



An introduction to the π -calculus

Model, Variations, Semantics

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The π calculus

The syntax

- An infinite set of names: $\mathcal{N} = \{x, y, z, \dots\}$.
- Action prefixes

$$\pi ::= x(y) \mid \bar{x}\langle y \rangle \mid \tau$$

- Processes

$$P ::= \sum_{i \in I} \pi_i.P_i \mid P \mid P \mid (\nu a)P \mid !P$$

Reductions

$$(vz)(\bar{x}\langle y\rangle + z(w).\bar{w}\langle y\rangle \mid x(u).\bar{u}\langle v\rangle \mid \bar{x}\langle z\rangle)$$

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$$(\nu z)(\bar{x}\langle y \rangle + z(w).\bar{u}\langle y \rangle \mid x(u).\bar{u}\langle v \rangle \mid \bar{x}\langle z \rangle)$$

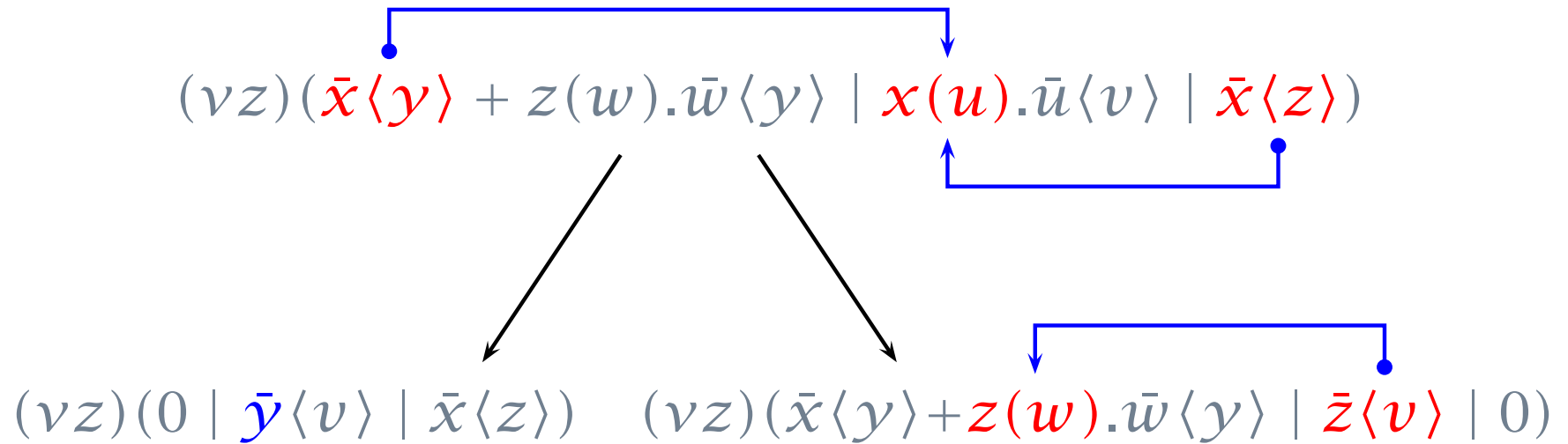
$$(\nu z)(0 \mid \bar{y}\langle v \rangle \mid \bar{x}\langle z \rangle)$$

Reductions

$$(\nu z)(\bar{x}\langle y \rangle + z(w).\bar{w}\langle y \rangle \mid x(u).\bar{u}\langle v \rangle \mid \bar{x}\langle z \rangle)$$

$$(\nu z)(0 \mid \bar{y}\langle v \rangle \mid \bar{x}\langle z \rangle) \quad (\nu z)(\bar{x}\langle y \rangle + z(w).\bar{w}\langle y \rangle \mid \bar{z}\langle v \rangle \mid 0)$$

Reductions



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Contexts and Congruences

Process Contexts

$$C ::= [] \mid \pi.C + P \mid (\nu a)C \mid C|P \mid P|C \mid !C$$

Congruences

A relation $\cong$ is a congruence if it is preserved by all contexts, that is $P \cong Q$ implies:

$$\begin{array}{ll} \pi.P + R \cong \pi.Q + R & (\nu a)P \cong (\nu a)Q \\ P \mid R \cong Q \mid R & R \mid P \cong R \mid Q \\ !P \cong !Q \end{array}$$

Structural Congruence

$P \equiv Q$ if they can be transformed into each other using

- alpha-conversion: for z not free in P

$$x(y).P \equiv x(z).\{z/y\}P$$

$$(\nu a)P \equiv (\nu z)\{z/a\}P;$$

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- commutative monoidal laws for $|$ (with 0 as unit);
- $(\nu z)(P | Q) \equiv (\nu z)P | Q$, if z not free in Q ;
 $(\nu z)0 \equiv 0$, $(\nu x)(\nu y)P \equiv (\nu y)(\nu x)P$.

