		FF / VII-VIII '99		4.203										
PM26							*		FF / XII '98		5.056	4.404						6.846	348.880		
PM27	225 t/h			D 2 x 412			*		FF / I-II '98		5.000							8.667			
PM28			1835	D 2 x 2300			*	6	FF / X '99		5.294	4.671						5.313	337.450		
PM29							*	6	FF / X '99		6.700	5.840						5.714	584.000		
PM30			2100	D 3 x 610		prop	*	21	FF / X '99		4.769	4.092						4.333	172.900		
PM31			2100	D 3 x 790		3 wj	*	21	FF / X '99		8.378	7.297						4.353	99.900		
PM32			2300	D 3 x 783		3 prop	*	14	FF / XI '99		4.675	3.913						3.265	250.400		
PM33	200 g/kWh		1850	D 2 x 2000			*	8	FF / XII '99		5.556	4.722						4.500	382.500		
PM34	598 t/h (75% mcr)		2100	D 3 x 790			*	36	FF / III '00	0.933	5.000	4.529						3.684	221.900		
PM35			2100	D 3 x 610	42 kVA at 1500 rpm	3 wj	*	22	FF / III '00		3.777	3.077						5.417	130.600		
PM36	470 t/h		2100	D 3 x 788	60 kVA at 1500 rpm	3 wj	*	22	FF / III '00		3.943	3.386						5.000	165.900		
PM37	455 t/h		1950	D 2 x 883		2 prop	*	22	FF / III '00	0.945	5.455	4.945						2.619	149.600		
PM38				D 3 x 2320		3 wj	*	23	FF / III '00		5.856	5.022						6.643	434.310		

APPENDIX II

A2. COMPUTER PROGRAM FOR CONCEPT DESIGN OF A FAST FERRY

A2.1. BACKGROUND

As part of the research a number of computer programs have been created to implement the preliminary design stages of fast ferries. Four main separate programs which estimated the main dimensions, main power, masses and costs of each vessel types (four types of vessel, namely passenger-only monohull, vehicle-passenger monohull, passenger-only catamaran and vehicle-passenger catamaran) have been developed. Each estimation method has been explained in detail in this thesis. The following table summarises all the inputs and outputs of each program.

PROGRAM	INPUTS	OUTPUTS
Dimension	$N_{PAX}, N_{CAR}, V_S, V_{TYPE}, C_B,$ $B/T, S/L, B_H/T, L/\nabla^{1/3}$	$L_{OA}, L_{WL}, B, b, T, D_{OA}, S, A_S, A_P, \Delta_1.$
Power	Outputs from "Dimension", $V_{TYPE}, E_{TYPE}, N_E, V_S, RPM$	$P_D, P_E, P_I.$
Mass	Outputs from "Dimension" and "Power", $N_{PAX}, N_{CAR},$ $V_{TYPE}, E_{TYPE}, V_S, N_E, R,$ $N_{CREW}, N_{DECK}.$	$W_H, W_O, W_M, W_{PAX}, W_{FUEL}, W_{FWPROV}, W_{CREW}, LS, DW, \Delta_2.$
Cost	Outputs from "Mass", $N_{PAX},$ $N_{CAR}, V_S.$	$C_H, C_O, C_M, BC, ABC.$

Table A2.1: Early Computer Programs Description.

A2.2. GENERAL DESCRIPTION

Research entailed modifying and combining all programs into one major program to create new designs efficiently and easily. This program inputs and outputs all the variables listed in the above table within one unique run. Table A2.2 displays all the inputs and outputs of this whole program. As shown in the relevant table, the user can select the number of passengers, cars, service speed, type of the vessel, type of the main engine and some variables at the beginning of each run.

PROGRAM	INPUTS	OUTPUTS
Pre-Fast	$N_{PAX}, N_{CAR}, V_S, V_{TYPE}, E_{TYPE},$ $N_E, RPM, N_{DECK}, N_{CREW}, R,$ $L/\nabla^{1/3}, B/T, B_H/T, S/L, C_B.$	$LOA, L_{WL}, B, b, T, D_{OA}, S, A_S, A_P, P_D, P_E, P_I, W_H, W_O, W_M,$ $W_{PAX}, W_{CAR}, W_{FUEL}, W_{FWPROV}, W_{CREW}, BC, ABC, LS,$ $DW, \Delta_1, \Delta_2.$

Table A2.2: Computer Program "Pre-Fast" Description.

The program is especially designed for very simple use where the process can be repeated as much as it is necessary. At the end of each run the program is designed to display all the inputs and outputs into a sheet, which can then be printed out.

It is important to mention how the mass balance study is included in the program. At the end of the each run the program assesses the final outcomes namely DISP1 and DISP2. This procedure has been detailed in chapter 2 under the name of mass balance. If there is no balance between these two variables, which means DISP1 and DISP2 have more than 1% of a difference, then the program asks the user to choose whether to carry on with a non balanced design or to create a mass balance. If the user chooses to create a mass balance the program follows the procedure detailed in chapter 2, and builds a mass balance between these two variables. If not, the run ends up with no mass balance.

Passenger comfort is another issue to point out. There are two variables which alter the passenger comfort, these are A_S/N_{PAX} and A_P/A_S . These variables can be changed with a quick alteration in the code. The ranges of these variables are mentioned in chapter 2, and by staying within these ranges they can be modified for different passenger comforts.

The computer program has been written in FORTRAN language. A full listing of the source code is included at the end of this appendix. The meanings of all the abbreviations can be found in the nomenclature of this thesis.

