

Digital Object Identifier 10.1109/ACCESS.2021.3106717

EDITORIAL

IEEE ACCESS SPECIAL SECTION EDITORIAL: ADVANCED ARTIFICIAL INTELLIGENCE TECHNOLOGIES FOR SMART MANUFACTURING

I. INTRODUCTION

Industry 4.0, also known as the fourth industrial revolution, is an area that many scientists and manufacturers are pursuing. Industry 4.0 consists of many topics such as the Internet of things (IoT), big data, cloud computing, smart manufacturing, and so on. Smart manufacturing is a crucial and valuable topic which aims at developing advanced techniques to improve the quality and costs of manufacturing. Through sensors, networks, and high-performance computers, powerful algorithms for smart manufacturing can be developed and implemented. Thanks to an innovative variety of sensors, reliable, and high-resolution information can be collected and utilized. Networks allow signals to be exchanged quickly between sensors, machines, and computers. Artificial intelligence (AI) requires huge computation power. Modern computers provide graphic cards with parallel computing, breaking this restriction. Algorithms related to smart manufacturing will be more complicated than before. As a result, this Special Section aims to speed up the development of smart manufacturing, attract the attention of communities, and disseminate novel research.

This IEEE ACCESS Special Section includes ten research articles with different innovative topics to help readers gain insight into this domain and to boost and inspire their research. These accepted articles were reviewed by professional and independent researchers. A brief introduction to each of these articles follows.

The first article “The optimization of lathe cutting parameters using a hybrid Taguchi-genetic algorithm,” by Chu *et al.*, uses the multi-objective hybrid Taguchi-genetic algorithm (HTGA) to search for the best processing parameters. A linear regression model is defined by the processed quality and the processing parameters. Then, HTGA is used to optimize the parameters. The experimental results show that HTGA surpasses conventional genetic on convergence rate and robustness.

The second article “A high-precision random forest-based maximum Lyapunov exponent prediction model for spherical porous gas bearing systems,” by Kuo *et al.*, proposes a high-precision machine learning-based maximum Lyapunov exponents (MLEs) prediction model for spherical porous gas bearing (SPAB) systems. In this article, the governing

equations of the SPAB system are solved to acquire dynamic behaviors. By generating MLEs, the performance of different conditions can be examined. The experimental results show the efficiency and high accuracy of the proposed method.

The third article “Sliding mode observer based multi-layer metal plates core temperature on-line estimation for semiconductor intelligence manufacturing,” by Tsai and Peng, applies a new sliding mode observer (SMO) proposed to cope with unknown system interference. The experimental results show that the proposed SMO accurately estimates core temperature.

The fourth article “Intelligence bearing fault diagnosis model using multiple feature extraction and binary particle swarm optimization with extended memory,” by Lee and Le, proposes an effective bearing fault diagnosis model based on multiple extraction and selection techniques. The proposed model excels compared to the other five models under different conditions.

The fifth article “Drill fault diagnosis based on the scalogram and mel spectrogram of sound signals using artificial intelligence,” by Tran and Lundgren, proposes a method that uses deep learning architecture to extract rich features from the image representation of sound signals combined with machine learning classifiers to classify drill fault sounds of drilling machines.

The sixth article “Industrial artificial intelligence in industry 4.0—Systematic review, challenges and outlook,” by Peres *et al.*, reviews current industrial artificial intelligence research. The challenges and outlook are also described to guide researchers for future works.

The seventh article “Adaptive vision-based method for rotor dynamic balance system,” by Chung and Chen, proposes a new adaptive vision-based method (AVBM) to automatically detect rotor balancing. The experimental results of industrial examples indicate that AVBM is better than conventional methods in different aspects.

The eighth article “Fault diagnosis of bearings based on multi-sensor information fusion and 2D convolutional neural network,” by Wang *et al.*, proposes a convolutional neural network (CNN)-based method for fault diagnosis of industrial equipment represented by bearings. A new multi-sensor

information fusion provides high-quality signals for CNN. The proposed CNN model performs high prediction accuracy on a bearing database and a dataset from designed bearing fault test rig.

The ninth article “Probabilistic indoor positioning and navigation (PIPn) of autonomous ground vehicle (AGV) based on wireless measurements,” by Lin *et al.*, proposes a method for wireless indoor positioning and navigation of autonomous ground vehicles. The proposed method is tested by two trajectories and shows promising experimental results.

