Towards Scalable Modeling of Biology in Event-B

Usman Sanwal¹, Thai Son Hoang², Luigia Petre¹, and Ion Petre^{3,4}

¹ Faculty of Science and Engineering, Åbo Akademi University, Finland

School of Electronics and Computer Science, University of Southampton, UK

³ Department of Mathematics and Statistics, University of Turku, Finland

⁴ National Institute for Research and Development in Biological Sciences, Romania

Abstract. Biology offers many examples of large-scale, complex, concurrent systems: many processes take place in parallel, compete on resources and influence each other's behavior. The scalable modeling of biological systems continues to be a very active field of research. In this paper we introduce a new approach based on Event-B, a state-based formal method with refinement as its central ingredient, allowing us to check for model consistency step-by-step in an automated way. Our approach based on functions leads to an elegant and concise modeling method. We demonstrate this approach by constructing what is, to our knowledge, the largest ever built Event-B model, describing the ErbB signaling pathway, a key evolutionary pathway with a significant role in development and in many types of cancer. The Event-B model for the ErbB pathway describes 1320 molecular reactions through 242 events.

1 Introduction

Biological systems are typically very large and complex, so much that it is remarkably difficult to capture all the necessary details in one modeling step. The concept of refinement – gradually adding details to a model while preserving its consistency – is thus instrumental and it has been shown before, in our [29] and related research [9,10,11,16], to bring value to biological modeling.

Biological systems are often modeled by so-called reaction networks, i.e., as sets of biochemical reactions of type

$$n_A * A + n_B * B \rightleftharpoons n_C * C + n_D * D,$$

where the reactants A, B, C, and D model species, proteins, genes, etc. and n_A , $n_B, n_C, n_D \in \mathbb{N}$. When refining a reaction network, usually more reactants and their corresponding new reactions are added, and/or some (abstract) reactions are replaced with specialized sets of reactions, more accurately modeling the phenomenon of interest. In both cases, the reaction networks grow, sometimes exponentially; suitable tools for handling the models, their correctness properties, as well as their refinements are needed.

Reaction network modeling, including refinement, has already been addressed with different approaches, such as ODE-based modeling [16], rule-based modeling [9], Petri nets [11], guarded command languages [10] and Event-B [29]. Event-B [2], in particular, is especially suitable for modeling complex systems, due to the concept of stepwise refinement that is a central part of this formal method. New details of a model are introduced by adding new variables (that model the state of the system) and events (that model the state changes in the system), potentially in several different refinement steps. This makes the modeling of large and complex systems more manageable. Correctness properties that were proved for a model are preserved when refining that model: the refinement approach is also called correctness-by-construction. The advantage that Event-B brings, when compared to other approaches (Petri nets, ODE modeling, etc.) is that it has refinement as the key concept of the development method and is supported by a toolset named Rodin [3]. System details can be introduced in several steps and the tool manages all the links between all the intermediary models. Consistency of refinement ensures that all the properties of a model M_i are still valid in its direct refinement successor M_{i+1} . At each refinement step, one can focus on the new elements that are introduced and on their consistency with the previous model. This approach allows to also separate the reasoning about the system under development into smaller steps.

In this paper, we model two biological systems using refinement in Event-B, i.e., we first model a simple, more abstract model of the system and then we add more details in a correct-by-construction manner, as explained above. The two systems we address are the heat shock response and the ErbB signaling pathway. Modeling the heat shock response in Event-B succeeded before [29]: we started with the abstract model having 10 variables and 17 events and ended up with the concrete model having 22 variables and 57 events. Modeling the ErbB signaling pathway only succeeded earlier [17] for the abstract model, with 110 variables and 242 events. The concrete model would have 1320 events, which was not supported by Rodin.

The contribution of this paper consists in demonstrating how a particular modeling feature of Event-B – the common mathematical function – enables us to significantly reduce the concrete models' sizes. The relation between the abstract and the concrete forms of a reactant is captured with a function. This enables us to model the concrete reactions more elegantly and concisely, and as a result, the total number of events in the refined model is reduced significantly. In the case of the heat shock response, the complete model is described through 21 events, instead of the 57 events of the model in [29]. The difference in the case of the ErbB model is drastic, as we now need only 242 events for the full model of the ErbB signaling pathway in Rodin, instead of 1320 events. Rodin is successfully handling this.

Thus, based on our experiments with modeling the two biological systems, we demonstrate a proof-of-concept about employing functions to address scalability with Event-B. To the best of our knowledge, the concrete ErbB signaling pathway model with 242 events is the biggest Event-B model ever built. This is significant, since we now have proof of how to manage the modeling and analysis of large systems formally.

We proceed as follows. In Section 2 we review the biological systems we address (the heat shock response and the ErbB signaling pathway); we also discuss Event-B particulars. In Section 3, we present our scheme for building an Event-B model corresponding to a given reaction network, also introducing the function-based modeling idea. In Sections 4 and 5, we illustrate the function-based modeling in Event-B of the heat shock response and of the ErbB signaling pathway, respectively. We discuss our results and potential impact in Section 6. All Event-B models constructed in the paper can be downloaded at https://combio.org/wp-content/uploads/2021/05/Event-B_Model_ICTAC2021.zip.

2 Preliminaries

In this section we describe the biological systems we model – the heat shock response and the ErbB signaling pathway – and then we briefly review Event-B, the modeling method we use.

2.1 The heat shock response (HSR)

The heat-shock response is a cellular-level regulatory mechanism [27,31]. Proteins are folded in three dimensional shapes and the fold determines whether it can achieve its functionality (e.g., bind to a certain site on a DNA molecule or on another protein). Protein folding is a dynamical process, continuously influenced by many factors, such as chemical modifications of the amino-acids forming the protein (e.g., phosphorylation, acetylation, sumovlation) and properties of the environment (e.g., temperature, radiation, heavy metals). Misfolded proteins quickly form large protein bundles that are detrimental to the normal physiology of a cell and eventually lead to cell death. The heat shock response is one of the stress response mechanisms of a cell, aiming to limit the accumulation of misfolded proteins and assisting misfolded proteins to regain their natural fold. The heat shock response synthesizes a group of proteins – called heat shock proteins (hsps) – that act as molecular chaperones for the misfolded proteins and support their recovery from stress. This is achieved either by repairing the damaged proteins or by degrading them, thus restoring protein homeostasis and promoting cell survival. Without such a mechanism, misfolded proteins will form plaque, which is the hallmark of many neurological diseases.