CODE "PRE-FAST"

```

PROGRAM ESTI OF DIME POWER MASS COST
CHARACTER *1 YESNO, YN
CHARACTER *2 VTYPE, ETYPE
COMMON/ONE/LOA, LWL, B, S, BH, T, D, CB, DISP1, WME, WP, WGB, WM, CME, CP, CGB,
$
CM, WO, CO, WH, CH, BC, WFUEL, WFWPROV, WCREW, WPAX, WCAR, DW, DISP2, VS, SOL,
$ LOD, WSA, FN, RN, CFM, CFS, FN1, FN2, FN3, CR1, CR2, CR3, CR4, CR5, CR6, CR7,
$ CR8, CR9, D1, A, B1, C, CR, CRS2, k, bk, CTS, RTS, PE, PD, PI, EFF, N, ABC,
$
AJ, AKT, AKQ, DIAM, RPM, NPAX, NCAR, NCREW, AS, AP, NDECK, NE, R, BHOT, BOT, LS
COMMON/TWO/VTYPE, ETYPE
REAL
NPAX, NCAR, NCREW, AS, AP, AV, LB, LWL, LOA, B, D, BH, T, S, DISP1, LOD, BOT,
$ CB, PB, RPM, R, VS, LOB, LOBH, LOBH1, SOL, BHOT, NE, NDECK, PI, PE, PD, FN, RN,
$ CO, WSA, CFM, CFS, FN1, FN2, FN3, CR1, CR2, CR3, CR4, CR5, CR6, CR7, CR8, CR9,
$
D1, A, B1, C, CR, CRS2, k, bk, CTS, RTS, EFF, n, AJ, AKT, AKQ, DIAM, DISP2, LS, ABC
500 WRITE (*, *) ' '
WRITE (*, *) ' *****'
WRITE (*, *) ' PRELIMINARY DERIVATION OF DIMENSIONS'
WRITE (*, *) ' ESTIMATIONS OF POWERING, MASSES AND COSTS'
WRITE (*, *) ' FOR ADVANCED FAST FERRIES'
WRITE (*, *) ' *****'

C-----
--
C-----INPUT REQUIREMENTS
WRITE (*, *) ' '
WRITE (*, *) ' INPUT NUMBER OF PASSENGERS. '
READ (*, *) NPAX
WRITE (*, *) ' '
WRITE (*, *) ' INPUT NUMBER OF CARS. '
READ (*, *) NCAR
WRITE (*, *) ' '
WRITE (*, *) ' INPUT SERVICE SPEED OF THE VESSEL (kn). '
READ (*, *) VS
WRITE (*, *) ' '
WRITE (*, *) ' INPUT VESSEL TYPE (PM/VM/PC/VC): '
WRITE (*, *) ' PM=PASSENGER-ONLY MONOHULL, '
WRITE (*, *) ' VM=VEHICLE-PASSENGER MONOHULL, '
WRITE (*, *) ' PC=PASSENGER-ONLY CATAMARAN, '
WRITE (*, *) ' VC=VEHICLE-PASSENGER CATAMARAN. '
READ (*, 520) VTYPE
WRITE (*, *) ' '
WRITE (*, *) ' INPUT MAIN ENGINE TYPE: '
WRITE (*, *) ' (D=DIESEL ENGINE T=GAS TURBINE). '
READ (*, 520) ETYPE
IF ((ETYPE.EQ.'D').OR.(ETYPE.EQ.'d')) THEN
WRITE (*, *) ' '
WRITE (*, *) ' INPUT NUMBER OF ENGINES AND THEIR SPEED (RPM). '
READ (*, *) NE, RPM
ELSE
WRITE (*, *) ' '
WRITE (*, *) ' INPUT NUMBER OF ENGINES. '
READ (*, *) NE
ENDIF
WRITE (*, *) ' '
WRITE (*, *) ' INPUT THE NUMBER OF DECKS. '
WRITE (*, *) ' Majority: passenger-only vessels 2, '

```

```

WRITE (*,*) '          vehicle-passenger vessels 3. '
READ (*,*) NDECK
WRITE (*,*) ' '
WRITE (*,*) ' INPUT NUMBER OF CREW. '
READ (*,*) NCREW
WRITE (*,*) ' '
WRITE (*,*) ' INPUT RANGE OF THE VESSEL (nmiles). '
READ (*,*) R
C-----
--
C-----DERIVATION OF DIMENSIONS FOR PASSENGER-ONLY MONOHULLS
IF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'pm')) THEN
WRITE (*,*) ' '
WRITE (*,*) ' INPUT LENGTH-DISPLACEMENT RATIO: '
WRITE (*,*) ' Majority: passenger-only monohulls      5.5-6.5, '
READ (*,*) LOD
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BREADTH-DRAUGHT RATIO: '
WRITE (*,*) ' Majority: passenger-only monohulls      4.0-6.5, '
READ (*,*) BOT
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BLOCK COEFFICIENT: '
WRITE (*,*) ' Majority: passenger-only monohulls      0.35-0.45.'
READ (*,*) CB
AS=0.6*NPAX
AP=1.15*AS
LB=146.0+(1.86E-3*(AP**2.0))
LOB=SQRT(((LOD**3.0)*CB)/BOT)
LWL=(LB*LOB)**0.5
LOA=1.14*LWL
B=LWL/LOB
T=B/BOT
D=4.0+(0.6*B)
DISP1=1.025*LWL*B*T*CB
WRITE (*,*) ' '
WRITE (*,*) ' DERIVATION OF DIMENSIONS          '
WRITE (*,*) ' ----- metres '
WRITE (*,*) ' '
WRITE (*,560) LOA
WRITE (*,561) LWL
WRITE (*,562) B
WRITE (*,563) T
WRITE (*,564) D
WRITE (*,565) CB
WRITE (*,566) DISP1
560 FORMAT (' OVERALL LENGTH:          ',F10.2)
561 FORMAT (' WATERLINE LENGTH:        ',F10.2)
562 FORMAT (' BREADTH:                      ',F10.2)
563 FORMAT (' DRAUGHT:                       ',F10.2)
564 FORMAT (' DEPTH:                          ',F10.2)
565 FORMAT (' BLOCK COEFFICIENT:             ',F10.2)
566 FORMAT (' DISPLACEMENT1:                 ',F10.2)
C-----
--
C-----DERIVATION OF DIMENSIONS FOR VEHICLE-PASSENGER MONOHULLS
ELSEIF ((VTYPE.EQ.'VM').OR.(VTYPE.EQ.'vm')) THEN
WRITE (*,*) ' '
WRITE (*,*) ' INPUT LENGTH-DISPLACEMENT RATIO: '
WRITE (*,*) ' Majority: vehicle-passenger monohulls      7.0-8.5.'
READ (*,*) LOD
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BREADTH-DRAUGHT RATIO: '
WRITE (*,*) ' Majority: vehicle-passenger monohulls      4.5-6.5. '

