# Active-RIS Enhances the Multi-User Rate of Multi-Carrier Communications

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Abstract—This paper explores a multi-user multi-carrier system leveraging an active reconfigurable intelligent surface (RIS), where the joint design of the RIS's programmable reflecting elements and the subcarrier-wise beamformers at the base station is investigated. To overcome the limitation of the conventional design, which aims solely at sum-rate maximization resulting in zero rates for some users across all sub-carriers and thus failing to boost all users rates, we propose the two alternative designs: one maximizing the geometric mean of the users' rates (GM-rate maximization) and the other maximizing the soft users' minimum rate (soft max-min rate optimization). However, they pose challenges as large-scale nonconvex problems, rendering convex-solver computational approaches impractical. To tackle this, we develop iterative computational procedures based on closed-form expressions of scalable complexity. Extensive simulations demonstrate the substantial benefits of these novel designs in significantly enhancing multi-user rates. Notably, under the same power budget, the active-RIS-assisted multi-carrier system achieves approximately twice the minimum user-rate or sum rate compared to RIS-less or passive-RIS-assisted counterparts.

*Index Terms*—Active reconfigurable intelligent surface, multicarrier communication, subcarrier-wise beamforming, multi-user rate enhancement, large-scale computation

#### I. INTRODUCTION

Reconfigurable intelligent surfaces (RISs) have shown great promise in enhancing the performance of future wireless communication networks by enabling the controlled reflection of incident waves in desired directions [1]–[3]. To date, passive RISs with programmable reflecting elements (PREs) have been extensively studied owing to their low power consumption [4]– [12]. However, the signals reflected by passive RISs encounter double path loss (multiplicative fading) and experience notable attenuation [13], thereby limiting their overall impact. The concept of an active-RIS, which facilitates power amplification of incident signals, has been introduced in [14], [15] to to

<sup>1</sup>School of Electrical and Data Engineering, University of Technology Sydney, Broadway, NSW 2007, Australia (email: tuan.hoang@uts.edu.au, eryk.dutkiewicz@uts.edu.au); <sup>2</sup>Department of Electrical Engineering and Center for Communication Systems and Sensing, King Fahd University of Petroleum and Minerals, Dhahran 31261, Saudi Arabia (email: anasir@kfupm.edu.sa); <sup>3</sup>The department of Electrical and Computer Engineering, Princeton University, Princeton, NJ 08544, USA (email: poor@princeton.edu). <sup>4</sup>School of Electronics and Computer Science, University of Southampton, Southampton, SO17 1BJ, U.K. (e-mail: h@ecs.soton.ac.uk). address this double path-loss phenomenon. Previous studies [15]–[17] have explored the joint design of transmit multiuser beamformers and the active RISs PREs to maximize the multi-user (MU) sum-rate (SR).

The employment of multi-carrier (MC) communication based on orthogonal frequency division multiplexing (OFDM) techniques to combat frequency-selective multi-path propagation is crucial for meeting the demands of high-data-rate applications [18]. Considering passive-RIS aided MC communication, recent papers have considered the design of the PREs for RIS-assisted single-user OFDM [19]-[22], for orthogonal frequency division multiple access (OFDMA) [23]-[26], and for MU OFDM [27], [28]. In particular, the authors of [27] addressed such joint design to maximize the SR. However, as observed in [29], maximizing the SR leads to zero rates across all frequency bands for certain users, failing to enhance rates for all users and thus is unsuitable for MU OFDM. Max-min rate optimization, which aims to maximize the users' minimum rate (MR), is a systematic approach for enhancing MU rates. However, it involves a nonsmooth optimization problem that is computationally challenging [28]. Building on the approaches to enhance MU rates in single-carrier scenarios [10], [11], the work [28] has proposed an approach to enhance MU rates in MC scenarios by maximizing the geometric mean of users rates (GM-rate). Leveraging the smoothness of the GM-rate objective, GM-rate maximization facilitates tractable computation through iterating closed-form expressions of scalable complexity. The joint design of the PREs and transmit beamformers for active RIS-assisted MC communication was recently considered in [30], aiming to maximize the SR. Beside failing to enhance all users rates, the computation method in [30] suffers from impractical computational complexity. For instance, in a scenario of 64 subcarries, 10 transmit antennas, and 10 users, the method in [30] necessitates iterating convex problems of  $64 \times 10 \times 10 = 6400$  decision variables for subcarrier-wise beamforming alternating optimization.

Against the above background, this paper presents the first comprehensive investigation into the potential of an *active-RIS-assisted MC communication system* conceived for delivering high rates to all users. By contrast, when the sum-rate of a system is optimized, typically the users having high channel-quality are granted a high rate while some others might have near-zero rate. The contributions of this paper can be summarized as follows:

• We present a joint design of the active-RIS PREs and of the MU transmit beamformers at the base station (BS) to maximize the GM-rate. We develop a computational solution that iteratively improves both the PREs and MU beamformers using closed-form expressions. Notably,

This work was supported in part by the Australian Research Council's Discovery Projects under Grant DP190102501, in part by the Deanship of Research Oversight and Coordination (DROC) at KFUPM for funding under the Interdisciplinary Research Center for Communication Systems and Sensing through project No. INCS2403, in part by the U.S National Science Foundation under Grants CNS-2128448 and ECCS-2335876, and in part by the Engineering and Physical Sciences Research Council projects EP/W016605/1, EP/X01228X/1, EP/Y026721/1 and EP/W032635/1 as well as of the European Research Council's Advanced Fellow Grant QuantCom (Grant No. 789028)

these iterations are computationally tractable even for large-scale networks.

- We also propose another optimization problem, referred to as "soft max-min (SMM) rate optimization," which is based on a smooth and approximate lower bound of the non-smooth MR function. We develop a computational solution for this problem relying on the iterative evaluation of closed-form expressions. Our simulation results demonstrate that the SMM-rate optimization further improves both the MR and SR, when it is initialized by the solution gleaned from GM-rate maximization.
- Our simulations demonstrate that the active-RIS-assisted MU MC system conceived achieves approximately twice the MR or SR compared to the RIS-less or passive-RISassisted MU MC system, given the same total powerbudget. We also observe that conventional SR maximization is not suitable for active-RIS-assisted MU OFDM, as it results in near-zero rates for certain users. By contrast, both GM-rate and SMM-rate optimizations effectively address this issue while maintaining a good SR. More particularly, SMM-rate optimization closely matches the SR provided by SR maximization, especially at higher total power budgets or with a larger number of transmit antennas at the BS.

In conclusion, Table I provides a concise and comprehensive comparison of our novel contributions to the literature.

The paper is organized as follows. Section II presents the system model and problem statement. Sections III and IV propose closed-form expression-based algorithms of scalable complexity for solving the GM-rate and SMM-rate optimization problems, respectively. Our simulation results are discussed in Section V, followed by our conclusions in Section VI.

Notation. Boldfaced letters are used for decision variables;  $I_N$  is the identity matrix of size  $N \times N$ . For  $x = (x_1, \ldots, x_n)^T$ , diag(x) represents a diagonal matrix of the size  $n \times n$  with  $x_1, \ldots, x_n$  on its diagonal. The notation ||x|| denotes the Euclidean norm of the vector x. The notation  $X \succeq 0$  ( $X \succ 0$ , resp.) for the Hermitian symmetric matrix X means that it is positive semi-definite (positive definite, resp.). Lastly,  $F_S$  is the fast Fourier transform (FFT) matrix of order S defined as

$$F_S \triangleq \frac{1}{\sqrt{S}} \left[ e^{-j2\pi kp/S} \right]_{k,p=0,1,\dots,S-1}$$

Note that  $F_S$  is unitary  $F_S F_S^H = I_S$  so  $F_S^H$  is called the inverse FFT (IFFT) matrix. Table II provides a summary of the basic notations used in the paper.

Tight minorant maximization and tight majorant minimization as key ingredients. For all  $\mathbf{v} \in \mathbb{C}$ ,  $\mathbf{y} > 0$ , and  $\bar{v} \in \mathbb{C}$ ,  $\bar{y} > 0$ , the following inequality holds [33]:

$$\ln\left(1+\frac{|\mathbf{v}|^2}{\mathbf{y}}\right) \ge \ln\left(1+\frac{|\bar{v}|^2}{\bar{y}}\right) - \frac{|\bar{v}|^2}{\bar{y}} + 2\frac{\Re\{\bar{v}^*\mathbf{v}\}}{\bar{y}} - \frac{|\bar{v}|^2}{\bar{y}(|\bar{v}|^2+\bar{y})}(|\mathbf{v}|^2+\mathbf{y}).$$
(1)

The right-hand side (RHS) of (1) matches its left-hand side (LHS) at  $(\mathbf{v}, \mathbf{y}) = (\bar{v}, \bar{y})$ , so the former provides a tight

minorant of the latter [34]. As such maximizing the former, called tight minorant maximization, helps to generate a better point than  $(\bar{v}, \bar{y})$  for the latter.

Over the domain dom  $\triangleq \{(\boldsymbol{x}_k, \mathbf{y}_k) \in \mathbb{C} \times \mathbb{R} : \mathbf{y}_k \geq |\boldsymbol{x}_k|^2, k = 1, ..., K\}$ , the following inequality holds true for all c > 0:

$$\ln\left(1 + \frac{1}{c}\sum_{k=1}^{K}\left(1 - \frac{|\boldsymbol{x}_{k}|^{2}}{|\boldsymbol{y}_{k}}\right)\right) \leq (2a)$$

$$\ln\left(1 + \frac{1}{c}\sum_{k=1}^{K}\left(1 - \frac{|\bar{x}_{k}|^{2}}{|\bar{y}_{k}}\right)\right)$$

$$+ \left(c + \sum_{k=1}^{K}\left(1 - \frac{|\bar{x}_{k}|^{2}}{|\bar{y}_{k}}\right)\right)^{-1}\sum_{k=1}^{K}\frac{|\bar{x}_{k}|^{2}}{|\bar{y}_{k}}$$

$$- \left(c + \sum_{k=1}^{K}\left(1 - \frac{|\bar{x}_{k}|^{2}}{|\bar{y}_{k}}\right)\right)^{-1}$$

$$\times \sum_{k=1}^{K}\left(\frac{2\Re\left\{\bar{x}_{k}^{H}\boldsymbol{x}_{k}\right\}}{|\bar{y}_{k}} - \frac{|\bar{x}_{k}|^{2}}{(\bar{y}_{k})^{2}}\boldsymbol{y}_{k}\right). \quad (2b)$$

In fact, the function defined by (2b) is the linearization of that defined by (2a) at  $(\bar{x}_k, \bar{y}_k), k = 1, ..., K$ . Since the former is concave, it provides a tight majorant of the latter [34]. As such minimizing the former, called tight majorant minimization, helps to generate a better point than  $(\bar{x}, \bar{y})$  for the latter.

#### II. ACTIVE-RIS AIDED OFDM SYSTEM



Fig. 1: Active RIS-assisted communication network

We consider the active-RIS-assisted MU MC system illustrated by Fig. 1, where an active-RIS of N reflecting units supports downlink transmission from an  $N_t$ -antenna array aided base station (BS) to K single-antenna users (UEs)  $k \in \mathcal{K} \triangleq \{1, \ldots, K\}$ . It is reasonable to assume the presence of a line-of-sight (LoS) link between the BS and RIS as well as between the RIS and UEs because the RIS is frequently installed on the facade of high-rise buildings and the BS is also normally at a particular elevated height [2].