The basic model we discuss for the eukaryotic heat shock response is presented in [25] and summarized in Table 1. When the temperature increases, proteins prot begin to misfold, namely transform into mfp (Reaction (10)). The heat shock proteins have a high affinity to bind to the misfolded proteins, acting as chaperones and forming hsp: mfp complexes (Reaction (11)). Then, the complex hsp: mfp can transform back into the original protein prot, freeing the heat shock factor protein hsp too (Reaction (12)). The hsp is synthesized as follows. A specific (called transcription factor) protein – known as the heat shock factor

3

| (1) $2 \operatorname{hsf} \rightleftharpoons \operatorname{hsf}_2$ | (7) $hsp + hsf_3 \rightarrow hsp: hsf + 2 hsf$ |
|--|---|
| $(2) hsf + hsf_2 \rightleftarrows hsf_3$ | (8) $hsp + hsf_3$: $hse \rightarrow hsp$: $hsf + 2 hsf + hse$ |
| (3) $hsf_3 + hse \rightleftharpoons hsf_3$: hse | $(9) hsp \to \emptyset$ |
| (4) $hsf_3: hse \rightarrow hsf_3: hse + hsp$ | $(10) \operatorname{prot} 	o \operatorname{mfp}$ |
| (5) $hsp + hsf \rightleftharpoons hsp: hsf$ | $(11) hsp + mfp \rightleftarrows hsp:mfp$ |
| (6) $hsp + hsf_2 \rightarrow hsp: hsf + hsf$ | (12) hsp: mfp \rightarrow hsp + prot |

Table 1. The molecular model for the eukaryotic heat shock response proposed in [25].

(hsf) – binds in trimmer form to the hsp's gene promoter – the heat shock element hse (Reactions (1)–(3) in Table 1). The formed hsf₃: hse then produces the hsp proteins (Reaction (4)). These tend to combine with hsf and stay in inactive state as hsp: hsf complexes (right arrow in Reaction (5), as well as Reactions (6)–(8)). Once the temperature increases and more hsp are becoming chaperons for mfp, less are available for forming hsp: hsf complexes and the balance changes: the left arrow in the Reaction (5) is activated. Finally, hsps can also degrade (Reaction (9)).

This is a simplified description of heat shock response, which is much more complex. As an example of the complexity, proteins can have multiple forms once they are synthesized, for instance they can be phosphorylated (slightly altered by an enzymatic reaction with an extra PO_4 phosphate group; since PO_4 has a negative electrical charge, this means that the protein folding is slightly different, leading to a changed activity). In this paper, we focus on the phosphorylation of only one aminoacid – called S230 – of the hsf protein. In our more detailed model, we take into account two versions of hsf: one where S230 is present in the non-phosphorylated form (denoted rhsf⁽⁰⁾) and the other where S230 is present in the phosphorylated form (denoted rhsf⁽¹⁾). The full details for the refinement of the heat shock response can be found in [25,29].

2.2 The ErbB signaling pathway

The ErbB signaling pathway is a very well studied evolutionary pathway, because it is essential in the growth and expansion of organs and of the central nervous system [24,6,8]. Its main role is to induce, through the cellular membrane, a signal instigating the cell's growth and differentiation. This pathway is often overly active in various types of cancer and has been used for a long time as a therapeutic target. Once activated, the pathway keeps signaling to the cell to grow and differentiate, potentially leading to the uncontrolled growth that is the hallmark of cancer.

We discuss briefly here the key functionality of the ErbB signaling pathway using a highly simplified language. For details we refer to [14,21,30]. The epidermal growth factors (EGF) are a family of proteins that signal to cells to grow and differentiate. They do that by binding to ligand proteins embedded in the cellular membrane – the epidermal growth factor receptors (EGFR). Once bound, the complex dimerizes and then gets phosphorylated. This then activates other (MAPK and ERK) signaling pathways. All of these activations are done step by step through a cascade of reactions, whose effect is the activation of some proteins, that then participate in other reactions activating other proteins, etc.

We follow in this paper the model of the ErbB signaling pathway presented in [14], that is a revised version of the two earlier models presented in [21] and [30]. The model is first presented on a more generic level, along the lines briefly described above. This initial model consists however of 148 reactions. The full model is then introduced essentially by differentiating between the four members of the EGFR family (ErbB1 (also known as EGFR), ErbB2, ErbB3, ErbB4) and the two members of the EGF family (EGF and HRG). Adding these details leads to many more species in the model. For example, the bonded complex EGF : EGFR is replaced by 8 different variants of it, and the dimer (EGF : EGFR)₂ is replaced by 64 complexes. The full model of [14] has 1320 reactions.

2.3 Event-B

Event-B [2] is a state-based formal method, building on earlier formalisms such as the B-Method [1] and the Action Systems [4]. The system state in Event-B is described by the values of *variables* and the state changes are modeled using *events*. The types of variables and other important properties that must hold during system execution are defined as *invariants*. The initial system state is described with a specific event named Initialisation. An event can contain parameters, a guard and an action. The parameters model some variables local to the event; the guard is a predicate on the variables and parameters, describing the conditions under which the action can take place; the action describes the updates to the variables. If a guard evaluates to true, then we say that the event is *enabled*. If two or more events are enabled at the same time, then one is non-deterministically chosen and executed. The variables and events in an Event-B model of a system are contained in a *machine*, also referred to as the "dynamic part" of the model. An Event-B machine can see one or more contexts, also known as the "static part" of the model. A context contains definitions of constants, carrier sets, as well as axioms about them. A general structure of an Event-B model, made out of machine M and context C is presented in Fig. 1.

A key concept in formal modeling with Event-B is that of *refinement* [2]: this allows the modeler to start from a simple model of the system and then gradually introduce more details, in the form of new events, variables or context data.

Event-B modeling has two types of refinements: *superposition refinement* and *data refinement*. Superposition refinement [5,20] is the term used when we refine a model by adding new variables and events to the existing model. The validity of model is preserved by making sure that newly added events must neither contradict nor take over the previous events in any of the preceding models. In *data refinement* [13], some variables in the more abstract machine are replaced by other variables in the refined machine; in this case, we need to add a *gluing invariant* in the refined machine, which formally defines the relation between the previous, abstract variables and the newly introduced, concrete ones.