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- $!P \equiv P | !P$

Standard Form

A process

$$(\nu \vec{a})(M_1 \mid \cdots \mid M_m \mid !Q_1 \mid \cdots \mid !Q_n)$$

is in standard form if

1. each M_i is a sum and
2. each Q_i is itself in standard form.

Thm: Every processes is structurally congruent to a process in standard form.

Reaction Rules

REACTION RULES

$$\text{TAU} : (\tau.P + M) \rightarrow P$$

$$\text{REACT} : (M + x(y).P) \mid (\bar{x}\langle z\rangle.Q + M') \rightarrow \{z/y\}P \mid Q$$

$$\text{PAR} : \frac{P \rightarrow P'}{P \mid Q \rightarrow P' \mid Q} \quad \text{RES} : \frac{P \rightarrow P'}{(\nu a)P \rightarrow (\nu a)P'}$$

$$\text{STRUCT} : \frac{P \equiv P' \quad P' \rightarrow Q' \quad Q' \equiv Q}{P \rightarrow Q}$$

An example

Although it may appear not obvious, the term

$$x(z).\bar{y}\langle z\rangle \mid !(\nu y)\bar{x}\langle y\rangle.Q$$

has a redex. Let us use $\equiv$ to uncover it.

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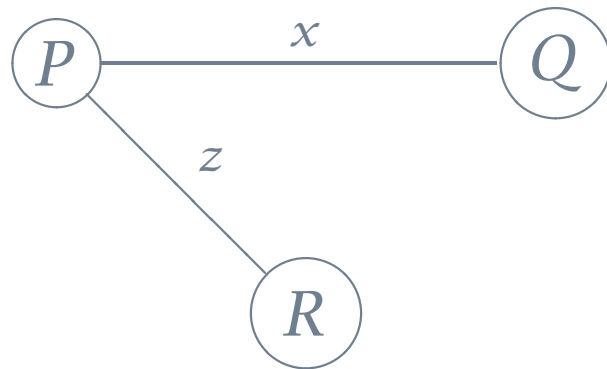
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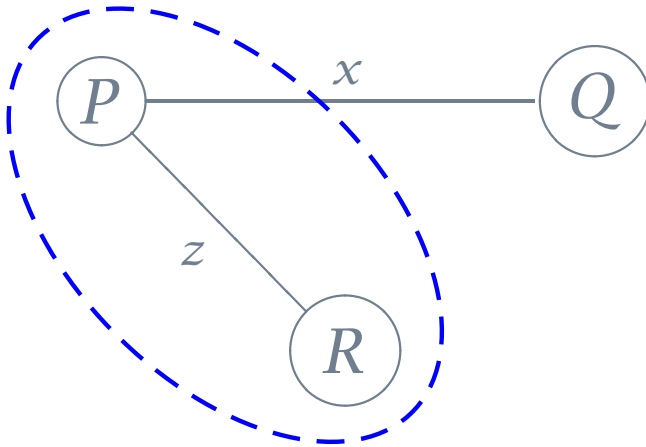
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Mobility