We consider signal propagation subject to multi-path effects, resulting in frequency-selective channels. We denote the channel gain matrix of the  $\ell$ -th multiple-input multiple-output (MIMO) path between the BS and the RIS by  $\tilde{G}_{\text{B-R},\ell} = \sqrt{\beta_{\text{B-R}}}G_{\text{B-R},\ell} \in \mathbb{C}^{N \times N_t}$ . Similarly,  $\tilde{g}_{\text{R-k},\ell} = \sqrt{\beta_{\text{R-k}}}g_{\text{R-k},\ell} \in \mathbb{C}^{N \times N_t}$ .

Literature	This work	[10] [22]	[21] [22]	[20]	[27]	[15] [17]
Contents	THIS WOLK	[19]-[22]	[31], [32]	[29]	[27]	[13]-[17]
MU MC	$\checkmark$		$\checkmark$	$\checkmark$		
Passive-RIS aided single-user MC		$\checkmark$				
Passive-RIS aided MU MC	$\checkmark$					
Active-RIS aided MU single-carrier	$\checkmark$					$\checkmark$
SR maximization	$\checkmark$		$\checkmark$			$\checkmark$
Active-RIS aided MU MC	$\checkmark$					
Individual rate enhancement	$\checkmark$					
Tractable large-scale computation	$\checkmark$					

TABLE I: Comparing our innovative contributions to the relevant literature.

**TABLE II: Basic Notations** 

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Notation	Description
$N_t/\mathcal{N}_t$	# of BS's transmit antennas / index set $\{1, \ldots, N_t\}$
$K/\mathcal{K}$	# of users / index set $\{1, \ldots, K\}$
N/N	# of active-RIS PREs / index set $\{1, \ldots, N\}$
S/S	# of subcarriers / index set $\{1, \ldots, S\}$
$L_1/L_2/L_3$	memory of the multipath BS-RIS / RIS-UE / BS-UE channel
L	$\max\{L_1 + L_2 - 1, L_3\}$
$oldsymbol{v}  riangleq (oldsymbol{v}_1, \dots, oldsymbol{v}_N)^T$	design vector of active PREs
$oldsymbol{\Upsilon}  riangleq diag\left(oldsymbol{v} ight)$	design PREs' reflection coefficient matrix
$\mathbf{w}_k(s) \triangleq \left(\mathbf{w}_{k,1}(s), \dots, \mathbf{w}_{k,N_t}(s)\right)^T$	user k' beamformer over subcarrier s
$\mathbf{w}(s) \triangleq (\mathbf{w}_1(s), \dots, \mathbf{w}_{N_t}(s))^T$	cascaded vectors for all UEs' beamformers over subcarrier s
$\mathbf{w}  riangleq \{\mathbf{w}(s), s \in \mathcal{S}\}$	set of all beamformers
$w^{( au)}/v^{( au)}$	generated values of $\mathbf{w}/\mathbf{\Upsilon}$ at the $(\tau - 1)$ -st round
$r_{k,s}(\mathbf{w}, oldsymbol{v})$	achievable throughput of UE $k$ over subcarrier $s$
$r_k(\mathbf{w},oldsymbol{v})$	total achievable throughput of UE $k$
$P_{\rm BS}/P_{\rm A}$	maximum transmit power budget at the BS / the active RIS

 $\mathbb{C}^{1\times N}$  represents the channel gain co-vector of the  $\ell$ -th multiple-input single-output (MISO) path between the RIS and UE k, and  $\tilde{g}_{\text{B-k},\ell} = \sqrt{\beta_{\text{B-k}}}g_{\text{B-k},\ell} \in \mathbb{C}^{1\times N_t}$  represents the channel co-vector of the  $\ell$ -th MISO path between the BS and UE k, where  $\beta_{\text{B-R}}$ ,  $\beta_{\text{R-k}}$ , and  $\beta_{\text{B-k}}$  represent the pathloss and large-scale fading of the BS-to-RIS link, the RISto-UE k link, and the BS-to-UE k link. Furthermore, due to the presence of the LoS link between the BS and the RIS and that between the RIS and UE k, their first respective channel paths,  $G_{\text{B-R},0} \in \mathbb{C}^{N\times N_t}$  and  $h_{\text{R-k},0} \in \mathbb{C}^{1\times N}$  are modeled by Rician fading, while the remaining channel paths  $G_{\text{B-R},\ell} \in \mathbb{C}^{N\times N_t}$ , for  $\ell \neq 0$ , and  $g_{\text{R-k},\ell} \in \mathbb{C}^{1\times N}$ , for  $\ell \neq 0$ , are modeled by Rayleigh fading [19]. On the other hand, all channel propagation paths between the BS and UE k,  $g_{\text{B-k},\ell} \in \mathbb{C}^{1\times N_t}$ , for all  $\ell$ , follow Rayleigh fading to model the non-LoS propagation paths between the BS and UE k [19].

The frequency selective channels from the BS to RIS, from the RIS to UE k, and from the BS to UE k are characterized by the following transfer co-vector functions:

$$\begin{split} \bar{G}_{\text{B-R}}(z) &\triangleq \sum_{\ell=0}^{L_1-1} \tilde{G}_{\text{B-R},\ell} z^{-\ell}, \\ \bar{g}_{\text{R-k}}(z) &\triangleq \sum_{\ell=0}^{L_2-1} \tilde{g}_{\text{R-k},\ell} z^{-\ell}, \\ \bar{g}_{\text{B-k}}(z) &\triangleq \sum_{\ell=0}^{L_3-1} \tilde{g}_{\text{B-k},\ell} z^{-\ell}, \end{split}$$

where  $L_1$ ,  $L_2$ , and  $L_3$  respectively define the memory of the multipath BS-RIS channel, the multipath RIS-UE channel, and the multipath BS-UE channel. Similar to numerous prior studies on RIS-aided beamforming [16], [17], [25], [27], the assumption of perfect CSI at the BS is commonly stipulated in order to evaluate the limit on the performance of the RIS-aided multi-user network. Tailor-made channel estimation solutions developed for RIS-aided networks can be harnessed for acquiring the CSI [23], [35]–[37].

For  $n \in \mathcal{N} = \{1, \dots, N\}$ , let  $v_n = a_n \theta_n$ , be the reflection coefficient of the *n*-th PRE at the active-RIS with  $a_n$  and  $\theta_n$  representing its amplification factor and phase. Accordingly, we have

$$\Upsilon \triangleq \mathsf{diag}\left(\boldsymbol{\upsilon}\right),\tag{3}$$

with  $\boldsymbol{v} = (\boldsymbol{v}_1, \dots, \boldsymbol{v}_N)^T \in \mathbb{C}^N$  is referred to as the PREs' reflection coefficient matrix. It is noteworthy that under active-RIS, the amplification factor  $a_n$  can be higher than one due to the use of an integrated reflection-type amplifier [15].

The composite channel spanning from the BS to UE k will also be frequency-selective and characterized by the transfer co-vector function

$$\hbar_k(z) = \bar{g}_{\mathbf{R}\cdot\mathbf{k}}(z)\mathbf{\Upsilon}\bar{G}_{\mathbf{B}\cdot\mathbf{R}}(z) + \bar{g}_{\mathbf{B}\cdot\mathbf{k}}(z) \in \mathbb{C}^{1 \times N_t}.$$
(4)

Let us assume that the system has  $S = 2^Z$  sub-carriers, for some positive integer Z. At the *i*-th transmit antenna with  $i \in \mathcal{N}_t \triangleq \{1, \ldots, N_t\}$ , each block of information

$$x_i \triangleq \begin{bmatrix} x_i(0) \\ \dots \\ x_i(S-1) \end{bmatrix}$$

of length S is processed by an orthogonal frequency division multiplexing (OFDM) operator to form an OFDM block of

$$\tilde{x}_i \triangleq \begin{bmatrix} x_{i,T} \\ x_{i,H} \\ x_{i,T} \end{bmatrix} \in \mathbb{C}^{S+L}$$

with

$$\begin{bmatrix} x_{i,H} \\ x_{i,T} \end{bmatrix} = F_S^H x_i, x_{i,H} \in \mathbb{C}^{S-L}, x_{i,T} \in \mathbb{C}^L,$$

where the OFDM cyclic prefix (CP) length is set to  $L \ge \max\{L_1 + L_2 - 1, L_3\}$  to avoid inter-block interference (IBI). The block  $\tilde{x}_i$  of length S + L is transmitted from the *i*-th transmit antenna. By discarding the first L entries of the received block and then applying the FFT, we obtain the received signal at each subcarrier  $s \in S \triangleq \{0, \ldots, S - 1\}$  for UE k as

$$y_k(s) = \hbar_{k,s}(\boldsymbol{v})x(s) + \bar{g}_{\text{R-k},s}\boldsymbol{\Upsilon}\tilde{n} + n_k(s), \qquad (5)$$

where

$$x(s) \triangleq \begin{bmatrix} x_1(s) \\ \dots \\ x_{N_t}(s) \end{bmatrix} \in \mathbb{C}^{N_t}, \tag{6}$$

and  $n_k(s)$  is the background noise of power  $\sigma^2$ ,

$$\hbar_{k,s}(\boldsymbol{v}) = \hbar_k(e^{j2\pi s/S}) \tag{7}$$

$$= \bar{g}_{\text{R-k,s}} \text{diag}(\boldsymbol{v}) G_{\text{B-R,s}} + \bar{g}_{\text{B-k,s}}$$
(8)

with

$$\begin{split} \bar{g}_{\text{B-k,s}} &\triangleq \bar{g}_{\text{B-k}}(e^{j2\pi s/S}), \\ G_{\text{B-R,s}} &\triangleq G_{\text{B-R}}(e^{j2\pi s/S}), \\ \bar{g}_{\text{R-k,s}} &\triangleq \bar{g}_{\text{R-k}}(e^{j2\pi s/S}), \end{split}$$

and  $\tilde{n} = (\tilde{n}_1, \ldots, \tilde{n}_N)^T \in \mathbb{C}^{N \times 1}$  is related to the input noise and the inherent device noise of the active-RIS elements and it is modeled as  $\tilde{n}_n \sim C\mathcal{N}(0, \sigma_{\tilde{n}}^2)$ . Therefore,  $\Upsilon \tilde{n}$  in (5) is the noise introduced and amplified by the reflection-type amplifier [38].