6



Fig. 1. General structure of machine M and context C in Event-B

Refinement in Event-B has been used to model numerous protocols and systems, see [2,7,23,12,18,28,26,15,19,29].

Event-B benefits from the tool support of the Eclipse-based Rodin platform [3]. Rodin allows to edit the model, to prove properties of the model, to animate the model and even allows model checking. Proving in Event-B employs several proof engines to automatically prove the different properties of the model. This works by Rodin automatically generating first proof obligations in the form of sequents; these need to be discharged in order for the different properties (e.g., invariance, termination, or refinement) to hold. The automatic provers usually discharge many of the proof obligations. The remaining ones can be tackled using the interactive prover, with input from the modeler, for instance by adding useful assumptions or choosing a different proof strategy. The fact that some properties are not discharged automatically shows that there might be some problem with some modeling aspect of the system. The modeler then has a chance to edit the model to address the issue. Such interleaving between modeling and proving is an important aspect of working with the Rodin platform and is quite similar to the compilation of programs [3].

3 Modelling reaction networks in Event-B

We model reaction networks as sets of biochemical reactions, where each reaction specifies its reactants, products, and possibly inhibitors and catalyzers, see [22]. These reactions can be either reversible or irreversible and each reaction could also have an associated flux, describing the rate at which its products are produced and its reactants consumed. For simplicity, we consider each reversible reaction in our methodology as two reactions and we model only the reactants and the products in this paper. With these assumptions, a reaction r can be written as a rewriting rule of the form:

$$r: \quad m_1 X_1 + m_2 X_2 + \dots + m_n X_n \to m'_1 X_1 + m'_2 X_2 + \dots + m'_n X_n, \qquad (\mathbf{R})$$

where $S = \{X_1, ..., X_n\}$ is the set of *reactants* and $m_1, ..., m_n, m'_1, ..., m'_n \in \mathbb{N}$ are non-negative integers.

Reaction networks are modeled rather straightforwardly in Event-B: every reactant is modeled by a variable and every reaction is modeled by an event. Invariants ensure the correctness of each reactant modeling as well as other biological properties of interest, for instance the mass conservation rule that requires that the number of certain reactants is constant in the system.

Thus, $X_1, X_2, ..., X_n$ are the variables of the model, their type (the set of nonnegative integers) being specified by corresponding invariants. This is another simplification through which we consider each species as being discrete instead of continuous. Initial values for all of these variables are set in the initialisation event. For each reaction r of the reaction network, we specify in its guard that it must have enough of each reactant in order for the reaction to be enabled, while the action of the event specifies the changes to happen to each variable. The general form of an Event-B model corresponding to a reaction network as described by (R) is presented in Table 2. For more details of this general scheme, we refer to [29].

 Table 2. The general form of an Event-B model for a reaction network.

```
VARIABLES X_1, X_2, ..., X_n
                                                 Event r
INVARIANTS
                                                  WHERE
 @inv1 X_1 \in \mathbb{N}
                                                   @grd1 X_1 \ge m_1
 @inv2 X_2 \in \mathbb{N}
                                                   @grd2 X_2 \ge m_2
 @invn X_n \in \mathbb{N}
                                                   @grdn X_n \ge m_n
                                                  THEN
INITIALISATION
                                                   @act1 X_1 := X_1 + (m'_1 - m_1)
@act2 X_2 := X_2 + (m'_2 - m_2)
 @act1 X_1 = init_1
 @act2 X_2 = init_2
                                                   \textbf{@actn } X_n := X_n + (m'_n - m_n)
 @actn X_n = init_n
                                                 END
```

In this work we use data refinement to add detail to a biological model. In the refined machine, we introduce gluing invariants modeling the relations between the variables-to-be-refined from the abstract machine and their concrete versions in the refined machine. In the following, we present the differences with respect to scalability in two different types of reactions, a binding and a dimerization. In Sections 4 and 5, we point out how this type of modeling was used for the heat shock response and the ErbB signaling pathway, respectively.

3.1 Binding

Say we have a reaction (bind) of type $A + B \rightarrow AB$. According to Table 2, the corresponding event is shown in event **AbstractBind** (bind_EB). Further assume the A reactant is to be refined into two special cases, A_0 and A_1 . The less scalable data refinement approach, used in [29], leads us to refine the (bind_EB) event into the two events shown in Table 3, where A_0B and A_1B are the refined bindings and the gluing invariants are $A = A_0 + A_1$ and $AB = A_0B + A_1B$.

8 Usman Sanwal, Thai Son Hoang, Luigia Petre, and Ion Petre

```
AbstractBind event

WHERE

@grd1 A \ge 1

@grd2 B \ge 1

THEN

@act1 A := A - 1

@act2 B := B - 1

@act3 AB := AB + 1

END
```

(bind EB)

Table 3. The traditional binding data refinement approach

| ConcreteBind0 event | ConcreteBind1 event |
|---------------------------------|---------------------------------|
| WHERE | WHERE |
| @grd1 $A_0 \ge 1$ | @grd1 $A_1 \ge 1$ |
| $@grd2 B \ge 1$ | @grd2 $B \ge 1$ |
| THEN | THEN |
| @act1 $A_0 := A_0 - 1$ | @act1 $A_1 := A_1 - 1$ |
| @act2 $B := B - 1$ | @act2 $B := B - 1$ |
| @act3 $A_0B := A_0B + 1$ | @act3 $A_1B := A_1B + 1$ |
| END | END |

Table 4. The scalable binding data refinement approach

Context... **Constants** A_0, A_1, A_0B, A_1B **Sets** A_SET, AB_SET Axioms $partition(A_SET, \{A_0\}, \{A_1\})$ $partition(AB_SET, \{A_0B\}, \{A_1B\})$ ScalableConcreteBind event **ANY** e.iWHERE **@grd1** A $FUNC(e) \ge 1$ **@grd2** $B \ge 1$ **@grd3** $(e = A_0 \land i = A_0 B) \lor (e = A_1 \land i = A_1 B)$ THEN **@act1** A FUNC(e) := A FUNC(e) - 1**@act2** B := B - 1**@act3** $AB_FUNC(i) := AB_FUNC(i) + 1$ END

If, instead of defining four concrete variables A_0, A_1, A_0B, A_1B in the refined machine as non-negative integers, we define two functions whose domains are special constant sets defined in the context, then we can replace the two events **ConcreteBind0** and **ConcreteBind1** with only one event, named **ScalableConcreteBind**, illustrated in Table 4. The two concrete variables are now A_FUNC and AB_FUNC , defined (in invariants in the refined machine) as

functions $A_FUNC : A_SET \to \mathbb{N}$ and $AB_FUNC : AB_SET \to \mathbb{N}$, respectively. The gluing invariants are $A = A_FUNC(A_0) + A_FUNC(A_1)$ and $AB = AB_FUNC(A_0B) + AB_FUNC(A_1B)$.