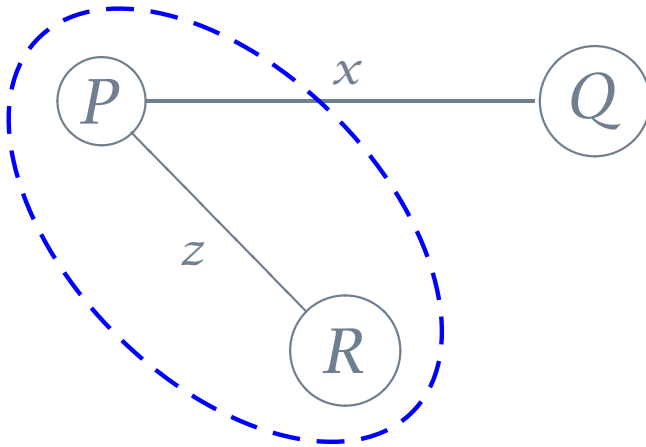
$P \mid Q \mid R$

Mobility



$$(\nu z)(P \mid Q) \mid R$$

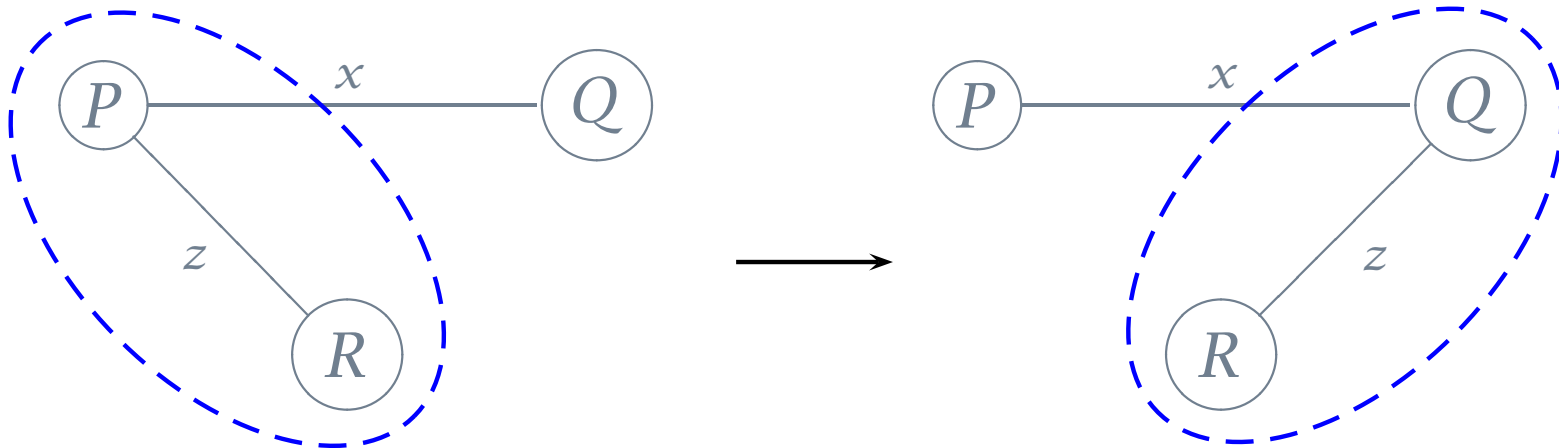
Mobility



$$(\nu z)(P \mid Q) \mid R$$

Suppose $P = \bar{x}\langle z \rangle.P'$ (x not free in P') and $Q = x(y).Q'$

Mobility



$(\nu z)(P \mid Q) \mid R$

$P' \mid (\nu z)(Q' \mid R)$

New scope of z

Polyadic π

The idea:

$$x(y_1, \dots, y_n).P \mid \bar{x}\langle z_1, \dots, z_n \rangle.Q \rightarrow \{\vec{z}/\vec{y}\}P \mid Q$$

Is it a more expressive paradigm? Or can it be encoded?

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Encoding? $\llbracket \bar{x}\langle z_1, z_2 \rangle.P \rrbracket = \bar{x}\langle z_1 \rangle.\bar{x}\langle z_2 \rangle.\llbracket P \rrbracket$.

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Wrong idea:

$$\llbracket \bar{x}\langle z_1, z_2 \rangle.P \mid x(y_1, y_2).Q_1 \mid x(y_1, y_2).Q_2 \rrbracket \\ \longrightarrow^*$$

$$\llbracket P \rrbracket \mid x(y_2).\{z_1/y_1\}\llbracket Q_1 \rrbracket \mid x(y_2).\{z_2/y_2\}\llbracket Q_2 \rrbracket$$

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Right idea:

$$\llbracket \bar{x}\langle z_1, z_2 \rangle.P \rrbracket = (\nu z)\bar{x}\langle z \rangle.\bar{z}\langle z_1 \rangle.\bar{z}\langle z_2 \rangle.\llbracket P \rrbracket$$

$$\llbracket x(z_1, z_2).P \rrbracket = x(y).y(y_1).y(y_2).\llbracket P \rrbracket$$

Thm. The translation is ‘fully abstract’.

Summation

The original calculus has **unguarded sums**:

$$P ::= \dots \mid P + P$$

This makes the theory more complex while producing little gains in expressiveness.