```

```

READ (*,*) BOT
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BLOCK COEFFICIENT: '
WRITE (*,*) ' Majority: vehicle-passenger monohulls 0.35-0.45.'
READ (*,*) CB
AS=0.95*NPAX
AP=1.2*AS
AV=156.0+(10.2*NCAR)
LB=121.0+(0.27*AP)+(0.60*AV)
LOB=SQRT(((LOD**3.0)*CB)/BOT)
LWL=SQRT(LB*LOB)
LOA=1.14*LWL
B=LWL/LOB
T=B/BOT
D=4.0+(0.6*B)
DISP1=1.025*LWL*B*T*CB
WRITE (*,*) ' '
WRITE (*,*) ' DERIVATION OF DIMENSIONS '
WRITE (*,*) ' ----- metres'
WRITE (*,*) ' '
WRITE (*,570) LOA
WRITE (*,571) LWL
WRITE (*,572) B
WRITE (*,573) T
WRITE (*,574) D
WRITE (*,575) CB
WRITE (*,576) DISP1
570 FORMAT (' OVERALL LENGTH: ',F10.2)
571 FORMAT (' WATERLINE LENGTH: ',F10.2)
572 FORMAT (' BREADTH: ',F10.2)
573 FORMAT (' DRAUGHT: ',F10.2)
574 FORMAT (' DEPTH: ',F10.2)
575 FORMAT (' BLOCK COEFFICIENT ',F10.2)
576 FORMAT (' DISPLACEMENT1: ',F10.2)
C-----
-
C-----DERIVATION OF DIMENSIONS PASSENGER-ONLY CATAMARAN
ELSEIF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
WRITE (*,*) ' '
WRITE (*,*) ' INPUT LENGTH-DISPLACEMENT RATIO: '
WRITE (*,*) ' Majority: passenger-only catamarans 8.5-9.5. '
READ (*,*) LOD
WRITE (*,*) ' '
WRITE (*,*) ' INPUT DEMIHULL BREADTH-DRAUGHT RATIO: '
WRITE (*,*) ' Majority: passenger-only catamarans 1.5-3.0. '
READ (*,*) BHOT
WRITE (*,*) ' '
WRITE (*,*) ' INPUT SEPARATION-LENGTH RATIO: '
WRITE (*,*) ' Majority: passenger-only catamarans 0.20-0.25. '
READ (*,*) SOL
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BLOCK COEFFICIENT: '
WRITE (*,*) ' Majority: passenger-only catamarans 0.40-0.55. '
READ (*,*) CB
C-----AS/NPAX=0.55-0.85
AS=0.7*NPAX
C-----AP/AS=1.10-1.30
AP=1.2*AS
LB=138.0+(0.910*AP)
LOBH=SQRT(((LOD**3.0)*CB)/BHOT)
LOBH1=1.0/LOBH
LOB=1.0/(SOL+LOBH1)
LWL=SQRT(LB*LOB)

```

```

LOA=1.14*LWL
B=LWL/LOB
S=LWL*SOL
BH=LWL*LOBH1
T=BH/BHOT
D=4.0+(0.44*B)
DISP1=2.0*1.025*LWL*BH*T*CB
WRITE (*,*) ' '
WRITE (*,*) ' DERIVATION OF DIMENSIONS'
WRITE (*,*) ' ----- metres '
WRITE (*,*) ' '
WRITE (*,580) LOA
WRITE (*,581) LWL
WRITE (*,582) B
WRITE (*,583) S
WRITE (*,584) BH
WRITE (*,585) T
WRITE (*,586) D
WRITE (*,587) CB
WRITE (*,588) DISP1
580 FORMAT (' OVERALL LENGTH;           ',F10.2)
581 FORMAT (' WATERLINE LENGTH:         ',F10.2)
582 FORMAT (' BREADTH:                   ',F10.2)
583 FORMAT (' SEPARATION BETWEEN DEMIHULLS: ',F10.2)
584 FORMAT (' DEMIHULL BREADTH:           ',F10.2)
585 FORMAT (' DRAUGHT:                     ',F10.2)
586 FORMAT (' DEPTH:                       ',F10.2)
587 FORMAT (' BLOCK COEFFICIENT:           ',F10.2)
588 FORMAT (' DISPLACEMENT1:              ',F10.2)
C-----
C-----DERIVATION OF DIMENSIONS FOR VEHICLE-PASSENGER CATAMARANS
ELSE
WRITE (*,*) ' '
WRITE (*,*) ' INPUT LENGTH-DISPLACEMENT RATIO: '
WRITE (*,*) ' Majority: vehicle-passenger catamarans 9.5-10.5. '
READ (*,*) LOD
WRITE (*,*) ' '
WRITE (*,*) ' INPUT DEMIHULL BREADTH-DRAUGHT RATIO: '
WRITE (*,*) ' Majority: vehicle-passenger catamarans 1.5-3.0. '
READ (*,*) BHOT
WRITE (*,*) ' '
WRITE (*,*) ' INPUT SEPARATION-LENGTH RATIO: '
WRITE (*,*) ' Majority: vehicle-passenger catamarans 0.20-0.25.'
READ (*,*) SOL
WRITE (*,*) ' '
WRITE (*,*) ' INPUT BLOCK COEFFICIENT: '
WRITE (*,*) ' Majority: vehicle-passenger catamarans 0.40-0.55.'
READ (*,*) CB
C-----AS/NPAX=0.80-1.40
AS=1.40*NPAX
C-----AP/AS=1.30-1.70
AP=1.70*AS
AV=12.4*NCAR
LB=471.0+(0.55*AP)+(0.28*AV)
LOBH=SQRT(((LOD**3.0)*CB)/BHOT)
LOBH1=1/LOBH
LOB=1/(SOL+LOBH1)
LWL=SQRT(LB*LOB)
LOA=1.14*LWL
B=LWL/LOB
S=LWL*SOL
BH=LWL/LOBH
T=BH/BHOT