3.2 Dimerization

Say we have a reaction (dimer) of type $A + A \rightarrow AA$. According to Table 2, its corresponding event is

AbstractDimer eventWHERE $@grd1 A \ge 2$ THEN@act1 A := A - 2@act3 AA := AA + 1END

(dimer_EB)

Further assume the A reactant is to be refined into two special cases, A_0 and A_1 . In the data refinement approach in [29], we refine the (dimer_EB) event into three events (see Table 5), with the refined dimers AA_0 , AA_1 and AA_{01} and the gluing invariants $A = A_0 + A_1$ and $AA = AA_0 + AA_1 + AA_{01}$.

Table 5. The traditional dimer data refinement approach

| | | ConcreteDimer01 event |
|---------------------------------|---------------------------------|---------------------------------------|
| ConcreteDimer0 event | ConcreteDimer1 event | WHERE |
| WHERE | WHERE | @grd1 $A_0 \ge 1$ |
| @grd1 $A_0 \ge 2$ | @grd1 $A_1 \ge 2$ | @grd2 $A_1 \ge 1$ |
| THEN | THEN | THEN |
| @act1 $A_0 := A_0 - 2$ | @act1 $A_1 := A_1 - 2$ | @act1 $A_0 := A_0 - 1$ |
| @act3 $AA_0 := AA_0 + 1$ | @act3 $AA_1 := AA_1 + 1$ | @act2 $A_1 := A_1 - 1$ |
| END | END | @act3 $AA_{01} := AA_{01} + 1$ |
| | | END |

If, instead of defining five concrete variables A_0 , A_1 , AA_0 , AA_1 , AA_{01} in the refined machine as non-negative integers, we define two functions whose domains are special constant sets defined in the context, then we can replace the three events **ConcreteDimer0**, **ConcreteDimer1** and **ConcreteDimer01** with only two events, named **ScalableConcreteBind** and **ScalableConcrete-Bind01**, illustrated in Table 6. The concrete variables are now A_FUNC and AB_FUNC , defined (in invariants in the refined machine) as functions $A_FUNC : A_SET \rightarrow \mathbb{N}$ and $AA_FUNC : AA_SET \rightarrow \mathbb{N}$, respectively. The gluing invariants are $A = A_FUNC(A_0) + A_FUNC(A_1)$ and $AA = AA_FUNC(AA_0) + AA_FUNC(AA_1) + AA_FUNC(AA_{01})$. The symbol \preccurlyeq in Table 6 is used so that the function A_FUNC is modified only for the elements A_0 and A_1 of its domain.

3.3 In a nutshell

What we propose in this paper is to use as concrete variable functions instead of non-negative integers. In the context part of the model, we define a constant

10 Usman Sanwal, Thai Son Hoang, Luigia Petre, and Ion Petre

Table 6. The scalable dimer data refinement approach

```
\begin{array}{l} \textbf{@grd1} A\_FUNC(e) \geq 2\\ \textbf{@grd2} (e = A_0 \land i = AA_0) \lor (e = A_1 \land i = AA_1)\\ \textbf{THEN}\\ \textbf{@act1} A\_FUNC(e) := A\_FUNC(e) - 2\\ \textbf{@act2} AA\_FUNC(i) := AA\_FUNC(i) + 1\\ \textbf{END} \end{array}
```

set for each variable-to-be-refined of the reaction network. This set contains all the refined forms of the variable-to-be-refined and is the domain of the function (concrete variable) in the refined machine. Since we can generalise the formulation of guards when we use functions, we do not need to distinguish between so many different cases, and hence, the number of events does not grow in a combinatorial explosion anymore. The number of variables remains constant.

4 An Event-B model for the heat shock response using functions

Here we use the approach described in Section 3 for modeling two reactions - (5) and (1) - of the heat shock response in Table 1 and their phosphorylationrelated refinement. To model the refinement of the heat shock factor (hsf) into its two variants (0- and 1-phosphorylated), we introduce a set named HSF and

11

Table 7. Basic model: the HSF sequestration event.

```
\begin{array}{l} \textbf{HSF Sequestration Basic Event}\\ \textbf{WHERE}\\ @grd1 \ hsp \geq 1 \land hsf \geq 1\\ \textbf{THEN}\\ @act1 \ hsp := \ hsp -1\\ @act2 \ hsf := \ hsf -1\\ @act3 \ hsp: \ hsf := \ hsp: \ hsf +1\\ \textbf{END} \end{array}
```

two distinct constants named HSF_0 and HSF_1; HSF is defined as HSF = {HSF_0, HSF_1}. Similarly, hsf can be 0- or 1-phosphorylated also in the binding hsp: hsf with the heat shock protein hsp. To capture this, we introduce a set named HSPHSF and two distinct constants named HSPHSF_0 and HSPHSF_1; HSPHSF is defined as HSPHSF = {HSPHSF_0, HSPHSF_1}. Likewise, hsf can be 0- or 1-phosphorylated also in the dimer hsf₂. To capture this, we introduce the set HSF2 and three distinct constants HSF2_0, HSF2_1, and HSF2_2, so that HSF2 = {HSF2_0, HSF2_1, HSF2_2}. This is implemented in the context part of the Event-B model.

In [29], the abstract event in Table 7 is replaced by two events (shown in Table 8), where the concrete variables that replace hsf are $rhsf^{(0)}$ and $rhsf^{(1)}$, with the gluing invariant $hsf = rhsf^{(0)} + rhsf^{(1)}$. Similarly, the abstract variable binding hsp: hsf is to be replaced by the two concrete variables hsp: $rhsf^{(0)}$ and hsp: $rhsf^{(1)}$, with the gluing invariant hsp: $hsf = hsp: rhsf^{(0)} + hsp: rhsf^{(1)}$.