In MU beamforming, each  $x(s) \in \mathbb{C}^{N_t}$  in (6) is given by

$$x(s) = \sum_{k=1}^{K} \mathbf{w}_k(s) u_k(s), \tag{9}$$

i.e. the information  $u_k(s) \in \mathcal{C}(0,1)$  intended for UE k is beamformed by

$$\mathbf{w}_{k}(s) \triangleq \begin{bmatrix} \mathbf{w}_{k,1}(s) \\ \dots \\ \mathbf{w}_{k,N_{t}}(s) \end{bmatrix} \in \mathbb{C}^{N_{t}}, k \in \mathcal{K}.$$
(10)

Thus, the received signal in (5) becomes

$$y_k(s) = \hbar_{k,s}(\boldsymbol{v}) \sum_{j=1}^K \mathbf{w}_j(s) u_j(s) + \bar{g}_{\mathbf{R}\text{-}k,s} \boldsymbol{\Upsilon} \tilde{n} + n_k(s).$$
(11)

The transmit power constraint for the BS is given by

$$\left(1 + \frac{L}{S}\right) \sum_{k=1}^{K} \sum_{s=0}^{S-1} \|\mathbf{w}_k(s)\|^2 \le P_{\text{BS}},\tag{12}$$

where  $P_{BS}$  is the maximum transmit power budget at the BS. For active-RIS, we have to include a power constraint for the power reflected from the active-RIS, which is given by [15]

$$\left(1+\frac{L}{S}\right)\left(\sum_{k=1}^{K}\sum_{s=0}^{S-1}\|\boldsymbol{\Upsilon}G_{\mathbf{B}-\mathbf{R},s}\mathbf{w}_{k}(s)\|^{2}+\|\boldsymbol{\Upsilon}\|^{2}\sigma_{\tilde{n}}^{2}\right) \leq P_{\mathbf{A}},$$
(13)

where  $P_A$  is the maximum transmit power budget at the active-RIS and (13) ensures that the power of the amplified signal reflected by the active RIS is less than  $P_A$ . Let

$$\mathbf{w}(s) \triangleq \begin{bmatrix} \mathbf{w}_1(s) \\ \dots \\ \mathbf{w}_K(s) \end{bmatrix} \in \mathbb{C}^{KN_t},$$

and  $\mathbf{w} \triangleq {\mathbf{w}(s), s \in S}$ . Then, using (11), the throughput of UE k over subcarrier s, in nats/sec, for our active-RIS-assisted OFDM communication system is given by (14) at the top of the page. Thus, the average rate of UE k is defined by

$$r_k(\mathbf{w}, \boldsymbol{v}) \triangleq \frac{1}{S} \sum_{s=0}^{S-1} r_{k,s}(\mathbf{w}(s), \boldsymbol{v}).$$
(15)

At the current state of research, the optimization of MU MC systems is primarily focused on maximizing the SR, formulated as:

$$\max_{\mathbf{w},\boldsymbol{v}} \sum_{k=1}^{K} r_k(\mathbf{w},\boldsymbol{v}) \quad \text{s.t.} \quad (12), (13).$$

However, our previous paper [29] has demonstrated that this approach leads to zero rates for certain users across the entire frequency band, rendering it unsuitable for MU MC communications. A promising technique of enhancing all user rates is based on max-min rate optimization formulated by

$$\max_{\mathbf{w},\boldsymbol{v}} \min_{k=1,\dots,K} r_k(\mathbf{w},\boldsymbol{v}) \quad \text{s.t.} \quad (12), (13), \qquad (16)$$

which constitutes a large-scale nonconvex problem, with its own computational challenges arising from the non-smooth nature of the MR objective function  $\min_{k=1,...,K} r_k(\mathbf{w}, \boldsymbol{v})$ . To overcome the computational challenges associated with max-min rate optimization, we propose a pair of surrogate problems of smooth optimization that offer a more computationally tractable solution and enhance rate fairness: GMrate optimization and soft max-min rate optimization. The subsequent sections provide further details on these surrogate problems.

### III. GM-RATE OPTIMIZATION FOR ACTIVE-RIS AIDED OFDM SYSTEMS

This section addresses the joint design of the beamformers' weight set w and the vector v of PREs to maximize the GM of the users' rates for our active-RIS-assisted OFDM communication system, which can be formulated as:

$$\max_{\mathbf{w},\boldsymbol{v}} f(\mathbf{w},\boldsymbol{v}) \triangleq \left(\prod_{k=1}^{K} r_k(\mathbf{w},\boldsymbol{v})\right)^{1/K} \quad \text{s.t.} \quad (12), (13). \quad (17)$$

Our previous treatises [10], [11] on single carrier systems have demonstrated the effectiveness of GM-rate optimization in

$$r_{k,s}(\mathbf{w}(s), \boldsymbol{\upsilon}) = \ln\left(1 + \frac{|\hbar_{k,s}(\boldsymbol{\upsilon})\mathbf{w}_k(s)|^2}{\sum_{j \in \mathcal{K} \setminus \{k\}} |\hbar_{k,s}(\boldsymbol{\upsilon})\mathbf{w}_j(s)|^2 + \|\bar{g}_{\mathsf{R}\text{-}k,s}\boldsymbol{\Upsilon}\|^2 \sigma_{\bar{n}}^2 + \sigma^2}\right).$$
(14)

improving the MU rate fairness, while achieving competitive SR. Following these solutions, we represent (17) by the following max-min problem:

$$\max_{\mathbf{w},\boldsymbol{v}} \min_{\gamma_k > 0, \prod_{k=1}^K \gamma_k \geq 1} \left[ \sum_{k=1}^K \gamma_k r_k(\mathbf{w},\boldsymbol{v}) \right] \quad \text{s.t.} \quad (12), (13).$$
(18)

Let  $(w^{(\tau)}, v^{(\tau)})$  be a feasible point for (18) that is found from the  $(\tau - 1)$ -st round. Note that

$$\min_{\gamma_k > 0, \prod_{k=1}^K \gamma_k \ge 1} \left[ \sum_{k=1}^K \gamma_k r_k(w^{(\tau)}, v^{(\tau)}) \right]$$
(19)

is attained at

$$\gamma_k^{(\tau)} \triangleq \frac{\max_{k' \in \mathcal{K}} r_{k'}(w^{(\tau)}, v^{(\tau)})}{r_k(w^{(\tau)}, v^{(\tau)})}, \ k \in \mathcal{K}.$$
 (20)

We solve the following problem at the  $\tau$ -th iteration to generate  $(w^{(\tau+1)}, v^{(\tau+1)})$ :

$$\max_{\mathbf{w},\boldsymbol{v}} f^{(\tau)}(\mathbf{w},\boldsymbol{v}) \triangleq \sum_{k=1}^{K} \gamma_k^{(\tau)} r_k(\mathbf{w},\boldsymbol{v}) \quad \text{s.t.} \quad (12), (13). \quad (21)$$

#### A. Beamforming ascent

To seek  $w^{(\tau+1)}$  so that the condition of

$$f^{(\tau)}(w^{(\tau+1)}, v^{(\tau)}) > f^{(\tau)}(w^{(\tau)}, v^{(\tau)}),$$
(22)

is met, we consider the following optimization problem:

$$\max_{\mathbf{w}} \quad f^{(\tau)}(\mathbf{w}, v^{(\tau)}) \tag{23a}$$

s.t. 
$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \|\mathbf{w}_k(s)\|^2 \le \bar{P}_{\text{BS}},$$
 (23b)

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \mathbf{w}_k^H(s) E_s \mathbf{w}_k(s) \leq \bar{P}_{A}, \quad (23c)$$

where

$$\bar{P}_{BS} \triangleq \frac{P_{BS}}{1 + \frac{L}{S}},$$

$$\bar{P}_{A} \triangleq \frac{P_{A}}{1 + \frac{L}{S}} - \|\Upsilon^{(\tau)}\|^{2} \sigma_{\tilde{n}}^{2},$$

$$E_{s} \triangleq (G_{B-R,s})^{H} (\Upsilon^{(\tau)})^{H} \Upsilon^{(\tau)} G_{B-R,s}.$$
(24)

Using the inequality (1) for  $\mathbf{v} = \hbar_{k,s}(v^{(\tau)})\mathbf{w}_k(s)$ ,  $\mathbf{y} = \sum_{j \in \mathcal{K} \setminus \{k\}} |\hbar_{k,s}(v^{(\tau)})\mathbf{w}_j(s)|^2 + \sigma_a^2$ , and  $\bar{v} = \hbar_{k,s}(v^{(\tau)})w_k^{(\tau)}(s)$ ,  $\bar{y} = y_{k,s}^{(\tau)} \triangleq \sum_{j \in \mathcal{K} \setminus \{k\}} |\hbar_{k,s}(v^{(\tau)})w_j^{(\tau)}(s)|^2 + \sigma_a^2$ , for  $\sigma_a^2 = \|\bar{g}_{\mathbf{R}\cdot\mathbf{k},s}\Upsilon^{(\tau)}\|^2\sigma_{\bar{n}}^2 + \sigma^2$ , yields the following tight concave minorant of  $r_{k,s}(\mathbf{w}(s), v^{(\tau)})$  at  $w^{(\tau)}(s)$ :

$$r_{k,s}(\mathbf{w}(s), \upsilon^{(\tau)}) \geq r_{k,s}^{(\tau)}(\mathbf{w}(s))$$
  
$$\triangleq a_{k,s}^{(\tau)} + 2\Re\{\langle b_{k,s}^{(\tau)}, \mathbf{w}_k(s) \rangle\}$$

with

$$a_{k,s}^{(\tau)} \triangleq r_{k,s}(\upsilon^{(\tau)}, w^{(\tau)}(s)) - \frac{|\hbar_{k,s}(\upsilon^{(\tau)})w_{k}^{(\tau)}(s)|^{2}}{y_{k,s}^{(\tau)}} - \sigma_{a}^{2}c_{k,s}^{(\tau)},$$

$$b_{k,s}^{(\tau)} \triangleq \frac{\hbar_{k,s}(\upsilon^{(\tau)})w_{k}^{(\tau)}(s)}{y_{k,s}^{(\tau)}}(\hbar_{k,s}(\upsilon^{(\tau)}))^{H},$$

$$0 < c_{k,s}^{(\tau)} \triangleq \frac{|\hbar_{k,s}(\upsilon^{(\tau)})w_{k,s}^{(\tau)}|^{2}}{y_{k,s}^{(\tau)}\left(y_{k,s}^{(\tau)} + |\hbar_{k,s}(\upsilon^{(\tau)})w_{k}^{(\tau)}(s)|^{2}\right)}.$$
(26)

 $-c_{k,s}^{(\tau)} \sum_{i=1}^{K} \left| \hbar_{k,s}(\upsilon^{(\tau)}) \mathbf{w}_{j}(s) \right|^{2}, (25)$ 

Thus, using (25), a tight concave minorant of  $f^{(\tau)}(\mathbf{w}, v^{(\tau)})$  at  $w^{(\tau)}$  is given by:

$$f_{b}^{(\tau)}(\mathbf{w}) \triangleq \sum_{k=1}^{K} \gamma_{k}^{(\tau)} \sum_{s=0}^{S-1} r_{k,s}^{(\tau)}(\mathbf{w}(s))$$
  
= 
$$\sum_{k=1}^{K} \gamma_{k}^{(\tau)} \sum_{s=0}^{S-1} a_{k,s}^{(\tau)} + 2 \sum_{k=1}^{K} \sum_{s=0}^{S-1} \Re\{\langle \bar{b}_{k,s}^{(\tau)}, \mathbf{w}_{k}(s) \rangle\}$$
  
$$- \sum_{s=0}^{S-1} \sum_{k=1}^{K} \mathbf{w}_{k}^{H}(s) \Psi_{s}^{(\tau)} \mathbf{w}_{k}(s), \qquad (27)$$

with

$$0 \preceq \Psi_{s}^{(\tau)} \triangleq \sum_{j=1}^{K} \gamma_{j}^{(\tau)} c_{j,s}^{(\tau)} (\hbar_{j,s}(v^{(\tau)}))^{H} \hbar_{j,s}(v^{(\tau)}), \ s \in \mathcal{S}, \\ \bar{b}_{k,s}^{(\tau)} \triangleq \gamma_{k}^{(\tau)} b_{k,s}^{(\tau)}.$$
<sup>(28)</sup>

Note that  $f_b^{(\tau)}(\mathbf{w})$  in (27) is a tight concave minorant of  $f^{(\tau)}(\mathbf{w}, v^{(\tau)})$  because  $r_{k,s}^{(\tau)}(\mathbf{w}(s))$  serves as a tight concave minorant of  $r_{k,s}(\mathbf{w}(s), v^{(\tau)})$ , as shown in (25).