```



```

D=4.0+(0.44*B)
DISP1=2.0*1.025*LWL*BH*T*CB
WRITE (*,*) ' '
WRITE (*,*) ' DERIVATION OF DIMENSIONS'
WRITE (*,*) ' ----- metres'
WRITE (*,*) ' '
WRITE (*,590) LOA
WRITE (*,591) LWL
WRITE (*,592) B
WRITE (*,593) S
WRITE (*,594) BH
WRITE (*,595) T
WRITE (*,596) D
WRITE (*,597) CB
WRITE (*,598) DISP1
590 FORMAT (' OVERALL LENGTH: ',F9.2)
591 FORMAT (' WATERLINE LENGTH: ',F9.2)
592 FORMAT (' BREADTH: ',F9.2)
593 FORMAT (' SEPARATION BETWEEN DEMIHULLS:',F9.2)
594 FORMAT (' DEMIHULL BREADTH: ',F9.2)
595 FORMAT (' DRAUGHT: ',F9.2)
596 FORMAT (' DEPTH: ',F9.2)
597 FORMAT (' BLOCK COEFFICIENT: ',F9.2)
598 FORMAT (' DISPLACEMENT1: ',F9.2)
ENDIF
C-----
--
C-----ESTIMATION OF MASSES
C-----Hull Mass
IF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
EC=(2*LOA*(BH+T))+(0.85*LOA*(D-T))+(1.6*LOA*(B-(2*BH)))
IF (EC.LE.3025) THEN
WH=0.00064*(EC**1.7)
ELSE
WH=0.39*(EC**0.9)
ENDIF
ELSEIF ((VTYPE.EQ.'VC').OR.(VTYPE.EQ.'vc')) THEN
EC=(2*LOA*(BH+T))+(0.85*LOA*(D-T))+(1.6*LOA*(B-(2*BH)))
IF (EC.LE.3025) THEN
WH=0.00064*(EC**1.7)
ELSE
WH=0.39*(EC**0.9)
ENDIF
ELSEIF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'pm')) THEN
EM=(LOA*(B+T))+(0.85*LOA*(D-T))
WH=0.032*(EM**1.2)
ELSE
EM=(LOA*(B+T))+(0.85*LOA*(D-T))
WH=0.032*(EM**1.2)
ENDIF
C-----Outfit Mass
WO=0.027*NDECK*LOA*B
C-----Machinery Mass and Powering Estimation
CALL POWER
C-----Diesel Engines
PB=PI/NE
IF ((ETYPE.EQ.'D').OR.(ETYPE.EQ.'d')) THEN
PSRATIO=PB/RPM
WME=NE*6.82*(PSRATIO**0.85)
WGB=NE*0.00348*(PB**0.75)
C-----Gas Turbines
ELSE
WME=NE*(3+(0.00056*PB))

```

```

      WGB=NE*0.00348*(PB**0.75)
      ENDIF
C-----Water Jets
      WP=NE*0.00018*(PB**1.18)
      WMM=WME+WP+WGB
C-----Remaining machinery mass is a function of WMM.
      FACTOR=1.55
      WM=WMM*FACTOR

C-----
--
C-----ESTIMATION OF COSTS
C-----Hull Costs
      IF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
      CH=((WH*5250*1.1)+(WH*900*30))*1E-6
      ELSEIF ((VTYPE.EQ.'VC').OR.(VTYPE.EQ.'vc')) THEN
      CH=((WH*5250*1.1)+(WH*900*30))*1E-6
      ELSEIF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'vm')) THEN
      CH=((WH*5250*1.1)+(WH*600*30))*1E-6
      ELSE
      CH=((WH*5250*1.1)+(WH*600*30))*1E-6
      ENDIF
C-----Outfit Costs
      CO=22000.0*WO*1E-6
C-----Machinery Costs (Main engine, Gearbox, Propulsor).
      IF ((ETYPE.EQ.'D').OR.(ETYPE.EQ.'d')) THEN
      CME=NE*(0.0003*PB-0.0423)
      ELSE
      CME=NE*((-4E-9*(PB**2))+(0.0004*PB))
      ENDIF
      CGB=NE*(2E-5*PB-(3E-10*(PB**2)))
      CP=NE*0.0031*(PB**0.6122)
      CM=(CP+CME+CGB)*1.40
C-----Total Building Costs (million US$)
      BC=(CM+CO+CH)
C-----Approximate Building Costs (million US$)
      IF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'pm')) THEN
      ABC=-37.6+(0.0115*NPAX)+(0.121*NCAR)+(1.23*VS)
      ELSEIF ((VTYPE.EQ.'VM').OR.(VTYPE.EQ.'vm')) THEN
      ABC=-37.6+(0.0115*NPAX)+(0.121*NCAR)+(1.23*VS)
      ELSEIF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
      ABC=-18.4+(0.0294*NPAX)+(0.111*NCAR)+(0.445*VS)
      ELSE
      ABC=-18.4+(0.0294*NPAX)+(0.111*NCAR)+(0.445*VS)
      ENDIF
C-----
--

      WRITE (*,*) ' '
      WRITE (*,*) ' POWER ESTIMATION                kW '
      WRITE (*,600) PD
      WRITE (*,601) PE
      WRITE (*,602) PI
      600 FORMAT (' DELIVERY POWER:                ',F20.2)
      601 FORMAT (' EFFECTIVE POWER:                ',F20.2)
      602 FORMAT (' INSTALLED POWER:                ',F20.2)

C-----
--

      WRITE (*,*) ' '
      WRITE (*,*) ' HULL MASS ESTIMATION                t '