Table 8. Previous approach: the refinement of the HSF sequestration event. The variable hsf is replaced in all possible ways with $rhsf^{(0)}$ and $rhsf^{(1)}$, leading to 2 events.

| HSF Sequestration Refinement-1 | HSF Sequestration Refinement-2 |
|--|---|
| WHERE | WHERE |
| $@\mathbf{grd1} hsp \geq 1$ | $@\mathbf{grd1}$ hsp ≥ 1 |
| $@\mathbf{grd2}$ rhsf $^{(0)} \ge 1$ | $@\mathbf{grd2}$ rhsf $^{(1)} \geq 1$ |
| THEN | THEN |
| @act1 hsp := hsp -1 | @act1 hsp := hsp -1 |
| $@\mathbf{act2} rhsf^{(0)} := rhsf^{(0)} - 1$ | $@\mathbf{act2} rhsf^{(1)} := rhsf^{(1)} - 1$ |
| $@\mathbf{act3} hsp: rhsf^{(0)} := hsp: rhsf^{(0)} + 1$ | @act3 hsp: rhsf ⁽¹⁾ := hsp: rhsf ⁽¹⁾ +1 |
| END | END |
| | |

Now, instead of the concrete variables $rhsf^{(0)}, rhsf^{(1)}, hsp: rhsf^{(0)}, hsp: rhsf^{(1)}$ we define two functions, $rhsf: HSF \rightarrow \mathbb{N}$ and $rhsp: hsf: HSPHSF \rightarrow \mathbb{N}$, so that we have the gluing invariants $hsf = rhsf(HSF_0) + rhsf(HSF_1)$ and hsp: hsf = $rhsp: hsf(HSPHSF_0) + rhsp: hsf(HSPHSF_1)$. The event of the abstract model (Table 7) will be refined to a single event covering all the cases. So, instead of the two events shown in Table 8, we now have the single event in Table 9. 12 Usman Sanwal, Thai Son Hoang, Luigia Petre, and Ion Petre

Table 9. Current approach: the refinement of the HSF sequestration event. Functions are used for a compact formulation of the refinement.

```
\begin{array}{l} \textbf{HSF Sequestration Refinement Functions} \\ \textbf{ANY} \\ e,i \\ \textbf{WHERE} \\ @grd1 \ hsp \geq 1 \land rhsf(e) \geq 1 \\ @grd2 \ (e = \mathsf{HSF\_0} \land i = \mathsf{HSPHSF\_0}) \lor (e = \mathsf{HSF\_1} \land i = \mathsf{HSPHSF\_1}) \\ \textbf{THEN} \\ @act1 \ hsp := hsp -1 \\ @act2 \ rhsf(e) := rhsf(e) -1 \\ @act3 \ rhsp: hsf(i) := rhsp: hsf(i) + 1 \\ \textbf{END} \end{array}
```



```
\begin{array}{l} \textbf{Dimerization Basic Event}\\ \textbf{WHERE}\\ @grd1 hsf \geq 2\\ \textbf{THEN}\\ @act1 hsf := hsf -2\\ @act2 hsf_2 := hsf_2 + 1\\ \textbf{END} \end{array}
```

For hsf's dimerization (reaction (1) in Table 1), we need to refine the abstract event in Table 10. In [29], this event is refined by three events (shown in Table 11), where the concrete variables that replace hsf are rhsf⁽⁰⁾ and rhsf⁽¹⁾, with the gluing invariant hsf = rhsf⁽⁰⁾ + rhsf⁽¹⁾. Similarly, the abstract dimer variable hsf₂ is to be replaced by three concrete variables rhsf⁽⁰⁾₂, rhsf⁽¹⁾₂ and rhsf⁽²⁾₂, with the gluing invariant hsf₂ = rhsf⁽⁰⁾₂ + rhsf⁽¹⁾₂ + rhsf⁽²⁾₂.

Now, instead of the concrete variables $\mathsf{rhsf}^{(0)},\mathsf{rhsf}^{(1)},\mathsf{rhsf}^{(0)}_2,\mathsf{rhsf}^{(1)}_2,\mathsf{rhsf}^{(2)}_2$ we define two functions, $\mathsf{rhsf}:\mathsf{HSF}\to\mathbb{N}$ and $\mathsf{rhsf2}:\mathsf{HSF2}\to\mathbb{N}$, so that we have the gluing invariants $\mathsf{hsf}=\mathsf{rhsf}(\mathsf{HSF}_0)+\mathsf{rhsf}(\mathsf{HSF}_1)$ and $\mathsf{hsf2}=\mathsf{rhsf2}(\mathsf{HSF2}_0)+\mathsf{rhsf2}(\mathsf{HSF2}_1)+\mathsf{rhsf2}(\mathsf{HSF2}_2)$. The event of the abstract model (Table 10) will be refined by two events. So, instead of the three events shown in Table 11, we now have two events in Table 12.

Thus, our new approach leads to a new, more compact, refinement-based approach to biological modeling. In the case of the heat shock response, the complete model is described through 10 variables and 21 events, instead of the 22 variables and 57 events of the model in [29]. The full model can be downloaded at https://combio.org/wp-content/uploads/2021/05/Event-B_Model_ICTAC2021.zip.

Also noteworthy is that, in [29], if multiple variables need to be refined in one event, we refine one variable per refinement step; as a result, we refine the basic HSR model in 5 different refinement steps. Here, we refine all the variables

Table 11. Previous approach: the refinement of the HSF dimerization event. The variable hsf is replaced in all possible ways with $rhsf^{(0)}$ and $rhsf^{(1)}$, leading to 3 events.