Input guarded sum: $\sum_{i \in I} x_i(y).P$

Rejects things like $(\textcolor{red}{x}.P + \bar{y}.Q) \mid (\bar{x}.P' + \textcolor{blue}{y}.Q')$.

No choice:

Still, purely internal choice $\tau.P + \tau.Q$ can be defined:

$$(\nu a)(\bar{a} \mid a.P \mid a.Q)$$

Matching and Mismatching

The original calculus has

$$P ::= \dots \mid [x = y]P \mid [x \neq y]P$$

$$[x = x]P \rightarrow P$$

$$[x \neq y]P \rightarrow P$$

Useful in programming, it somehow complicates the theory. A general encoding is not known, but in some interesting cases its effect can be recovered to a certain extent:

$$\llbracket a(x).(\sum_i [x = k_i]P_i) \rrbracket = a(x).(\bar{x}\langle \rangle \mid \sum_i k_i().\llbracket P_i \rrbracket)$$

This works provided nobody interferes with k_i .

Recursive Definitions

It is useful to be able to write

$$A(\vec{x}) \stackrel{\text{def}}{=} Q_A, \quad \text{where } Q_A = \dots A\langle\vec{w}\rangle \dots A\langle\vec{w}\rangle \dots$$

It can be obtained using replication as follows

1. Choose a_A to stand for A ;
2. $\hat{R}$ = replace $A\langle\vec{w}\rangle$ with $\bar{a}_A\langle\vec{w}\rangle$ in R ;
3. $\hat{\hat{P}} = (\nu a_A)(\hat{P} \mid !a_A(\vec{x}).\hat{Q}_A)$.

On the other hand, replication can be defined from recursive defs.

Asynchronous π

No continuation on output: $\bar{x}\langle y \rangle \cancel{P}$

The closest you can simulate it: $P \equiv \tau.(P' \mid \bar{x}\langle y \rangle)$.

How can P know when and if the output is received?

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No sums

Asynchronous calculi often do not consider sums: those compatible with the idea of asynchrony are encodable.

Other variants

- **Local π :** Disallow inputs on x in the body of $a(x).P$.
- **Internal π :** Disallow external mobility (output of free names): Processes can only pass names their own private names.
- **Distributed π :** Several interesting calculi based on π_A : Dpi, Join, Blue, Seal, Nomadic Pict,...

Higher Order π

The most natural suggestion for process mobility:

$$\pi ::= \dots \mid \mathcal{X}(X) \mid \bar{\mathcal{X}}\langle P \rangle$$

$$P ::= \dots \mid X$$

$$\mathcal{X}(X).P \mid \bar{\mathcal{X}}\langle R \rangle.Q \rightarrow \{R/X\}P \mid Q$$

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$$\bar{a}\langle \bar{b}\langle u \rangle \rangle.b(x) \mid a(X).(X \mid \bar{c}\langle v \rangle) \rightarrow b(x) \mid \bar{b}\langle u \rangle \mid \bar{c}\langle v \rangle.$$

This is very expressive: A general purpose replicator

$$D \stackrel{\text{def}}{=} a(X).(X \mid \bar{a}\langle X \rangle)$$

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Thm. Encoding ‘fully abstract’. Assume a name an unused name x associated to each X .

$$\llbracket \bar{a}\langle P \rangle.Q \rrbracket = (\nu p)\bar{a}\langle p \rangle.(\llbracket Q \rrbracket \mid !p.\llbracket P \rrbracket), \text{ } p \text{ fresh}$$

$$\llbracket a(X).P \rrbracket = a(x).\llbracket P \rrbracket$$

$$\llbracket X \rrbracket = x$$

Observations and Bisimulation

Observations: $P \downarrow_a$ if P can engage in action a

$$P \equiv (\nu \vec{x})(\alpha.P + \dots) \quad \alpha \in \{\bar{a}\langle z \rangle, a(y)\}, \quad a \notin \vec{x}$$

Barbed Bisimulation $\dot{\sim}_B$: is the largest equivalence relation $\dot{\sim}$ s.t. for all $P \dot{\sim} Q$

1. $P \rightarrow P'$ then $Q \rightarrow Q'$ for some such that $P' \dot{\sim} Q'$;
2. $P \downarrow_x$ then $Q \downarrow_x$