```

```

WRITE (*,605) WH
605 FORMAT (' TOTAL HULL MASS:          ',F7.2)

```

```

C-----
--

```

```

WRITE (*,*) ' '
WRITE (*,*) ' OUTFIT MASS ESTIMATION      t '
WRITE (*,610) WO
610 FORMAT (' TOTAL OUTFIT MASS          ',F7.2)

```

```

C-----
--

```

```

WRITE (*,*) ' '
WRITE (*,*) ' MACHINERY MASS ESTIMATION      t '
WRITE (*,615) WME
WRITE (*,616) WP
WRITE (*,617) WGB
WRITE (*,618) WM
615 FORMAT (' MAIN ENGINES:              ',F20.2)
616 FORMAT (' PROPULSORS:                ',F20.2)
617 FORMAT (' GEARBOXES:                 ',F20.2)
618 FORMAT (' TOTAL MACHINERY MASS:        ',F20.2)

```

```

C-----
--

```

```

WRITE (*,*) ' '
WRITE (*,*) ' HULL COST ESTIMATION          KUS$ '
WRITE (*,625) CH
625 FORMAT (' TOTAL HULL COST:           ',F20.1)

```

```

C-----
--

```

```

WRITE (*,*) ' '
WRITE (*,*) ' OUTFIT COST ESTIMATION          KUS$ '
WRITE (*,626) CO
626 FORMAT (' TOTAL OUTFIT COST          ',F10.1)

```

```

C-----
--

```

```

WRITE (*,*) ' MACHINERY COST              K$US '
WRITE (*,630) CME
WRITE (*,631) CP
WRITE (*,632) CGB
WRITE (*,633) CM
630 FORMAT (' MAIN ENGINES:              ',F20.2)
631 FORMAT (' PROPULSORS:                ',F20.2)
632 FORMAT (' GEARBOXES:                 ',F20.2)
633 FORMAT (' TOTAL MACHINERY COST:        ',F20.2)

```

```

C-----
--

```

```

WRITE (*,*) ' '
WRITE (*,*) ' BUILDING COST ESTIMATION          KUS$ '
WRITE (*,635) BC
635 FORMAT (' TOTAL BUILDING COST:        ',F20.1)

```

```

C-----
--
C-----Deadweight Analysis
      SFC=0.22
      WFUEL=((PE*SFC*(R/VS))*1.09*1.1)/1000.0
      WFWPROV=0.00125*NPAX*(R/VS)
      WPAX=NPAX*0.105
      WCREW=NCREW*0.135
      WCAR=NCAR*1.0
      DW=1.06*(WFUEL+WFWPROV+WPAX+WCREW+WCAR)
C-----Lightship
      LS=WH+WO+WM
C-----Displacement from 'LS+DW'
      DISP2=DW+LS
      WRITE (*,*) ' '
      WRITE (*,*) ' DEADWEIGHT ANALYSIS'
      WRITE (*,*) ' -----'
      WRITE (*,*) ' '
      WRITE (*,640) WFUEL
      WRITE (*,641) WFWPROV
      WRITE (*,642) WCREW
      WRITE (*,643) WPAX
      WRITE (*,644) WCAR
      WRITE (*,645) DW
      WRITE (*,646) LS
      WRITE (*,647) DISP2
640 FORMAT (' FUEL & LUBRICANT',F8.2)
641 FORMAT (' WATER & PROVISIONS',F8.2)
642 FORMAT (' CREW & EFFECTS',F8.2)
643 FORMAT (' PASSENGERS & LUGGAGE',F8.2)
644 FORMAT (' CARS',F8.2)
645 FORMAT (' DEADWEIGHT',F8.2)
646 FORMAT (' LIGHTSHIP',F8.2)
647 FORMAT (' DISPLACEMENT2=LS+DW',F8.2)

C-----
--
C-----MASS BALANCE CALCULATIONS

      IF (((ABS(DISP2-DISP1)*100)/DISP1).GE.1.0) THEN
      WRITE (*,*) ' '
      WRITE (*,*) ' There is not a balance between DISP1 & DISP2.'
      WRITE (*,*) ' Do you want to perform the calculations for '
      WRITE (*,*) ' a different CB and LOD (Y/N)?'
      READ (*,520) YN
      IF ((YN.EQ.'Y').OR.(YN.EQ.'y')) THEN
      CONTINUE
      ELSE
      GOTO 510
      ENDIF
      CB=(DISP2*CB)/DISP1
C-----CB2=CB1*(LOD2/LOD1)**(1.0/3.0) with these equations without
C-----changing the dimension of the vessel, we can balance the mass.
      LOD=LOD*((DISP1/DISP2)**(1.0/3.0))
      IF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'pm')) THEN
      DISP1=1.025*LWL*B*T*CB
      ELSEIF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
      DISP1=1.025*2*LWL*BH*T*CB
      ELSEIF ((VTYPE.EQ.'VM').OR.(VTYPE.EQ.'vm')) THEN
      DISP1=1.025*LWL*B*T*CB
      ELSE
      DISP1=1.025*2*LWL*BH*T*CB
      ENDIF

```

```

ELSE
CONTINUE
ENDIF

```

```

C-----
--
510 WRITE (*,*) ' '
WRITE (*,*) ' DO YOU WANT TO PERFORM CALCULATIONS'
WRITE (*,*) ' FOR ANOTHER VESSEL (Y/N)?'
READ (*,520) YESNO
IF ((YESNO.EQ.'Y').OR.(YESNO.EQ.'y')) THEN
GOTO 500
ELSE
GOTO 530
ENDIF
520 FORMAT (A)
530 CALL HARDCOPY
STOP
END