| Dimerization Refinement-1 |
|---|
| WHERE |
| $@grd1$ rhsf ⁽⁰⁾ ≥ 2 |
| THEN |
| $@act1 rhsf^{(0)} := rhsf^{(0)} - 2$ |
| @act2 $rhsf_{2}^{(0)} := rhsf_{2}^{(0)} + 1$ |
| END |
| |
| |
| Dimerization Refinement-3 |
| Dimerization Refinement-3 WHERE |
| Dimerization Refinement-3 WHERE @grd1 rhsf ⁽⁰⁾ $\geq 1 \land$ rhsf ⁽¹⁾ ≥ 1 |
| $\begin{array}{l} \textbf{Dimerization Refinement-3}\\ \textbf{WHERE}\\ @grd1 \ rhsf^{(0)} \geq 1 \land rhsf^{(1)} \geq 1\\ \textbf{THEN} \end{array}$ |
| Dimerization Refinement-3 WHERE @grd1 rhsf ⁽⁰⁾ $\geq 1 \land rhsf^{(1)} \geq 1$ THEN @act1 rhsf ⁽⁰⁾ := rhsf ⁽⁰⁾ -1 |
| $\begin{array}{l} \textbf{Dimerization Refinement-3}\\ \textbf{WHERE}\\ @grd1 \ rhsf^{(0)} \geq 1 \land rhsf^{(1)} \geq 1\\ \textbf{THEN}\\ @act1 \ rhsf^{(0)} := rhsf^{(0)} - 1\\ @act2 \ rhsf^{(1)} := rhsf^{(1)} - 1 \end{array}$ |
| $\begin{array}{l} \textbf{Dimerization Refinement-3}\\ \textbf{WHERE}\\ @grd1 \ rhsf^{(0)} \geq 1 \land rhsf^{(1)} \geq 1\\ \textbf{THEN}\\ @act1 \ rhsf^{(0)} := rhsf^{(0)} - 1\\ @act2 \ rhsf^{(1)} := rhsf^{(1)} - 1\\ @act3 \ rhsf^{(1)}_2 := rhsf^{(1)}_2 + 1 \end{array}$ |

 $\begin{array}{l} \textbf{Dimerization Refinement-2}\\ \textbf{WHERE}\\ @grd1 \ rhsf^{(1)} \geq 2\\ \textbf{THEN}\\ @act1 \ rhsf^{(1)} := rhsf^{(1)} -2\\ @act2 \ rhsf^{(2)}_2 := rhsf^{(2)}_2 +1\\ \textbf{END} \end{array}$

of the event in one refinement step, since there are not so many new variables to handle and is conceptually clearer.

5 An Event-B model for the **ErbB** signalling pathway using functions

We extended the basic Event-B model of the ErbB signaling pathway presented in [17] to include details about epidermal growth factor receptor (EGFR) and epidermal growth factor (EGF). The epidermal growth factor receptor is refined

| Dimerization Refinement Symetric | Dimerization Refinement Asymetric |
|--|--------------------------------------|
| Any | WHERE |
| e, f | $@grd1 rhsf(HSF_0) \ge 1$ |
| WHERE | $@\mathbf{grd2} rhsf(HSF_1) \ge 1$ |
| $@\mathbf{grd1} rhsf(e) \geq 2$ | THEN |
| @grd2 $(e = HSF \ 0 \land f = HSF2 \ 0) \lor$ | $@act1 rhsf := rhsf \Leftrightarrow$ |
| $(e = HSF_1 \land f = HSF2_2)$ | $\{HSF_0\mapstorhsf(HSF_0)-1,$ |
| THEN | $HSF_1 \mapsto rhsf(HSF_1) - 1\}$ |
| @act1 rhsf(e) := rhsf(e) - 2 | $@act2$ rhsf2(HSF2_1) := |
| @act2 rhsf2(f) := rhsf2(f) + 1 | $rhsf2(HSF2_1)+1$ |
| END | END |

 Table 12. Current approach: the refinement of the HSF dimerization.

into the four receptor members of the ErbB family: ErbB1, ErbB2, ErbB3, ErbB4. Also, the epidermal growth factor is refined into two types: EGF and HRG. We refined all the reactions of the basic model of ErbB signaling pathway present in [17] where EGFR and EGF are present as a single species or present in the form of a dimer. This data refinement is presented as follows:

```
\begin{split} \mathsf{EGFR} & \rightarrow \{\mathsf{ErbB1}, \mathsf{ErbB2}, \mathsf{ErbB3}, \mathsf{ErbB4}\}; \\ \mathsf{EGF} & \rightarrow \{\mathsf{EGF}, \mathsf{HRG}\}. \end{split}
```

To refine the dimers, the two sets EGFEGFRrdim and EGFEGFRxrdim are each partitioned into eight, accounting for the eight possible forms of these dimers:

```
@axm3:
    partition(EGFEGFRrdim,{EGFErbB1dim}, {EGFErbB2dim},
        {EGFErbB3dim}, {EGFErbB4dim},{HRGErbB1dim},
        {HRGErbB2dim}, {HRGErbB3dim}, {HRGErbB4dim})
@axm4:
    partition(EGFEGFRxrdim,{EGFErbB1xdim}, {EGFErbB2xdim},
        {EGFErbB3xdim}, {EGFErbB4xdim}, {HRGErbB1xdim},
        {HRGErbB2xdim}, {HRGErbB1xdim},
        {HRGErbB2xdim}, {HRGErbB1xdim},
        {HRGErbB2xdim}, {HRGErbB1xdim},
        {HRGErbB2xdim},
        {HRGErbB2xdim},
        {HRGErbB2xdim},
        {HRGErbB2xdim},
        {HRGErbB2xdim},
        {HRGErbB2xdim},
        {HRGErbB4xdim},
        {HRGErb4xdim},
        {HRGErbB4xdim},
        {HRGErb4xdim},
```

 Table 13. Two events modeling the forward and reverse directions of the third reaction

 of the ErbB signaling pathway

| Rec3f | Rec3r |
|--------------------------------|--------------------------------|
| WHERE | WHERE |
| $@grd1 EGFEGFRdim \ge 1$ | $@$ grd1 EGFEGFRxdim ≥ 1 |
| THEN | THEN |
| @act1 | @act1 |
| EGFEGFRdim := EGFEGFRdim - 1 | EGFEGFRxdim := EGFEGFRxdim - 1 |
| @act2 | @act2 |
| EGFEGFRxdim := EGFEGFRxdim + 1 | EGFEGFRdim := EGFEGFRdim + 1 |
| END | END |

In the refined model, all events involving the variable-to-be-refined are replaced with new events. For example, consider the refinement of the events presented in the Table 13. The event **Rec3f** is replaced with event **Rec3f_Ref** while the event **Rec3r** is replaced with event **Rec3r_Ref**, shown in Table 14. The dimer of **EGFEGFRdim** is refined to 8 different species. In this refinement strategy, we only consider homodimers (with their two components identical). The second guard **grd2** of these events is important for the refinement as it covers all the refinement scenarios. This guard has eight different conditions which are to cover all homodimers. The benefit of using functions is also shown in this event. Had we not used functions, we would have had to include 8 new events for the refinement of event **Rec3f** and similarly 8 new events for the refinement of event **Rec3f**. Without using functions the refined model of **ErbB** signalling pathway present in [17] would have 1320 events but now it has 242 events, as many as the basic model. It also has 53 axioms and 110 variables (same number of invariants as well). All proof obligations were discharged automatically.