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Barbed equivalence is very weak:

$$\bar{a}\langle u \rangle \dot{\sim}_B \bar{a}\langle v \rangle \dot{\sim}_B (vu)\bar{a}\langle u \rangle$$

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But contexts are very powerful enquirers:

$C = (\nu a)([] \mid a(x).x)$. Then

$$\begin{aligned} C[\bar{a}\langle u \rangle] &\rightarrow (\nu a)u \downarrow_u & C[\bar{a}\langle v \rangle] &\rightarrow (\nu a)v \downarrow_v \\ C[(\nu u)\bar{a}\langle u \rangle] &\rightarrow (\nu au)u \downarrow \end{aligned}$$

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Therefore

$$C[\bar{a}\langle u \rangle] \not\dot{\sim}_B C[\bar{a}\langle v \rangle] \not\dot{\sim}_B C[(\nu u)\bar{a}\langle u \rangle]$$

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Barbed Congruence $\sim_B$: Is the largest congruence in $\dot{\sim}_B$, that is $P \sim_B Q$ iff $C[P] \dot{\sim}_B C[Q]$, for all C .

Labelled Transitions

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- Congruences are brought about by engineering, mathematical and logical considerations.
- But barbed congruence is hard to understand and work with.
- Desiderata: Characterise it in terms of:
 1. bisimulations (easy to reason with – coinduction)
 2. labelled transition systems (describe interactions with environment explicitly, help intuition, bag of tools, ...)

Abstractions and Concretions

$x(y).P$ has the shape $\mathbf{x}F$, for $F = (y).P$

$\bar{x}\langle z \rangle.Q$ has the shape $\mathbf{\bar{x}.C}$, for $C = \langle z \rangle.Q$

For bound output: $C = (\nu a)\langle z \rangle.Q$ ($a = z$ or ν absent).

$$(y).P \bullet (\nu a)\langle z \rangle.Q = (\nu a)(\{z/y\}P \mid Q),$$

a not free

$$(y).P \mid R = (y).(P \mid R),$$

y not free

$$(\nu c)(y).P = (y).(\nu c)P,$$

$c \neq y$

$$(\nu a)\langle z \rangle.Q \mid R = (\nu a)\langle z \rangle.(Q \mid R),$$

z not free

$$(\nu c)(\nu a)\langle z \rangle.Q = \begin{cases} (\nu a)\langle z \rangle.(\nu c)Q, & c \neq z \\ (\nu c)\langle z \rangle.Q, & c = z (= a) \end{cases}$$

Commitment Relation

COMMITMENT RULES

$$\text{SUM} : M + \alpha A \xrightarrow{\alpha} A$$

$$\text{REACT}_{L,R} : \frac{P \xrightarrow{x} F \quad Q \xrightarrow{\bar{x}} C}{P \mid Q \xrightarrow{\tau} F \cdot C} \quad \frac{P \xrightarrow{\bar{x}} C \quad Q \xrightarrow{x} F}{P \mid Q \xrightarrow{\tau} F \cdot C}$$

$$\text{PAR}_{L,R} : \frac{P \xrightarrow{\alpha} A}{P \mid Q \xrightarrow{\alpha} A \mid Q} \quad \frac{Q \xrightarrow{\alpha} A}{P \mid Q \xrightarrow{\alpha} A \mid P}$$

$$\text{RES} : \frac{P \xrightarrow{\alpha} A}{(\nu a)P \xrightarrow{\alpha} (\nu a)A} \alpha \notin \{a, \bar{a}\} \quad \text{REP} : \frac{P \mid !P \xrightarrow{\alpha} A}{!P \xrightarrow{\alpha} A}$$

Thm. $P \xrightarrow{\tau} \equiv Q$ iff $P \rightarrow Q$.

An example

Let us show how to prove that

$$x(y).P \mid (\nu a)\bar{x}\langle a\rangle.Q \xrightarrow{\tau} (\nu a)(\{a/y\}P \mid Q)$$

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$$\frac{\frac{}{x(y).P \xrightarrow{x} (y).P} \quad \frac{\bar{x}\langle a\rangle.Q \xrightarrow{\bar{x}} \langle a\rangle.Q}{(\nu a)\bar{x}\langle a\rangle.Q \xrightarrow{\bar{x}} (\nu a)\langle a\rangle.Q}}{x(y).P \mid (\nu a)\bar{x}\langle a\rangle.Q \xrightarrow{\tau} (\nu a)(\{a/y\}P \mid Q)}$$