```

```

C-----
--
SUBROUTINE HARDCOPY
CHARACTER *2 VTYPE,ETYPE
COMMON/ONE/LOA,LWL,B,S,BH,T,D,CB,DISP1,WME,WP,WGB,WM,CME,CP,CGB,
$
CM,WO,CO,WH,CH,BC,WFUEL,WFWPROV,WCREW,WPAX,WCAR,DW,DISP2,VS,SOL,
$ LOD,WSA, FN, FN,CFM,CFS,FN1,FN2,FN3,CR1,CR2,CR3,CR4,CR5,CR6,CR7,
$ CR8,CR9,D1,A,B1,C,CR,CRS2,k,bk,CTS,RTS,PE,PD,PI,EFF,N,ABC,
$
AJ,AKT,AKQ,DIAM,RPM,NPAX,NCAR,NCREW,AS,AP,NDECK,NE,R,BHOT,BOT,LS
COMMON/TWO/VTYPE,ETYPE
REAL

```

```

NPAX,NCAR,NCREW,AS,AP,AV,LB,LWL,LOA,B,D,BH,T,S,DISP1,LOD,BOT,
$ CB,PB,RPM,R,VS,LOB,LOBH,LOBH1,SOL,BHOT,NE,NDECK,PI,PE,PD,
$ CO,WSA,CFM,CFS,FN1,FN2,FN3,CR1,CR2,CR3,CR4,CR5,CR6,CR7,CR8,CR9,
$
D1,A,B1,C,CR,CRS2,k,bk,CTS,RTS,EFF,n,AJ,AKT,AKQ,DIAM,DISP2,LS,ABC
OPEN (16,FILE='G:\HARDCOPY.DAT',STATUS='unknown')
WRITE (16,10) NPAX,LOD,WO,NCAR,BOT,WM,VS,BHOT,WPAX,LOA,SOL,WCAR
WRITE (*,10) NPAX,LOD,WO,NCAR,BOT,WM,VS,BHOT,WPAX,LOA,SOL,WCAR
10 FORMAT(' NPAX = ',F8.2,' LOD = ',F8.2,' WO = ',F8.2,
',F8.2/,
' NCAR = ',F8.2,' BOT = ',F8.2,' WM = ',F8.2,
',F8.2/,
' VS = ',F8.2,' BHOT = ',F8.2,' WPAX = ',F8.2,
',F8.2/,
' LOA = ',F8.2,' SOL = ',F8.2,' WCAR = ',F8.2)
WRITE (16,20) LWL,NE,WFUEL,B,RPM,WFWPROV,BH,PD,WCREW,T,PE,BC
WRITE (*,20) LWL,NE,WFUEL,B,RPM,WFWPROV,BH,PD,WCREW,T,PE,BC
20 FORMAT(' LWL = ',F8.2,' NE = ',F8.2,' WFUEL = ',F8.2,
',F8.2/,
' B = ',F8.2,' RPM = ',F8.2,' WFWPROV = ',F8.2,
',F8.2/,
' BH = ',F8.2,' PD = ',F8.2,' WCREW = ',F8.2,
',F8.2/,
' T = ',F8.2,' PE = ',F8.2,' BC(milUSS) = ',F8.2)

```

```

WRITE(16,30)D,PI,ABC,S,R,LS,CB,NCREW,DW,AS,NDECK,DISP1,AP,WH,DISP2

```

```

WRITE(*,30)D,PI,ABC,S,R,LS,CB,NCREW,DW,AS,NDECK,DISP1,AP,WH,DISP2
  30 FORMAT(' D = ',F8.2,' PI = ',F8.2,' ABC(milUS$)=
',F8.2/,
$ ' S = ',F8.2,' R = ',F8.2,' LS =
',F8.2/,
$ ' CB = ',F8.2,' NCREW = ',F8.2,' DW =
',F8.2/,
$ ' AS = ',F8.2,' NDECK = ',F8.2,' DISP1 =
',F8.2/,
$ ' AP = ',F8.2,' WH = ',F8.2,' DISP2 =
',F8.2)
  CLOSE(16)
  RETURN
  END