Table 14. Two events modeling the refinement of the forward and reverse directions of the third reaction of the ErbB signaling pathway

| Rec3f Ref | |
|---|---|
| ANY | Rec3r Ref |
| h, i | ANY - |
| WHERE | h, i |
| $@grd1 EGFEGFRdim(h) \ge 1$ | WHERE |
| @grd2 | $@grd1 EGFEGFRxdim(i) \ge 1$ |
| $(h = EGFErbB1dim \land i = EGFErbB1xdim) \lor$ | @grd2 |
| $(h = EGFErbB2dim \land i = EGFErbB2xdim) \lor$ | $(h = EGFErbB1dim \land i = EGFErbB1xdim) \lor$ |
| $(h = EGFErbB3dim \land i = EGFErbB3xdim) \lor$ | $(h = EGFErbB2dim \land i = EGFErbB2xdim) \lor$ |
| $(h = EGFErbB4dim \land i = EGFErbB4xdim) \lor$ | $(h = EGFErbB3dim \land i = EGFErbB3xdim) \lor$ |
| $(h = HRGErbB3dim \land i = HRGErbB3xdim) \lor$ | $(h = EGFErbB4dim \land i = EGFErbB4xdim) \lor$ |
| $(h = HRGErbB4dim \land i = HRGErbB4xdim) \lor$ | $(h = HRGErbB3dim \land i = HRGErbB3xdim) \lor$ |
| $(h = HRGErbB3dim \land i = HRGErbB3xdim) \lor$ | $(h = HRGErbB4dim \land i = HRGErbB4xdim) \lor$ |
| $(h = HRGErbB4dim \land i = HRGErbB4xdim)$ | $(h = HRGErbB3dim \land i = HRGErbB3xdim) \lor$ |
| THEN | $(h = HRGErbB4dim \land i = HRGErbB4xdim)$ |
| @act1 | THEN |
| EGFEGFRdim(h) := EGFEGFRdim(h) - 1 | @act1 EGFEGFRxdim(i) := EGFEGFRxdim(i) - 1 |
| @act2 | @act2 EGFEGFRdim(h) := EGFEGFRdim(h) + 1 |
| EGFEGFRxdim(i) := EGFEGFRxdim(i) + 1 | END |
| END | |

6 Discussion

Modeling and analyzing complex biological systems has never been as easy task. A solution to addressing complexity is to use refinement and start modeling from a conceptually simple (abstract) model that is consistent: all its properties of interest hold. Then, we can gradually add all the necessary details in a correctness-by-construction approach, so that the most detailed (concrete) model still preserves all properties of interest. When models are large and complex, size becomes a bottleneck and it is simply unfeasible to model without tool support. Fortunately, Event-B is a (state-based) formal method built on the idea of refinement and has a suitable toolset - Rodin. However, when used liberally and without proper planning, even Rodin cannot handle arbitrarily large models. We have encountered this problem two years ago when trying to model the ErbB signaling pathway in Event-B and the concrete model had 1320 reactions: Rodin could not handle it.

In this paper, we propose a modeling method that plays at Event-B's and Rodin's strengths: the high-level abstraction mechanisms, in particular using the common mathematical concept of function. The combinatorial explosion in the number of variables and events is generated in the case of data refinements. One species (protein, gene, etc) is to be replaced by a number of subspecies and each event involving the original species is refined by a set of events. This set is potentially as big as the number of subspecies or, if there is more than one species refined in one event, then the set can be as big as the product of the numbers of subspecies. Clearly, biology is so complex that we would have very soon a combinatorial explosion of variables modeling subspecies and events handling their reactions.

Our proposal is to go more abstract ('higher-level') and replace each species to be refined by a function defined on the constant set of all the subspecies. This simple artifact lets us express almost all the complexity in the event guards, where we can have many cases and combinations of parameters. Event-B and Rodin excel at handling guards and suddenly we have only a slight increase in the number of events, while the number of variables remains constant.

Our approach in this paper is demonstrated through two case studies, the heat shock response and the ErbB signaling pathway, both simplified enough to prove our point. Thus, we offer a proof-of-concept that our solution is viable, as its evaluation on the two case studies indicates.

The impact of this approach on future models of complex biological systems is significant. If we can start modeling from a conceptually simple but still consistent version of our system of interest, then we can add the necessary details via refinement, but so that we capture the main complexity in guards, via the high-level abstraction provided by functions. Size-wise, our models would remain manageable and still very expressive, albeit in a disciplined manner. Meanwhile, in this paper, we constructed the largest Event-B model ever built.

Acknowledgment Ion Petre was partially supported by the Romanian Ministry of Education and Research, CCCDI – UEFISCDI, project number PNIII-P2-2.1-PED-2019-2391, within PNCDI III.

References

- Jean-Raymond Abrial. The B-book: Assigning Programs to Meanings. Cambridge University Press, New York, NY, USA, 1996.
- Jean-Raymond Abrial. Modeling in Event-B: System and Software Engineering. Cambridge University Press, New York, NY, USA, 1st edition, 2010.
- Jean-Raymond Abrial, Michael Butler, Stefan Hallerstede, Thai Son Hoang, Farhad Mehta, and Laurent Voisin. Rodin: an open toolset for modelling and reasoning in Event-B. STTT, 12(6):447–466, 2010.
- Ralph-Johan Back and Reino Kurki-Suonio. Decentralization of process nets with centralized control. In *Proceedings of the Second Annual ACM Symposium on Principles of Distributed Computing*, PODC '83, pages 131–142, New York, NY, USA, 1983. ACM.
- Ralph-Johan Back and Kaisa Sere. Superposition refinement of reactive systems. Formal Aspects of Computing, 8:324–346, 1996.
- Marc R Birtwistle, Mariko Hatakeyama, Noriko Yumoto, Babatunde A Ogunnaike, Jan B Hoek, and Boris N Kholodenko. Ligand-dependent responses of the erbb signaling network: experimental and modeling analyses. *Molecular systems biology*, 3:144, 2007.