Thus, a specific  $w^{(\tau+1)}$  verifying (22) can be found as the optimal solution of the following convex problem of tight minorant maximization of (23)

$$\max_{\mathbf{w}} \quad f_b^{(\tau)}(\mathbf{w}) \quad \text{s.t.} \quad (23b), (23c). \tag{29}$$

Since we have a pair of quadratic constraints in (29) due to the use of active-RIS, a simple bisection approach, as adopted in [28] in conjunction with a single quadratic constraint can no longer be applied. Hence a sophisticated bisection procedure based on iterating closed-form expressions is conceived for computing (29) in Appendix A, where the symbols  $b_{k,s}$ ,  $\boldsymbol{x}_{k,s}$ ,  $Q_s$ ,  $P_1$ ,  $P_2$  are used in place of  $\bar{b}_{k,s}^{(\tau)}$ ,  $\mathbf{w}_k(s)$ ,  $\Psi_s^{(\tau)}$ ,  $\bar{P}_{\text{BS}}$ , and  $\bar{P}_{\text{A}}$ .

# B. PREs ascent

Upon using (5), we have

m

$$\hbar_{k,s}(\boldsymbol{v})w_j^{(\tau+1)}(s) = q_{k,s,j}^{(\tau+1)}\boldsymbol{v} + \bar{g}_{\text{B-k},s}w_j^{(\tau+1)}(s)$$
(30)

for

$$q_{k,s,j}^{(\tau+1)} = \left(w_j^{(\tau+1)}(s)\right)^T \left(G_{\mathbf{B}-\mathbf{R},s}\right)^T D_{k,s} \in \mathbb{C}^{1\times N},$$

$$r_{k,s}(w^{(\tau+1)}(s),\boldsymbol{v}) = \ln\left(1 + \frac{\left|q_{k,s,k}^{(\tau+1)}\boldsymbol{v} + \bar{g}_{\mathsf{B}\text{-}\mathsf{k},s}w_{k}^{(\tau+1)}(s)\right|^{2}}{\sum_{j\in\mathcal{K}\setminus\{k\}}\left|q_{k,s,j}^{(\tau+1)}\boldsymbol{v} + \bar{g}_{\mathsf{B}\text{-}\mathsf{k},s}w_{j}^{(\tau+1)}(s)\right|^{2} + \|\sigma_{\bar{n}}^{2}D_{k,s}\boldsymbol{v}\|^{2} + \sigma^{2}}\right).$$
(32)

$$k \in \mathcal{K}, j \in \mathcal{K}, n \in \mathcal{N},$$

where

$$D_{k,s} \triangleq \operatorname{diag}\left(\bar{g}_{\mathrm{R-k},s}\right). \tag{31}$$

Upon using (30), the throughput of  $u_k(s)$  for UE k in (14) can be written as (32), which is provded at the top of the page.

To seek a specific  $v^{(\tau+1)}$  so that the condition of

$$f^{(\tau)}(w^{(\tau+1)}, v^{(\tau+1)}) > f^{(\tau)}(w^{(\tau+1)}, v^{(\tau)})$$
(33)

is met, we consider the following problem:

$$\max_{\boldsymbol{v}} f^{(\tau)}(w^{(\tau+1)}, \boldsymbol{v})$$
(34a)

s.t. 
$$\left(1+\frac{L}{S}\right)\boldsymbol{v}^{H}X^{(\tau)}\boldsymbol{v} \leq P_{A},$$
 (34b)

where

$$f^{(\tau)}(w^{(\tau+1)},\boldsymbol{v}) \triangleq \sum_{k=1}^{K} \gamma_k^{(\tau)} \left( \frac{1}{S} \sum_{s=0}^{S-1} r_{k,s}(w^{(\tau+1)}(s),\boldsymbol{v}) \right)$$

is obtained by using (15) and (21), and  $X^{(\tau)}$  is defined as

$$X^{(\tau)} \triangleq \sum_{k=1}^{K} \sum_{s=0}^{S-1} \operatorname{diag} \left( G_{\text{B-R},s} w_k^{(\tau+1)}(s) \right)^H \\ \times \operatorname{diag} \left( G_{\text{B-R},s} w_k^{(\tau+1)}(s) \right) + \sigma_{\tilde{n}}^2 I_N.$$
(35)

Using the inequality (1) for  $\mathbf{v} = q_{k,s,k}^{(\tau+1)} \mathbf{v} + \bar{g}_{\text{B-k,s}} w_k^{(\tau+1)}(s)$ ,  $\mathbf{y} = \sum_{j \in \mathcal{K} \setminus \{k\}} \left| q_{k,s,j}^{(\tau+1)} \mathbf{v} + \bar{g}_{\text{B-k,s}} w_j^{(\tau+1)}(s) \right|^2 + \|\sigma_{\bar{n}}^2 D_{k,s} \mathbf{v}\|^2 + \sigma^2$ , and  $\bar{v} = q_{k,s,k}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k,s}} w_k^{(\tau+1)}(s)$ ,  $\bar{y} = y_{k,s}^{(\tau)} \triangleq \sum_{j \in \mathcal{K} \setminus \{k\}} \left| q_{k,s,j}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k,s}} w_j^{(\tau+1)}(s) \right|^2 + \|\sigma_{\bar{n}}^2 D_{k,s} v^{(\tau)}\|^2 + \sigma^2$ , yields the following tight concave minorant of  $r_{k,s}(w^{(\tau+1)}(s), \mathbf{v})$  at  $v^{(\tau)}$ :

$$r_{k,s}(w^{(\tau+1)}(s), \boldsymbol{v}) \geq r_{k,s}^{(\tau)}(\boldsymbol{v})$$

$$\triangleq a_{k,s}^{(\tau)} + 2\Re\{b_{k,s}^{(\tau)}\boldsymbol{v}\}$$

$$- c_{k,s}^{(\tau)}\left(\sum_{j=1}^{K} \left|q_{k,s,j}^{(\tau+1)}\boldsymbol{v}\right|^{2} + \left\|\sigma_{\bar{n}}^{2}D_{k,s}\boldsymbol{v}\right\|^{2}\right)$$

$$= a_{k,s}^{(\tau)} + 2\Re\left\{b_{k,s}^{(\tau)}\boldsymbol{v}\right\} - c_{k,s}^{(\tau)}\boldsymbol{v}^{H}\Phi_{k,s}^{(\tau)}\boldsymbol{v},$$
(36)

with

$$\begin{split} a_{k,s}^{(\tau)} &\triangleq r_{k,s}(w^{(\tau+1)}, v^{(\tau)}) - \frac{|\rho_{k,s}^{(\tau)}|^2}{y_{k,s}^{(\tau+1)}} \\ &\quad + 2\Re\left\{\frac{(\rho_{k,s}^{(\tau)})^*}{y_{k,s}^{(\tau+1)}} \left(\bar{g}_{\text{B-k},s}w_k^{(\tau+1)}(s)\right)\right\} \\ &\quad - c_{k,s}^{(\tau)} \left(\sum_{j=1}^{K} \left|\bar{g}_{\text{B-k},s}w_j^{(\tau+1)}(s)\right|^2 + \sigma^2\right) \\ b_{k,s}^{(\tau)} &\triangleq \frac{(\rho_{k,s}^{(\tau)})^*}{y_{k,s}^{(\tau+1)}} q_{k,s,k}^{(\tau+1)} - c_{k,s}^{(\tau)} \sum_{j=1}^{K} \left(\bar{g}_{\text{B-k},s}w_j^{(\tau+1)}(s)\right)^* q_{k,s,j}^{(\tau+1)} \\ 0 &< c_{k,s}^{(\tau)} \triangleq \frac{|\rho_{k,s}^{(\tau)}|^2}{y_{k,s}^{(\tau+1)} \left(y_{k,s}^{(\tau+1)} + \left|\rho_{k,s}^{(\tau)}\right|^2\right)} \\ \rho_{k,s}^{(\tau)} &\triangleq q_{k,s,k}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k},s}w_k^{(\tau+1)}(s) \in \mathbb{C} \\ \Phi_{k,s}^{(\tau)} &\triangleq \sum_{j=1}^{K} \left(q_{k,s,j}^{(\tau+1)}\right)^H q_{k,s,j}^{(\tau+1)} + \sigma_{\bar{n}}^2 D_{k,s}^H D_{k,s} \in \mathbb{C}^{N \times N}. \end{split}$$

Thus, upon using (36), a tight concave minorant of  $f^{(\tau)}(w^{(\tau+1)}, v)$  at  $v^{(\tau)}$  is given by:

$$f_{c}^{(\tau)}(\boldsymbol{v}) \triangleq \sum_{k=1}^{K} \gamma_{k}^{(\tau)} \sum_{s=0}^{S-1} r_{k,s}^{(\tau)}(\boldsymbol{v})$$
$$= a^{(\tau)} + 2\Re\{b^{(\tau)}\boldsymbol{v}\} - \boldsymbol{v}^{H} \Psi^{(\tau)}\boldsymbol{v}, \quad (37)$$

with  $a^{(\tau)} \triangleq \sum_{k=1}^{K} \gamma_k^{(\tau)} \sum_{s=0}^{S-1} a_{k,s}^{(\tau)}, \quad b^{(\tau)} \triangleq \sum_{k=1}^{K} \gamma_k^{(\tau)} \sum_{s=0}^{S-1} a_{k,s}^{(\tau)}, \quad b^{(\tau)} \triangleq \sum_{k=1}^{K} \gamma_k^{(\tau)} \sum_{s=0}^{S-1} c_{k,s}^{(\tau)} \Phi_{k,s}^{(\tau)}.$ 

Thus, a particular  $v^{(\tau+1)}$  verifying (33) can be found as the optimal solution of the following convex problem of tight minorant maximization of (34)

$$\max_{\boldsymbol{v}} f_c^{(\tau)}(\boldsymbol{v}) \quad \text{s.t.} \quad (34b), \tag{38}$$

which admits the closed-form solution

$$v^{(\tau+1)} = \begin{cases} (\Psi^{(\tau)})^{-1} (b^{(\tau)})^{H} & \text{if } \Xi \le P_{A}, \\ (\Psi^{(\tau)} + \mu X^{(\tau)})^{-1} (b^{(\tau)})^{H} & \text{otherwise,} \end{cases}$$
(39)

where  $\Xi \triangleq (1 + \frac{L}{S}) (v^{(\tau)})^H X^{(\tau)} v^{(\tau)}$  and  $\mu > 0$  is chosen by bisection for ensuring that  $(1 + \frac{L}{S}) (v^{(\tau)})^H X^{(\tau)} v^{(\tau)} = P_A$ . The solution in (39) can be explained as follows. If  $\Xi \leq P_A$ , we have to solve for unconstrained optimization

$$\max_{\boldsymbol{v}} f_c^{(\tau)}(\boldsymbol{v}) \triangleq a^{(\tau)} + 2\Re\{b^{(\tau)}\boldsymbol{v}\} - \boldsymbol{v}^H \Psi^{(\tau)}\boldsymbol{v}.$$

Taking the derivative of  $f_c^{(\tau)}(v)$  with respect to v and equating the result to zero yields the first expression in the case equation (39). On the other hand, if  $\Xi > P_A$ , we can introduce a ' Lagrangian parameter  $\mu$  and solve the following optimization problem:

$$\max_{\boldsymbol{v}} f_c^{(\tau)}(\boldsymbol{v}) - \mu \left( \left( 1 + \frac{L}{S} \right) \left( v^{(\tau)} \right)^H X^{(\tau)} v^{(\tau)} - P_{\mathrm{A}} \right).$$

By taking the derivative of the above objective function with respect to v and equating the result to zero yields the second expression in the case equation (39).