```

```

C-----
      SUBROUTINE POWER
      CHARACTER *2 VTYPE,ETYPE
      COMMON/ONE/LOA,LWL,B,S,BH,T,D,CB,DISP1,WME,WP,WGB,WM,CME,CP,CGB,
$
CM,WO,CO,WH,CH,BC,WFUEL,WFWPROV,WCREW,WPAX,WCAR,DW,DISP2,VS,SOL,
$ LOD,WSA,FN,RN,CFM,CFS,FN1,FN2,FN3,CR1,CR2,CR3,CR4,CR5,CR6,CR7,
$ CR8,CR9,D1,A,B1,C,CR,CRS2,k,bk,CTS,RTS,PE,PD,PI,EFF,N,ABC,
$
AJ,AKT,AKQ,DIAM,RPM,NPAX,NCAR,NCREW,AS,AP,NDECK,NE,R,BHOT,BOT,LS
      COMMON/TWO/VTYPE,ETYPE
      REAL
NPAX,NCAR,NCREW,AS,AP,AV,LB,LWL,LOA,B,D,BH,T,S,DISP1,LOD,BOT,
$ CB,PB,RPM,R,VS,LOB,LOBH,LOBH1,SOL,BHOT,NE,NDECK,PI,PE,PD,FN,RN,
$ CO,WSA,CFM,CFS,FN1,FN2,FN3,CR1,CR2,CR3,CR4,CR5,CR6,CR7,CR8,CR9,
$
D1,A,B1,C,CR,CRS2,k,bk,CTS,RTS,EFF,n,AJ,AKT,AKQ,DIAM,DISP2,LS,ABC
C-----PASSENGER MONOHULL
      IF ((VTYPE.EQ.'PM').OR.(VTYPE.EQ.'pm')) THEN
          FN=(VS*0.5144)/SQRT(9.81*LWL)
          RN=(VS*0.5144*LWL)/1.19E-6
          CFM=0.075/(((ALOG10(FN*5.56E+6))-2)**2)
          CFS=0.075/(((ALOG10(RN))-2)**2)
          WSA=(1.7*LWL*T)+(LWL*B*CB)
          FN1=0.60
          FN2=0.80
          FN3=1.0
          CR1=(1702.0*LOD**(-2.96))*0.001
          CR2=(533.0*LOD**(-2.58))*0.001
          CR3=(122.0*LOD**(-1.96))*0.001
          D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
          A=(CR1*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR2*FN3**2-CR3*FN2**2)
$           +(FN1**2)*(CR2*FN3-CR3*FN2))/D1
          B1=((CR2*FN3**2-CR3*FN2**2)-CR1*(FN3**2-FN2**2)
$           +FN1**2*(CR3-CR2))/D1
          C=((FN2*CR3-FN3*CR2)-FN1*(CR3-CR2)+CR1*(FN3-FN2))/D1
          CR=A+B1*FN+C*FN**2
          k=0.15
          CTS=(CFS+CR)-(k*(CFM-CFS))
C-----VEHICLE MONOHULL
      ELSEIF ((VTYPE.EQ.'VM').OR.(VTYPE.EQ.'vm')) THEN
          FN=(VS*0.5144)/SQRT(9.81*LWL)
          RN=(VS*0.5144*LWL)/1.19E-6
          CFM=0.075/(((ALOG10(FN*5.56E+6))-2)**2)
          CFS=0.075/(((ALOG10(RN))-2)**2)
          WSA=(1.7*LWL*T)+(LWL*B*CB)

```

```

      FN1=0.60
      FN2=0.80
      FN3=1.0
      CR1=(1702.0*LOD**(-2.96))*0.001
      CR2=(533.0*LOD**(-2.58))*0.001
      CR3=(122.0*LOD**(-1.96))*0.001
      D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
      A=(CR1*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR2*FN3**2-CR3*FN2**2)
$      +(FN1**2)*(CR2*FN3-CR3*FN2))/D1
      B1=((CR2*FN3**2-CR3*FN2**2)-CR1*(FN3**2-FN2**2)
$      +FN1**2*(CR3-CR2))/D1
      C=((FN2*CR3-FN3*CR2)-FN1*(CR3-CR2)+CR1*(FN3-FN2))/D1
      CR=A+B1*FN+C*FN**2
      k=0.15
      CTS=(CFS+CR)-(k*(CFM-CFS))
C-----PASSENGER CATAMARAN
      ELSEIF ((VTYPE.EQ.'PC').OR.(VTYPE.EQ.'pc')) THEN
      WSA=2*((1.7*LWL*T)+(LWL*BH*CB))
      FN=(VS*0.5144)/SQRT(9.81*LWL)
      RN=(VS*0.5144*LWL)/1.19E-6
      CFM=0.075/((ALOG10(FN*5.56E+6)-2)**2)
      CFS=0.075/((ALOG10(RN)-2)**2)
      FN1=0.60
      FN2=0.80
      FN3=1.0
      CR4=(1774.0*LOD**(-2.87))*0.001
      CR5=(180.0*LOD**(-1.97))*0.001
      CR6=(48.0*LOD**(-1.41))*0.001
      CR7=(5084.0*LOD**(-3.30))*0.001
      CR8=(130.0*LOD**(-1.82))*0.001
      CR9=(22.0*LOD**(-1.06))*0.001
c-----S/L=0.3
      IF (SOL.EQ.0.3) THEN
      D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
      A=(CR4*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR5*FN3**2-CR6*FN2**2)
$      +(FN1**2)*(CR5*FN3-CR6*FN2))/D1
      B1=((CR5*FN3**2-CR6*FN2**2)-CR4*(FN3**2-FN2**2)
$      +FN1**2*(CR6-CR5))/D1
      C=((FN2*CR6-FN3*CR5)-FN1*(CR6-CR5)+CR4*(FN3-FN2))/D1
      CR=A+B1*FN+C*FN**2
C-----S/L=0.2
      ELSEIF (SOL.EQ.0.2) THEN
      D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
      A=(CR7*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR8*FN3**2-CR9*FN2**2)
$      +(FN1**2)*(CR8*FN3-CR9*FN2))/D1
      B1=((CR8*FN3**2-CR9*FN2**2)-CR7*(FN3**2-FN2**2)
$      +FN1**2*(CR9-CR8))/D1
      C=((FN2*CR9-FN3*CR8)-FN1*(CR9-CR8)+CR7*(FN3-FN2))/D1
      CR=A+B1*FN+C*FN**2
C-----0.4>S/L>0.3
      ELSEIF (SOL.GT.0.3.AND.SOL.LE.0.4) THEN
      D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
      A=(CR4*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR5*FN3**2-CR6*FN2**2)
$      +(FN1**2)*(CR5*FN3-CR6*FN2))/D1
      B1=((CR5*FN3**2-CR6*FN2**2)-CR4*(FN3**2-FN2**2)
$      +FN1**2*(CR6-CR5))/D1
      C=((FN2*CR6-FN3*CR5)-FN1*(CR6-CR5)+CR4*(FN3-FN2))/D1
      CR=A+B1*FN+C*FN**2
C-----0.3>S/L>0.2
      ELSEIF (SOL.GE.0.2.AND.SOL.LE.0.3) THEN
      D1=(FN2*FN3**2-FN3*FN2**2)-FN1*(FN3**2-FN2**2)+FN1**2*(FN3-FN2)
      A=(CR7*(FN2*FN3**2-FN3*FN2**2)-FN1*(CR8*FN3**2-CR9*FN2**2)
$      +(FN1**2)*(CR8*FN3-CR9*FN2))/D1