The role of $\bullet$:

$$\begin{aligned} (y).P \bullet \langle a\rangle.Q &= (\{a/y\}P \mid Q) \\ (y).P \bullet (\nu a)\langle a\rangle.Q &= (\nu a)(\{a/y\}P \mid Q) \end{aligned}$$

Bisimulation

Strong (late) Bisimulation $\sim_L$: is the largest equivalence relation $\hookrightarrow$ s.t. for all $P \hookrightarrow Q$

1. $P \xrightarrow{x} (y).P'$ then $Q \xrightarrow{x} (y').Q'$ for some $(y').Q'$ such that $\{z/y\}P' \hookrightarrow \{z/y'\}Q'$, for all $z \in \mathcal{N}$;
2. $P \xrightarrow{\bar{x}} (\nu a)\langle z \rangle.P'$ then $Q \xrightarrow{\bar{x}} (\nu a)\langle z \rangle.Q'$ for some Q' such that $P' \hookrightarrow Q'$;
3. $P \xrightarrow{\tau} P'$ then $Q \xrightarrow{\tau} Q'$ for some Q' such that $P' \hookrightarrow Q'$.

Congruence

$\dot{\sim}_L$ is not preserved by substitution:

$$\begin{aligned}\bar{x} \mid y &\dot{\sim}_L \bar{x}.y + y.\bar{x} \\ \bar{x} \mid x &\dot{\sim}_L \bar{x}.x + x.\bar{x} + \tau \not\dot{\sim}_L \bar{x}.x + x.\bar{x}\end{aligned}$$

Similarly for matching.

$$[x = y]c \dot{\sim}_L 0 \quad \text{but} \quad [x = x]c \not\dot{\sim}_L 0$$

Thm. Let $\sim_L$ be the largest congruence in $\dot{\sim}_L$. Then, $P \sim_L Q$ iff $\sigma P \dot{\sim}_L \sigma Q$ for all substitutions σ .

Thm. $\dot{\sim}_L$ is a congruence for πA

Early bisimulation

Strong early Bisimulation $\dot{\sim}_E$: is defined as $\dot{\sim}_L$ replacing

if $P \xrightarrow{x} (\mathcal{Y}).P'$ then $\exists Q \xrightarrow{x} (\mathcal{Y}').Q' . \forall z. \{z/\mathcal{Y}\}P' \dot{\vdash} \{z/\mathcal{Y}'\}Q'$

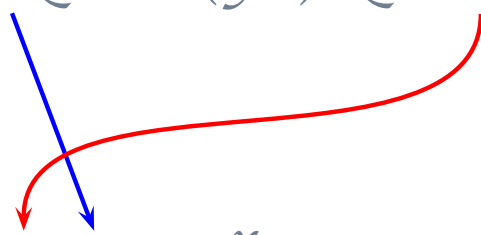
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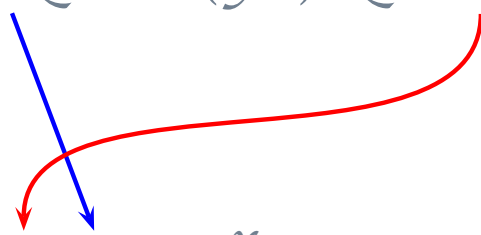
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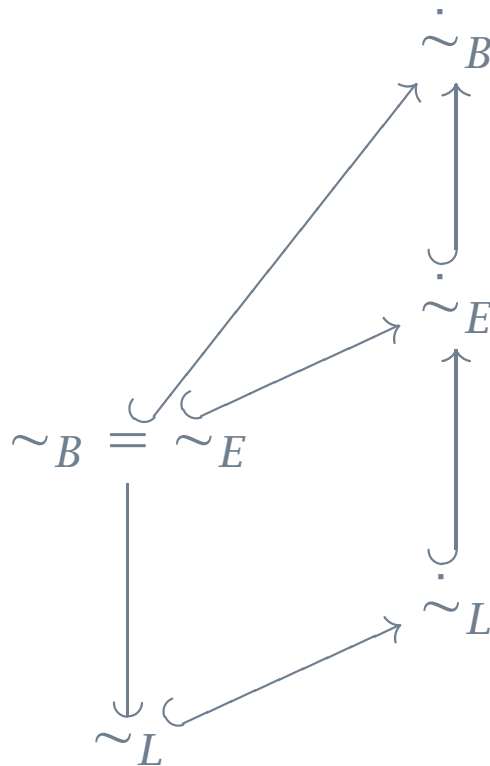


Thm. Let $\sim_L$ be the largest congruence in $\dot{\sim}_L$. Then,
 $P \sim_L Q$ iff $\sigma P \dot{\sim}_L \sigma Q$ for all substitutions σ .