The tenth article “An end-to-end intelligent fault diagnosis application for rolling bearing based on MobileNet,” by Yu and Lv, proposed a lightweight convolutional neural network MobileNet for fault diagnosis. The lightweight model enables it to implement in an end-to-end system to classify faults.

Finally, the editors would like to express gratitude for the authors’ enthusiastic participation and contributions to this IEEE ACCESS Special Section. They are also grateful to the IEEE ACCESS editorial staff who helped to support this Special Section.

HER-TERNG YAU, *Lead Editor*
Department of Mechanical Engineering
National Chung Cheng University
Chiayi 621301, Taiwan

STEPHEN D. PRIOR, *Guest Editor*
Faculty of Engineering and Physical Sciences
Aeronautics, Astronautics and
Computational Engineering
University of Southampton
Southampton SO17 1BJ, U.K.

YANG WANG, *Guest Editor*
School of Civil and Environmental Engineering
School of Electrical and Computer Engineering
Georgia Institute of Technology
Atlanta, GA 30332, USA

YUNHUA LI, *Guest Editor*
Department of Mechanical Engineering
Beihang University
Beijing 100191, China



HER-TERNG YAU (Senior Member, IEEE) received the B.S. degree in mechanical engineering from National Chung Hsing University, Taichung, Taiwan, in 1994, and the M.S. and Ph.D. degrees in mechanical engineering from National Cheng Kung University, Tainan, Taiwan, in 1996 and 2000, respectively. He is currently a Professor with the Department of Mechanical Engineering, National Chung Cheng University, Chiayi, Taiwan. He is the author of more than 200 research articles on a wide variety of topics in mechanical and electrical engineering. His research interests include AI applications, systems control of mechatronics, nonlinear systems analysis, and control. He obtained the honor of IET Fellow, in 2018. He has been a Technical Editor of IEEE/ASME TRANSACTIONS ON MECHATRONICS, since 2020.



STEPHEN D. PRIOR received the B.Eng. degree in mechanical engineering and the Ph.D. degree in robotics from Middlesex University, London, in 1987 and 1993, respectively. He was the Project Lead of the MoD Grand Challenge i-Spy Team, in 2008 and was the Team Leader for Team HALO. He is a Reader in unmanned air vehicles with the Faculty of Engineering and Physical Sciences, University of Southampton. He is a Chartered Mechanical Engineer, a Corporate Member of the IMechE, and a fellow of the Higher Education Academy. He is also a Non-Executive Director of Tethered Drone Systems, Ltd. His research interests are in the areas of aeronautics, autonomous unmanned systems, robotics, and design engineering. He was the winner of the DARPA UAVForge Competition 2012. He has been an Editor of the *International Journal of Micro Air Vehicles*, since 2010 and *Unmanned System Journal*, since 2013.



YANG WANG received the B.S. and M.S. degrees in civil engineering from Tsinghua University, Beijing, China, and the Ph.D. degree in civil and environmental engineering and the M.S. degree in electrical engineering from Stanford University, in 2007.

He joined Georgia Tech, in 2007. He is currently an Adjunct Associate Professor in ECE and an Associate Professor in civil and environmental engineering with Georgia Tech. His research is dedicated to exploring state-of-the-art sensing, control, and information technologies for the development of future smart structural systems. His work encompasses structural sensing, identification, monitoring, and control. He received an NSF Early Faculty Career Development (CAREER) Award, in 2012 and a Young Investigator Award from the Air Force Office of Scientific Research (AFOSR), in 2013. Since 2011, he has been serving as an Associate Editor for the *Journal of Bridge Engineering* (ASCE). He also served as a Guest Editor for Special Issues of IEEE/ASME TRANSACTIONS ON MECHATRONICS and the *International Journal of Intelligent Robotics and Applications*.



YUNHUA LI (Senior Member, IEEE) received the M.S. degree in mechanical engineering from Jilin University of Technology, Changchun, China, in 1988, and the Ph.D. degree in mechatronics from Xi'an Jiaotong University, Xi'an, China, in 1994.

He has been a Full Professor of mechanical engineering with Beihang University, since 1999. In 2008, as a Senior Research Fellow, he visited George Woodruff School of Mechanical Engineering, Georgia Institute of Technology, for three months. His research interests include nonlinearity dynamics and control, power transmission and control, network-based motion and control, and vehicle and construction machinery. From 2010 to 2014, he was a Technical Editor of IEEE/ASME TRANSACTIONS ON MECHATRONICS. He is currently a Senior Editor of IEEE/ASME TRANSACTIONS ON MECHATRONICS.

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