```

```

      B1=( (CR8*FN3**2-CR9*FN2**2) -CR7*(FN3**2-FN2**2)
$      +FN1**2*(CR9-CR8) ) /D1
      C=( (FN2*CR9-FN3*CR8) -FN1*(CR9-CR8) +CR7*(FN3-FN2) ) /D1
      CRS2=A+B1*FN+C*FN**2
      CR=CRS2-((SOL-0.2)/(0.3-0.2))*(CR2-CR3)
      ELSE
      WRITE (*,*) 'S/LWL RATIO IS OUT OF RANGE.'
      STOP
      ENDIF
      bk=0.25
      CTS=(CFS+CR) - (bk*(CFM-CFS))
C-----VEHICLE CATAMARAN
      ELSE
      WSA=2*((1.7*LWL*T)+(LWL*BH*CB))
      FN=(VS*0.5144)/SQRT(9.81*LWL)
      RN=(VS*0.5144*LWL)/1.19E-6
      CFM=0.075/((ALOG10(FN*5.56E+6)-2)**2)
      CFS=0.075/((ALOG10(RN)-2)**2)
      FN1=0.60
      FN2=0.80
      FN3=1.0
      CR4=(1774.0*LOD**(-2.87))*0.001
      CR5=(180.0*LOD**(-1.97))*0.001
      CR6=(48.0*LOD**(-1.41))*0.001
      CR7=(5084.0*LOD**(-3.3))*0.001
      CR8=(130.0*LOD**(-1.82))*0.001
      CR9=(22.0*LOD**(-1.06))*0.001
C-----S/L=0.3
      IF (SOL.EQ.0.3) THEN
      D1=(FN2*FN3**2-FN3*FN2**2) -FN1*(FN3**2-FN2**2) +FN1**2*(FN3-FN2)
      A=(CR4*(FN2*FN3**2-FN3*FN2**2) -FN1*(CR5*FN3**2-CR6*FN2**2)
$      + (FN1**2)*(CR5*FN3-CR6*FN2) ) /D1
      B1=( (CR5*FN3**2-CR6*FN2**2) -CR4*(FN3**2-FN2**2)
$      +FN1**2*(CR6-CR5) ) /D1
      C=( (FN2*CR6-FN3*CR5) -FN1*(CR6-CR5) +CR4*(FN3-FN2) ) /D1
      CR=A+B1*FN+C*FN**2
C-----S/L=0.2
      ELSEIF (SOL.EQ.0.2) THEN
      D1=(FN2*FN3**2-FN3*FN2**2) -FN1*(FN3**2-FN2**2) +FN1**2*(FN3-FN2)
      A=(CR7*(FN2*FN3**2-FN3*FN2**2) -FN1*(CR8*FN3**2-CR9*FN2**2)
$      + (FN1**2)*(CR8*FN3-CR9*FN2) ) /D1
      B1=( (CR8*FN3**2-CR9*FN2**2) -CR7*(FN3**2-FN2**2)
$      +FN1**2*(CR9-CR8) ) /D1
      C=( (FN2*CR9-FN3*CR8) -FN1*(CR9-CR8) +CR7*(FN3-FN2) ) /D1
      CR=A+B1*FN+C*FN**2
C-----0.4>S/L>0.3
      ELSEIF (SOL.GT.0.3.AND.SOL.LE.0.4) THEN
      D1=(FN2*FN3**2-FN3*FN2**2) -FN1*(FN3**2-FN2**2) +FN1**2*(FN3-FN2)
      A=(CR4*(FN2*FN3**2-FN3*FN2**2) -FN1*(CR5*FN3**2-CR6*FN2**2)
$      + (FN1**2)*(CR5*FN3-CR6*FN2) ) /D1
      B1=( (CR5*FN3**2-CR6*FN2**2) -CR4*(FN3**2-FN2**2)
$      +FN1**2*(CR6-CR5) ) /D1
      C=( (FN2*CR6-FN3*CR5) -FN1*(CR6-CR5) +CR4*(FN3-FN2) ) /D1
      CR=A+B1*FN+C*FN**2
C-----0.3>S/L>0.2
      ELSEIF (SOL.GE.0.2.AND.SOL.LE.0.3) THEN
      D1=(FN2*FN3**2-FN3*FN2**2) -FN1*(FN3**2-FN2**2) +FN1**2*(FN3-FN2)
      A=(CR7*(FN2*FN3**2-FN3*FN2**2) -FN1*(CR8*FN3**2-CR9*FN2**2)
$      + (FN1**2)*(CR8*FN3-CR9*FN2) ) /D1
      B1=( (CR8*FN3**2-CR9*FN2**2) -CR7*(FN3**2-FN2**2)
$      +FN1**2*(CR9-CR8) ) /D1
      C=( (FN2*CR9-FN3*CR8) -FN1*(CR9-CR8) +CR7*(FN3-FN2) ) /D1
      CRS2=A+B1*FN+C*FN**2

```



```
CR=CRS2-((SOL-0.2)/(0.3-0.2))*(CR2-CR3)
ELSE
WRITE (*,*) 'S/LWL RATIO IS OUT OF RANGE.'
STOP
ENDIF
bk=0.25
CTS=(CFS+CR)-(bk*(CFM-CFS))
ENDIF
RTS=CTS*0.5*1.025*WSA*((VS*0.5144)**2.0)
C-----Effective power (kW)
PE=RTS*VS*0.5144
C-----Water jet efficiency
EFF=1.0/(1.0+(16.8/VS))
C-----Delivery power (kW)
PD=PE/EFF
C-----15%resistance increase due to hull roughness, fouling and
weather.
PI=PD*1.15
RETURN
END
```