Algorithm 1 provides the pseudo-code for the proposed steep descent procedure of computing (17). Although (22) and (33) only show that  $f^{(\tau)}(w^{(\tau+1)}, v^{(\tau+1)}) > f^{(\tau)}(w^{(\tau)}, v^{(\tau)})$ , our simulations confirm that Algorithm 1 also achieves

$$f\left(w^{(\tau+1)}, v^{(\tau+1)}\right) > f\left(w^{(\tau)}, v^{(\tau)}\right),$$
 (40)

i.e. there is no need for line search to find a better feasible point than the incumbent  $(w^{(\tau)}, v^{(\tau)})$ . Therefore, the sequence  $\{(w^{(\tau)}, v^{(\tau)})\}$  of improved feasible points for the GM-rate problem (17) is seen to be convergent by Cauchy's theorem.

Algorithm 1 GM-rate optimization algorithm for active-RIS aided MU MC system

- 1: Initialization: Set  $\tau = 0$ . Generate random  $(w^{(0)}, v^{(0)})$ meeting the constraints (12) and (13). Caclulate  $\gamma_k^{(0)}$  by (21).
- Repeat until convergence of the objective function in (17): Generate w<sup>(τ+1)</sup> by solving (29) using the procedure proposed in Appendix A. Generate v<sup>(τ+1)</sup> by (39). Reset τ = τ + 1.
- 3: **Output**  $(w^{(\tau)}, \theta^{(\tau)})$  and user rates  $r_k(w^{(\tau)}, v^{(\tau)}), k \in \mathcal{K}$ .

#### IV. SOFT MAX-MIN RATE OPTIMIZATION FOR ACTIVE-RIS AIDED OFDM SYSTEMS

In this section, we introduce another surrogate optimization problem, which we refer to as "soft max-min (SMM) rate optimization". This problem is formulated based on a soft and smooth approximation of the non-smooth MR function.

We have

$$r_k(\mathbf{w}, \boldsymbol{v}) = -\frac{1}{S} \sum_{s \in S} \ln \left( 1 + \frac{|\hbar_{k,s}(\boldsymbol{v})\mathbf{w}_k(s)|^2}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right)^{-1}$$
(41)

$$\geq -\ln\left[\frac{1}{S}\sum_{s\in\mathcal{S}}\left(1+\frac{|\hbar_{k,s}(\boldsymbol{\upsilon})\mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w},\boldsymbol{\upsilon})}\right)^{-1}\right] (42)$$
$$=\ln S+\ln\left[\sum_{s\in\mathcal{S}}\left(1+\frac{|\hbar_{k,s}(\boldsymbol{\upsilon})\mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w},\boldsymbol{\upsilon})}\right)^{-1}\right]^{-1}.$$

for

$$\phi_{k,s}(\mathbf{w}, \boldsymbol{\upsilon}) \triangleq \sum_{j \in \mathcal{K} \setminus \{k\}} |\hbar_{k,s}(\boldsymbol{\upsilon}) \mathbf{w}_j(s)|^2 + \|\bar{g}_{\mathsf{R-k},s} \Upsilon\|^2 \sigma_{\tilde{n}}^2 + \sigma^2$$

The steps of obtaining (42) from (41) are provided in Appendix B. Instead of (16), we consider its minorant maximization

$$\max_{\mathbf{w},\mathbf{v}} \min_{k \in \mathcal{K}} \left\{ \ln \left[ \sum_{s \in \mathcal{S}} \left( 1 + \frac{|\hbar_{k,s}(\mathbf{v})\mathbf{w}_k(s)|^2}{\phi_{k,s}(\mathbf{w},\mathbf{v})} \right)^{-1} \right]^{-1} \right\} (44)$$
  
$$\Leftrightarrow \max_{\mathbf{w},\mathbf{v}} \left\{ \max_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 + \frac{|\hbar_{k,s}(\mathbf{v})\mathbf{w}_k(s)|^2}{\phi_{k,s}(\mathbf{w},\mathbf{v})} \right)^{-1} \right\}^{-1}$$
(45)

$$\Leftrightarrow \min_{\mathbf{w}, \boldsymbol{v}} \max_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 + \frac{|\hbar_{k,s}(\boldsymbol{v})\mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right)^{-1}$$
(46)  
$$\Leftrightarrow \min_{\mathbf{w}, \boldsymbol{v}} \max_{k \in \mathcal{K}} \ln \left[ 1 + \frac{1}{c} \sum_{s \in \mathcal{S}} \left( 1 + \frac{|\hbar_{k,s}(\boldsymbol{v})\mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right)^{-1} \right]$$
(47)

for c > 0, while

$$\max_{k \in \mathcal{K}} \ln \left[ 1 + \frac{1}{c} \sum_{s \in \mathcal{S}} \left( 1 + \frac{|\hbar_{k,s}(\boldsymbol{v}) \mathbf{w}_k(s)|^2}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right)^{-1} \right] \leq (48)$$

$$\ln\left[\sum_{k\in\mathcal{K}}\left(1+\frac{1}{c}\sum_{s\in\mathcal{S}}\left(1+\frac{|\hbar_{k,s}(\boldsymbol{v})\mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w},\boldsymbol{v})}\right)^{-1}\right)\right] = (49)$$

$$\ln \left[ \frac{1}{K} \sum_{k \in \mathcal{K}} \left( 1 + \frac{1}{c} \sum_{s \in \mathcal{S}} \left[ 1 + \frac{|h_{k,s}(\boldsymbol{v}) \mathbf{w}_{k}(s)|}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right] \right] + \ln K \leq (50)$$

$$\max_{k \in \mathcal{K}} \ln \left[ 1 + \frac{1}{c} \sum_{s \in \mathcal{S}} \left( 1 + \frac{|h_{k,s}(\boldsymbol{v}) \mathbf{w}_{k}(s)|^{2}}{\phi_{k,s}(\mathbf{w}, \boldsymbol{v})} \right)^{-1} \right]$$

$$+\ln K.$$
 (51)

For small c > 0, the constant  $\ln K$  becomes very small compared to the LHS of (48), so the first term in the LHS of (50) is an accurate approximation for the LHS of (48). We now address the max-min rate optimization problem (16) via the following soft max-min rate optimization problem:

$$\min_{\mathbf{w},\mathbf{v}} \ln\left[\frac{1}{K}\sum_{k\in\mathcal{K}} \left(1 + \frac{1}{c}\sum_{s\in\mathcal{S}} \left(1 + \frac{|\hbar_{k,s}(\mathbf{v})\mathbf{w}_k(s)|^2}{\phi_{k,s}(\mathbf{w},\mathbf{v})}\right)^{-1}\right)\right]$$
  
s.t. (12),(13), (52)

which is rewritten as

$$\min_{\mathbf{w},\mathbf{v}} \tilde{f}(\mathbf{w},\mathbf{v}) \triangleq \ln \left[ 1 + \frac{1}{c} \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 - \frac{|\hbar_{k,s}(\mathbf{v})\mathbf{w}_k(s)|^2}{\bar{\phi}_{k,s}(\mathbf{w},\mathbf{v})} \right) \right]$$
  
s.t. (12),(13). (53)

for

$$egin{aligned} egin{aligned} &\phi_{k,s}(\mathbf{w},oldsymbol{v})&\triangleq\phi_{k,s}(\mathbf{w},oldsymbol{v})+|\hbar_{k,s}(oldsymbol{v})\mathbf{w}_k(s)|^2\ &=\sum_{j\in\mathcal{K}}|\hbar_{k,s}(oldsymbol{v})\mathbf{w}_j(s)|^2+\|ar{g}_{ ext{R-k,s}}oldsymbol{\Upsilon}\|^2\sigma_{ ilde{n}}^2+\sigma^2 \end{aligned}$$

Let  $(w^{(\tau)}, v^{(\tau)})$  be the feasible point for (53) that is found from the  $(\tau - 1)$ -th round.

### A. Beamforming alternating optimization

To seek a particular  $w^{(\tau+1)}$ , so that the condition of

$$\tilde{f}(w^{(\tau+1)}, v^{(\tau)}) > \tilde{f}(w^{(\tau)}, v^{(\tau)})$$
 (54)

is met, we consider the following problem:

$$\min_{\mathbf{w}} \quad \tilde{f}(\mathbf{w}, \upsilon^{(\tau)}) \triangleq \ln \left[ 1 + \frac{1}{c} \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 - \frac{\left| \hbar_{k,s}(\upsilon^{(\tau)}) \mathbf{w}_{k}(s) \right|^{2}}{\sum_{j \in \mathcal{K}} \left| \hbar_{k,s}(\upsilon^{(\tau)}) \mathbf{w}_{j}(s) \right|^{2} + \sigma_{a}^{2}} \right) \right]$$
s.t. (23b), (23c), (55)

where  $\sigma_a^2 \triangleq \|\bar{g}_{\mathbf{R}\cdot\mathbf{k},\mathbf{s}}\Upsilon^{(\tau)}\|^2 \sigma_{\tilde{n}}^2 + \sigma^2$ . Using the inequality (2) for  $\boldsymbol{x} = \hbar_{k,s}(\upsilon^{(\tau)})\mathbf{w}_k(s), \ \mathbf{y} = \sum_{j \in \mathcal{K}} |\hbar_{k,s}(\upsilon^{(\tau)})\mathbf{w}_j(s)|^2 + \sigma_a^2$ , and  $\bar{x} = \hbar_{k,s}(\upsilon^{(\tau)})w_k^{(\tau)}(s), \ \bar{y} = y_{k,s}^{(\tau)} \triangleq \sum_{j \in \mathcal{K}} |\hbar_{k,s}(\upsilon^{(\tau)})w_j^{(\tau)}(s)|^2 + \sigma_a^2$ , yields the following tight majorant of  $\tilde{f}(\mathbf{w}, \upsilon^{(\tau)})$  at  $w^{(\tau)}$ :