In practice the difference is minimal, but in theory:

Thm. $\sim_L = \sim_B$

Summary Strong Equivalences



Weak bisimulations

Ignore internal steps (τ)

Weak Barbed $\dot{\approx}_B$ and $\approx_B$: Replace

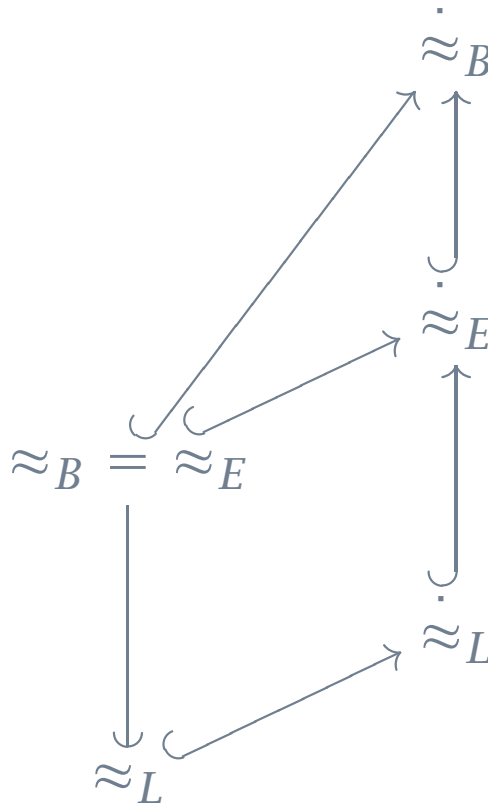
$$\downarrow_x \text{ with } \downarrow_x \stackrel{def}{=} \rightarrow^* \downarrow_x, \text{ and} \\ \rightarrow \text{ with } \Rightarrow \stackrel{def}{=} \rightarrow^*$$

Weak Bisimulations $\dot{\approx}_L$ and $\approx_L$: Replace

$$\begin{aligned} \xrightarrow{\tau} & \text{ with } \Rightarrow \stackrel{def}{=} \xrightarrow{\tau}^*, \\ \xrightarrow{x} & \text{ with } \xRightarrow{x} \stackrel{def}{=} \xRightarrow{x} \Rightarrow \text{ and} \\ \xrightarrow{\bar{x}} & \text{ with } \xRightarrow{\bar{x}} \stackrel{def}{=} \xRightarrow{\bar{x}} \end{aligned}$$

Summary Weak Equivalence

The theory parallels that of the strong equivalences.



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Thm. For finite agents, $P \dot{\sim}_L Q$ iff $P = Q$.

Examples

Expansion law:

$$x(y).P \mid \bar{x}\langle z\rangle.Q = \bar{x}\langle z\rangle.(x(y).P \mid Q) + x(y).(P \mid \bar{x}\langle z\rangle.Q) \\ + \tau.(\{z/y\}P \mid Q)$$

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Congruence and Weak Bisimulation

In order to extend '=' to capture $\sim_L$

- replace the two **congruence** rule by '=' is preserved by all contexts.
- the **expansion** law must include terms

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In order to capture $\approx_L$ add the three **tau laws**:

- $\alpha.\tau.P = \alpha.P$
- $P + \tau.P = \tau.P$
- $\alpha.(P + \tau.Q) = \alpha.(P + \tau.Q) + \alpha.Q$

Modal Logics

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$A \models x = y$ iff x and y are the same name

$A \models \langle \alpha \rangle \varphi$ iff exists $A \xrightarrow{\alpha} B$ and $B \models \varphi$

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Thm. $P \dot{\sim}_L Q$ iff $P \models \varphi \iff Q \models \varphi$, for all φ .

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Let $P = \bar{x}\langle y \rangle$ and $\varphi = \langle \bar{x} \rangle (\sum z)(z = y)$, and let us prove that $P \models \varphi$.

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So, we can conclude that $P \not\vdash_L Q$.

Conclusion

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The π calculus is ...

Well, I'll leave it to you to complete the sentence as you wish.