- 7. Michael Butler and Divakar Yadav. An incremental development of the mondex system in Event-B. Formal Aspects of Computing, 20(1):61–77, 2007.
- William W Chen, Birgit Schoeberl, Paul J Jasper, Mario Niepel, Ulrik B Nielsen, Douglas A Lauffenburger, and Peter K Sorger. Input–output behavior of erbb signaling pathways as revealed by a mass action model trained against dynamic data. *Molecular Systems Biology*, 5, 2009.
- Vincent Danos, Jérôme Feret, Walter Fontana, Russ Harmer, and Jean Krivine. Rule-based modelling and model perturbation. In *Transactions on Computational Systems Biology XI*, pages 116–137. Springer, 2009.
- Diana-Elena Gratie, Bogdan Iancu, Sepinoud Azimi, and Ion Petre. Quantitative model refinement in four different frameworks, with applications to the heat shock response. In Luigia Petre and Emil Sekerinski, editors, *From Action Systems to Distributed Systems*, pages 201–214. Taylor&Francis, 2016.
- Diana-Elena Gratie and Ion Petre. Hiding the combinatorial state space explosion of biomodels through colored petri nets. Annals of University of Bucharest, LXI:23– 41, 2014.
- Thai Son Hoang, Hironobu Kuruma, David Basin, and Jean-Raymond Abrial. Developing topology discovery in Event-B. In Michael Leuschel and Heike Wehrheim, editors, *Integrated Formal Methods*, volume LNCS 5423, pages 1–19, Berlin, Heidelberg, 2009. Springer Berlin Heidelberg.
- C.A.R. Hoare, H.E. Jifeng, and J.W. Sanders. Prespecification in data refinement. Information Processing Letters, 25(2):71–76, 1987.
- Jorrit J Hornberg, Bernd Binder, Frank J Bruggeman, Birgit Schoeberl, Reinhart Heinrich, and Hans V Westerhoff. Control of MAPK signalling: from complexity to what really matters. *Oncogene*, 24(36):5533–5542, 2005.
- Seppo Horsmanheimo, Maryam Kamali, Mikko Kolehmainen, Mats Neovius, Luigia Petre, Mauno Rönkkö, and Petter Sandvik. On proving recoverability of smart electrical grids. In NASA Formal Methods - 6th International Symposium, NFM 2014, Houston, TX, USA, April 29 - May 1, 2014. Proceedings, pages 77–91, 2014.
- Bogdan Iancu, Elena Czeizler, Eugen Czeizler, and Ion Petre. Quantitative refinement of reaction models. *International Journal of Unconventional Computing*, 8(5-6):529–550, 2012.
- Bogdan Iancu, Usman Sanwal, Cristian Gratie, and Ion Petre. Refinement-based modeling of the erbb signaling pathway. *Computers in Biology and Medicine*, 106:91 – 96, 2019.
- Maryam Kamali, Linas Laibinis, Luigia Petre, and Kaisa Sere. Self-recovering sensor-actor networks. In Proceedings Ninth International Workshop on the Foundations of Coordination Languages and Software Architectures, FOCLASA 2010, Paris, France, 4th September 2010., pages 47–61, 2010.
- Mojgan Kamali, Peter Höfner, Maryam Kamali, and Luigia Petre. Formal analysis of proactive, distributed routing. In Software Engineering and Formal Methods - 13th International Conference, SEFM 2015, York, UK, September 7-11, 2015. Proceedings, pages 175–189, 2015.
- Shmuel Katz. A superimposition control construct for distributed systems. ACM Trans. Program. Lang. Syst., 15(2):337–356, April 1993.
- Boris N. Kholodenko, Oleg V. Demin, Gisela Moehren, and Jan B. Hoek. Quantification of short term signaling by the epidermal growth factor receptor. *Journal* of *Biological Chemistry*, 274(42):30169–30181, 1999.
- Edda Klipp, Ralf Herwig, Axel Kowald, Christoph Wierling, and Hans Lehrach, editors. Systems Biology in Practice: Concepts, Implementation and Application. Wiley-Blackwell, 2006.

- 18 Usman Sanwal, Thai Son Hoang, Luigia Petre, and Ion Petre
- Arnaud Lanoix. Event-B specification of a situated multi-agent system: Study of a platoon of vehicles. In *Theoretical Aspects of Software Engineering*, pages 297–304, Los Alamitos, CA, USA, 2008. IEEE Computer Society.
- Kanae Oda, Yukiko Matsuoka, Akira Funahashi, and Hiroaki Kitano. A comprehensive pathway map of epidermal growth factor receptor signaling. *Molecular* Systems Biology, 1(1), 2005.
- Ion Petre, Andrzej Mizera, Claire L. Hyder, Annika Meinander, Andrei Mikhailov, Richard I. Morimoto, Lea Sistonen, John E. Eriksson, and Ralph-Johan Back. A simple mass-action model for the eukaryotic heat shock response and its mathematical validation. *Natural Computing*, 10(1):595–612, 2011.
- Luigia Petre, Petter Sandvik, and Kaisa Sere. Node coordination in peer-to-peer networks. In Coordination Models and Languages - 14th International Conference, COORDINATION 2012, Stockholm, Sweden, June 14-15, 2012. Proceedings, pages 196-211, 2012.
- Marissa V. Powers and Paul Workman. Inhibitors of the heat shock response: Biology and pharmacology. *{FEBS} Letters*, 581(19):3758 – 3769, 2007. Cellular Stress.
- 28. Asieh Salehi Fathabadi, Abdolbaghi Rezazadeh, and Michael Butler. Applying atomicity and model decomposition to a space craft system in Event-B. In Mihaela Bobaru, Klaus Havelund, Gerard J. Holzmann, and Rajeev Joshi, editors, NASA Formal Methods, pages 328–342, Berlin, Heidelberg, 2011. Springer Berlin Heidelberg.
- 29. Usman Sanwal, Luigia Petre, and Ion Petre. Stepwise construction of a metabolic network in event-b. *Computers in Biology and Medicine*, 91(C):1–12, 2017.
- Birgit Schoeberl, Claudia Eichler-Jonsson, Ernst Dieter Gilles, and Gertraud Müller. Computational modeling of the dynamics of the map kinase cascade activated by surface and internalized egf receptors. *Nature Biotechnology*, 20:370 EP -, 2002.
- Richard Voellmy. Transduction of the stress signal and mechanisms of transcriptional regulation of heat shock/stress protein gene expression in higher eukaryotes. Critical reviews in eukaryotic gene expression, 4(4):357-401, 1994.