$$\tilde{f}_{b}^{(\tau)}(\mathbf{w}) \triangleq a^{(\tau)} - \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left( 2\Re\{\langle b_{k,s}^{(\tau)}, \mathbf{w}_{k}(s) \rangle\} - c_{k,s}^{(\tau)} \sum_{j=1}^{K} |\hbar_{k,s}(v^{(\tau)}) \mathbf{w}_{j}(s)|^{2} \right),$$

$$= a^{(\tau)} - 2 \sum_{k=1}^{K} \sum_{s=0}^{S-1} \Re\{\langle b_{k,s}^{(\tau)}, \mathbf{w}_{k}(s) \rangle\} + \sum_{s=0}^{S-1} \sum_{k=1}^{K} \mathbf{w}_{k}^{H}(s) \Psi_{s}^{(\tau)} \mathbf{w}_{k}(s) \quad (56)$$

with

$$a^{(\tau)} \triangleq \ln\left(1 + \frac{1}{c}\chi^{(\tau)}\right) + \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left(\frac{|\hbar_{k,s}(v^{(\tau)})w_{k}^{(\tau)}(s)|^{2}}{y_{k,s}^{(\tau)}(c + \chi^{(\tau)})} + \sigma_{a}^{2}c_{k,s}^{(\tau)}\right),$$

$$\chi^{(\tau)} \triangleq \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left(1 - \frac{|\hbar_{k,s}(v^{(\tau)})w_{k}^{(\tau)}(s)|^{2}}{\sum_{j \in \mathcal{K}} |\hbar_{k,s}(v^{(\tau)})w_{j}^{(\tau)}(s)|^{2} + \sigma_{a}^{2}}\right),$$

$$b_{k,s}^{(\tau)} \triangleq \frac{\hbar_{k,s}(v^{(\tau)})w_{k}^{(\tau)}(s)}{y_{k,s}^{(\tau)}(c + \chi^{(\tau)})} (\hbar_{k,s})^{H},$$

$$0 < c_{k,s}^{(\tau)} \triangleq \frac{|\hbar_{k,s}(v^{(\tau)})w_{k,s}^{(\tau)}|^{2}}{\left(y_{k,s}^{(\tau)}\right)^{2} (c + \chi^{(\tau)})},$$

$$0 \leq \Psi_{s}^{(\tau)} \triangleq \sum_{j=1}^{K} c_{j,s}^{(\tau)} (\hbar_{j,s}(v^{(\tau)}))^{H} \hbar_{j,s}(v^{(\tau)}), \ s \in \mathcal{S}.$$
(57)

We thus solve the following convex problem of majorant minimization for (55) to generate  $w^{(\tau+1)}$ , verifying (54):

$$\min_{\mathbf{w}} \tilde{f}_b^{(\tau)}(\mathbf{w}) \quad \text{s.t.} \quad (23b), (23c). \tag{58}$$

An innovative bisection procedure, which is based on iterating closed-form expressions, for computing (58) is provided in Appendix A, where the symbols  $b_{k,s}$ ,  $\boldsymbol{x}_{k,s}$ ,  $Q_s$ ,  $P_1$ ,  $P_2$  are used in place of  $b_{k,s}^{(\tau)}$ ,  $\boldsymbol{w}_k(s)$ ,  $\Psi_s^{(\tau)}$ ,  $\bar{P}_{BS}$ , and  $\bar{P}_{A}$ .

#### B. PREs alternating optimization

To seek a specific  $v^{(\tau+1)}$  so that

$$\tilde{f}(w^{(\tau+1)}, v^{(\tau+1)}) > \tilde{f}(w^{(\tau+1)}, v^{(\tau)}),$$
 (59)

is met, we consider the following problem:

$$\min_{\boldsymbol{v}} \ln \left[ 1 + \frac{1}{c} \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 - \frac{\left| \hbar_{k,s}(\boldsymbol{v}) w_k^{(\tau)}(s) \right|^2}{\sum_{j \in \mathcal{K}} \left| \hbar_{k,s}(\boldsymbol{v}) w_j^{(\tau)}(s) \right|^2 + \|\bar{g}_{\mathsf{R}\text{-}\mathsf{k},\mathsf{s}} \boldsymbol{\Upsilon}\|^2 \sigma_{\bar{n}}^2 + \sigma^2} \right) \right]$$
(60a)

s.t. 
$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| \Upsilon G_{\text{B-R},s} w_k^{(\tau)}(s) \right\|^2 + \| \Upsilon \|^2 \sigma_{\tilde{n}}^2 \leq \widetilde{P}_{\text{A}},$$
(60b)

where  $\widetilde{P}_{A} \triangleq \frac{P_{A}}{1+\frac{L}{S}}$ . By relying on (30), the problem (60b) can be expressed as:

$$\min_{\boldsymbol{v}} \quad \tilde{f}(w^{(\tau+1)}, \boldsymbol{v}) \tag{61a}$$

s.t. 
$$\boldsymbol{v}^H X^{(\tau)} \boldsymbol{v} \leq \widetilde{P}_A,$$
 (61b)

where

$$\tilde{f}(w^{(\tau+1)}, \boldsymbol{v}) \triangleq \ln \left[ 1 + \frac{1}{c} \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 - \frac{\left| q_{k,s,k}^{(\tau+1)} \boldsymbol{v} + \bar{g}_{\text{B-k},s} w_k^{(\tau+1)}(s) \right|^2}{\sum_{j \in \mathcal{K}} \left| q_{k,s,j}^{(\tau+1)} \boldsymbol{v} + \bar{g}_{\text{B-k},s} w_j^{(\tau+1)}(s) \right|^2 + \|\sigma_{\tilde{n}}^2 D_{k,s} \boldsymbol{v}\|^2 + \sigma^2} \right) \right]$$
(62)

with  $D_{k,s}$  defined in (31), and  $X^{(\tau)}$  defined in (35). Using the inequality (2) for  $\boldsymbol{x} = q_{k,s,k}^{(\tau+1)} \boldsymbol{v} + \bar{g}_{\text{B-k,s}} w_k^{(\tau+1)}(s)$ ,  $\mathbf{y} = \sum_{j \in \mathcal{K}} \left| q_{k,s,j}^{(\tau+1)} \boldsymbol{v} + \bar{g}_{\text{B-k,s}} w_j^{(\tau+1)}(s) \right|^2 + \|\sigma_{\tilde{n}}^2 D_{k,s} \boldsymbol{v}\|^2 + \sigma^2$ , and  $\bar{x} = q_{k,s,k}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k,s}} w_k^{(\tau+1)}(s)$ ,  $\bar{y} = y_{k,s}^{(\tau)} \triangleq \sum_{j \in \mathcal{K}} \left| q_{k,s,j}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k,s}} w_j^{(\tau+1)}(s) \right|^2 + \|\sigma_{\tilde{n}}^2 D_{k,s} v^{(\tau)}\|^2 + \sigma^2$ , yields the following tight majorant of  $\tilde{f}(w^{(\tau+1)}, \boldsymbol{v})$  at  $v^{(\tau)}$ :

$$\tilde{f}_{c}^{(\tau)}(\boldsymbol{v}) \triangleq \tilde{a}^{(\tau)} - \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left( 2\Re\{\tilde{b}_{k,s}^{(\tau)}\boldsymbol{v}\} - \tilde{c}_{k,s}^{(\tau)} \\
\times \left( \sum_{j=1}^{K} \left| q_{k,s,j}^{(\tau+1)} \boldsymbol{v} \right|^{2} + \left\| \sigma_{\tilde{n}}^{2} D_{k,s} \boldsymbol{v} \right\|^{2} \right) \right) \\
= \tilde{a}^{(\tau)} - \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left( 2\Re\{\tilde{b}_{k,s}^{(\tau)}\boldsymbol{v}\} - \tilde{c}_{k,s}^{(\tau)} \boldsymbol{v}^{H} \Phi_{k,s}^{(\tau)} \boldsymbol{v} \right) \\
= \tilde{a}^{(\tau)} - 2\Re\{\tilde{b}^{(\tau)} \boldsymbol{v}\} + \boldsymbol{v}^{H} \tilde{\Psi}^{(\tau)} \boldsymbol{v} \tag{63}$$

with

$$\begin{split} \tilde{a}^{(\tau)} &\triangleq \ln\left(1 + \frac{1}{c}\tilde{\chi}^{(\tau)}\right) + \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left(\frac{|\rho_{k,s}^{(\tau)}|^2}{\eta_{k,s}^{(\tau)}} -2\Re\left\{\frac{(\rho_{k,s}^{(\tau)})^*}{\eta_{k,s}^{(\tau)}} \left(\bar{g}_{\text{B-k},s} w_k^{(\tau+1)}(s)\right)\right\} \\ &+ c_{k,s}^{(\tau)} \left(\sum_{j=1}^{K} \left|\bar{g}_{\text{B-k},s} w_j^{(\tau+1)}(s)\right|^2 + \sigma^2\right)\right) \end{split}$$

$$\begin{split} \eta_{k,s}^{(\tau)} &\triangleq \tilde{y}_{k,s}^{(\tau)}(c + \tilde{\chi}^{(\tau)}), \\ \tilde{\chi}^{(\tau)} &\triangleq \sum_{k \in \mathcal{K}} \sum_{s \in \mathcal{S}} \left( 1 - \frac{\left| q_{k,s,k}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\mathbf{B}\text{-}\mathbf{k},s} w_k^{(\tau+1)}(s) \right|^2}{\varphi_{k,s}^{(\tau)}} \right), \\ \varphi_{k,s}^{(\tau)} &\triangleq \sum_{j \in \mathcal{K}} \left| q_{k,s,j}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\mathbf{B}\text{-}\mathbf{k},s} w_j^{(\tau+1)}(s) \right|^2 \\ &\quad + \|\sigma_{\tilde{n}}^2 D_{k,s} v^{(\tau)}\|^2 + \sigma^2 \end{split}$$

$$\begin{split} \tilde{b}_{k,s}^{(\tau)} &\triangleq \frac{\left(\rho_{k,s}^{(\tau)}\right)^{*}}{\eta_{k,s}^{(\tau)}} q_{k,s,k}^{(\tau+1)} - c_{k,s}^{(\tau)} \sum_{j=1}^{K} \left(\bar{g}_{\text{B-k},s} w_{j}^{(\tau+1)}(s)\right)^{*} q_{k,s,j}^{(\tau+1)} \\ 0 &< \tilde{c}_{k,s}^{(\tau)} \triangleq \frac{|\rho_{k,s}^{(\tau)}|^{2}}{\left(\bar{y}_{k,s}^{(\tau)}\right)^{2} \left(c + \tilde{\chi}^{(\tau)}\right)} \\ \rho_{k,s}^{(\tau)} &\triangleq q_{k,s,k}^{(\tau+1)} v^{(\tau)} + \bar{g}_{\text{B-k},s} w_{k}^{(\tau+1)}(s) \in \mathbb{C} \\ \Phi_{k,s}^{(\tau)} \triangleq \sum_{j=1}^{K} \left(q_{k,s,j}^{(\tau+1)}\right)^{H} q_{k,s,j}^{(\tau+1)} + \sigma_{\tilde{n}}^{2} D_{k,s}^{H} D_{k,s} \in \mathbb{C}^{N \times N} \\ \tilde{b}^{(\tau)} \triangleq \sum_{k=1}^{K} \sum_{s=0}^{S-1} \tilde{b}_{k,s}^{(\tau)} \\ 0 \leq \tilde{\Psi}^{(\tau)} \triangleq \sum_{k=1}^{K} \sum_{s=0}^{S-1} c_{k,s}^{(\tau)} \Phi_{k,s}^{(\tau)}. \end{split}$$

We thus solve the following convex problem of majorant minimization for (60) to generate  $v^{(\tau+1)}$ , verifying (59):

$$\min_{\boldsymbol{v}} \quad \tilde{f}_c^{(\tau)}(\boldsymbol{v}) \quad \text{s.t.} \quad (61b), \tag{64}$$

which admits the closed-form solution:

$$\upsilon^{(\tau+1)} = \begin{cases} (\tilde{\Psi}^{(\tau)})^{-1} \left(\tilde{b}^{(\tau)}\right)^{H} & \text{if } \bar{\Xi} \leq \tilde{P}_{A}, \\ \left(\tilde{\Psi}^{(\tau)} + \mu X^{(\tau)}\right)^{-1} \left(\tilde{b}^{(\tau)}\right)^{H} & \text{otherwise,} \end{cases}$$

$$\tag{65}$$

where  $\overline{\Xi} \triangleq (v^{(\tau)})^H X^{(\tau)} v^{(\tau)}$  and  $\mu > 0$  is chosen by bisection, so that  $(v^{(\tau)})^H X^{(\tau)} v^{(\tau)} = \widetilde{P}_A$ .

The pseudo-code for solving the problem (53) is provided in Algorithm 2. It follows from (54) and (59) that

$$\tilde{f}(w^{(\tau+1)}, v^{(\tau+1)}) < \tilde{f}(w^{(\tau)}, v^{(\tau)}),$$
 (66)

so the sequence  $\{(w^{(\tau)}, v^{(\tau)})\}$  of improved feasible points for (53) converges to  $(\bar{w}, \bar{v})$  by Cauchy's theorem.

Algorithm 2 Soft max-min rate optimization algorithm for active-RIS aided OFDM system

- 1: Initialization: Set  $\tau = 0$ . Generate  $(w^{(0)}, v^{(0)})$  meeting the constraints (12) and (13).
- Repeat until convergence of the objective function in (53): Generate w<sup>(τ+1)</sup> by solving (58) using the procedure proposed in Appendix VI. Generate v<sup>(τ+1)</sup> by (65). Reset τ = τ + 1.
- 3: **Output**  $(w^{(\tau)}, v^{(\tau)})$  and user rates  $r_k(w^{(\tau)}, v^{(\tau)}), k \in \mathcal{K}$ .

# V. NUMERICAL RESULTS

In this section, we evaluate the performance of our algorithms. Unless otherwise specified, we assume  $N_t = 10$ transmit-antennas at the BS and N = 100 PREs at the active-RIS. We define P as the total transmit power budget, so that  $P := P_{\rm BS} + P_{\rm A} + N(P_{\rm DC} + P_{\rm SW})$ , where  $P_{\rm DC} = -5$ dBm is the direct current biasing power consumed by the amplifiers of PREs and  $P_{\rm SW} = -10$  dBm is the power used by the phase-shift switch and control circuit in each PRE [39]. We set  $P_{\rm BS} = 0.99C$  and  $P_{\rm A} = 0.01C$ , for  $C \triangleq P_{\rm BS} + P_{\rm A}$ . Unless stated otherwise, we set P = 32dBm. The noise power spectral density is -174 dBm/Hz and the transmission bandwidth is B = 10 MHz. This implies that the noise power over the total bandwidth is -104 dBm. Thus, the noise power at the RIS receiver is  $\sigma_{\tilde{n}}^2 = -104$  dBm and at the user-receiver over the subcarrier bandwidth is  $\sigma^2 = -104 - 10 \log_{10}(S)$  dBm. We set S = 64 subcarriers for our MC system. The convergence tolerance of the proposed algorithms is set to  $10^{-3}$  and the channel parameters are described in the following paragraph.

We set the path-loss of the BS-to-UE k link at a distance  $d_{B,k}$  to  $\beta_{B,k} \triangleq \mathcal{G}_{BS} - 33.05 - 36.7 \log_{10}(d_{B,k})$  (dB), that of the BS-to-RIS link at a distance  $d_{B,R}$  to  $\beta_{B,R} = \mathcal{G}_{RIS} + \mathcal{G}_{BS} - \mathcal{G}_{RIS}$  $35.9 - 22 \log_{10}(d_{B,R})$  (dB), and that of the RIS-to-UE k link at a distance  $d_{R,k}$  to  $\beta_{R,k} \triangleq \mathcal{G}_{RIS} - 33.05 - 30 \log_{10}(d_{R,k})$ (dB), where  $\mathcal{G}_{RIS} = 5$  dBi and  $\mathcal{G}_{BS} = 5$  dBi are the antenna gains of the BS and RIS elements [7], [40], [41]. The BS and the RIS are deployed at the coordinates of (40, 0, 25) meters and (0, 60, 40) meters in the three-dimensional (3D) space, respectively, while K = 10 UEs are randomly distributed in a  $(120 \times 120)$  meter area right of the BS and the RIS. We consider an  $L_3 = 12$ -tap multipath channel between the BS and the UEs,  $L_1 = 2$ -tap multipath channel between the BS and the RIS, and  $L_2 = 4$ -tap multipath channel between the RIS and the UEs. As explained in Section II, the elements of normalized small-scale fading channel vector  $h_{B,k,\ell}$ , for all  $\ell$ , those of the channel matrix  $G_{B,R,\ell}$ , for  $\ell \neq 0$ , and those of the channel vector  $h_{\mathbf{R},\mathbf{k},\ell}$ , for  $\ell \neq 0$ , follow Rayleigh distribution. On the other hand, the elements of the first tap of the channel matrix, G<sub>B,R,0</sub>, and those of the first tap of the channel vector,  $h_{R,k,0}$ , obey Rician distribution with Rician K-factors of 5 and 0 dB, respectively [19]. We assume a negative-exponentially decaying delay profile with the root-mean-square delay spread of  $T_s$ , for the symbol time  $T_s = 1/B$ .

For performance comparison and validation purposes, we compare the performance of the proposed active-RIS-based implementation to that of the RIS-less and passive-RIS-based implementations. Explicitly, the RIS-less implementation simply assumes having no RIS, relying solely on direct communication between the BS and the UEs. On the other hand, the passive-RIS implementation utilizes a conventional RIS having passive elements and does not have the active-RIS power constraint of (13), resulting in  $P_{\rm BS} + NP_{\rm SW} \equiv P$ .

Fig. 2 illustrates the convergence of Algorithm 1 for GMrate optimization. It can be observed that the GM-rate objective monotonically increases, validating (40), and the algorithm achieves rapid convergence within 25-35 iterations. Fig. 3 plots the rate distribution over 64 subcarriers by the proposed GM-rate and SMM-rate optimization Algorithms 1 and 2, at P = 30 dBm. We can observe that the achievable rate is wellbalanced over all the subcarriers. Particularly, the SMM-rate optimization Algorithm 2 is more profound in rate balancing feature compared to the GM-rate optimization Algorithm 1.

Figs. 4 and 5 depict the achievable rates of individual UEs obtained using the proposed GM-rate and SMM-rate optimization Algorithms 1 and 2, at P = 20 dBm and P = 30 dBm, respectively. The results are compared to those obtained using SR maximization, which is carried out by adapting Algorithm 1 for  $\gamma_k \equiv 1$  for all  $k \in \mathcal{K}$ . The SR maximization leads to zero rates for certain UEs, whereas the proposed GM-rate and SMM-rate optimization algorithms aim for balancing the rates of all UEs and avoid zero rates.



Fig. 2: Convergence of GM-rate optimization Alg. 1



Fig. 4: Individual user-rates,  $r_k(\mathbf{w}, \boldsymbol{v})$ , for all users  $k \in \mathcal{K}$  by different algorithms at P = 20 dBm.

In Fig. 6, the achievable MR is plotted against the total transmit power budget P. We can observe from Fig. 6 that the conventional passive-RIS-based implementation provides a modest performance advantage over the RIS-less-based implementation. On the other hand, Fig. 6 shows that the proposed active-RIS-based optimization algorithms outperform the conventional RIS-less or passive-RIS-based optimization methods. For example, considering SMM-rate optimization, the achievable MR of the active-RIS-based Algorithm 2 is 1.9 and 2.1 times higher than that of the passive-RIS and RIS-less based implementations, respectively, at P = 32 dBm. Similarly, upon considering GM-rate optimization, the achievable MR of the active-RIS Algorithm 1 is 1.8 times higher that of the respective passive-RIS and RIS-less based implementations at P = 32 dBm. This is because, in contrast to passive-RIS implementation, the use of active-RIS facilitates the power amplification of the incident signals. For a fair comparison,



Fig. 3: Rate distribution over subcarriers at P = 30 dBm.



Fig. 5: Individual user-rates,  $r_k(\mathbf{w}, \boldsymbol{v})$ , for all users  $k \in \mathcal{K}$  by different algorithms at P = 30 dBm.

we ensure that both implementations are simulated under the same power budget. The details of this are provided at the start of Section V. Note that since we initialize the SMM-rate optimization Algorithm 2 by the solution of the GM-rate maximization Algorithm 1, the former outperforms the latter and the performance gap increases with the increase in P.

Fig. 6 demonstrates that the conventional passive-RIS-based implementation provides only a marginal performance advantage over the RIS-less implementation. By contrast, the proposed active-RIS-based optimization algorithms outperform both the passive-RIS and RIS-less methods. For instance, considering SMM-rate optimization, the achievable MR of the active-RIS Algorithm 2 is 1.9 and 2.1 times higher than that of the passive-RIS and RIS-less implementations, respectively, at P = 32 dBm. Similarly, for GM-rate optimization, the achievable MR of the active-RIS Algorithm 1 is 1.8 times higher than that of the respective passive-RIS and RIS-less



Fig. 6: Achievable MR versus the total transmit power budget *P*.



Fig. 8: Achievable MR versus the number of transmit antennas  $N_t$ .

implementations at P = 32 dBm. Moreover, since the SMMrate optimization Algorithm 2 is initialized from the solution of the GM-rate maximization Algorithm 1, the former outperforms the latter in terms of its achievable MR, with the performance gap increasing upon increasing P.

Fig. 7 displays the achievable SR versus the total transmit power budget P. The proposed active-RIS-based optimization algorithms surpass the conventional RIS-less methods in terms of achievable SR. Additionally, the achievable SR using the SMM-rate optimization Algorithm 2 approaches that of SR maximization at higher power budgets. It is worth noting that SMM-rate optimization offers the advantage of fairer rate distribution among users and avoids zero rates for certain UEs, as already shown in Figs. 4 and 5.

Fig. 8 illustrates the achievable MR versus the number of transmit antennas  $N_t$ . The achievable MR increases upon



Fig. 7: Achievable SR versus the total transmit power budget *P*.



Fig. 9: Achievable SR versus the number of transmit antennas  $N_t$ .

increasing  $N_t$  due to the enhanced transmit antenna diversity. The superiority of the proposed active-RIS-based optimization algorithms over the conventional RIS-less methods is evident for various values of  $N_t$ . Notably, when initialized with the solution of the active-RIS-based GM-rate Algorithm 1, the SMM-rate optimization Algorithm 2 further enhances the MR by approximately 15% compared to the former across different  $N_t$  values.

Fig. 9 presents the achievable SR versus the number of transmit antennas  $N_t$ . Notably, the achievable SR using the SMM-rate optimization Algorithm 2 approaches that of SR maximization, as  $N_t$  increases. This approach maintains a fair rate distribution among users and avoids zero rates for any UE, as already demonstrated in Figs. 4 and 5

Figs. 10 and 11 show that unlike the conventional passive-RIS-based implementation, which fails to achieve any increase



Fig. 10: Achievable MR versus the number of PREs N.

in the achievable MR or SR upon increasing N, our proposed active-RIS based optimization algorithms manage to increase the achievable MR or achievable SR upon increasing N. When initialized by the solution of the active-RIS based GM-rate maximization Algorithm 1, the active-RIS-based SMM-rate optimization Algorithm 2 is capable of further enhancing the MR and SR over a range of values of N. The resultant gain is around 17% in terms of the achievable minimum user-rate and around 2% in terms of the sum rate.

Next, the computational complexity of the proposed algorithms is analysed.

Table III shows that, on average, the GM-rate optimization Algorithm 1 and SMM-rate optimization Algorithm 2 require 38.2 and 58.3 iterations for convergence, respectively. For the SMM-rate optimization Algorithm 2, we include the number of iterations required for its initialization, because it is initialized from the solution of the GM-rate maximization Algorithm 2. The readings are obtained by assuming  $N_t = 10$  transmit antennas, N = 100 active-PREs, S = 64 subcarriers, and K = 10 UEs, at P = 32 dBm. Notably, both algorithms exhibit scalable complexities and are computationally efficient due to their iterative nature and the evaluation of closed-form expressions.

#### VI. CONCLUSIONS

The potential of an active-RIS-assisted MU MC system in delivering high rates to all users has been investigated. The joint design of the RIS's PREs and the transmit beamformers at the BS has been addressed to enhance the users' individual rates. To overcome the intractability of large-scale computation in the conventional max-min rate optimization, we have proposed two surrogate problems: GM-rate maximization and soft max-min rate optimization. Specifically, we have developed computational solutions that iterate closed-form expressions for gradually enhancing both the PREs and multiuser beamformers for arbitrarily large multi-user networks.



Fig. 11: Achievable SR versus the number of PREs N.

Under the same total power-budget, the proposed active-RISassisted MU MC system design has approximately doubled the achievable MR or SR compared to the RIS-less or passive-RIS-assisted MU MC system. Moreover, the advantage of our proposed GM-rate and SMM-rate optimization-based designs over the conventional SR-maximization-based design has been demonstrated in terms of providing rate-fairness for all users. The performance of our proposed algorithms can serve as a benchmark for future studies.

# APPENDIX A: BISECTION PROCEDURE FOR COMPUTING (29) OR (58)

Given positive semi-definite matrices  $Q_s$  and  $E_s$  of size  $N \times N$ , vectors  $b_{k,s} \in \mathbb{C}^N$ ,  $s = 0, \ldots, S$ , and  $P_1 > 0$ , and  $P_2 > 0$ , consider the following convex problem:

$$\max_{\boldsymbol{x}} \quad f(\boldsymbol{x}) \triangleq -2\sum_{k=1}^{K} \sum_{s=0}^{S-1} \Re\{\langle b_{k,s}, \boldsymbol{x}_{k,s} \rangle\} + \sum_{k=1}^{K} \sum_{s=0}^{S-1} \boldsymbol{x}_{k,s}^{H} Q_{s} \boldsymbol{x}_{k,s} \quad (67a)$$

s.t. 
$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \|\boldsymbol{x}_{k,s}\|^2 \le P_1,$$
 (67b)

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \boldsymbol{x}_{k,s}^{H} E_{s} \boldsymbol{x}_{k,s} \leq P_{2}.$$
 (67c)

An obvious solution of (67) is

$$x_{k,s}^{\text{opt}} = (Q_s)^{-1} b_{k,s},$$
 (68)

whenever

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \| (Q_s)^{-1} b_{k,s} \|^2 \le P_1$$
(69)

and

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} (b_{k,s})^{H} (Q_{s})^{-1} E_{s} (Q_{s})^{-1} b_{k,s} \leq P_{2}.$$
(70)

TABLE III: Complexity of GM-rate and SMM-rate optimization algorithms for  $N_t = 10$  transmit antennas, N = 100 PREs, S = 64 subcarriers, and K = 10 UEs, at P = 32 dBm.

	GM-rate optimiza	ation Alg. 1	SMM-rate optimization Alg. 2			
	Beamforming ascent	PREs ascent	Beamforming optimiz.	PREs optimiz.		
Computational Complexity	$\mathcal{O}\left(N_t \log_2(N_t) K S\right)$	$\mathcal{O}(N\log_2(N))$	$\mathcal{O}\left(N_t \log_2(N_t) K S\right)$	$\mathcal{O}(N\log_2(N))$		
Average # of iterations for convergence	38.2		58.3			
Average computation time per iteration	2.27 se	c	2.4 sec			

If (70) is not met, we use bisection to find  $\mu_2$  so that

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} (b_{k,s})^{H} (Q_{s} + \mu_{2}E_{s})^{-1} E_{s} (Q_{s} + \mu_{2}E_{s})^{-1} b_{k,s}$$
$$= P_{2}. (71)$$

Then the solution of (67) is

$$x_{k,s}^{\text{opt}} = (Q_s + \mu_2 E_s)^{-1} b_{k,s}, \tag{72}$$

whenever

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| \left( Q_s + \mu_2 E_s \right)^{-1} b_{k,s} \right\|^2 \le P_1.$$
 (73)

Analogously, whenever (69) is not met, we use bisection to find  $\mu_1$  so that

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| \left( Q_s + \mu_1 I_{N_t} \right)^{-1} b_{k,s} \right\|^2 = P_1.$$
 (74)

The solution of (67) is given by

$$x_{k,s}^{\text{opt}} = \left(Q_s + \mu_1 I_{N_t}\right)^{-1} b_{k,s} \tag{75}$$

if

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} (b_{k,s})^{H} (Q_{s} + \mu_{1} I_{N_{t}})^{-1} E_{s} (Q_{s} + \mu_{1} I_{N_{t}})^{-1} b_{k,s} \le P_{2}.$$
(76)

For the remaining case when (71) and (74) are not met, the solution of (67) is

$$x_{k,s}^{\text{opt}} = (Q_s + \mu_2 E_s + \mu_1 I_{N_t})^{-1} b_{k,s}, \tag{77}$$

where  $\mu_1 > 0$  and  $\mu_2 > 0$  are the roots of the nonlinear equations:

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| \left( Q_s + \mu_2 E_s + \mu_1 I_{N_t} \right)^{-1} b_{k,s} \right\|^2 = P_1, \quad (78a)$$

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left( b_{k,s} \right)^H \left( Q_s + \mu_2 E_s + \mu_1 I_{N_t} \right)^{-1} E_s$$

$$\times \left( Q_s + \mu_2 E_s + \mu_1 I_{N_t} \right)^{-1} b_{k,s} = P_2, \quad (78b)$$

which however are computationally intractable. To resolve this issue, we employ a partial Lagrange multiplier method, which aims to find  $\lambda_2 > 0$ , so that the solution of the problem

$$\min_{\boldsymbol{x}} f(\boldsymbol{x}) + \lambda_2 \left( \sum_{k=1}^{K} \sum_{s=0}^{S-1} \boldsymbol{x}_{k,s}^H E_s \boldsymbol{x}_{k,s} - P_2 \right) \quad \text{s.t.} \quad (67b),$$
(79)

satisfies  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} \boldsymbol{x}_{k,s}^{H} E_s \boldsymbol{x}_{k,s} = P_2$ . For fixed  $\lambda_2$ , the solution of (79) is given by

$$x_{k,s}(\lambda_2) = \begin{cases} (Q_s + \lambda_2 E_s)^{-1} b_{k,s} & \text{if } \omega \le P_1 \\ (Q_s + \lambda_2 E_s + \lambda_1 I_{N_t})^{-1} b_{k,s} & \text{otherwise,} \end{cases}$$
(80)

where

$$\omega = \sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| (Q_s + \lambda_2 E_s)^{-1} b_{k,s} \right\|^2,$$

and  $\lambda_1$  is found by bisection such that  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} \left\| (Q_s + \lambda_2 E_s + \lambda_1 I_{N_t})^{-1} b_{k,s} \right\|^2 = P_1$ . It follows from (76) that  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^H(0) E_s x_{k,s}(0) > P_2$ , while for  $\lambda_s$  sufficiently large while for  $\lambda_2$  sufficiently large

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^{H}(\lambda_2) E_s x_{k,s}(\lambda_2) < P_2.$$

We thus start from  $\lambda_l = 0$  and  $\lambda_u$  is such that

$$\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^{H}(\lambda_{u}) E_{s} x_{k,s}(\lambda_{u}) < P_{2},$$

and conduct the following innovative bisection procedure.

We set  $\lambda_2 = (\lambda_u + \lambda_l)/2$  and solve the problem (79). We stop the procedure if  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^H(\lambda_2) E_s x_{k,s}(\lambda_2) \approx P_2$ . Otherwise, update  $\lambda_l \leftarrow \lambda_2$  if  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^H(\lambda_2) E_s x_{k,s}(\lambda_2) > P_2$  or  $\lambda_u \leftarrow \lambda_2$  if  $\sum_{k=1}^{K} \sum_{s=0}^{S-1} x_{k,s}^H(\lambda_2) E_s x_{k,s}(\lambda_2) < P_2$ .

### APPENDIX B: PROOF OF INEQUALITY (42)

By Cauchy's inequality, we have

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$$\sqrt[S]{\prod_{i=1}^{S} \frac{1}{q_i}} \leq \frac{1}{S} \sum_{i=1}^{S} \frac{1}{q_i}$$

$$\Rightarrow \ln\left(\sqrt[S]{\prod_{i=1}^{S} \frac{1}{q_i}}\right) \leq \ln\left(\frac{1}{S} \sum_{i=1}^{S} \frac{1}{q_i}\right) \quad (81)$$

$$\Rightarrow \quad \frac{1}{S} \sum_{i=1}^{S} \ln \frac{1}{q_i} \le \ln \left( \frac{1}{S} \sum_{i=1}^{S} \frac{1}{q_i} \right) \tag{82}$$

$$\Leftrightarrow \quad -\frac{1}{S}\sum_{i=1}^{S}\ln\frac{1}{q_i} \ge -\ln\left(\frac{1}{S}\sum_{i=1}^{S}\frac{1}{q_i}\right). \tag{83}$$

The inequality (42) is obtained from (83) by using

$$q_i \equiv 1 + \frac{|\hbar_{k,i}(\boldsymbol{\upsilon})\mathbf{w}_k(i)|^2}{\sum_{j \in \mathcal{K} \setminus \{k\}} |\hbar_{k,i}(\boldsymbol{\upsilon})\mathbf{w}_j(i)|^2 + \|\bar{g}_{\text{R-k,i}}\boldsymbol{\Upsilon}\|^2 \sigma_{\tilde{n}}^2 + \sigma^2},$$
$$i = 1, \dots, S.$$

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